

### SRM Institute of Science and Technology Faculty of Engineering and Technology Department of Chemical Engineering Course Code & Title: 15CH308 Process Dynamics, Control and Instrumentation Course Strategy Description

#### **Course description:**

This course enables the students to know about control methods and make the students knowledgeable in various types of measuring Instruments used in chemical process industries.

**Compulsory/Elective course:** Compulsory for B.Tech. Chemical Engineering

Credit hours: 4 credits

**Course coordinator(s):** Dr.P.Muthamilselvi, Assistant Professor (O.G.), Department of Chemical Engineering **Instructor(s):** 

| Name of the instructor | Room number | Email (@ktr.srmuniv.ac.in)        | Consultations (day order/periods) |
|------------------------|-------------|-----------------------------------|-----------------------------------|
| Dr.K.Sofiya            | PGA 205     | sofiya.k@ktr.srmuniv.ac.in        | Day – 1: 10                       |
| Dr. P.Muthamilselvi    | PGA 205     | muthamilselvi.p@ktr.srmuniv.ac.in | Day – 3: 10                       |
| Ms.R.Thilakavathi      | PGA 205     | thilakavathi.r@ktr.srmuniv.a.cin  | Day – 4: 1 and 2                  |

# **Relationship to other courses**

Course category: Professional core Prerequisite: 15MA202, 15CH303

Co-requisite: Nil

Following courses: Nil

## Text book(s) and/or required materials:

1.Donald R. Coughanowr., Steven E. LeBlanc., "Process system Analysis & Control ", 3 rdedition., McGraw Hill, New york, 2009.

2. George Stephanopoulos, "Chemical Process Control: An Introduction to Theory and Practice", Prentice Hall, New Delhi, 1984.

## **Reference book(s):**

3.Peter Harriott, "Process Control " Tata McGraw Hill, New Delhi, 1972.

4. Donald P. Eckman, "Industrial Instrumentation", Wiley Eastern Limited, 2004.

5. William L. Luyben, "Process modeling, simulation, and control for Chemical Engineers", 2 ndedition, McGraw Hill, New York, 1996.

**Class schedule:** D2 Slot; Four 50 minutes lecture sessions per week, for 15 – 16 weeks

| DAY ORDER: HOUR | TIMING            |
|-----------------|-------------------|
| DAY - 1: 10     | 4.10 PM – 5.00 PM |
| DAY - 3: 10     | 4.10 PM – 5.00 PM |
| DAY - 4: 1 &2   | 8.AM to 9.40 AM   |



# Instructional Objectives (IOs) and Student Outcomes (SOs)

| S.No. | Instructional Objectives   | Student Outcomes |   |  |  |
|-------|--|------------------|---|--|--|
| 1     | Understand the importance of process control in industrial process plants.   | а                |   |  |  |
| 2     | Understand the use of block diagrams & the mathematical basis for the design and stability of control systems.                       | а                | e |  |  |
| 3     | Understand the application of good instrumentation for the effective design of process control loops for process engineering plants. | а                |   |  |  |
| 4     | Draw a Process & Instrumentation Diagram and devise simple but effective plant wide control strategies using appropriate methods.    | а                | k |  |  |
| 5     | Design and tune process controllers and specify the required final elements to ensure that well -tuned control is achieved.          | а                | k |  |  |

# Teaching plan

| Section                            | Topics   | L / T | Text book/chapter                    | IOs | SOs | Problem<br>solving<br>(Y/N) |
|------------------------------------|--|-------|--------------------------------------|-----|-----|-----------------------------|
| Unit – I: LINEAR OPEN LOOP SYSTEMS |  | 13    |                                      |     |     |                             |
| 1                                  | Basic Concepts of process control, Why process control,<br>Modeling for process dynamics -mathematical tools for<br>modeling, Laplace transform of simple functions, transforms<br>of derivatives. | 2     | Text book [1]<br>Chapter 1,2,3,4,5,6 | 1   | a   | Y                           |
| 2                                  | Solution of differential equations, inversion by partial fractions   | 2     | Text book [1]<br>Chapter 1,2,3,4,5,6 | 2   | a   | Y                           |
| 3                                  | Physical examples of first - order systems   | 3     | Text book [1]<br>Chapter 1,2,3,4,5,6 | 2   | a   | Y                           |
| 4                                  | Response of first -order systems   | 3     | Text book [1]<br>Chapter 1,2,3,4,5,6 | 2   | a   | Y                           |
| 5                                  | Response of first - order systems in series  | 1     | Text book [1]<br>Chapter 1,2,3,4,5,6 | 2   | a   | Y                           |



