ACADEMIC CURRICULA

Professional Elective Courses

AEROSPACE ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)
Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code 18AS	E201T Course Name	INDUSTRIAL AERODYNAMICS			Cou Cate		Е			Profes	siona	l Electi	ve			L 3	T 0	P C 0 3
Pre-requisite C	Courses 18ASC202J Co-requisite Courses	ses Nil			Pro	aressive	Course	s N	il									
Course Offerin			Standards		Nil	91000110	000100	<u> </u>										
			LINITE															
	ng Rationale (CLR): The purpose of learning thi		1000		Learr							earning						
	erstand the application of aerodynamics in fields <mark>ot</mark>	· · · · · · · · · · · · · · · · · · ·	1	2		1	2	3	4	5 6	7	8	9			2 13	14 15	
	rstand effect of terrain types on the wind flows	133			5	Expected Attainment					a					Finance		
CLR-3: understand the concepts on wind energy and wind turbine aerodynamics								<u>.s</u>		Ć.	Modern 100l Usage	ט		E		. ⊟a	<u>E</u>	
CLR-4: Understand how buildings are affected by wind flows and how to mitigate the unwanted aerodynamic forces								Problem Analysis	<u>.</u>	Analysis, Design, Research	Modern Tool Usag	Environment &	>	Individual & Team	Communication	∞	Life Long Learning PSO - 1	
	erstand how aerodynamics plays a majo <mark>r role in s</mark> ti			evel of Thinking	(Bloom) Expected Proficiency	T A	Engineering Knowledae	Añ	Development	ച്ച്	8 2	<u> </u>		∞	<u>:</u>	Project Mgt. &	Ee	
CLR-6 : Unde	erstand the role of aerodynamics in s <mark>ports balls</mark> an	d vortex induced vibrations		of.	自等	Stec	led	em %		sis, arch	ڍ ۽	a luc .	, IIIa	dua	l I	ן כל	-	
0 1 .	0.1 (010) 414 1541	70.00		_ e	(Bloom) Expecte	c be	nigi wor	Problem /	evel evel	Analysis, I Research	oge Se	<u>`</u> i <u>Ş</u>	Sustall	ndivi	Į L	ë j	PSO	PSO.
	ng Outcomes (CLO): At the end of this course, le		Children Tallet III		<u>e</u> û	<u>இறி</u>	교호		<u>, </u>	₹₩:	Žΰ		ガ世	≗≥	ŭ	<u>~</u> :	5 6	
	erstand different aspects of atmosphere and atmos			2			H	M	L	L		M	-	-	-	-		M L
	iire knowledge on Atmospheric b <mark>oundary l</mark> ayer in a n the working principles of wind t <mark>urbines</mark>	a wina tunnei		2			H	M	M	L		· М	-	-	-	-	- H	M M
	eciate the usefulness of drag reduction devices		NA PROPERTY.	2			Н		L	L		· п	-	-	-		 - H	
	knowledge on building aerodynamics			2			Н	_	M	L		. <u> </u>	-	-	-	-	- п - М	
	ire comprehensive understand <mark>ing on sp</mark> orts aerod	lynamica		2			H	M	I	L		IVI	-	-	-	-		M M
OLO-0 . Acqu	me comprehensive understanding on sports aerod	ynamics	10 mg - 10 mg - 10 mg	1 4	00	70	11 ''	IVI	_	L				_	- 1	-	- 101	IVI IVI
Duration (hour)	9	9	9	T		9				9								
S-1 SLO-1	Aerodynamics / Aviation Aero <mark>dynamics</mark> / Non- Aviation Aerodynamics	Need for renewable energy sources	Rolling resistance Vs Air resi	resistance /			Aerodynamics of race cars				Introduction to building aerodynamics			mics				
SLO-2	Introduction to Industrial Aerodynamics	Wind energy and its importance	Need for automotive aerodyr	namic	s	Ground effects					Environ			Environmental winds in city blocks				
S-2 SLO-1	Need for Industrial Aerodynamics	Wind turbine and its parts	History of Automotive Aerody	ynami	ics	Down force generation					Lov	-rise	buildin	gs (Li	RB)			
SLO-2	Branches of Industrial Aerodynamics	Classification of wind turbines	Evolution of Automobile styli	ng		Front	al and re	ar wing	gs			Roc	f suct	ion eff	ects			
S-3 SLO-1	Atmospheric layers	Horizontal axis wind turbine (HAWT)	Classification of cars				ynamic			oilers		Hig	h-rise	buildir	ngs (F	IRB)		
SLO-2	Atmospheric circulations	Advantages and disadvantages of HAWT	Pressure distribution over ca	irs	- 111	Aeroc	ynamics	of wh	eels					loads				
SLO-1	Local winds	Vertical axis wind turbine (VAWT)	Aerodynamic forces on Auto	mobil	les	Introd	uction to	sports	s aero	dynan	ics	for	LRB			•		nniques
	Terrain types	Advantages and disadvantages of VAWT	Lift, Drag and Moments		1	Aeroc	ynamics	of Cri	cket b	all			odyna HRB	mic lo	ad mi	tigatio	on teci	nniques
S-5 SLO-1	Atmospheric Boundary Layer (ABL)	Wind power, Power coefficient	Sources of vortices in autom	obiles	S	Swing	and Sp	in				Flo	v ovei	r a sim	plified	d build	ding	
S-5 SLO-2	Aerodynamic Roughness length	Flow separation and wake dy	ynami	ics	Effect	of dimp	les on	golf b	all		Pre	ssure	distrib	ution				
S-6 SLO-1	Mean velocity profiles	1-D Momentum theory	Aerodynamic Improvements			Vorte	sheddi	ng				Win	d load	ds – T	VL Fo	rmula		
SLO-2	Power-law and Logarithmic law	Betz limit	Aerodynamics Vs Styling - Li	imitati	ions	Strou	nal numl	per				Fun	neling	g effec	t			
S-7 SLO-1	Variation of wind velocity with height in ABL for different terrain types	Power losses	· ·			Flow induced vibrations				Ventilation								
SLO-2	Turbulence Intensity and its variation in ABL	Energy density of different rotors	Aerodynamics of roofless ve	less vehicles					HVAC									
S-8 SLO-1	Need for ABL simulation	Aerodynamic power control Methods for power control	Aerodynamics of Trucks and	cks and Buses Effect of Reynolds numb		umbe	r on wa											
SLO-2	Boundary layer tunnels	Aerodynamics of Trains	Aerodynamic flutter Wind catchers															

	uration hour)	9	9	9	9	9
5	SLO-1	Simulation of ABL in a wind tunnel	IBlade sections - Airtoils	Ahmed body – Generic automobile shape	Wake galloping	Building codes
S-9 SLO-2		Methods to produce ABL	Wind turbine siting	Wind tunnel experiments and simulations	Vortex speading control methods	Loads on launch vehicles subjected to winds

Learning Resources	 Tom Lawson, Building aerodynamics: Imperial College Press, 2001. Joseph Katz, Automotive Aerodynamics, John Wiley & Sons, 2016. Joseph Katz, Race Car Aerodynamics, Robert Bentley, 1995 Erich Hau, Wind turbines: fundamentals, technologies, application, economics. Springer Science & Business Media, 2013. 	 Martin OL Hansen, Aerodynamics of wind turbines. Routledge, 2015. Robert D Blevins, Flow-induced vibration. Van Nostrand Reinhold Co., 1977. Helge Nørstrud, Sport aerodynamics. Springer Science & Business Media, 2009.
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Learning	Assessment							4.00				
	Bloom's			Con	tinuous Learning Ass	essment (50% weigh	tage)			Final Examination (50% weightage)		
		CLA –	1 (10%)	CLA –	2 (15%)	CLA -	3 (15%)	CLA -	4 (10%)		i (50% weightage)	
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Lovol 1	Remember	40 %		30 %	Control of the second	30 %	258.6	30 %		30%		
Level 1	Understand	40 /0		30 70		30 //		30 78		3070	-	
Level 2	Apply	40 %	1,000	40 %	1000	40 %	400	40 %		40%	_	
LEVEI Z	Analyze	40 70		40 70		40 70		40 /0		4070		
Level 3	Evaluate	20 %		30 %	100	30 %		30 %		30%		
Level 3	Create	20 /0		30 /6	Witness River	30 /6	Teller C			3070	-	
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10	0 %	

Course Designers		W 223
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. C. Palani Kumar, CFD Application Expert, DJAIR, Korea. Email: kumar@djair.co.kr	1. Dr .Arun Kumar Perumal, Mechanical Eng, IIT Jammu,	1. Dr. Bharadwaj <mark>K K, SRM</mark> IST
1. Dr. C. Palarii Kuriiar, CPD Application Expert, DJAIK, Korea. Email. kumar@ujair.co.ki	arun.perumal@iitjammu.ac.in	2. Dr. Kannan B T, SRMIST

Co.		18ASE202T	Course Name	APPLIED STRUCTURAL MECH	ANICS	Course		Е			Profess	sional E	Electiv	/e			L 3	T 0	P C 0 3
	Oro roquio	site Courses	18ASC201J C	co-requisite Courses Nil		Drogr	roccivo	Course	c Nil										
		Department	Aerospace Engineering		indarde	Nil	essive	Course	S IVII										
Cours	Ollering	Department	Aerospace Engineening	Data Book / Codes/Sta	ilidalus	IVII													
Cours	e Learning	Rationale (CLR	\ The nurnose of lea	arning this course is to:	13 1 11 11 11 11		earnir	ıa			Pı	rogram	Lear	ning Ou	itcomes	(PLO	1		-
			cept of external load actin			1	2	3	1	2 3		5	6	7				12 13	14 15
CLR-2			cept of statically indeterm										Ť			- 10			11110
CLR-3			rious energy methods.				Proficiency	Expected Attainment (%)		(0	_	age			ے			စ္	
CLR-4		miliarize with the				Thinking	ficie	E E		Problem Analysis Design &	nent Design,	Modern Tool Usage	Culture	∞ ర	Team	5	∞ .	Learning	
CLR-5	CLR-5: To study the concepts of failure theories.						PG	Atte	g a	Inal	Development Analysis, Des Research	00	3	Environment & Sustainability	~ ∞	Work Communication	£ .	Ea	
CLR-6	CLR-6: Utilize the concepts in better understanding of various structural elements dealing with loads.						eq	99	erii	E &	is, I	i i	∞ _	nme Jab	lal	Ę.	Ĭ	Long 1	2 8
		•		The Report of the Party of the	Level of (Bloom)	ect	ect	yine	ble	velo	deri	jet	/irol stair	Ethics Individual &	된 분	Project Mgt.	의능	1 1 1	
Cours		Outcomes (CLC		course, learners will be able to:	CONTRACT TABLE	Level (Bloor	Expected F	M S	Engineering Knowledge	Problem / Design &	Developme Analysis, E Research	S S	Society	Sus	티글	Work	P :	PSO	PSO PSO
CLO-1			or loads acting <mark>on an acc</mark> e			2	80	70	H	$H \mid H$	Н	-	-			-		ММ	M M
CLO-2				ar force and bending moment diagram.	The second second	2	85	75		H H		-	-	-		-		M M	M M
CLO-3				y different energy methods.	And the state of	2	75	70		H H		-	-	-		-		M M	
CLO-4			g load of a c <mark>olumn und</mark> er			2	85	80	Н	H H		-	-	-		-		M M	
CLO-5				ve for statically indeterminate beams.	The state of the s	2	85	75	Н	H H		-	-	-		-			M M
CLO-6	: Apply	the concepts of	theories of f <mark>ailure to d</mark> ete	rmine the safe design.	ACTION TO A STATE OF THE STATE	3	80	70	H	$H \mid H$	Н	-	-	-		-	-	$M \mid M$	M M
		T		PER ASIDA WAS															
Durati	on (hour)	1 1 1 1 1	9	9	9					9	121 1	.0.				,	9		
	SLO-1			Continuous beam concept. Derivation of								assifica	tion.	Introdu	ction to	failure	theori	es.	
S-1		and factor of sa		Clapeyron's equation of three moments. Application of Clapeyron's equation of three	axial, bending and Torsional lo				load, fa										
3-1	SLO-2	Broad classifica a conventional	alion of extern <mark>al loads o</mark> n	moments to continuous beam with simply			ergy t	heory fo	r long co	lumns.				Discuss propert		ut diffe	erent n	nateria	als and its
	SLO-1	Problems involv	ving accelerated motion of	Problem solving	Derivation of Castigliano's theo Maxwell's Reciprocal theorem	orem I ar	''u '',	ong colu	ımns. D	fferent	Eul <mark>er's</mark> end cond ing stres	ditions	of o	Maximu Derivati		rincipa	al si	tress	theory:
S-2	SLO-2	rigid airplane.		Application of Clapeyron's equation of three moments to continuous beam with fixed end supports.	Application of Castigliano's the find deflection of beams.	eorem –	- I to [Derivation	n of Eu	ıler's fo nds a <mark>re</mark>	r <mark>mula fo</mark> hinged	or crip		solving		•		•	
	SLO-1	Landing Gear S	Structure	Problem solving	Problem solving	14								Maximu	ım Princ	ipal st	rain the	eory D	erivation.
S-3	SLO-2	Problems of andLoads on M Units	Calculating Reactions fembers of Landing Gear		Problem solving		16		en one		<mark>rm</mark> ula fo ced and		ther	Maximu solving	ım Prin	cipal s	train t	heory:	Problem
S-4	SLO-1	Problem solving	9	Problem solving	Differences between statically determinate and statically indeterminate structures with load when one end fixed and the examples				or crip _l other l	oling free.	ing Maximum Shear stress theory: Derivation.								
Learni Resou	U			, S.Chand publications, Sixth Edition, 2015. gth of Materials and structures", Edward Arnolo		E. F. B. (U.S.A),		'Analysis	s and De	sign of	Flight Ve	ehicle S	Structi	ures", T	ri-State	Offset	Сотр	any	

Learning A	Assessment											
	Bloom's			Cont	<mark>inuous Learning Ass</mark>	essment (50% weigh	ntage)			Final Examination (50% weightage)		
	Level of Thinking	$\ (1 \Delta - 1 / 10)\%$		CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4 (10%)#		Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Lovol 1	Remember	40%		30%	100	30%		30%		30%		
Level 1	Understand	40%	-	30%	17 11 1	30%	· -	30%	-	30%	-	
Level 2	Apply	40%		40%	Sec. 13.	40%	The state of the s	40%	_	40%	_	
LCVCI Z	Analyze	4070		4070	100	4070	- 1 A	4070	-	4070	-	
Level 3	Evaluate	40%		30%		30%	THE P.	30%	_	30%		
Level 3	Create	40 /0		3078		30%		3070	-	3070	-	
	Total	10	0 %	10	0 %	100	0 %	10	0 %	10	0 %	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. G.Balamurugan, National Aerospace Laboratories, Bangalore,	1. Dr. V.Arumugam, Madras Institute of Technology, Chennai,	1 Dr. L. D. Congnethy Cubramanian CDMICT
gbala@nal.res.in	arumugam.mitaero@gmail.com	1. Dr.L.R.Ganapathy Subramanian, SRMIST
2. Dr.A. Sakthiyel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R. Velmurugan, Indian Institute of Technology Madras, ryel@ae.iitm.ac	in 2. Dr.T.Selvakumaran SRMIST



	urse ode	18ASE203T Course Name	EXPERIMENTAL STRESS ANAI	LYSIS	Course Category	Е	Professional Elec	tive		
Pre-r	equisite C	ourses 18PYB101J, 18ASC201J	Co-requisite Courses Nil		Prog	ressive Cou	rses Nil			
Cours	e Offering	Department	Aerospace Engineering Data B	ook / Codes/Standards	Nil					
Cours	e Learning	g Rationale (CLR): The purpose of lear	ning this course is to:		Lea	rning	Program Le	arning Outcomes (PLO)		
CLR-	l: Unde	erstand the various aspects of measuremen	ts	188111111111111111111111111111111111111	1	2 3	1 2 3 4 5 6	7 8 9 10 11 12 13 14 15		
CLR-2		erstand the different physical principles of st		111111111111111111111111111111111111111	>	r d				
CLR-3		tify the different materials for resistance type			g id	m me	n, n,	m gilling		
CLR-4		v the various circuits for strain measuring pu			Thinking d Proficie	tain	alys ssig	K V V Light High K W W W W W W W W W W W W W W W W W W		
CLR-5		v the principles and materials in photo elasti			ig a	AA	An A	nen lbilliti		
CLR-6	s: Unae	erstand the various non-destructive te <mark>sting n</mark>	netnoas.	No. of the Control of	jo (El je	cte	vled lem 8 30 8 90 8 90 8 90 8 90 8 90 8 90 8 90	s s sidual idual i		
Cours	a Laarnin	g Outcomes (CLO): At the end of this co	urse, learners will be able to:		Level of Thinking (Bloom)	(%) Expected Attainment (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage	Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3		
CLO-		cribe the measuring process of va <mark>rious instr</mark> u		STATE OF THE PARTY.		35 75	H - H H L H			
CLO-2		cribe about the various strain me <mark>asuring de</mark> v		PORT TO SERVICE		35 75	H H H H - H	H H M M M M		
CLO-		ain the physical principle and c <mark>ircuits use</mark> d in		market and the second		35 75	H - H H - H	H H M M M M		
CLO-4		ain the rosette analysis		A 100		35 75	H H - H - H	H H M M M M		
CLO-		cribe the various photo elastic <mark>concepts</mark> of st	ress measurements	U. R. Harry		35 75	H - H H - H	H H M M M M		
CLO-6	S: Expla	ain the various non destructiv <mark>e method</mark> s of fi	law detection	STATE OF THE STATE OF	2 8	35 75	H H H H - H	H H M M M M		
Durat	ion (hour)	9	9	9	116		9	9		
20.00	SLO-1	Introduction-Stress and strain	Properties of strain gage system	Introduction to resistance strain	gage	Introducti	on to photoelasticity	NDT method-Introduction		
S-1	SLO-2	Introduction- Relation betwe <mark>en stress</mark> es and strains for different materials	Basic characteristics of strain gage	Principle of operation of the resi strain gage, Strain sensitivity			wave plates, polarized light Classification of flaws, Ste			
S-2	SLO-1	Principles of measurements	Huggenberger tensometer	Materials for resistance strain ga Advance alloy, Isoelastic alloy, I and other materials		Stress op	tic law	Fluorescent penetrant technique		
3-2	SLO-2	Aspects of measurements	Advantages and disadvantages, limitations	strain gage	nded wire	Strain op	A	Magnetic particle inspection		
S-3	SLO-1	Fundamental methods of measurements	Diffraction strain gage	Types of resistance strain gage- foil strain gage, Weldable strain	gage	of light in	ariscope , Deriv <mark>ation of int</mark> ensity circular polaris <mark>cope</mark>	Eddy current testing		
3-3	SLO-2	Generalized measuring system	Advantages and disadvantages	Strain gage adhesives, Selection Properties and types	HIM	Effect of s	stressed mod <mark>el in plane</mark> pe	Radiography		
S-4	SLO-1	Accuracy and Precision	Interferometric strain gage	Mounting methods-Gage installa Curing	College Control	Circular p	polaris <mark>cope</mark>	Ultrasonic inspection		
0-4	SLO-2 Repeatability and Reproducibility Advantages and disadvantages Temperature compensation, sensitivity, Gage factor			Temperature compensation, Ga sensitivity, Gage factor	ge	polarisco		A scan, B scan and C scan		
S-5	SLO-1	Tolerance and Range	Tuckerman strain gage	Strain gage circuits, Potentiome		polarisco	<mark>stressed</mark> model in a circular oe	Thermography		
3-3	SLO-2	Bias and Linearity	Advantages and disadvantages	Temperature compensation ,ser range in potentiometer circuit	nsitiv <mark>ity</mark> an	Explanali	on of fringe patterns	Holography		
S-6							ation techniques- Babinet soleil compensation Acoustic emission technique			

Durat	ion (hour)	9	9	9	9	9
	SLO-2	Numerical solving	Advantages and disadvantages			Moire method of strain analysis
	SLO-1	Hysteresis	Inductance strain gage	Circuit sensitivity and different	Fringe separation methods-Shear	Methods
S-7	3LO-1	11/3(6163)3	inductance strain gage	arrangements in wheat stone bridge circuit	difference method, interferometer method	Wethous
	SLO-2	Dead space, Threshold and Resolution	Advantages and disadvantages	Rosette analysis, Different conditions of	Electrical analogy method, Oblique-	Moire fringe pattern
3LU-2		Dead space, Threshold and Nesoldtion	Advantages and disadvantages	strain measurements	incidence method	Mone minge pattern
	SI O 1	Error Analysis- Classification	Semiconductor strain gage	Three element rectangular rosette	Fringe multiplication method	Physical explanation of moiré fringe
S-8	SLO-1	Littor Arialysis- Classification		Three element rectangular rosette	Tringe maniphoanon memod	pattern
	SLO-2	Error analysis- Sources	Advantages and disadvantages			Brittle coating methods
	SLO-1	Error analysis numerical	Acoustical strain gage	Four element rectangular rosette	Properties of photoelastic materials	Types of brittle coating methods
S-9	SI O 2	Calibration	Advantages and disadvantages	Tee delta rosette	Explanation of different photoelastic	Advantages and disadvantages of brittle
	SLO-2	Calibration	Auvantages and disadvantages	Tee della loselle	materials	coating methods

Learning Resources	1. 2.	Dally, J.W., and Riley, W.F., Experimental Stress Analysis, McGraw Hill Inc., New York, 1978 Hetyenyi, M., Hand Book of Experimental Stress Analysis, John Wiley and Sons Inc., New York, 1972
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- Srinath, L.S., Raghava, M.R., Lingaiah, K.Gargesha, G.Pant B., and Ramachandra, K., Experimental Stress Analysis, Tata McGraw Hill, New Delhi, 1984
 Pollock, A.A., Acoustic Emission in Acousticsand Vibrations Progress, ed. By StephensR.W.B., Chapman
- and Hall, 1983

Learning A	Assessment				100 miles							
	Bloom's			Conti	nuous Learning Asse	ssment (50% weig	htage)	91 //-		Final Evamination	(E00/ weightege)	
	Level of Thinking	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	(10%)#	Final Examination (50% weightage)		
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Lovel 1	Remember	40 %		30 %	MAD - 14500	30 %	NAME OF TAXABLE PARTY.	30 %		30%		
Level 1	Understand	40 %		30 %	100000000000000000000000000000000000000	30 %		30 %		30%	-	
Level 2	Apply	40 %		40 %		40 %	The state of the s	40 %		40%		
Level 2	Analyze	40 %		40 %		40 %		40 %		40%	-	
Level 3	Evaluate	20 %		30 %		30 %	And the second second	30 %		30%		
Level 3	Create	20 /0		30 /8		30 /6	· ·	30 76		3070	-	
	Total	10	0 %	100) %	10	00 %	100	%	10	0 %	

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. G.Balamurugan, National Aerospace Laboratories, Bangalore, gbala@nal.res.in	1. Dr. V.Arumugam, Madras Institute of Technology, Chennai, arumugam.mitaero@gmail.com	1. Dr. L.R. Ganapathi Subramanian, SRMIST
2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R. Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	2. Mr. S. Chandra Sekhar, SRMIST

Course Code	18ASEZIM I (Course Name) COMPOSITE MATERIALS AND STRUCTURES Protessional Elective																											
Pre-requ	Pre-requisite Courses 18ASC201J Co-requisite Courses Nil Progressive Courses Nil																											
Course Offering Department Aerospace Engineering Data Book / Codes/Standards Nil																												
Course L	oornina	Rationale (CI	D\.	The nu	rnono of loc	arning thi <mark>s cour</mark> s	oo io to:			-				oornir	\a				D	oaror	m l 00	rnina	Outco	maa	/DI ()	١		
CLR-1:		fy Composite			rpose or lea	arning unis cours	se is to:				***		1	_earnir 2	3	1	2	3	4		6 6	ming 7	8	9	(PLU) 11 1	2 12	14 15
CLR-1:					r of compos	site materials		-							3		2	3	4	3	U	1	0	9	10	11 1	2 13	14 15
CLR-3:		rstand the me											• /	ncy	Expected Attainment (%)					ge			١,	_			ກ	
CLR-4:		fying the sele			comologica								Thinking	icie	in in		Problem Analysis		Analysis, Design,	Modern Tool Usage	Society & Culture	×	1	Nork	<u>_</u>		Lile Long Leaning PSO - 1	
CLR-5:		fy material's A					-						Ę	orof Drof	∖tta	0	nal	ent.)esi	9	<u></u>	ĕ <u>≧</u>	l-	<u> </u>	÷ atic	<u>ა</u>	g E	
CLR-6:		rstand the ap			s composite	es		1					of T	pe	pe /	erin	n A	∞ E	S, L	<u>ا</u> ک	∞	ime iabi	<u>c</u>	<u> </u>	ig §	ຼີ ຄ	101	~ m
,	1						71					-	elo	ect	ect	ine	bler	e gi	llysi	Jerr	iet)	iai id	S	¥ \$			- l)-2)-3
Course L	earning	Outcomes (C	LO):	At the e	end <mark>of this c</mark>	course, learners	will be abl	e to:		. 199	7		Level		XX S	Engineering	Po	Des	Ana	Moc	80	Environment & Sustainability	Ethics	Work	Communication	Finance	DSO LIIET	PSO.
CLO-1:		e of the comp						ALTERNATION D	7.70	71111			2	80	70	Н	Н		-	-	-	-		-	-		л M	M
CLO-2:	Under	rstands applic	ation of c	composit	e materials	in different airc	craft compo	nents	1000	177		- 1	2	85	75	Н	Н	-	-	Н	-	-	-	-	-	- 1	<i>I</i> М	M M
CLO-3:	Identi	fy different tre	eatments	to stren	gthen mate	rials		200			100		2	75	70	Н	-	Н	Н	-	-	-	-	-	-	- 1	<i>I</i> М	M M
CLO-4:	Under	rstand moldin	g techniq	ues		1		10000	10.00				2	85	80	Н	Н	Jr. 1	-	Н	-	-	-	-	-	- 1	<i>I</i> М	M M
CLO-5:	Under	rstand Variou	s termino	logies <mark>us</mark>	<mark>sed in c</mark> omp	oosite Materials			110.0	200	Water .		- 2	85	75	Н		Н	-	-	-	-	-	-	-	- 1	<i>I</i> М	M M
CLO-6:	Under	rstand forming	g Techniq	ues		1					73517		2	80	70	Н	-	-	-	-	-	-	-	-	-	- 1	<i>I</i> М	M M
								77	350						- 20		- 6											
Duration			9				9	(1) × (// 1)	-140	100	9							9							9			
U C 1		Introduction to		site M <mark>ate</mark>	erials e	Hooke's law		c Materials		o Mechani					Governii	•	rentia	l equa	tion o	f <mark>ge</mark> ne								
٥ ' S	SLO-2	Natural Comp	osites			Numericals s	solving			Mechani				la	aminate							Block	diagr	am oi	^f Man	ufactu	ring	
S-2	SLO-1	Basic Definiti	ons			Generalized	Hooke's la	V	Fract	tion	olume Frac		ass	Α	ngle pl	y lamin	ates	P	Ц							on Fil		
		Basic Definiti				Numericals s		of the same		sity and Vo	oid Content	t			ross pl			٠.				Block	diagr	am oi	^f Man	ufactu	ring	
S-3		Introduction to				Hooke's law	for 3D Orth	otropic Materials	Nume	ericals sol	lving			٨	lumeric	als solv	/ing					Fabri	cation	of Co	тро	site Ma	aterials	3
3-3 S	SLO-2	Types of Fibe	ers			Hooke's law	for 3D Orth	otropic Materials		ericals sol				٨	lumeric	als solv	/ing						ing Te					
- C /		Matrices				Numericals s	colvina				iterials appi			L	aminat	e Code	S						Layu _l					
5		Types of Mat				Ivalliencals	solving				our Elastic	Modulii			aminat								/ layup					
		Properties of				Hooke's law	for 2D Unio	lirectional lamina		ericals sol					pecial								oressio					
SLO-2 Properties of Matrices Numericals solving ABD Matrix representation								Resin	Tran	sfer n	าoldin	g																
	SLO-1 Classification of Composite Materials Numericals solving Elasticity						ticity appro	oach to dete	ermine l	Materi		1aximui											ssure l	ag Mo	ödling			
5		Block Diagrai			1	Numericals s	solving	March 1982		erties	P. 11/2				1aximui				ory				clave I					
		Application or				Hooke's law	for 2D Ana	le I amina		ro Mechai					sai Hill								ent w			ess		
8		Application or		ites				C Lamina		ro mechan					sai wu								ısion l		SS			
		Hooke's Law				Numericals s					elationship		pect to		Basic concept of sandwich construction Types of resins Materials used in sandwich construction Properties and Application													
		Basics of Hoo	oke's Law	/		Nume <mark>ricals s</mark>	solving		neutr	ral axis an	d arbitrary	axis		Λ	laterial:	s used	<mark>in s</mark> an	dwich	const	tructio	n	Prope	erties a	and A	pplica	ations		
	SLO-1 SLO-2	Numericals s	olving			Numericals s	solving		Ехре	erimental c	characteriza	ation of I	Lamin	a F	ailure r	nodes (of Sar	dwich	pane	ls		Nettir	ng Ana	alysis				

