B. Tech in Biomedical Engineering

2018 Regulations

Professional Elective Courses (O)

Department of Biomedical Engineering SRM Institute of Science and Technology SRM Nagar, Kattankulathur – 603203, Kancheepuram District, Tamilnadu

				Category		3	0	0	3
Pre-requisite Nil Courses		Co-requisite Nil		Progressive Courses	Nil				
Course Offering Department	Biomedical Engineering		Data Book / Codes/Standards	Nil					

Course Le	se Learning Rationale (CLR): The purpose of learning this course is to:				earnin	ıg				ı	Progra	ım Lea	arning	Outco	mes (F	PLO)					
CLR-1:	To Know the concepts of spec	troscopy		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	To Know the concepts of various	us biosensors								등			ıţ								
CLR-3:	Outline the various application	s of biosensors in medicine		(E)	(%)	(%)	Φ		_	ਗ਼ੌ			labil		¥						
CLR-4:	To understand the concepts of	f various microscopes used in medicine		(Bloom)			ledg		men	Rese	<u>e</u>		stainability		Work		Finance	_			
CLR-5:	Acquire knowledge on the trea	ntment mechanism of Phototherapy		ging	Proficiency	Attainment	, now	nalysis	Development	igu,	Usage	Culture	& Su:		Team	ioi	Ē	arning			
CLR-6:	To understand the special tech	nniques like optical holography		of Thinking	-	ed Atta	ering k	⋖	∞	s, Design,	T00	∞ŏ	ment		∞ŏ	Communication	Mgt. &	۳	_	2	က
Course Le	earning Outcomes (CLO):	At the end of this course, learners will be able to:		Level o	Expecte	Expected	Engineering Knowledge	Problem	Design	Analysis,	Modern	Society	Enviror	Ethics	Individual	Comm	Project	Life Long	PS0	PSO - 2	PS0 -
CLO-1:	Implement spectroscopy for b	piological imaging		1, 2	80	70	Μ	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2:	Implement the various applica	ations of biosensors in medicine		1, 2	80	70	-	-	-	М	-	-	-	-	-	-	-	М	М	-	-
CLO-3:	Implement Microscopy in med	dical diagnosis		2	80	70	-	-	-	М	-	-	-	-	-	-	-	М	М		-
CLO-4:	Identify the principle behind n	nodern imaging techniques		1	80	70	-			М	-	-	-	-	-	-	-	М	-	М	-
CLO-5:	Describe the medical applicat	ions of phototherapy	·	1	80	70	-	-	-	М	-	-	-	-	-	-	-	М	-	-	-
CLO-6:	Analyze the physics behind o	ptical holography		1,2	80	70	-	-	-	-	-	-	-	-	-	-	-	Н	-	-	-

	ration	Light - Matter Interaction & Principle Of Optics	Optical Biosensors	Bio-Imaging	Photodynamic Therapy	Optical Holography
(1	nour)	9	9	9	9	9
S-1	SLO-1	Concepts of Light matter interaction	Biosensors: Definition	Introduction of optical imaging	Basics of radiation therapy	Fundamentals - Object wave
3-1	SLO-2	Interactions Between Light and a Molecule	Block diagram & description	Needs of optical imaging	Basic principles	Photography
0.0	SLO-1	Interaction of light with bulk matter	Principles of Optical Bio sensing	Microscopy: Principles	Mechanism of Photodynamic Photo oxidation	Holography
S-2	SLO-2	Fate of Excited State	Bio recognition	Types of microscopy: Transmissionmicroscopy	Photosensitizers For Photodynamic Therapy	Interference during recording
S-3	SLO-1	Spectroscopy: Principles	Optical Transduction	Fluorescence microscopy	Photosensitizers For Photodynamic Therapy	Diffraction during reconstruction
3-3	SLO-2	System description	Fluorescence Sensing, FluorescenceEnergy Transfer Sensors	Scanning microscopy	Mechanism of photodynamic action	Imaging techniques –In line hologram

S-4	SLO-1	Types of spectroscopy	Molecular Beacons, Optical Geometries of Bio sensing	Inverted and Upright Microscopes	Three Principal Mechanisms of Photodynamic Therapy	Off axis hologram, Fourier hologram
	SLO-2	Conventional Spectrometers	Immobilization of bio-recognition elements	Confocal Microscopy	Light Irradiation For Photodynamic Therapy	Fraunhofer hologram, Reflection hologram
0.5	SLO-1	Fourier Transform Spectrometers	Fiber optic Biosensors	Multi-photon- microscopy	Light sources	Optical properties of holographic imaging
S-5	SLO-2	Michelson interferometer	chelson interferometer Operating principles of Fiber optic Biosensors		Laser dosimetry	Hologram of an object
S-6	SLO-1	Electronic absorption spectroscopy	Types of optical biosensor: Fiber optic Biosensor	Total Internal Reflection Fluorescence Microscopy	Light delivery	Image equation, Angular magnification
3-0	SLO-2	Types of Electronic Transitions	Planar waveguide Biosensor Near-Field Optical Microscopy Two-Photon		Two-Photon Photodynamic Therapy	longitudinal magnification, Imageaberrations
S-7	SLO-1			Fluorescence Resonance Energy Transfer (FRET) Imaging	PUVA technique	Properties of light source -spectral bandwidth
	SLO-2	Electronic luminescence spectroscopy	Principle of Evanescent Wave Biosensors	Fluorescence Lifetime Imaging Microscopy (FLIM)	PUVA technique	Image plane holograms
•	SLO-1	Vibrational spectroscopy	Interferometric biosensor	Advantages and disadvantages of optical imaging	Applications of PDT	Image luminance- Without pupil
S-8	SLO-2	Principle of Vibrational spectroscopy	Surface plasmon resonance Biosensor	Applications of Bio imaging, Fluorophores as Bio imaging Probes	Applications of PDT	With pupil, Image plane holograms
S-9	SLO-1	Fluorescence spectroscopy	Applications of optical Biosensors in medicine	Green Fluorescent Protein, CellularImaging	Advantages of PDT	Speckles- diffuser
J-9	SLO-2	Fluorescence Correlation Spectroscopy	Advantages and Disadvantages	Tissue Imaging, In Vivo Imaging	Disadvantages of PDT	Resolution, Incoherent illumination

	1. Wilson J and Hawkes J.F.B, "Optoelectronics - An Introduction", Prentice Hall of India Pvt. Ltd., NewDelhi, 3rd
Learning	edition, 2003.
Resources	2. Leon Goldman, M.D., & R.James Rockwell, Jr., Lasers in Medicine, Gordon and Breach Science PublishersInc.,
	1975.

3. Tuan Vo Dirh, Biomedical Photonics – Handbook, CRC Press, Bocaraton, 2003. 4. Paras N, Prasad, "Introduction to Biophotonics", John Wiley & Sons, FirstEdition,

5. Gerhard K. Ackermann, Jürgen Eichler, "Holography: A Practical Approach", WILEY-VCH Verlag GmbH & Co, first edition, 2008.

Learning Asses	sment										
	Dis seeds I seed of			Co	ontinuous Learning Asse	essment (50% weighta	ge)			Final Evannination /	FOO(waishtaga)
	Bloom's Level of	CLA – 1	(10%)	CLA – 2	(15%)	CLA – 3	(15%)	CLA – 4 (10%)#	Final Examination (50% weightage)
	Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Lavald	Remember	40.0/		40.0/		40.0/		00.0/		000/	
Level 1	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
l aval 0	Apply	40 %		40 %		40.0/		40 %		40%	
Level 2	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate	20 %		20 %		20 %		30 %		30%	
Level 3	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	100	0 %	10	0 %	100	100 %		

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldives	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1.Dr.P.Vinupritha,SRMIST

Course Code	18BME262T	Course Name	HOME MED	DICARE TECHNOLOGY	Course Category	Е	Professional Elective	L 3	T 0	P 0	C 3
Pre-requisi Courses Course Offeri	INII	Biomedical Engineering	Co-requisite Courses	Nil Data Book / Codes/Standards	Progres Cours		Nil				

	7																	7
Course Learning Rationale (CLR): The purpose of learning this course is to:	L	earnir	ng					Progra	am Le	arning	Outco	omes (F	PLO)					
CLR-1: Utilize the Home health Nursing practice	1	2	3	•	2	3	4	5	6	7	8	9	10	11	12	13	14 15	j
CLR-2: Utilize homecare care working with different clients	(mo	(%)	(%)	4								~						
CLR-3: Utilize the various medical devices used at home	<u> </u>			de)	ent						Work		8				
CLR-4: Utilize the advancement in medical technologies	- (B)	ency	l e	<u>8</u>	ω,	l d	_	age	a)				_	Finance	g			
CLR-5: Utilizte the use of wireless technology in health care	Thinking	oficie	Attainment	Knowledge	Analysis	dole/	ign,	Tool Usage	Culture	∞ 、		eam	at ioi	∞	arning			
CLR-6: Utilize the various mode of healthcare technology at home	j≓	4	A#	٦	\ \	è	Des	. 0		nent		× ⊥			Ĕ			
		ected	eg	i.i.	E	∞ ~	sis, l	Ė	∞ >	= -		nal	Ę	t Mgt.	ong	_	3 2	
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level	Expect	Expected	Engineering	Problem	Design	Analys	e e	Society	Enviror Sustair	Ethics	Individual	Communic	Project	Life Lo	PSO -	PSO -	
CLO-1: Applying Home health Nursing practice	3	80	75	L	-	-	-	-	-	-		-	-	-	-	L	- L	1
CLO-2: Illustrate the homecare care working with different clients	3	80	70	L	-	-	-		-		-	1	-	-	-	L	- L	
CLO-3: Analyze the various medical devices used at home	3	75	70	М		-	-		-		-	1	-	-	-	L	- L	
CLO-4: Identify the advancement in medical health technologies	3	80	75	М	-	-	-	-	-	-	-	-	-	-	-	L	- L	
CLO-5: Analyze the use of wireless technology in health care	3	80	70	М	-	-	-	-	-	-	-	-	-	-	-	L	- L	
CLO-6: Describe the various type of healthcare technology at home	3	80	70	L	-	-	-	-	-	-	-	•	-	-	-	L	- L	1

	Introduction to Home health Nursing	Working With Clients	Medical Devices At Home	Advancement In Medical Technologies	Wireless Technology
Duratio	on (hour) 9	9	9	9	9
S-1	SLO-1 Home health care – purpose	Basic human needs	Medical devices at home	Advances and trends in health care technologies	Wireless communication basics
3-1	SLO-2 Organization of homecare system	Communication and interpersonal skills	Medical devices at home	Advances and trends in health care technologies	Wireless communication basics
	SLO-1 Historical development of home care	Caregiver observation	ECG monitors	Driver impacting the growth of medical Technologies	Types of wireless network
S-2	SLO-2 Environmental influences of home care	Caregiver observation	ECG monitors	Driver impacting the growth of medical Technologies	Types of wireless network
S-3	SLO-1 Home care Organization	Recording and reporting, confidentiality.	Smart watch	Impact of Moore"s law of medical imaging-	Body area network
3-3	SLO-2 Legal and ethical issues in home care	Recording and reporting, confidentiality.	Smart watch	Impact of Moore"s law of medical imaging	Body area network
S-4	SLO-1 Case management and leadership strategies	Working with elderly – aging and body systems.	Wireless infant monitoring system	E-health and personal healthcare	Emergency rescue
3-4	SLO-2 Organisation of home care system	Working with elderly – aging and body systems.	Wireless infant monitoring system	E-health and personal healthcare	Emergency rescue
	SLO-1 Home care organization	Working with children	PCG monitors,	Defining the future of health Technology	Remote recovery

S-5	SLO-2	Home care organization	Working with children	PCG monitors,	Defining the future of health Technology	Remote recovery
0.0	SLO-1	Role of home care nurse and orientation	Need for home care	Medical alert services.	Inventing the future -tools for self-health	Personalized ambient monitoring
S-6	SLO-2	Role of home care nurse and orientation strategies	Need for home care		Inventing the future -tools for self-health	Personalized ambient monitoring
	SLO-1	Environmental influences on home care	Mobility transfers and ambulation	Activity monitors	Future of Nano fabrication molecular scaledevices	Future trends in healthcare technology.
S-7	SLO-2	Environmental influences on home care	Mobility transfers and ambulation	Automatic wireless healthcare monitoringsystem	Future of Nano fabrication molecular scaledevices	Future trends in healthcare technology.
S-8	SLO-1	Infection control in home	Range of motion exercises	The ventilator dependent patient	Future of telemedicine	Multi model interaction and technologies forcare at home
3-8	SLO-2	Infection control in home	Range of motion exercises,	Device for patient with congestive heart failure	Future of telemedicine	Multi model interaction and technologies forcare at home
S-9	SLO-1	Patient education in home.	Skin care and comfort measures	Device for Patient with chronic Obstructive pulmonary disease	Future of medical computing	Cost of home healthcare
3-9	SLO-2	Patient education in home.	Skin care and comfort measures	Device for patient with Diabetic Mellitus	Future of medical computing	Direction for emerging technology

Learning	1.	Robyn Rice, "Home care nursing practice: Concepts and Application", 4th edition, Elsevier, 2006.	3.	Yadin David, Wolf W. von Maltzahn, Michael R. Neuman, Joseph. D,Bronzino, "Clinical Engineering", CRC Press, 2010.
Resources	2.	2. LodewijkBos, "Handbook of Digital Homecare: Successes and Failures", Springer, 2011.	4.	Kenneth J. Turner, "Advances in Home Care Technologies: Results of the match Project", Springer, 2011.

Learning Assess	ment										
	Bloom's Level				ontinuous Learning Asse					Final Evancination /	FOO(waishtaga)
		CLA – 1	(10%)	CLA – 2	(15%)	CLA – 3	(15%)	CLA – 4 ((10%)#	Final Examination (50% weightage)
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10	0 %

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Course Designers		
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		2. Mrs.Lakshmi Prabha.P, SRMIST

Course Code	18BME263T	Course Name	(CELLULAR AND M	DLECULAR BIOLOGY			urse egory	E	E Professional Elective L T 3 0				T 0	P 0	C 3								
Pre-requ Course Course Off		Biomedical		quisite Nil urses	Data Book / Codes	Standards		ressiv		lil														
Course Lea	arning Rationale (CLR):	The purpose	e of learning this course	is to:			Le	arnin	g					Progra	ım Lea	arning	Outco	mes (PLO)					
CLR-1:	Have an idea about the basi	cs of cells					1	2	3	Ī	1	2	3 4	5	6	7	8	9	10	11	12	13	14	15
	Know the basic aspects of co		nctions							ŧ			5											_
CLR-3:	Learn the principles of cell si						(mc	(%)	(%)		<u>a</u>		Design, Research					논		4				
CLR-4:	To understand the concept of						Thinking (Bloom)	Proficiency (%)	nt (edg		Development Design, Rese	Ф				Work		Finance				
	Understand the concept beh) g	iei	i me		₩ 	. <u>s</u>	n,R	sag	<u>e</u>			Team	Ę	-iu	ing			
CLR-6:	Learn about cell replication a	nd repair					n <u>Ŗ</u> i	ofic	Itair		줃	Analysis	eve esig	ž	Culture	t &		Te	atic	∞ŏ	Learning			
	arning Outcomes (CLO):		of this course, learners v	vill be able to:			Level of	Expected	SExpected Attainment		Engineering Knowledge		Design & De Analysis, De	Modern Tool Usage	Society & C	Environment & Sustainability	Ethics	8 Individual	Communication	Project Mgt.	Life Long Le	PS0 - 1	PS0 - 2	PS0 - 3
CLO-1:	Explain the basics of cell a						1, 2	80			М	-	- -	-	-	-	-	-	-	-	-	-	-	-
CLO-2:	Describe the basic concepts						1, 2	80	70		-	-	- M	-	-	-			-	-	М	М	-	-
CLO-3:	Implement the various proce		ling and cell regulation		-		2	80	70		-	-	- M	-	-	-			-	-	М	М		-
CLO-4:	Understand the concept of				<u> </u>		1	80	70		-	-	М	-	-				-		М	-	М	-
CLO-5:	Explain the structures and p						1	80	70		-	-	- M	-	-	-			-	-	М	-	-	-
CLO-6:	Apply the recent advancem	ents in cell repair a	and replication				1,2	80	70		-	-		-	-	-			-		Н	-	-	-

	ration	An Overview Of Cells	Cell Structure And Function	Cell Signaling –Cell Regulation	Introduction To MolecularBiology– DNA And RNA	Replication And Repair
,	hour)	9	9	9	9	9
S-1	SLO-1	Origin and evolution of cells	Introduction to Nucleus	General principles of cell signaling	Scope and history	Replication in prokaryote and eukaryote
3-1	SLO-2	Origin and evolution of cells	Endoplasmic reticulum	Modes of cell	Structure of DNA	Types and function of DNA
S-2	SLO-1	Evolution of metabolism	Golgi apparatus and Lysosomes	Cell signaling	Nucleoside	Polymerases
3-2	SLO-2	Origin of Prokaryotes	Golgi apparatus and Lysosomes	Pathways of intracellular signal transduction	Nucleotide	Proof reading activity
	SLO-1	Origin of Eukaryotes	Bioenergetics and Metabolism	Function of cell surface receptors	Base pairing	5'- 3' exonuclease activity
S-3	SLO-2	Development of multicellular organisms	Mitochondria	G-protein coupled receptor pathway(GPCR) pathway	Base stacking	Topoisomerase activity
S-4	SLO-1	Development of multicellular organisms	Chloroplasts	Cyclic adenosine 3',5'-monophosphate (cAMP) pathway	Double helix	Telomeric DNA replication and Plasmid replication
3-4	SLO-2	Cells as experimental models	Peroxisomes	Receptor protein tyrosine kinase pathway	Features of Watson and crick model	Theta model

S-5	SLO-1	Tools of cell biology	The cytoskeleton and cell movement	Mitogen-activated protein kinase (MAPK) pathway	Major and minor groove	Strand replacement model
3-3	SLO-2	Tools of cell biology	Cell surface	Cell division : Cell cycle	Supercoiling	Rolling circle model
S-6	SLO-1	Molecular composition	Transport of small molecules	Mitosis - Stages of mitosis	Twist	DNA repair
3-0	SLO-2	Biosynthesis of cellular constituents	Endocytosis	Meiosis - Meiosis I and Meiosis II	Writhe and linking number	Nucleotide excision repair
6.7	SLO-1	Central role of enzymes as biocatalysts	Cell –cell interactions	Cell death: Necrosis	Forms of DNA	Mismatch repair
S-7	SLO-2	Central role of enzymes as biocatalysts	Cell –cell interactions	Programmed cell death	A, B, Z - Structure and function of RNAs	Photo-reactivation
0.0	SLO-1	Metabolic energy	Adhesion junctions	Apoptosis	mRNA	Recombination repair
S-8	SLO-2	Metabolic energy	Tight junctions	Extrinsic pathway, Intrinsic pathway	rRNA	Recombination repair
	SLO-1	Cell membrane	Gap junctions	Cell differentiation: Stem cells-embryonicstem cells	tRNA	SOS repair
S-9	SLO-2	Cell membrane	Plasmodesmata	Adult stem cells, therapeutic applications of stem cells	Secondary structures in RNA	SOS repair

Learning Resources	 Channarayappa, "Cell biology," Universities Press, 2010 Rastogi, S.C, "Cell biology," New Age International publishers, 2005.
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Learning Asse	essment										
	Bloom's Level			Co	ontinuous Learning Ass	essment (50% weighta	ge)			Final Evamination	FOO(waightens)
		CLA – 1	(10%)	CLA – 2	(15%)	CLA – 3	(15%)	CLA – 4 (10%)#	Final Examination	50% weightage)
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	00 %	100	0 %	10	00 %	100	0 %	10	0 %

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.PVinupritha, SRMIST

Course Code	18BME264T	Course Name	BIOMEDICAL I	ASER INSTRUMENTS	Course Category	Ε	Professional Elective	L 3	T 0	P 0	C 3
Pre-requisite Courses	NII		Courses	Nil	Progres Cours		Nil				
Course Offering	g Department	Biomedical Engineering	na	Data Book / Codes/Standards	Nil						

Course Lea	rning Rationale (CLR):		The purpose of learning this course is to:	Lear	nina						Progra	am Lea
CLR-1:	Know the functioning of a laser		-	Loui	9						ı iogic	AIII ECU
CLR-2:	Learn about the working princip	ole of laser		1	2	3	1	2	3	4	5	6
CLR-3:	Learn the optical characteristics	s of tissue								_		
CLR-4:	Familiarise the applications of la	aser in Urology, Gynecology ar	nd dentistry	(Bloom)	(%)	(%)	ge		ŧ	earc		
CLR-5:	Learn the non- thermal applicat	tions of laser in medicine		g (Blo	ency	nent	Knowledge	S	pme	,Res	Usage	Φ
CLR-6:	Acquire knowledge on laser sat	fety and management		Thinking	Proficiency	Attainment		Analysis	Development	Design,Research	Tool Us	Culture
Course Le	arning Outcomes (CLO):	At the end of this course, lea	arners will be able to:	evel of T	Expected	Expected	Engineering	Problem A	Design &	Analysis, I	Modern To	Society &
CLO-1:	Have a deep understanding on	technical aspects of a LASER	system	3	80	75	-	-	-	٠.	-	-
CLO-2:	Learn about the working princip	ole of laser		3	80	70	М	-	-	-	-	-
CLO-3:	Describe the optical properties	of tissues		3	75	70	-	М	-	-	-	-
CLO-4:	Describe the applications of las	er in Urology, Gynecology and	dentistry	3	80	75	-	М	-	-	-	-
CLO-5:	Explain the non- thermal applica	ations of laser in medicine		3	80	70	-	-M	-	-	-	-
CLO-6:	Implement the aspects of laser	safety		3	80	70	-	-	-	-	-	-

	Program Learning Outcomes (PLO)													
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design,Research	Modern Tool Usage	Society & Culture	Environment &Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
-		-		-	-	-	-	-		-	-			-
М		-	-	-		-	-			-		М		-
-	М	-	-	-	-	-	-	-	-	-	-		М	
-	М	-	-	-	-	-	-	-	-	-	-	М		
-	-М	-	-	-	-	-	-	-	-	-	-	М		
-			-	-	-	-	М			-	-	L		

Duratio	on (hour)	Laser System	Types Of Laser	Mechanism Of Laser TissueInteraction	Laser Applications	Non Thermal Applications Of LaserAnd Laser Safety Management
	. (,	9	9	9	9	9
S-1	SLO-1	Absorption and Emission of Radiation by atoms	Classification of Laser	Photochemical interaction	Disorders in Eye	Optical coherence tomography
3-1	SLO-2	lons and Molecules	Solid state Laser Construction		Diagnostic and Therapeutic Applications of laser in ophthalmology	System description
S-2	SLO-1	Laser - Definition	Working principle	Thermal interaction	Dermatological disorders	Applications of Optical coherence tomography
3-2	SLO-2	Properties of laser	Atomic laser Construction	Heat generation	Applications of Lasers in dermatology	Laser Induced Fluorescence (LIF)-Imaging,
0.0	SLO-1	Characteristics of Laser	Working principle	Heat transport	Diagnostic Applications of Lasers in cardiology	FLIM Raman Spectroscopy and Imaging
S-3	SLO-2	Construction and working principle of lasersystem	Molecular Laser Construction	Heat effects	Therapeutic Applications of Lasers incardiology	FLIM – Holographic and speckle
	SLO-1	Mono-chromaticity, Coherence	Working principle	LASER induced interstitial thermotherapy (LITT)	Lasers in Surgery	Laser hazards

S-4	SLO-2	Directionality, Brightness	Dye Laser Construction	Photoabalation	Tissue welding and Soldering	Laser hazards
S-5	SLO-1	Pumping mechanism	Working principle	Model, cytotoxicity of UV radiation	Lasers in urology- Lithotripsy	Laser hazards classification
	SLO-2	Optical pumping	Semiconductor Laser Construction	Plasma induced ablation	Therapeutic applications of Lasers in urology	Laser hazards classification
S-6	SLO-1	Electrical pumping	Working principle	Model, analysis of plasma parameters	Laparoscopy- System description	Laser hazards to eye and skin
3-6	SLO-2	Laser pumping, Levels of laser	Gas Laser Construction	Photo distribution	Applications of laser in Gynecology	Viewing laser radiation
S-7	SLO-1	Resonators	Working principle	Plasma formation	Applications of laser in Gynecology	Non beam hazards
3-7	SLO-2	Q-switching	Chemical Laser Construction	Shock wave generation	Applications of laser in laryngeal surgery	Non beam hazards
S-8	SLO-1	Methods of Q-switching	Working principle	Shock wave generation	Applications of laser in Otology	Laser safety control
3-8	SLO-2	Gain switching	Metal-vapor lasers construction	Cavitation	Applications of laser in neurology	Laser signage
S-9	SLO-1	Mode locking and its types	Working principle	Jet formation.	Applications of Lasers in dentistry	Laser risk management
3-9	SLO-2	Cavity damping	Free-electron laser construction and working	Jet formation.	Applications of Lasers in Orthopedics	Good laser safety practices

Learning Resources

- 1. Leon Goldman, M.D., & R.James Rockwell, Jr., Lasers in Medicine, Gordon and BreachScience Publishers Inc., 1975.
- Abraham Katzir, Lasers and Optical Fibers in Medicine, Academic Press Edition, 1998.
- Markolf H.Niemz, _Laser Tissue Interaction-Fundamentals and Applications", Springer, Third edition, 2007.
- Tuan Vo Dirh, Biomedical Photonics Handbook, CRC Press, Bocaraton, 2003. Glasser, O., Medical Physics -- Vol 1, 2, 3 Adam Hilgar Brustol Inc, 1987.
- G.David Baxter, Therapeutic Lasers Theory and practice, Churchill Livingstone Publications

Learning Assessm	ent										
	Dia anala i anal			Final Francischies (
	Bloom's Level	CLA – 1	(10%)	CLA – 2	(15%)	CLA - 3	(15%)	CLA – 4 (10%)#	Final Examination (50% weightage)
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	10	0 %	100	100 %		00 %	10	0 %	100) %

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. P. Vinupritha, SRMIST

Cauras Cada	40DME205T	Course Name	ADTICION ODCA	UC AND TICCUE ENGINEEDING	Course Category	_	Dynfaccional Floatives	L	Т	Р	С	
Course Code	18BME265T	Course Name	ARTIFICIAL ORGAI	ARTIFICIAL ORGANS AND TISSUE ENGINEERING			Professional Electives	3	0	0	3	
Pre-requisite Courses	Bas	ic Biology and Biomaterials	Co-requisite Courses	Nil	Progre Cou		Nil					
Course Offering D	epartment	Biomedica	Biomedical Engineering Data Book / Codes/Standards				Nil					

Course Lea	arning Rationale (CLR): To study the learners to acquire knowledge to the basic properties of biomaterials and various biomaterials used in biomedical applications.	L	.earnir	ıg					Prog	gram L	earning.	Outco	mes (Pl	LO)					
CLR-1:	learn the fundamentals of various organs	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Study the different biomaterials used in artificial organs		>-	=											Finance				
CLR-3:	Acquire basic knowledge of various types of artificial organs	Б	enc	Attainment		Sis.		-	Usage	æ			ε	L	ina	ng			
CLR-4:	Familiarize with basic biological system in human system	÷	Proficien	tain		_		esign,	Ns	Culture	∞ _≥		Team	atio	∞	earning			
CLR-5:	Obtain the concept of different types biomaterials applied in-vitro test tissue engineering application	Thinking	Ā.	T A	ing	A P		اج ۵	T00	S S	ment & ability		∞ =	nica	Mgt.				
CLR-6:	Have an Gain the knowledge about technology transfer and ethical problem	Jo e	cted	sctec	ngineering	Problem	gn &	ysis, eard	E		ronna	S	idua	ommunication	roject N	Long	-	-2	.3
Course Le	arning Outcomes (CLO): At the end of this course, learners will be able to:	Level		1119	Engi	Prob	Design	Anal	Modern	Society	Environme Sustainab	Ethics	Individual a	Con	Proje	Life	PSO	PSO	PSO
CLO-1:	Understand the basic Knowledge of artificial organs	1, 2	80%	70%	L				L							L			М
CLO-2:	Analyze various types of materials used in implant applications.	2	80%	70%	L				М							М			М
CLO-3:	Explain the process of importance of Tissue organization	2	80%	70%	L				М							L			М
CLO-4:	Select appropriate class of polymers using scaffold applications	3	80%	70%	М											L	М	М	
CLO-5:	Understand the concepts different types biomaterials applied in-vitro and in-vivo biomedical implant application.	3	80%	70%	М											М	М	М	
CLO-6:	Apply the various biomaterials used in implants and artificial organs	3	80%	70%	М		М	Н										М	М