| 6  | Higher order systems: Second -order and transportation lag   | 2  | Text book [1]<br>Chapter 1,2,3,4,5,6   | 2   | a     | Y |
|--|--|----|--|-----|-------|---|
| UNIT II                                      | : -LINEAR CLOSED LOOP SYSTEMS  | 12 |  |     |       |   |
| 7  | Introduction to controllers and final control element  | 1  | Text book [1]<br>Chapter 8,9,10,11,12  | 3   | a,e,k | Y |
| 8  | Principles of pneumatic and electronic controllers and<br>mechanism of control system & block diagram                  | 2  | Text book [1]<br>Chapter 8,9,10,11,12  | 3   | a,e,k | Y |
| 9  | Mechanism of controllers   | 3  | Text book [1]<br>Chapter 8,9,10,11,12  | 5   | a,e,k | Y |
| 10   | Mechanism of control valves  | 3  | Text book [1]<br>Chapter 8,9,10,11,12  | 5   | a,e,k | Y |
| 11   | Dynamic behavior of controllers  | 3  | Text book [1]<br>Chapter 8,9,10,11,12  | 5   | a,e,k | Y |
| UNIT II<br>AND DE                            | I: STABILITY, FREQUENCY RESPONSE ANALYSIS<br>CSIGN   | 11 |  |     |       |   |
| 12   | Concept of stability, definition of stability, stability criterion   | 1  | Text book [1],[2]                      | 1   | e,k   | Y |
| 13   | Stability for linear system: Routh -<br>Hurwitz stability criterion  | 2  | Text book [1],[2]                      | 2   | e,k   | Y |
| 14   | Root locus diagram   | 3  | Text book [1],[2]                      | 2   | e,k   | Y |
| 15   | Design of control system using frequency response: Bode<br>diagram -<br>stability criterion, phase and gain margins    | 3  | Text book [1],[2]                      | 2   | e,k   | Y |
| 16   | Tuning of controller settings: Ziegler Nichols controller settings   | 2  | Text book [1],[2]                      | 2   | e,k   | Y |
| UNIT IV: CONTROL SCHEMES AND MICRO PROCESSOR |  | 12 |  |     |       |   |
| 17   | Control systems with single loops: Feedback control systems with examples  | 2  | Text and Reference book<br>[2] [3] [5] | 4   | k     | Ν |
| 18   | Control systems with multiple loops: cascade control, selective control systems and split -range control with examples | 4  | Text and Reference book [2] [3] [5]    | 3,4 | k     | Ν |
| 19   | Feed forward and Ratio Control with examples   | 2  | Text and Reference book                | 3,4 | k     | Ν |



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|----------|---|----|-------------------------|-----|---|---|
|          |   |    | [2] [3] [5]             |     |   |   |
|          |   |    |                         |     |   |   |
| 20       | Control of distillation column: control of composition and    | 2  | Text and Reference book | 3,4 | k   | N |
| 20       | pressure  | 2  | [2] [3] [5]             |     |   | 1 |
|          | Microprocessor - based controllers: Introduction to PLC's and | -  | Text and Reference book | 4   | k   |   |
| 21       | DCS   | 2  | [2] [3] [5]             |     |   | Ν |
| LINITT V | MEASUDINC DEVICES   |    |                         |     |   |   |
| UNIT     | WIEASURING DEVICES  | 12 |                         |     |   |   |
|          |   |    |                         |     |   |   |
|          | Principles of measurements and classification of process      |    |                         | 3   | k   |   |
| 22       | control instruments   | 2  | Text book [4]           |     |   | Ν |
|          |   |    |                         |     |   |   |
|          |   |    |                         | 3   | k   |   |
| 23       | Temperature measuring instruments                             | 2  | Text book [4]           | 5   | R   | Ν |
|          | Liquid -level measuring instruments                           | _  |                         | 3   | k   |   |
| 24       |   | 2  | Text book [4]           | C   |   | Ν |
|          |   |    |                         | 2   | 1.  |   |
| 25       | Pressure measuring instruments                                | 2  | Text book [4]           | 3   | к   | Ν |
|          |   |    |                         | 2   | 1.  |   |
| 26       | Composition measuring instruments                             | 2  | Text book [4]           | 3   | к   | Ν |
|          | Magnumenta of minoresitan all concentration thermol           |    |                         | 2   | 1.  |   |
|          | Measurements of viscosity, pH, concentration, thermal         |    |                         | 3   | к   |   |
| 27       | conductivity and humidity of gases.                           | 2  | Text book [4]           |     |   | Ν |
|          |   |    |                         |     |   |   |

#### **Evaluation methods**

| S.NO. | Test            | Topics covered           | Marks | Test/Exam<br>duration (min) |
|-------|-----------------|--------------------------|-------|-----------------------------|
| 1.    | Cycle test – I  | Unit I and II            | 15    | 100                         |
| 2.    | Cycle test – II | Unit III, IV and V       | 25    | 180                         |
| 3.    | Surprise test   | Questions from any units | 5     | 20                          |
| 4.    | Assignment      | Questions from any units | 5     | -                           |
| 5.    | Final exam      | All the units            | 50    | 180                         |

#### Surprise test

The surprise test will not be announced. The questions for this test will be covered until the previous class.

# Home assignments

A few units will have home assignment. All the assignments should be submitted on or before the last date of submission. **Teaching Methodology** 



Chalk and talk for the entire course

 Prepared by: Dr. K. Sofiya, Assistant Professor (Sr.G.), Department of Chemical Engineering

 Dated:

 Revision no.: 1
 Date of revision:

 Revised by:

Course Coordinator

Academic Coordinator

HoD/Chemical