Learning
Resources

- Autar K Kaw, "Mechanics of Composite Materials" CRC Press, Taylor and Francis Group 2005.
 Jones.R.M, "Mechanics of Composite Materials", McGraw-Hill, Kogakusha Ltd., Tokyo, 1985.
- Agarwal.B.D, and Broutman.L.J, "Analysis and Performance of Fibre Composites", John Wiley and sons. Inc., New York, 1995
- Lubin.G, "Handbook on Advanced Plastics and Fibre Glass", Von Nostrand Reinhold Co., New York, 1989

Learning /	Assessment										
	Bloom's			Cont	tinuous Learning Ass	essment (50% weigh	itage)			Final Evamination	n (FOO/ woightage)
	Level of Thinking	CLA – 1	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	4 (10%)#	Filiai Examinatio	n (50% weightage)
	Level of Trilliking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %		30 %		30 %	-4717	30 %		30%	
Level	Understand	40 %		30 %		30 %	- 1/	30 %		30%	-
Level 2	Apply	40 %		40 %		40 %		40 %		40%	
Level 2	Analyze	40 %		40 %	The second second second	40 %		40 %		40%	-
Level 3	Evaluate	20 %	The state of the s	30 %	11.00	30 %		30 %		30%	
Level 3	Create	20 %		30 %		30 %	-	30 %		30%	-
	Total	100	<mark>) %</mark>	10	0 %	100	0 %	10	0 %	10	0 %

Course Designers		
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2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R. Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	2. Mr. N. Bharat, SRMIST



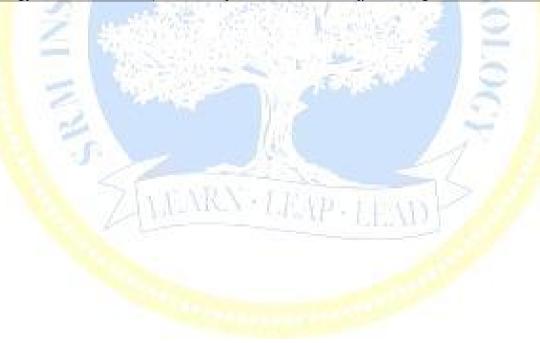
Cou		18ASE205T	LS		ourse t <mark>egory</mark>	Е		F	rofessio	nal Ele	ective				T 0	P C 0 3		
	Pre-req	uisite Courses	18ASC304J	Co-requisite Courses Nil		F	rogres	ssive Co	ırses	Nil								
Course Offering Department Aerospace Engineering Data Book / Codes/Standards Nil																		
Course	Learning	g Rationale (CLR)): The purpose of learni	ing this course is to:	THE NAME OF STREET		Learnii	ng			Progr	am Le	earning	Outo	omes (l	PLO)		
CLR-1	: Iden	tify Plates and Sh	ells			1	2	3	1 2	3	4 5		7			0 11	12 1	3 14 15
CLR-2			anical behavior of Plates and	l <mark>shells </mark>	OF ARTHUR DESCRIPTION	-	े	Ħ			a	,						
CLR-3		erstand the existin		(1)		<u>D</u>	Sien	me	.Sis		بَــ ا	<u>e</u>			E ,	_	ing	
CLR-4 CLR-5		tifying the selection				iş.	rofic	ttair	alys	펕	esig	블	nt & t∨		ě	<u></u> ∞	earr	
CLR-6		tify Plates Applica	ration of various Plat <mark>es and s</mark>	hells	elia visa	ΪΞ	В	d A	dae A	a se	ا ج	\ \&	mer		<u>w</u> w	Mgt	g Le	- 2 8
OLIV-0	. Ona	erstand the applic	ation of various f lates and s	HeliS		Level of Thinking	ecte	ecte	wlec	ign	lysis eard	et	ron	တ္သ	ndividual & Team Work	ect	Long E	. `.` .
Course	Learning	g Outcomes (CLO)): At the end of this cou	rse, learners will be able to:	Tayler .	F e e	Expected Proficiency	Expected Attainment (%)	Engineering Knowledge Problem Analy <mark>sis</mark>	Design & Development	Analysis, Design, Research Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Tea Work	Project Mgt. 8	Life Long Learning	PSO
CLO-1	: Awa	re of the plates an	nd shells and it properties	D10/	The same	2	80	70	H H	- 1		-	-	-				1 M M
CLO-2			on of plates an <mark>d shells in</mark> diff		Mark Street	2	85	75	H H	-	- H	-	-	-				1 M M
CLO-3			ments to stre <mark>ngthen ma</mark> terial	ls .	The second second	2	75	70	Н -	Н	Н -		-	-	-		M N	
CLO-4			solving techniques		No. of Concession, Name of Street, or other Persons, Name of Street, or ot	2	85	80	H H		- H	-	-	-	-	-		1 M M
CLO-5			erminologies <mark>used in P</mark> lates a	and shells	- 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1	2	85	75	H -	H -		-	-	-	-			1 M M
CLO-6		erstand forming T					80	70	H -		- -	_	-	-			IVI I	1 M M
Duration	on (hour)		9	9	9		ж.			9						9		
S-1		Classical Plates	theory	Plates of Various shapes	Eigen value analysis			Approx	imate Meth	nods			Intro	ductic	n to sh	ells		
0.0			theory- Ass <mark>umptions</mark>	Leavy's Method of Solution for Rectangular	0.1111 (ļ.,				- ,	O
S-2	SLO-2	Theory		Plates under Different Boundary Conditions	Stability of Rectangular Pr	ates		Rayleig	ıh – Ritz M	etnoa			Basi	c Con	cepts o	Snell	ype of	Structures
	SLO-1	Classical Plates	theory-Differential	Leavy's Method of Solution for Rectangular	Free Vibration Analysis of	Rectan	nular						Men	hrane	Theor	es for (Sircular i	Cylindrical
S-3	SLO-2	equations	theory-binerential	Plates under Different Boundary Conditions-	Plates	rtoctari	guiui	Numer	icals solvin	g			Shel		, 1110011	03 101 0	moulai	Symianical
		· ·	theom. Downdon.	governing equations									Don	din a T	boomioo	for Cir	oulan Cu	lindrical
S-4	SLO-1 SLO-2		theory – Boun <mark>dary</mark>	Solution for Axi-symmetric loading	Numericals solving			Galerki	n Methods				Shel		neones	ior Circ	cular Cy	imancai
			of solution for simply	- 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1					407						Fauati	on for F	uckling	of
S-5			ported Rectangular plates Numericals solving Numericals solving Bending Theory of Plates Finite Difference Method Cylindri															
S-6	SLO 1 Differential equation for equipment handing								ling									
3-0				Allitulai Flates	rvumencais solving	To the		Ivumen	cais solvill	g			Equa	ation				
0.7	SLO-1		ling of Uniformly Loaded			(5)	11	Applica	tion to Red	tangula	Plates i	or						
S-7	SLO-2	Rectangular Plat	tes with Simply Supported	Numericals solving	Bending-Membrane Theo	ry of Pla	ates	Static A	Analy <mark>sis</mark>				Buck	kling u	nder Ax	al Con	npressic	n
	SLO-1		ling of Uniformly Loaded					Annlica	tion to Red	tangula	r Platos i	or fre	Forn	nulatio	n for B	ıcklina	Stross 2	and
S-8			tes with Built-in Edges	Introduction to plates of other shapes	Numericals solving				n analysis	ariyula	i iales i	OI II C		kling N		ickiirig	011633 6	iiu
	SLO 1 Cylindrical Randing of Uniformly Loaded				, Dlate :					m4 m :!	Datel- · f							
S-9 Rectangular Plates with Elastically Built-in Theory of plates of other shapes Equilibrium Equation and Boundary Applica				<mark>tion to Red</mark> analysis	angula	riates i	or		kling C imetei		rit and	Batdorf						
	JLU-Z	Edges			CONTUILIONS			Stabilly	anaiysis				гага	iiiietel				

Learning	1.	Timoshenko, S.P. Winowsky. S., and Kreger, "Theory of Plates and Shells", McGraw-Hill Book Co. 1990.	3.	Flugge, W. "Stresses in Shells", Springer – Verlag, 1985.
Resources	2.	T. K. Varadan and K. Bhaskar, "Theory of Plates and Shells", 1999, Narosa.	4.	Timoshenko, S.P. and Gere, J.M., "Theory of Elastic Stability", McGraw-Hill Book Co. 1986

Learning	Assessment										
	Bloom's			Con	tinuous Learning Ass	essment (50% weigh	ntage)			Final Evamination	n (50% weightage)
	Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	4 (10%)#	Filiai Examinatio	i (50 % weightage)
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	200	30 %	AA.	30 %	-	30%	-
Level 2	Apply Analyze	40 %		40 %		40 %	//	40 %	-	40%	-
Level 3	Evaluate Create	20 %	(A) P	30 %	NEW Y	30 %		30 %		30%	-
	Total	100) <mark>%</mark>	10	0 %	10	0 %	10	0 %	10	0 %

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Code	1 187	ASE206T	Course Name	THEORY OF ELASTICITY		Cour Categ		E	E Professional Elective L T P C 3 0 0 3								P 0	C 3				
Course		uisite Course Department	es 18ASC304J Aerospace Eng	s/Standards	Nil	Pro	gressiv	e Cours	es	Nil												
Course	Learning			Learnir	าต				Prog	ram I	earnin	a Out	comes	(PLC))							
CLR-1				learning this course is to: g elasticity problems, equilibrium equations		1	2	3	1	7	8				12 1	3 14	15					
CLR-2				displacement relations, compatibility equations				_		2 3		4 5	5 6		Ť						1	
CLR-3				esses & displacements for simple, cantilever bea	ams.		Suc	Je J		(0		. 6	g g			E			Б			
CLR-4				s for axisymmetric problems		king	ficie	in		ysis	ig	5 2	# S	∞ర		ear	5	×	Ē			
CLR-5		the various	theory of torsion for circula	<mark>r, elliptica</mark> l, sections.	A STATE OF THE PARTY OF THE PAR	hin	Pro	Att	ا ک ک	Ina	Des	-	3 3	i i i	ill ()	~ ~	gi.	~: H	Les			
CLR-6	: Get a	a better under	rstanding of solving ela <mark>stici</mark>	ty problems	RESERVED TO THE PARTY OF THE PA] T	ted '	E G	erii	m / 8	ppm is.	ᄓ	_ «୪ = »	i i i	g	nal	Ē.	۾ ڪ	gu +	- 2	-3	
						Level of Thinking	Expected Proficiency	Expected Attainment	Engineering Knowledge	Problem Analysis Design &	Development Analysis, Des	Research	Society & Culture	Environment &	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	6 6	0	
		Outcomes (is course, learners will be able to:)		2 <u>~</u> =	교 2		A An	Re	S S	<u>Б</u>	古	P ≥	රි ර					
CLO-1				ations & compatibility conditions.	AUTOMATICAL TOTAL	2	85	/5	H	H I	1 .	- 1		-	-	-	-	-	$M \mid \mathcal{N}$		М	
CLO-2			e stress & plane st <mark>rain probl</mark>			2	85		Н	H				-	-	-	-	-	M N		М	
CLO-3				mple two dimensional problems in Cartesian co	pordinate	2	85	75	Н	H		Η .		-	-	-	-	-	M N		М	
CLO-4			nensional problem <mark>s in pola</mark> r			2	85		Н	H		- -		-	-	-	-	-	M N		М	
CLO-5				r non circular cross-sections	Control of the Control	2	85	75	Н	H				-	-	-	-	-	M N		М	
CLO-6	: Accru	ie comprene	nsive knowledg <mark>e in theor</mark> y	of elasticity problems	ALC: NO PERSON NAMED IN	2	85	75	H	H	1 1	Η .	- -	-	-	-	-	-	$M \mid \mathcal{N}$	1 M	М	
Durati	on (hour)		9	9	9			_		9								9				
Durati	on (nour)		-	The second secon		_	-	Faus	tions of	•		nolar		Intr	oduct	ion to t		•	n-circ	ular		
S-1	SLO-1	Introduction	to Theory of Ela <mark>sticity</mark>	Introduction to equations of elasticity	Airy's stress function	's stress function					Equations of equilibrium in polar coordinates						Introduction to torsion of non-circular members					
	SLO-2		of stress & strain	Stress-strain relations	Biharmonic equation equations	3	Equations of equilibrium in polar coordinates						Sail	Saint-Venant's theory of torsion								
S-2	SLO-1	strain	ntions, notations fo <mark>r stress b</mark>	Lame's constant-cubical dilatation	Solutions by polynomials of se	cond de	egree	Stres	s-strain	relation	3			Gei	neral .	solutior	ns of t	orsior	n probl	ems		
3-2	SLO-2	Sign convers	ntions, notations for <mark>stre</mark> ss &	Lame's constant-cubical dilatation	Solutions by polynomials of se	cond de	egree.	Strail	г сотро	nents in	polar	coord	inates	s Gei	neral .	solutior	ns of t	orsion	n probl	ems		
S-3	SLO-1	Components		Compressibility of materials, Bulk Modulus	Solutions by polynomials of thi				n-displac							/ condi						
S-3	SLO-2	Generalized	l Hooke's Law	Solving problems	Solutions by polynomials of thi	rd degre	е		n-displac					Cor	nditior	is at th	e ena	of a t	wistea	bar		
S-4	SLO-1	Components	s of strain	Compatibility equations for plane stress with constant body force	Solutions by polynomials of fo	urth deg	gree		tions of linates.	compati	bility in	n pola	r	Sol	ving p	roblem	s					
3-4	SLO-2	Solving prob	blems	Compatibility equations for plane stress with general body force.	Solutions by polynomials of for	urth deg	ree		tions of linates.	compati	b <mark>ility i</mark> r	pola	r		olications	ons of s	shafts	of ell	iptical	cross	;-	
0.5	SLO-1	Stress at a p	point	Compatibility equations for plane strain with constant body force.	Solutions by polynomials of fift	h degre	ее	Solvi	ng <mark>pro</mark> bl	ems				Sol	ving p	roblem	s					
S-5	SLO-2	Boundary co	onditions	Compatibility equations for plane stress with general body force.	Solutions by polynomials of fift	h degre	е	Solvi	ng probl	ems				Sol	ving p	roblem	s					
0.0	SLO-1	Strain at a p	point	Principal stresses and strain	Stresses due to bending of a c	antile <mark>ve</mark>	r bean	Stres	s distrib	ution sy	nmetri	ical al	out a		olications	ons of s	shafts	of re	ctangu	lar cı	oss-	
S-6	SLO-2	Solving Pro	blems	Solving problems	Stresses due to bending of a c in Cartesian coordinate	antileve	r bean		s distrib	ution sy	nmetri	ical al	out a	n App		ons of s	shafts	of re	ctangu	lar cı	oss-	

Duration	on (hour)	9	9 9 9		9	9
0.7	SLO-1	Equations of equilibrium in 2D		Displacements due to bending of a cantilever beam in Cartesian coordinate	Stress distribution in pure bending of curved bars	Solving problems
S-7	SLO-2	Solving problems		Displacements due to bending of a cantilever beam in Cartesian coordinate	Stress distribution in pure bending of curved bars	Solving problems
S-8	SLO-1	Equations of equilibrium in 3D		Stresses due to bending of a simply supported beam in Cartesian coordinate	Stress distribution in rotating disc	Applications of shafts of equilateral cross- sections
3-0	SLO-2	Solving problems	Solving problems	Stresses due to bending of a simply supported beam in Cartesian coordinate	Stress distribution in rotating disc	Applications of shafts of equilateral cross- sections
S-9	SLO-1	Index notations for stress & strain		Displacements due to bending of a simply supported beam in Cartesian coordinate	Solving problems	Solving problems
3-9	SLO-2	Solving problems		Displacements due to bending of a simply supported beam in Cartesian coordinate	Solving problems	Solving problems

Learning	1.	Timoshenko, S.P and Goodier J.N., Theory of Elasticity, McGraw-Hill Education, Third Edidtion., 2017
Resources	2.	Enrico Voltorra and J.H.Caines, Advanced Strength of Materials, Prentice Hall, New Jersey 1991.

- Wang, C.T., Applied Elasticity, Mc-Graw-Hill Co., New York 1993
 Sokolnkoff, IS., Mthematical Theory of Elasticity, Mc-Graw-Hill Co., New York 1978.

Learning A	Assessment				Particular Property	11 N A 7						
	Dia ami'a		Continuous Learning Assessment (50% weightage)									
	Bloom's Level of Thinking	CLA – 1 (10%)		CLA -	2 (15%)	CLA – 3 (15%)		CLA – 4	· (10%)#	Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Laval 1	Remember	40.0/		30 %	100 C	30 %	11 S 11 11 11 11 11 11 11 11 11 11 11 11	30 %		30%		
Level 1	Understand	40 <mark>%</mark>		30 /		30 70	THE STATE OF	30 /0		30%	-	
Level 2	Apply	40 %		40 %	10.5	40 %		40 %		40%		
Level 2	Analyze	40 /0	_	40 /0		40 /0	ten in 10	40 /0	- I	40 /0	-	
Level 3	Evaluate	20 %		30 %		30 %	5-47	30 %		30%		
Level 3	Create	20 %		30 %	-	30 %	1000000	30 %		30%	-	
	Total	10	0 %	10	0 %	10	0 %	100) %	10	0 %	

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2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R.Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	2. Mr. S. Chandra Sekhar, SRMIST

Cour Cod	- 1	8ASE207T Course Name	FUNDAMENTALS OF COMBL	USTION	Course Categor	H	Professional E	lective
	Pre-requi	site Courses 18ASC102J, 18ASC103	ST Co-requisite Courses	Nil	Progre	essive Co	urses Nil	
		Department Aerospace Engineering		Data Book / Codes/Standards			erties table of C-H-N-O system	
Course	Learning	g Rationale (CLR): The purpose of lean	ning this course is to:	TINGE	Learr	ning	Program Le	earning Outcomes (PLO)
CLR-1			cy o <mark>f burning proces</mark> ses and about pollutant e	emissions.	1 2	3	1 2 3 4 5 6	7 8 9 10 11 12 13 14 15
CLR-2		ify the applications of basic thermal and fluid		The second second	ठ	ŧ	g)	
CLR-3	: Ident	ify the significance of material identification	or industrial applications, including burners a	and engines.	Level of Thinking (Bloom) Expected Proficiency	(%) Expected Attainment (%)	Engineering Khowledge Problem Analysis Design & Development Analysis, Design, Rassarch Modern Tool Usage	Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Einance Life Long Learning PSO - 1 PSO - 2 PSO - 3
CLR-4			gas turbines, controlled experimentation and	d computational combustion.	of Thinking n) sted Proficie	ttair	ing and Analysis nent Design, ool Usaç	tt & Tes Sarr
CLR-5 CLR-6		yze the principle of normal and microgravity	larnes for space activities and fire safety. I <mark>erstanding of system testing, validation and</mark>	docianina	d P	d A	An A	abilii Mgt Agt
CLN-0	. Othiz	e the combustion concepts for the broad unit	derstanding or system testing, validation and	designing.	l of	scte	wlec wlec lem gn d glob ysis ysis ern ern	ronm ss ss ss idua idua mun mun ect N ect
Course	Learning	Outcomes (CLO): At the end of this co	urse, learners will be able to:	S. W.	Level of (Bloom) Expecte	Exp.	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usag	Environment & Sustainability Ethics Individual & Team Mork Work Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3
CLO-1		erstand the combustion phenomenon and its		CHARLES THE PARTY OF	2 80	70	H M L L	
CLO-2		prehend the concept and applications of the			2 80		H M M M	L L - H M M M
CLO-3			nation, premixed and diffusion combustion p	roblems with applications.	2 80	70	H M L M	L H
CLO-4		erstand the chemical kinetics, c <mark>hain reac</mark> tions		And the state of	2 80		H M M	M M M M L H M M M
CLO-5			and Numerical modelling of combustion pro		2 80		H M M M L	L - L M L H M M M
CLO-6	: Unde	erstand normal and micrograv <mark>ity flames</mark> and	apply the knowledge to Aerospace Engineer	ing Applications.	2 80	70	H M M M L	L M L M L H M M M
Durati	on (hour)	9	9	9	7 E S		9	9
S-1		Basic Concepts: Ideal gases, mass and mole concept, fuel and oxidizer, basics of thermodynamics.	Combustion regimes and classification of combustible materials.	Introduction to Chemical kinetics, order and molecularity, Forward a Reactions.	nd Reverse	Flame cla	assification and structures.	Combustion in Normal and microgravity.
5-1	SLO-2	Various modes of combustion and their characteristics	Flammability limits- Flame stabilization and material identification systems.	Energy Release Rates in a Chemi Reaction, Concentration, Law of M Action, Arrhenius Law.	Mass flame velocityMethods of measuring p			Factors affecting heat transfer and flame propagation in normal and low gravity flames.
S-2	SLO-1	Combustion and thermo chemistry - Review of property relations.	Maxwell equation and parametric analysis of enthalpies and internal energy	Variations of Reaction Rate, Temp and Concentration in a Chemical I with Time.	perature Reaction Stability limits of laminar flames.			Fire safety, Soot formation and related implications.
3-2	SLO-2	Laws of thermodynamics-Reactant and product mixtures.	Phase transformation, Clausius Clapeyron equation and Gibbs-Helmholtz equation.	Rate of Reactions, Temperature of rate coefficients, Pressure deperate coefficients.		Flame pr mixtures.	opagation through combustible	Interactive session with demo on practical working of premixed gas burners and candle flames.
0.3		Solving Problems	Solving Problems	Solving Problems	THE P	Solving F		Solving Problems
S-3	SLO-2	Solving Problems	Solving Problems	Solving Problems		Solving F		Solving Problems
	SLO-1	Combustion Stoichiometry, Heat of Formation, Reaction, combustion.	Combustion products, Flow analysis and approaches.	Phase Rule for a System with Che Reactions. Thermodynamic Equili Constant for a Gaseous Reaction.	emical brium		ion <mark>to diffusion</mark> flames; a <mark>ce, structu</mark> re, theoretical ations.	Comparison of normal and microgravity experiments.
S-4	SLO-2	Lower Calorific Value (LCV) and Higher Calorific Value (HCV), Relationships between Calorific Values, Reaction Enthalpies and Formation Enthalpies	Partial differential equations for combustion analysis.	Chain Reactions and Methods of Chemical Kinetic Rate Equations.	Solving		n convective atmospheres and spontaneous ignition.	Flame spread over thin fuels in actual and simulated microgravity conditions.
S-5	SLO-1	Thermochemical calculations: Enthalpies, Internal energy, Entropy.	Vectors and conservation equations for energy and momentum.	Solving Problems		Solving F	Problems	Solving Problems

Duratio	on (hour)	9	9	9	9	9
	SLO-2	Chemical reaction and Stoichiometric coefficients, Air-Fuel ratio, Equivalence ratio.	Application of Mass Energy and species Conservation.	Solving Problems	Solving Problems	Solving Problems
S-6	SLO-1	Calculation of Energy Release for Stoichiometric, oxidizer-rich and fuel rich Explosives.	Solving Problems	Introduction to diffusion mass transfer.	Image processing and combustion experimentation science.	Environnemental combustion considérations.
	SLO-2	Adiabatic flame temperature calculations: Analysis and practical considerations.	Solving Problems	Transport properties for gas mixtures.	Introduction to computational combustion and relevance.	Combustion, heat transfer and emission in industrial applications.
S-7	SLO-1	Chemical equilibrium, volumetric and gravimetric analysis.	Emission reduction and techniques in combustion instruments.	Mass transfer laws, Fick's law of Diffusion.	Numerical modeling of flame spreading phenomenon	Fire safety aspects of combustion sciences.
5-1	SLO-2	Dissociation process and related issues.	Aerospace Engineering Applications of fundamental combustion physics.	Available and non-available energy of a source and finite body.	Numerical modeling of combustion processes.	Prospects in Aerospace propulsion and combustion.
S-8	SLO-1	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
3-0	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
S-9	SLO-1	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.
3-9	SLO-2	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.

	1. Stephen R. Turns, "An Introduction to Combustion: Concepts and Applications", 3rd Edition,	4. H.S. Mukunda., "Understanding Combustion", Universities Press, Second edition 2009.
Learning	McGraw-Hill Education <mark>, 2011.</mark>	5. Anil W. Date., "Analytic Combustion: With Thermodynamics, Chemical Kinetics and Mass Transfer",
Resources	2. Kenneth K Kuo, "Principles of Combustion", 2nd Edition, John Wiley and Sons, 2005.	Cambridge University Press, 2011.
	3. D. P. Mishra., "Fundamentals of Combustion", Prentice Hall of India, New Delhi, 2008.	6. Irvin Glassman and Richard A. Yetter., "Combustion", 4th Edition, Elsevier, 2008.