		Basics of artificial organ	Types of Artificial organs	Basics concepts of tissue engineering	Types and application of tissue engineering	Recent advancement of tissue engineering
Duration	(hour)	9	9	9	9	9
S-1	SLO-1	Introduction -artificial organ	Introduction to Biomaterials in Ophthalmology	Introduction to Tissue engineering	Scaffolds for tissue engineering	Immunochemical techniques in tissue engineering and biomaterial science
0-1	SLO-2	Immunological considerations	Anatomy of eye	Cell source	Classes of potential scaffold materials	Basic immunological principles
S-2	SLO-1	Blood transfusion	Viscoelastic solution	Types of cell Sources	The criteria for an ideal scaffold	Common immunochemical techniques usedin biomaterials
	SLO-2	Artificial kidney	Contact lenses	Three-dimensional interactions	Polymer scaffolds	Immunochemical applications in biomaterial science and tissue engineering research
	SLO-1	Cardiovascular organ	Optical implants	Cells as therapeutic Agents with examples, Cell numbers and growth rates.	Polymer scaffolds applications	Clinical applications of tissue engineering
S-3	SLO-2	Vascular organ	Scleral buckling materials for retinaldetachment	Tissue organization	Bioactive ceramic scaffolds	Cell source, Stable 3D constructs
S-4	SLO-1	Cardiac pacemakers	Artificial exchange systems: Blood viscosity		Bioactive ceramic scaffolds and its applications	Cartilage
	SLO-2	Introduction to Kidney organ	Effects of shear on blood cells	Tissue types, Functional subunits.	Substrate Scaffold Materials	Tendons, ligaments and bone

	Artificial Kidney	Blood-air interactions	Tissue Dynamics, Dynamic states of tissues	Nano Composites	Regeneration in the cardiovascular system
SLO-2	Artificial Lung	Blood flow in artificial devices	Homeostasis in highly prolific tissues and Tissue repair. Angiogenesis	Control of architecture	3D printing techniques in cardiac stent andbone scaffold
SLO-1	Liver implant	Exchangers	Measurement of cell characteristics - cell morphology	A guide to basic cell culture and applications in biomaterials and tissue engineering	Regulatory classification of biomaterialsand medical devices
SLO-2	Artificial Pancreas	Hemodialysis	Cell number and viability	sterilization of scaffolds	Classification of medical devices
SLO-1	Bone, Bone Marrow, and Hands	Soft Tissue Applications	Cell-fate processes, cell motility,	Sterilization methods	Differences between FDA and EU regulations
SLO-2	Skin and Hair organ	Bulk space fillers	Cell function.	Cell culture protocols	How do companies get through the FDA Process?
SLO-1	Artificial ear	Maxillofacial implants	Cell-extracellular matrix interactions -	Basic techniques for assessment of cell viability	Technology transfer and Technology transfer paths
SLO-2	Artificial Nose	Fluid transfer implants	Binding to the ECM, Modifying the ECM,	culture environment	Efficient technology transfer and Factorsaffecting rapid technology transfer
SLO-1	Regeneration and Potential Future Uses forStem Cells	Functional load-carrying and supportingimplants	Malfunctions in ECM signaling	maintenance of cells in vitro, cryopreservation	Ethical issues, The ethical problem and Moral uncertainties
SLO-2	Ethical consideration	Microencapsulation of live animal cells	Direct Cell-Cell contact - Cell junctions in tissues, malfunctions in direct cell-cell contact Signaling.	Regeneration stimulated electrically	Principles of distributive justice, Sources of conflict and Specific ethical concerns about biomaterials
	SLO-1 SLO-2 SLO-1 SLO-2 SLO-1 SLO-2	SLO-1 Liver implant SLO-2 Artificial Pancreas SLO-1 Bone, Bone Marrow, and Hands SLO-2 Skin and Hair organ SLO-1 Artificial ear SLO-2 Artificial Nose SLO-1 Regeneration and Potential Future Uses for Stem Cells	SLO-1 Liver implant Exchangers SLO-2 Artificial Pancreas Hemodialysis SLO-1 Bone, Bone Marrow, and Hands Soft Tissue Applications SLO-2 Skin and Hair organ Bulk space fillers SLO-1 Artificial ear Maxillofacial implants SLO-2 Artificial Nose Fluid transfer implants SLO-1 Regeneration and Potential Future Uses for Stem Functional load-carrying and supporting implants SLO-2 Ethical consideration Microencapsulation of live animal cells	SLO-1 Liver implant Exchangers Measurement of cell characteristics - cell morphology SLO-2 Artificial Pancreas Hemodialysis Cell number and viability SLO-1 Bone, Bone Marrow, and Hands Soft Tissue Applications Cell-fate processes, cell motility, SLO-2 Skin and Hair organ Bulk space fillers Cell function. SLO-1 Artificial ear Maxillofacial implants Cell-extracellular matrix interactions - SLO-2 Artificial Nose Fluid transfer implants Binding to the ECM, Modifying the ECM, Cell Regeneration and Potential Future Uses for Stem Cells Functional load-carrying and supporting matrix in ECM signaling Direct Cell-Cell contact - Cell junctions in	SLO-1 Liver implant Exchangers Measurement of cell characteristics - cell morphology Applications in biomaterials and tissue engineering Applications in biomaterials and tissue engineering SLO-2 Artificial Pancreas Hemodialysis Cell number and viability sterilization of scaffolds SLO-1 Bone, Bone Marrow, and Hands Soft Tissue Applications Cell-fate processes, cell motility, Sterilization methods SLO-2 Skin and Hair organ Bulk space fillers Cell function. Cell culture protocols SLO-1 Artificial ear Maxillofacial implants Cell-extracellular matrix interactions - Basic techniques for assessment of cell viability SLO-2 Artificial Nose Fluid transfer implants Binding to the ECM, Modifying the ECM, Culture environment SLO-1 Regeneration and Potential Future Uses for Stem Cells SLO-2 Ethical consideration Microencapsulation of live animal cells Microencapsulation of live animal cells Measurement of cell characteristics - cell morphology Applications in direct cell-cell contact A guide to basic cell culture and applications in direct cell-cell contact A guide to basic cell culture and applications in direct cell-cell contact A guide to basic cell culture and applications in direct cell-cell contact A guide to basic cell culture and applications in direct cell-cell contact A guide to basic cell culture and applications in direct cell culture and applications in direct cell-cell contact A guide to basic cell culture and applications in direct cell-cell contact A guide to basic cell culture and applications in biomaterials and tissue engineering A guide to basic cell culture and applications in biomaterials and tissue engineering Sterilization of scaffolds Sterilization of sc

- 1. Larry L. Hench and Julian R. Jones, Biomaterials, artificial organs and tissue engineering, CRC Press 2010
- 2. Sujata V. Bhat "Biomaterials" springer 2002

Learning Assessn	nent										
	Bloom's Level		Final Examination (50% weightage)							
	of Thinking	CLA – 1	(10%)	CLA – 2	(15%)	CLA – 3	(15%)	CLA – 4	(10%)#		
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	10	0 %	100	0 %	10	0 %	100) %

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Course Code	18BME266T	Course Name	DI	OMEDICAL NANOTECHNOLO	ic.v	Course Category	_	Professional Electives	L	T	Р	С
Course Code	TODIVIEZOOT	Course Name	ы	DIOMEDIONE MANOTEDINOLOGI				Fiolessional Electives	3	0	0	3
Pre-requisite		Nil		Co-requisite	Nil	0	essive	Nil				
Courses		IVII		Courses	1411	Co	irses	TVII				
Course Offering D	Department		Biomedic	al Engineering	Data Book / Codes/Standards	Nil						

Course Lee	rning Potionals (CLP).	To study the learners to acquire knowledge to the basic properties of biomaterials and various		Learni	ng					Prog	gram L	earning	Outco	mes (P	LO)					
Course Lea	rning Rationale (CLR):	biomaterials used in biomedical applications.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1:	Attain the knowledge or	n different synthesis method and application of Nano material	Ê	(%)	(%)	40														
CLR-2:	Study the phenomena v	rarious characterization techniques used in Nano material method	8		t (%	wledge		ent						Work		90				
CLR-3:	Acquire knowledge on I	Nanotubes and its applications	<u> </u>	l one	Leu	≪ ≪	10	Шd	_	age	an.				_	Finance	βL			
CLR-4:	Acquire knowledge imp	ortance of nanotechnology based biomedical diagnostics	king.	roficiency	J.E	X	Analysis	/elopi	Design, h	Tool Usage	Culture	∞ -		Team	<u>.</u>	.E ≪	arning			
CLR-5:	Familiarize with biologic	al system, prosthetic and medical implants in nanotechnology	ir	<u>۾</u>	Attai	g f	۱na	Dev	Se c	00	Cu	ment & ability		∞ర	<u>.</u>	Mgt. 8	Les			
CLR-6:	Have an Gain the know	ledge about nano material used in biomedical application	of T	cted	cted	neering	roblem A	sign &	sis, arcl	`_	sty &	onme ainat	ş	ndividual	ommunication	ğ	ong-	-	-2	د -
Course Lea	rning Outcomes (CLO):	At the end of this course, learners will be able to:	Level	Expe	Expe	Engin	Probl	Desi	Analy: Rese	Moder	Society	Environr Sustaina	Ethics	Indivi	Corr	Project	Life L	PSO	PSO	PSO
CLO-1:	Explain the familiarity with	n different synthesis method and application of Nano material in medical application	1, 2	80%	70%	L				L							L			M
CLO-2:	Analyze the phenomena t	taking various characterization techniques used in Nano material method	2	80%	70%	L				М							М			М
CLO-3:	Explore the technolog	gy of Nanotubes and its applications	2	80%	70%	L				М							L			М
CLO-4:	Explain the process of im	portance of nanotechnology based biomedical diagnostics	3	80%	70%	М											L	М	М	
CLO-5:	Select appropriate class of	of Nano materials using knowledge of, prosthetic and medical implants in nanotechnology	3	80%	70%	M											М	М	М	
CLO-6:	Understand the concepts	of biomedical application of different organic particles	3	80%	70%	M		М	Н										М	M

		Nano materials preparation techniques	Characterization techniques of Nano Material	Nanotubes and its applications	Biomedical implants in nanotechnology	Organic - Inorganic nanoparticles and is applications
Duration	n (hour)	9	9	9	9	9
S-1	SLO-1	Introduction - synthesis Nano material	Introduction to Nano scale phenomena	Introduction to carbon Nano tube and its types	Introduction to prosthesis and implants	Introduction to Nano-bio conjugates
0-1	SLO-2	Types of bulk synthesis Material	Nano particle determination	Carbon Nano tube for biomedical application	Nano materials used in Neural implant	Nano-bio conjugates and their significance
S-2	SLO-1	Top Town approaches	Introduction to characterization techniques	Introduction to Improved diagnosis by in vivo imaging	Recent and advancement in Neural implant	Introduction -Nano Biodegradable material
3-2	SLO-2	Bottom up approaches	X-Ray diffraction method	Types of In vivo imaging and its application	Nano materials and coating used in HIPimplant	Nano Biodegradable material for biomedical application
	SLO-1	Insert Gas condensation techniques	Particles size determination	Detection of tumors for Nano materials	Recent and advancement in Hip implant	synthesis methods of Magnetic nanoparticles
S-3	SLO-2	Application of gas condensation techniques	Principle of Scanning electron microscopy	Nano particle using drug delivery system		Magnetic nanoparticles for biomedical application
6.4	SLO-1	Types of Physical Vapour deposition Method	Construction and working of SEM	Different types in drug delivery system	Recent advancement in Knee implant	Multi-functional inorganic Nano particles
S-4	SLO-2	Sputtering Techniques	Application of SEM	Nano particle using genetic defect diagnostics	Nano materials and coating used in Dentalimplant	Multi-functional inorganic Nano particles for biomedical application
S-5	SLO-1	Evaporation techniques	Energy dispersive X-ray spectroscopy	Introduction to Nano robotic medical devices	Recent advancement in Dental implant	Carbon nano tube (CNT) based inorganicNano particles

	SLO-2	Chemical evaporation techniques	EDS Using elemental analysis	Application of Nano robotic medical devices	Nano Technology in ocular implant	Biomedical application of CNT based inorganic Nano particles.
S-6	SLO-1	SLO-1 Laser ablation method Principle and working of Transmissionelectron microscope Cantilever Sensors in L		Cantilever Sensors in biomedical application.	Recent advancement in Ocular implant	Carbon nano tube (CNT) based organic Nano particles
	SLO-2	Pulsed laser deposition	Application of TEM	Introduction to Nano material in medical imaging	Nano Technology in ear implant	Biomedical application of CNT based organic Nano particles.
S-7	SLO-1	Introduction to chemical synthesis	Principle and working of atomic forcemicroscope	Magnetic resonance imaging based contrast reagent used in Nano particles	Recent advancement in ear implant	Introduction to Nano biosensor
	SLO-2	Sol gel process and micro emulsion method	thod Application of AFM Organic Nano particles and Its applications		Artificial skin in Nano material	Nano Biosensor: Fabrication methods
S-8	SLO-1	Hydrothermal process and wet chemical	Fourier transform infrared (FTIR) spectroscopy and its application	Nanoprobes for CT images	Introduction to regenerative medicine in Nano technology	Nano Materials based in breathing gassensor
	SLO-2	Spray pyrolysis Techniques	Application of Scanning probe microscopy(SPM)	Different types of nanoprobe in CT image	Tissue engineering in nanotechnology	Fabrication of breathing gas sensor
S-9	SLO-1	Spin coating methods	IL.Ontact andie measurement	PET based contrast reagent used as a Nano particle.	Nano fiber scaffold technology	Glucose Nano sensor for Diabetic diagnostics
3-9	SLO-2	Electrochemical deposition method	Nano indentation techniques	SPET based contrast reagent used as a Nano particle.	Nano fiber scaffold technology in Biomedical application	Nano oxygen sensor and its application.

	1.W.Gaddand, D.Brenner, S.Lysherski and G.J.Infrate(Eds.), "Handbook of NanoScienceEngineering and Technology", CRC Press, 2013
	2.K. Barriham, D.D. Vvedensky, "Low dimensional semiconductor structure fundamental and device applications", Cambridge University Press, 2010 REFERENCE BOOKS /
Learning	OTHER READING MATERIAL
Resources	1.Cao,G,Nanostructures Nanomaterials Synthesis: Properties Applications", Imperial College Press, 2011. Brian, R Eggins; Wiley; New York, Chichester, 3rdedition, 2012 2.Allen J Bard and Larry
	R Faulkner; Wiley, "Electrochemical Methods: Fundamentals and Applications", New YorkChichester, 4th edition, 2009
	3. David Wild; "The Immunoassay Handbook", Elsevier, 4thedition, 2013.

Learning Asse	essment										
	Dia and I am		Continuous Learning Assessment (50% weightage)								
	Bloom's Level	CLA – 1	(10%)	CLA – 2	(15%)	CLA – 3	(15%)	CLA – 4 (10%)#	Final Examination (50% weightage)
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	100	0 %	1(00 %	100	0 %	10	0 %

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0	4001450075	O N	DIOMET	DIOO					0	0-1		,				- (L	T	Р	С
Course Code	18BME267T	Course Name	BIOMET	RICS					Col	irse Cat	egory	E	: P	Professional Elective			3	0	0	3		
Courses	Pre-requisite Co-requisite Courses									Pro	ogressi	ve Cou	ses									
Course Offering	Department	Biomedical E	ngineering	Data Bo	ook / Code	s/ Stand	ards			Nil												
Course Learning Rationale (CLR): The purpose of learning this course is to:					Lear	ning						Prog	ram Le	arning (Outcom	es (PLC	D)					
CLR-1:					1 2	2 3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Acquire the knowledge ab	out the finger print and h	and geometry recognition						"		_		-			٦	_		g			ళ్ల
CLR-3:	Utilize the knowledge in fa	ce recognition system			ing		-		ysis		ign,		ture	م×		Team	Ęį		Ē	_	ect It	Ñ
CLR-4:	Identitfy the applications o	f biometrics in gait recogi	nition.			(%)	<u> </u>	e g	Analy	eut	Desi	<u> </u>	Cultu	ment & ability		oX	<u>8</u>	Jt. &	Lea	na	rroje nent	Analy
CLR-5:	Analyze the concepts of vi	oice biometrics			ted 1	and the	5	erir		& pmer	is, l	Ľ,	∞ _	nab		ra	Ę	e ĭ	ng	 SS:	z. Jen	-3: / ach
Course Learning	Course Learning Outcomes (CLO): At the end of this course, learners will be able to:				Level of Th (Bloom) Expected	Proficiency Expected		Engineering Knowledge	Problem	Design Develop	Analysis, Researd	Modern ' Usage	Society	Environme Sustainat	Ethics	Individual a	Communication	Project Mgt. Finance	Life Long Learn	rso – r. Professional	rso – z. r Managem	PSO – Resea
CLO-1:	Analyze the performance a	and characteristics of bior	netric systems		3 8	0 75		_M					~~	_ ′						M		
					3 8	0 70		M													М	1
CLO-3:	-3: Illustrate the concepts of face recognition system in 2D and 3D imaging				3 7	5 70		M														M
CLO-4 :	Implement the gait algorithm in gait recognition process and perform on line signature verification using image processing techniques				3 8	0 75				М												М

80 70 80 70

		Fundamentals of biometrics	Finger print and Hand geometry recognition	Face Recognition	Gait Recognition and Palm print identification	Voice biometrics
Duration	(hour)	9	9	9	9	9
S-1	SLO-1	Introduction to biometrics	Introduction to finger print technology	Face recognition -Introduction	Gait -Introduction	Voice biometrics-Technology
3-1	SLO-2	Definition and Evolution	General description		Human ID gait challenge problem	
S-2	SLO-1	Operation of biometric systems	Finger print sensing-optical sensors	Techniques-Eigen faces, Linear discriminant analysis	Base line gait Algorithm	Identity information in the speech signal
0-2	SLO-2	Block diagram description	Solid state sensor and ultrasound sensors	Independent component analysis , Local feature analysis	Base line gait Algorithm	Language generation and speech production
S-3	SLO-1	Biometric functionalities	Feature extraction-segmentation	Face recognition databases-FRGC,FERET	Recognition Approaches-Temporal alignment	Feature extraction and Tokenization-shortterm analysis
	SLO-2	Verification vs identification	Enhancement, minutiae extraction	PIE, AR, Yale face database	Shape based approach	parameterization
S-4	SLO-1	Performance of biometric systems	Finger print matching-correlation basedmethods	Advanced correlation filters	Palm print identification system-block diagram	Phonetic and word Tokenization
	SLO-2		Rigid feature based techniques	Kernel class dependent analysis	Image preprocessing techniques	Prosodic Tokenization
S-5	SLO-1	Biometric system errors-failure to acquire	Performance evaluation-finger printverification competition	Support vector machine for classification	Feature extraction	Text dependent speaker recognition-classification
	SLO-2	Failure to enroll	Finger print vendor technology evaluation	Algorithm	Feature matching	Databases and benchmarks
S-6	SLO-1	Benefits of biometrics	Synthetic finger print generation	Tensor faces method-multilinear analysis of training images	Online signature verification	Text –independent speaker recognition-shortterm spectral systems
	SLO-2	Parameters of good biometrics	Securing finger print based biometric systems	multilinear analysis of testing images	Architecture	Idiolectal systems
S-7	SLO-1	Application of biometrics-Forensics	Hand geometry: Historical perspective	3D sensor and data for face recognition	Data acquisition and preprocessing	Phonotactic systems
3-1	SLO-2	Government, commercial	Modern hand reader		Feature extraction and enrolment	Prosodic systems
S-8	SLO-1	Characteristics of biometrics	Processing steps -hand capture, processing	3D Face image processing-smoothing	Similarity computation	Applications of voice biometrics-voice authentication

CLO-5 : CLO-6:

Analyze the concept of palm print identification system Explain the application of voice biometrics technology

	SLO-2	Commonly used biometrics characteristics	Classification, template adaptation	Local feature extraction	Matching	Speaker detection
S-9	SLO-1	Accuracy in biometric systems	Partormanca matrice	.,	Resources for online signature verification systems-Reference systems	Strength of voice biometrics
	SLO-2	Legal consideration in use of biometricsystems	Standardization	Deformation model	On-line signature databases	Weakness

Learning 2. John	K jain, Patrick Flynn, Arun A. (Eds.), Handbook of Biometrics, Springer, 2008. D. Woodward, Jr. Nicholas M. Orlans Peter T. Higgins, "Biometrics", dreamtech, 2003 Sayman, A. Jain, D. Maltoni and D. Maio (Eds.), Biometric Systems: Technology, Design and Performance Evaluation, Springer, 200
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Ì	B	Continuous Learning Assessment (50% weightage)								F: 1.F. : (: (500(: 1.)			
	Bloom's Level	CLA – 1 (10%)		CLA – 2		CLA – 3		CLA – 4 (10%)#	Final Examination (50% weightage)			
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-		
evel 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-		
evel 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	30 % - ;		-		
Total		10	0 %	10	00 %	10	00 %	10	0 %	10	0 %		

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Course Designers								
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts						
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1.Dr.U.Snekhalatha, SRMIST						

Course Code	18BME361T	Course Name		BioMEMS	Course Category	Ε	Professional Elective	3	T 0	P 0	C 3
Pre-requisite Courses Course Offering	INII	Biomedical Engineering	Co-requisite Courses	Nil Data Book / Codes/Standards	Progressive Courses Nil	Nil					

Course Le	arning Rationale (CLR): The purpose of learning this course is to:	L	earnir	ng				ı	Prograi	m Lea	rning (Outcon	nes (Pl	-O)				
CLR-1:	Understand the fundamental principles of microsensors and microactuators	1	2	3	1	2	3	4	5	6	7	8	9	10	11 12	2 13	3 14	15
CLR-2:	Get an idea about the materials used in MEMS and fabrication processes	om)	(9	<u></u>														
CLR-3:	Acquire an idea about the micromachining		%	(%)	ge		i						동		8			
CLR-4:	Get an idea about the biomedical application of MEMS in POCT	(B)	υς	ent	<u>\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\</u>		J. We		ge				≥		Finance	ס		
CLR-5:	Get an idea about the research based development in the area of BioMEMS	ing	icie	E E	Knowledge	Analysis	elop	ign,	Usage	ure			eam	io		Ė		
CLR-6:	Understand the different biomedical application of MEMS	Thinkir	Jot	√tta	₽ 2	naj	Dev	esi)	0	Cult	nent & ability		∞ –	cati	t. &	3		
			- Pe	99	ering	Ψ	∞ర	s, L	T0	∞ŏ	ab de		ā	E	ct Mgt.	_ م	. 2	က
Course Le	arning Outcomes (CLO): At the end of this course, learners will be able to:	Level o	Expect	Expecte	Engine	Problem	Design	Analysi Resea	Modern	Society	Enviror Sustair	Ethics	Individu	Commi	Project ifa Lor			1
CLO-1:	Analyze the working principle of MEMS & Microsystems in healthcare domain	1, 2	80	70	M	-	-	-	•	-	-	-	-	-		-	-	-
CLO-2:	Explain the micro system fabrication processes and materials used for MEMS	1, 2	80	70	М	-	-	-		-	-	-	-	-		М	-	-
CLO-3:	Differentiate the various Micromanufacturing techniques	2	80	70	-	-	L	-	-	-	-	-	-	-		М		-
CLO-4:	Illustrate the concepts of BioMEMS in POCT	1	80	70	-	-	L	-	-	-	-	-	-	-		-	М	-
CLO-5:	Illustrate the concepts of BioMEMS with suitable examples	1	80	70	-	-	L	-		-	-	-	-	-		-	-	-
CLO-6:	Outline the research areas in the field of BioMEMS	1,2	80	70	-	-	L	-	-	-	-	-	-	-		-	-	-

Dtin	(1	MEMS and Microsystem	MEMS Materials and Fabrication Processes	Overview of Micro-manufacturing	BioMEMS-1	BioMEMS-2
Duratio	on (hour)	9	9	9	9	9
	SLO-1	MEMS and microsystems- Introduction	Substrates and wafers	Micro-Machining- Introduction	Introduction to BioMEMS	Microcantilever BioMEMS
S-1	SLO-2	Typical MEMS and microsystem products	Silicon as a substrate material	Micromachining Techniques	Home Pregnancy Test	Basic Principles of Sensing Biomechanical Interactions
S-2	SLO-1	Difference between MEMS and Microsystems	Silicon compounds, Silicon piezoresistor	Bulk Micromanufacturing (BM)	Lab on a Chip	Detection Modes of Biomechanical Interactions- Static Mode
3-2	SLO-2	Application of Microsystems in healthcareindustry	Gallium arsenide, Quartz	Steps in Bulk Micromanufacturing	Lab on a cellphone	Detection Modes of Biomechanical Interactions- Dynamic Mode
S-3	SLO-1	Working Principles for Microsensor	Piezoelectric crystals, Polymers	Construction of a Microcantilever using BM	Mobile Point of Care Monitors	Fabrication and Functionalization of Microcantilevers
3-3	SLO-2	Types of microsensors: Chemical Sensors	Packaging materials	Types of Etching process in bulk micromanufacturing	DNA Sensors	Fabrication and Functionalization of Microcantilevers
S-4	SLO-1	Biomedical Sensors & Biosensor	Photolithography	Types of Etching process in bulk micromanufacturing	Drug Delivery- Insulin Delivery	Tissue scaffold fabrication using MEMSapproaches
3-4	SLO-2	Optical Sensors	Ion implantation	Surface Micromachining (SM)	Artificial Retinal Prosthesis	Tissue scaffold fabrication using MEMSapproaches
0.5	SLO-1	Pressure Sensors	Diffusion	Construction of a Microcantilever using SM	Endoscopic Wireless Pill	Applications of MEMS-fabricated tissuescaffold
S-5	SLO-2	Pressure Sensors	Oxidation	Steps in Surface Micromachining	Medtronic Reveal	Applications of MEMS-fabricated tissuescaffold

	SLO-1	Thermal Sensor	Chemical vapor deposition (CVD)	Steps in Surface Micromachining	Microsystem Approaches to PCR	Paper-Based Microfluidic Devices
S-6	SLO-2	Acoustic Wave Sensors	Types of CVD	LIGA	Microsystem Approaches to PCR	Paper-Based Microfluidic Devices
S-7	SLO-1	Working Principle for Microactuator	Physical vapor deposition (PVD)	Steps in LIGA process	Implantable Microelectrodes	Lens-Based Glucose Sensor
5-1	SLO-2	Actuation using Thermal Forces	Types of PVD	Difference between LIGA, SM, BM	The Michigan Probes	Lens-Based Glucose Sensor
	SLO-1	Actuation using Shape-Memory Alloys, Piezo- Electric Crystals	Epitaxy	Difference between LIGA, SM, BM	The Utah Electrode Array	Catheter based sensors
S-8	SLO-2	Actuation using Electrostatic Forces, Magnetic field	Types of Epitaxy	Applications of LIGA	Microfabricated Cochlear Implants	Catheter based sensors
	SLO-1	Application of Microactuations	Etching	Applications of Surface Micromachining	Microfabricated Electrocorticography Arrays	Microneedles
S-9	SLO-2	Application of Microactuations	Types of Etching	Applications of Bulk Micromachining	Microelectrodes for Visual Prostheses	Types of Microneedles

1. Tai-Ran Hsu,	"MEMS &	Microsystems-	Design,	Manufacture an	d Nanoscale	Engineering	John Wil	ey &	Sons,	2 nd
Edition, 2008		•	•					•		

2. Nitaigour PremchandMahalik, "MEMS", Tata McGraw Hill, 2nd Reprint, 2008

3. Steven S.Saliterman, "Fundamentals of BioMEMS & Medical Microdevices", International Society for Optical Engineering, 1st Edition, 2006

4. Ellis Meng, "Biomedical Microsystems", CRC Press, 1st Edition, 2011

5. Simona Badilescu and Muthukumaran Packirisamy, "BioMEMS Science and Engineering Perspectives", CRC Press, 1st

6. Albert Folch, "Introduction to BioMEMS", CRC Press, 1st Edition, 2013

7. Wanjun Wang & Steven A.Soper, "BioMEMS- Technologies and applications", CRC Press, 1st Edition, 2007 8. Walter Karlen and Krzysztof Iniewski, "Mobile Point-of-Care Monitors and Diagnostic Device Design", CRC Press, 1st Edition,

9. Chao-Min Cheng, Chen-MengKuan & Chien-Fu Chen, "In-Vitro Diagnostic Devices: Introduction to Current Point of Care Diagnostic Devices", Springer, 1st Edition, 2016

10. Mel L. Mendelson, "Learning Bio-Micro-Nanotechnology", CRC Press, 1st Edition, 2013

	Dia anala I awal			C	Continuous Learning Ass	essment (50% weighta	ige)			Fig. 1 Francis of the 1	F00/!= -t
	Bloom's Level	CLA – 1	(10%)	CLA – 2	(15%)	CLA – 3	(15%)	CLA – 4 (10%)#	Final Examination (50% weightage)
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
_evel 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
_evel 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	10	0 %	10	00 %	100) %	10	0 %

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Learning

Resources

Course	4001450007	Course		DIOTO	ANODODE DUENOMENON		Cou	ırse								-,					L	Т	Р	С
Code	18BME362T	Name		BIOTR	ANSPORT PHENOMENON	1	Cate	gory	E				Pro	essic	nai E	Electiv	ve				3	0	0	3
Pre-requis	s IVII			Co-requisite Courses	Nil		COL	ressi urses	ve S	iil														
Course Offe	ering Department	Biome	edical Engineering		Data Book / Codes/Stand	ards N	lil																	
Course Lea	rning Rationale (Cl	_R):	The purpose of I	learning this co	ourse is to:		Lea	rnin	g				Р	rogra	ım L	earni	ng O	utcor	nes ((PLO))			
CLR-1:	To expose the stud	lents to the fu	undamental physic	s, modeling of	transport phenomena in biological syste	ms	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	To understand the	momentum,	heat and mass tra	ansport phenor	nena in biological systems				(%)	e		ıt						논		a)				
CLR-3 :	R-3: To employ various coordinate systems for transport phenomena problems							5	t) be		Je		a)				Work		nce				
CLR-4:	To enable the learn	ners to formul	late conservation e	equations			0	ë	шe	<u>8</u>	S	ρd	ا ئے	age	Φ			Έ		Finance	ng			
CLR-5:	To enable the learn	ners to apply	the mathematical t	techniques to s	solve conservation equations	id Sid			Attainment	Knowledge	llysi	evelopment	Design,	N	Culture	જ ્		Team	.o	<u>«</u>	Leaming			
CLR-6:	To solve the conse				·	<u>.</u>	ב	두			√na		Ë	8	S	ert iik		∞ర	cat		Ľe			
	1	•				· '	t (a)	cted Proliciency	cted	heeri	em /	yn &	sıs, arch	Tu	ety &	onmainab	S	dual	muni	ξ	Long	-	- 2	8
Course Lea	rning Outcomes (C	LO): At the	end of this course,	, learners will b	pe able to:		(Bloor	exbe (%)	Expected	Engineering	Problem Analysis	Design	Analysis, L Research	Modern Tool Usage	Society	Environment { Sustainability	Ethics	Individual	Communication	Project Mgt.	Life L	PSO	PSO	PSO
CLO-1:	To identify the med	hanism and t	fundamentals behi	ind the transpo	rt phenomena in biological systems	1	1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2:					process in biological systems	1	1, 2	80	70	-	-	-	М	-	-	-	-	-	-	-	М	М	-	-
CLO-3:	To visualize the val	rious coordina	ate systems in trar	nsport phenom	ena		2	80	70	-	-	-	М	-	-	-	-	-	-	-	М	Μ		_
CLO-4 :	To formulate conse	ervation equa	ntions of transport p	phenomena in l	biological systems		1	80	70	-	-		М	-	-	-	-	-	-	-	М	-	М	-
CLO-5 :	To apply mathema	tical techniqu	ies to solve the cor	nservation equ	ations		1	80	70	-	-	-	М	-	-	-	-	-	-	-	М	-	-	-
CLO-6:	To understand the	complex tran	sport phenomena	in biological sy	stems		1,2	80	70	_	_	-	-	-	-	-	-	-	-	-	Н	-	-	-

Duration (bour)	Rheology of Biological Fluids	Macroscopic/Shell Balance Approach for One-Dimensional Bio-fluid Transport	Microscopic Approach for Bio fluid Transport	Fundamentals and macroscopic approach to Bio-heat transfer	Mass Transfer
(hour)	9	9	9	9	9
	1 Introduction - Solids and Fluids	Shell Momentum Balances and Velocity Distributions in Laminar Flow: Shell momentum balances and boundary conditions, Flow of a falling film.	The equation of continuity	Convection and Thermal Radiation Thermal Resistance in Conduction	Diffusivity and the Mechanisms of Mass Transport: Fick's law of binary diffusion (Molecular Mass Transport). Temperature and pressure dependence of diffusivities
S-1	2 Introduction - Solids and Fluids	Shell Momentum Balances and Velocity Distributions in Laminar Flow: Shell momentum balances and boundary conditions, Flow of a falling film.	The equation of continuity	Thermal Resistance in Conduction	Diffusivity and the Mechanisms of Mass Transport: Fick's law of binary diffusion (Molecular Mass Transport). Temperature and pressure dependence of diffusivities

S-2		Flow Regimes: Laminar and Turbulent Flow Boundary Conditions	One-Dimensional Shell Balances in Cylindrical Coordinates	The equation of motion for Newtonian fluids	Unsteady-State	Concentration Distributions in Solids and in Laminar Flow: Shell mass balances; boundary conditions, Diffusion through a stagnant gas film
3-2		Flow Regimes: Laminar and Turbulent Flow Boundary Conditions	One-Dimensional Shell Balances in Cylindrical Coordinates	The equation of motion for Newtonian fluids		Concentration Distributions in Solids and in Laminar Flow: Shell mass balances; boundary conditions, Diffusion through a stagnant gas film
	SLO-1	Viscous Properties of Fluids	Shell Momentum Balances and Velocity Distributions in Laminar Flow: Flow through a circular tube,	The equation of motion for Newtonian fluids	Macroscopic Heat Transfer Applications	Diffusion with a heterogeneous chemical reaction, Diffusion with a homogeneous chemical reaction
S-3	SLO-2	Viscous Momentum Flux and Shear Stress	Shell Momentum Balances and Velocity Distributions in Laminar Flow: Flow through a circular tube,	The equation of motion for Newtonian fluids	Macroscopic Heat Transfer Applications	Diffusion with a heterogeneous chemical reaction, Diffusion with a homogeneous chemical reaction
S-4	SLO-1	Newtonian and	Flow through an annulus	Use of Navier – stokes equations in rectangular coordinates – Hydrostatics, reduction of equations of motion	Radiation: Flame Burn Injury	Diffusion and chemical reaction inside a porous catalyst Equations of Change for Multicomponent Systems: The equations of continuity for a multicomponent mixture, Use of the equations of change for mixtures
	SLO-2	Non-Newtonian Fluid Models	Flow through an annulus	Use of Navier – stokes equations in rectangular coordinates – Hydrostatics, reduction of equations of motion	Human Thermoregulation	Diffusion and chemical reaction inside a porous catalyst Equations of Change for Multicomponent Systems: The equations of continuity for a multicomponent mixture, Use of the equations of change for mixtures
S-5	SLO-1	Rheology of Biological Fluids	Shell Momentum Balances and Velocity Distributions in Laminar Flow: Flow of two adjacent immiscible fluids	Use of Navier – stokes equations in rectangular coordinates – Hydrostatics, reduction of equations of motion	Steady-State Conduction with Heat Generation in a Slab, cylinder	Analogies between momentum, heat and mass transport
	SLO-2	Rheological Properties of Extravascular Body Fluids - Blood	Shell Momentum Balances and Velocity Distributions in Laminar Flow: Flow of two adjacent immiscible fluids	Use of Navier – stokes equations in rectangular coordinates – Hydrostatics, reduction of equations of motion	Steady-State Conduction with Heat Generation in a Slab, cylinder	Analogies between momentum, heat and mass transport
	SLO-1	Rheology - Biorheology and Disease	Laminar flow in a narrow slit	Use of Navier – stokes equations in rectangular coordinates – Hydrostatics, reduction of equations of motion	Steady-State Conduction with Heat Generation in a Slab, cylinder	Convection, Diffusion, and Chemical Reaction
S-6	SLO-2	Rheology - Biorheology and Disease	Laminar flow in a narrow slit	Use of Navier – stokes equations in rectangular coordinates – Hydrostatics, reduction of equations of motion	Steady-State Conduction with Heat Generation in a Slab, cylinder	Transcapillary Exchange of O2 and CO2 -
	SLO-1	Fluid Inertia	Flow of a Casson Fluid Through a Circular Cylinder	Navier – stokes equations in cylindrical and rectangular coordinates and its applications in Newtonian flow	Heat Exchange in Tissue: Transient and Steady-State Pennes Equation	Tissue Solute Exchange
S-7	SLO-2	Fluid Inertia	Flow of a Casson Fluid Through a Circular Cylinder	Navier – stokes equations in cylindrical and rectangular coordinates and its applications in Newtonian flow	Heat Exchange in Tissue: Transient and Steady-State Pennes Equation	Tissue Solute Exchange

	SLO-1	Blood Flow in Organs	Constitutive Relationships for Non- Newtonian Fluids	Krogh Cylinder - Bioreactors One-Dimensional
S-8	SLO-2	Blood Flow in Organs	Constitutive Relationships for Non- Newtonian Fluids	Krogh Cylinder - Bioreactors One-Dimensional
	SLO-1	Osmotic Pressure and Flow	Power Law Fluid - Bingham Fluid - Casson Fluid - Herschel–Bulkley Fluid	Unsteady-State Shell Balance Applications - Diffusion to Tissue
S-9	SLO-2	Osmotic Pressure and Flow	Power Law Fluid - Bingham Fluid - Casson Fluid - Herschel–Bulkley Fluid	Unsteady-State Shell Balance Applications - Diffusion to Tissue

Learning Resources	2. Byron R.	sport: Principles and Applications, Robert J. Roselli, Kenneth R. Diller R.Bird., Warren E. Stewart and Edwin N. Lightfoot, "Transport Phenomena", 2nd edition /iley & Sons, New York, 2007.	3. 4.	Continuum Analysis of Biological systems: Conserved quantities, Fluxes and Forces by G. K. Suraish kumar, 2014 Springer. Transport Phenomena in Biological Systems, 2nd Edition, by G.A. Truskey, F. Yuan, and D.K. Katz, Pearson Prentice Hall, 20092010.
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Learning Asse	essment										
				Contin	uous Learning Ass	essment (50% weig	ntage)			E. 15	(500)
	Bloom's Level of Thinking	CLA –	1 (10%)	CLA – 2 (15%)		CLA –	3 (15%)	CLA – 4	ł (10%)#	Final Examination	n (50% weightage)
	g	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	100	0 %	100) %	100	0 %	100	0 %	10	0 %

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. S. Sam David, SRMIST
		2. Dr. Ashish Kapoor

Course Code	18BME363T	Course Name	HUMAN ELECT	ROPHYSIOLOGY	Course Category	E	Professional Elective	L	T	Р	С
Course Code	TODIVIESOST	Course Name	HOWAN ELECT	(OFTITISIOLOGT	Course Category	L	Professional Lieuwe	3	0	0	3
Pre-requisit Courses	e Anato	omy and Physiology	Co-requisite Courses	Nil	Progres Cours		Nil				
Course Offering Department		Bio	medical Engineering			Nil					

Course Lea	arning Rationale (CLR): The purpose of learning this course is to:		Learnir	g				Pro	gram L	earning	Outco	mes (PL	.0)					
CLR-1:	Understand cell elcrophysiology	1	2	3	1	2	3 4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Know about neuronal communication		_											ce				
CLR-3:	Learn about electrophysiology at neuromuscular junctions			Jen				ge	-			_	_	inan	g			ı
CLR-4:	17 07 7			i i		ysis	ig,	Usa	ture	∞ ∽		eam	ation	ĕ	<u>=</u>			.
CLR-5:			Profi	Attain	ge gg	nal	ent Des	00	Cultu	ment & ability		% T	<u>.</u>		Fea			
CLR-6:	Explore the latest technologies with Electrophysiology studeies	J E @	eq		ie 8	۲	mp m is, [∞ర			nal	Communic	Mgt.	ng	_	7	e e
			ect	Expected (%)	Engine	Problem	Design Develor Analysis Reseal	Modern	Society	Environ Sustair	is	ndividu Nork	Ä	Project	으	Ċ		Ö
	ing Outcomes (CLO): At the end of this course, learners will be able to:	Level (Bloo	Xp (%)	X 8		Po	Designation Development Develo	ĕ	Soc	Sus El	Ethic	Individ Work	Ö	Po	Life	PSO	PSO	PSO
CLO-1:	Describe the physiology of cellular communication	1, 2	80%	70%														1
CLO-2:	Explain how neuron communicate and about perception	2	80%	70%														1
CLO-3:	Elaborate on hoe skeletal muscles working with neural system	2	80%	70%														1
CLO-4:	Describe how human systems are controlled by the electrical signals from btrain	3	80%	70%														
CLO-5:			80%	70%		L												1
CLO-6:	0-6: Undertake basic electrophysiological studies using EEG and other acquired signals.		80%	70%			M L	L									L	

		Cell electrophysiology	Neural communication and perception	Neuromuscular physiology	Electrophysiology of human systems	Electrophysiology studies
Duratio	n (hour)	9	9	9	9	9
S-1	SLO-1	Physiology- levels of organization in the body	Synapse	Autonomic nervous system	Heart anatomy review	Electrophysiology studies (EPS)
0.	SLO-2	Concept of homeostasis	Process involved in synapse	Somatic nervous system	Electrical activity of heart	Facts -EPS
S-2	SLO-1	Homeostasis control systems	Intracellular communication	Neuromuscular junction	Pacemaker activity	Need for EPS
-	SLO-2	Cell structure overview	Signal transduction	Chemical linkage	Refractory periods	Risks involved
S-3	SLO-1	Plasma membrane structure	Organization of nervous system	Skeletal muscles	ECG- Spread of electrical activity	Procedure involved
	SLO-2	Plasma membrane functions	Organization of nervous system- Overview	Skeletal muscles structure and functions	ECG- diagnostic applications	Procedure involved ctd.
S-4	SLO-1	Membrane transport overview	Brain review	Molecular basis of muscular contraction	Cardiac output	Pacing Maneuvers
0 1	SLO-2	Assisted , unassisted transports	Spinal cord review	Skeletal muscle mechanics	Cardiac output and its control	Pace mapping
S-5	SLO-1	Membrane potential	Peripheral nervous system	Muscle mechanics ctd.	Blood pressure (BP)	Vagal Maneuvers (VM)
	SLO-2	Membrane potential causes	Receptor physiology	Shortening of skeletal muscles	Reflexes responsible for BP	Indications of VM
S-6	SLO-1	Neural communication- Introduction	Pain	Skeletal muscle mechanism	Respiratory mechanics	Technologies for VM
	SLO-2	Graded potentials	Pain perception	Fiber types	Adjustments in ventilation	Special considerations
S-7	SLO-1	Action potential	Eye revisited	Nervous control of motor movements	Nervous control of respiration	Supra ventricular tachycardia (SVT)
	SLO-2	Action potential-generation	Visual perception	Nervous control of motor movements ctd.	Nervous control of respiration ctd.	Causes, types SVT
S-8	SLO-1	Action potential-Propagation	Ear and hearing	Smooth muscle	Nervous control of digestive system	Symptoms of SVT

	SLO-2 All or none law	Ear and equilibrium	Phasic contraction	Defecation reflex	Treatments for SVT
S-9	SLO-1 Myelination	Chemical sensing	Cardiac muscles	Nervous control of excretory system	Latest trends in EPS
	SLO-2 Myelination challenges	Taste and Smell	Blend with smooth and skeletal muscles	Micturition reflex	Future scope

Learning Resources	1. 2. 3.	Laura lee Sherwood, "Human Physiology from cell to system", Brooks Cole , 2012. Laura lee Sherwood, "Fundamental of Physiology of Excitable Cells", 2010 Lionel Opie, "Heart Physiology" , Lippincott-Raven, 1998	5.	Aidley, "The Physiology of Excitable Cells", Cambridge Press.,2008 Francis D Murgatroyd, Andrew D. Krahn, "Handbook of cardia Electrophysiology, A practical guide to invasive EP studies and catheter Ablation", Remedica Publisher, 2002
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	B			C	Continuous Learning Ass	essment (50% weightag	ge)			F: 1.F : // //	-00/ '
	Bloom's Level	CLA – 1	(10%)	CLA – 2	(15%)	CLA – 3	(15%)	CLA – 4	(10%)#	Final Examination (50% weightage)
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
evel 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
evel 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	10	00 %	10	0 %	100 %		100) %

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Course Code	18BME364T	Course Name	BIOMEDICAL DEVICE DE	ESIGN FUNDAMENTALS	Course Category	Е	Professional Elective	3	T I) ;	3
Pre-requisite Courses			Co-requisite Courses		Progressive Courses	Nil					
Course Offering	Department	Biomedical Engineering		Data Book / Codes/Standards	Nil						

Course Learning Rationale (CLR): The purpose of learning this course is to:	Le	arninç]					F	Progra	m Lea	arning	Outco	mes (F	PLO)					
CLR-1: Understand the basic concepts of design issues in medical devices	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Get an idea about the forming applications in the design of medical devices CLR-3: Acquire an idea about the laser processing applications		Proficiency	inment						ge				_		nance	Вí			
R-4: Get an idea about the machining applications and different advanced techniques R-5: Acquire an idea about the applications of various technical methods					D 40	nalysis	3	Design, h	ool Usa	Culture	nt & ility		& Team	atic	t. & Fir	-earnir			
CLR-6: Get an overall idea about the regulation and protection in medical device design		ted F	ted Attai	ŀ	ngineering nowledge	E A	∞	is, arc		ج م	nme inab	"		<u> </u>	t Mgt.	ong L	_	2	က
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level (Bloor	Expec	Expec (%)		Engine Knowl	Problem	Design	Analys Rese	Modern	Society	Enviro Susta	Ethics	Individua	Comm	Project	Life Lo	PSO -	PSO -	PSO-
CLO-1: Understand the challenges in the Medical Device Industry	1, 2	80	70	Ī	Н	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2: Have a thorough understanding of typical process parameters	1, 2	80	70	Ī	Μ	-	-	М	-	-	-	-	-	-	-	-	Μ	-	-
CLO-3: Understand the basics of microscale medical device applications	2	80	70	Γ	-	-	-	М	-	-	-	-	- 1	•	-	-	L		-
CLO-4: Identify the importance of different biomaterials used in device design	1	80	70	Ī	Н	-		М	-	-	-	-	-	-	-	М	-	L	-
CLO-5: Analyze the knowledge on machining based fabrication of medical devices	1	80	70	Ī	-	-	-	М	-	-	-	-	-	-	-	L	-	-	-
CLO-6: Extend the basics of safety regulation and protection risk in medical device design	1,2	80	70	Γ	Н	-	•	-	-	-	•	•	•	-	-	Н	-	-	-

Duratio	on (hour)	Design Issues in Medical Devices	Forming Applications on Implantable Devices	Laser Processing Applications on Medical Devices	Machining Applications and Advanced Techniques on Medical Implants	Regulation and Protection of Medical Devices
		9	9	9	9	9
	SLO-1	Introduction - Need for Medical Devices	Forming Applications - Forming	Laser Processing procedures	Machinability of Biocompatible Metal Alloys	Minimisation of exposure to radiation
S-1	SLO-2	Technology Contribution to Medical Devices	Typical Process Parameters	Microscale Medical Device Applications	Surfaces Engineering of Metal Implants	Medical devices intended to emit radiation
0.0	SLO-1	Subtractive Technologies	Typical Process Parameters - Temperature	Microscale Medical Device Applications	Surfaces Engineering of Metal Implants	Minimisation of exposure to unintendedradiation
S-2	SLO-2	Net-Shape Technologies	Typical Process Parameters - Strain	Processing Methods for Medical Device Fabrication	Wear and Failure of Metal Implants	Medical devices intended to emit ionisingradiation – additional requirements
S-3	SLO-1	Additive Technologies	Typical Process Parameters - Strain Rate	Processing Methods for Medical Device Fabrication	Wear and Failure of Metal Implants	Medical devices intended to emit ionisingradiation – additional requirements
3-3	SLO-2	Challenges in the Medical Device Industry	Tribology and Micro-Tribology	Processing Methods for Medical Device Fabrication	Wear and Failure of Metal Implants	Medical devices connected to or equipped withan energy source
S-4	SLO-1	Medical Device Development	Tribology and Micro-Tribology	Biomaterials Used in Medical Devices	Micromilling-Based Fabrication of Metallic Microchannels for Medical Devices	Medical devices incorporating electronic programmable systems
	SLO-2	Biomedical Product Life Cycle	Manufacturing Process Chain	Biomaterials Used in Medical Devices	Micromilling-Based Fabrication of Metallic Microchannels for Medical Devices	Safety dependent on internal power supply
S-5	SLO-1	Biomedical Product Life Cycle	Manufacture of Alloys and Raw Materials	Biomaterials Used in Medical Devices	Machining-Based Fabrication of Polymeric Microneedle Devices	Safety dependent on external power supply
5-5	SLO-2	Medical Device Development Process	Forming	Microjoining of Similar and Dissimilar Materials	Machining-Based Fabrication of Polymeric Microneedle Devices	Medical devices intended to monitor clinical parameters
	SLO-1	Medical Devices' Design Process	Machining and Finishing	Microjoining of Similar and Dissimilar Materials	Degenerative Disc Disease	Minimisation of risk of electromagnetic fields

S-6	SLO-2 Scapholunate Interosseous Ligament	Coating	Microjoining of Similar and Dissimilar Materials	Degenerative Disc Disease	Protection against electrical risks associated with mechanical, vibration, electrical, heat and noise
0.7	SLO-1 Conceptual Design	Packaging and Sterilization		Intervertebral Spinal Spacers	IEC standards: IEC 60601-2-44: Computed tomography
S-7	SLO-2 Conceptual Design	Implantable Devices	Laser Micromachining for Microfluidics	Intervertebral Spinal Spacers	IEC 60601-2-43: Interventional procedures
	SLO-1 Embodiment Design	Implantable Devices	Laser Micromachining for Microfluidics	Inkjet Technology	IEC 60601-2-45: Mammographic X-rayequipment
S-8	SLO-2 Detailed Design	Bone Implants	Laser Micromachining for Metallic CoronaryStents	Medical Applications of Inkjet Technology	IEC 60601-1-3: Radiation protection in diagnostic X-ray equipment
	SLO-1 Manufacturing a Prototype	Bone Implants	Laser Micromachining for Metallic Coronary Stents	Material Extrusion Technology	IEC 60601-2-54: X-ray equipment forradiography and radioscopy
S-9	SLO-2 Manufacturing a Prototype	Bone Implants		Medical Applications of Extrusion-Based Systems	IEC 60601-2-63: Dental extra-oral X-ray equipment; IEC 60601-2-65: Dental intra-oralX-ray equipment

Learning	1.	Claudio Becchetti, Alessandro Neri, "Medical Instrument Design and Development: From Requirements to Market	4.	Brendan Cooper, "Design Control for Medical Devices: A Short Introduction", Tata McGraw-Hill, New Delhi, 2nd edition, 2016.
Resources		Placements", Wiley; 1st edition, 2013.	5.	Paul H. King, Richard C. Fries, Arthur T. Johnson, "Design of Biomedical Devices and Systems", CRC Press, 4th edition,
	2.	Andreoni, Giuseppe, Barbieri, Massimo, Colombo, Barbara, "Developing Biomedical Devices Design,		2018.
		Innovation and Protection", Springer, 2014.		
	3.	Tugrul Özel, Paolo Jorge Bártolo, Elisabetta Ceretti, Joaquim De Ciurana Gay, Ciro Angel Rodriguez, Jorge		
		Vicente Lopes Da Silva, "Biomedical Devices: Design, Prototyping, and Manufacturing", 1st Edition,		
		2016.		

Learning Asse	essment											
	Dia anda Land			C	ontinuous Learning Asso	essment (50% weighta	ge)			Fig. 1 Francis of the	(F00/	
	Bloom's Level	CLA – 1	(10%)	CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Final Examination (50% weightage)		
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
	Remember	40.04		40.04		40.04				2001		
Level 1	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
110	Apply	40.0/		40.0/		40.0/		40.0/		400/		
Level 2	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
	Evaluate	00.0/		00.0/		00.0/		00.0/		000/		
Level 3	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total	10	00 %	10	0 %	10	0 %	10	0 %	10	00 %	

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mr.P. Muthu, SRMIST

0	AODMEOGET	0 N	ININOVATION TRANSPATION AND ENTREPRENEUROUIR	0		Professional Elective	L	T	Р	С
Course Code	18BME365T	Course Name	INNOVATION, TRANSLATION AND ENTREPRENEURSHIP	Course Category	E		3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Departs	nent	Biomedical Engineering	Data Book / Codes/Standards		Nil

Course Lea	rning Rationale (CLR):	The purpose of learning this course is to:		Learni	ng					Prog	ram Le	earning	Outco	mes (P	LO)					
CLR-1:	Learn a range of creative thinking tool and how	to practically apply these to the innovation and entrepreneurial process.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	zipiam are business erm ermen and acce generation																			
CLR-3:	Understand Marketing feasibility and feasibility	plan					S		,	age	Ф			Ε	_		ng			
CLR-4:	Understand about Entrepreneurship			8	(%)		Analysis	-	sign	Tool Usage	Culture	∞ ≥		Team	Sommunication	∞	earning			
CLR-5:	·				d int(%)	ring Age	Ans	ment	۾ ۾	Lool	& CL	ment & ability		~	nici	Mgt.				
CLR-6:	LR-6: Apply deep learning in real life medical problems		l of king	cien	octec	neer	lem em	gn 8	ysis			onn aina	S	en pi	E	oct N	Long	-	- 2	.3
Course Lear	rning Outcomes (CLO): At the	end of this course, learners will be able to:	Level	Expected Proficiency	Expected Attainmer	Engineering Knowledge	Problem	Design & Developm	Analysis, De Research	Modern	Society	Environment & Sustainability	Ethics	Individual & ⁻ Work	Son	Project	ije.	080	080	PSO
CLO-1:	Understand the basic of creative thinking lean	ning techniques and correlate to innovation	1, 2	80%	70%	M			<u> </u>	_	0)	шо								
CLO-2:	Understand the business environment and ide	ea generation	2	80%	70%	М						L								
CLO-3:	Apply knowledge of Marketing feasibility and	easibility plan	2	80%	70%			М		М				L				М		L
CLO-4:	Apply Knowledge about entrepreneurship and	new opportunities	3	80%	70%					М				L						
CLO-5:	Use Knowledge about current scenario on en	trepreneurship	3	80%	70%	М		L										М		L
CLO-6:	Apply innovation to come up with new busines	ss plan	3	80%	70%	М			L					М						

		Innovation & Creative thinking	Business Plan / Idea	Marketing Feasibility and Planning	Entrepreneurship	Intellectual properties and responsibilities
Durat	tion (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Creativity	Scanning of Environment	Market survey & Assessment	Understanding the Meaning of "Entrepreneur"	Product Strategies
3-1	SLO-2	Introduction to Innovation	Understanding factors	Market survey & Assessment	Universal definitions	Product Strategies
	SLO-1	Need for Creativity & Innovation	Sensing Opportunities	Demand and Supply	Characteristics of an Entrepreneur	Distribution Strategies
S-2	SLO-2	Need for Creativity & Innovation	Identify and evaluate factors	Nature of Competition	Characteristics of an Entrepreneur	Distribution Strategies
S-3	SLO-1	The process of Technological Innovation	harnessing different sources of knowledge and information	Fixing cost and price of product	Classification of Entrepreneurs	Promotional Strategies
3-3	SLO-2	The process of Technological Innovation	harnessing different sources of knowledge and information	Fixing cost and price of product	Classification of Entrepreneurs	Promotional Strategies
0.4	SLO-1	Sources of Innovative Opportunity : ProcessNeed		Project Innovation and Changes	The Entrepreneurial Scene in India	Concept of Intellectual Property Rights (IPR)
S-4	SLO-2	Sources of Innovative Opportunity: Industry and market structures	Methods for Generating ideas	Identification of applicable Entrepreneurial Opportunities	The Entrepreneurial Scene in India	Patents, Trademarks
	SLO-1	Sources of Innovative Opportunity : demographics	Product Planning	Data collection for setting up small ventures	Factors Influencing Entrepreneurship	Copyright, Industrial Designs Registrations

S-5	SLO-2	Sources of Innovative Opportunity: changes in perception	Product Planning	Data collection for setting up small ventures	Factors Influencing Entrepreneurship	Geographical Indications, Trade Secrets
S-6	SLO-1	Organization and personal factors to promote creativity	Writing a Business Plan	Financial, Economic Feasibilities	Entrepreneurial Growth	Territoriality of IPR
3-0	SLO-2	Organization and personal factors to promote creativity	Writing a Business Plan	Technical Feasibilities	Entrepreneurial Growth	Concept and procedures of obtaining rightsand ownership for creative works in India
S-7	SLO-1	Creativity and analytical skill	Using and Implementing the Business Plan	Legal Feasibilities	Problems of Entrepreneurs	Environment protection
	SLO-2	Difference between Creativityand Analytical skill	Using and Implementing the Business Plan	managerial, Locational and Other Feasibilities	Problems of Entrepreneurs	Environment protection
S-8	SLO-1	Creativity and Problem Solving	Difference between 'Basic Ideas'and post scanning ideas	Preliminary screening	HEIs Strategies & Governance for Promoting Innovation & Entrepreneurship	importance of Business Ethics and Values in Business
3-0	SLO-2	Creativity and Problem Solving	Difference between 'Basic Ideas' and post scanning ideas	Preliminary screening in market	National Innovation and Startup Policy (NISP) for Higher Educational Institutions (HEIs)	importance of Business Ethics and Values in Business
	SLO-1	Different Techniques for Creative Intelligence	Self Assessment of idea	Preparation of detailed feasibility plan	Creating Innovation Pipeline and Pathwaysfor Entrepreneurs	Role of entrepreneur in economic growth
S-9	SLO-2	Brain storming technique	Reasons for Business Plans Failure	Key features of detailed feasibility plan	Collaboration Co-creation and Business Relationship and Knowledge Exchange	Role of entrepreneur in economic growth