Learning As	ssessment											
_	Bloom's			Contin	uous Learning Asse	essment (50% weigh	ntage)			Final Evaminatio	n /FO0/ weightege)	
	Level of Thinking	CLA – 1 (10%)		CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	1 (10 <mark>%)#</mark>	Final Examination (50% weightage)		
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	40%		30%		30%		30%		30%		
Level I	Understand	40%		30%		3076	-	30%		3070	-	
Level 2	Apply	40%	PEALS	40%	- 11/	20%	20%	20%	20%	40%		
Level 2	Analyze	40 /0		40 / 0		2070	2070	2078	2070	40 /0	-	
Level 3	Evaluate	20%		30%		30%	10.0	30%		30%		
Level 3	Create	2070		3070		3070		3070	-	30 /0	-	
	Total	10	<mark>0 % ===================================</mark>	100	%	100) %	100	0 %	10	00 %	

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Vinay Kumar Gupta, National Physical Laboratory, guptavinay@nplindia.org	1. Prof. D.P. Mishra, IIT Kanpur, mishra@ iitk.ac.in. (NPTEL- Fundamentals of Combustion)	1. Dr. T. Selvakumaran, SRMIST
2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Prof. Amit Kumar, IIT Madras, Chennai, amitk@ae.iitm.ac.in.	2. Dr. Pankaj Kumar, SRMIST

Cou		18ASE208T	Course Name	HEAT TRANS	FER		Co	ourse C	Category	Е			Profes	siona	l Electiv	е		L 3	T 0	P C 0 3
Course		uisite Courses Department	18ASC102J, 18ASC Aerospace	103T Co-requisite Co	ourses	Nil Data Book / Codes/Standards			sive Cour lass Tran				edition l	ру С І	P Kotha	ndaran	nan, S	Subrai	manya	1
Course CLR-1		Rationale (CLR):	The purpose of le	arning this course is to:	4	Allanda de	1	Learni 2	ing 3	1	2	3		am Le	arning (10 1	3 14 15
CLR-1			ept of amerem modes or ept of conduction in plan				-				2	3	4 (0	'	0	יו פ	9 11	12 1	0 14 10
CLR-3			ation of extended surface					Expected Proficiency	(%) Expected Attainment (%)		(A)		. 8	200		ء	:	Finance	б	
CLR-4				nd it various applications		S-ALLE-	king	Ofici	ainr		lysi			Culture	જ ્	9	5	ᇹᄬ	Learning	
CLR-5			ept of Radiationmod <mark>e an</mark>	<mark>d it va</mark> rious applications		CONT. THE	Thinking	Pro	Att	Engineering Knowledge	Problem Analysis	Development	Analysis, Design, Research Modern Tool Head	3 3	Environment & Sustainability	Ethics Individual & Team	Work	gt.	Le	
CLR-6	To so	olve the heat trans	fer practical probl <mark>ems</mark>		_		b 2	cted	cted	led	em.	x Ldo	Analysis, Research Modorn T	Society &	onm	w = =		Project Mgt.	Long	-2 -2
C	1	· Outoomoo (CLO)	. At the and of this	anne le amere vill be able to			evel of	(Bloom) Expecte	Exper (%)	ngi	qo.	esig	ese:	Scie	oviro Jesta	Ethics	Work	je je	Life L	PSO
CLO-1		Outcomes (CLO)	iffusion equation under o	course, learners will be able to:	-	PERSONAL PROPERTY OF	2	80 日 日 日 日 日 日 日 日 日 日 日 日 日 日 日 日 日 日 日		H T	H	A A	₹ ₾ ≥	Š	ய் ல	ᄪ	: ≥ €		M N	
CLO-2				site walls and cylindrical objects			2	85		Н	Н	Н			-	-			M N	
CLO-3				face or fin needed for heat transfer		4	2	75		Н	Н	Н			-	-	- -		M F	
CLO-4				tion & natural convection	777	100	2	85		Н	Н	Н			-	-		_	M N	
CLO-5			fer rate in Radiation mod			CANCEL TO PORT AND ADDRESS OF	2	85		Н	Н	Н			-	-	- -	-	L N	
CLO-6		olve the heat trans	fer practica <mark>l problem</mark> s				3	80		Н	Н		Н -	-	М	-	- -	-	L N	I M H
				A STATE OF THE STA		CAN DE LA CONTRACTOR DE	W.		1000											
Duratio	n (hour)		9	9		9		141			9							9		
S-1	SLO-1	Introduction to modes of heat principles	heat tran <mark>sfer, Diff</mark> ere transfer <mark>and ge</mark> ner	nt Conduction with Thermal E Generation – Plane wall systems	nergy	physical mechanism on convectio	on,		aminar co lows betw				fer <mark>ana</mark> l	y <mark>sis</mark> in	Radiat Stefan Displa	Boltzn	ann la	es, Blac w, Plar	k body ick'sla	radiation- w& Wein's
	SLO-2	Solving problems		Solving problems		classification of fluid flows,			Solving pr						Solving	g proble	ems			
S-2	SLO-1	equation Cartesia		Generation – composite Plane wall	nergy	Governing equation: Continuity ed	quatio		urbulent I flows be					alysis	Radiat	ion inte	nsity			
3-2	SLO-2	Derivation	uation Cartesia <mark>n systems</mark>	Solving Problems	(Governin <mark>g equation: Momentum L</mark>	Equati	ion S	Solving pr	oblems		м			Solving	g proble	ems			
S-3	SLO-1	systems	equation forCy <mark>lindric</mark>	Generation –radial systems	nergy	Governing equation: Energy Equa	ation		amin <mark>a</mark> r co lows over			t t <mark>rans</mark> :	f <mark>er an</mark> al	ysis in	Radiat	ion pro	perties	s, kirch	off's la	N
3-3	SLO-2	Heat diffusion systems - Derivat	equation for Cylin <mark>dric</mark> ion	Solving problems	0	Governing equation: Energy Equa	ation	S	Solving pr	oblems					Solving	g proble	ems			
S-4	SLO-1	Heat diffusion systems	equation for Spheric	al Conduction with Thermal El Generation – composite radial system	nergy ns	velocity and thermal boundary lay	er		urbulent n flows ov				nsfer ar	alysis	. Radia	ation sh	ape F	actors	& Its re	lations
3-4	SLO-2	Heat diffusion systems - Derivat	equation for Spheric ion	Solving problems	ŀ	Rayleigh number &Grashoff numb	ber	S	Solving pr	<mark>oble</mark> ms					Solving	g proble	ems			
S-5	SLO-1	One-Dimensional Conduction – plan		Heat Transfer from Extended Surfactive Rectangular circumferential Fin. Uniform Cross-Sectional Area, Performance, Overall Surface Efficien	s of E	Empirical Correlations: Exterr Convection Flows over a v horizontal flat plate			aminar co lows over				fer anal	ysis in	Conce betwee				-Heat	Exchange
	SLO-2	Solving Problems		Solving problems		Solving Problems		S	Solving pr	oblems					Solving	g proble	ems			

Duratio	n (hour)	9	9	9	9	9
S-6	SI ()-1 I	One-Dimensional, Steady-State Conduction – composite walls	Heat Transfer from Extended Surfaces – Cylindrical Fins of Uniform Cross-Sectional Area, Fin Performance, Overall Surface Efficiency	Empirical Correlations: External Free Convection Flows over a Inclined flat plate	turbulerit convective neat transfer analysis	Radiation Heat Transfer in a grey surfaces - Net Radiation Heat Transfer between Any Two Surfaces
	SLO-2	Solving Problems	Solving problems			Solving problems
S-7	SI ()_1 I				Laminar convective heat transfer analysis in flows in a circular pipe	Radiation Heat Transfer in Two-Surface Enclosures
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving problems	Solving problems
S-8	SI ()_1 I		Transient Conduction - Large walls & long cylinders	Empirical Correlations: External Free Convection Flows over a horizontal cylinder	turbulent conve <mark>ctive heat tr</mark> ansfer analysis in flows in a circular pipe	Radiation Heat Transfer in Three-Surface Enclosures
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving problems	Solving problems
S-9	SLO-1	One-Dimensional, Steady-State Conduction – Radial & Spherical systems for Composite		Empirical Correlations: External Free Convection Flows over a Sphere	Laminar &turbulent convective heat transfer analysis in flows in a non-c <mark>ircular pipe</mark>	Radiation shields
	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving problems	Solving problems

Learning	1.	Yunus A. Cengel&Afs <mark>hin J. Gha</mark> jar, "Heat & Mass Transfer", fifth Edition,McGraw-Hill, 2014 Theodore L. Bergman , Adrienne S. Lavine , Frank P. Incropera , David P. DeWitt, "Fundamentals 3. John H Lienhard, "A Heat Transfer Text Book", Dover publications inc, New York, 2011.
Resources	۷.	of Heat and Mass Transfer", seventh Edition, John Wiley and Sons, New York, 2011

Learning A	Assessment			200	10 10 mg			69				
	Bloom's			Conti	nuous Learning Ass	sessment (50% weig	htage)			Final Evamination	n (E00/ weightege)	
	Level of Thinking	CLA – 1 (10%)		CLA – 2 (15%)		CLA -	3 (15%)	CLA – 4	l (10%)#	Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	- 40 <mark>%</mark>	1	30%		30%	3.7	30%		30%	-	
Level 2	Apply Analyze	40 <mark>%</mark>	153	40%		40%	-	40%	-	40%	-	
Level 3	Evaluate Create	20%	1	30%	-	30%	- 19	30%		30%	-	
	Total	10	0 %	100	0 %	10	00 %	100	0 %	10	0 %	

[#]CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	ANALY THERE EDGES AS	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr Raja Samikkannu, Senior Principal Scientist at National Aerospace Laboratories	1.Dr.K.M.Parammasivam,Professor,, MIT, Chennai, Email Id:mparams@annauniv.edu	1. Mr. K.B.Ravichandrakumar,SRMIST

	Course Code 18ASE209T Course Name THEORY OF FIRE PROPAGATION AND SAFETY						Е			Pr	ofessio	onal I	Electi	ive			L 3	T 0	P C 0 3
	Pre-requ	uisite Courses 18ASC102J, 18ASC103	T Co-requisite Courses Nil		Pro	ogress	sive Cou	irses	Nil										
Course	Offering	Department Aerospace Engineering	Data Book / C	odes/Standards															
Course	Lagraina	Rationale (CLR): The purpose of learning	y this source is to	H M /		Loorn	nin a				D		n l oc	unina Ou	toomoo	· /DL /	2)		
CLR-1		g Rationale (CLR): The purpose of learning tify the fire dynamics, the burning processes and			1	Learn 2	3	1	2	3	4	ogran 5	6	arning Ou		10	J) 11	12 13	14 15
CLR-2		tify the life dynamics, the burning processes and tify the engineering applications of basic che <mark>mic</mark> a					1 -		J		J		1 0	3	10		12 10	14 13	
CLR-3		tify the significance of material identificatio <mark>n for i</mark>		engines.		enc)	lent					ge	4		_			g	
CLR-4		te insights to the fires in engines, buildings, fore			Thinking	Expected Proficiency	Expected Attainment (%)		Problem Analysis		Analysis, Design, Research	Modern Tool Usage	Society & Culture	ං ජ	Individual & Team Work	5	∞ŏ	Life Long Learning PSO - 1	
CLR-5	: Analy	yze the fire related hazards in practica <mark>l, function</mark>	al, engineering, industrial applications.	THE REAL PROPERTY.	in	Pro	Atts	g a	hal	Design & Development	Des	00	3	Environment & Sustainability Ethics	~× _	Communication	Project Mgt. & Finance	Lea	
CLR-6	: Utiliz	e the fire safety principles for syste <mark>m testing, v</mark> a	lidation and designing.		of T	ted	ted	Engineering	m /	Design & Deve <mark>lopm</mark>	Analysis, [Research	L u.	∞ >-	nap	lna	ī	je je	1	-2
				5 19 Y	evel of	be /	bec (gine	ple	sign	alys	oder	ciet	Enviro Sustail Ethics	를 못	шu	Project N Finance	Life Long PSO - 1	PSO -
_			e, learners will be able to:		9 8	Щè	<u> ೫ ೫ ೯</u>				A S	Mc	တ	回る苗	2 ≥	ပိ	ᇍᇤ		8 8
CLO-1		erstand fire phenomenon, its app <mark>lications a</mark> nd sa			2	80	70	Н	М	L	L	-	-		-	-	-	Н -	
CLO-2		prehend the concept and applic <mark>ations of</mark> energy neering advancement.	conservation in fires utilizations and apply to	he same for recent	2	80	70	Н	М	М	М	-	-	L -	-	L	-	Н М	M M
CLO-3		erstand basic knowledge to th <mark>e physical</mark> principle	es governing fire growth.		2	80	70	Н	М	L	М	-	-		L	-	-	Н -	
CLO-4	: Unde	erstand the behavior and che <mark>mical react</mark> ions rela	ited.	AND WARRY	2	80		Н	М	М	М	•	-	M M	М	Μ	L	H M	
CLO-5		y the latest engineering capa <mark>bility in fir</mark> e detectio			2	80		Н	М	М	М	М	L	L -	L	М	L	H M	
CLO-6	: Unde	erstanding prospects of norm <mark>al and mi</mark> crogravity	fire safety for Aerospace Engineering Applie	cations.	2	80	70	H	М	М	М	М	L	L M	L	Μ	L	$H \mid M$	M M
Durati	on (hour)	9	9	9					т	9							9		
S-1	SLO-1	Introduction to Fire Science, fires in history, fire losses, fire and combustion.	Importance of fire dynamics on a fire strategy.	Development and behavior propagation in free and con atmosphere.	of fire fined	ü		Identifying fire spread hazards and risks.					Active and Passive Fire Protection Features.						
3-1	SLO-2	Relevant material properties, combustion and heat transfer.	Fundamentals of heat and mass transfer for fire, smoke production and transport.	Factors affecting fire growth).		dev	ety and a	safe v	vork sy	stems			Fire prev flammab liquids/fu	le and	comb	oustible		ng
S-2	SLO-1	Chemistry and classification of fires- Composition of Combustion- (Flame, heat, fire gases, smoke).	Fundamentals of ignition and flame propagation.	Buoyant Plumes, Combusti Starting plume.	ng Plun	nes,	Ехр	oduction losion h ctrical ur	azaro			al,		Eliminati	on of ig	gnitioi	n sourc	ces.	
	SLO-2	Review of Thermodynamics and Fluid Mechanics in fire behavior	Role of Material flammability in fire propagation.	Fireball, Transient Aspects	of Fire	Plume		te Real						Fire prot walls, fire	e doors	S	nts an	d factoi	ies, Fire
S-3		Solving Problems	Solving Problems	Solving Problems		233		ving Pro						Solving I					
SLO-2 Solving Problems Solving Problems Solving Problems								ving Pro						Solving I					
	SLO-1	Heat and mass transfer. Relevance of fire classification and governing dynamics.	Parameters affecting ignition, flame spread.	Fire spread over liquid and surfaces.	solid fu	iel		haz <mark>ard</mark> ctivity (s			mmab	ility-		Fire prev Microgra				n featui	es,
S-4	SLO-2	Material Flammability principles, Thermal Ignition.	Heat release rate and flame extinction phenomenon. Explosions and fires –fundamental	Enclosure fires, Incineration).		Air	contamii gases.			-toxic	effec	ts of	Fire supposprinkler	oressio	n. Fix	ced au		lesign.
S-5	SLO-1	Sources of ignition of combustible materials.	Solving Problems			Solv	ving Pro	blems	5				Solving I	Probler	ns				
SLO-2 Application of Mass Energy and species Egress– principles and calculations. Solving Problems				Solving Problems	Solving Problems Solving Problems														

Duration (hour)		9	9	9	9	9
	SLO-1	Rate of burning. Heat transfer from Flames- Ignition temperature.	Solving Problems	Forest fires Analysis of fire plumes.	Smoldering combustion science.	Environnemental fire propagation considérations.
S-6	SLO-2	Flash point, Fire point, Flash over.	Solving Problems	Fire safety aspects of plumes.	Introduction to smoke formation, composition and movement, hazards.	Role of combustion detectors (Fire detection, smoke detection, types of ionization-photo electric-light intensity-scattered light detectors.
	SLO-1 Components and objectives of a fire safety strategy.		Fire safety techniques in combustion instruments.	Standardized material flammability testing.	Essential conditions for explosion occurrence.	Heat detectors. Flame detectors -infra redetector - ultraviolet flame detector).
S-7	SLO-2	Fire dynamics process and related issues.	Aerospace Engineering Applications of fire dynamics.		Explosion characteristics and Prevention.	Portable fire Extinguishers-Types- extinguisher-location, Inspection–testing principles and calculations.
S-8	SLO-1	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
3-8	SLO-2	Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
S-9	SLO-1	Chapter Doubt clarification.		Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.
J-9	SLO-2	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.	Chapter Doubt clarification.

	1.	James G. Quintiere, "Fundamentals of Fire Phenomena", 2006 Wiley.
Learning	2.	Dougal Drysdale, "An Introduction to Fire Dynamics", 2011 Wiley.
Resources	3.	Akhil Kumar Das., "Principles of Fire Safety Engineering: Understanding Fire and Fire Protection",
		Prentice Hall of India New Delhi 2014

- R.S. Gupta., "A Hand Book of Fire Technology", Second edition, Modern press, 2005. V, K, Jain, "Fire safety in buildings", New age international publisher, 2006. Niamh Nic Daeid., "Fire Investigation", CRC Press, 2004.

Learning A	Assessment			20 /50 PV	Kennya Managaran	11								
	Bloom's			Contin	uous Learning Asse	ssment (50% weight	age)	AN		Final Examination (50% weightage				
	Level of Thinking	CLA - 1	(10%)	CLA –	2 (15%)	CLA – 3	3 (15%)	CLA – 4	(10% <mark>)#</mark>	Filiai Examination	i (50% weightage)			
	Level of Trilliking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	40%		30%		30%	1.00	30%		30%				
Level I	Understand	40%	100	30%		30%		30%		30%	-			
Level 2	Apply	40%		40%		40%		40%		40%				
Level 2	Analyze	40 /0	754	40 /0	-	40 //	=	40 /0		40 /0	=			
Level 3	Evaluate	20%		30%		30%		30%		30%				
Level 3	Create	20 /0		30 /6		30 /6	10.4	30 /6		30 /6	-			
	Total	100 %		100	0 %	100) %	100) %	100 %				

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Vinay Kumar Gupta, National Physical Laboratory, guptavinay@nplindia.org	1. Prof. Raghavan, V., IIT Madras, Chennai, raghavan@iitm.ac.in.	1.Dr. T. Selvakumaran, SRMIST
	2. Prof. Amit Kumar, IIT Madras, Chennai, amitk@ae.iitm.ac.in.	2.Mr. Vinayak Malhotra, SRMIST

Cou Co	118	ASE210T Course Name		AIRFRAME MAINTENANCE AND REP	AIR	_	ourse ategory	y	Е			Pr	ofessi	onal Elec	ctive				T 0	P 0	C 3
	Pre-regu	uisite Courses	Nil	Co-requisite Courses Nil		F	rogre	ssive C	ourses	ı	Nil										
Course	e Offering	Department	Aerospace Engin		/ Codes/Standards	Nil															
			1=-	1,44	THE WAY																
		Rationale (CLR):		arning this course is to:	112 11 11 11 11 11	L	.earnir		Program Learning Outcomes (PLO)							40 4	0 4 4	1 45			
CLR-1				ss to be used in aircraft.		1	2	3	1	2	3	4	5	6 7	8	9	10	11	12 1	3 14	15
CLR-2		rm Plastic and Comp out Assembly & Rigg		ir i <mark>n Aircraft Stru</mark> ctures			Cy	ent					e e								
CLR-3				jor and auxiliary systems	1000	ng	ciel	Ē		Sis		gu,	Tool Usage	Culture ent &		Team	_		ij.		
CLR-5		ify the various hazard			CONTRACTOR OF THE PARTY OF THE	Thinking	rofi	\ttai	σ.	Jaly	ij	esi	ol C	# 2	<u> </u>	Ϋ́	aţi	<u>~</u> خ	ear		
CLR-6				maintenance activities on aircraft structure.		Ę.	ğ L	pg pg	Prin a	٦Ā	S E	ر ال	은 <u>;</u>	s le le		al 8	i.	Mg.	J G		, e
3211	. Journe	c c momoago dog	a ca for ropan and f	Tantonano donvinos on anoram cardotaro.	THE PARTY OF	Level of	Expected Proficiency	Expected Attainment (%)	Engineering	Problem Analysis	Design & Development	Analysis, D <mark>esign,</mark> Res <mark>earch</mark>	Modern	Society & Cultur Environment &	8	ndividual & Nork	Communication	Project Mgt. & Finance	Life Long Learning)-2	·
Course	e Learning	Outcomes (CLO):	At the end of this	course, learners will be able to:	CONTRACT THE	-eve	XX 8	XX %	gi d	jo l	Dev	Ana Res	Mod	in Vi	Ethics	Individ Work	Sol	Poj Fina	Life L	PSO	PSO
				al repair operations and maintenance practices	in aviation industry	2	80	70	Н	-	М	L	M	 	, ш		-		L	. М	
CLO-2				rocedures on plastics and composite structures		2	80	70	Н	-	М	L	M		-	-	-	-	- 1	1 M	1 M
CLO-3	: Unde	rstand the Assembly	& Riggin <mark>g procedu</mark> r	es and operation of Aircraft flight controls.	and the state of t	2	80	70	Н	-	L	L	М		-	М	-	-	LA	1 M	1 M
CLO-4	: Learn	the inspection and i	maintena <mark>nce of ma</mark> jo	or and auxiliary systems	the Reports	2	80	70	Н	-	L	L	М	- M	М	-	-	-	L	1 M	
CLO-5				afety, Inventory Procedures & Troubleshooting	g practices	2	80	70	Н	L	L	L	М		-	-	М	-	L F		
CLO-6	: Acqui	ire comprehensive kı	nowledg <mark>e onairfra</mark> me	e maintenance and repair.	Market 15	2	80	70	Н	L	L	L	М	- M	М	М	М	-	L	1 M	1 M
Durati	on (hour)		9	9	0			-				9						9			
Durati	, ,		•	Applications & Advantages of Plastics used	Introduction to Aircraft Asse	mhly a	nd Ric	aaina			-										
S-1	SLO-1	Introduction to Aircr	aft Weld <mark>ing</mark>	in Aircraft.	operations.	mory c	irra rug	99"'9	Insped	ction c	of Land	ing Ge	ar Sys	tem	Intro	oductio	n to F	lazard	ous Ma	terials	3
	SLO-2	Nomenclature & Ty	pes.of W <mark>elding</mark>	Classification & Types of Plastics	Rigging Specifications				Mainte	enanc	e of La	nding (Ge <mark>ar S</mark>	System	Types						
S-2	SLO-1	Equipments used in	7 11 1	Identification of Clear Plastics	Aircraft Leveling Procedure				Insped	ction c	of Air - o	conditio	oning (S <mark>yste</mark> m	Flammables - Handling, Storage & Emergency Procedure						
3-2	SLO-2	Need for Maintenan Equipments	ce of Weldi <mark>ng</mark>	Storage and Protection, Cutting, & Drilling of Plastics	Assembly <mark>of Maj</mark> or Structure	al Com	ponen	nts	Mainte	enanc	e of Air	- cond	litionin	<mark>g S</mark> yster	'' Em	rosives ergency	/ Prod	cedure			
S-3	SLO-1	Maintenance of We	Idina Equipmento	Forming of Plastics.	Assembly of Movable Contr	ol Surl	aces		Insped	ction c	of Press	suri <mark>zati</mark>	on Sy:	stem		ins ℜ merger				, Stor	age
3-3	SLO-2			Cementing, Annealing & Cleaning of Plastics	Fixed Surface Alignment – S	Symme	etry Ch	neck	Mainte	enanc	e of Pre	essuriz	ation	System	1 -	sical &		•			
SLO-1 Characteristics of a good weld & Installation of Plastic Windows and Windshields					Demonstration of Symmetry	Chec	k in Ce	essna	Insped	ction c	of Aircra	aft Insti	rumen	ts		ndling, S cedure		ge & E	merger	ісу	
S-4	SLO-2	Introduction to Non- Process - Soldering	fusion Welding	Inspection of Plastic Components	Aircraft				Mainte	enanc	e of Air	craft Ir	strum	ents	Sta	na's Ha ndards				catior	1
S-5	SLO-1 Requirements & Process Repair of Cracks in Plastics.			Effects of Rigging on Flight						<mark>nstru</mark> me				Material Safety Data Sheet							
S-0	SLO-2	Advantages & Disadvantages. Repair of Holes in Plastics.			Checking & Adjusting Dihea	Iral an	gle.		Handl	ing of	Instrun	nents			Inve	entory &	& Lab	eling			
2.6	SLO-1 Classification of Damage Introduction to Advanced Composites in Aircraft.				Checking & Adjusting Incide	cidence angle. Inspection of Fire Protection Systems				Introduction to Troubleshooting Theory											
SLO-2 Damage Investigation Advantages of Composites over Metals in Aerospace Applications				Alignment Check of Empeni	nage			Mainte	enanc	e of Fir	e Prote	ection	Systems	ems Types							

Duration (hour)			9	9	9	9
	SLO-1	Repair Layout Techniques	Equipments used in Composite Fabrication	Alignment Check of Wings	Inspection of Ice Protection Systems	Troubleshooting with Chart
S-7	SLO-2	Repair Practices	Wet Layup Process of Building Composite Parts.	Alignment Check of Engines.	Maintenance of Ice Protection Systems	Examples
S-8 SLO-1		Introduction to Riveting Process in Aviation Industry.	1Parts	Demonstration of various checks in Cessna	Inspection of Water & Waste Systems	Troubleshooting without chart
	SLO-2	Types & Nomenclature of Rivets	Repair of Composite Components	- Aircraft	Maintenance of Water & Waste Systems	Examples
S-9	SLO-1	Equipments used for Riveting	Special Precautions	Need for Balancing Control Surfaces		Troubleshooting intermittent discrepancies
		Installation of Rivets	NDT methods in Composite Materials.	Procedure for Balancing Control Surfaces	Maintenance of Position & Warning Systems	Examples

Loorning	1. Michael J.Kroes, William A.Watkins ad Frank Delp, Aircraft Maintenance and Repair, 7th ed., Tata McGraw Hill, 2013	3. Larry Reithmeir., Aircraft Repair Manual, Palamar Books, Marquette, 1992.
Learning	2. Aviation Maintenance Technician Handbook – Airframe, Vol.1, 2, U.S.Dept. of Transportation, Federal Aviation	4. Civil Aircarft Inspection Procedures Part I & II, CAA, English Book House, New Delhi
Resources	Administration, Flight Standards Service, 2012	1986.

Learning .	Assessment				Control of the Control	- 17 / T- 32 /	V. /							
_	Dia ami'a			Conti	nuous Learning Asse	essment (50% weigl	ntage)			Final Examination (50% weightage)				
	Bloom's	CLA – 1 (10%)		CLA –	2 (15%)	CLA -	3 (15%)	CLA – 4	l (10 <mark>%)#</mark>	Final Examination (50 % weightage)				
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember Understand	- 40 <mark>%</mark>	3	30 %		30 %		30 %	-	30%	-			
Level 2	Apply Analyze	- 4 <mark>0 %</mark>	-	40 %		40 %	115	40 %	-	40%	-			
Level 3	Evaluate Create	- 20 <mark>%</mark>		30 %	Min C	30 %	2-1-13	30 %	-	30%	-			
	Total	10	0 %	100	0 %	10	0 %	100	0 %	10	0 %			

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	The state of the s	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Wg.CdrK.Manoharan (Retd), Blue Dart Aviation Ltd., manoharank@bluedart.com	1. Dr. A. P. Haran, Park College of Engineering & Technology, ap_haran@rediffmail.com	1. Dr. S. Sivakumar, SRMIST
2.Mr.K.Senthilkumar,Deputy Chief Aircraft Engineer, Air India , Bangalore ks_senthilkumar@yahoo.co	2. Dr.Wg.Cdr.N.Muthusamy, Rajalakshmi Engineering college, Chennai, muthusamy55@gmail.com	2. Mr. G. Mahendra Perumal, SRMIST

Course Code 18ASE211T Course Name AIRBORNE SENSORS AND ACTUATORS					E			Р	rofess	sional E	Elective	!			<u>L</u>	T 0	P 0	C 3
Pre-requisite Courses Nil	Co-requisite Courses Nil		Pı	ogress	sive Co	urses		Nil										
Course Offering Department Aerospace Engin		ta Book / Codes/Standards Nil		Ĭ				"										
Course Learning Rationale (CLR): The purpose of	earning this course is to:	THE WAY	L	earnir	ng				Pro	ogram	Learnir	ıg Ou	tcomes	s (PL	O)			
CLR-1: Understand the advanced concepts in airbo							2	3		5 6		8	9			12 1	3 14	15
CLR-2: Provide mathematical knowledge for modell	ng			Expected Proficiency	Ħ					a)								
CLR-3: Understand the aircraft actuation systems			D	ien	me		<u>.v</u>		Ć.	gg	د		E			<u>ng</u>		
CLR-4: Understand the servo components			Thinking	olic	tain		alys		Design,	$ \tilde{z} $	<u>∞</u> ×	>	Team	tion	⋖	Learning		
CLR-5: Learn the modeling of sensors and actuator			星	P.	A	Engineering Knowledge	An	ner	۾ ر	8 2			≪	ica	∕lgt.	_		
CLR-6: To solve problems in avionics engineering			<u>ع</u> و	cte	ctec	leel /led	em	S us	/sis	E \$	onn	S	enp	Jur	ct N	Long	- 2	
Course Learning Outcomes (CLO): At the end of the	is course, learners will be able to:	The state of the s	Level of (Bloom)	x be	Expected Attainment (%)	Engineer	Problem Analysis	Design & Development	Analysis, I Resea <mark>rch</mark>	Modern Tool Usage	Environment &	Sustairiability Ethics	Individual & Mork	Communication	Project Mgt. & Finance	Life L	PSO	PSO
CLO-1: Describe the concepts of airborne sensors a		DIFFE OF THE REAL PROPERTY.	2	<u>в ше</u> 85	75	H	٠.		<u>-</u>	2 0	э ш с	о ш	<u>-</u> ≤	- 0	Ч.		<u>.</u> М	
CLO-2: To apply mathematical knowledge in model		TOP TO THE PARTY OF THE PARTY O	2	85	75	Н	Н	Н	_		_	-	_	-	-	- /		
CLO-3 : Describe the aircraft actuation systems		The second second	2	85	75	Н		Н	Н		-	-	-	-	-	- 1	· M	
CLO-4: Describe the servo components		the death of the second	2	85	75	Н	Н		-	Н -	-	-	-	-	-	- /	1 M	М
CLO-5: Model the sensors and actuators	The second second	Mary Residence	-2	85	75	Н	- 1	Н	-	Н -	-	-	-	-	-	- /	1 M	М
CLO-6: Solve problems in avionics engineering		CONTRACTOR OF THE PARTY OF THE	2	85	75	Н	Н	Н	Н	Н -	-	-	-	-	•	- 1	1 M	М
Duration (hour) 9	9	9					1	9							9			
S-1 SLO-1 Introduction to aircraft actuation system	ns Servo Actuators	Linear and non linear actuation	systen	าร	Gyrosc	ope prin	ciples				Те	sting	philoso	ophie	S			
S-2 SLO-1 Introduction to aircraft actuation system	Linear Servo Actuators and types	Modeling of actuation systems	7		Gyro e	quation	1				Te	sting	protoc	ols				
S-3 SLO-1 Principles of aircraft actuation systems	Rotary Servo Actuators and types	Modeling of actuation systems			Rate gy	ro an <mark>d</mark> i	ntegra	ation			Te	sting	proces	SS				
S-4 SLO-1 Hardware elements for the actu	Servo vaives	Servo loop analysis		,	Free gy	ro, Verti	cal ar	nd dire	ctiona	l gyro	So	lenoi	d voltm	neter,	wheat	stone	oridge	
S-5 SLO-1 Functional block diagram of the actual SLO-2 systems	Servo loop analysis		ı	Inertial	navigati	on				EΛ	1F me	eter, ele	ectroi	meter				
S-6 SLO-1 Types of actuation systems	Actuator design			Basic p	rinciples	theo	ry and	applic	ations	Sig	gnal g	enerat	tors					
S-7 SLO-1 Electromagnetic actuators	Testing methodologies	Accelerometer- principle and theory Pe				Performance testing of sensors												
S-8 SLO-1 Electric motors	Performance testing		Spring, mass, force balance Data evaluation															
S-9 SLO-1 Slo-2 Solenoid actuators	Test equipment for actuation sy	/stems		Piezoe sensor	ectric e	ccele	romete	er an	d ME	MS Ca	Calculation of performance parameters				3			

Learning Resources	2.	James Ephraim Johnson, Electro hydraulic servo systems, hydraulics <mark>an</mark> Pallett, EHJ, Aircraft instruments, principles and applicati <mark>ons, pitman pub</mark>
Resources		Neal F wood et al. Flectromechanical actuation development AFFDI -TR

- and pneumatic magazines, 1984 ublishers, London, 1981
- TR-150. Dec 1978

- Alan S Moris, Measurement and instrumentation principles, Third edition, 2001
- J Jaidev vyas et al, Electro hydraulic actuation systems: Design testing, Identification and validation, 2019
- Oing Guo, Non linera control techniques for electro hydraulic actuators, 2017

	Bloom's			Cont	inuous Learning Ass	essment (50% weig	htage)			Final Examination (50% weightage)		
		CLA –	1 (10%)	CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4	4 (10%)#	Final Examination	1 (50% weightage)	
	Level of Thinking Remember Understand	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1		40 %	A	30 %	- ya	30 %	Z	30 %	-	30%	-	
Level 2	Apply Analyze	40 %	200	40 %	AE AL	40 %		40 %	-	40%	-	
Level 3	Evaluate Create	20 %	~~	30 %	F 33.	30 %		30 %	-	30%	-	
	Total	100	0 %	10	0 %	10	0 %	10	0 %	10	0 %	

Course Designers	Secretary Secret	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Raja, National Aerospace Laboratori <mark>es, Bang</mark> alore, raja@nal.res.in	1. Dr.Parammasivam, professor, MIT, Chennai, mparams@mitindia.edu	1. Mr. Umar Rizwan M, SRMIST

Code	1 1	8ASE301T	Course Name	AIRCRAFT CONTROL SYSTE	:MS	Cour Categ		E			Profe	ssional	Electiv	е		<u>L</u>	T 0	P C 0 3
		isite Courses Department	18ASC305T Aerospace Engineerii		uisite Courses Nil x / Codes/Standards	F	rogre	ssive C	ourses	M	lil							
Course CLR-1		Rationale (CLF	R): The purpose of learn	ning this course is to:	Mark fr	L	earnir	ng 3	1	2 3		rogran	Learni		tcomes (PLO) 10 11	12 1	3 14 15
CLR-2	: Unde	erstand the root	locus analysis							2 ,) 4		0 1	0	9	10 11		3 14 15
CLR-4	CLR-3: Understand the frequency response analysis CLR-4: Understand the time and frequency domain design of control system								2	llysis	t sign,	Usag	Culture ent &		Team	.ioi ⊗	arning	
	CLR-5 : Understand the control system design in state space CLO-6 : Understand control systems, various response analysis and control system in state space								Engineering Knowledge	Problem Analysis Design &	Development Analysis, Design,	Modern Tool Usage	ety & Cu onment	Sustainability Ethics	ndividual & Team Nork	ical	Life Long Learning	-2 -3
Course CLO-1		Outcomes (CL	O): At the end of this co	ourse, learners will be able to:		Level of Thinking	Sected Proficiency	Expected Attainment (%)	H Know	Problem A	Deve Analy	Modern T	Society & Environme		Indivi	Comi Proje	Life Long	PSO SO
CLO-2	: Analy	yze the system (using Root Loc <mark>us plot</mark>	10 mg/l	The state of the	2	85	75	Н	H		-			-			Λ
CLO-3 CLO-4	: Desig	gn a control sys	using Frequen <mark>cy respon</mark> se a tem in time an <mark>d frequen</mark> cy o	lomain		2 2	85 85	75 75	H	- H	1 -	-		-	-			и м -
CLO-5 CLO-6	: Design	gn and analyze gn and analyze	the control sy <mark>stem in s</mark> tate s control syste <mark>ms, vario</mark> us res	space sponse analysis and control system in state s	space	2	85 85	75 75	H	- H H		-		-	-	 		И - М И М М
Duratio	n (hour)		9	9	9					9						9		
S-1		Open-Loop, Cl	Control Syst <mark>ems</mark> osed-Loop C <mark>ontrol,</mark>	Introduction to Root Locus Analysis	Bode Diagrams Rules for Constructing the Bo	da Plote				ime don			ncy L	apund	ov Stabil	ity		
S-2	SLO-1	Feedback cont	rol system s and their Simplification	General Rules for Constructing the Root	Nyquist Plots			PD Cor	troller D	esign	i oyoton				otic Stab			
S-3	SLO-2 SLO-1	Mason's Gain		Locus Positive feedback Systems	Rules for Constructing the Ny Stability and Relative Stability				oller De ntroller L				S	ate Tr	utput Sta ansition	Matrix		
		Numerical Mathematical I	Modeling ofDynamical	Root Locus plot for positive feedback					ompens	ŭ						nd Obser	vability	
S-4		Systems		system	Systems with Transport Lags Gain Margin			Lag Co.	mpensa	tion					punov E te Feedl	quation ack Con	trol Des	ianand
S-5	SLO-2	Modeling in the Transfer Funct		Negative feedback Systems	Phase Margin			Lead-La	ag Com _l	oensati <mark>o</mark>	n				acement		0, 000	.5114114
S-6	SLO-1 SLO-2	ImpulseRespo	nse Functions	Root Locus plot for Negative feedback system	Closed-Loop Frequency Resp	oonse		Sensitiv	rity				0	otimal	State S	pace Cor	trol Sys	tem
S-7	SLO-1	Maximum Ove	ise Time, Peak Time, rshoot,and Settling Time sis and Routh's Stability	Parameter Variation	Frequency Domain Performar Specifications	псе		Complii Functio		Sensitiv	ity Trans	sfer	Li	near C	Quadratio	: Regulat	or	
S-8			Perivative, and Integral	Stability analysis of positive feedback system using root locus	Peak Resonance Resonant Frequency			Disturb	ance Re	jection			С	assica	al Contro	l Theory		
S-9	SLO-1 Steady-State Error Analysis in Feedback Stability analysis of Negative feedback Bandwidth							Loop Si	haping				М	odern	Control	Theory		

Learning Resources	 Ogata, K., Modern Control Engineering, Prentice Hall, 2002 Kuo, B.C., Automatic Control Systems, Prentice Hall, 1991 Franklin, G.F., Powell, J.D., and Emami-Naeini, A., Feedback Control of Dynamic Systems, AddisonWesley, 1994. 	 Dorf, R.C., and Bishop, R.H., Modern Control Systems, Prentice Hall, 2001. Nise, N.S., Control Systems Engineering, Benjamin-Cummings, 1995.
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	Diameia			Cont	inuous Learning Ass	essment (50% weig	htage)			Final Evamination	Final Eversination (FOO/ weighters)			
	Bloom's Level of Thinking	CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA –	4 (10%)#	Final Examination (50% weightage)				
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Lovel 1	Remember	40 %		30 %		30 %	1/1	30 %		30%				
_evel 1	Understand	40 %		30 %		30 %		30 %	-	30%	-			
Level 2	Apply	40 %	· ·	40 %	100000	40 %		40 %		40%	-			
	Analyze			-										
Level 3	Evaluate Create	20 %	- ~	30 %	Mary -	30 %	\	30 %	- 1	30%	-			
	Total	10	0 %	10	0 %	10	00 %	10	0 %	10	0 %			

Course Designers	CONTRACTOR OF THE PARTY OF THE	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Raja, Senior Principal Scientist and Professor, NAL – Bangalore. raja@nal.res.in	1. Dr.K.M.Parammasivam, Professor, MIT-Chennai. mparams@mitindia.edu	1. Mr.A. Vinoth Kumar, SRMIST.



Cour		18ASE302T Course Name	HELICOPTER AERODYNAM	ICS	Cou Cate		Е				Profes	sional	Electiv	/e			L 3	T 0	P 0	C 3
F	Pre-requi	site Courses 18ASC202J	Co-rec	quisite Courses Nil		Progre	essive Co	urses		٨	lil									
		g Department			Vil	1 Togic	000110 01	Jarooo			•••									
		g - cpaniment management = ngmeeting			<u> </u>															
Course	e Learnir	ng Rationale (CLR): The purpose of lear	rning this course is to:	LAND THE PARTY NAMED IN		Learni	ng				Pr	ogram	Learn	ng Ou	tcomes	s (PL	O)			
CLR-1	: Und	derstand the helicopter configurations, charac	cteristics and its rotor systems	200	1	2	3	1	2	3	4	5 6	6 7	8	9	10	11	12	13 14	4 15
CLR-2	: Lea	arn the momentum theory used in the analysis	s of helicopter aerodynamics			>	=													
CLR-3		mprehend the performance of helicopter in <mark>ho</mark>				enc	ner		S			Modern Tool Usage	ω		Ε			g		
CLR-4	: Und	derstand the flow states of the rotor and helic	opter vertical descent performance		Thinking	je je	air	2	lysi		igi	US	<u></u> ∞		ndividual & Team Work	등	~	Learning		
CLR-5		dy the performance of helicopter in ho <mark>rizonta</mark>		ASSESSMENT OF THE REAL PROPERTY.	hi	PG	Att	g a	lna	ent	Des	00	3 t	≟	~	cati	jt. ⊱	Fee		
CLR-6	: Acq	quaint with forward flight performance <mark>of helic</mark>	opter and theory of blade stall.			ed (eq	eri od	m	∞ Du	, S, L) Tr	ع ا ي	ap	la	ü	ĕ ĕ	_	- 0	ა დ
				77.5	evel of		ect	anit We	ple	sign /elc	alys	deri		igi is	is x	E E	jed and of	의		
Course	e Learnir	ng Outcomes (CLO): At the end of this c	ourse, learners will be able to:	ACTIVITY DIMEN	Le	(Bloom) Expecte	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Develop <mark>ment</mark>	Analysis, Design, Research	Mo	Society & Cuiture Environment &	Sustail Ethics	Indivi	Communication	Project Mgt. & Finance	Life Long	PSO	PSO
CLO-1	l: Acq	quire knowledge of helicopter fund <mark>amentals</mark> , o	configurations and rotor systems.	ASSESSATATION OF THE SEC.	2	85	80	Н	М	L	L	-			-	-	-			1 H
CLO-2		oly momentum theory in the anal <mark>ysis of he</mark> lico		The state of the s	2	90	75	Н	Н	М	М	L ·		-	-	-	-	L	H M	1 M
CLO-3	B: Acc	quire theoretical foundation on the hovering a	nd climbing performance of helicopter.	A STATE OF THE STA	2	85	75	Н	M	М	L	•		-	-	-	-	L	M H	l M
CLO-4	: Ana	alyze the vertical descent perfor <mark>mance of</mark> heli	copter.	Mary Republican	2	80	70	Н	М	L	L	-		-	-	-	-	L	M M	1 M
CLO-5		quire basic understanding of he <mark>licopter p</mark> erfor		The state of the s	2	85	75	Н	М	L	L			-	-	-	-	L	H H	l M
CLO-6		crue information on the helicop <mark>ter perfor</mark> manc		35 m 3 d m	2	80	70	Н	М	М	М	L		-	-	-	-	L	M M	1 H
			\$25.750 a VAD.	THE RESIDENCE OF		E (*)													•	
Du	ration						797			_							^			
(h	our)	9	9	9		45				9							9			
	SLO-1	Introduction to Helicopters – History																		
S-1		Helicopter Configurations – Single Rotor,	Momentum Theory - Introduction	Performance in Hovering and	Climbin															
	SLO-2	Two Rotor and Multi Rotor Machines			CIIIIIIIIII	$g \mid I$	-low Stat	es of t	he Ro	otor –	Introdu	ıction	F	orwara	' Flight	– Pe	forma	nce E	guatio	on
0.0	SLO-1		The second secon	The second second	Cilitibili	g	-low Stat	es of t	he Ro	otor –	Introdu	ıction	Fo	orward	' Flight	– Pe	forma	nce E	quatic	on
S-2		Specifics of Helicopters	The state of the s	Out to Date	Ollitiolit										•				•	on
	SLO-2	Specifics of Helicopters Articulated Rotor System	Thrust Generation	Optimum Hovering Rotor	Ollimbili	1	-low Stat Normal V States						mill Di	rag-Lif	t Ratio	n – F	orward	Fligh	nt	
		Articulated Rotor System		Optimum Hovering Rotor	Cilitibili	1	Vormal V						mill Di	rag-Lif	•	n – F	orward	Fligh	nt	
S-3	SLO-1	Articulated Rotor System Definitions – Tip Path, Tip Path Plane, Axis	20	Optimum Hovering Rotor Induced Torque	Cilitibili	1	Vormal V	/orking	g, Vori	tex-Ri	ng <mark>and</mark>		mill Di	rag-Lif arasite	t Ratio	n – F Coeff	orward icient -	Fligh Fon	nt ward F	light
S-3		Articulated Rotor System Definitions – Tip Path, Tip Path Plane, Axis		1/4//	Cintibili	1	Normal V States	/orking	g, Vori	tex-Ri	ng <mark>and</mark>		mill Di	rag-Lif arasite	t Ratio	n – F Coeff	orward icient -	Fligh Fon	nt ward F	light
S-3	SLO-1 SLO-2	Articulated Rotor System Definitions – Tip Path, Tip Path Plane, Axis of Rotation, Shaft Axis, Disc Area, Chord, Blade Angle, Angle of Attack	20	1/4//	Cilitiditi	,	Normal V States Vertical D	/orking	g, Vori	tex-Ri	ng and	l Windi	mill Di	rag-Lif arasite	t Ratio	n – F Coeff	orward icient -	Fligh Fon	nt ward F	light
S-3	SLO-1 SLO-2 SLO-1	Articulated Rotor System Definitions – Tip Path, Tip Path Plane, Axis of Rotation, Shaft Axis, Disc Area, Chord, Blade Angle, Angle of Attack Definitions – Feathering Angle, Feathering,	Hovering	Induced Torque	Cinnon	, , , , , , , , , , , , , , , , , , ,	Normal V States Vertical E Curves fo	orking Descen	g, Vori	tex-Ri format g Vert	ng and	l Wind	mill Di	rag-Lif arasite limb D	t Ration Drag (n – Fo Coeff t Ratio	orward icient - o – Fol	Fligh Forward	nt ward F Flight	Flight
	SLO-1 SLO-2	Articulated Rotor System Definitions – Tip Path, Tip Path Plane, Axis of Rotation, Shaft Axis, Disc Area, Chord, Blade Angle, Angle of Attack Definitions – Feathering Angle, Feathering, Disc Loading, Blade Loading, Solidity,	20	1/4//	Girinbiri		Normal V States Vertical D	/orking ∕escen r Calc r, Fligh	g, Vori t Perf ulatin t Mod	tex-Ri formations g Vertiles of	ng and	l Wind	mill Di	rag-Lif arasite limb D	t Ratio	n – Fo Coeff t Ratio	orward icient - o – Fol	Fligh Forward	nt ward F Flight	Flight
	SLO-1 SLO-2 SLO-1 SLO-2	Articulated Rotor System Definitions – Tip Path, Tip Path Plane, Axis of Rotation, Shaft Axis, Disc Area, Chord, Blade Angle, Angle of Attack Definitions – Feathering Angle, Feathering,	Hovering	Induced Torque Profile Drag Torque		Coring	Normal V States Vertical E Curves fo Velocities Autorotat	orking Descent r Calc r, Flight	g, Vorn t Perf ulatin t Mod agram	iorman g Vert	ng and nce ical-De a Roto	escent	mill Di	rag-Lif arasite limb D	t Ration Drag (n – Fo Coeff t Ratio	orward icient - o – Fol	Fligh Forward	nt ward F Flight	Flight
	SLO-1 SLO-2 SLO-1 SLO-2 SLO-1	Articulated Rotor System Definitions – Tip Path, Tip Path Plane, Axis of Rotation, Shaft Axis, Disc Area, Chord, Blade Angle, Angle of Attack Definitions – Feathering Angle, Feathering, Disc Loading, Blade Loading, Solidity, Flapping, Lead-Lagging Effect of Cyclic Pitch Change	Hovering	Induced Torque	um Hov	// ()	Normal V States Vertical E Curves fo Velocities Autorotat Performa	orking Descent r Calc r, Flight ion Dia	g, Vorn t Perf ulatin t Mod agram	iorman g Vert	ng and nce ical-De a Roto	escent	mill Di Pa	rag-Lif arasite limb D rofile E	t Ration Drag (n – Fo Coeff t Ratio	orward icient - o – Fol	Fligh Forward	nt ward F Flight	Flight
S-4	SLO-1 SLO-2 SLO-1 SLO-2 SLO-1 SLO-2	Articulated Rotor System Definitions – Tip Path, Tip Path Plane, Axis of Rotation, Shaft Axis, Disc Area, Chord, Blade Angle, Angle of Attack Definitions – Feathering Angle, Feathering, Disc Loading, Blade Loading, Solidity, Flapping, Lead-Lagging Effect of Cyclic Pitch Change Swash Plate	Hovering Figure of Merit	Induced Torque Profile Drag Torque Numerical Problems on Optim	um Hov	// ()	Normal V States Vertical E Curves fo Velocities Autorotat	orking Descent r Calc r, Flight ion Dia	g, Vorn t Perf ulatin t Mod agram	iorman g Vert	ng and nce ical-De a Roto	escent	mill Di Pa	rag-Lif arasite limb D rofile E	t Ration Drag (rag-Lift	n – Fo Coeff t Ratio	orward icient - o – Fol	Fligh Forward	nt ward F Flight	Flight
S-4 S-5	SLO-1 SLO-2 SLO-1 SLO-2 SLO-1 SLO-2	Articulated Rotor System Definitions – Tip Path, Tip Path Plane, Axis of Rotation, Shaft Axis, Disc Area, Chord, Blade Angle, Angle of Attack Definitions – Feathering Angle, Feathering, Disc Loading, Blade Loading, Solidity, Flapping, Lead-Lagging Effect of Cyclic Pitch Change Swash Plate	Hovering Figure of Merit Blade Element Theory	Induced Torque Profile Drag Torque Numerical Problems on Optim Rotor, Induced Torque, Profile Torque	um Hov	vering	Normal V States Vertical E Curves fo Velocities Autorotat Performa	escent r Calc r, Flight ion Dia nce in	g, Vori t Perf ulating t Mod agram Horiz	formar g Vert les of s	ng and nce ical-De a Roto	escent	mill Di Pa Ci Pi	rag-Lift arasite limb D rofile E	t Ration Drag (rag-Lift Drag-Lin	n – For	orward icient - o – Fol io – Fo	Flight	nt ward F Flight	Flight
S-4	SLO-1 SLO-2 SLO-1 SLO-1 SLO-2 SLO-1	Articulated Rotor System Definitions – Tip Path, Tip Path Plane, Axis of Rotation, Shaft Axis, Disc Area, Chord, Blade Angle, Angle of Attack Definitions – Feathering Angle, Feathering, Disc Loading, Blade Loading, Solidity, Flapping, Lead-Lagging Effect of Cyclic Pitch Change	Hovering Figure of Merit	Induced Torque Profile Drag Torque Numerical Problems on Optim Rotor, Induced Torque, Profile	um Hov	vering	Normal V States Vertical E Curves fc Velocities Autorotat Performa	Pescent or Calc or Calc on Dia on	g, Vori	iormar g Vert les of s ontal	ng and nce ical-De a Roto Flight	escent	mill Di Pa Ci Pi In	rag-Lif arasite limb D rofile E duced	t Ration Drag (rag-Lift Drag-Lin	n – For	orward icient - o – Fol io – Fo	Flight	nt ward F Flight	Flight
S-4 S-5 S-6	SLO-1 SLO-2 SLO-1 SLO-1 SLO-2 SLO-1	Articulated Rotor System Definitions – Tip Path, Tip Path Plane, Axis of Rotation, Shaft Axis, Disc Area, Chord, Blade Angle, Angle of Attack Definitions – Feathering Angle, Feathering, Disc Loading, Blade Loading, Solidity, Flapping, Lead-Lagging Effect of Cyclic Pitch Change Swash Plate Rotor Systems – Fully Articulated, Semi-	Hovering Figure of Merit Blade Element Theory General Expression for Induced Velocity	Induced Torque Profile Drag Torque Numerical Problems on Optim Rotor, Induced Torque, Profile Torque Performance Equation	um Hov	vering	Normal W States Vertical E Curves for Velocities Autorotat Performa Introducti Flapping Steady H	Vorking Vescender Calc Les, Flight John Dia John Ce in John La Jover —	g, Vori t Perf ulating t Mod agram Horiz ag Hin Horiz	tex-Ri format g Vert les of s ontal	ng and nce ical-De a Roto Flight -	escent or,	mill Direction Property Inc.	rag-Lift arasite limb D rofile E duced rofile F orward	t Ration Drag (rag-Lift Drag-Lift Drag -	n – Foreign Point	orward icient - o – Fol io – Fo vard F vard F	Flight	nt ward F Flight	Flight
S-4 S-5	SLO-1 SLO-2 SLO-1 SLO-2 SLO-1 SLO-2 SLO-1 SLO-2 SLO-1	Articulated Rotor System Definitions – Tip Path, Tip Path Plane, Axis of Rotation, Shaft Axis, Disc Area, Chord, Blade Angle, Angle of Attack Definitions – Feathering Angle, Feathering, Disc Loading, Blade Loading, Solidity, Flapping, Lead-Lagging Effect of Cyclic Pitch Change Swash Plate Rotor Systems – Fully Articulated, Semi-Rigid Rotor, Rigid Rotor	Hovering Figure of Merit Blade Element Theory	Induced Torque Profile Drag Torque Numerical Problems on Optim Rotor, Induced Torque, Profile Torque	um Hov	vering	Normal V States Vertical E Curves fc Velocities Autorotat Performa Introducti Flapping	Vorking Vescender Calc Les, Flight John Dia John Ce in John La Jover —	g, Vori t Perf ulating t Mod agram Horiz ag Hin Horiz	tex-Ri format g Vert les of s ontal	ng and nce ical-De a Roto Flight -	escent or,	mill Direction Property Inc.	rag-Lift arasite limb D rofile E duced rofile F orward	t Ration Drag rag-Lift Drag-Lift Drag -	n – Foreign Point	orward icient - o – Fol io – Fo vard F vard F	Flight	nt ward F Flight	Flight

	ration our)	9	9	9	9	9
	SLO-2	Atmospheric Density and Power Required – Definitions of Rotor Profile Power, Induced Power, Parasite Power	Equivalent Chord			Introduction to Quadcopter / Multirotaor Aerodynamics
_ \ \-\u	SLO-1 SLO-2	Tutorial	Tutorial	Tutorial	Tutorial	Tutorial

	1.	Rathakrishnan E., Helicopter Aerodynamics, PHI Learning Private Limited, Delhi, 2019.
Learning	2.	Nikolsky Alexander A., Helicopter Analysis, John Wiley & Sons Inc., New York, 1951
Resources	3.	Alfred Gessow, Garry C. Myers Jr., Aerodynamics of the Helicopter, College Park Press, USA,
		1999.

- George H. Saunders, Dynamics of Helicopter Flight, John Wiley & Sons Inc., New York, 1975.
 Wayne Johnson, Helicopter Theory, Dover Publications, USA, 1994.

- Gordon Leishman J., Principles of Helicopter Aerodynamics, Cambridge University Press, New York, 2000.
 John Seddon, Simon Newman, Basic Helicopter Aerodynamics, 3rd Edition, John Wiley & Sons, Ltd., 2011.