	1.	Peter Drucker, "Innovation and Entrepreneurship", Routledge Classics 2015	6.	S.S.Khanka, Entrepreneurial Development, S.Chand and Company Limited, New Delhi. 2013
	2.	Carolina Machado, J. Paulo Davim, "Entrepreneurship and Organizational Innovation", Springer 2020	7.	Gupta C.B. & Khanka. S.S, —Entrepreneurship and small business managementll, 5th edition, sultan
Learning	3.	Norman M. Scarborough , "Essentials of Entrepreneurship and Small Business Management" (6th Edition) by		chand & sons, 2014
Resources		(Paperback - Jan 13, 2010)	8.	Jayshree Suresh, —Entrepreneurial Developmentll, Margham Publishers, Chennai, 2011.
	4.	Dr.Jayashree suresh –Entrepreneurship DevelopmentMargham Publication-2012	9.	Jeff Cornwall, —Entrepreneurship From Idea to Launchll, Udemy online Education,
	5.	Ganguli Prabuddha "Intellectual Property RightsUnleashing the Knowledge Economy", Tata McGrawHill (2001)		https://www.udemy.com/entrepreneurship-from-idea-to-launch/
		, , , , , , , , , , , , , , , , , , , ,	1	apara and a same and a

Learning Assessi	ment											
	Diagrata Laval			С	ontinuous Learning Ass	essment (50% weightag				Final Evancination /	FOO(weightens)	
	Bloom's Level	CLA – 1	(10%)	CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Final Examination (50% weightage)		
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total	10	0 %	10	0 %	100	0 %	10	0 %	10	0 %	

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Course Designers									
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts							
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mrs.P.Bhargavi Haripriya, SRMIST							

Course Code	18BME366T	Course Name	BIOMEDICAL MICROSCOPY AND QUANTITATIVE IMAGING	Caurae Category	Е	Drafaggional Floative	L	T	Р	С
Course Code	IODIVIE3001	Course Name	DIOWEDICAL WICKOSCOPT AND QUANTITATIVE IWAGING	Course Category	E	Professional Elective	3	0	0	3

Pre-requisite Courses		Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Departr	nent	Biomedica	al Engineering	Data Book / Codes/Standards		Nil

Course Learn	ing Rationale (CLR):	The purpose of learning this course is to:		Learning Program Learning Outcomes (PLO)															
CLR-1:	Understand the basics of optics in mid	croscopy	1	2	3	1	2	3 4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Understand the basics of fluorescence	e microscopy		,											99			i	
	Understand the techniques in low ligh			luc)	ent				ge				_	_	Jan	Ð		1	
CLR-4:	Analyze the various methods for quantitative analysis of microscopic images			oficie	ainπ		alysis	r jign,	ool Usage	ulture	∞ >		Lean	ation	& Fin	arning		1	
CLR-5:	Analyze the various methods for quan	titative analysis of fluorescence microscopic images	iğ	P P	d Attair	ring	An	men ch	T00	န	ment & ability		8	ınica	Mgt.	g Le		ł	
CLR-6:	Understand the optics of microscopy a	and the various methods of quantitative analysis	el of .	ွ	ecte	Enginee Knowled	Problem	sign {	Modern	Society		<u>S</u>	Individual a	ommunication	Project I	Long	0-1) - 2	0 - 3
		At the end of this course, learners will be able to:	Leve (Blo	(%)	(%)	III S	Pro	Design Develor Analys Reses	ĕ	Soc	Enviror Sustai	Ethics	N N	S	Po	Life L	PSO	PSO	PSO
CLO-1:	Describe optics and principle of operation	ion of microscopic image formation	1, 2	80%	70%	M												i	
CLO-2:	Describe optics and principle of operation	tion of fluorescence microscopic image formation	2	80%	70%	М												i	
CLO-3:	Demonstrate the techniques for low lig	ht microscopy	2	80%	70%			М	М								М	i	L
	Apply the different methods for quantit		3	80%	70%				М									i	
CLO-5:	Apply the different methods for quantit	ative analysis of fluorescence microscopic images	3	80%	70%	М											М	i	L
CLO-6:	Apply the knowledge in microscopic in	nage formation and its quantitative analysis	3	80%	70%	М												1	

Durat	tion (hour)	Optics of microscope image formation	Fluorescence Microscopy	Low-light microscopy	Quantitative Analysis of digital microscope images	Quantitative Fluorescence microscopy
		9	9	9	9	9
S-1	SLO-1	Finite tube length microscope	Fluorescence Microscopy	Low light imaging	Optical systems as block boxes	Quantitative fluorescence—detectors
3-1	SLO-2	Upright microscope	Beer's Law	Detection of low light	Calibration toolkit	Limits on linearity
S-2	SLO-1	Infinity optics microscope	Atomic fluorescence	Parameters characterizing imaging devices	Simple calibration curve-relative scale	Illumination variations
3-2	SLO-2	Objective basics	Organic molecular fluorescence	Sensitivity and quantum efficiency	Simple calibration curve-Absolute scale	Detector noise
	SLO-1	Physical optics: superposition of waves	Excited state lifetime	Spectral response, Units	Precision in a calibration curve	Photon shot noise
S-3	SLO-2	Huygen's Principle	Excited state saturation	Fill factor (CCD format), Camera noise andthe signal-to-noise ratio	Standard deviation and errors	Characterizing the performance of an imaging system
S-4	SL0-1	Young's experiment : two slit interference, Diffraction from single slit	Nonradiative decay mechanisms	Shot noise, Readout noise	Signal to noise ratio	Preprocessing of images for quantitativeanalysis
3-4	SLO-2	Microscope resolution, Issues in Microscope resolution	Fluorescence Resonance energy	Background and noise, Example calculation	Signal to background ratio	Processing data for quantitative analysis
	SLO-1	Key components of light microscope	Fluorescence Depolarization	Spatial resolution, Example	Propagation of error in calculated quantities	Methodologies for quantitative imaging
S-5	SLO-2	Illumination Section, Light source	Measuring fluorescence in steady state	Linearity and uniformity, Time response	Error propagation in imaging	Approaches for image deblurring by deconvolution
	SLO-1	Lamp collector	Construction of monochromator	Dynamic range, Gain	Accuracy and precision	Deblurring or neighbor-based methods
S-6	SLO-2	Internal components of illumination paths	Construction of photomultiplier tube	Frame rate and speed, Resolution, sensitivity, and imaging rate	Flatfield Correction	Restoration methods
S-7	SLO-1	Field diaphragm, Condenser, Stage and specimen holder	Measuring fluorescence in the time domain	Imaging Detectors and features	Spatial corrections	Image deconvolution: effects and results
3-7		Microscope imaging section, Objective	Boxcar-gated detection method	Video CCD cameras, Slow-scan and fastCCD cameras	Maximizing resolution	Image deconvolution: practical issues

S-8	SLO-1	Objective Back Focal Plane	Streak Camera method	Intensified Cameras	Converting pixels to microns	Applications for Image Deconvolution
	SLO-2	Revolving nosepiece Turret	Photon correlation method, Phase modulation method	Digital still cameras, SIT Cameras		Quantitative Ratiometric Imaging of FRET- Biosensors in Living Cells
	SLO-1	Infinity space, Tube lens, Eyepieces	Filters for the selection of wavelength	CMOS imagers	Two color coincidence	Image processing methods
S-9	SLO-2	Koehler Illumination, Conjugate light paths	Power of fluorescence of microscopy	Image acquisition	Two camera and two color imaging	Imaging considerations and caveats and pitfalls

Learning	Greenfield Sluder, David E. Wolf," Digital Microscopy", 4th Ed, Academic Press, 2013. Irving J. Bigio, Sergio Fantini "Quantitative Biomedical Optics: Theory, Methods, andApplications",	2. Jennifer Waters, Torsten Wittmann, "Quantitative Imaging in Cell Biology" Academic Press,
Resources	Cambridge University Press, 2016	2014.

Learning Assessm	nent												
	Bloom's Level	01.4	(4.00/.)			essment (50% weighta		01.4.4./	100/) //	Final Examination (50% weightage)			
	of Thinking	CLA – 1 Theory	Practice	CLA – 2 (Theory	Practice	CLA – 3 Theory	Practice	CLA – 4 (Practice	Theory	Practice		
Level 1	Remember	40 %	-	40 %	-	40 %	-	30 %	-	30%	-		
	Understand	.6 ,6		7.6 7.0		70 70		30 /0		30,0			
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-		
	Analyze												
Level 3	Evaluate	20 %	-	20 %	-	20 %	-	30 %	-	30%	-		
	Create												
	Total	100 %		100 %		100 %		100) %	100 %			

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr.P.Vinupritha, SRMIST

					_		L	Т	Р	С
Code	18BME367T	Course Name	HOSPITAL MANGEMENT SYSTEM	Course Category	E	Professional Elective	3	0	0	3
Pre-requisite			Co-requisite	Progres	eiva					

Pre-requisite Courses		Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	nt	Biomedica	al Engineering	Data Book / Codes/Standards		Nil

Course Lea	arning Rationale (CLR):	The purpose of learning this course is to:			Learn	ng					Prog	ram Le	arning	Outcor	mes (PL	.0)					
CLR-1:	Understand about quality and performal	nce improve methods		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Analysis of performance management methods and project management				(%)	<u></u>				arch											
CLR-3:	, , , , ,			(mools	· %	nt (%)	dge		ent	ese					Vork		e)Ce				
CLR-4:	Understand the analytics in healthcare	organizations and population health		Thinking (B	ienc	mer	Knowled	. <u>v</u>	elopment	Ä,	age	e e			Feam V	5	Fina	.ug			
CLR-5:	, , , , , , , , , , , , , , , , , , , ,				rofic	ttain		alys		esign	SO IO	Culture	₩ ±	2		ation	∞ర	earning			
CLR-6:					<u>В</u>	ν P	Engineering	- An	& De	s, De	Tool	∞	mer		<u>8</u>	.iu	Mgt.				
				el of	ecte	ecte	inee.	roblen	sign	lysis,	Aodern	Society	iron	S	vidu	Æ	roject	Long	-1) - 2	0-3
Course Lea	arning Outcomes (CLO):	At the end of this course, learners will be able to:		Lev	Exp	Exp	Eng	Pro	Des	Analy	Moc	Soc	Envir	Eth	Indi	Col	Proj	Life	PSO	PSO	PSO
CLO-1:	Describe performance improve methods			1, 2	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2:	Identify the project management in hea	thcare		2	80%	70%	М		-	-	-	-	•	-	-	-	-	-	-	-	-
CLO-3:	Apply the process redesign and data ar	alytics in population health		2	80%	70%	-	-	М	-	М	-	-	-	-	-	-	-	М	-	L
CLO-4:	Gain the knowledge of health care orga	nizations		3	80%	70%	-	-	-	-	М	-		-	-	-	-	-	-	-	-
CLO-5:	LO-5: Analyzes the population health management			3	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	М	-	L
CLO-6:	: Understand hospital management system			3	80%	70%	М	-	-	-	-		-		-	-	-	-	-	-	-

		Quality and Performance improve Methods	Performance Management Methods and Project Management	Process Redesign, Data analytics and Population health	Analytics in healthcare organizations and population health management	Strategically Hospital management system
Duration	(hour)	9	9	9	9	9
S-1	SLO-1				Strategic, Tactical, and Operational Information Management	
3-1	SLO-2	Quality Management	Process and outcome Measures	Importance of Process Improvement in system implementation	Information Management	
	SLO-1	Core components of Quality managements	Plan do check act	Basic process Improvement Approach	The values of analytics in health care	Strategic Information Management
S-2	SLO-2	Planning, Improvement and control	Six sigma and Lean	Lean Six Sigma	Types of data in health care organizations	Operational Information Management
0.0	SLO-1	Need for health improvement	Theory of constraints and process modeling	Documenting the process	Understanding managing data (Analytical tooland data)	Organizational Structures for Information Management
S-3	SLO-2	Performance improvement	Others Tools and Techniques	Communication Planning	Statistical analysis in health analytics and performance improvement.	Typical Organizational Structures forStrategic Information Management
	SLO-1	Introduction to performance management	Introduction to developing new quality teams	Solidifying the process ImprovementApproach	Introduction to population health management	Typical Organizational Structures for Tacticaland Operational Information Management
S-4	SLO-2	Performance management	Building a new Quality	Creating Future State	Measure of population health status	Examples: Organizational Structures for Information Management in a Hospital
	SLO-1	Health care strategy	Managing performance improvement	Identify metrics and Information capturepoints	Interaction with community Public health service Provider	Information Systems Managers as Architects

S-5	SLO-2	Performance frame work	mance frame work Measure the project status Gap Analysis definition Factors influencing population hea			Organizational Structures for Information Management in a Hospital
	SLO-1	Change versus improvement	Recommendation of Building capacity	Impact of health disparities and inequities	Strategic Planning of Hospital InformationSystems	
S-6	SLO-2	Performance based planning	Recommendation of Building capacity to all	Decision Model	Healthcare delivery systems	Strategic Alignment of Business Plans and Information Management Plans
0.7	SLO-1	Benchmarking	Introduction to project management in healthcare	Predictive Modeling	Continuum of care	The Strategic Information ManagementPlan
S-7	SLO-2 Identifying problem and gap		Project initiation and design	Define the objects and data collection	Care of co-ordination	Purpose of Strategic Information Management Plans
S-8	SLO-1	Research and Prepare benchmarking visit.	Project risk	Applying algorithm	Network Affiliation Strategies	Strategic Monitoring of Hospital Information Systems
3-8	SLO-2	Guideline for performance management	Project Execution and Control	Apply Prediction to decisions	Community needs assessment	Certification, Accreditation, and Excellence Programs of HIS
S-9	SLO-1	Measure the Historical Performance	Change Management	Information sharing beyond the Organizational walls	Evaluating Community Health status measures	Assessment Study of a Telemedicine System to Improve Care
3-9	SLO-2	Forecast the desired Improvement target	Project Communication	Health information Exchanges	Data sources and incentive for health program	Strategic Directing of Hospital Information Systems

Learning Resources	1. 2.	James R. Lang beer II "Performance Improvement in Hospitals and Health Systems Managing Analytics and Quality in Healthcare 2nd Edition", Taylor francs, 2018. Kathryn J. Hannah Marion J. Ball Series Editors, "Health Informatics", Springer Scienc Business Media, LLC2ndedition, 2009	3. 4.	Pradip Kumar Ray, Jhareswar Maiti, "Healthcare Systems Management: Methodologies and Applications: 21st Century Perspectives of Asia", Springer, 2018 Gerald L. Glandon, Donna Jean Slovensky, Detlev Herb Smaltz," Information Systems for Healthcare Management", Health Administration Press, 2014	
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	5			C	Continuous Learning Ass	essment (50% weightag	je)			· · · ·	
	Bloom's Level	CLA – 1	(10%)	CLA – 2		CLA – 3 (CLA – 4	(10%)#	Final Examination (50% weightage)
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
evel 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
evel 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	10	00 %	100	0 %	10	0 %	100) %

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Course Designers		
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			1																				
Course	18BME368T	Course	SOFT TISSUE AND BIOFI	LUID MECHANICS		Cou		E				ı	Professi	onal F	lective	1				L	Т	Р	С
Code	TODINIEGGOT	Name				Cate	gory	_					1010001	onui L		1				3	0	0	3
Pre-req Cours			Co-Requisite Courses				gressi ourses		1														
Course Off	ering Department	Biomedi	ical Engineering	Data Book / Codes/Standards	ı	Nil																	
Course Lea	arning Rationale (CLR):	The purp	pose of learning this course is to:			Le	arning	}					Progra	m Lea	rning	Outco	mes (F	PLO)					
CLR-1:	Understand the fundamenta		mechanics			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Get an idea about the biotr											등			iity								
CLR-3:	Acquire an idea about the	fundamental con	cepts of biofluid mechanics			E (E)	(%)	(%	9	2	L -	ear			lab		논		a)				
CLR-4:	Get an idea about the med	hanics of cardio	vascular system			읎	5	Ħ	1 5	3	leu	ese	an l		tair		Work		nce				
CLR-5:	Get an idea about the biofli	uid mechanics o	f various human body organ systems) g	ë	шe	1	<u>.v</u>	obu	L,	age	ஒ	sns		E	<u>_</u>	Finance	ing			
CLR-6:	Understand the soft tissues	and biofluid me	echanics			돌	ofic	Attainment (%)	2	S S	Development	Design,Research	ŝ	Culture	80		Team	atic	∞ŏ	Learning			
						Thinking (Bloom)	٩	T A	2	Analysis		Ď	00	چ در	ent		య	Ľ.	g.	Ę.			
						, 5	ted	ted	3	<u> </u>	∞ _	Sis.	E	%	шu	w	dua	Ē	≥ ;	Long	-	7	33
Course Lea	arning Outcomes (CLO):	At the en	nd of this course, learners will be able to:			-evel	Expected Proficiency	% Expected	or o	Problem	Design	Analysis, I	Modern Tool Usage	Society	Environment &Sustainability	Ethics	Individual	Communication	Project Mgt.	life L	OSc	080	PSO.
CLO-1:	Understanding of the funda	amental of the m	nechanics soft tissue			1, 2	80	70	F	-	-	-	-	-	٠.	-	-	-	-	-	-	-	-
CLO-2:	Analyze the various transp		system			1, 2	80	70	٨		-	-	-	-	-	-	-	-	-	-	Μ	-	-
CLO-3:	Conceptualization of bioflu					2	80	70	F	М	-	-	-	-	-	-	-	-	-	-	М		-
CLO-4:	Illustrate of the concepts of	f cardiac system	and its biofluid mechanics	·		1	80	70	-	-	L	-	-			-	-	-	-	Н		М	М
CLO-5:	Illustrate the role of biofluid					1	80	70	-	-	L	-	-	-	-	-	-	-	-	Н	-	-	-
CLO-6:	Outline the importance of u	understanding so	oft tissues and biofluid mechanics			1,2	80	70	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duneti	(h)	Fundamental of Soft Tissue mechanics	Basic concept of Biofluids	Macrocirculation and microcirculation system	Cardiac mechanics	Biofluid mechanics of organs system
Duratio	on (hour)	9	9	9	9	9
S-1	SLO-1	Introduction: Structural organizationof skeletal muscle	Introduction –Body fluids, Dimension and unit	Introduction of macrocirculation andmicrocirulation	Introduction	Kidney :Structure and function
3-1	SLO-2	Muscle fiber	Basic Concepts and Definitions of Fluid Mechanics	Pulsatile flow properties	Cardiac Geometry and Structure	Fluid flow in an artificial kidney model
S-2	SLO-1	Motor unit	Fluid Kinematics and Viscosity	Arteries	Cardiac Geometry and Structure	Fluid flow in an artificial kidney model
3-2	SLO-2	Fiber types	Newtonian Fluids	Veins	Ventricular Geometry	Mass transfer in an artificial kidney model
S-3	SLO-1	Fiber architecture	Non-Newtonian Fluids	Vascular bifurcations and branches	Ventricular Geometry	Mass transfer in an artificial kidney model
3-3	SLO-2	Muscle function	Dimensionless Numbers of Biofluid Mechanics	Blood flow through curved vessels	Myofiber Architecture	Liver: structure and function
S-4	SLO-1	Muscle function	Steady versus Unsteady Flow and Laminar Versus Turbulent Flow	Mechanical and elasticity properties of vessels	Myofiber Architecture	Hepatic acinus model
5-4	SLO-2	Maximum Muscle Stress	Boundary Conditions and No Slip Boundary Condition	Atherosclerosis characteristics	Extracellular Matrix Organization	Fluid flow in hepatic acinus model
S-5	SLO-1	Maximum Muscle Contraction Velocity	Compressible and Incompressible Flows, Stress Tensor	Blood flow through stenosis	Cardiac Pump Function: Ventricular Hemodynamics	Mass transfer in hepatic acinus model
3-3	SLO-2	Types of Muscle Models	Viscoelasticity and Viscoplasticity	Arterioles and blood flow aspects	Ventricular PressureVolume Relations and Energetics	Lung : Structure and function

S-6	SLO-1	Huxley biochemical models	Basic Equations of Fluid Mechanics- conservation of Mass, Momentum and Energy	Capillaries and venules	Ventricular PressureVolume Relations and Energetics	Elasticity of the lung blood vessels and alveoli
3-0	SLO-2	Hill phenomenological models	NavierStokes Equations	Fahraeus and Fahraeus lindqvist effects	Myocardial Material Properties	Pressure-volume relationship for air flowin the lungs
	SLO-1	Constitutive models	Bernoulli Equation	Fahraeus and Fahraeus lindqvist effects	Myocardial Material Properties: Muscle Contractile Properties	Oxygen/carbon dioxide diffusion and transport in the blood
S-7	SLO-2	Tendon-morphology	Hagen Poiseuille Equation	Mass transport in tissue	Muscle Contractile Properties	Compressible fluid flow
S-8	SLO-1	Tendon-properties	Steady Flow Along Tube, Pulsatile Flow in Rigid and Elastic Tubes	Porosity, tortuosity and permeability	Resting Myocardial Properties	Lubrication of joints: function
3-8	SLO-2	Ligament –morphology	Resistance, Compliance and Inertance, Two- Phase Flows	Governing equations in porous media	Resting Myocardial Properties	Formation of synovial fluid
	SLO-1	Ligament -properties	Hematology and blood rheology	Governing equations in porous media	Regional Ventricular Mechanics: Stress and Strain	Synovial fluid flow
S-9	SLO-2	Articular cartilage –morphology and properties	Hematology and blood rheology	Fluid transport in poroelastic media	Regional Ventricular Mechanics: Stress and Strain	Mechanical forces within joint

Learning Resources

- 1. David A. Rubenstein, Wei Yin&Mary D. Frame "Biofluid mechanics: An introduction to fluid mechanics, macrocirculation and microcirculation (Biomedical Engineering)", Elsevier, 2nd edition ,2012
- Clement Kleinstreuer "Biofluid Dynamics: Principles and Selected Applications", CRC Press; 1 edition, 2016
 Benjamin Loret, Fernando Manuel & Fernandes Simoes "Biomechanical Aspects of Soft Tissues", CRC Press; 1
- edition, 2017
 4. Yuan-Cheng Fung, "Biomechanics: Mechanical Properties of Living Tissues", Second Edition, 1993
- 5. Susan Hall, "Basic Biomechanics" McGraw-Hill Education, 6th edition August 2011
- 6. Ali Ostadfar," Biofluid Mechanics -Principles and Applications," Elsevier,1st edition,20167. Jagan N.

Mazumdar, "Biofluid Mechanics," World Scientific, 2nd edition, 1992

Learning Assessr	ment										
	B			Co	ontinuous Learning Ass	essment (50% weighta				F: 15 : 6	'F00/ '.l. \
	Bloom's Level	CLA – 1	(10%)	CLA – 2 ((15%)	CLA – 3	(15%)	CLA – 4 (10%)#	Final Examination (50% weightage)
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	100	0 %	100) %	10	0 %	100) %	10	0 %

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Course Code	18BME369T	Course Name	TROUBLESHO	OTING OF MEDICAL DEVICES	_	ourse		E				Profes	sional	Elective	9				L 3	T	Р	C
		114																	3	U	U	ა
Pre-requi Cours		devices and circuits, Linear s, Biomedical Instrumentation	Co-requisite Courses	Nil		gressi ourse		Nil														
Course Offe	ring Department	Biomedical Engineering	7	Data Book / Codes/Standards	Nil																	
Course Lea	rning Rationale (CLR):	The purpose of learning	this course is to:			Learn	ing					Proc	ıram L	earnin	a Outo	comes	(PLO)					_
CLR-1:	Inderstand the fundament	al troubleshooting procedures a	nd testing of basic electi	onic components	1	2	3		1	2	3 4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Learn the methods to ensu	re electrical safety	<u>-</u>	·							5			lity								
CLR-3:	Get an idea about the fault	diagnosis in analog and digital i	ICs.		(Bloom)	(%)	(%		<u>e</u>		earch			ıstainability		논		an an				
CLR-4:	Acquire an idea about the l	pasic troubleshooting procedure	s for biomedical equipm	ent	8	Ś	Attainment (%)		Knowledge		Development Design, Rese	e,		stail		Work		Finance				
CLR-5 :	earn the methods of troub	leshooting Diagnostic medical L	Equipments		ng Li	cier	Ĭ.		No.	.S	velop sign,	Usage	<u>e</u>	ng 1		Team	ation	Fin	arning			
CLR-6:	Understand the methods of	troubleshooting therapeutic me	edical Equipments		Thinking	Profici	Attai		g X	Analysis	Desi	Tool	Culture	ent 8		8 T	icat	Jt. &	-ear			
<u>.</u>					of I	De J	ted		eering	~	ა არ		∞ర	nme		<u>~</u>	unu	t Mgt.	ng l	←	2	က
Course Lea	rning Outcomes (CLO):	At the end of this course	e, learners will be able to	:	Level	Expect	Expect		Engine	Problem	Design Analysi:	Modern	Society	Enviro	Ethics	Individu	Comm	Project	Life Lo	PSO -	PSO -	PSO -
CLO-1:	Apply the common trouble	shooting procedures in Electror	nic Equipment and Outlin	e the testing procedures of active and passive component	ts 1, 2	80	70		М	-	- -	-	-	-	-	-	-	-	-	-	-	-
	Analyze the faults in analo				1, 2		70		М	-		-	-	-	-	-	-	-	-	М	-	-
CLO-3:				working and provide a suitable solution	2	80	70		-	М		-			-	-	-	-	-	М		•
		dge in fault diagnosis of medica			1	80	70		-	-	Н -	-	-		-	-			М	-	М	-
		ubleshooting Diagnostic medica			1	80	70		-	-		-	-	-	-	-	-	-	М	-	-	-
CLO-6:	implement the methods of	troubleshooting therapeutic me	edical Equipments		1.2	80	70		-	-		-	-	-	-	-	-	-	L	-	-	-

Duratio	on (hour)	Basic Troubleshooting Techniques & Procedures	Grounding Systems	Troubleshooting Active and Passive components	Troubleshooting of diagnostic Equipments	Troubleshooting of Therapeutic & Surgical Equipments
	` ,	9			9	9
S-1	SLO-1	Making of an electronic equipment	Electrical Hazards	Testing of passive components: Fixed Resistors	Parts of an ECG Machine	Troubleshooting of Defibrillator
5-1	SLO-2	description	Causes	Testing of passive components: variableResistors	Sources of ECG artifacts	Preventive maintenance of Defibrillator
S-2	SLO-1	PCB	Types of electrical shock	Testing of passive components: Capacitors	Troubleshooting- ECG Machine	Troubleshooting of Electrosurgical unit
3-2	SLO-2	PCB types	Threshold levels of electrical shock	Testing of passive components: variable Capacitors	Preventive maintenance of ECG system	Preventive maintenance of Electrosurgicalunit
0.0	SLO-1	Causes of Equipment Failure	Electrical grounding	Testing of passive components: Inductors	Parts of an EEG Machine	Troubleshooting of Incubator
S-3	SLO-2	Types of Equipment Failure	Need for grounding	Testing of passive components: variableInductors	Sources of EEG artifacts	Preventive maintenance of Incubator unit
S-4	SLO-1	Functional block diagram of a troubleshooting system	Grounding Systems in Electronic Equipment	Testing of PN Diodes	Troubleshooting- EEG Machine	Troubleshooting of Suction apparatus
5-4	SLO-2	Description of a troubleshooting system	Methods	Testing of Zener Diodes	Preventive maintenance of EEG system	Preventive maintenance of Suction apparatus
0.5	SLO-1	TroubleshootingProcess	Temperature Sensitive Intermittent Problems	Testing of NPN transistor	X ray System	Troubleshooting of Anaesthesia Machine
S-5	SLO-2	Description	Methods to rectify	Methods	Sources of errors	Preventive maintenance of Anaesthesia Machine

S-6	SLO-1	Fault finding Aids	Correction Action to repair the Equipment	Testing of PNP transistor	Troubleshooting- X-ray Machine	Troubleshooting of Nebulizer Machine
	SLO-2	Description	Correction Action to repair the Equipment	Methods	Preventive maintenance of X-ray system	Preventive maintenance of Nebulizer Machine
C 7	SLO-1	Troubleshooting techniques: Preliminary Observations	Tools & Aids for Servicing & Maintenance	Testing of FET	Endoscopy: Sources of artifacts	Oxygen cylinders
S-7	SLO-2	Troubleshooting techniques: Functional block diagram approach	Tools & Aids for Servicing & Maintenance	Methods	Troubleshooting of endoscope& its preventive maintenance	Preventive maintenance of Oxygen cylinders
0.0	SLO-1	Troubleshooting techniques: Split half method	Situations where repair not to be attempted	Typical op-amp based medical circuits	Ultrasound: Sources of artifacts	Radiation Monitors-trouble shooting
S-8	SLO-2	Application of Split half method in circuit troubleshooting	Situations where repair not to be attempted	Fault diagnosis in op-amp circuits	Troubleshooting of Ultrasound system& its preventive maintenance	Radiation Monitors-calibration
S-9	SLO-1	Troubleshooting techniques: Systematic Troubleshooting	Types of power supply	Digital IC Troubleshooter:, Logic clip, Logicprobe	Troubleshooting of Pulse oximeter	Troubleshooting of Autoclaves & sterilizers
5-9	SLO-2	Correction action	World power supply types	Logic pulser, Logic current tracer	Troubleshooting of Sphygmomanometers	Preventive maintenance of Autoclaves &sterilizers