Learning Assessment			100		100 - 1		476				
Bloom's			Continuo	ous Learning Assess	ment (50% weighta	ige)			Final Evamination	(E00/ woightogo)	
	CLA - 1	CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		l (10%)#	Final Examination (50% weightage)		
Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1 Remember Understand	40 <mark>%</mark>	1500	30 %	100 Av.	30 %	Marine Service	30 %	-	30%	-	
Level 2 Apply Analyze	40 <mark>%</mark>	100	40 %	100	40 %	1	40 %	-	40%	-	
Level 3 Evaluate Create	2 <mark>0 %</mark>	Z	30 %		30 %		30 %	-	30%	-	
Total	100	%	100	0 %	100	0 %	100	0 %	10	0 %	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Expert
1.Dr. Manishankar C., Senior Scientist, NAL, Bangalore	1. Prof. Arun Kumar P., Assistant Professor, IIT Jammu	1. D <mark>r. S. M. Ara</mark> vindh Kumar, SRMIST

Cour		18ASE303T	Course	ROCKET AERODYNAMICS		Course	E	Professional Electi	ive	L	T F	P C
Cod	Э		Name		Ca	ategory		Troisedictial Electric		3	0 (0 3
Pre-r	equisite (Courses 18ASC3	01J Co-requisite Co	ourses Nil		Progr	ressive Cou	rses Nil				
		g Department	Aerospace Engl		Data Book / Codes/Standards			17.11				
		<u>J = 1p = </u>	, <u> </u>									
Cours		ng Rationale (CLR)		se o <mark>f learning this c</mark> ourse is to:			Learning		earning Outcomes (
CLR-1	: Un	nderstand the conc	ept of boundary layer and its c	haracteristics.			1 2 3	1 2 3 4 5 6	7 8 9 10) 11	12 13	14 15
CLR-2				<mark>at plate bo</mark> undary layer, importance of shock			(m) (%)	8 9 4	×			
CLR-3		nderstand and appr ewtonian theory in I		of hypersonic flow, hypersonic shock-wave a	nd Expansion-wave relations, appli	cation of	Level of Thinking (Bloom) Expected Proficiency (%)	Engineering Knowledge Problem Analysis Design & Development Analysis, Design, Research Modern Tool Usage Society & Culture	n Work	Finance	б	
CLR-4				amic configurations of missiles.	All and Salitane		Level of Thinking Expected Proficie	Engineering Know Engineering Know Problem Analysis Design & Develop Analysis, Design, Research Modern Tool Useg Society & Culture	t & ty ty Team '	_ i <u>E</u>	Learning	
CLR-5	: Ap	pply cross-flow ana	lysis in the analysis <mark>of aerody</mark> n	amics characteristics of missiles, vortex she	dding and flow separation.		Pro #	Des Josephan	ent Illity & T	# H	Les	
CLR-6			ous aerodynamic l <mark>aunching p</mark> ro				E ed T	m A rich Tr	Jac lual	ξĺΞ̈́	_	2 8
				A	ELECTRICAL PROPERTY.		el c	yine sign sign derr	Environment & Sustainability Ethics Individual & Tea	Project Mgt. &	Life Long PSO - 1	0 0
Cours	e Learnin	ng Outcomes (CLC)): At the end	of this course, learners will be able to:	STATE OF THE STATE			Engineerin Problem A Problem A Analysis, E Research Modern To Society & (Environment & Sustainability Ethics Individual & Tea	P S	Life Long PSO - 1	PSO.
CLO-1			f boundary lay <mark>er theory.</mark>		STATE OF THE STATE OF		2 85 7	5 H M L L		-	L H	M M
CLO-2		equire the fundame th shock layer.	ntal differenc <mark>es betwee</mark> n incon	raction	2 80 7	0 H M L M		-	L M	НМ		
CLO-3	: Ap	preciate the variou	us qualitative <mark>aspects o</mark> f hypers	sonic flow.		40.00	2 85 7			-	L H	M M
CLO-4	: Ac	crue knowledge of	f different ae <mark>rodynami</mark> c configu	rations of missiles, missile classification.			2 80 7			-	L M	
CLO-5				in study of missile aerodynamics	The second	45.	2 85 7	5 H L L L		-	L M	
CLO-6	: Ac	crue information o	n aerodyna <mark>mic launc</mark> hing probi	lems of missiles.	ALTERNATION AND SERVICE	500	2 80 7	5 H M L L		-	L M	$M \mid M$
									,			
	ration our)		9	9	9	1	31 //	9		9		
	SLO-1	Concept of Bound	dary Layer	Qualitative Aspects of Hypersonic Flow –	The state of the s		Δerodynan	nic Characteristic <mark>s of Slen</mark> der	Aerodynamic Laui			
S-1	SLO-2	Boundary Layer [Definitions an <mark>d Charact</mark> eristics	Thin shock layer, Viscous Interaction, High Temperature Shock Layer.	Classification of Missiles		and Blunt B		Considerations for Aircraft			
	SLO-1		- Boundary Con <mark>ditions,</mark>	Qualitative Aspects of Hypersonic Flow –	External Aerodynamic Configuration		Missiles at	Small Angles of Attack	Considerations for			
S-2	020 1	Laminar and Turk	bulent Boundary Layers	Entropy Layer, Low-Density Flow, High	Missiles - Wing Control, Canard C	ontroi	Wildones at	oman ringles of rittack	Aircraft (Air Launc			
02	SLO-2	Boundary Layer 7	Thickness - Types	Temperature Effects, etc.	Tail Control, Tail-Less (or Wing Co	ontrol),	Cross-Flow	v Analysis	Missile-Aircraft Co	llision,	Missile)
				Aerodynamic heating of re-entry bodies –	Body Extension External Aerodynamic Configuration	one of			Structural Failure Launch Boundarie	o Int	ro du oti	on to
	SLO-1	Displacement Thi	ickness of Boundary Layer –	slender and blunt re-entry vehicles.	Missiles - Nose Flap Control, Dors		Total Lift o	n a Missile Body – Cross-Flow	Launch-Aircraft Tr			
S-3		Concept, Derivati		Hypersonic Flight Paths – Velocity-Altitude	Control, Wing Arrangements (Mon		Analysis	ii a wissile Body – Cross-Flow	Trajectory, Launch			ille
	SLO-2	Concept, Denvati	1011	Map	Triform, Cruciform)	lowing,	Allalysis		Determination	Doun	Jaiy	
					Forces Acting on Missile during				Ground Launch –	Proble	m of l :	aunchina
	SLO-1 Momentum Thickness of Boundary Layer – Newtonian Theory				Atmospheric Flight, Effect of Angle	e of	Total Lift of	<mark>n a Slend</mark> er Wing – Cross Flow				larioring
S-4	Concept Derivation				Attack on Aerodynamics Forces a		Analysis	a distriction of the second second	Sources of Detrim			causina
	SLO-2	1 ,		Newton's Sine-Squared Law – Derivation,	Moments				Excessive Missile	Disper	sion	3
		Incompressible B		Modified Newtonian Law Mach Number	Introduction to Bodies of Revolution	on	Total Lift a	n a Wing-Body Combination –	Factors Affecting I			
S-5			ow over a flat plate, Governing	Independence	Nose, Mid-Section, Boat-tail)II —	Cross-Flow		Dispersion – Laun	cher D	eflectic	on, Tip-
		Equations, Nume	erical Results.	muepenuence	Nose, Miu-Section, Doat-tall		Off,					
S-6	SLO-1											

	ration nour)	9	9	9	9	9
	SLO-2		and Exact Shock-Expansion Theory	3	missile	Factors Affecting Missile Launch Dispersion - Thrust and Fin Malalignment, Wind
S-7	SLO-1 SLO-2	Boundary Layer Separation – Introduction			and High Angles of Attack	Mechanisms
S-8	SLO-1 SLO-2	Shock Wave Boundary Layer Interaction	Relations of inviscin Hypersonic Flows	Introduction to Missile Drag – Friction drag, Pressure drag, Induced drag, Interference drag	LOT MISSILE OF LITTERANT ANGIOS OF ATTOCK	Impulse Devices for Separation – Stage Ignition, Auxiliary Rockets, Thrust Reversal, Springs
S-9	SLO-1 SLO-2	Tutorial	Tutorial	Tutorial	Tutorial	Tutorial

Learning
Resources

- 1. John D. Anderson Jr., Fundamentals of Aerodynamics, 5th Edition, McGraw-Hill Companies, Inc., 2010.
- 2. John D. Anderson., Modern Compressible Flows, 3rd Edition, McGraw-Hill Companies, Inc., 2003.
- 3. Rathakrishnan E., High Enthalpy Gas Dynamics, John Wiley & Sons Singapore Pte. Ltd., 2015.
- 4. John D. Anderson Jr., Hypersonic and High-Temperature Gas Dynamics, 3rd Edition, AIAA Education Series, AIAA, 2003.
- 5. Chin S. S., Missile Configuration Design, McGraw-Hill Book Company Inc., New York, 1961.
- 6. Jack N. Nielsen, Missile Aerodynamics, McGraw-Hill Book Company Inc., New York, 1960.

Learning .	Assessment					1000					
	Bloom's			Cont	inuous Learning Asse	essment (50% weigh	tage)	- All - All -		Final Evamination	(E00/ woightogo)
	Level of Thinking	CLA –	1 (10%)	CLA -	2 (15%)	CLA – 3	3 (15%)	CLA – 4	(10% <mark>)#</mark>	Filiai Examination	n (50% weightage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %		30 %	200	30 %		30 %		30%	
Level	Understand	40 %		30 %		30 %	Territoria de la constanta de	30 %		30%	-
Level 2	Apply	40 %		40 %		40 %		40 %		40%	
Level 2	Analyze	40 /0		40 /0		40 /6	1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1	40 /6		40 /0	-
Level 3	Evaluate	20 %	the state of	30 %		30 %		30 %		30%	
Level 3	Create	20 %		30 %		30 %	-	30 76		30 76	-
	Total	100	0 %	10	0 %	100) %	100	%	10	0 %

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Expert
1 Dr. Manishankar C., Senior Scientist, NAL, Bangalore	1. Prof. Arun Kumar P., Assistant Professor, IIT Jammu	1. Dr. S. M. Aravindh Kumar, SRMIST

Cours		18ASE304T Course Name	SPACE MISSION DESIGN & ANA	LYSIS	Cours	-	Е			Profes	ssional	l Elec	ctive				L 3	T 0	P 0	C 3
	Pre-rea	uisite Courses 18ASC306T, 18ASC	C303J Co-requisite C	Courses Nil	Progr	essive	Course	s Nil												$\overline{}$
Course		Department Aerospace Engineer					-													
				111111111111																
Course	Learning	Rationale (CLR): The purpose of learni	ing this course is to:	A VIII VIII VIII		Learni	ng			Р	rograr	n Lea	arning	Outco	omes	(PLC))			
CLR-1		erstand the space mission profiles and types	of space missions		1	2	3	1 2	3	4	5	6	7	8	9 '	10	11	12 1	3 14	15
CLR-2		erstand the mission objectives, constraints, ne				5	ı,													
CLR-3		v the complete set of space systems and v <mark>ari</mark>		ft		Expected Proficiency	Expected Attainment (%)	U	2	ے ا	Modern Tool Usage	ىو		1	Εl			Б		
CLR-4		v the basics of spacecraft motions and th <mark>e gc</mark>		The state of the	Thinking	ofic	aj.	Engineering Knowledae Problem Analysis	+	Design,	ട്	Culture	Environment & Sustainability	1	Mork	Communication	×ŏ	ife Long Learning		
CLR-5		prehend the satellite attitude dynamics <mark>and r</mark> e		AND DESCRIPTION OF THE PARTY OF	_ :≣	P.	# A	ng Je		Ö	8	징.	ent E		ర	<u>g</u>	g:	Le Le		
CLR-6	: Interp	oret the interplanetary mission trajec <mark>tories an</mark>	d associated concepts	N. C. Landerson	IJĘ́́́́́́	ig g	ted	Engineering Knowledge	∞ 6	Analysis, Deg Research		Society & (inat	. 3	ng		Project Mgt. Finance	gr +	- 2	.3
-				100	evel .	g g	bed	ngin	Design		ge	Sie .	vir Sta	Ethics	Mork Nork	Ĕ :	Project N Finance	Life Long	PSO.	
			urse, learners will be able to:		<u>ا</u> و	ЭЩξ	2000				Z	တိ ၊	ᄪᇲ		ĭĕ	ပိုင်	<u>ت</u> ت	<u> </u>	. 6	8
CLO-1		ribe the space mission and the classifications			2	85	80	Н -	М	М	-	-	-	-	-	-	-		L	-
CLO-2	: Desc	ribe the various aspects space environments	s, mission objective, needs and design of the	space mission	2	85	80	Н -	-	-	-	-	L	-	-	-	-		-	-
CLO-3		ain the importance of the spacecraft systems			2	80	75 75	H L	L	Н	-	-	-	-	-	-	-	- -	IVI	-
CLO-4 CLO-5		ain the necessity of Kepler's e <mark>quations a</mark> nd or		The state of the s	2	80	75	H H		M H	-	-	-	-	-	-	-		L L	-
CLO-5		ribe the key features reentry <mark>flight phys</mark> ics an onstrate the interplanetary mi <mark>ssion pro</mark> file and		The state of the s	2	80	75	H N	1 M	Н	-	-	L	-	-	-	-		L	
CLU-6	. Dem	onstrate the interplanetary mission profile and	u trie importance		2	00	/5	П L	IVI	П	-	-	L	-	-	-	-	- -	L	
Duration	on (hour)	9	9	9	W. 1	76			9								9			
S-1	SLO-1	Delininon of space mission	Requirements, constraints of spacecraft design	The N-body problem		E	Basis of	aunching	of a sa	tellite			Gene	ral as	spects	of in	iterpla	netary	trajed	ctory
	SLO-2	Classification of space missions	Design process of spacecraft	The N-body problem		(General	aspects o	f satelli	te injed	ction		Interp	lanet	ary H	ohma	ann tra	nsfer		
S-2	SLO-1	Low Earth Orbit mission, medium altitude mission	Spacecraft configuration	The orbit equation				ehicle as					Rend	ezvoi	us opp	ortui	nities			
3-2	SLO-2	Geosynchronous Earth Orbit mission, deep space mission	Integrating the spacecraft design	The energy law.				nce of o			ters o	n in-	Sphe	re of	influer	псе				
S-3	SLO-1	Space mission life cycle	Spacecraft payload design	Revision of circular orbits a orbits	nd ellip	otical L	_aunch v	ehicle pe	rformar	псе			Meth	od of	patch	ed co	onics			
	SLO-2	Mission objectives	Payload sizing process	Parabolic trajectories		(Orbit dev	iation due	to inje	ction e	errors		Plane	tary o	depart	ure				
S-4	SLO-1	Identification of mission needs	Mission requirements	Hyperbolic trajectories				ection erro					Plane				S			
	SLO-2		Observation of payload design	Keplers equation		E	Basics of	reentry f	ig <mark>ht d</mark> yı	namics	3		Plane	tary i	flyby					
S-5	SLO-1	Mission evaluation	Observation of payload sizing	Lamberts problem		F	undame	entals of e	ntry flig	ght med	chanic	s	Desig	ın of t	ransfe	er elli	ipse			
3-5	SLO-2	Orbit design	Spacecraft subsystems	Restricted three body problem		F	undame	entals of e	ntry he	ating			Desig	ın of t	ransfe	er elli	ipse			
S-6			Propulsion subsystem selection and sizing	The Lagrange coefficients		E	Entry vel	ni <mark>cle d</mark> esig	n								raject	ory		
3-0			Basic of rocket propulsion and its types	The Lagrange coefficients			anding	echnique	S	'					arrival					
S-7		,	Attitude determination and control	Jacobi constants		F	Recover	<mark>⁄ techni</mark> qu	es				Gravi							
3-1			Telemetry, tracking and command system	Introduction to orbit perturbation	n		Reentry										y orbi			
S-8			Command and data handling	Earth gravity harmonics				of existir								rth-N	100n s	ystem	1	
0-0	SLO-2	Launch systems selection process	Power and thermal system	Lunisolar gravitational attraction	ns	(Challeng	es of exis	ting ree	entry m	ission		Time	of flig	ght					

Durati	on (hour)	9	9	9	9	9
S-9	SLO-1	Determining the spacecraft design envelop and environments	Guidance and navigation system	Radiation pressure effects, atmospheric drag	Parametric design of a reentry capsule	Time of injection velocity
3-9	SLO-2	Payload environments	l Ground system design	Tidal friction effects and Mutual gravitational attraction	Planetary entry vehicle optimization	Lunar patched conic

earning esources	 Larson, Wiley J., and James Richard Wertz. Space mission analysis and design. No. DOE/NE/32145-T1. Torrance, CA (United States); Microcosm, Inc., 1992. Curtis, Howard D. Orbital mechanics for engineering students. Butterworth-Heinemann, 2013. Cornelisse, Jacobus W., H. F. R. Schoyer, and Karel F. Wakker. "Rocket propulsion and spaceflight dynamics." London: Pitman, 1979 (1979). 	 Tewari, Ashish. Atmospheric and space flight dynamics. Birkhüser Boston, 2007. Griffin, Michael Douglas. Space vehicle design. AIAA, 2004. Fortescue, Peter, Graham Swinerd, and John Stark, eds. Spacecraft systems engineering. John Wiley & Sons, 2011.
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Learning A	Assessment			L //							
	Bloom's			Contir	nuous Learning Asse	essment (50% weigh	itage)	477		Final Evaminatio	n (50% weightage)
		CLA –	1 (10%)	CLA – 2	2 (15%)	CLA – 3	3 (15%)	CLA – 4	4 (10%)#		n (50% weightage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %		30 %	Shappy.	30 %	11.	30 %	1	30%	-
Level 2	Apply Analyze	- 40 <mark>%</mark>	NEW Y	40 %	200	40 %		40 %		40%	-
Level 3	Evaluate Create	- 20 <mark>%</mark>	2	30 %		30 %	The m	30 %	-	30%	-
	Total	10	0 %	100) %	100) %	10	0 %	10	0 %

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Cour		18ASE305T Course Name	VIBRATIONS AND ELEMENTS OF AER	OELASTICITY		urse egory		Е			Prof	essio	nal Ele	ective			L 3	T 0	P C 0 3
		uisite Courses 18ASC101T		site Courses Nil					Progre	ssive (Cours	ses				٨	'il		
Course	Offering	Department Aerospace Engineerin	ng Data Book	/ Codes/Standards	Nil														
Course			ning this course is to:	11 1 1 1 m		L	.earnin	g				Prog	ram Le	earning	Outcor	nes (P	LO)		
CLR-1	: Und	derstand the concept of drawing a vibratory i	model	11 11 11 11		1	2	3	1	2 3	3	4	5 6	7	8 9	10	11	12	13 14 15
CLR-2		derstand the methods of deriving the equation					5	Ħ					a)						
CLR-3		ntify the problems of vibration in aerospace				g D	Expected Proficiency (%)	Expected Attainment (%)		.s		ć.	Modern Tool Usage Society & Culture	2	Ethics Individual & Team			ing	
CLR-4		ow the functioning of various vibration measu			- :	Thinking	ojjo.	tai	Engineering Knowledge	alys	<u>+</u>	Design, າ	Modern Tool Usage	± 5 ∞ >	Ľ	Work Communication	∞	Life Long Learning	
CLR-5		arn the various approximate methods of solv		and the second second	_ i	Ē	d P	A	ring Ge	A «	mer o	٦ ک	8 Z	neu Ipilit	<u>∞</u>	<u> </u>	∕lgt.	gLe	
CLR-6	: Get	t an idea of the various aero elastic ph <mark>enome</mark>	ena that arise in real time flight conditions.		:	<u>ā</u> <u>ē</u>	cte	cte	lee/	em Sur	<u>g</u> .	/sis	E ≥	one	s		<u>ت</u>	3 E	-1 -2 -
Cource	Logrning	g Outcomes (CLO): At the end of this co	ourse, learners will be able to:			Level of (Bloom)	Expe	% (%)	ngi No	rob	Development	Ana <mark>lysis,</mark> I Research	od si	Environment & Sustainability	Ethics Individ	Ž E	Project Mgt. &	Life Long	PSO - 1 PSO - 2 PSO - 3
CLO		scribe the elements of a vibratory model	ourse, rearriers will be able to.			<u>그 巴</u> 2	<u>ше</u> 85	75	H	- 0	<u> </u>	∢ Ω H	≥ S	- ш σ	<u>ш</u> <u>-</u> -	> C	-		M M M
CLO		scribe the equations of motion of any vibrato	rv system			2	85	75			1	Н		-		-	-		M M M
CLO		plain the solving methods of ap <mark>proach to a</mark> ny		16-314 Sept.	77-1	2	85	75			1	Н		-		-	-		M M M
CLO		olain the functionality of various vibration me				2	85	75		Н	_	Н		-		-	-	М	M M M
CLO			etermining the natural frequency of various v	vibratory systems.		2	85	75	Н		1	Н	-	-		-	-		M M M
CLO	-6 : Inve	estigate the different aero ela <mark>stic pheno</mark> men	a for different flight conditions	The state of the s		2	85	75	H	H	1	Н		-		-	-	М	$M \mid M \mid M$
				A CONTRACTOR OF THE PARTY OF TH	93			- 1						1					
Durati	on (hour)		9	9	E-11				1	9							9		
٠,	SLO-1	Introduction-Basic Terminology	Single degree of freedom system	Multi degree of freedom syste		371	A th	ree degr	ee of fre	edom	rotor	syste	em	Introdu	iction to	Aeroe	lasticit	у	
S-1	SLO-2	Elements of vibratory system	Examples-spring mass system	Free body diagram and equati motion	ions of		Nun	nerical s	olving	•				Collar'	s triangi	е			
S-2	SLO-1	Degrees of freedom	Solution of equation of motion- Complementary function	Natural modes of vibration			Veh	icle susp	ension	problei	m			Torsio	nal dive	rgence	2D ca	se	
	SLO-2	Examples of vibratory system	Forced damped vibratory system	Mode shapes			Auto	mobile _l	oroblem					Numer	rical solv	<i>r</i> ing			
0.0	SLO-1	Simple Harmonic motion-Definition and explanation	Numerical solving –solution of equation of motion	Principal Coordinates			Disc	rete sys	tems					Torsio	nal dive	rgence	-finite	wing	
S-3	SLO-2	Sum of harmonic motions-different conditions	Numerical solving –solution of equation of motion	Principal modes			Exa	mples	7					Numer	rical sol	ving			
	SLO-1	Numerical solving	Solution of equation of motion-Particular Integral	Orthogonal condition				leigh me uency	thod of	finding	the r	natura	al	Aileror	contro	rever	sal		
S-4	SLO-2	Numerical solving	Solution of equation of motion-Particular Integral	Eigen value problem	. 10	Ш		nerical S	olving					Numer	ical sol	ving			
S-5	SLO-1	Newton's law	Transient motion of damped forced vibration problem	Hamilton's principle			Sen	ni-definite	e <mark>systen</mark>	1				Flutter					
	SLO-2	D'Alembert's principle	Numerical solving	Vibration of elastic bodies			Nun	nerical s	olving					Numer	ical solv	ving			
S-6		Equation of motion-Newton's law of motion		Lateral Vibration of a string				hod of in		coeffic	ient r	matrix		Bufetir					
5-0	SLO-2	Example	Numerical solving	Numerical solving			Nun	nerical s	olving					Numer	ical solv				
S-7		Equation of motion- Energy method	Elevator and control tab numerical	Longitudinal vibration of rod			Dun	<mark>kerley</mark> m	ethod	-		-			nic resp		-		
J-1	SLO-2	Example	Helicopter rotor blade numerical	Numerical solving		Numerical –cantilever beam				Numerical solving									
S-8		Free Vibrations-Forced Vibrations	Springs connected in series	Lateral vibration of beam				range's e							l Effecti		5		
	SLO-2	Damped vibrations-Undamped vibrations	Springs connected in parallel	Numerical solving			Nun	nerical s	olving					Numer	ical solv	⁄ing			

Duration	on (hour) 9	9	9	9	9
0.0	SLO-1 Periodic vibrations-Aperiodic vibration	s Support Excitation	Torsional vibration of shaft	Holzer method	Coop atudios
5-9	SLO-2 Numerical Solving	Vibration measuring instruments	Numerical solving	Numerical solving	Case studies

	1. Timoshenko S., "Vibration Problems in Engineering" – John Wiley and Sons, New York, 1993.	4. Tse, F.S., Morse, I.F., Hinkle, R.T., "Mechanical Vibrations" – Prentice Hall, New York, 1984
Learning	2. Fung Y.C., "An Introduction to the Theory of Aeroelasticity, - John Wiley & Sons, New York, 1995.	5. Scanlan R.H. & Rosenbaum R., "Introduction to the study of Aircraft Vibration & Flutter", John Wiley
Resources	3. Bisplinghoff R.L., Ashley H and Hoffman R.L., "Aeroelasticity"- Addison Wesley Publication, New York,	and Sons. New York, 1982
	1983.	6. Tongue. B.H., "Principles of Vibration". Oxford University Press, 2000.

	Bloom's			Continuous Learning Assessment (50% weightage)							o (EOO) waishtasa)		
		CLA -	1 (10%)	CLA –	2 (15%)	CLA -	3 (15%)	CLA –	4 (10%)#		n (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	40 %	7.0	30 %		30 %	/	30 %		30%	-		
Level 2	Apply Analyze	40 %	1	40 %		40 %		40 %	10.	40%	-		
Level 3	Evaluate Create	20 <mark>%</mark>		30 %	Sec. 3.	30 %	1	30 %	17.	30%	-		
Total 100 %			0 %	10	0 %	10	0 %	10	0 %	100 %			

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R. Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	2. Mr. S. Chandra Sekhar, SRMIST

Code	1 13	8ASE306T	Course Name	DIGITAL AVIONICS		Cours Catego	-	Е			Prof	fessior	nal Ele	ctive				L 3	T 0	P C 0 3	
	Pre-requ	isite Courses	Nil		Co-requisite Course	es Nil				Prog	ressive	e Cour	ses	Ni	1					-	1
Course	Offering	Department	Aerospace Engineering	Data Book / Codes/S	Standards				Nil												Ī
Course	Learning	Rationale (CL	R): The purpose of learning	na this course is to:	THE WAY		Learnii	na				Proa	am Lo	earning	Outco	omes (PLO)			7
CLR-1			nics systems and its design	.g	11.31.7.	1	2	3	1	2	3		5 6		8	9			2 13	14 15	,
CLR-2			nics system Integration																		-
CLR-3				used in Avionics communication			Suc	Jen		(0		_	ge			E		nan .	ည		
CLR-4	: Knov	v the display ted	chniques used in Glass coc <mark>kp</mark>	it		Thinking	ficie]. <u>E</u>		ysis	2	5 .	ture Casa	ంద		ear	등	& Finance	Learning		
CLR-5	: Knov	v the Electroma	gnetic interference sourc <mark>es in</mark>	the aircraft and cooling techniques		in	Pro	Atte	g a	na	ent	g :		ا تٰے ≧		⊢ ≪	äţi	±; (Ğ		
CLR-6			ntenance aspect of avi <mark>onics s</mark>		COLUMN TOWN	of T	ed	ed /	erir	A L	E E		_ \ <u>~</u>	- mre		<u>a</u>	Ë	Ñ :	[-	2 8	
						Level of (Bloom)	Expected Proficiency	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Development	Research	Modern 1001 Usage Society & Culture	Environment & Sustainability	જ	Individual & Team Work	Communication	Project Mgt.	LITE Long I PSO - 1		
Course	Learning	Outcomes (CL	-O): At the end of this cou	ırse, learners will be able to:	1 N. W.			S T S	Eng	Pro	Dev S	Ses :	Soc 8	Env Sus	Ethics	Individ Work	ပ်	Proj	PSO	PSO PSO	
CLO-1			s systems and integration	The second secon	Con Cold Con Cold	2	85	75	H	-	-	-		-	-		-	-	- H	HH	1
CLO-2			nics certification and design		CONTRACT OF STREET	2	85	75	Н	Н	Н	-	-	-	-	-	-	-	- H	Н Н	1
CLO-3			ture and communication proto	cols of the avionics systems	100000	2	85	75	Н		Н	Н	- -	-	-	-	-		- M	Н Н	
CLO-4	: Differ	rentiate the diffe	erence in displa <mark>y techniq</mark> ues u	ised in Glass cockpit	4	2	85	75	Н	Н	-	-		-	-	-	-	-	- M	Н Н	1
CLO-5							85	75	Н		Н	-		-	-	-	-	-	- H	H M	
CLO-6			The second second	2	85	75	Н	Н	Н	Н		-	-	-	-		- H	Н Н	1		
											- 7										
Duratio	on (nour)		· ·	9 9 Network Topologies & types of data bus			-	-la atua wa s												4	
S-1 -	SLO-1	Introduction to	Avionics	used in Avionics network	Introduction to Head Up Displag	Electromagnetic interference (E effect				EIVII) a	aria its	Alum	inum	wires/cables							
	SLO-2	Need for Avior	nics	Types Bit encoding & Types of communication Protocol	Principle & Optical configuration	7	E	EMI on current carrying conduct <mark>or</mark>					Bonding								
	SLO-1	Role of Avionic	cs in civil aircr <mark>afts</mark>	Introduction to ARINC 429	Functional description of HUD	100	1	Need for I	EMI pre	eventio	1			Types	s of b	onding	in co	mpos	ite ma	terials	1
S-2	SLO-2	Role of Avionic	cs in Military air <mark>craft</mark> s	Hardware elements,Word format, Bit encoding and protocols	Introduction to Helmet mounted	l display	, 5	Shielding,	, Twiste	d pairs	and b	andwi	dth	Lighti	ning p	rotecti	ion in	comp	osite a	aircrafts	Ī
	SLO-1	Top-Down des system Design	sign Procedure fo <mark>r Avionics</mark>	Introduction to MIL-STD 1553B	Optical configurations		F	Radiated	ЕМІ					Earth	Retu	rns					
S-3	SLO-2	Avionics Design		Hardware element, Bit encoding	Helmet Design factors and Fun description of HMD	ctional	E	EMI susc	eptibility	/				Aircra	aft ma	nuals					
0.4	SLO-1	Ilities of Avioni	ics Systems	Word format and protocols	Introduction to MFD		Ε	MI reduc	ction	-				Maint	tenan	ce mar	nuals				1
S-4		Avionics certifi			Working of MFD	7.5	(Continuin	g airwo	rthines	S			Wirin	g diag	gram m	nanua	als		-	1
0.5	SLO-1	FTA- Fault tree			Direct voice input techniques a	nd HOT.		Vire and						Circu						-	1
S-5	SLO-2	Qualitative and	unt tree analysis Introduction to AFDX network Direct voice input techniques ve and quantitative methods Hardware elements, Protocols FLIR- IR vision				(Cable det	finition					Avon	neter a	and its	type	S			1
0.0	SLO-1	FMEA- Failure	mode and effect analysis	Ethernet frame format, AFDX frame format	Evaluating Avionics cooling req	uiremer	nts F	ailure m	odes of	wires	and ca	bles		Bond	ing m	eter					1
S-6	SLO-2	Steps in FMEA			Heat transmission in Avionics F			Viring pro						oscille						-	1
C 7		Pros & cons o		Trends in Display technologies	Avionics cooling specifications			Cabl <mark>es ar</mark>						Autor	natic	Test e	quipn	nents		_	1
S-7	SLO-2	Difference bet	ween FTA & FMEA	CRT construction & working	Avionics cooling for Airplanes								Built	In Tes	st equi	omen	ıt		_	1	
	SLO-1	Avionics Archi	tectures evolution		Avionics cooling for missiles		(Guid <mark>eline</mark>	s for the	e instal	lation	of wire	loom						3ITE		1
S-8			architecture evamnles	Plasma panels And <mark>EL panels construction</mark> and working	Avionics cooling for satellites&	Spacec	Guidelines for the installation of wire loom Spacecrafts Types of wire looms							Centralized Maintenance systems							

Durati	on (hour)	9	9	9	9	9
0.0	SLO-1	#A380 & B787 architecture examples	Comparison of CRT, LCD, LED, Plasma and EL panels	Radiation heat transfer in space	Hydrolysis in wires and cables	Aircraft communication and addressing systems
S-9	SLO-2		Capacitive and resistive touch screen technologies	Effect of α/e ratio on temperature in space	Wire connectors	Cost of maintenance

	The second secon	TO BE SEED OF THE
Lograina	1. Carry R spitzer, "The Avionics Handbook", CRC Press, 2000	4. RPG Collinson, "Introduction to Avionics", Chapman and Hall, 1996
Learning Resources	2. Spitzer CR, "Digital Avionics systems",	5. Dave S Steinberg, "Cooling Techniques for electronic equipments", Second edition, 1991
	3. Lan Moir, "Civil Avionics Systems", Second edition wiley publications, 1996	6. Jim curren, "Trends in Advanced Avionics", IOWA state university, 1992

Learning	Assessment						- 11						
	Dia a maila			Cont	tinuous Learning Asse	Final Eventination	- (FOO(inhtone)						
	Bloom's	CLA –	<mark>1 (10%)</mark>	CLA –	2 (15%)	CLA –	3 (15%)	CLA – 4	4 (10%)#	Final Examination (50% weightage)			
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	40 %		30 %	A Second	30 %		30 %	-	30%	-		
Level 2	Apply Analyze	40 %		40 %	SHAPPIN.	40 %		40 %	1 -	40%	-		
Level 3	Evaluate Create	20 <mark>%</mark>		30 %	100	30 %	77 000	30 %	-	30%	-		
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10	0 %		

Course Designers		
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1. Dr. S. Maja, National Aerospace Laboratories, Darigatore, Tajawilai.res.iir	1.Dr.Faraminasivam, Froiessor, Wirr, Oriennam, params@miundia.edu	2. Dr. P. Eswaran, SRMI <mark>ST</mark>

Cou		18ASE307T Course Name COM	PUTATIONAL HEAT TRANSFER AND FLUID D	urse		E	Professional Elective L 3								T 0	P 0	<u>C</u>				
CO	Je	iname		Call	egory													<u> </u>	U	U	<u> </u>
Pi	e-reauisit	te Courses 18MAB202T, 18ASE208T	Co-requisite Courses Nil			Pro	oaress	ive Cou	ırses		N	1									
Course	Offering	Department Aerospace Engineering	Data Book / Codes/S	Standards Nil				uhi.													
				The state of the s																	
		Rationale (CLR): The purpose of learning					arning									tcome	s (PLC	D)			
CLR-1		duce the students with various techniques of				1	2	3	1	2	3	4	5 6	7	8	9	10	11	12	3 14	15
CLR-2		e the students to understand the governing e				-	<u>ک</u>	i i					<u>o</u>						_		
CLR-3		ide suπicient background to the students to g e the students to simulate and analyze fl <mark>uid f</mark> l	tain the ability to discretize fluid flow problems		2	<u>.</u>	Expected Proficiency (%)	Expected Attainment (%)		Sis	2		Modern Tool Usage Society & Culture			ndividual & Team	_		ife Long Learning		
CLR-4		e the students to simulate and analyze hald in			evel of Thinking	,	Į į	ıttai	D	Problem Analysis	in it	Design,	Modern Tool Usa Society & Culture	Environment &	. <u>≥</u>	E Te	Communication	≪ .:	ear		
CLR-6			for elementary fluid flow/heat transfer problems		[<u>-</u>	: [<u>8</u>	D D	Engineering Knowledge	۾ ا _م	Development	, 5	P &		Sustainability Ethics	al &	ligi.	Project Mgt. & Finance	J GL	_	3
OLITO	. Liido	no the stadente to write compater programs r	of clotherically hard new model transfer problems	200 100 12		(Bloom)	ecte	ecte	inee	Problem A	Developm Applyaic	Research	letv letv	<u>.</u> [2]	tain S	vidu ¥	<u>, E</u>	Project N Finance	ر اد)-1	1
Course	Learning	g Outcomes (CLO): At the end of this cou	urse, learners will be able to:	- 2727	ĕ	[)	X 3	xx (%	Eng Sh	Prof	Sev Sev	Zes Ses	Noc.	<u>.</u>	Sustair Ethics	Individ	등	jo je	j <u>e</u>	PSO	PSO.
CLO-1		erstand the governing equations for flow and		CARL TARGET				70					M -	-	-		-		L	L H	
CLO-2			ential equations of fluid flow and heat transfer pr					70					Н -	-	-	-	-	-	-	ИΗ	
CLO-3			numerical solutions and the numerical uncertaint	/.				70					M -	-	-	-	-	-		ИΗ	-
CLO-4		yze convection-conduction pro <mark>blems thr</mark> ough		The state of the s				70	Н				Н -	M	М	L	L	-	L	ИН	<u> </u>
CLO-5	: Gain	fundamental knowledge abo <mark>ut numeric</mark> al co	de development			2	80	70	Н	M	М	Н	M -	-	-	Н	-	-	L	- H	'
Durati	on (hour)	9	9	9	7	4	9										9				
		The Three Fundamental Approaches to		HE STATE OF THE ST		-15	77														
S-1		problem solving - Analytica <mark>l, Experi</mark> mental			nstea	dy dii		n Discretization of 1 – D convection diffusion Equation													
		& Numerical		Equation	-		- 1														
		Introduction to CFD	Finite Difference Approximation of derivatives	Into who are a conducative in a				Contro	Staggered Grid												
S-2		Processes involved in CFD	Truncation error	Interface conductivity				Central differencing scheme Numerical oscillations of			Con	Checker-board pressure oscillations ntral Basics of Pressure-velocity coupli						lina			
3-2	SLO-2	Applications of CFD	Order of magnitude of error	Nonline <mark>arity </mark>				differe				OI	Cen				F1699	ui e-vi	ыосну	соир	ning
	SLO-1	Conservation Principles	Basics of Finite volume Method	Explicit Approaches				Proper				n sch	eme		algorithm Discretization of 2D continuity equation						_
S-3		·						Hair								zation				sional	u-
	SLO-2	J J		Implicit Approaches				Scarbo	orougn	Criteri	on			m	omeni	tum eq	uatior	1			
S-4	SLO-1	Derivation of continuity equation	Discretization of Computational Domain	Illustrative example				Transp								zation			-dimen	sional	V-
U 7	SLO-2	Derivation of continuity equation	Discretization of 1 – D diffusion equation	madirative example				Conse							omeni	tum eq	uatior	1			
S-5	SLO-1 SLO-2	Derivation of momentum equations	Example of numerical solution – 1-D steady Heat conduction problem in a rod	Tri – diagonal Matrix Algo	orithm	1		Asses: schem	ie				fferenc	-				equat	ion foi	mulatio	n
S-6		Newton's hypothesis for fluid flow	Example of numerical solution – cooling of a	Analysis of Numerical osc	cillatio	าทร		Upwin						_		Algor					
0.0		Navier-Stokes equations	circular fin by convective heat transfer					First o	rder up	wind s	cheme	9		A	Applications of SIMPLE						
		Conservation law for Energy equation	on call and system of the act and see	Stability condition for Exp	olicit A	Appro	ach	Asses	sment	of U	Jowina	l Dit	fferend	ina O	ng Overview of other pressure-velocity					ocitv	
S-7	SLO-2	Work done by surface forces & Energy flux due to heat conduction	Comparison with analytical solution	Stability condition for Imp	licit A	Approa	ach	Scheme Of Opwind Difference				٠,	coupling algorithms					,			
S-8	SLO-1	Derivation of Energy equation		Overrelaxation and under	rrelax	ation		Overview of other unwind schemes Types of practical hour			ounda	ny con	ditions								
J-0	SLO-2	=- '		Grid layout-2D domain				Overview of other upwind schemes				Types of practical boundary conditions Grid independency Test					uiliOHO				
S-9				Discretization of 2 – D unsteady diffu			ady diffusion Numerical Diffusion						G	rid ind	epend	ency	Test				
SLO-2 Initial and boundary conditions General forms of discretized equations E		Equation			Best practices for CFD solution																

Learning Resources	Anil Date, Introduction to CFD Cambridge University Press First Edition (2005) Versteeg. H.K and Malalasekera. W, "An Introduction to Computational Fluid Dynamics, the Finite Volume Method" Addison Wesley Longmen Limited, Second Edition (2007)		
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Learning .	Assessment					1. 160						
	Bloom's			Cont	nuous Learning Ass	essment (50% weig	htage)			Final Evaminatio	n (E00/ woightogo)	
	Level of Thinking	CLA –	1 (10%)	CLA – 2 (15%)		CLA – 3 (15%)		CLA –	1 (10%)#	Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	40 %		30 %		30 %		30 %		30%		
Level I	Understand	40 %		30 %		30 %		30 %	_	30%	-	
Level 2	Apply	40 %		40 %	HARTT.	40 %		40 %		40%		
Level 2	Analyze	40 %		40 /0	The second	40 %		40 %		4070	_	
Level 3	Evaluate	20 %		30 %		30 %		30 %		30%		
Level 3	Create	20 %		30 %	Marie Control	30 %		30 %		30%	-	
	Total	100	0 %	10	0 %	10	0 %	10	0 %	100 %		

CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	Process of	- 174	Total Transfer	100			
Experts from Industry		Experts	from Higher Technical Institutions			Internal Ex	perts
1. Mr. N. R. Hero Hemaraj, Senior Data Scie	ntist, General Electric, Bangalo	e 1.	Dr. B. Premachandran, Professo	r, Mechanical Engineering	IIT Delhi	1.	Dr. S. Senthilkumar, SRMIST



						_															
Cours	1 18	ASE308T Course Name	ROCKETS AND MISSILES				urse egory	Е			F	rofess	ional E	lective					L T 3 0	0 0	C 3
0000	<u> </u>					Jul	0 ,												, , ,	0	
			o-requisite Courses Nil				Prog	gressive	Course	es	N	il									
Course	Offering	Department Aerospace Engineering	Data Book / Codes/S	Standards		Nil															
Course	Learning	Rationale (CLR): The purpose of learning	a this course is to:	11-74		Learnin	na					Progra	m Lear	nina O	outcon	nas (P	I ())				
CLR-1		part design basics of rockets and missiles s			1	2	3	1	2	3	4	5	6	7	8	9		11	12	13 1	14 15
CLR-2	: To foo	cus on design principles, materials selection	, testing and performance assessment.											∞ .			u .	~×			
CLR-3	. To un	derstand aerodynamics, flight dynamics, op	<mark>timization</mark> of performance of multi-stage roci	kets and separation		9)	Expected Attainment (%)	ng		Design & Developm <mark>ent</mark>		8		Environment 8 Sustainability		∞ 돈	Communication	Project Mgt. 8 Finance	ļ İ		
OLIVO	· dynan	nics.		16-11-16	of in	sted	sted	Engineering Knowledge	em	Design & Developm	Analysis, Design,	Modern Tool Usage	Society & Culture	onm inat		Individual & Team Work	Jul 3	ce Se	Life Long Learning	- 0	-2
Course	Lograina	Outcomes (CLO): At the end of this cours	logracy will be able to:		Level of Thinking	Expected Proficiency (%)	xpe	ngin	Problem Analysis	esiç eve	naly esic	Moderr Usage	osie Ultu	nvir usta	Ethics	divi	om.	Project N Finance	fe L earr	PSO	PSO
	To los	arn about the different systems of rockets an		otion and about the									ν C	шσ	்ப்	드는	O	ᆸᇤ			
CLO-1	-	nced rockets for future missions	a missing, formalation of the equation of the	onon and about the	2	80	70	Н	Н	Н	Н	М	-	-	-	-	-	-	М	Н	H L
CLO-2		derstand the function of the soli <mark>d propella</mark> nt			2	80	70	Н	Н	Н	Н	Н	-	М	-	-	М	М	М		Н -
CLO-3		derstand the function of the liq <mark>uid propell</mark> ant mulate the equation of motion <mark>s for a mis</mark> sion		80	70	Н	Н	Н	Н	М	-	М	-	-	М	М	М	Η .	Н -		
CLO-4	: To for	lerstanding the	2	80	70	Н	Н	Н	Н	Н	-	Н	-	L	L	Н	Н	Н	Н -		
01.0.5	principles of navigation, guidance and control of rockets and missiles, and design of a multistage rocket To understand the system design, construction, function, performance and testing aspects, and to familiarize with							100													
CLO-5	the selection of suitable materials for different rocket systems.		ket systems		3	80	70	Н	М	М	Н	М	L	Н	L	Н	М	Η	Н	Н	H L
			The state of the s								النيا										
Durati	on (hour) SLO-1	Introduction 9	9		9	-					9							9			
S-1		Classification of launch vehicles and	Solid propellant rocket fundamentals	Liquid propellant roc	ket fun	dameni	tals	Multi-	staging	of roc	kets			ח	esian	of pro	totyni	e rock	cet		
0 1	SLO-2	missiles		Erquia proponant root	NOT TUTT	damon	uio	Water	otaging	01100	1010			Design of prototype rocket							
S-2		Different space missions	Propellant ingredients, Propellant properties	Liquid propellant roc			าร	Perfor		e estima	ation o	f multi-	- <mark>stage</mark>	Requirement and design approach							
		Rocket flight systems	Propellant grain processing	Liquid propellant roc	ket typ	es		roone	10												
S-3		Forces and moments acting on a rocket	Propellant Grain types, requirements	Design of propellant	feed sy	/stem		Multi-	stage v	ehicle	optimiz	zati <mark>on</mark> i	te <mark>chni</mark> q	ues P	roduc	t desig	n				
		Propulsion, aerodynamics Gravity, control systems						Flight	traiect	ory ont	imicati	on									
S-4		Stability analysis	Grain design, properties	Gas pressure feed system Flight trajectory optimisation Constraints in optimisation			P	roces	s plan	ning a	aspec	ts									
	SI O 1	Inertial and non-inertial frames, coordinate	Service	Design of fuel tanks			1	1ateria	al seled	rtion i	critori:	a									
S-5		transformation	Ballistics of missiles	Rocket flight simulation techniques																	
		Coriolis theorem	753 111	Turbo-pump design	H			Ctorr	20000	otion o	otom			S	uper	alloys,	Com	posite	S		
S-6		equations of motion for three dimensional motion through vacuum and atmosphere	Burn rate control design and evaluation	Liquid propellant roc	ket eng	ine cyc	ele			ati <mark>on s</mark> ation d		cs		— T	est ar	nd Qua	alificat	tion			
S-7	SLO-1	Reentry flight dynamics	Solid rocket components	Cooling systems				Sepai	rati <mark>on t</mark>	echniqi	ıes				vnes	of test	s				
	SLO-2 SLO-1	Rocket flight performance dispersion		Liquid Slosh, Pogo						cles lan			ies I systei		,,,,,,,	.,					
S-8		Computation methods	Solid rocket <mark>motor design</mark>	Water hammer, Gey	ser effe	ect			nch vei		e and	COHLIO	ı systei	"S E	nviroi	nmenta	al test	's			
S-9	SI O 1	Introduction to single stage to orbit concepts, reusable launch vehicles	Separation systems	Thrust vector control (Planning details									
		Advanced space propulsion systems	Pyrotechnic devices	Performance improve		of TVC		Aerodynamic control systems				Concluding a normal and incomplete test									

	1. Ramamurthi.K: "Rocket Propulsion", Macmillan Publishers, New Delhi-110002, March, 2010	5. Ashish Tewari, "Atmospheric and Space Flight Dynamics", Birkhauser Boston, 2007
	2. George.P.Sutton, Oscar Biblarz: "Rocket Propulsion Elements" John Wiley India, New Delhi-110002,	6. Martin J L Turner, "Rocket and Spacecraft Propulsion", Springer Praxix Publising Co, 2004
Learning	June,2010	7. Ronald Humble, Henry and Larson, "Space Propulsion Analysis and Design", McGraw-Hill, 1995
Resources	3. Taylor, Travis. S:"Introduction to rocket science and engineering" CRC Press, New York, 2009.	8. George M Siouris, "Missile guidance and control systems", Springer, 2004
	4. Cornelisse, J.W, Schoyer H F R, and Wakker K F, "Rocket Propulsion and Space Dynamic", Pitman	9. W J Larson and J R Wertz, "Space Mission Analysis and Design", Kluwer Academic Publishers, 1999
	Publishing Co., 1979	10 Michael Griffin, "Space Vehicle Design", AIAA education series, 2004

Learning A	∖ssessment				The state of the s							
	Dia am'a		Final Evamination	a (EOO) waishtasa)								
	Bloom's	CLA – 1 (10%)		CLA – 2 (15%)		CLA -	3 (15%)	CLA -	4 (10%)#	Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	40 %		30 %	1175341	30 %		30 %		30%		
Level I	Understand	40 %		30 %	- The Control of the	30 %		30 %		30%	-	
Level 2	Apply	40 %		40 %		40 %		40 %		40%		
LEVEI Z	Analyze	40 /0		40 /0	# 17 55 mil	40 70		40 78		4070	-	
Level 3	Evaluate	20 %	1.00	30 %	F - 1 - 1 - 1 - 1 - 1 - 1	30 %	E-7	30 %		30%		
Level 3	Create	20 /0		30 /	Company of the	30 /6		30 /6		30 /0	-	
	Total	100) %	10	0 %	10	0 %	10	0 %	10	0 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Manishankar C., Senior Scientist, NAL, Bangalore	1. Prof. Arun Kumar P., Assistant Professor, IIT Jammu	1. Dr. S. M. Aravindh Kumar, SRMIST
		2. Mr. K. Allwyn, SRMIST



Code	1 18	ASE309T	Course Name	FATIGUE AND FRACTURE ME	CHANICS	Course	Categ	gory E				Profe	essior	nal El	Elective			P 0	C 3			
	Pre-regu	isite Courses	18ASC304J	Co-requis	site Courses Nil		Progre	essive Co	urses		Nil											
Course		Department	Aerospace Engii	neering Data	a Book / Codes/Standards	Nil																
Course	e Learning	Rationale (Cl	IR): The nurnose of	learning this course is to:	CHAC		Learni	ina				Pr	ogra	m l e	arning	Outco	mes	(PLO)			
				rve, mea <mark>n stress, stres</mark> s concentration	A STATE OF THE PARTY OF THE PAR	1	2	3	1	2	3	4	5		7	8			11	12	3 14	4 15
CLR-2				ad histo <mark>ries, cumulati</mark> ve damage & statistical a	aspects of fatique.					Ī											Ť	
CLR-3				ffects, temperature effects of fatigue.			oue	nen		(A)		_	age	a			F			б		
CLR-4				erg <mark>y release r</mark> ate, theoretical strength of mate		of Thinking	Expected Proficiency	(%) Expected Attainment (%)		Problem Analysis		Analysis, Design, Research	Modern Tool Usage	Culture	જ ્	١.	ndividual & Team Nork	Б.	ంగ	Life Long Learning		
CLR-5				<mark>, case histo</mark> ries, fatig <mark>ue resistance of fiber lan</mark>	ninates	Ę	P	Att	Engineering	√na	Design & Development	Des	8	ਹ	Environment & Sustainability	,	_ න	Communication	Project Mgt. & Finance	Les		
CLR-6	: Get a	a better unders	standing of solving Fati <mark>gu</mark>	<mark>ue problems</mark>		ᆘᇦᇃ	ted	ted	eri Seri	m/	∞ L	rch rch	L	∞ >	nab		nai	Ē	و ک	ng .	٠ ،	႔ ကု
						Level of	S S	bec (gine	ple	Design & Develo <mark>pm</mark>	Analysis, I Research	der	Society &	viro	Ethics	돌	ш. Н	Project N Finance	٦,		
		g Outcomes (C		nis course, learners will be able to:	WAS PARTY			\mathbb{S} $\stackrel{\sim}{\text{M}}$ $\stackrel{\sim}{\text{S}}$	표 ?			A Re	×	တိ	E S	亩.	Work	ප	ᇎᇤ		200	
			ge to plot S-N curv <mark>e for v</mark>			2	85	75	H	Н	Н	-	-	-	-	-	-	-	-		M N	
			atigue & load histories p		Share Harries and the	2	85					-	-	-	-	-	-		M N			
CLO-3			aspects of fatigu <mark>e for sol</mark>	ving problems.		2	85			H H H H				-	-	-	-	-	-		M N	
CLO-4 CLO-5			various materials		The state of the s	2	85 85		Н					-	-	-	-	-	-		M N	И М И М
CLO-5			s design philoso <mark>phies.</mark> sive knowledg <mark>e in fatig</mark> u	o & fracture, problems	and the second	2	85		Н	H	H	- H		-	-	-	-	-	-	M	M N	и IVI И М
CLO-0	. Accri	de comprenen	sive knowledg e in raligu	le & tracture problems			00	13		П		П	-	-	-	-	-	-	-	IVI	VI IV	1 IVI
Durati	on (hour)		9	9	9		T			Q								С)			
	` '	Introduction t	o Fatigue & Fr <mark>acture</mark>	Low cycle fatigue	Structural aspects of fatigue, Continitiation, slip band crack growth	rack	T.	ypes of fi	acture	in me	tals		Ī		Introdu	ction	to var	rious	desigr	philo	soph	ies
S-1	SLO-2	S-N curve		High cycle fatigue	Structural aspects of fatigue, Continitiation, slip band crack growth	rack	T	ypes of fi	racture	in me	tals		Ī		Safe life and fail safe design philosophy							
0.0	SLO-1	Endurance lir	mit	Coffin-Manson's relation	Crack growth on planes of high stress, Ultimate fracture		T	heoretica	l cohe	sive st	trength				Infinite philoso			anage	tolera	ant de	sign	
S-2	SLO-2	Effect of mea	n stress on fatigue	Transition life	Crack growth on planes of high stress, Ultimate fracture.	tensile	T	heoretica	l cohe	sive st	trength				Infinite philoso			anage	tolera	ant de	sign	
S-3	SLO-1	Goodman dia	agram	Solving problems	Fatigue crack propagation, Paris	s law	S	Solving pr	oblems	,					Uncert	aintie	s, sca	tter a	nd sat	ety m	argin	S
3-3	SLO-2	Gerber and S	Soderberg relations	Solving problems	Fatigue crack propagation, Paris	s law	S	Colving pr	oblems	3					Uncert							
S-4	SLO-1	Solving probl	ems	Cyclic hardening, cyclic softening, cyclic stress strain curve	Solving problems	Griffith theory of brittle fracture.					Some of fillets											
3-4	SLO-2	Solving probl	ems	Cyclic hardening, cyclic softening, cyclic stress strain curve	Solving problems		Ir	win-Orwi	n theoi	у.					Secono holes.	dary b	endin	ng du	e to no	n-syr	nmeti	ric
S-5	SLO-1	Notches and	Stress concentrations	Solving problems	Size effects on fatigue Solving problems					Cracked aircraft wing panel repaired with a poorly designed patch												
3-0	SLO-2	Notches and	Stress concentrations	Solving problems	Surface effects on fatigue	Surface effects on fatigue Solving problems			Online structural monitoring of the Tsing Ma bridge													
S-6	SLO-1	Solving probl	ems	Strain life equations	Surface roughness, surface properties		e properties Strain energy releas			elease rate			Fatigue resistance of fiber-metal laminates, laminated sheet without fibers									
3-0	SLO-2	Solving probl	ems	Solving problems	Surface residual stresses			tress inte nodes	nsity f	actor,	Crack	deform	ation		Fatigue resistance of fiber-metal laminates, laminated sheet without fibers							

Durati	on (hour)	9	9	9	9	9
S-7	SLO-1	Neuber's stress concentrations	Analysis of load histories	Fatigue under combined stresses		Fiber-metal laminate Arall and Glare, Fiber metal laminate concept
3-1	SLO-2	Solving problems	Level crossing method	Fatigue under combined stresses	Solving problems	Fiber-metal laminate Arall and Glare, Fiber metal laminate concept
S-8	SLO-1	Plastic stress concentration	Range counting method, Rain flow method	Effects of metallurgical variables on fatigue		Fiber-metal laminate Arall and Glare, Fiber metal laminate concept
	SLO-2	Solving problems		Corrosion fatigue, fretting	Plane strain toughness testing	Fiber-metal laminates as sheet material
S-9	SLO-1	Notched S-N curve	Cumulative damage, Miner's rule	Effect of low temperature fatigue		Crack growth on Glare
3-9	SLO-2	Solving problems	Solving problems	Effect of high temperature fatigue	Solving problems	Fatigue properties of Glare components

Learning	1.	George E.Dieter., "Mechanical Metallurgy", McGraw Hill Education (India) Private Limited, New Delhi, Third Edition, 2013.	Barrels, W., and Ripley, "Fatig <mark>ue of Aircraft</mark> Structures", Pergamon Press, Oxford, 1983 Knott J.F., "Fundamentals of fracture Mechanics", Butterworth & Co., (Publisher) Ltd., London,
Resources	2.	Jaap Schijve, "Fatigue of structures and materials" Springer, Second edition, 2009.	1983

Learning Ass	essment			10 1014	40.00	1300							
	Dia ami'a			Conti	nuous Learning Ass	essment (50% weig	htage)			Final Eversination (FOO) weight			
	Bloom's Level of Thinking	CLA – 1 (10%)		CLA – 2 (15%)		CLA -	3 (15%)	CLA – 4	(10%)#	Final Examination (50% weightage)			
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	40 %	100	30 %		30 %	1000	30 %		30%	-		
Level 2	Apply Analyze	40 %	Z- E	40 %		40 %	18 S	40 %		40%	-		
Level 3	Evaluate Create	20 %		30 %		30 %		30 %	1 2	30%	-		
	Total	10	00 %	10	0 %	10	0 %	100) %	100 %			