1. Joseph D Bronzino & Donald R Peterson, "Medical Devices and Human Engineering", CRC Press, 4th Edition, 2015
2. Myer Kutz, "Biomedical Engineering and Design Handbook- Volume 2: Applications", McGraw-Hill, 2nd Edition, 2009

- 3. Richard Fries, "Reliable Design of Medical Devices", CRC Press, 2nd Edition, 2006
- 4. Basem S EL-Haik & Khalid S Mekki, "Medical Device Design for Six Sigma: A Road Map for Safety and Effectiveness", John Wiley & Sons. 1st Edition, 2008

Learning Resources

- 5. John J Tobin & Gary Walsh, "Medical Product Regulatory Affairs- Pharmaceutical, Diagnostics, Medical Devices", Wiley-Blackwell, 1st Edition, 2008
- 6. Norbert Leitgeb, "Safety of Electromedical Devices Law Risks Opportunities", SpringerWienNewYork, 1st Edition, 2010
- 7. "Medical Device Regulations Global overview and guiding principles", World Health Organization Geneva, 2003
- 8. Jack Wong and Raymond K Y Tong, "Handbook of Medical device regulatory affairs in Asia", Pan Stanford Publishing Pte. Ltd., 2nd Edition, 2018
- 9. Khandpur R S, "Troubleshooting Electronic Equipment- Includes Repair & Maintenance", Tata McGraw-Hill, 2nd Edition, 2009

 10. Nicholas Cram & Selby Holder, "Basic Electronic Troubleshooting for Biomedical Technicians", TSTC Publishing, 2nd edition, 2010
- 11. Dan Tomal & Neal Widmer, "Electronic Troubleshooting", McGraw Hill, 3rd edition, 2004
- 12. Ministry of Health &Family Welfare, "Medical Equipment Maintenance Manual- A first line maintenance guide for end users", New Delhi, 2010

Learning Assess	ment										
	B			Co	ontinuous Learning Asse	essment (50% weightag	je)			F: 15 : ::	F00/ ' \
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	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
evel 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
evel 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	100	0 %	10	0 %	100) %	10	0 %	10	0 %

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Course Code	18BME370T	18BME370T Course Name QUALITY ASSURANCE AND REGULATORY ASPECTS FOR MEDICAL DEVICES					Е			F	Professi	onal E	lective					L 3	T 0	P 0	C 3
Pre-requisite Basic Electronic devices and circuits, Linear Co-requisite Courses Integrated circuits, Biomedical Instrumentation Course Offering Department Biomedical Engineering Data Book / Codes/Standards							Nil														
Course Lear	rning Rationale (CLR):	The purp	ose of learning this course is to:	L	earnin	ıg					Progra	m Lea	rning (Outco	mes (F	PLO)					
CLR-1: Understand the fundamental troubleshooting procedures and testing of basic electronic components				1	2	3		2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Get an idea about the fault diagnosis in analog circuits and digital ICs. CLR-3: Acquire an idea about the basic troubleshooting procedures for biomedical equipment CLR-4: Get an idea about the medical device classification globally and regulatory standards CLR-5: Get an idea about the Indian perspective medical device regulatory system CLR-6: Get an overall idea about the importance of troubleshooting and medical device classification in India CLR-1: Understand the fundamental troubleshooting procedures and testing of basic electronic components Course Learning Outcomes (CLO): At the end of this course, learners will be able to:				evel of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)		Problem Analysis	Design & Development	Analysis, Design, Research	Aodern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	ndividual & Team Work	Sommunication	Project Mgt. & Finance	ife Long Learning	oS0 - 1	2SO - 2	30 – 3
CLO-1:			1, 2	80	70		1 -	-	-	-		-	-	-	-	-	-	-	-	-	
CLO-2: Analyze the faults in analog circuits and digital ICs				1, 2	80	70		1 -	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-3: Identify the problems in common biomedical equipment in hospitals when it is not working and provide a suitable solution				2	80	70		· M	-	-	-	-	-	-	-	-	-	-	М		-
CLO-4: Outline the importance of medical device classification based on the application and ISO standards				1	80	70		-	Н	-	-	-	-	-	-	-	-	М	-	М	-
					80	70			-	-	-	-	-	-	-	-	-	М	-	-	-
CLO-6:	5: Outline the job opportunities in regulatory affairs in India				80	70		-	-	-	-	-	-	-	-	-	-	L	-	-	-

Duratio	on (hour)	Fundamentals Of QualityManagement	Quality Management Principles	Statistical Process Control Tools	Quality Management Techniques	Regulatory Strategy
			9	9	9	9
S-1	SLO-1	Definition of Quality	Customer satisfaction	The seven tools of quality: Flow chart	Benchmarking	Purpose of regulation
3-1	SLO-2	Dimensions of Quality	Customer Perception of Quality	Check list	Benchmarking	Principles of regulation
S-2	SLO-1	Dimensions of Quality	Customer Complaints	Histograms	Reasons to Benchmark	Legal frame work for regulation: National Legislative process
3-2	SLO-2	Quality Planning	Service Quality	Pareto Diagram	Reasons to Benchmark	Legal frame work for regulation: EU Legislative process
S-3	SLO-1	Quality costs.	Customer Retention	Cause and Effect diagram	Benchmarking Process	Relationship between national and EU legal instruments
	SLO-2	Analysis Techniques of quality Cost	Employee Involvement- Motivation	Scatter diagram	Benchmarking Process	Basic legialation
S-4	SLO-1	Analysis Techniques of quality Cost	Empowerment	Control Charts for variables	Quality Function Deployment (QFD)	Scope of legislation
5-4	SLO-2	Basic concepts of Total Quality Management	Teams	Control Charts for attributes	Quality Function Deployment (QFD)	Basic regulatory stratergy
S-5	SLO-1	Historical Review	Recognition and Reward	New seven Management tools: Affinity diagram	House of Quality	Need for Accreditation of hospitals
0-3	SLO-2	Historical Review	Performance appraisal	Relationship diagram	House of Quality	Need for Accreditation of hospitals
S-6	SLO-1	Principles of TQM	Continuous process improvement	Tree diagram	QFD Process	FDA Regulations
3-0	SLO-2	Leadership	Juran Trilogy	Matrix Diagram	Taguchi Quality Loss Function	Joint Commission

S-7	SLO-1	Role of Senior Management -	PDSA Cycle	Matrix diagram	Total Productive Maintenance (TPM	Regulatory Bodies of India-Medical Council of India
	SLO-2	Quality Council	5S	Matrix data analysis diagram	Six sigma	Importance of regulatory system
0.0	SLO-1	Quality Statements	Kaizen	Matrix data analysis diagram	Six sigma	Market Overview
S-8	SLO-2	Strategic Planning	Performance Measures-Basic concepts	Process decision program chart	FMEA	Overview of Regulatory Environment
0.0	SLO-1	Deming Philosophy	Strategy	Process decision program chart	Types of FMEA	Details of Key Regulator
S-9	SLO-2	Barriers to TQM Implementation	Performance measurement.	Arrow diagram	Benefits of Fmea	Organization Chart — CDSCO

	1. Rose, J.E., "Total Quality Management", Kogan Page Ltd., 1993
	2. Cesar A. Cacere& Albert Zana, :ThePractise of clinical Engineering". Academic Press, Newyork, 1997
	3. John Bank, "The Essence of Total Quality Management", Prentice Hall of India, 1993
Learning	4. Webster J.G and Albert M.Cook, "Clinical Engineering, Principles & Practices", Prentice Hall Inc., Engle wood cliffs
	New Jersey, 1979
Resources	5. John J Tobin & Gary Walsh, "Medical Product Regulatory Affairs- Pharmaceutical, Diagnostics, Medical Devices",
	Wiley-Blackwell, 1st Edition, 2008
	6. Medical Device Regulations Global overview and guiding principles". World Health Organization Geneva, 2003

7. Jack Wong and Raymond K Y Tong, "Handbook of Medical device regulatory affairs in Asia", Pan Stanford Publishing Pte. Ltd., 2ndEdition, 2018

- 8. Khandpur R S, "Troubleshooting Electronic Equipment- Includes Repair & Maintenance", Tata McGraw-Hill, 2nd Edition, 2009 9. Nicholas Cram & Selby Holder, "Basic Electronic Troubleshooting for Biomedical Technicians", TSTC Publishing, 2nd
- 10. Dan Tomal& Neal Widmer, "Electronic Troubleshooting", McGraw Hill, 3rd edition, 2004
- 11...Ministry of Health &Family Welfare, "Medical Equipment Maintenance Manual- A first line maintenance guide for end users", New Delhi, 2010

Learning Asses	earning Assessment											
	Continuous Learning Assessment (50% weightage)											
	Bloom's Level	CLA – 1	(10%)	CLA – 2	(15%)	CLA – 3	(15%)	CLA – 4 (10%)#	Final Examination (50% weightage)	
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total	10	0 %	10	0 %	10	00 %	100) %	10	0 %	

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. Rajalakshmi T, SRMIST

Course Code	18BME371T	Course Name		NEUROENGINEERING	Course Category	E Professional Elective	3	T 0	P 0	C 3
Pre-requisite Courses Course Offering	IVII	Biomedical Engineering	Co-requisite Courses	Nil Data Book / Codes/Standards	Progressive Courses	Nil				

Course Lea	arning Rationale (CLR):	ourpose of learning this course is to:		Le	arnin	3				Progr	am Le	arning	Outco	omes (PLO)					
CLR-1:	Understand the basic principles of bra	in anatomy and function		1	2	3	1 2	2 3	4	5	6	7	8	9	10	11	12	13	14 1	5
CLR-2:	Learn about the principles of nervous		-	Œ	6)	<u></u>														
CLR-3:	Learn about the applications of neural	engineering in sensory disorders		0	(%) /	t (%)	dge	5	=					/ork		9				
CLR-4:	Understand the concepts of BCI and I	neurophysiologic recording and imaging technologies		(B)) O	Attainment	Knowledge	8	[ge	-			× ×	_	inan	g			
CLR-5:	Understand the basics of neuro prosth			ķing	ficie	Ë	ğ.	Analysis	sign,	Usa	ture	οž ~		eam	ţį	i <u>≡</u> ≪	Ti.			
CLR-6:	Learn about the concepts of neural im	aging and its modeling techniques for various applications		Phinkin	Pro	Atte	g .			_ 0	Cit	t ∰		~ ~	<u>8</u>	- 1	Lea			
	<u> </u>		ļ '	ot⊥	eq	eq	ering .	= ~	ສ ່ຕົ	ပ <u>ျ</u>	∞	nab		<u>a</u>	틸	Mgt.	oug	_	2 0	2
Course Le	earning Outcomes (CLO): At th	e end of this course, learners will be able to:		evel o	Expect	Expecte	Engine	Problem &	Analysi	Modern	Society	Enviror	Ethics	ndividua	Communication	Project	-ife Lo	-080	PSO -	000
CLO-1:	Understand the anatomy of brain and	its functions	1	1, 2	80	70	M		-	-	-	-	-	-	-	-	-	M		
CLO-2:	Understand the nervous system		1	1, 2	80	70	М			-	-	-	-	-	-	-		М		
CLO-3:	Identify the applications of neural engi	neering		2	80	70	М			-	-	-	-	-	-	-		-	- N	I = I
CLO-4:	Understand BCI system and neuro ima			1	80	70	IVI			•	-	•	-	-	-				- N	1
CLO-5:	Identify the various neuro prosthetic de			1	80	70	М			•	•	•	•	-	-				- N	4
CLO-6:	Understand the concepts of neuro pro-	sthetics and its modeling techniques	1	1,2	80	70	M	. -	-	-	-	-	-	-	-	-		-	- 1	I

Duratio	on (hour)	Introduction To Neurons And Nervous Systems	Neuro-Transmission And Neuro- Transmitters	Neural Imaging Techniques	Neural stimulation and Neural modeling	Neuro-Prosthetics
		9	9	9	9	9
S-1	SLO-1	Brain anatomy	Nervous system	Brain Computer Interface	Sensory prosthetics	Deep brain stimulation
3-1	SLO-2	Structure of neurons	Nervous system	History of BCI	Retinal prosthetics	Deep brain stimulation
S-2	SLO-1	Function of neurons	Central nervous system	Components of a BCI System	Visual prosthetics	Spinal cord stimulation
3-2	SLO-2	Types of neurons	Peripheral nervous system	Functional Components	Bionic eye	Spinal cord stimulation
S-3	SLO-1	Neuroglia	Neurotransmission	Feedback	Bionic eye	Cortical stimulation
3-3	SLO-2	Myelinated and unmyelinated nerve fibers	Stages in neurotransmission	Signal Acquisition	Auditory prosthetics	Cortical stimulation
	SLO-1	Properties of nerve fibres	Synaptic transmission	Invasive Techniques	Cochlear implant	Transcranial direct current stimulation
S-4	SLO-2	Excitability, conductivity, all-or none law, accommodation, adaptation, summation, refractory period, indefatiguability	Synaptic transmission	Noninvasive Techniques	Cochlear implant	Transcranial direct current stimulation

S-5	SLO-1	Synapse	Chemical synaptic transmission	Feature Extraction and Translation Techniques	Bionic ear	Single neuron model
	SLO-2	Glial cells	Chemical synaptic transmission	Types of BCI Signals	Bionic ear	Single neuron model
S-6	SL0-1	Myelination	Electrical synaptic transmission	Training of BCI signals	Spinal cord stimulator	Hodgkin Huxley neuron model
3-6	SLO-2	Neuronal differentiation	Electrical synaptic transmission	Signal Processing and Feature Extraction	Motor prosthetics	Hodgkin Huxley neuron model
S-7	SLO-1	Characterization of neuronal cells	Neurotransmitters and their release	BCI development	Bladder control implant	Fitzhugh Nagumo models
3-1	SLO-2	Characterization of neuronal cells	Neurotransmitters and their release	Electroencephalography (EEG)	Bladder control implant	Fitzhugh Nagumo models
S-8	SLO-1	Blood Brain barrier	Types of neurotransmitters	Principle and working of EEG	Sacral anterior root stimulator	Morris lecar model
	SLO-2	Blood Brain barrier	Types of neurotransmitters	Computerized axial tomography (CAT) scans in brain imaging	Sacral anterior root stimulator	Morris lecar model
S-9	SLO-1	Meninges	Fast and slow neurotransmission	Functional Magnetic Resonance Imaging (fMRI)	Prosthetics for conscious control of movements	Hind marsh rose model
3-9	SLO-2	Cerebrospinal fluid	Fast and slow neurotransmission	Functional Magnetic Resonance Imaging (fMRI)	Prosthetics for conscious control of movements	Hind marsh rose model

Learning Resources	1. Bin He, Neural Engineering, Plenum Publishers, 2005. 2. R.S.Khandpur, Handbook of Biomedical Instrumentation, Mc Graw Hill, 3 rd Edition, 2015.

	DI			C	ontinuous Learning Ass	essment (50% weighta	ge)		Final Examination (50% weightage)			
	Bloom's Level	CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3	(15%)	CLA – 4 (10%)#	Final Examination (50% weightage)	
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
_evel 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total	10	0 %	10	0 %	10	0 %	100) %	100) %	

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Course Coo	de	18BME372T	Course Name		IOT AND TEL	EHEALTH TECHNO	DLOGY				C	ourse C	ategory		E	Pi	rofessio	nal Elec	tive		L 3	T 0	P 0	C 3
Pre-requ Cours	ses		Nil		Co-requisite Courses			Nil					Progre							Nil				
Course Offe	ring Depart	ment		Biomedic	al Engineering		Data Book	/ Codes/S	Standards									Nil						
Course Lear	ning Ration	nale (CLR):	The purpose of	of learning this course	is to:			Learnii	ng					Pro	gram L	earning	g Outco	mes (P	LO)					
CLR-1:	Understand	d the building blocks	of IoT				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Understand	d the technologies in	IoT										_			ty								
CLR-3:	Gain knowl	ledge in system mai	nagement in wearab	le devices			(mo	(%)	(%)	9	<u>p</u>	±	earch			Sustainability		논				,	i	
CLR-4:	Explore the	architecture of sma	rt healthcare systen	18			(Bloom)	Proficiency		Anowledge	Ď.	Development	Res	ge		ıstai		Team Work		Janci	б			
CLR-5:	Gain knowl	ledge in basics of te	le-health technology	and architecture invo	lved		Thinking	officie	ttainment	X o	Analysis	velop	Design,	Usa	Culture	∞ర		Tean	ation	る	Learning		i	
CLR-6:	Gain knowl	ledge in architecture	of IoT systems and	its applications in hea	lthcare			ed Pro	d Att		Ana		Ď.	Tool Usage	∞ŏ	ment			nica	Mgt. & Finance			i	
Course Lear	ning Outco	mes (CLO):	At the end	of this course, learne	ers will be able to:		evel of	Expecte	Expecte	aguica	Problem Ana	Design 8	Analysis,	Modem	Society	=nvironment	Ethics	ndividual &	Sommunication	Project	-ife Long	- 050	- 20	- 080
CLO-1:	Explain th	e various models ar	nd protocols in IoT				1, 2	80%	70%	M	- "		-	-	-	-	-			-		M	-	-
CLO-2:	Demonstra	ate the various tech	nologies for building	IOT			2	80%	70%		-	-	L	-	-	-	-	-	-	-	-	Μ	-	-
CLO-3:	Explain th	e loT system mana	gement and its appli	cations			2	80%	70%		-	-	L	-	-	-	-	-	-	-	-	Μ	-	-
CLO-4:	Apply the	techniques in Realt	ime healthcare appli	cations			3	80%	70%	М	-	-	-	-	-	-	-	-		-	-	М	-	-
CLO-5:	Explain th	e architecture in tele	health technology				3	80%	70%	М	-	-	-	-	-	-	-	-		-	-	М	-	-
CLO-6:	Demonstra	ate the IoT system a	architecture for heal	hcare applications			3	80%	70%	М	-	-	-	-	-	-	-	-		-	-	М	-	-

Duratio	on (hour)	Building blocks of IoT	IoT Enabling Technologies	Machine-to-Machine and system management	Smart healthcare applications	Telehealth Technology
		9	9	9	9	9
S-1	SLO-1	Characteristics of IoT	Wireless sensor network	Smart healthcare	Real time smart healthcare model using IoT	Mobile application for medical diagnosis
3-1	SLO-2	Physical design of IoT	Cloud computing	Distributed Analytics and Edge Intelligence	Sensor modules	Architecture of the program, design of the modules
S-2	SLO-1	IoT protocols	Big data analytics	Smart Healthcare Use Cases and Applications	Model Architecture	Telecardiology to detect cardiac abnormalities
0-2	SLO-2	IoT devices	Communication protocols	Healthcare Monitoring	Wearable smart health management clothing	Telecommunications, Wearable device for ECG monitoring
	SLO-1	Network/internet layer	Embedded systems	Wearable Devices	Data acquiring	Virtual clinic – a telemedicine framework
S-3	SLO-2	Transport layer,	Key components	architecture of wearable devices in healthcare	Training and testing, accuracy prediction	System model
S-4	SLO-1	Application layer	IoT levels and deployment templates	Pulse Rate Monitoring System	Fog based Real time analytics	Research methodology
3-4	SLO-2	Layer protocols	System components	Smart Glove for Paralyzed Patients	IoT analytics	Proposed clinical decision support systems
	SLO-1	Logical design of IoT	IoT level - 1	Automatic Medicine Dispenser	Data gathering and Consumptions	Personalized Telehealth care

S-5	SLO-2	IoT functional blocks	IoT level - 2	Smart Healthcare Applications and Real-Time Analytics Through Edge Computing q	Protocols used for IoT platform	Categories based tele-based services
S-6	SLO-1	Communication models	IoT level - 3	Comparison cloud, fog and edge computing	Real-Time Stream Processing	Telediagnosis
	SLO-2	Request response model	Applications	Edge Computing and Healthcare Systems	Fog Computing	Machine learning approach for telediagnosis
S-7	SLO-1	Publish subscribe model	IoT Level – 4	Edge Computing General Framework	Fog computing architecture	Architecture of Mobile Telemedicine Systemusing MMS for telediagnosis
	SLO-2	Push pull model, Exclusive pair model	IoT Level – 5	Edge Computing Use Cases	Characteristics of fog computing	Teleconsultation, Telenursing
	SLO-1	IoT communication ApIs	IoT Level – 6	Edge Computing for Real-Time Analysis	Comparison of fog, cloud, and edge	Teletreatment and Telerehabilitation
S-8	SLO-2	Rest based communication APIs	Applications	Serverless Framework for Real-Time Analysis	Role of Fog Computing in Healthcare	Tele-Psychiatry
	SLO-1	Request response model used by REST	Wellness monitoring and diagnosis	Real-Time Map-Reduce Framework UsingEdge	Deployment of Healthcare Applications	Ethical Challenges, TelemedicineAuthorization
S-9	SLO-2	WebSocket based communication APIs	Wearable electronics	Challenges for IoT-based Edge computing and deployment	Case Study: A Real-Time Fog HealthcareScenario, Patient monitoring system	Challenges to Tele-Based Healthcare

Loorning	1. Arshdeep Bahga, Vijay Madisetti ," Internet of things-Hands on approach"VPT Edition 1, 2014.
Learning	2. Pethuru Raj, Jyotir Moy Chatterjee, Abhishek Kumar, B. Balamurugan. "Internet of ThingsUse Cases
Resources	for the Healthcare Industry" Springer, 2020

Rajkumar Buyya, Amir Vahid Dastjerdi, "Internet of Things: Principles and Paradigms", Elsevier, 2016.
Hemanth D. Jude, Valentina Emilia Balas, "Telemedicine Technologies: Big Data, Deep Learning, Robotics, Mobileand Remote
Applications for Global Healthcare", Academic Press, 2019

Learning Asses	ssment										
	Dia and Lauri			C	Continuous Learning Ass	sessment (50% weightag	ge)			Fig. 1 Francis of the	(FOO(
	Bloom's Level	CLA – 1	(10%)	CLA – 2	CLA – 2 (15%) CLA – 3 (15%)		CLA – 4	(10%)#	Final Examination	(50% weightage)	
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
evel 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	10	00 %	10	0 %	1(00 %	1(00 %

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Course Code	18BME373T	Course Name		MICRO FLUIDICS	Course Category	Е	Professional Elective L T P C 3 0 0 3
Pre-requisite Courses Course Offerin		Biomedic	Co-Requisite Courses	Nil Data Book / Codes/Standards	Progressive Courses Nil	Nil	
Course Learnin	Course Learning Rationale (CLR): The purpose of learning this course is to:						Program Learning Outcomes (PLO)
	· · · · · · · · · · · · · · · · · · ·				1 2	3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15

Oourse Lee	The pulpose of realiting this course is to.			carriii	9					riogra		arring	Outoo	11100 (1						
CLR-1:	Understand the basic concepts o	the microfludic and nanofluidic	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Get an idea about the Interfaces in	n Microfluidic and Nanofluidic Systems	<u> </u>	_	_															
CLR-3:	Acquire an idea about the materia	Is and various fabrication methods and techniques		(%)	(%)	ge		Ħ						夫		99				
CLR-4:	Get an idea about the fluidic contr	ol methods and detection methods	<u> </u>	l co	eut	Je Je		J Bu		ge				>		auc	g			
CLR-5:	Get an idea about the application	of various microfludic and nanofluidic in biological system	ing	Se.	E	Knowledge	SiS.	형	gu,	Usa	nre	_		Team	<u>.</u> E	듄	بق			
CLR-6:	Get an overall idea about the micr	rofluidic and nanofluidic system importance in Medical Domain	į	Prof	Attainme		naly	eke	esi	ا ا	Ę	≓ &		& Te	gat	∞ .:	ear			
			_ È	cted F	pe l	.⊑	⋖	∞ □	S, D	욘	<u>«</u>	ap ap			E	Mgt	ng [_	2	6
Course Lea	arning Outcomes (CLO):	At the end of this course, learners will be able to:	Level o	Expecte	Expecte	Engineering	Problem	Design	Analysi Resea	Modern	Society	Environ Sustair	Ethics	Individu	Communication	Project	Life Lor	PSO - 1	PSO - 2	PS0 -
CLO-1:		of the microfluidic and nanofluidic	1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2:	Analyze the various interfaces wi	th surface and devices	1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-3:		and methods with materials used for fabrication of micofluidic and nanofluidic structures	2	80	70	-	М	-	-	-	-	-	-	-	-	-	-	М		-
CLO-4:	Overview of problem for control a	nd detection 's of fluid interaction and techniques used for solving	1	80	70	-	-	Н	-	-	-	-	-	-	-	-	М	-	М	-
CLO-5:	Explain the various Microdevice Technologies		1	80	70	-	-	-	-	-	-	-	-	-	-	-	М	-	-	-
CLO-6:	Outline the importance of microfluidic and nanofluidic in biological application					-	-	-	-	-	-	-	-	-	-	-	-	-	-	-

Duratio	Basic Microfludic concepts	Materials and fabrication Processes for Microfluidic	Fluidic control methods and Detection methods	Microdevice Technologies	Applications to Biological System
	9	9	9	9	9
S-1	SLO-1 Introduction to Microfluidics	Materials for Microfluidic Devices	Fluid Control :Basic theory	Actuators for micropumps	Electrophoresis:DNA separation
3-1	SLO-2 Introduction to Microfluidics	Silicon Based Materials	Pressure – Driven Flow	Actuators for micropumps	Case study :DNA separation
	SLO-1 The microfluidic advantage	Glass Based Materials	Shear driven Flow	Actuators for Microvalves	Shear-driven flow: Biomolecular separation
S-2	SLO-2 Fluidics and Transport Fundamentals: The continuum approximation	Polymers Based Material	Shear driven flow examples	Actuators for Microvalves	Case study : Biomolecular separation
	SLO-1 Laminar flow	Fabrication of Microfluidics devices	Electrokinetically -driven flow	Flow sensors	Ion Transport with case study
S-3	SLO-2 Laminar flow(contd.)	Photolithography & its techniques	Electrokinetically –driven flow problem and examples	Microarrays	Concentration with case study
S-4	SLO-1 Diffusion in microfluidic systems	Additive Techniques	Single Molecule Detection Methods	Microarrays	Bioanalysis:Immunoassay
3-4	SLO-2 Diffusion in microfluidic systems(contd.)	Subtractive Techniques	Optical detection methods	Microreactors	DNA analysis
S-5	SLO-1 Surface forces and droplets	Silicon microfabrication	Optical detection methods examples	Microreactors	On-chip separations and combinations

	SLO-2	Surface forces and droplets(contd.)	(Dry Reactive Ion Etching) DRIE	Electrochemical method	Pipettes and Dispensers	Sample injection and separation
	SLO-1	Pumps and valves	Surface micromachining	Electrochemical method examples	Pipettes and Dispensers	Micro-gas chromatography:
S-6	SLO-2	Pumps and valves(contd.)	Glass Microfabrication – wet isotropic etching	Measurement of Fluidic Properties: Nonintrusive flow measurement techniques	Microanalytical Chips	Micro gas sensors for micro GC
S-7	SLO-1	Electrokinetics	Wafer Bonding – Fusion, Anionic and Adhesive	Streaming potential/current measurementin pressure-driven flows	Microanalytical Chips	Case study for a micro GC
3-1	SLO-2	Electrokinetics(contd.)	Polymer microfabrication	Current monitoring in electroosmotic flow	Electrochemical microfluidics devices	Micro-scale impedance measurements
S-8	SLO-1	Electro-osmosis	Injection molding and Hot embossing	Optical flow imaging techniques using a tracer: Properties of flow tracers	Electrochemical microfluidics devices(contd.)	Biosensor
3-6	SLO-2	Electro-osmosis(contd.)	Casting & Lithography	Scalar image velocimetry	Paper Microfluidics devices	Biosensors: Case study 1
	SLO-1	Electrophoresis	Fabrication of microfluidic channels in SU-8	Scalar image velocimetry	3D Printed Microfluidic Devices	Nano- Biosensors
S-9	SLO-2	Dielectrophoresis	Microfluidic networks created in biodegradable materials.	Laser-induced fluorescence photo bleaching anemometer with stimulated emission depletion	3D Printed Microfluidic Devices(contd.)	Nano-Biosensors: Case study 2

	1. Patric Tabeling "Introduction to Microfluids" Oxford U. Press, New York 2005. 2. Yujun Song, Daojian Cheng& Liang Zhao," Microfluidics: Fundamentals, Devices, and Applications", Wiley- VCH.First	5. V 6. N
Learning	edition ,2018 3. Xiujun (James) Li and Yu Zhou," Microfluidic devices for biomedical applications", Woodhead Publishing	Edi 7. S
Resources	Limited,16th edition,2013. 4.Jeffrey D. Zahn, "Methods in Bioengineering -Biomicrofabrication and Biomicrofluidics".Artech House, 1st	Ap _j 8. J
	edition,2010	9. C

- 5. Wei-Cheng Tian, Erin Finehout," Microfluidics for Biological Applications"Springer, 2008
 6. Nam-Trung Nguyen, Steven T. Wereley, "Fundamentals And Applications of Microfluidics, Artech Print on Demand, Second dition,2006
- Sushanta K. Mitra, Suman Chakraborty "Microfluidics and Nanofluidics Handbook: Fabrication, Implementation, and Applications", CRC Press; 1 edition, 2017.