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	The United States of the Control of	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. G.Balamurugan, National Aerospace Laboratories, Bangalore, gbala@nal.res.in	1. Dr. V.Arumugam, Madras Institute of Technology, Chennai, arumugam.mitaero@gmail.com	1. Dr.L.R.Ganapathy Subramanian, SRMIST
2. Dr.A. Sakthivel, CEMILAC, Bangalore, asakthironika@gmail.com	2. Dr. R. Velmurugan, Indian Institute of Technology Madras, rvel@ae.iitm.ac.in	2. Mr. S. Chandra Sekhar, SRMIST

Cour Coc		18ASE310T Course Name	CRYOGENIC ENGINEERIN	NG Cou			Е			Prof	essiona	ıl Elect	ive			Professional Flactive										
	Pre-requis	site Courses 18ASC103T	Co-requisite C	ourses Nil					Р	roares	sive Co	urses				N	il									
Course	Offering [Department Aerospace Engineeri		ok / Codes/Standards	Nil																					
	Ŭ			CARL DATE OF THE SECOND																						
Course		Rationale (CLR): The purpose of le	arning <mark>this course i</mark> s :			Learn	ing				Progr	am Le	arning	Outo	omes	(PLC)									
CLR-1	scie	ence	gen <mark>ic systems an</mark> d to provide the knowledg		1	2	3	1	2	3	4	5	â 7	' 8	9	1	0 11	12	13 1	14 15						
CLR-2			Systems, Cryo-coolers and gas Refrigeratio	n Systems		3	ŧ					-														
CLR-3		provide the knowledge of cryogenic in <mark>sula</mark>		0-0-0-0-0	D	enc	mer		S		<i>-</i> -	age	go		E			В								
CLR-4			<mark>instru</mark> mentation and to understand Cryo pun	mping.	Level of Thinking	(Bloom) Expected Proficiency	(%) Expected Attainment (%)		Problem Analysis		Analysis, Design, Research	Modern Tool Usage	Society & Culture Environment &	Sustainability	Individual & Team		ଅ ≪	Long Learning								
CLR-5		provide design aspects of cr <mark>y</mark> ogeni <mark>c storaç</mark>	ge and transfer lines.		l'E	P.	#W	g a	Ans	Jen	De _	<u> </u>	텔	1	∞		펄	Ë								
CLR-6	To	understand cryogenic systems, g <mark>as liquef</mark> a	action system and pumping system and app	plcations	Ę,	n)	ted	Engineering	E E	Design & Development	sis,	L L	S E	inat	qual		Communication Project Mat. &	guc	- c	2 6						
			The same of	7 Sept. To real and I was	<u>e</u>	bec oo	bec	gin	age	sig	aly	ge .	Vir.	Sustail	3 !≧	논		Ę,	- SS - SS	PSO - 2 PSO - 3						
			urse, learners will be able to:	19.7					P.	200	A Re	ĭ ĕ o	있ᇤ	S I	길	ŏ (ბ	3 5		8 6	<u> </u>						
CLO-1	: Ana	alyze the Cryogenic systems	101 mg	100000000000000000000000000000000000000	2			Н	-	-	-	-	- -		-			Н		- M						
CLO-2	: Hav	ve a detailed knowledge of, Gas-Liquefact	ion Systems, cryo-coolers and gas Refriger	ation Systems	2			Н	Н	Н	Н	-	- -		-				М -	- M						
CLO-3		derstand Cryogenic Insulation <mark>s and Cr</mark> yogo		Mississippi	2			Н	Н	Н	Н		- -		-		- -		M N							
CLO-4		derstand different cryogenic <mark>instrumen</mark> tatio		The state of the s	2			Н	-	-	-			_	-					ММ						
CLO-5		ow and to understand variou <mark>s cryogen</mark> ic flu			2		75	Н	-	-	-	-			-		- -		H							
CLO-6	Knc	ow cryogenic systems, gas li <mark>quefactio</mark> n sys	stem and pumping system and applications	A TANK THE PARTY OF THE PARTY O	2	85	75	Н	Н	Н	Н							H	MIN	M M						
Duratio	n (hour)	9	9	9				g								9										
S-1		Introduction - Cryogenic propellants	Claude cycle	Vuilleumier refrigerator		Nume	rical Pro	blems o	n Ga	s Sepa	ration	1	echan	ical v	מוווים	กบก	ne									
3-1		Liquid hydrogen, liquid oxyg <mark>en</mark>	Gladde Cycle	Cryogenic regenerators	34	Syster	n					IVI	conan	icai v	acuun	pun	ιμο									
		liquid nitrogen, liquid helium	The state of the																							
S-2		Properties of cryogenic fluids at	Claude Liquefaction System	Numerical Problems on Cryogenic				Problems on Gas Sep <mark>aration</mark>				Diffusion pumps														
02	SLO-2	cryogenic temperature - Mech <mark>anical</mark>	Sidudo Elquoladion System	Refrigeration system		Syster	n						1140101	, pan	PO											
		properties																								
S-3		Thermal properties	Heylandt System	Thermodynamic ideal Gas separation system	1		ırificatior						ryo-Pι		•											
		Electrical properties	Comparison of Claude and L.H system	Principles of gas separation		Vacuu	m Techr	nology- i	Introd	luction		C	ryogei	nic flu	d stor	age ı	esse/	ls								
S-4		Ortho Hydrogen & Para Hydrogen	Numerical Problems on Claude cycle	Linde single column gas separation		Produ	ction of h	nigh vac	uum			C	ryogei	nic Ins	ulatio	n - In	trodu	ction								
0 7		Safety in Cryogenics	76.0 (3.0) (3.1)	Linde double column gas separation		Trodu	ction or i	ngri vac	uum				yogor	no me	uiutioi	' '''	liouu	CHOIT								
S-5	SLO-1 SLO-2	Applications in Space Technology	Numerical Problems on L-H cycle Cryocoolers- Introduction	Argon and Neon separation systems	L	Flow F	Regimes	in Vacu	ium			М	Methods of Cryogenic Insulation													
S-6	SLO-1	On a linear fraction of the state of the state of	Classification of Cryocoolers	On an area in One Advantage		Condu	ıctan <mark>ce i</mark>	n Vacuu	ım			E	Evacuated powder insulation													
5-0	SLO-2	Gas Liquefaction systems- Introduction	Stirling Cryo – cooler	Cryogenic Gas Adsorption		Pressure drop- Slip flow and mixed flow Opacified powder insulation																				
	SLO-1	Joule Thomson effect	Gifford-McMahon Cry cooler			Numa	rical Pro	hlome	n 1/0/	ouum		\Box°	vaciile	u pov	ruer II	suia	uon									
S-7	SLO-2	Joule Thomson Coefficient	Gas Cycle Refrigeration system- Introduction	Cryo-condensation Process	Numerical Problems on Vacuum Technology Gas filled powders Multilaye						layer	supei	r-													
0.0	SLO-1	Linda Hamnaan ayel-	Classification of Cas Couls as friends the	Numerical problems on Gas separati						uper-	insul	lation														
S-8	SLO-2	Linde –Hampson cycle	Classification of Gas Cycle refrigeration	system		Techn							opella					•								

Pulse tube refrigerator Numerical problems on Gas separation Numerical Problems on Vacuum Propellant management	9
CO Lindo Hompoon System	ment
S-9 SLO-2 Linde – Hampson System Solvay cycle refrigerator system Technology Cryogenic fluid tra	nsfer systems

Lograina	1.	Randall F. Barron., "Cryogenic Systems", Oxford University, Second edition,1985	4.	J.H.Bell ,"Cryogenic Engineering" , Prentice Hall, Englewood Cliffs, First edition, 1963
Learning	2.	Walker.G ,"Cryocoolers", Plenum Press, First edition, New York (1983)	5.	Parner, S. F., "Propellant Chemistry", Reinhold Publishing Corpn., New York, 1985
Resources	3.	Mamata Mukhopadhyay ,"Fundamentals of Cryogenic Engineering",PHI Learning (P) Ltd, India, Fourth edition 2010	6.	R.B.Scott, "Cryogenic Engineering", Van Nostrand Co, New Jercy, 1959

Learning A	Assessment			100			1/1/				
	Dloomio			Conti	nuous Learning Ass	essment (50% weigh	tage)			Final Evamination	n /FO0/ weightege)
	Bloom's Level of Thinking	CLA –	1 (10%)	CLA –	2 (15%)	CLA – 3	(15%)	CLA – 4	4 (10%)#	Filiai Examinatio	n (50% weightage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%		30%	100	30%		30%		30%	
Level I	Understand	40%		30%		30%		30%		30%	-
Level 2	Apply	40%		40%	AND A STATE OF	40%		40%		40%	
Level 2	Analyze	4070		4070	A1. 4. 100	4076		4070		40 /0	-
Level 3	Evaluate	20%		30%	51257	30%		30%		30%	
revel 2	Create	20%		30%		30%		30%			-
	Total	10	0 %	100) %	100	%	10	0 %	10	0 %

#CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1 Dr. S. Poio Sonior Principal Scientist and Professor NAI	1.Dr.Parthasarathi Ghosh, Head, Cryogenic Engineering Centre, IIT Kharagpur psghosh@hijli.iitkgp.ernet.in	1.Mr. G. Saravanan SRMIST
1. Dr. S. Raja, Senior Principal Scientist and Professor, NAL – Bangalore. raja@nal.res.in	2. Dr P.K Dsah, Professor and Head, Department of Aeronautical Engineering Nitte Menakshi Institute of Technology,	2.Mr Vinavak Malhotra SRMIST
Bangalore, raja@nal.res.in	Bangalore. drpdash@gmail.com	Z.ivii Viilayak Mainotta Si (WiS i

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Cou	1 12	BASE311T	Course Name		AIRCRAFT ENGIN	E AND INSTRUMENT SYS	STEMS		Cou Cate		Е				Profes	sional E	Elective	9			3	0	0	3
	_	0	140			0 1 11 0		A 111								1.00								
Couro		uisite Courses Department		Enginooring	~	Co-requisite Co Data Book / Codes/Standa		Nil		Nil	Pr	ogressiv	e Cour	ses		Nil								
Cours	e Oneim <u>c</u>	Department	Aerospace i	Engineening		Data Book / Codes/Standa	ilus			IVII														
Cours	e Learnin	g Rationale (CLR): The purpos	se of learni	ng this course is to:					earnin	a				Pro	ogram l	earnir	a Out	comes	(PLO))			
CLR-1	: Iden	tify the type o	ofReciprocating engin	efuel meter	ring system and its co	omponents used in aircraft.			1	2	3	1	2	3	4	5 6		8	9			12	3 14	1 15
CLR-2			onents and accessorie							S	nt					4)								
CLR-3			type ofinduction and			es.			D	Expected Proficiency (%)	Expected Attainment (%)		<u>.s</u>		Ć.	Modern Tool Usage	2		Individual & Team Work			Learning		
CLR-4			ical systems used in i						Ŗ	.olic	tain		alys	¥	Design,		∞ 4	>-	Teg	ţio	∞ర	ar		
CLR-5			is aircraft engine instr			e of aircraft & aero engine	ovotomo		ΞĒ	d P	d Ai	ring	A ~	mer	۾ ح	8 2	nen	IIIQ	<u>∞</u>	jë		g Le		
CLR-C	. Otiliz	ze trie kriowie	uge acquired for desi	igri, develo	omeni & maintenance	e or aircrait & aero engine :	systems.		l of	cte	cte	nee	lem	d di	alysis, lesearch	E S	. Jo	alne	idus	III	5 5 E	ė,		1 3
Cours	e Learnin	g Outcomes ((CLO): At the end	of this cou	rse, learners will be a	able to:			Level of Thinking (Bloom)	expe %)	:xpe	Engineering Knowledge	Problem Analysis	Development	Analysis, Research	Modern Tool Usa	Environment &	Sustal	Jdiv Vor	Communication	Project Mgt. & Finance	Life Long	PSO - 1	PSO
CLO-1						and its components used	in aircraft.		2	<u>во</u> 80	70 70	H		L	L	L -	-	и —	=>	-	-		L N	1 M
CLO-2			ge on components <mark>an</mark>					-	2	80	70	Н		M	L	М -	-	-	-	-	-			1 M
CLO-3	: Lear	n the working	g of induction and <mark>exh</mark>	<mark>naust s</mark> yster	m in aircraft engines.				2	80	70	Н	-	L	L	М -	-	-	-	-	-	L.		1 M
CLO-4			ed and functions <mark>of a</mark>				The Mary Co.		2	80	70	Н		L	L	L -	М	М	-	-	-			1 M
CLO-5			on principle and o <mark>pera</mark>				100		2	80	70	Н		L	L	M -	-	-	-	М	-	_		l M
CLO-6	i: Acqu	uire comprehe	ensive knowledg <mark>e of a</mark>	aircraft syst	tems, engine systems	s and its instrumentation.			2	80	70	Н	L	L	L	M -	М	М	-	М	-	L .	M M	1 M
Durat	on (hour)		9			9		9		₹#:				9							9			
	SLO-1		to Reciprocatin <mark>g Eng</mark>	gines	Introduction to Gas	Turbine Engines	Introduction to Ind	uction S	Systems	3	Elec	trical Po	wer Ev	olutio	on		In	troduc	tion to	Aircra	aft Eng	ine In	strum	ents
S-1	SLO-2		Construction, modula		Gas Turbine Engine		Reciprocating Eng	ine Indu	uction S	Systems	Airc	raft Elect	rical S	yster	ns		Re	eciprod	cating (engine	e instru	ımeni	s	
S-2	SLO-1	Fuels and the engines.	heir characteristic <mark>s fo</mark>	r IC	Fuels and their char engines	acteristics for gas turbine	Basic Carburetor I	nductio	n Syste	m	Bas	ic Aircraf	t Electi	rical .	Systen	าร	Oį	peratio	n of O	il pres	ssure			
3-2	SLO-2	Contaminat	ion of fuels and preve	ention	Contamination of fue	els and prevention	Induction System Filtering	lcing,Ind	duction	System	Pow	er Gene	ration				Oi	l temp	eratur	e indic	cators			
S-3	SLO-1	Fuel system	n- Basic Fuel System		Turbine Engine Fuel	System	Supercharged Ind	uction S	Systems	;	DC .	Power G	enerati	ion					n of C		er head	temp	eratu	re
	SLO-2		n Requirements		General Requiremen	nts	Operation & Adva	ntages			Турі	ical Aircr	aft DC	Syst	em		M	anifold	press	ure in	dicato	•		
S-4	SLO-1	Fuel Meterii Engines	ng Devices for Recipi	roc <mark>ating</mark>	Hydro mechanical F	uel Control	Reciprocating Eng	ine Exh	aust Sj	/stems	AC	Power G	enerati	ion							ıantity,			ure
3-4	SLO-2	Fuel/Air Mix	ctures, Carburetion Pr	rinciples	Hydromechanical/El	ectronic Fuel Control	Exhaust Systems	With Tu	ırbocha	rger.	Inve	rters, red	tifiers					arbure: dicator		perat	ture, Ta	achon	neter	
S-5	SLO-1	Application Carburetor	of Venturi Principle to)	Operation of Hydron Control	nechanical/Electronic Fuel	Gas Turbine Engii systems	nes engi	ine inle	t	Trar	nsformers	s, Batte	eries					tion to ents typ		Turbine	Eng	ine	
	SLO-2		Systems, Carburetor	Types	Introduction to FADE	EC	Compressor Inlet	Screens	3		Airp	lan <mark>e lig</mark> h	ing sys	stem	s						n of Oi	l pres	sure	
S-6	SLO-1	Float-Type Mechanism	Carburetors, Float Ch System	hamber	FADEC Fuel Contro	l Systems	Turboprop and Tu Inlets	rboshafi	t Comp	ressor	Clas	sification	of ligh	hting	syster	าร	E	xhaus	t gas to	empei	rature	EGT,		
5-0	SLO-2	Main Meteri Economizer	ing,Idling, Acceleratin rSystem	ng and	FADEC for an Auxili	ary Power Unit	Turbofan Engine I	nlet Sec	ctions		Exte	ernal Ligh	iting Sy	ysten	ns				inlet te beratu		ature (GT)	TIT) c	r turb	ine
S-7	SLO-1		jection Carburetors		FADEC Fuel Control	l Propulsion Engine	Gas Turbine Engir Systems	nes Eng	iine Ext	aust	Inte	rnal Light	ing Sy	stem	ıs		Ŭ			1	o (EPF	₹)		

Durat	on (hour)	9	9	9	9	9
	SLO-2	Operation of Pressure Injection Carburetors	Operation and its Advantages	Turbine engine exhaust nozzles	Airplane lighting– Power utilization in airplanes	Principle & Operation of Fuel quantity, Fuel pressure
	SLO-1	Manual Mixture Control	Engine Fuel System Components	Thrust Reversers	Ground Power	Fuel flow indicator
S-8	SLO-2	Automatic Mixture Control (AMC)	Main Fuel Pumps, Fuel Heater, Fuel Filters	Afterburning / Thrust augmentation	Emergency Power Generation	Principle & Operation of Tachometer (percent calibrated) N1 and N2 compressor speeds
S-9	SLO-1	Fuel-Injection Systems	Flow Divider, Fuel Pressurizing and Dump Valves	Thrust Vectoring	Ram Air Turbine, Backup Power Converters	Principle & Operation of Torquemeter
3-9	SLO-2	Bendix/Precision Fuel-Injection System	Fuel Spray Nozzles and Fuel Manifolds	Engine noise suppression, Turbine engine emissions.	Permanent Magnet Generators (PMGs)	Torquemeter (on turboprop and turboshaft engines)

	1. Aviation Maintenance Technician Handbook – Airframe, Vol.2, U.S.Dept. of Transportation, Federal	3.	E.H.J.Pallet, Aircraft Instruments, 2 nd edition,Pearson Publishing Company, 2009
Learning	Aviation Administration, Flight Standards Service, 2012	4.	Adrian P. Mouritz, "Introduction to aerospace materials" Woodhead Publishing Limited, 2012
Resources	2. Aviation Maintenance Technician Handbook – Powerplant, Vol.1, 2, U.S.Dept. of Transportation, Federal	5.	Michael J.Kroes, William A.Watkins ad Frank Delp, Aircraft Maintenance and Repair, 7th ed., Tata
	Aviation Administration, Flight Standards Service, 2012		McGraw Hill, 2013

Learning A	ssessment					1 1 1 W A 7 A					
	Dia ami'a		- Pro-	Contin	uous Learning Ass	essment (50% weigh	ntage)			Final Eversination	n /F00/oiabtaaa)
	Bloom's Level of Thinking	CLA –	1 (10%)	CLA – 2	(15%)	CLA – 3	3 (15%)	CLA – 4	(10%)#		n (50% weightage)
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	7 11	30 %	e medic	30 %		30 %		30%	
Level 1	Understand	40 /0		30 78	10-1400-0	30 78	CHE COLOR	30 /0		3070	-
Level 2	Apply	40 %		40 %	100	40 %		40 %		40%	_
LCVCI Z	Analyze	40 /0		40 /0		40 /0		40 /0		70 / 0	_
Level 3	Evaluate	20 %		30 %		30 %	AL AND	30 %		30%	_
Level 5	Create	20 70		30 70		30 70	1.30	30 70		3070	_
	Total	10	0 %	100	%	100) %	100	%	10	0 %

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	The state of the s	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Wg.CdrK.Manoharan (Retd), Blue Dart Aviation Ltd., manoharank@bluedart.com	1. Dr. A. P. Haran, Park College of Engineering & Technology, ap_haran@rediffmail.com	1. Dr. S. Sivakumar, SRMIST
2 Mr.K.Senthilkumar,Deputy Chief Aircraft Engineer, Air India, Bangalore	2. Dr.Wg.Cdr.N.Muthusamy, Rajalakshmi Engineering college, Chennai,	2. Mr. S. Rai Kumar SRMIST
ks_senthilkumar@yahoo.co	muthusamy55@gmail.com	2. IVII. S. Maj Muillai SMIVIIST

Cour	1 18	SASE312T	Course Name	HELICOPTER MAINTENAN		ourse tegory	Е				Profe	ssion	al Ele	ective				L 3	T 0	P 0	C 3	
	Dro rogu	uisite Course	es Nil	Co-requisite Cours	ses Nil		Dro	aroccive	Course	20	1	Vil										
Course		Department			ok / Codes/Standards	Nil	FIU	gressive	Course	55		VII										
Course	o Ollering	Department	Aerospace En	gineering Data bo	ok / Codes/Standards	IVII																
Course	a Learnine	Rationale (The nurnose of	f learning this course is to:			Learnir	na				D ₁	mara	m I a	arnino	ı Outo	comes	(PLC))			
CLR-1				s ,gears, bearings and ground handling		1	2	3	1	2	3	4	5	6	7 7	8	9	10	11	12 1	13 1.	1 15
CLR-2			otor system components						-	2	J	7	J	-		U	- 3	10	- ' '	12	13 1	+ 13
CLR-3			engine power transmissio				ncy	ent					ge				_			5		
CLR-4			plant installation and ma			Thinking	Expected Proficiency (%)	Expected Attainment (%)		Problem Analysis		Analysis, Design, Research	Modern Tool Usage	Society & Culture	_*		ndividual & Team Nork	_		Life Long Learning		
CLR-5			is airframe construction a		and the second second	i X	Jo	\tta	D	Jal	Ħ	esi	0	ᅔ	Environment & Sustainability		<u>~</u>	Communication	જ	ear		
CLR-6				development & maintenance of Helicopter.		<u>⊨</u>	Di H	Do	Engineering Knowledge	Ž,	Development	ص د	To	8	Environment Sustainability		<u>a</u>	ië.	Project Mgt. 8 Finance	l g		ر س
OLIVO	. Other	o the knowle	age acquired for accign,	development a maintenance of Helicopter.		1 of (2	发) See	nee	len	동향	ysig	ern	et	ai g	တ္သ	₽ P	립	듗	P		- L
Course	a Learning	Outcomes ((CLO): At the end of t	his course, learners will be able to:		evel of Bloom)	XX S	ž Š	ingi	go.	Developm	nal	lod	SC	in st	Ethics	ndivi Nork	ωį	Project IN Finance	<u>e</u>	PSO - ,	PSO -
CLO-1			elicopter fundamentals ar		A STATE OF THE STA	2	80	70	H	<u>-</u>		A IX		S	ш ഗ	ш	<u>-</u> >	-	<u>а</u> ш	L		M M
CLO-2			ie on main rotor co <mark>mpone</mark>		PERSONAL PROPERTY.	2	80	70	Н		М	ī	М	_	-		_					M M
CLO-3			of helicopter tran <mark>smissio</mark>			2	80	70	Н		7	Ī	M	_		-	_	_			MA	и м
CLO-4				tenance of helicopter engines.	Total Table Bridge	2	80	70	Н		ī	ī	M	_	М	М	-	_	_			M M
CLO-5				struction and related systems.	The Report of	2	80	70	H	L	ī	ī	M	_	-	-	_	М	_			и и
CLO-6	A	iire comprehe		opter rotors ,transmission, fuselage and other co	omponents and its maintenance	2	80	70	Н	L	L	L	М	-	М	М	-	М	-			и м
				47.050			E C									1 1				II		
Durati	on (hour)		9	9	9						9								9			-
S-1	SLO-1	Introduction	to Helicopters	Head maintenance	Gradient control boosts	1		Diffe	erent typ	es of p	ower	plant					ural co structu		nents	and m	nateria	als-
	SLO-2	Evolution of	f helicopter	Blade alignment	Maintenance in control riggin	g		Diffe	erent typ	es of	ower	plant	main	tena	nce E	3ottor	n struc	ture				
0.0	SLO-1		otor arrangements	Static main rotor balance	Inspection in control rigging				ntenanc								sectio					
S-2	SLO-2	Rigid rotor a	arrangements	Vibration, Tracking methods	Engine transmission coupling	7			rotor sy							Rears	section	1				
0.0	SLO-1	Semi-rigid r	otor arrangements	Spanwise dynamic balance	Drive shaft			Ser	vicing ta	il rotor	track				7	Tail E	oom					
S-3	SLO-2	Helicopter fi	light controls	Blade sweeping	Maintenance clutch				tem rigg							/ertic						
S-4	SLO-1	Basic direct	ions ,colour codes	Electronic balancing	Freewheeling units				ary wing struction		ge sti	ructur	al		ŀ	Horizo	ntal s	ablize	er			
	SLO-2	Ground han	ndling	Dampener maintenance	Spray clutch				ular, she		tal co	nstruc	ction		5	Skid g	ear					
C E	SLO-1	Towing		Counter weight adjustments	Roller unit		Title		ded con								oration	devid	ce			
S-5	SLO-2	Towing pred	cautions	Auto rotation adjustments	Torque meter				-206								al purp			nents		
0.0	SLO-1	Helicopter p		Mast& Flight Control rotor	Rotor brake			Euro	ocopter	BO-10	5						kid ge					
S-6	SLO-2	protection e	quipments	Mast Stabilizer	Rotor brake maintenance of r	roller ui	nit		slage						F	loats						
	SLO-1	Bearing and	l It's types	Mast Dampeners	Rotor brake maintenance of t	torque	meter	Fus	elage m	ainten	ance				F	Resqu	ie hois	ts				
S-7	SLO-2	Bearing inst		Swash plate flight control systems collective	Vibrations in transmission sys			Airfi	ame sys	stems					C	Cargo	Hook	s				
0.0	SLO-1	Bearing ma	intenance	Cyclic	Mounting systems			Stre	ss and I	loads d	n airf	rame			L	itter i	nstalla	ations				
S-8		Elastomeric		Push-pull tubes	Transmissions			Whe							L	ight l	nstalla	tions				
														Spray equipment								
0.0	S-9 SLO-1 Gear, types Torque tubes, bell cranks Fixed wing power plant modification of typical Eurocopte. Mixer box Installation of typical Eurocopte.			fication	S	Skic	l gear							Sprav	equip	ment						

Learning	1. Jeppesen, Helicopter Maintenance Hand Book, Jeppesons and Sons Inc, 2000.	3. Civil Aircraft Inspection procedures part I and II ,CAA.English Book House ,New Delhi,1986.	
Resources	2. Gupta L,Helicopter Engineering , Himalayan books ,1996	4. Larry Reiethmier ,Aircraft repair manual ,Palamar Books Marquette,1992	

Learning .	Assessment										
	Bloom's			Cont	inuous Learning Ass	essment (50% weigh	ntage)			Final Evamination	n /F00/ woightaga)
	Level of Thinking	4 (10%)#	Filiai Examinatio	n (50% weightage)							
	Level of Thirtking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %		30 %		30 %	7777	30 %		30%	
Level I	Understand	40 %		30 %	-	30 %		30 %	-	30%	-
Level 2	Apply	40 %		40 %		40 %	1	40 %		40%	
Level 2	Analyze	40 %		40 //	The state of the	40 %		40 %		4070	-
Level 3	Evaluate	20 %		30 %	1000	30 %		30 %		30%	
Level 3	Create	20 %		30 %		30 %	- 1	30 %		30%	-
	Total	100	0 %	10	0 %	10	0 %	10	0 %	10	0 %

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2. Mr.K.Senthilkumar, Deputy Chief Aircraft Engineer, Air India, Bangalore	2. Dr.Wg.Cdr.N.Muthusamy, Rajalakshmi Engineering college, Chennai,	2. Mr. S. Rai Kumar SRMIST
ks_senthilkumar@yahoo.co	muthusamy55@gmail.com	2. Wr. S. Raj Kurrar Skivilo i



Code	INAS	SE313T	Course Name		AERIAL ROBOTICS			ourse egory	Е				Profe	essiona	l Elect	ve			<u>L</u>	T 0	P 0	C 3
Pr	e-requisite	Courses	Nil		Co-requisite Courses Nil			Progre	ssive Co	ourses		Nil										
	Offering D			e Engineering	Data Book / Code	es/Standards		. regio				1										
					2.73	1. 3. 7. 1.																
Course	Learning I			e purpose of learning this		11111		Learnir					Pi				utcome					
CLR-1					unmanned aerial vehicle		1	2	3	1	2	3	4	5	6 7	8	9	10	11	12	13 1	4 15
CLR-2				dynamics of multi <mark>rotor i</mark>	micro aerial vehicle.			ठ	Ħ					a)								
CLR-3				n of Aerial Robots			DE DE	ien	me		sis		Ć.	sag	ഉ		ᇤ	_		ing		
CLR-4				nethods of Aerial Robots			of Thinking	ofic	Itai		alys	=	Design,	<u> </u>	culture ent &	2	ĕ	lig.	∞	Learning		
CLR-5	R-5 : Understand the applications of Aerial Robots D-6 : Know dynamics of different types of aerial vehicle,, flight control methods and its applications							d P	d A	ring	An	× me	ے کے		a le	<u> </u>	<u>∞</u>] <u>:</u>	Мgt.	g Le		
CLU-6	J-6: Know dynamics of different types of aerial vehicle,, flight control methods and its applications							g ë	cte	Jee Vled	lem	gn 8	alysis, I	E.		, aii	gng] =	g g) i		-3
Course							Level of	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design &	Analysis, Research	Modern Tool Usage	Society & Cultur Environment &	Sustail	ndividual & Team	work Communication	Project Mgt. & Finance	Life Long l	PSO	. SS
CLO-1	se Learning Outcomes (CLO): At the end of this course, learners will be able to: -1: Mathematically model the kinematics and dynamics of fixed wing unmanned aerial vehicle						2	85	75	H	<u>-</u>	Н	1 4 K	_	л ш		J = :	> O	<u>а</u> ц	-		- M
CLO-2					multirotor micro aerial vehicle	10 11 32	2	85	75	Н	-	Н	-	-		T -		-	-	-		И -
CLO-3			of Aerial Rol		Makington Hillord derivan vermens	100	2	85	75	Н	Н	Н	Н	-		-	-	-	-	-		M M
CLO-4		flight cont	rols of Aerial I	Robots	100	N. Brandson	2	85	75	Н	-		-	Н		-	-	-	-	-		и м
CLO-5			tions of Aeria			Ser La York Conne	2	85	75	Н	-		-	-	Н -	-	-	-	-	-		- -
CLO-6	: Unders	stand dyna	mics of differ	ent <mark>types of a</mark> erial vehicl	e, flight controls and its applications	EA BARRELL	2	85	75	Н	-	Н	Н	Н	Н -	-	-	-	-	-	МΛ	И М
					to the second of the second	2162 - 17 14	400	10.0														
Durat	ion (hour)		(9	9		150					9						9			
S-1	SLO-2	Vehicle(FI	WUAV)		Introduction of Multirotor Micro Aerial Vehicle (MMAV)	Navigational Sensors	4	46		Introduc	tion t	to Con	trol Me	th <mark>od</mark> s (of UAV							
S-2		History of Vehicle	Fixed Wing L	Inm <mark>anned A</mark> erial	History of Multirotor Micro Aerial Vehicle(MMAV)	Inertial Sensors	20			PID Cor	ntrol	-					ial Rob connais		r Militai	у		
S-3	SLO-1	Classificat	tion of Fixed V	Ving <mark>Unmann</mark> ed Aerial	Classification of Multirotor Micro Aerial	Magnetometer				l otorol	o o n t v	ol of N	11.101/.	oina D	ID	Targ	get atta	cking	aerial	robots	3	
3-3	SLO-2	Vehicle			Vehicle(MMAV)	Pressure Sensor				Lateral	COTILI	OI OI IV	IIVIA V U	sing P	ט	Civi	l Applio	cation	S			
S-4	SLO-1 SLO-2	Modelling	and Dynamic	s Form <mark>ulation</mark>	Propeller Theory	GPS based Navigation	n	1		LQR Co	ntrol						veying ial map		Robot	S		
S-5		Frame Ro Euler angi		epresent <mark>ations</mark>	Thrust and Drag moment	Camera based Naviga	ation			Design (MATLAI		R ser	vo <mark>c</mark> ont	rol in		Aen	ial robo	ts for	Precisi	on Ag	gricultu	ıre
S-6	SLO-1 SLO-2	Quaternio			Dynamics of a Multirotor Micro Aerial Vehicle(MMAV)	Position Estimation				Model F	redic	tive C	ontrol t	or UAV	/		rload D n makir		/			
S-7	SLO-1			elling of FWUAV ling of FWUAV	Gravitational force modelling of MMAV Propulsive force modelling of MMAV	Velocity Estimation	1		W.	Linear N	⁄lode/	Predi	ctive C	ontrol			entific F	J	rch			
S-8	SLO-1	Aerodynai	mic Force mo	delling FWUAV	Aerodynamic Force modelling MMAV Moments acting on MMAV	Inertial Navigation Syst				De <mark>sign</mark>	ofa L	inear l	MPC fo	r MMA	V	Sea	rch an	d Res	cue			
S-9 SLO-2 Moments acting on FWUAV Moments acting on MMAV S-9 SLO-1 SLO-2 Vehicle Moments acting on FWUAV Moments acting on MMAV Moments acting on MMAV Mental acting on MMAV Mathematical modelling of Multirotor Micro AerialVehicle(MMAV) Attitude estimation						Attitude estimation				Impleme MMAV	entati	on of a	a Linea	r MPC	for	Min	eral Ex	plorat	ion Aeı	ial Ro	bots	

Learning	1.	R. Beard, and T. W. McLain, 'Small Unmanned Aircraft: Theory and Practice' Princeton University Press. 2012.	3.	L.R. Newcome., Unmanned Aviation, a Brief History of Unmanned Aerial Vehicles, American Institute of Aeronautics and Astronautics. Reston 2004.
Resources	2.	R.C. Nelson., Flight Stability and Automatic Control, McGraw Hill, New York 1998.	4.	Kuo, B.C., Automatic Control Systems, Prentice Hall, 1991.

Learning A	Assessment				1000						
	Bloom's			Cont	inuous Learning Ass	essment (50% weig	htage)			Final Evamination	n (EOO/ waightaga)
		CLA –	1 (10%)	CLA –	2 (15%)	CLA –	3 (15%)	CLA –	4 (10%)#		n (50% weightage)
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %		30 %		30 %	(17)	30 %	-	30%	-
Level 2	Apply Analyze	40 %	W- K	40 %	A SAME	40 %		40 %	-	40%	-
Level 3	Evaluate Create	20 %		30 %		30 %	- \	30 %	101-	30%	-
	Total	100	<mark>) %</mark>	10	0 %	10	0 %	10	0 %	10	0 %

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	the same of the sa	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Raja, Senior Principal Scientist and Professor, NAL – Bangalore. raja@nal.res.in	1. Dr.K.M.Parammasivam, Professor, MIT-Chennai. mparams@mitindia.edu	1. Mr <mark>.A.Vinoth</mark> Kumar, SRMIST.



Cours Code		8ASE314T	Course Name	TURBULENCE AND TURB	BULENCE MC	DELING			urse egory	Е				Prof	essioi	nal Ele	ective				T 0	P 0	C 3
		uisite Courses ering Departme		ASC202J ce Engineering		te Courses ok / Codes/Sta	Nil andards			Progres	sive Co	urses	3		18 Nil	BASES	307T						
CLR-1	: Unde		nt flow physics		551	,10	MC	1	Learnin 2	3	1	2	3	Pr 4	ogran 5			utcome 9		O) 11	12	13	14 15
CLR-2 CLR-3 CLR-4	: Ident : Asse	tify the type of ess the method	e and need for turbulence mod model for turbulent flow simu <mark>la</mark> lologies for turbulent flow s <mark>imu</mark>	ations		No. 10 a		king	Expected Proficiency (%)	Expected Attainment (%)		alysis		sign,	Usage	Culture	8	Team	ion	- త	arning		
CLR-5 CLR-6			ssification of shear flows ge acquired towards turbulent	flow simulations and experimer	nts		STATE OF THE PARTY	Level of Thinking	ected Pr	ected At	Engineering Knowledge	Problem Analysis	Design & Development	Anal <mark>ysis, Design,</mark> Research	Modern Tool Usage	Society & Cu	Sustainability Ethics	ndividual & Team	Communication	Project Mgt. &	ife Long Learning		0-2 0-3
CLO-1 CLO-2	: Unde		CLO): At the end of this count aspects of turbulent flows on turbulence closure and mo	urse, learners will be able to:	2 2	80 80	70 70 70	H Kng	. Pro	H H	- Ang	- Moc	- 800	Sustair		- Co	- Pro	- Life	-	M L M M			
CLO-3 CLO-4	: Deriv	ve the governir reciate the use:	ng equations for t <mark>urbulent</mark> flows fulness of RANS	10.7	2 2	80	70 70	H	1	H	L	- H	-	 		-	-	-	- Н	М М Н Н			
CLO-5 CLO-6	: Acqu	knowledge on iire compreher	LES and DNS nsive understan <mark>ding on t</mark> urbule	nt flow simulations and experin	ments		Part.	2 2	80	70 70	H	-	H M	L	<u>M</u>	-	- - М -		-	-			M M M M
Duration	on (hour)	Daview of he	sic fluid dynam <mark>ics</mark>	Trumbuda matinata	100	Valacity at a	9			0,00	guation	a al	9				f	- d-1		9			
S-1			ies and flow properties	Turbulent jets Flow field physics of jets		Velocity at a Velocity time					quation t-Allam						v²-f mo						
	SLO-2	Conservation		Turbulent wakes		Statistics	361163		-		ation mo		moder				Q-ζ m						
S-2			ntum and transport equations	Flow field physics of wakes		Statistical pro	pperties	W. 1	-		tages a		sadva	ntages			Q-ζ m						
	SLO-1	Flow classific		Mixing layers		Reynolds De					quation			nagoo				– ω mo	del				
S-3	SLO-2		Furbulent flow	Flow field physics of mixing la	avers	Reynolds Ave					tages a			ntages				– ω mo					-
S-4		Reynolds nu		Wall bounded shear flows	.,, 0.10		Reynolds Ave	raged			ard k-ε i			nagoo				r order		I			
3-4	SLO-2	Effect of Rey	nolds number on flow	Wall bounded shear flows		Continuity eq	Reynolds Ave			Stand	ard k-ε i	mode	1				Сотр	lete clo	sure				
S-5	SLO-1	How to define	e turbulence	Wall Y+	CAR	Momentum e	Reynolds Ave equation Reynolds Ave			RNG I	κ-ε mod	el					Reyno	olds Str	ess Ti	ranspo	rt Mod	lel (R	STM)
	SLO-2		cs of turbulence	Wall shear stress	M. T. A.	Momentum e	quation	rayeu			k-ε mod							olds Str		ranspo	rt Mod	lel (R	'STM)
S-6	SLO-1 SLO-2		cribing turbulent flows es associated with turbulent	Layers in boundary layers Layers in boundary layers		Reynolds Stre				Realizable k-ε model Realizable k-ε model					Wall functions Wall damping functions								
S-7	SLO-1	How to meas	eure turbulence	Energy cascade		Closure prob				Standard k-ω model						Assessment of turbulence models and its selection						nd its	
	SLO-2	Hot-wire Ane	mometer, LDA, PIV	Transfer of energy Need for modeling						Standard k-ω model						Need for transient simulations - LES							
S-8	SLO-1	Classification	of turbulent shear flows	Kolmogorov scales Eddy viscosity						SST k-ω model Governing equ					g equations for LES								
3-0	SLO-2	Classification	of turbulent shear flows	Dissipation	pothesis SST k-ω model Sub grid scale modeling																		

Durati	on (hour)	9	9	9	9	9
	SLO-1	Free shear flows	Homogeneous turbulence	Zero equation model	Advanced models	Hybrid models (DES)
S-9	SLO-2	Free shear flows	Isotropy and Anisotropy	IMixing length model	Requirements and needs for advanced models	Direct numerical simulation

Learning
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Resources

- Tennekes H, Lumley J.L., "A first course in turbulence", MIT Press, 1972.
 Pope S. B., "Turbulent flows", South Asian Edition, Cambridge University Press, 2009
- Kundu P. K., Cohen I M and Dowling D R, "Fluid Mechanics", 5th Edition, Academic Press, 2014
 Malalasekera, W., and H. K. Versteeg. An introduction to computational fluid dynamics: the finite volume method. PEARSON, 2009.

Learning	Assessment				1000		- "				
	Bloom's			Continuous	Learning Assessm	ent (50% weightage)		/		Final Evamination	n (E00/ woightogo)
	Level of	CLA – 1 (1	0%)	CLA –	2 (15%)	CLA - 3	(15%)	CLA – 4	<mark>1 (10%)</mark> #	Filiai Examinatio	n (50% weightage)
	Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Lovel 1	Remember	40 %		30 %	MARKET R	30 %		30 %		30%	
Level 1	Understand	40 %		30 %	444 5 10 0	30 %		30 %		30%	-
Level 2	Apply	40 %		40 %	25亿元的	40 %		40 %		40%	
Level 2	Analyze	40 %		40 %		40 %	The state of	40 %		40%	-
Level 3	Evaluate	20 %		30 %	51700 N	30 %		30 %		30%	
Level 3	Create	20 %	17 100	30 %		30 %		30 %		30%	-
	Total	100 %	4.	10	0 %	100	%	10	0 %	10	0 %

[#]CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. C. Boloni Kumor, CED Application Function Function Function Function	1. Dr. Joydeep Bhowmik, Aerospace and Applied Mechanics, IIEST Shibpur email:	1. Dr. Kannan B T, SRMIST
1. Dr. C. Palani Kumar, CFD Application Expe <mark>rt, DJAIR</mark> , Korea. Email: kumar@djair.co.kr	joydeep@aero.iiests.ac.in	2. Dr. Bharadwaj K K, SRMIST

Course Code	1	18ASE3151 HIGH TEMPERATURE GAS ITANIAMUS													Profe	ssional	Electi	ve			L 3	T 0	P 0	C 3
Pre-	enuisite	Courses 18	8ASC301 I		Co-requisite Course	as Nil				Pr	ogressiv	A Cours	20:		Ni	7								
		Department		Engineering			k / Coo	des/Standards	Nil		ogrossii	o Oour			1 11	'								
000,00	Jiioiiiig_	Dopartimont	71010000	Linginiooning	9	Data Book																		
Course I	earning	Rationale (CLR	:): The purpo	ose of learni	ing this <mark>course is to:</mark>	127				Learnir	ng				Pr	ogram	Learnii	ng Out	comes	(PLC))			
CLR-1:					ion <mark>of gases and c</mark> he	mically reacting ga	as		1	2	3	1	2	3	4	5 6	7				11	12	13 1	14 15
CLR-2:	Know	the microscopic	nature of gas a	nd the asso	ciated probable state	e and its calculatio	ns			>	Ħ													
CLR-3:	Demo	onstrate equilibri	um and nonequi	ilibrium no <mark>rn</mark>	<mark>nal and obl</mark> ique shoc	k flows			-	enc	Je.		S			age	ار		Ε			Б		
CLR-4:									king	Offici	aji.		lysi		Design,	US I	_ ≪	_	Геа	.u	∞ర	Learning		
CLR-5:									Ę	P.	Att	g a	√na	Jen	_ G	8 2	et S		•ర	cat	gt.	Fe		
CLR-6:	CLR-6: Understand the viscous high temperature flows and its significance in the real-world engineering problems								evel of Thinking	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Development	Anal <mark>ysis,</mark> I Researc <mark>h</mark>	Modern Tool Usage	Environment &	Sustainability Ethics	ndividual & Team Nork	Communication	Project Mgt. & Finance	Long	- C	-2 -3
-									Level of (Bloom)	be (be (gin	oble	ve ve	aly	ode	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	Sustair Ethics	Individ	E I	Project N Finance	e C	PSO.	PSO - PSO -
		Outcomes (CLC			urse, learners will be			A STATE OF THE STA					م د		A A				ĕ≥	ပိ	Ŗ	Life		
CLO-1:					etween calorically ar	nd thermally perfec	ct gas		2	85	80	H		-	-		-	-	-	-	-	-		M L
CLO-2 :					most probable state	d abliance absolutes			2	85	80	Н	-		-		-	-	-	-	-	-		H L
CLO-3:		iin the significant iin key aspects o			uilibirum normal and	oblique snock wa	ave	A STATE OF THE STA	2	80	75 75	H	M M		-		-	-	-	-	-	-		M L H L
CLO-4 .					riscid high temperatu	ro nonoguilibrium	flowo		2	80	75	Н	M		L		-	-	-	-	-	-		M L
CLO-5 :		in the viscous hi			isciu nigri temperatu	re nonequilibrium i	IIOWS		2	80	75	Н	M		Ī			_	-	-	-	-		M L
CLO-0.	Схріа	iii tiie viscous iii	ign temperature	HOWS				Carlotte Contract		00	73	1 11	IVI						_	- 1	-	- 1	,, ,,	VI L
Duration	(hour)		9			9		9		77				9							9			
		Nature of high t	temperature flow	/	Intro to statistical th	ermodvnamics	117			77														
S-1		Definition of rea			Microscopic descrip	otion of gases, mos	st	Governing equations for invise equilibrium flows	scia			ning equ uilibrium			VISCIO				ng equ viscou			nemic	cally	
(· · · · · · · · · · · · · · · · · · ·	SLO-2	Various forms o state			Limiting case: Boltz			Equilibrium normal and obliques			wave i						А		e form					
S-3	SLO-2	Various descrip gas mixture			Evaluation of therm terms of partition fu		ies in	Equilibrium quasi-one-dimen flows		nozzle	Noneq nozzle	uilibriun flows	n quas	i-one-	dimer	nsional		ounda eacting	ry layei gas	r equa	ations	for ch	nemic	ally
	SLO-2	Calorically perfe gas			Evaluation of partiti T and V			Frozen and equilibrium fows: distinction			Noneq	uilibriun	n blunt	-body	flows				ry cond					
SLO-2 and real gases properties for a single chemical species and frozen specific heats							Frozen and equilibrium flows: and frozen specific heats		brium	Binary	scaling	for no	nequil	libriun	n flows			ry layei nsfer fo					1-point	
		First and secon Calculation of e		dynami <mark>cs</mark>	Calculation of the e		nt	Frozen and equilibrium flows speed of sound	: equilil	brium	Noneq cone	uilibriun	flow	o <mark>ver</mark> b	lunte	d sh <mark>a</mark> rp	В	ounda	ry layei	r solu	tions :	nons	imilai	r flows
S 7	SLO-1	Gibbs free ener	gy and entropy		Calculation of the e for high-temperatur	quilibrium compos	sition	Equilibrium conical flow				uilibriun for s <mark>pac</mark>			hock-ı	wave			-shock- ally read			ons to	0	
S_8	SLO-1	Composition of reacting mixture	equilibrium cher	mically	Thermodynamic pro	operties of an		Equilibrium blunt-body flows:	circula	ar cone					charac	cteristic	, P	arabol	ized Na ally read	avier-	Stokes	solu	tions	to
S-9 SLO-1 Composition of equilibrium chemically SLO-2 reacting mixture: heat of reaction Equilibrium properties of high temperature orbiter						space	shuttle		i <mark>cally rea</mark>				um flov	/ F		rier-Sto			is to	chem	ically			

	1.	Anderson Jr, John D. Hypersonic and high-temperature gas dynamics. American Institute of Aeronautics and
Lograina		Astronautics, 2006.
Learning	2.	Bose, Tarit K. "High temperature gas dynamics." High Temperature Gas Dynamics. Springer, Berlin, Heidelbe
Resources		2004 250 204

berg, 2004. 259-281..

3. Rathakrishnan, Ethirajan. High enthalpy gas dynamics. John Wiley & Sons, 2014. Zucker, Robert D., and Oscar Biblarz. Fundamentals of gas dynamics. John Wiley &

Anderson, John David. Modern compressible flow: with historical perspective. Vol. 12. New York: McGraw-Hill, 1990.

Learning A	Assessment					NI I						
	Dia ana'a			Cont	inuous Learning Asse	ssment (50% weig	htage)			Final Evansination	a (EOO) waishtasa)	
Bloom's		CLA – 1	1 (10%)	CLA – 2 (15%)		CLA -	3 (15%)	CLA –	4 (10%)#	Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	40 %	- ·	30 %		30 %	73	30 %	h	30%	-	
Level 2	Apply Analyze	40 %		40 %		40 %	-\	40 %	(A) -	40%	-	
Level 3	Evaluate Create	20 %		30 %	AND STATE	30 %	h	30 %	-	30%	-	
	Total	100) %	10	0 %	10	0 %	10	0 %	10	0 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Expert
Mr. Amit Palankar, GE aviation, Bangalore, palankr.amit@gmail.com	Dr.Arun Kumar P, Indian Institute of Technology Jammu, email: arun.perumal@iitjammu.ac.in	Dr. <mark>Malaikann</mark> an G, SRMIST

	Course Code 18ASE316T Course Name HYPERSONIC AEROTHERMODYNAMICS					ırse gory	Е				Profes	sional	Elect	ive			- (. T	P 0	C 3
Pre-r	Pre-requisite Courses 18ASC301J Co-requisite Courses Nil Progressive Courses Nil																			
	Course Offering Department Aerospace Engineering Data Book / Codes/Standards Nil																			
Cours	Course Learning Rationale (CLR): The purpose of learning this course is to: Learning Program Learning Outcomes (PLO)																			
	CLR-1: Understand the hypersonic flow and importance of hypersonic flows 1 2 3 1 2 3 4 5 6										7					13 1	4 15			
CLR-2	: Unde		(ma	(%	(%	Φ	٠,						×							
	CLR-3: Demonstrate the shock-wave and expansion-wave and their significance in hypersonic flow								edg	200	2	a)				No.	n Finance			
CLR-4		w various approximate models for hypers				l) g	Sien	me	lwo	Sis	2 _	sag	<u>a</u>			믋	_ ii	ing		
CLR-5	inter	action	inviscid flows, boundary layer equations and sh	A SHARE BUILD		of Thinking (Bloom)	Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design,	Modern Tool Usage	Society & Culture	Environment & Sustainability		Individual & Team Work	Communication Project Mat. & F	-ear		
CLR-6	S: Unde	erstand the various hypersonic exp <mark>erimer</mark>	<mark>ntal f</mark> acilities and hypersonic vehicle aerodynam	ics		of T	ted	ted	eeri	ma /	Sis,	- E	⊗ >-	nab		_ al	in in	Sug	<u>-</u> c	-3
-						evel	Expected	bec	gi	Problem A	Analysis, I	odel	ciet	ivirci Istai	Ethics	<u>≅</u>	ojeci	Life Long I	PSO-	PSO-
			is course, learners will be able to:				ŭ		ш И					ந் ஜ						
CLO-2		cribe the hypersonic flow and th <mark>e charact</mark> cribe shock-wave and expansio <mark>n-wave r</mark> e				2	85 80	80 75	H	 М -		-	-	-	-		- - - -			И L И L
CLO-2		ain the importance of the simp <mark>lified mod</mark> e				2	80	70	Н	IVI -			_	-	-	-				VI L
CLO-4		ain the importance of the simplined mode ain various forms shock-shock interaction		The state of the s		2	80	75		М -	М			-	-	-				H L
CLO-			dary layer interaction and viscous interaction	100000000000000000000000000000000000000		2	80	75		M -	М	-	-	-	-	-				и <u>г</u>
CLO-6		ain the various techniques an <mark>d visualiz</mark> ati		Name of the last		2	85	80	Н	М -	Н	L	-	-	-	-		-	M I	Н М
Durati	on (hour)	9	9	9	-	₹4				9							9			
Duran	SLO-1	Basic concepts of hypersonic flow				-											<u> </u>			
S-1	SLO-2	Importance and physical aspects of hypersonic flow	Newtonian flow model for hypersonic flows	Governing equations for hypersonic			low model for hypersonic flows Governing equations for hypersonic flow Governing equations for hypersonic flow				nic	Intro to hypersonic vehicle aerodynamics								
0.0	SLO-1	Thin shock layer	Newtonian flow model for flat plate, circular	or flat plate, circular			Simila	aritv pai	amete	rs and	bounda	arv								
S-2	SLO-2	Entropy layer	cylinder of infinite span and sphere	Hypersonic small disturbance	e equatio	ons	conditions for viscous hypersonic flow				namics									
	SLO-1	Viscous interaction	Modified Newtonian theory	Hypersonic similarity parame	ter		Boundary layer equation for hypersonic													
S-3	SLO-2	Classification of hypersonic space transport vehicle	Centrifugal force corrections to Newtonian theory	Hypersonic equivalence princ	ciple		flow				3	Shuttle orbiter aerodynamics								
	SLO-1		Comparison of Newtonian with exact theory	-450-		Self-similar and non-similar solutions of hypersonic boundary layer Pre-flight prediction of aerodynamics			n of th	e orbit	er									
S-4	SLO-2	Effects if high temperature flow	Newtonian-Busemann theory	Blast-wave theory				rsonic t					F		neası	reme	nts of	the ork	iter	
S-5	SLO-1	Communication blackout	Mach number independence principle I him check layer theory			Prediction of transition						s								
	SLO-2 SLO-1	Low density flow Free molecular flow					Hypersonic turbulent boundary layer				X-15 aerodynamics									
S-6	SLO-2 Hypersonic flight paths range in wedge range in cone methods shapes			shapes		effects on entropy layer measurements for hype			hype.		low									
S-7				Shock-shock interactions in I	nyperson	nic			hock-v	vave/b	oundar	y layei		lypers						
-	SLO-2	high Mach numbers	TIOW				interactions				Hypersonic shock tunnel									
0 0	SLO-1	Hypersonic Expansion-wave relations	Shock-expansion method for airfoil and an	Different types of sheet sheet	de intores	otions	Strong and weak hypersonic viscous				ľ	Gun tunnel, arc-jets								
ა-გ	SLO-2		ogive and its comparison with experiment and method of characteristics	Dillerent types of snock-snoc	k interac	cuons	intera	-					F	ree pi	iston v	vind t	unnel			

Duration (hour)		9	9	9	9	9
S-9	151 ()-1	7.	1	CFD techniques for hypersonic inviscid flow	Role of similarity parameter in hypersonic viscous interaction	Ludwig tube
3-9	SLO-2	Tutorial problems	Tutorial problems	Tutorial problems	Lutorial problems	Measurement and visualization techniques in hypersonic flow

	1.	Anderson Jr, John D. Hypersonic and high-temperature gas dynamics. American Institute of	4.	Brun, Raymond. Introduction to reactive gas dynamics. OUP Oxford, 2009.
Lograina		Aeronautics and Astronautics, 2006.	5.	Davis, Harry J., and Herbert D. Curchack. Shock tube techniques and instrumentation. No. HDL-TR-1429. HARRY
Learning Resources	2.	Bertin, J. J. "Hypersonic Aerothermodynamics, AIAA, Education Series, Washington, D."		DIAMOND LABS ADELPHI MD, 1969.
Resources		(1994).	6.	Burtschell, Y., R. Brun, and D. Zeitoun. "Two dimensional numerical simulation of the Marseille University free piston
	3.	Hayes, Wallace. Hypersonic flow theory. Elsevier, 2012.		shock tunnel-TCM2." Shock Waves. Springer, Berlin, Heidelberg, 1992. 583-590.

Learning A	Assessment			1 /								
	Continuous Learning Assessment (50% weightage)							#7/L		Fig. 1 F (F00/ i - b.t)		
	Bloom's	CLA –	CLA – 1 (10%)		CLA – 2 (15%)		3 (15%)	CLA – 4	1 (10%)#	Final Examination (50% weightage)		
	Level of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Laval 1	Remember	40.0/		20.0/	40.00	30 %		30 %		30%		
Level 1	Understand	- 40 %		30 %	The state of the s	30 %		30 %		30%	-	
Level 2	Apply	40 %		40 %	Tilly or Wall	40 %		40 %		40%		
Level 2	Analyze	40 /0		40 /0		40 /6	47 1000	40 /0		4070	-	
Level 3	Evaluate	20 %	- P - 1	30 %	The state of the s	30 %		30 %		30%		
Level 3	Create	20 %	- J	30 %		30 %	DRIGO MA	30 %		30%	-	
	Total	10	0 %	100	1 %	100) %	10	0 %	10	0 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Inte <mark>rnal Expe</mark> rt
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