 8. Jan Korvink, Oliver Haber, "MEMS: A Practical Guide to Design, Analysis, and Applications", Springer, 2006

 9. Chandra K. Dixit, Ajeet Kaushik, "Microfluidics for Biologists: Fundamentals and Applications", Springer, 2016

Learning Assessme	ent												
	Continuous Learning Assessment (50% weightage)												
	Bloom's Level	CLA – 1	(10%)	CLA – 2	(15%)	CLA - 3	(15%)	CLA – 4 (10%)#	Final Examination (50% weightage)		
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-		
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-		
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-		
	Total	10	0 %	100	100 % 100 %				0 %	10	100 %		

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Course Code	18BME374T	Course Name	MEDICAL ETHICS AND INTELLECTUAL PROPERTY RIGHTS	Course Category	Е	Professional Elective	3	T 0	P 0	C 3
Pre-requisite Courses Course Offering	NII	Biomedica	Co-requisite Courses Nil	Progressive Courses Nil	Nil					

Course Lea	arning Rationale (CLR): The purpose of learning this course is to:		earniı	ng	Program Learning Outcomes (PLO)														
CLR-1:	Understand the fundamentals of medical ethics	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14 15
CLR-2:	Get an idea about the codes of medical ethics		_						당			Sustainability							
CLR-3:	Acquire an idea about intellectual property rights	(Bloom)	(%)	(%)		ge		ent	seal			inat		Work		æ			
CLR-4:	Get an idea about patents	(B)	ြင့်	Attainment		Knowledge		a l	Re	e Je		sta				ance	_		
	Get an idea about copyrights	ng	Cie.	Ĕ		δ	SS.	elopme	esign,	Usage	<u>e</u>			eam	o	Ë	arning		
CLR-6:	Get an overall idea about trademarks and geographical indicators	hinking	Proficie	ttai		조	Analysis	Deve	esi) loo	Culture	t &		& Te	Sati	∞	ear		
		_	8	β		i)		∞ర	sis, D	_	∞ŏ	mei			E	Mgt.	ong L	_	3 2
Course Le	arning Outcomes (CLO): At the end of this course, learners will be able to:	evel of	Expecte	Expected		Engineering l	Problem	Design	Analysi	Modern	Society	Environment	Ethics	ndividual	Comm	Project	-ife Lor	- 08c	- 0Sc - 0Sc
CLO-1:	Outline the importance of medical ethics	1, 2	80	70		-	-	-	-	-	-	-	H	-	-	-	М	-	7 7
CLO-2:	Analyze the development of IPR	1, 2	80	70		-	-	-	-	-	М	-	-		-	-	М	М	
CLO-3:	Understand the principle of various agreements	2	80	70		-	-	-	-	-	-	-	-	-	-	-	М	М	-
CLO-4:	Outline the importance of patents	1	80	70		-	-	-	-	-	М	-	-	-	-	-	М	-	М -
CLO-5:			80 80	70		-	-	-	-	-	М	-	-	•	-		М	•	
CLO-6:	D-6: Understand the concept of trademarks and geographical indicators			70		-	-	-	-	-	-	-	-	•	-	-	М	-	

Dti	(1	Medical Ethics	Introduction to Intellectual Property Rights	Patents	Copyrights	Trademarks and Geographical Indicators
Duratio	on (hour)	9	9	9	9	9
S-1	SLO-1 D	Definition and historic evolution of bioethics	Origin and development of IPR	Definition of patents	What is copyright	Trademark and purpose of a trademark
5-1	SLO-2	Codes and guidelines, universal principles	History of IPR	Purpose of a patent	Why copyright	Characteristics of trademark
S-2	SLO-1	Medical ethics:some basic issues	Importance and need for protection of intellectual property	What sort of things can be patented, Patentable and non-patentable inventions,	Literature and artistic works	Functions of trademarks
	SLO-2	Medical ethics:some basic issues	ome basic issues Rights to be given Conditions for an invention		Protection of copyright	Guidelines for the registration of a trademark
0.0	SLO-1	Feaching and learning medical ethics	Patentable subject matter	Invention vs Innovation	Right of reproduction	Nontraditional trademarks
S-3	SLO-2	Feaching and learning medical ethics	Emerging trends and issues in IPR	Process Patent	Right of public performance	Major types of trademarks
0.4	SLO-1 C	Codes of conduct	Creativity and Invention	Product Patent	Right of broadcasting	Protection of a trademark
S-4	SLO-2 C	Codes of conduct	Theories on concept of property	Types of patent applications	Right of translation	Purpose of a trademark
	SLO-1 R	Rights of patients	Public Vs. Private	Precautions while patenting	Right of Adaptation	Madrid system for the International registrationof trademarks

S-5	SLO-2 Rights of patients	Tangible Vs. Intangible Industrial Vs. Intellectual	Patent specification	Transfer of copyright	Madrid system for the International registration of trademarks
0.0	SLO-1 Rights of life	World Intellectual Property Organization(WIPO)	Patent claims	Limitations of copyright	Industrial design
S-6	SLO-2 Rights of life	World Trade Organisation (WTO)	Disclosures and non-disclosures	Enforcement of Rights	Purpose of industrial design
0.7	SLO-1 Malpractice	General Agreement on Tariffs and Trade(GATT) agreement	Patent rights and infringement	International conventions and treaties	Protection of industrial design
S-7	SLO-2 Negligence	Major Conventions on IP	Patent rights and infringement	International conventions and treaties	The Hague agreement
0.0	SLO-1 Care of the terminally ill	Berne Convention	Rights of a patent owner	Benefits from copyright protection	Geographical indication
S-8	SLO-2 Distributive Justice in Health Care	Paris Convention	Patent cooperation treaty	Benefits from copyright protection	Appellation of origin
0.0	SLO-1 Human experimentation	TRIPS agreement	Paris convention for the protection of industrial property	Works that are protected by copyright	Protection of geographical indication(GI)
S-9	SLO-2 Clinical trials	Basic forms of intellectual property rights	Importance, advantages and disdvantages of patents	Works that are not protected by copyright	Difference between a GI and a trademark

Learning Resources	1. 2.	Ramakrishna B and Anil Kumar H S, 'Fundamentals of Intellectual Property Rights: For Students, Industrialist and Patent Lawyers', Notion Press, 2017. C M Francis, Medical Ethics, Second Edition, Jaypee Brothers, 2004.	3.	Chawla H S, Introduction To Intellectual Property Rights, Oxford and IBH Publishing, 2020.
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Learning Assessm	nent											
	Dia			C	ontinuous Learning Ass					Fig. 1 Franciscotion (F00/!- -t)	
	Bloom's Level	CLA – 1	(10%)	CLA – 2	CLA – 2 (15%)		CLA – 3 (15%)		10%)#	Final Examination (50% weightage)		
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total	100 %		0 %	10	00 %	100	0 %	100 %			

[#] CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	Dr.A.K.Jayanthy, SRMIST

Course Code 18BME375T		Course Name	VIRTUAL INSTRUMENTATIO	N FOR BIOMEDICALENGINEERS	Course Category	Е	Professional Elective	3	T 0	P 0	C 3
Pre-requisite Courses Course Offering	IVII	Biomedia	Co-requisite Courses cal Engineering	Nil Data Book / Codes/Standards	Progressive Courses Nil	Nil					

Course Lea	arning Rationale (CLR):	The purpose of learning this course is to:	Le	arnin	g				P	rogra	m Lea	rning	Outco	mes (l	PLO)					
CLR-1:	Understand the fundamental Virtu	al Instrumentation	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Get an idea about the software us	ed in Virtual Instrumentation and function							£			lity								
CLR-3:	Acquire a concept about the VI pr	ngramming	(Bloom)	(%)	(%)	dge		ŧ	Research			nabi		폱		Ф			1	
CLR-4:	Get an idea about the biomedical	application of Virtual Instrument	(B)	ncy		vled		relopment		ge		Sustainability		n Work		inanc	g		i	
CLR-5:	Get an idea about the research ba	sed development in the area of Virtual Instrument	hinking	Proficie	Attainment	Knowlec	Analysis	velo	Design,	Usage	Culture	∞ర		Геаш	ation	» Fi	arning		i	
CLR-6:	Understand the different biologica	application of LabVIEW	of Thin	cted Pro	ed Att	ering		& De	is, De	Tool r	∞ర	Environment		-s s	mmunica	Mgt.	ong Le	1	2	3
Course Lea	arning Outcomes (CLO):	At the end of this course, learners will be able to:	Level	Expect	Expected	Engineering	Problem	Design	Analysis,	Modern	Society	Enviror	Ethics	Individual	Сотп	Project	Life Lo	PSO -	PSO -	- OSd
CLO-1:	Analyze the Virtual Instrument in	healthcare domain	1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-		-	-
CLO-2:	Explain the Virtual Instrument pro	cesses and software	1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-3:	Differentiate the various Program	ming techniques	2	80	70	-	-	L	-	-	-	-	-	-				Μ	1	-
CLO-4:	Illustrate the concepts of LabVIE	V in Real time experimental	1	80	70	-	-	L	-	-	-	-	-	-	-	-	-		М	-
CLO-5:	Illustrate the concepts of LabVIE	V with suitable examples	1	80	70	-	-	L	-	-	-	-	-	-	-	-	-		-	-
CLO-6:	Outline the research application i	n Biological	1,2	80	70	-	-	L	-	-	-	-	-	-		-	-	-	-	-

Dti	(1)	Virtual Instrumentation	Programming Mode& Techniques	Hardware Instrument	Common Instrument Interface	Labviews Tools & Its Applications
Duratio	n (hour)	9	9	9	9	9
0.4	SLO-1	Virtual Instrumentation - Introduction	Data Flow Programming	Digital I/O Techniques	General Purpose Interface Bus(GPIB)	Signal Process: Fourier transform
S-1	SLO-2	Conventional Instrumentation	G' Programming Concepts	Digital I/O Techniques	GPIB :IEEE 488.2 STANDARD	Fourier transform problem
0.0	SLO-1	Architecture of VI	Creating and Saving VIs, SubVIs	Data Acquisition in LabVIEW	RS232	Power spectrum
S-2	SLO-2	Architecture of VI	Wiring, Editing, and Debugging VI	Data Acquisition in LabVIEW	RS485	Correlation
S-3	SLO-1	Conventional Virtual Instrumentation	Control Structures such as the For Loop andthe While Loop	Hardware Installation and Configuration	Virtual Instrument Software Architecture(VISA)	Windowing
3-3	SLO-2	Distributed Virtual Instrumentation	Shift Registers and Their function	Components of DAQ	VXI	Filters
C 4	SLO-1	Virtual Instruments Versus Traditional Instruments	Selection Structures: Case and sequencestructures	Components of DAQ	VXI	Oscilloscope
S-4	Advantages of VI	Selection Structures: Formulae nodes, feedback nodes	DAQ Signal Accessory	USB	Waveform generator	

S-5	SLO-1 Evolution of LabVIEW	Arrays	DAQ Signal Accessory	USB	Multi-channel data acquisition
	SLO-2 Creating Virtual Instruments Using LabVIEW	Arrays	DAQ Assistant: Create a MAX-Based Task	PCI	Vision and Motion tools
•	SLO-1 Creating Virtual Instruments Using LabVIEW	Cluster :Creating Cluster Controls and Indicator	DAQ Assistant: Create a Project-Based Task	PCI Express	Vision and Motion tools- problems
S-6	SLO-2 Advantages of LabVIEW	Cluster functions	DAQ Hardware	PXI	Vision and Motion tools -problems
0.7	SLO-1 Front Panel of Virtual Instruments	Waveform Chart and graph	DAQ Hardware	PCMCIA	Bio Bench
S-7	SLO-2 Block Diagram of Virtual Instruments	XY Graph	DAQ Software	PCMCIA	Biomedical work bench
	SLO-1 LabVIEW Environment and its Menus	Strings, Creating String Controls and Indicators	4–20mA Current Loop	SCXI	Biomedical real time application- ECG
S-8	SLO-2 LabVIEW Environment and its Menus	String Functions	4–20mA Current Loop	SCXI	Biomedical real time application-EMG
	SLO-1 Palletes of LabVIEW	Tables and List Boxes	60 mA Current Loop	LXI	Biomedical real time application-EEG
S-9	SLO-2 Palletes of LabVIEW	File Input/Output Functions	60 mA Current Loop	LXI	Biomedical real time application-EOG

Learning Resources

- 1. S. Sumathi and P. Surekha, "Labview based Advanced Instrumentation Systems", Springer, First edition, 2007
 2. Gary Jonson, "Labview Graphical Programming", Second Edition, McGraw Hill, New York, Fourth edition2006.
 3. Lisa K. wells and Jeffrey Travis, "Labview for everyone", Prentice Hall Inc., New Jersey; First edition 1997.
- 4. Gupta S and Gupta J P, "PC interfacing for Data Acquisition & Process Control", Instrument Society of America, Second Edition, 1994

5. Jon B. Olansen and Eric Rosow, "Virtual Bio-Instrumentation: Biomedical, Clinical, and Healthcare Applications in LabVIEW ", Prentice Hall, First edition, 2001

6. Ronald W. Larsen , "LabVIEW for Engineers", Pearson ,First edition, 2010 7. Robert H. Bishop," Learning with LabVIEW", Pearson, First edition, 2014

8. John Essick," Hands-On Introduction to LabVIEW for Scientists and Engineers ",Oxford University Press, Fourth edition ,2018

Learning Assessm	nent										
	Dia anala i anal			Co	ontinuous Learning Ass	essment (50% weighta	ge)			Final Francis etter /	F00/!=ht====\
	Bloom's Level	CLA – 1	CLA – 1 (10%)		5%) CLA – 3 (15%)		(15%)	CLA – 4 (10%)#	Final Examination (50% weightage)
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	100) %	10	0 %	100	0 %	10	0 %

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Ms Oinam Robita Chanu, SRMIST

		Course	Course HEALTH CARE DATA ANALYTICS					L	Т	Р	С	
Course Code	18BME376T	Name	HEALTH (Course Category	Ε	Professional Elective	3	0	0	3		
Pre-requisi	Pre-requisite Pre-requisite		Co-requisite		Progressive							

Pre-requisite Courses		Co-requisite Courses			Progressive Courses
Course Offering Department	Biomedical Engineering		Data	Book / Codes/ Standards	Nil

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	L	earnir	ıg
CLR-1:	Understand the basics of Health	care data	1	2	3
CLR-2:	Understand the basics of data a	nalysis			
CLR-3:	Understanding about complexity	of health care data and information system	Thinking	(9)	· 6
CLR-4:	Utilize the knowledge of data an	alytics to solve health problems	hin	(e) >	t (%)
CLR-5:	Data security and Ethics in Hea	th care data	-	ected	pected ainment
1			evel of Bloom)	oect ofici	xpected
Course L	earning Outcomes (CLO):	At the end of this course, learners will be able to:	Le Bi	Exp	Exp
CLO-1:	Understand the conceptual and	practical difficulties in getting health care data	3	80	75
CLO-2:	Know how to find clean and per	form suitable statistical methods for analysis	3	80	70
CLO-3:	Understand the information syst business development	em design and technical skills to use data for decision making and	3	75	70
CLO-4:	Understand the importance of D	ata standards, security and ethics in health care data	3	80	75
CLO-5:	Understand how data analytics	can provide potential solutions to improve health outcomes.	3	80	70
CLO-6:	Understand concepts related to analytics	health care data innovation, big data analytics and predictive	3	80	70

				Pro	gram	Learni	ing O	utcom	es (Pl	- O)				
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO – 1: Professional	PSU='2::Project Management	PSO – 3: Analyze & Reseach
L	M	-	L	L	-	M	M	L	-	M	M	L	M	L
М	М	-	L	L	-	М	М	L	-	М	М	L	М	L
М	М	1	L	L	-	М	Н	L	L	М	М	L	М	М
Н	М	Г	М	Г	Н	М	Н	L	-	М	М	L	М	М
Н	М	L	Н	Н	Н	М	М	L	L	М	М	L	М	Н
Н	М	I	I	I	-	М	М	L	-	М	М	L	М	Н

Duration	on (hour)	Health care data	Data management and Information system	Pre processing	Big data analytics	Predictive modelling
	(- ,	9	9	9	9	9
S-1	SLO-1	Introduction to health care data	Introduction to MIS	Introduction to pre processing	Introduction to big data analytics	Introduction to modelling
3-1	SLO-2	Data analytics life cycle				Regression models
S-2	SLO-1	Complexity of Health care data	Management pyramid	Concept of Outliers	Properties of Big data	Introduction to Regression models
3-2	SLO-2	Importance of Data in health care	Concept of Informatics	Ways to Detect outliers	Introduction to Big data analytics	Types of Regression models
S-3	SLO-1	Evidence based medicine	Components of information system	Ways to deal with outliers	Classification and Prediction	Types of Link functions
3-3	SLO-2	Evidence based medicine	Data sources and Data tools	Ways to deal with outliers		Concept of Correlation
S-4	SLO-1	Data sources	Management of databases	Process of Dealing outliers	Data mining	Auto correlation
3-4	SLO-2	Digital health initiatives	Management systems	Missing Values	Importance of data mining in Health care	Multicollinearity and its effects
S-5	SLO-1		Decision support system development	Concept of Missing values	care	Ways to detect multicollinearity
	SLO-2	Concept of M health	Ethical issues in health care data	Possible reasons for Missing values	Association rule mining	Multiple correlation
S-6	SLO-1	M Health and data types	Ethical issues in health care data	Types of missing values	Association rule mining using R	
3-0	SLO-2	e-Health	HIPAA standards	Ways to deal with missing values		Concept of Validation
S-7	SLO-1	e- health and data	Standardization - ICD	Ways to deal with missing values		Types of validation
3-7	SLO-2	Telemedicine	Steps to Secure Big data	Concept of Dimensionality	Introduction to Decision trees	Cross validation
S-8	SLO-1	Telemedicine and its importance	Steps to Secure Big data	Importance of dimensionality reduction	Introduction to CART	Internal validation

	SLO-2	Ways to manage the different data types	Classifying data	Statistical methods for dimensionality reduction		External Validation
S-9	SLO-1	Ways to manage the data types	Protecting big data	Statistical methods for dimensionality reduction	Classification by decision tree induction	Concept of over and under fitting
3-9	SLO-2	Ways to manage the data types	Intellectual property challenge	Statistical methods for dimensionality reduction	Classification by decision tree induction	Ways to deal with over fitting and under fitting
Learning Resources 1.		Big Data Analytics in Healthca	re: A Critical Analysis, Editor(s): Nilanjan I	atrick Siarry, Pramod Kumar Singh, Ajith A Dey, Himansu Das, Bighnaraj Naik, Himan Integr Bioinform. 2018;15(3):20170030. Pu	su Sekhar Behera,	7-0030

Learning Asses	sment													
				Contin	uous Learning Ass	essment (50% weig	ghtage)			Final Evamination	(E0% weightage)			
	Bloom's Level of Thinking	CLA – 1	1 (10%)	CLA – 2	2 (15%)	CLA –	3 (15%)	CLA – 4	4 (10%)#	Final Examination (50% weightage				
	3	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	30 %	_	30 %		30 %	_	30 %	_	30%	_			
Level 1	Remember Understand Apply	30 %	-	30 %	-	30 %	-	30 %	-	30%	-			
Level 2	Apply	40 %	_	40 %	-	40 %	_	40 %	_	40%	_			
Level 2	Analyze	40 /6	_	40 %		40 %	-	40 /6	_	4076	_			
Level 3	Evaluate	30 %		30 %		30 %	_	30 %	_	30%				
Level 3	Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-			
	Total 100 % 100 % 100 %		10	0 %	10	0 %								

[#]CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Prof M Bagawandas – Centre for statistics , SRM IST	1.Dr.M Prakash , SRMIST

	400145 4045								_			_		_					L	T	Р	С
Course Code	18BME461T	Course Name	BIOME	EDICAL INFORMATION	S				Cour	se Cate	gory	Ε		Pro	tession	al Electi	ve		3	0	0	3
Pre-requ Cours		Nil	Co-requisite Courses			Nil					Progre Cour							Nil				
Course Offeri	ng Department	Biomedia	cal Engineering	Dat	a Book / (Codes/S	Standards									Nil						
Course Learni	ng Rationale (CLR):		The purpose of learning this course is to:			Learni	ng					Prog	gram Le	arning	Outco	mes (Pl	LO)					
CLR-1:	Understand what is medical	informatics, The type	s of medical databases and carious theft issues	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	1
CLR-2:	Gain knowledge about the si	tructure of Hospital in	formation system, clinical Information system																			
CLR-3:	Understand the telemedicine	technology, and type	es of data transfer		= F	(%)	(9)				arch			ability								
CLR-4:	Gain knowledge in an autom	ation of clinical labor	atories		(Bloo		(%) tue	Knowledge		ment	Research	e g		stain		Work		ance	-			
CLR-5:	Learn different decision mak	ing algorithms and co	omputerized imaging techniques		Thinking (Bloom)	Proficiency	Attainment	Know	Analysis	Development	Design,	Tool Usage	Culture	s Su		Team Work	ation	roject Mgt. & Finance	Learning			
CLR-6:	The learn different types of o	computer aids for har	dicapped and computers in the care of critically	ill patients	of Thi	ed Pr	8	Engineering	m An	∞ర	is, De	υ T00	∞ర	nment		ndividual &	ommunication	Mgt.	ng Le	-	2	
Course Learn	ing Outcomes (CLO):	At the end	of this course, learners will be able to:		evel	xpected	xpect	ngine	roblem	esign	nalysis,	Nodem -	ociety	nvironm	Ethics	pdivid	omu	rojed	ife Long	- OS	-080	Ċ.
CLO-1:	Understand applications of co	omputers in health ca	are and different types of medical databases		1, 2	2 80%	70%	М	-		4		0)	ш	ш		U	п.		т.		_ °
CLO-2:	Implement Hospital Information	on system and Clinica	al Information system		2	80%	70%	М														
CLO-3:	Gain knowledge on telemedic	cine technology			2	80%	70%			М		М								М		L
CLO-4:	Implement automation of clini	ical laboratories			3	80%	70%					М										
CLO-5:	Apply different decision makin	ng algorithm for imag	ing and diagnosis		3	80%	70%	М												М		L
CLO-6:	Gain knowledge on various c	omputer aids for han	dicapped and computers role in care of critically	ill patients	3	80%	70%	М														1

Duration	(hour)	Medical informatics and Computer based patient record	Hospital Information system and Clinical information system, Telemedicine	Computers in a Clinical Laboratory	Computer assisted medical Decision making	Computer aids for the handicapped & Computers in the care of critically ill patients
		9	9	9	9	9
S-1	SLO-1	What is Medical Informatics?	Functional capabilities of computerizedHospital information system	Microprocessor for automation	General model of CMD	Mobility, EMG controlled limbs
5-1	SLO-2	Prospects of medical informatics	s of medical informatics Need for computerization oh hospitals in India Database approach to laboratory computerization		Various approaches in decision making	Aids for Blind and visually handicapped
S-2		Historical review of the development of computers and informatics	Security of computer records	Automation of clinical laboratories	Computer assisted decision support systems	Braille system, bat cane
5-2	SLO-2	Foundation ontology	Cost effectiveness of information processing by computer	Automated methods in hematology	Algorithmic methods	Portable reading aids
	SLO-1	What is computer based patient record	Benefits of clinical information system	Chromosome analysis by computer	Elements of a protocol	Artificial vision for the blind
S-3		History taking by computer and Dialoguewith Sources of data for decision making Computerized cytology and histology the computer		Probabilistic approaches to decision making	Concept of artificial retina	
	SLO-1	Development toolsIntranet	Modes of decision output to Physician	Automated scanning for cervical scanner	Sequential Bayes, Linear discriminant function	Computer aids for the deaf

S-4	SLO-2	CPR in radiology	Registry of Computerized Medical record system	Computer assisted semen analysis	Multivariate analysis	Computer speech generation and recognition
S-5	SLO-1	Types of databases: Bibliographic databases	CIS in obstetrics – Gynecology	Radio Immunoassays	Database comparisons and case based reasoning	Robotics to assist the elderly infirm
	SLO-2	Non Bibliographic databases	Fetal Monitoring	Intelligent laboratory information system	Production rule systems	Cognitive system engineering
S-6	SLO-1	Medical information retrieval	What is telemedicine	Computer aided analysis of Echocardiograms	Cognitive models	Automated computer assisted Fluid and metabolic balance
	SLO-2	Medical information retrieval techniques	Need for telemedicine	Computerized ECG, analysis of signals	Semantic networks	Pulmonary function Evaluation
S-7	SLO-1	Legal, Security and privacy issues in computers and internet	Telemedicine technology	Assessment of performance of ECG computer programs	Decision analysis in clinical medicine	Computerized decision support for mechanical ventilation
	SLO-2	Types of threats	Types of data transfer	Computerized EEG	Computers in nuclear medicine	Cardiovascular physiological evaluation
S-8	SLO-1	Cryptography	Mode of transmission	Long term monitoring of EEG	Data acquisition, manipulation and processing	Computer assisted surgery
	SLO-2	Digital Signature	Internet and telemedicine	Computerized EMG	Computer assisted medical imaging-CT	Robotics in surgery
S-9	SLO-1	User Authentication	Telemedicine websites	Single fibre EMG	CT-Radiation therapy planning	Sensing system
	SLO-2	Attacks from inside and outside the system	Applications of telemedicine	Computerized EEG	Computer for MRI	Interactive modes

Learning Resources	1. Ramchandra Lele., "Computers in Medicine Progress in Medical Informatics", Tata McGraw-Hill Publishing Company Limited, New Delhi First Edition, 2005 2. Mohan Bansal, M S., "Medical Informatics A Primer", Tata McGraw-Hill Publishing Company Limited, New Delhi, 2nd	 Edward H.Shortliffe, James J. Climino., "Biomedical informatics Computer Applications in Health Care and Biomedicine", Springer, Third Edition, 2006.
	edition 2003.	

Learning Asse	essment										
	Bloom's Level			C	ontinuous Learning Asso	essment (50% weighta	ge)			Final Evansination	FOO(waishtaga)
		CLA – 1	(10%)	CLA – 2 (15%)		CLA – 3	(15%)	CLA – 4 (10%)#	Final Examination (50% weightage)
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	Total 100 % 100 % 100 %		0 %	10	0 %	10	0 %			

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1., Dr. S. P. Angeline Kirubha, SRMIST

Course Code	18RM	E462T	Cour Nar		PHYSIOL	OGICAL MODELING	Cor Cate	ırse gory		Ε				Pro	fession	al Elec	ctive					L 3	T 0	P 0	C 3
Pre-require Cour		MC305T Biod	control S	vstems	Co-requisite Courses	Nil			ressiv		Vil											3	0	0	
Course Of	ffering Departme	ent	В	omedical Engineering		Data Book / Codes/Stan	dards	Vil																	-
Course Lea	arning Rational	e (CLR):			The purpose of	of learning this course is to:		L	.earni	ng					Prog	ram Le	earning	g Outc	omes	(PLO)					
CLR-1:	Understand t	the process	of model	ng to various physiologic	al systems			1	2	3		1	2 3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Understand t	the mathema	atical too	s for static analysis of mo	odels																				
CLR-3:	Perform time	domain ana	alysis of t	he physiological models				om)	(%)	(9				arch			Sustainability								
CLR-4:	Perform frequ	uency doma	in analys	is of the physiological mo	dels			(Bloor	6)	ant (%)		edde	100	Research	Ф		staina		Work		Finance	_			
CLR-5:	Understand t	techniques ii	n system	identification and parame	eter estimation			Thinking (oficien	Attainment		Know	Analysis	Design, 1	Tool Usage	Culture			Team	ation	& Fin	Learning			
CLR-6:	Understand th	he technique	es in desi	gning physiological syste	m models and to pe	rform analysis		of Thin	ed Pro			ering			T ₀₀	∞ర	ment		ంగ	unica	Mgt.	ong Le	_	2	3
Course Le	earning Outcom	es (CLO)·	Д	t the end of this course, l	earners will be able	to.		evelo	Expected Proficiency	Expected		Engineering Knowledge	Problem .	Analysis,	Modem -	ociety	Environment &	Ethics	ndividual	Communication	Project	ife Lor	· - 0Sc	0Sc)-0Sc
CLO-1 :				designing physiological m				1,2		70%				_	-	-	-	-	-	-	-	-	M	-	-
CLO-2:	Detail about th	ne tools for s	static ana	lysis of physiological syst	em			1,2	80%	70%		-	М -	-	-	-	-	-	-	-	-	-	М	-	-
CLO-3:	Describe the to	echniques fo	or time de	omain analysis of physiolo	ogical model			1,2	80%	70%		-	М -	-	-	-	-	-	-	-	-	-	М	-	-
CLO-4:	Describe the to	echniques fo	or freque	ncy domain analysis of th	e physiological mod	els		1,2	80%	70%		-	М -	-	-	-	-	-	-	-	-	-	М	-	-
CLO-5:	Outline the val	rious metho	ds for sy	stem identification and pa	rameter estimation			1,2	80%	70%		-	М -	-	-	-	-	-	-	-	-	-	М	-	-
CLO-6:	Interpret the vi	arious physi	iological	system models				1,2	80%	70%		И		-	-	-	-	-	-	-	-	-	М	-	-

D	(h)	Linear Model	Static Analysis	Time Domain Analysis	Frequency Domain Analysis	System Identification
S-1 SLO-1 models Model Simule Simule System SLO-2 Physiol SLO-2 SLO-1 Engine physiol SLO-2 Science Scien	9	9	9	9	9	
6.4	SLO-1	Introduction to modeling methodology, needfor models, approaches to modeling	Static analysis: Open loop versus closed loop	Introduction to time domain analysis	Frequency response: Open loop frequency response	Identification of physiological control system
3-1	SLO-2	Model identification, model validation and Simulation	Loop gain calculation: Room temperaturecontrol	Linearized respiratory mechanics transient response	Closed loop frequency response	Basic problems in Physiological systemanalysis
6.0	SLO-1	System analysis, fundamental concepts	Steady state characteristics	Linearized respiratory mechanics first ordermodel – impulse response for open loop	Relation between transient and frequencyresponse	Nonparametric and parametric identification methods
5-2	SLO-2	Physiological control system an example	Determination of steady state operating pointfor simple model of muscle stretch reflex	Linearized respiratory mechanics first ordermodel – impulse response for closed loop	Frequency domain specifications	Numerical Deconvolution, Least square estimation
6.2		Engineering control system versus physiological control system	Human body Glucose – Insulin regulatorysystem	Transient response descriptors : Impulse response	Graphical representation of frequency response: Bode plot	Estimation using correlation functions
3-3	SLO-2	Science of modeling	Steady state analysis of glucose –insulin model	Transient response descriptors : Step response	Bode plot :Linearized lung mechanics	Estimation in frequency domain, optimization techniques
6.4	SLO-1	Generalized system properties	Human body chemical regulation of ventilatory system	Concept of sliding theory	Graphical representation of frequency response: Nicholas chart	Problems in parameter estimation
S-4	SLO-2	Models with combinations of system elements	Mechanism of respiration	Neuromuscular reflex action	Nicholas chart : Linearized lung mechanics	Input design
	SLO-1	Linear model of respiratory mechanics	Gas exchanger mathematical modeling	Mathematical model of neuromuscular reflex motion	Graphical representation of frequency response : Nyquist plot	Identification of closed loop systems – "opening the loop"

S-5	SLO-2	Linear model of respiratory mechanics:Derivation of transfer function	Respiratory controller mathematical modeling	Calculation of transfer function	Nyquist plot: Linearized lung mechanics	Starling heart- lung preparation
	SLO-1	Linear model of muscle mechanics	Closed loop analysis : lung and controller	Stability and transient response	Introduction : Circulatory system	Kao's cross – circulation experiment
S-6	SLO-2	Linear model of muscle mechanics: Derivation of transfer function	Calculation of transfer function	Root locus and Routh-Hurwitz stability criterion	Mathematical model of circulatory system	Opening the Pupillary reflex loop
0.7	SLO-1	Distributed versus lumped parameter model	Heart and systemic circulation	Stability analysis: root locus method	Frequency response of circulatory system	Read rebreathing technique
S-7	SLO-2	Distributed versus lumped parameter model: Derivation of transfer function	Mathematical modeling of cardiac output	Introduction to Nyquist plot	Graphical representation for frequencyresponse of circulatory system	Adaptive control of Physiological variables
S-8	SLO-1	Linear system and superposition principle	Calculation of transfer function for simplifiedmodel of cardiac output regulation	Nyquist criterion for stability	Frequency response of glucose – insulinmodel	General adaptive control system
3-0	SLO-2	Laplace transform and transfer function	Cardiac characteristics curve analysis	Relative stability theory	Mathematical model and simulation of glucose – insulin model	Multiple model adaptive control
	SLO-1	Impulse function analysis	Venous return curve	Physiology: Pupillary reflex control	Frequency response approach to pupil control	Model reference adaptive control
S-9	SLO-2	Basics of Linear convolution	Closed loop analysis of heart and systemic circulation	Stability analysis of pupillary reflex control	Frequency response characteristics curve for pupillary control	Optimization in systems with negativefeedback

	Michael C.K. Khoo, "Physiological Control Systems - Analysis, Simulation and Estimation", Prentice Hall of India Private Ltd 2 nd edition. New Delhi. 2001.	
Learning Resources	 Claudio Cobelli Ewart Carson, "Introduction to Modeling in Physiology and Medicine", Academic press series, 1st edition, 2008. 	
	5. Dorf, "Modern Control Systems", Pearson Education India, 1 st edition, 2008.	

. V.Z. Marmarelis, "Advanced Methods of Physiological System Modeling", Vol.3, Springer Science and Business Media, 2013.

 Johnny T. Ottesen, Mette S. Olufsen, Jesper K. Larsen, "Applied Mathematical Models in HumanPhysiology", Vol.9,SIAM, 2004.

	5	Continuous Learning Assessment (50% weightage)								Fig. Franciscation (FOO) and otherway				
	Bloom's Level	CLA – 1	(10%)	CLA – 2	(15%)	CLA – 3 ((15%)	CLA – 4 (10%)#	Final Examination (50% weighta				
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-			
_evel 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-			
_evel 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-			
	Total	100) %	100) %	100) %	100) %	100 %				

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Course Code	18BME463T	Course Name	BIOMIMETICS	Cour Catego		E					Proi	ession	al Ele	ctive				L	. T	P 0	+	C
Jour		Hame		Catog	, y													3	U	U		J
Pre-requi Cours			Co-requisite Courses	Progre Cou		^	Vil															
Course Offe	ering Department	Biomedical Engineering	Data Book / Codes/Standards	Nil																		
Course Lea	rning Rationale (CLR):	The purpose of learning this	course is to:	L	earni	ng					F	rograr	m Lea	rning	Outco	mes (l	PLO)					
CLR-1:	Understand the fundame	entals of biomimetics and its applica	tions	1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Study the concepts of bi	omimetic materials and process												y								
CLR-3:	Acquire an idea about th	e mechanism of cognition and oper	ended design automation	æ	(%)	(%)		m			arch			abilit		~						
CLR-4:	Utilize the basic concept	s of bio-inspired sensors and actuat	ors	(Bloom)		ent (9		/ledg		Development	Rese	e Je		Sustainability		Work		Finance				
CLR-5:	Employ the skills about	he biomimetics of human motion		nking	Proficiency	Attainment		Knov	Analysis	velop	Design,	Usa	Culture	~ઇ		Team	ation	& Fi	Learning			
CLR-6:	Get an overall idea abou	t the application of biomimetic techi	ologies	홑				ering	א ח	∘ర	s, De	T 90	∞ŏ	ment		ంగ	unica	Mgt.	g Le			3
Course Lea	arning Outcomes (CLO):	At the end of this course, lea	arners will be able to:	Level of	Expected	Expected		Engineering Knowledge	Problem	Design	Analysis,	Modern Tool Usage	Society	Environment	Ethics	Individual	Communication	Project	Life Long	PSO - 1	PSO - 2	PS0 – (
		m in biomimetic design in various a		1, 2	80	70		L	L	-	-	-	-	-	-	-	-	-	-	L	М	-
CLO-2:	Identify the basic biologic	ally inspired mechanism, materials a	nd process	1, 2	80	70		М	•	•	-	-	•	-	-	-		-	-	L	-	-
CLO-3:	Identify the mechanism o	f cognition and open ended design a	automation	2	75	65		-	L	L	-	-	-	-	-	-	-	-	-	L		-
CLO-4:	Analyze the importance b	io-inspired sensors and biomimetic	actuators	1,2	75	65		-		М	-			-	-	-		-	М	-	М	-
CLO-5:	Analyze the biomechanic	s and rhythmics of motion		2,3	75	65		L	М	L	-	-		-	-	-	-	-	М	-	L	М
CLO-6:	Outline the application of	biomimetic technologies		1,2	75	65		-	L		L	-		-	-	-	-	-	М	-	-M	-

	ation our)	Introduction to Biomimetics	Mechanism of cognition and open ended design automation	Bio-Inspired Sensors and Biomimetic Actuators	Biomimetics of motion	Application of Biomimetic Technologies
(11	Jui)	9	9	9	9	9
S-1	SLO-1	Introduction : Biologically Inspired Mechanisms	Mechanized Cognition	Biomimetic tactile sensing:Human sense oftouch	Biomechanics of motion: Control center	Artificial intelligence through symbolic connectionism
3-1	SLO-2	Biologically Inspired Mechanisms	Training and Education	Biomimetic tactile sensing:Human sense oftouch	Biomechanics of motion: Control center	Localist symbolic connectionism
	SLO-1	Biologically Inspired Structures and Parts	Language Cognition	Biomimetic artificial touch	Passive external and internal actuation	Distributed symbolic connectionism
S-2	SLO-2	Defense and Attack Mechanisms in Biology	Language Cognition	Examples of bio-inspired tactile sensing	Active external and internal actuation	Symbolic connectionism in biological models
S-3	SLO-1	Materials and Processes in Biology	Sound Cognition	Bio-Inspired hair based interial sensors: Hair structures for inertial sensing	Agonist Mechanism: Hygroscopic mechanism	Neurofuzzy systems
	SLO-2	Materials and Processes in Biology	Sound Cognition	Cricket-inspired accelerometer	Muscular actuation	Neurofuzzy systems
	SLO-1	Bio-Sensors	Visual Cognition	Fly-inspired gyroscope	Antagonist mechanism: Spring Antagonism	Bio-Inspired adhesion technologies
S-4	SLO-2	Bio-Sensors	Visual Cognition	Fly-inspired gyroscope	Muscular Antagonism	Bio-Inspired adhesion technologies
S-5	SLO-1	Robotics Emulating Biology	Machine Bodies and Brains: Evolving Controllers and Some Aspects of the Morphology	Olfactory sensor system for the e-nose	Power amplification: Elastic amplification	Bio-Inspired locomotion mechanisms
	SLO-2	Interfacing Biology and Machines	Evolving Bodies and Brains	Olfactory classification-data processing	Deformation of a constant volume	Size and current technology constrains
S-6	SLO-1	Muscle function	Morphology Representations: Tree representations	Polymer network actuators	Mechanics of hydrostatic systems: Single compartment systems	Quadruped robot system: Mechanical components

	SLO-2	Muscle function	Developmental representations	Biomimetic vision systems	Multiple compartment systems	Quadruped robot system: Mechanical components
	SLO-1	Muscle design	Regulatory network representations	Novel biomimetic materials :Introduction	Rhythmics of motion: Gait	Electrical components of quadruped robot
S-7	SLO-2	Muscle design	Evolving Machines in Physical Reality	Design of self-oscillating polymer gel	Rhythmics of motion: Gait	Electrical components of quadruped robot
S-8	SLO-1	Muscle adaptation	Evolving Machines in Physical Reality	Control of self-Oscillating chemomechanical behaviors	Passive Locomotion	Biologically inspired antenna array design
	SLO-2	Biomimetics of muscle design	Economy of Design Automation	Design of biomimetic soft actuators	Passive locomotion	Biologically inspired antenna array design
	SLO-1	Bio-inspired fiber composites	Principles of Design	Design of autonomous mass transportsystems	Limbless locomotion	Biologically inspired antenna beam patterndesign
S-9	SLO-2	Bio-inspired fiber composites	Research Methodology	Self-oscillating fluids	Multiple limb locomotion	Biologically inspired antenna beam pattern design

Learning Resources
Resources

1. Yoseph Bar-Cohen, "BIOMIMETICS Biologically Inspired Technologies", CRC Press, 1 st Edition, 2006. 2. Trung Dung Ngo, "Biomimetic Technologies: Principles and Applications", Wood head Publishing Ltd, 1 st Edition, 2015. 3. Sandra Persiani, "Biomimetics of Motion: Nature-Inspired Parameters and Schemes for Kinetic Design", Springer, 1 st Edition, 2019.

4. P Gruber, D Bruckner, C Hellmich, · H B. Schmiedmayer, H. Stachelberger, I C. Gebeshuber, "Biomimetics – Materials, Structures and Processes Examples, Ideas and Case Studies", Springer, 1 st Edition, 2011

Learning Asses	sment													
	Bloom's Level			Co	ontinuous Learning Ass	essment (50% weighta	ige)			Final Examination	(50% weightage)			
	of Thinking	CLA – 1	(10%)	CLA – 2	(15%)	CLA - 3	(15%)	CLA – 4	(10%)#	, , ,				
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-			
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-			
Level 3	Evaluate	20 %	_	20 %	_	20 %	_	30 %	_	30%	_			
Level 3	Create	20 %	-	20 %	-	20 %	-	30 /6	-	30%	-			
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10	00 %			

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Course Code	18BME464T	Course Name	NE	EURAL NETWO	ORKS AND GE	NETIC ALGORITHMS			urse egory	Е	Ē			Pro	ofessio	nal El	lective					L 3	T F	P C 3
Pre-request			(o-requisite Courses	Nil				gressi ourses		lil										<u>'</u>	1	'	
Course Offe	ering Department	Electron in BioEle	ics and Communication E ectronics	Engineering wit	hspecialization	Data Book / Codes/Standards	٨	lil																
Course Lea	rning Rationale (CLR):	The pu	rpose of learning this cou	rse is to:				L	_earni	ng				Р	rogran	n Lea	rning	Outco	mes (PLO)				
CLR-1:	Understand the fundar	mental of Artificial I	Neural Network					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13 ′	14 15
CLR-2:	Get an insight about v	arious ANN model						(رط و										
CLR-3:	Familiarize about the	orinciple of self-org	anizing map					Thinking (Bloom)	(%) /	t (%)	ge		aut	Research					Work		920			
CLR-4:	Study the basic conce	pts of Genetic algo	rithm					g (B	Proficiency	Attainment	Knowledge	. <u>v</u>	evelopment	n,	sage	உ				5	-inan	ing.		
CLR-5:	Get an idea about gen	etic algorithm oper	rators					E	rofic	vttain			evel	Design,	Tool Usage	Culture	t &		& Team	catic	~ ~	Leaming		
CLR-6:	Explore on the concept	ts of ANN for Bion	nedical Application					of Th	ected F	ed A	elin	ΑĀ	8	.s.	2	ంగ	nment			in	Mgt.	ng L	-	2 6
Course Lea	arning Outcomes (CLO	At the e	nd of this course, learners	s will be able to	D.:			Level	Expect	Expected	Engineering	Problem	Design	Analysis,	. Modem	Society	Environ	Ethics	Individual	Communication	Project	Life Long		PSO -
CLO-1:	Apply the concepts of A	Artificial neural netv	vork					1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-2:	Implement the algorithm	n of various ANN						1, 2	80	70	М	-	-	-	-	-	-	-	-	-	-	-	М	
CLO-3:	Apply the concepts of I	Neural network bas	ed on competition					2	80	70	-	М	-	-	-	-	-	-	-	-	-	-	М	-
CLO-4:	Outline the concepts of	genetic algorithm						1	80	70	-	-	Н	-	-	-	-	-	-	-	-	М		М -
CLO-5 :	Describe the genetic al	gorithm operators						1	80	70	-	-	-	-	-	-	-	-	-	-	-	М	-	
CLO-6:	Implement the concept	s of ANN for Biome	edical applications					1,2	80	70	-	-	-	-	-	-	-	-	-	-	-	L	-	

Duratio	on (hour)	Artificial neural network: An Overview	Artificial Neural network model	Neural network based on competition	Introduction to Genetic Algorithm	GA Operators and Biomedical Applications
Duratio	ii (iioui)	9	9	9	9	9
S-1	SLO-1	Basics of Artificial Neural network	Feed forward networks	Kohonen SOM : Architecture	Biological Background	Genetic operators:
3-1	SLO-2	Basics of Artificial Neural network	Feed forward networks	Algorithm	Genetic algorithm world	Reproduction, Crossover
S-2	SLO-1	Biological neuron, Properties	Back propagation network- structure	Learning vector Quantization(LVQ) : Architecture	Evolution and optimization	Mutation, Replacement
3-2	SLO-2	Artificial model	Algorithm, Applications	Algorithm	Evolution and Genetic algorithm	Fitness form
	SLO-1	Network parameters: Weight, activation, threshold	Tutorial: BPN	Max net: Architecture	Gradient based local optimization method	Scaling
S-3	SLO-2	Typical architecture: Single layer net, Multilayer net, competitive layer	Tutorial: BPN	Application procedure	Gradient based local optimization method	Population
S-4	SLO-1	Common activation function	Associative memory: Heteroassociative memory: Architecture	Mexican Hat: Architecture	Random search	Data structure
5-4	SLO-2	Common activation function	Applications	Training algorithm	Stochastic Hill climbing	Encoding: Binary , Octal,
S-5	SLO-1	McCULLOCH-PITTS net: Architecture	Associative memory:Autoassociative Net: Architecture	Hamming net : Architecture	Simulated anneling	Encoding: Hexadecimal

	SLO-2	Algorithm	Algorithm, Applications	Application procedure	Simple genetic algorithm	Encoding: Permutation
	SLO-1	HEBB net: Architecture	Hopfield network:Architecture,Algorithm	ART Fundamentals	Simple genetic algorithm	Encoding: Value and Tree
S-6	SLO-2	HEBB net: Algorithm	Tutorials	ART: Basic architecture	Comparison of Genetic algorithm with other optimization techniques	ECG signal classification using neural network
S-7	SLO-1	Perceptron: Architecture	Hopfield -travelling salesmanproblem	Learning in ART	Genetic algorithm at work simulation by hands	ECG signal classification using neural network
5 -7	SLO-2	Perceptron: Algorithm	Boltzman machine	Visualization in U matrix	Genetic algorithm at work simulation by hands	ECG signal classification using neural network
	SLO-1	Delta rule	Issue in network design	Basics of SVM	Data structures	EMG pattern recognition
S-8	SLO-2	Tutorial	Radial Basis function	Basics of SVM	Data structures	EMG pattern recognition
	SLO-1	Tutorial	Matlab programing	Tutorial	Application of Genetic algorithm	Breast cancer detection
S-9	SLO-2	Tutorial	Matlab programing	Tutorial	Advantages and limitation of Genetic algorithm	Breast cancer detection

		T. Learning asset, 1 and american of Neural Networks. Architectures, Algorithms, and Applications, 1 carson
		Education India, 3rd edition, 2008.
	Learning	2. Mohamad H. Hassoun, "Fundamentals of Artificial Neural Network", Cambridge, The MIT Press,
- 1	Resources	1stedition, 1995
	Resources	3. B. Yegnanarayana, "Artificial Neural Networks", Prentice Hall of India, 3rd edition,2006.
		4 S. N. Sivanandam, S. N Deepa, "Introduction to Neural Networks Using Matlab 6.0", Tata McGrawHill, 2006.

1 Laurene Fausett "Fundamentals of Neural Networks: Architectures Algorithms and Annications" Pearson

5.James A Freeman and David M.Skapra, "Neural Network", Addison – Wesley, India, Third edition, 2008 6.Robert J Schalkoff, "Artificial Neural Networks", McGraw Hill, Third edition, 2011.

7. David Goldberg, Genetic Algorithms in Search, Optimization and Machine Learning", Pearson Education, Fourth edition, 2009.

8. Melanie Mitchell, An Introduction to Genetic Algorithms" Prentice Hall of India, New Delhi, First edition, 1998

Learning Asse	ssment										
_	5			С	ontinuous Learning Ass	essment (50% weighta	ge)			F: 15 1 1 (500)	
	Bloom's Level	CLA - 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Final Examination (50% weightage)	
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
	Remember	40.04		40.04		40.04		22.01		2001	
_evel 1	Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
1.0	Apply	40.07		40.07		40.07		40.07		4007	
evel 2	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
1.0	Evaluate	00.0/		00.0/		00.0/		00.0/		000/	
evel 3	Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	10	0 %	10	0 %	10	0 %	10	0 %	10	00 %

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Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. Rajalakshmi T, SRMIST

Code 18BME4051 Name WEARABLE STSTEMS AND MOBILE HEALTH CARE Category E Professional Elective 3 0 0 3	Course	40DME 40ET	Course	WEARABLE SYSTEMS AND MOBILE HEALTH CARE	Course	_	Professional Elective	L	T	Р	С
		18BME465T	Name	MEAKABLE SYSTEMS AND MOBILE HEALTH CAKE		E		3	0	0	3

Pre-requisite Courses	Principles of Communication	Co-requisite Nil		Progressive Courses Nil
Course Offering De	partment Biomedical Engineering		Data Book / Codes/Standards	Nil

Course L	earning Rationale (CLR):	The purpose of the learning this course is to provide an overview of the technical background of wearable system and its application in health care using mobile technology	L	earniı	ng
CLR-1:	Comprehend technical info	rmation and challenges in WBAN.	1	2	3
CLR-2:	Describe the hardware requ	uirements of BAN			
CLR-3:	Review the wearable sensor	ors and standards for BAN	-	<u> </u>	
CLR-4:	Describe the mobile device	s that is available for health care	(Bloom)	cy (%	int (%)
CLR-5:	Summarize the possible an	d latest applications of mobile healthcare	Thinking (ficien	Attainment
CLR-6:	Learn about context-aware	health care applications	of Thin	Expected Proficiency (%)	
Course L	earning Outcomes (CLO):	At the end of this course, learns will be able to:	Level of	Expec	Expected
CLO-1:	List out the BAN challenge	DS CONTRACTOR OF THE PROPERTY	1	80%	
CLO-2:	Identify the hardware nece	essary for BAN	1	80%	75%
CLO-3:	List and describe the vario	nus wearable sensors	1,2	80%	75%
CLO-4:	Appreciate the mobile dev	ices available for healthcare	1.2	80%	75%
CLO-5:	List the latest applications	and research opportunities with mobile healthcare.	2	80%	75%
CLO-6:	Think about context-aware	health care solutions	3	80%	75%

				Progra	am Le	arning	Outc	omes	(PLO)					
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
	L													
L														
	L											L		
L														
													L	
														М

D	(1)	Basics of BAN	Hardware requirement for BAN	Wireless communication	Application of WBAN	WBAN application in healthcare
Duration (hour)		9	9	9	9	9
S-1 SLO-1 SLO-2		BAN-Definition	Processor in BAN	RF communication	Sensors for wearable system	Mobile health technologies
		Terminologies used with BAN	Low Power MCUs	RF communication in and around the body	Wearable system design for specific applications	Mobile nutrition tracking
S-2	SLO-1	Technical Challenges	Mobile Computing MCU	Antennal Design	Wearable system for ECG monitoring,	Accessing existing virtual electronic patientrecord
3-2	SLO-2	Sensor design concepts	Integrated processor	Antenna testing	Wearable system for EEG monitoring,	Mobile personal health records,
S-3	SLO-1	Types of sensors	Radio transceiver along with the processor	Propagation issues	Wearable system for Gait analysis	Monitoring hospital patients,
3-3	SLO-2	Biocompatibility issues	Integrated processor with Memory	Base Station considerations	Evaluation of general performance	Sensing vital signs
S-4	SLO-1	Energy Requirements	Antenna for BAN	Network topology	Evaluation of night time performance	Transmission using wireless networks
		Energy supply	Antenna Requirements	Stand – Alone BAN	Evaluation parameters	Continuous monitoring
S-5	SLO-1	Nodes, number of node	Antenna Considerations	Wireless personal Area Network	Latest health monitoring methods	Patient Monitoring and wearable devices

	SLO-2	Optimal node placement in BAN	Types of antenna	Wireless personal Area Network Technologies	Smart phone based health care monitoringsystem	Patient Monitoring in Diverse Environments
S-6	SLO-1	System security	Wire antenna	IEEE 802.15.1	Phone based fall risk prediction	A framework for Capturing Patient Consent in Pervasive Healthcare Applications
0-0	SLO-2	System Reliability	Ceramic antenna	IEEE P802.15.13	Emergency alerts	M-health application
	SLO-1	BAN Standards	External antenna	IEEE 702.15.14	RFID based personal mobile medicalassistance	Context aware sensing
S-7	S-7 SLO-2	BAN with other standards	Sensor Interface	Zigbee	Other similar technologies	Technology Enablers for context-Aware healthcare Applications
S-8	SLO-1	BAN Architecture	Considerations on the interface	BAN and WBAN technologies	Infusing image processing capabilities	8 channel ECG using Ultra wide band WBAN
5-8	SLO-2	BAN and other technologies	Power sources- Batteries	Limitations in use	Secure medical sensor network with HIP	Pulse generator using Ultra wide band WBAN
S-9	SLO-1	BAN and Healthcare	Fuel cells for sensor nodes.	Coexistence issues with BAN	Diagnostic applications	Multichannel neural recording system
3-9	SLO-2	Medical Applications of BAN	Other novel power sources	Other practical considerations	Therapeutic applications	Electronic pills

Learning Resources

- Annalisa Bonfiglio, Danilo De Rossi, "Wearable Monitoring Systems", Springer, 2011.
 Philip Olla, Josep Tan, "Mobile Health solutions for Biomedical applications", Medical Information science reference, Hershey New York, IGI Global 2009.
- 3. Zhang, Yuan-Ting, Wearable Medical Sensors and systems, Sringers, 2013.
- 4. Guang-Zhogn Yang(ED), "Body Sensor Networks", Springers, 2013

- 5. Mehmet R. Yuce Jamil Y.Khan, "Wireless Body Area Networks Technology, Implementation and applications", Pan Standford Pte. Ltd., Singapore, 2012
- 6. Konstantina, James C. Lin, Dimitrios, Maria Teresa, "Wireless mobile communication and healthcare", Secon International ICST conference, Mobihealth 2011, Springers 2011.
- 7. Ullah, Sana, Et at, "A review of wireless body area networks for medical applications", arXiv: 1001.083, 2010
- Patel, Shyamal, Et al, " A review of wearable sensors and systems with application in rehabilitation", Neuroeng Rehabil 9.12, 2012, 1-17.

Learning Asse	ssment										
	Dia amala i amal			Final Examination (50% weightage)							
	Bloom's Level of Thinking	CLA – 1	CLA - 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		(10%)#	- I mai Examination (50% weightage)	
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	_	30 %	_	30 %	-	30 %	_	30%	_
LEVEI I	Understand			30 70				30 70			
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate	20 %	_	30 %	_	30 %	_	30 %	_	30%	_
LGVGI J	Create	20 /0	_	30 /6		30 /8	_	50 /6	_	3078	
	Total	10	0 %	10	00 %	10	00 %	10	0 %	10	00 %

[#]CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Dr. Varshinin Karthik SRMIST
		2.Mrs. Laskhmi Prabha, SRMIST

Course Code	40DME 4CCT	Course Name	ARTIFICIAL INTELLIGENCE IN HEALTH CARE	Course Catemany	_	Professional Flective	L	Т	Р	С
Course Code	18BME466T	Course Name	ARTIFICIAL INTELLIGENCE IN HEALTH CARE Course Category	E	Professional Elective	3	0	0	3	
Dra raguisi			Co vermileite	Drawas			1			

Pre-requisite Courses	Nil	o-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Biomedical Eng	gineering	Data Book / Codes/Standards		Nil

Course Lea	rning Rationale (CLR):	The purpose of learning this course is to:			Learnir	g					Pro	gram L	.earning	Outco	omes (P	LO)					
CLR-1:	CLR-1: Understand the basics of Artificial Intelligence and its principles						1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Learn the algorithm of various sea	ch techniques			_												се				
CLR-3:	Become familiar with knowledge re				sucò	Jent					ge	•			_	_	Finan	ng			
CLR-4:	Explore the techniques of machine	learning applicable for healthcare		ıking	roficier	in in		alysis		ign,	Usa	ture	∞ √		eam	ation	& Fi	ij			
CLR-5:	Understand the use of machine lea			Ē	Po	Attainı	g e	na	ent	Jes 1	ool Us	Cul	ent 8 oility		~ ĭ	<u>ica</u>		Lea			
CLR-6:	Understand the role of artificial inte	lligence in healthcare		a T	eq	cted	ering edge	٦ ۲	∞હ	is, l	_	∞	nab		ष्ट	unic	Mgt.	В	_	2	က
				_ ō	ecte	l ō	Engine Knowle	Problem	sign	alys ses	Modern	ciety	Enviror Sustai	Ethics	출축	Ľ.	Project	2	Ċ	0	-
Course Lea	rning Outcomes (CLO):	At the end of this course, learners will be able to:		Leve (Blo	% % %	(%)	E S	Po	De G	Ans	Moc	Soc	Envir Susta	Eth	Individ	Ö	Pro	Life	PSO	PSO	PSO
CLO-1:	Demonstrate the basic principles	of Al towards problem solving		1, 2	80%	70%	М	-	-	-			-		-	-		-	-		-
CLO-2:	Explain the various search technic	ues in problem solving		2	80%	70%	М	-	-	-			-		-	-		-	-		-
CLO-3:	Describe the techniques in knowle			2	80%	70%	-	-	М		М		-		-	-		-	М		L
CLO-4:	Explain the role of machine learni			3	80%	70%	-	-			М		-		-	-	-	-	-		-
CLO-5:		earning in healthcare applications		3	80%	70%	М	-	-	-			-		-	-	-	-	М		L
CLO-6:	Use the AI algorithms for various	nealthcare applications to solve problems		3	80%	70%	М	-	-	-	-	-	-	-	-	-	-	-	-	-	-

		Principles of Artificial Intelligence	Search Techniques	Knowledge Representation	Machine learning in Healthcare	Machine learning – applications in healthcare
Duration	n (hour)	9	9	9	9	9
S-1	SLO-1	Al-introduction and definition	Informed search methods	First order logic-syntax and semantics	Data Preparation, Feature Cleaning	Healthcare Survey Dataset with Unsupervised Learning
3-1	SLO-2	Turing Test approach	Best first search-Greedy search	Symbols, terms, sentences	Feature Engineering, Feature Transformation	Feature selection using the Particle swam optimization
S-2	SLO-1	Intelligent agents	A* search-behavior	Quantifiers, equality	Feature Extraction, Feature Selection	Disease Detection System (DDS) UsingMachine Learning Technique
3-2	SLO-2	Structure of intelligent agents, Agentprograms, example	Complexity of A* search	Extensions	Machine learning models	System Implementation and Disease Detection Methodology
0.0	SLO-1	Simple reflex agents	Heuristic functions	notational variations	Machine learning categories	Architecture of DDS
S-3	SLO-2	Goal based agents	Heuristics for constraint satisfaction problem	Higher order logic, A-expression	Machine Learning Challenges	Use Case Diagram of DDS
S-4	SLO-1	Utility based agents	Iterative deepening A* search (IDA*)	Using first order logic-kinship domain	Machine Learning Tools	Accuracy Comparison of DDS with Previous Works
	SLO-2	Environment programs	Simplified Memory Bounded A* search	Axioms, definitions and theorems	Patient centric Machine learning model	Simulation for Result
S-5	SLO-1	Problem solving-problem solving agents	Hill-climbing search	Domain of sets	Pre-processing of data, Results and discussions	Deep learning solutions for skin cancer detection
3-3	SLO-2	Formulating problems,	Simulated annealing	special notations for sets, lists and arithmetic	Machine Learning Models to ClassifyHealthcare Data	Convolution neural network, methods, dataset
6.6	SLO-1	Well defined problems and solutions	Applications in constraint satisfactionproblems	Logical agents for Wumpus world	Exploratory Data Analysis	Data augmentation,
3-6		Example-Toy problems, travelling salesman problem	Knowledge and reasoning	Simple reflex agent-limitations	Machine learning techniques-supervised and unsupervised approaches	Network architecture, performance metrics

S-7	SLO-1	Searching solutions	Knowledge based agent	Representing change in the world-situation calculus	Natural language Processing	Security of Healthcare Systems with Smart Health Records Using Cloud Technology
	SLO-2	Data structures for search trees	Representation reasoning and logic	Frame problem and its relatives	Types of Unsupervised Learning	Cloud Computing in Healthcare
S-8	SLO-1	Search Strategies-breadth first, Uniform cost search	Semantics, Inference	Deducing hidden properties if the world	Clustering	Cloud Service Models
	SLO-2	Depth first search	Propositional logic	Preferences among actions, toward a global agent		Deployment Models in Cloud Computing
	SLO-1	Iterative search	Syntax, semantics	Knowledge engineering - introduction	K-Means Algorithm	Cloud Computing Security
S-9	SLO-2	Bidirectional search	Validity and inference	Knowledge engineering and programing	Density Based Clustering	Healthcare Data Security in the Cloud,sample algorithm

	Eugene Charniak, "Introduction to Artificial Intelligence", Pearson Education India, 1985 Stuart Jonathan Russell, Peter Norvig, Ernest Davis, "Artificial Intelligence: A Modern Approach, Prentice Hall series in artificial intelligence, Prentice Hall, 2010	 Bernard Nordlinger, Cédric Villani, Daniela Rus, "Healthcare and Artificial Intelligence", Springer Nature, 2020 Vishal Jain, Jyotir Moy Chatterjee "Machine Learning with Health Care Perspective: Machine Learning and Healthcare Volume 13 of Learning and Analytics in Intelligent Systems", Springer Nature, 2020
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Learning Asse	ssment											
	B1 1 1			С	ontinuous Learning Ass	essment (50% weighta	ge)			F: 15 : 0	(500/ 11/)	
	Bloom's Level	G A - 1 (10%)		CLA – 2 (15%)		CLA – 3	(15%)	CLA – 4	(10%)#	Final Examination	(50% weightage)	
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
evel 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
evel 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-	
evel 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Total 100		0 %	10	0 %	10	0 %	10	0 %	100 %		

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mrs.Bhargavi Haripriya, SRMIST

Course	400145 4077	Course		DIG WIGDINED DODGTIGG	C	ourse		_				D (··					L	Т	Р	С
Code	18BME467T	Name		BIO INSPIRED ROBOTICS	Ca	tegory	,	E		Professional Elective						3	0	0	3				
Pre-requisite Courses Course Offering Department Co-requisite Courses Nil							es	Nil															
Course Learning Rationale (CLR): The purpose of learning this course is to:						_earni	ng					Pr	ogram	Lear	ning (Outco	mes (PLO)					
CLR-1:	Understand the basic about	t bio inspired ro	bots		1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Get an idea about the musc	culoskeletal mo	vements									_			ty								
CLR-3:	Acquire an idea about the b	asic of postura	l balances			(%)	(%)		40			Research			Sustainability		~						
CLR-4:	Get an idea about assistive	and rehabilitat	ion robotics			5			adge		Jent	ese			itai.		Work		Finance				
CLR-5:	Get an idea about the stabil	lity analysis			9	ien e	me		owle	.82	ldol	c,	sage	<u>e</u>	Sus		Team \	Ę	-ina	ing			
CLR-6:	Get an overall idea about th	ne importance o	f Develop skills related to the des	ign, construction and testing of advanced robotic systems	— Single F	d Proficiency	d Attainment		Engineering Knowledge	Analysis	& Development	s, Design,	<u>⊢</u> •	S S C I	ment &		య	Communication	∞	g Learning			3
Course Le	earning Outcomes (CLO):	At the e	nd of this course, learners will be	able to:	ţo lava		Expected		Enginee	Problem	Design	Analysis,	Modern	Society	Environment	Ethics	Individual	Comm	Project Mgt.	Life Long	PS0 - 1	PS0 - 2	PS0 - (
CLO-1:	Apply the common troubleshooting procedures in Electronic Equipment and Outline the testing procedures of active and passive component				nents 1,		70		М	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2:					1,	2 80			М	-	-	-	-	-	-	-	-	-	-	-	М	-	-
CLO-3:					2		70		-	М		-	-	-	-	-	-	-	-	-	М		-
CLO-4:	1				1	80			-	-	Н	-	-	-	-	-	-	-	-	М	-	М	-
CLO-5:	• , ,				1	80	70		-	-	-	-	-	-	-	-	-	-	-	М	-	-	-
CLO-6:	: Outline the job opportunities in regulatory affairs in India				1,.	2 80	70		-	-	-	-	-	-	-	-	-	-	-	L	-	-	-

Duratio	n (hour)	Introduction to Bio Inspired Robots	A review of computational Musculoskeletal Analysis of Human Lower Extremities	Personalized Modeling for Home –Based Postural Balance Rehabilitation	Non Invasive brain machine interfaces for assistive and rehabilitation robotics	Psychological modeling of humans by assistive robots
		9	9	9	9	9
S-1	SLO-1	Introduction to Bio-inspired Robotics	Introduction to Musculoskeletal Analysis	Introduction	Introduction to brain machine interfaces	Introduction
3-1	SLO-2	Introduction to Bio-inspired Robotics	Introduction to Musculoskeletal Analysis	Introduction	Introduction to brain machine interfaces	Introduction
S-2	SLO-1	Principles of Biomechanics	Human walking Gait cycle	Home – Based postural balance rehabilitation	BMI for assistive robotics	Dimensions of Human characterization
3-2	SLO-2	Basic Features	Human walking Gait cycle	Home – Based postural balance rehabilitation	BMI for assistive robotics	Dimensions of Human characterization
S-3		What is a biologically Inspired Robotic System, and its advantages and disadvantages	Biomechanics of Normal human walking	Body segment parameters	BMI for rehabilitation robotics	Constructing behavioral models for HRI
	SLO-2	its advantages and disadvantages	Biomechanics of Normal human walking	Body segment parameters	BMI for rehabilitation robotics	Constructing behavioral models for HRI
S-4	SLO-1	Mobility systems Requirements	Quantitative Human Walking Models	Estimating center of mass position for human subjects	Kalman Filter Implementation	Economic decision-making models
3-4	SLO-2	Mobility systems Requirements	Quantitative Human Walking Models	Estimating center of mass position for human subjects	Kalman Filter Implementation	Economic decision-making models

S-5	SLO-1 legs	Computational Musculoskeletal AnalysisInteraction with articulated systems	Various Methods for balance rehabilitation	Challenges in exoskeleton design	Interfering psychological models
3-3	SLO-2 swimming	Computational Musculoskeletal AnalysisInteraction with articulated systems	Various Methods for balance rehabilitation	Challenges in exoskeleton design	Interfering psychological models
	SLO-1 flying system	EMG motion classification	Dynamic Model	Biomechanical modeling	Haptic stability
S-6	SLO-2 Sensors	EMG motion classification	Dynamic Model	Biomechanical modeling	Haptic stability
S-7	SLO-1 Characteristics of Sensors	Task modeling for human interfaces	Dynamic Optimization	Development of HRI model	Human operator Modeling
5-7	SLO-2 tactile,	Task modeling for human interfaces		Development of HRI model	Human operator Modeling
S-8	SLO-1 vision	An EMG –controlled Human Robot Interfaceusing Task modelling	Body motion sensing	Design examples	Haptic assist control
5-8	SLO-2 electronic nose	An EMG –controlled Human Robot Interfaceusing Task modelling	Body motion sensing	Design examples	Haptic assist control
	SLO-1 Evolution of Bio Inspired Robot	Modeling of joint stiffness	Strain-Sensitive conductive polymers	Stability analysis	System validation and experimental evaluation
S-9	SLO-2 Evolution of Bio Inspired Robot	Modeling of joint stiffness	Strain-Sensitive conductive polymers	Stability analysis	System validation and experimentalevaluation

	1. Biologically Inspired Robotics 1st Edition by Yunhui Liu (Editor), Dong Sun (Editor)	
Learning	2 Bio-Inspired Artificial Intelligence: Theories, Methods, and Technologies (Intelligent Robotics and Autonomous Agent	
Resource	series) by <u>Dario Floreano</u>	

Learning Asse	ssment												
	Dia anda Laval	Continuous Learning Assessment (50% weightage)											
	Bloom's Level	CLA – 1 (10%)		CLA – 2	(15%)	CLA - 3	(15%)	CLA – 4	(10%)#	Final Examination (50% weightage)			
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-		
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-		
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-		
	Total	10	0 %	10	0 %	10	0 %	10	0 %	100 %			

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. G.Anitha, SRMIST

Course Code	18BME468T	Course Name COMF		COMPUTATIONAL TOOLS IN BIOENGINEERING AND BIOMEDICINE		Cou Categ			Professional Elective	L 3	T 0	P 0	C 3	
Pre-requisite Courses				Co-requisite Courses	Nil		Progre Cou	essive rses	Nil			'		
Course Offering D	Department	Biomedic	al Engineering			Data Book / Codes/Standards	Nil							

Course Learning Rationale (CLR): The purpose of learning this course is to:	Learning					P	rogra	m Lea	arning	Outco	omes (PLO)					
CLR-1: Understand the basic concepts of computational tools in bioengineering and biomedicinie	1 2 3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Get an idea about the Concept of aortic dissection					ut								nce				
CLR-3: Acquire an idea about the Mechanistic approach to analysis antioxidant action	ncy				Ĕ.		ge				_		au	б			
CLR-4: Get an idea about the Radical adduct formation (RAF) mechanism	nking roficiency ttainment			nalysis	evelopment	gu'	Sa	nre	_		eam	ation	ᆵ	rning			
CLR-5: Acquire an idea about the coupling algorithms on cochlear mechanics	Prof Attal	,	D 40	a)	e S	esi	-	nltr.	± ₹		& Te		∞ŏ	ear			
CLR-6: Get an overall idea about the advanced computational approach			ğ	Ā	∞ .	., ² .	P	ø	ment a		_	Ē	Mgt.	g L			83
	om)	i co	<u>≸</u>	len	g	ysis eai	en	ety	ron tain	S	idu K	ommunic	roject	Lo	-	- 2	T I
Course Learning Outcomes (CLO): At the end of this course, learners will be able to:	Level (Bloor (%) (%) (%)	2	X S	Proble	Design	Anal	Mod	Society	Environ Sustain	Et	Individu: Work	Co	Proj	Life	PSC	PSO	PSO
CLO-1: Understand the need for computational tools in the field of bioengineering and biomedicine	1, 2 80 70		Н	-	-	-	-	-	-	-	-	-		М	-	-	-
CLO-2: Have a thorough understanding of basic equations of fluid flow and solid motion	1, 2 80 70		Н	-	-	-	-	Н	-	-	-	-		-	L	-	-
CLO-3: Understand the basics of antiradical mechanisms in the presence of different free radicals	2 80 70		-	L	-	-	-	Н	-	-	-	-		-	L		L
CLO-4: Identify the importance of radical adduct formation mechanism	1 80 70		Н	-		-	-	Н	-	-	-	-		-	-	М	-
CLO-5: Analyze the knowledge on the model of cochlea including feedforward and feedbackward forces	1 80 70		-	-	-	-	-	Н	-	-	-	-		-	-	-	-
CLO-6: Extend the basics of functional Spaces and functional inequalities	1,2 80 70		Н	-	-	-	-	-	-	-	-	-		М	-	-	-

Duratio	on (hour)	Need for computational tools	Computational approach in aortic dissection	Computational approach in antioxidative mechanisms	Computational approach in cochlear mechanics	Advanced computational approach
		9	9	9	9	9
S-1	SLO-1	Elements of computational tools	Diagnostic techniques of acute aortic dissection	Prevention of oxidative stress	Cochlear mechanics	Functional Spaces and Functional Inequalities
SLO-2		Elements of computational tools	Diagnostic techniques of acute aortic dissection	Prevention of oxidative stress	Concepts of modeling	Metric Spaces
0.0	SLO-1	Elements of mathematical modeling	Treatment of acute aortic dissection	Characteristics of good antioxidants	Concepts of modeling	Complete Metric Spaces
S-2	SLO-2	Elements of mathematical modeling	Treatment of acute aortic dissection	Characteristics of good antioxidants	Solid model	Normed Spaces
0.0	SLO-1	Elements of physics	Basic equations of fluid flow	The proposed reaction mechanisms	Solid model	Banach Spaces
S-3	SLO-2	The rational continuum mechanics approachto matter in motion	Basic equations of fluid flow	The proposed reaction mechanisms	Fluid model	Banach Spaces
0.4	SLO-1	Balance laws in integral form	Basic equations of solid motion	The proposed reaction mechanisms	Fluid model	Hilbert Spaces
S-4	SLO-2	Balance laws in integral form	Basic equations of solid motion	Mechanistic approach	Loose coupling algorithm	Hilbert Spaces
S-5	SLO-1	Balance laws in local form	Basic equations of solid motion	Mechanistic approach	Loose coupling algorithm	The Nonlinear Differential Model System
5-5	SLO-2	Balance laws in local form	Solid fluid interaction	Thermodynamical parameters for quercetinand gallic acid	Strong coupling algorithm	Time Semidiscretization

S-6	SLO-1	Continuum approach for multicomponent mixtures	Solid fluid interaction	Thermodynamical parameters for quercetinand gallic acid	Strong coupling algorithm	Time Semidiscretization
3-0	SLO-2	Continuum approach for multicomponent mixtures	Concept of aortic dissection	Thermodynamical parameters for quercetinand gallic acid	Need for finite element modeling of cochlea	Time Semidiscretization
S-7	SLO-1	Continuum approach for multicomponent mixtures	Concept of aortic dissection		Basic criteria for finite element modeling of cochlea	Block Nonlinear Jacobi and Gauss-Seidel Iterations
5-7	SLO-2	Constitutive relations for fluids	Need for 3D reconstruction		Concept of finite element modeling of cochlea	Block Nonlinear Jacobi and Gauss-Seidel Iterations
S-8	SLO-1	Constitutive relations for solids		Mechanistic approach to analyze antioxidantaction		Block Nonlinear Jacobi and Gauss–Seidel Iterations
5-8	SLO-2	Constitutive relations for solids	Need for 3D reconstruction	Mechanistic approach to analyze antioxidantaction	Finite element models of cochlea	Application of Functional Iterations to Biological Models
0.0	SLO-1	Constitutive relations for multicomponent mixtures	Need for geometric 3D modeling		Model of cochlea including feedforward and feedbackward forces	Application of Functional Iterations to Biological Models
S-9	SLO-2	Constitutive relations for electromagnetismand electrodynamics	Need for geometric 3D modeling	Radical adduct formation (RAF) mechanism	Model of cochlea including feedforward and feedbackward forces	Application of Functional Iterations to Biological Models

Learning
Learning Resources
Resources

1.Nenad Filipovic, "Computational Modeling in Bioengineering and Bioinformatics", Academic Press, 1st Edition, 2019.
2.Z.C.Yang, "Finite Element Analysis for Biomedical Engineering Applications", CRC Press, 1st Edition, 2019 3.Butta Singh," Computational Tools and Techniques for Biomedical Signal Processing", IGI Global, 1st edition, 2016.

4. Andreas Öchsner, Holm Altenbach, "Applications of Computational Tools in Biosciences and Medical Engineering", Springer, 1st edition, 2015.
5. Geris, Liesbet, "Computational Modeling in Tissue Engineering", Springer, 1st edition, 2013.

Learning Asse	ssment												
	Dia anala i anal		Continuous Learning Assessment (50% weightage)										
	Bloom's Level	CLA – 1	(10%)	CLA – 2	(15%)	CLA – 3	(15%)	CLA – 4 ((10%)#	Final Examination (50% weightage)		
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-		
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-		
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-		
	Total	10	0 %	10	0 %	10	0 %	10	0 %	100 %			

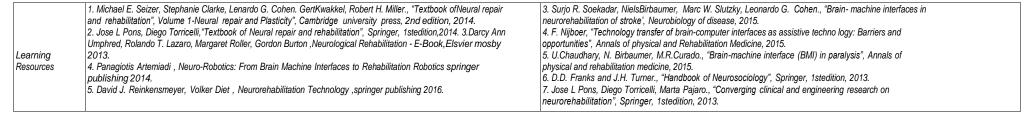
[#]CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers											
Experts from Industry Experts from Higher Technical Institutions Internal Experts											
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mr.P. Muthu, SRMIST									

Course 18	BME469T Cours		O REHABILITATION	I AND HUMAN MACHINE IN	ITERFACE		urse egory	Ε		Professional Electiv					ective	/e L T 3 0					T 0	P 0	C 3
Pre-requisite Courses	Basic Electronic devices a		Co-requisite Courses	Nil		Cc	ressiv ourses		lil														
Course Offering Depart	ertment Bi	omedical Engineering		Data Book / Co	odes/Standards	Nil																	
Course Learning Rationale (CLR): The purpose of learning this course is to:									Learning Program Learning Outcomes (PLO)														
CLR-1:	,	of neurons with cellular and	l molecular mechani	sm		1	2	3		1 2	2 3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2: Analyze the plasticity of cerebral motor function CLR-3: Summarize the role of inflammatory response in central nervous system CLR-4: Illustrate the future perspective of human machine interface (HMI) CLR-5: Explain the motor recovery and compensation in neurorehabilitation								ment (%)		lowledge	& Development	. <u>c</u>	sage	ıre			Team Work	uc	Finance	guir			
	ding the usage of Human	machine Interface in transle	ational research			I _evel of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment		Engineering knowleage	Design & Deve	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	ndividual & Te	Communication	Project Mgt. &	ife Long Learning	0 - 1	0-2	0 – 3
1	` ,	ar mechanisms of neural pla				<u>9</u> 1, 2	80 EX	<u>益</u> 70				Ang	8 €	Š.	БS	<u></u>	pu •	<u>දි</u>	- P	Ĕ	PSO .	PSO .	PSO
		in the Central Nervous Sysi				1, 2	80	70	-	1 1	"	-	-	-	-	-	-	-		_	М		÷
		,	lem						_			-	-			-							÷
	e Regeneration in the Injury		M/)			2	80	70 70		1 -			-	-	-	-	-	-	-	- Н	М	М	<u>.</u>
CLO-5: Application of Human machine interface in translational research								70		1	-	-	-	-	-	-	-	-	-	M H	М	-	-
CLO-6: Understar	iuing the usage and desig	ırı development ol Hivil lor i	esearur			1,2	80	70		1 .	· IVI	М	-	-	-	-	-		-	П	Н	-	-
Duration (hour)	·	Cellular and Molecular anisms		ity in the Central Nervous System	Determination of Regenerat Nervous System		he Inju	ıred	Am		•	nce and g Scena	d Ubiqu ario	itous	1	Transl	ationa			Applicaterface		in Hu	nan
	9 9								9 9														
	1																						

Durat	ion (hour)	Neural Plasticity: Cellular and Molecular Mechanisms	Functional Plasticity in the Central Nervous System	Determination of Regeneration in the Injured Nervous System	Ambient Intelligence and Ubiquitous Computing Scenario	Translational Research: Application in Human Machine Interface
		9	9	9	9	9
S-1 =	SLO-1	Learning and memory: basic principles andmodel systems	Plasticity of mature and developing somatosensory systems	Non-mammalian models of nerve regeneration	The advanced human machine interface(HMI) framework	Application uses in robotics
3-1	SLO-2	Learning and memory: basic principles andmodel systems	Plasticity of mature and developing somatosensory systems	Non-mammalian models of nerve regeneration	The advanced human machine interface(HMI) framework	Application uses in robotics
S-2 -	SLO-1	Cellular and molecular mechanisms of associative and nonassociative learning	Activity-dependent plasticity in the intactspinal cord	Myelin-associated axon growth inhibitors, Inhibitors of axonal regeneration	The advanced human machine interface(HMI) framework	Robotics and wearable technology for measurement
3-2	SLO-2	Cellular and molecular mechanisms of associative and nonassociative learning	Activity-dependent plasticity in the intactspinal cord	Myelin-associated axon growth inhibitors, Inhibitors of axonal regeneration	The advanced human machine interface(HMI) framework	Robotics and wearable technology for measurement
	SLO-1	Degenerative changes and reactive growth responses of neurons following denervation and axotomy	Plasticity of cerebral motor functions: Implications for repairand rehabilitation	Role of the inflammatory response in central nervous system injury and regeneration	Human machine interface systems – structure, protocols,	Clinical application of robotics and technologyin restoration of walking

S-3	SLO-2	Degenerative changes and reactive growth responses of neurons following denervation and axotomy	Plasticity of cerebral motor functions: Implications for repairand rehabilitation	Role of the inflammatory response in central nervous system injury and regeneration	Human machine interface systems – structure, protocols	Clinical application of robotics and technologyin restoration of walking
S-4	SLO-1	Contemporary issue and theories of motorcontrol learning.	Plasticity of cerebral motor functions: Implications for repairand rehabilitation	Role of the inflammatory response in central nervous system injury and regeneration	Human machine interface systems –applications	Clinical application of robotics and technologyin children undergoing neurorehablitation
S-4	SLO-2	Contemporary issue and theories of motorcontrol learning.	Plasticity of cerebral motor functions: Implications for repairand rehabilitation	Role of the inflammatory response in central nervous system injury and regeneration	Human machine interface systems –applications	Clinical application of robotics and technologyin children undergoing neurorehablitation
	SLO-1	Limbic system influence over motor controland learning	Plasticity in visual connection retinal ganglion cell axonal development andregeneration	Sensor-motor interaction and erroraugumentation	Human machine interface systems –applications	Clinical application of robotics and technologyin children undergoing neurorehablitation
S-5	SLO-2	Limbic system influence over motor controland learning	Plasticity in visual connection retinal ganglion cell axonal development and regeneration	Sensor-motor interaction and erroraugumentation	. The next-generation advanced HMI 2	Biomimetic design of neural prosthesisBrain responses to neural prosthesis
0.0	SLO-1	Learning of damaged brain/spinal cord neuroplasticity	Plasticity in auditory function cross model plasticity in visual system	Limbic system influence on motor control and learning	The next-generation advanced HMI 2	Biomimetic design of neural prosthesisBrain responses to neural prosthesis
S-6	SLO-2	Learning of damaged brain/spinal cord neuroplasticity	Plasticity in auditory function cross model plasticity in visual system	Limbic system influence on motor control and learning	The next-generation advanced HMI 2	Biomimetic design of neural prosthesisBrain responses to neural prosthesis
	SLO-1	Movement neuroscience foundation of neurorehabilitation	Plasticity in auditory function cross model plasticity in visual system	Normal and impaired cooperative handmovement role of neural coupling	A future perspective for next-generation HMI: fNIRS-EEG	Intracranial human machine interfaces for communication and control
S-7	SLO-2	Movement neuroscience foundation of neurorehabilitation	Plasticity in auditory function cross model plasticity in visual system	Normal and impaired cooperative handmovement role of neural coupling	A future perspective for next-generation HMI: fNIRS-EEG	Intracranial human machine interfaces for communication and control
	SLO-1	Sensor-motor interaction and error Augumentation	Plasticity in auditory function	Physiological aspect of adaptation andadjustment during various phase of neurological Disablity	A future perspective for next-generation HMI: fNIRS-EEG	Intracranial human machine interfaces for communication and control
S-8	SLO-2	Sensor-motor interaction and error Augumentation	Plasticity in auditory function	Physiological aspect of adaptation and adjustment during various phase of neurological Disablity	A future perspective for next-generation HMI: fNIRS-EEG	Understanding motor recovery and compensation in neurorehabilitation
	SLO-1	Physiological aspect of adaptation andadjustment during various phase of neurological Disablity	Plasticity in auditory function	Multisystem neurorehablitation in rodents w ith spinal cord injury	Multi-Modal HMI.	Understanding motor recovery and compensation in neurorehabilitation
S-9	SLO-2	Physiological aspect of adaptation andadjustment during various phase of neurological Disablity	Plasticity in auditory function	Multisystem neurorehablitation in rodents with	Multi-Modal HMI.	Understanding motor recovery and compensation in neurorehabilitation



Learning Asse	ssment											
	Bloom's Level	Bloom's Level Continuous Learning Assessment (50% weightage)										
	of Thinking	CLA – 1	(10%)	CLA – 2 (15%)	CLA – 3 ((15%)	CLA – 4 (1	0%)#	,	-	
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	40 %	-	40 %	-	40 %	-	30 %	-	30%	-	
	Understand											
evel 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%		
	Analyze											
evel 3	Evaluate	20 %	-	20 %	-	20 %	-	30 %	-	30%	-	
	Create											
	Total	100	%	100	0 %	100	0 %	100	%	100	%	

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Course		Course					Cours	20													L	Т	Р	С
Code	18BME470T	Name		ASSISTIVE A	ND AUGMENTATIVE TECHNOLOGIES	-	atego		Ε		Professional Elective			tive					3	0	0	3		
Pre-requ Cours Course Off		Biomedia		-requisite Courses	Nil Data Book / Codes/Standards		rogre Coui	ssive 'ses	Nil															
Course Lea	arning Rationale (CLR):	The purp	oose of learning this cours	se is to:			Lea	rning					ı	Program	m Lea	rning	Outco	mes (PLO)					_
CLR-1:	Understand the fundamenta	als of assistive te	echnology tools in various	disabilities		1	2	? 3	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Use the universal principles	s and human fact	nmunication and assistive technology																					
CLR-3:	Utilize the idea about the lo	w and high techr	nology tools for various di	isabilities					_				ıch			bility								
CLR-4:	Study the assistive technology	ogy tools for dear	fness and hearing impair	ments		(Bloom)	è	(%)	Audillielli (70)	Knowledge		ent	esearch			Sustainability		Work		oce				
CLR-5:	Study the assistive technology	ogy tools for visu	ial and dual sensory impa	nirments		B			D E	owle	.si	lopm	∝	Usage	<u>e</u>	Sus		Team V	uc	Finance	ing			
CLR-6:	Get an overall idea about th	he various assisti	ive technology tools for m	nobility, seating a	and daily living	Thinking	3	Proliciency (la l	g K	Analysis	Development	Design,	Tool U	Culture	ıt S		& Tea	catic	∞ŏ	Learning			
1							7			erin	ш Ч	∞ర	is, [n To	∞ŏ	nme		nal	nuni	t Mgt.	Long l	_	2	ď
Course Le	arning Outcomes (CLO):	At the en	nd of this course, learners	will be able to:		Level		Lxpected	Lypecied	Engineering I	Problem	Design	Analysis,	Modern	Society	Environment	Ethics	Individual	Communication	Project	Life Lc	PSO -	PSO -	PSO -
CLO-1:	Apply the universal princip					1, 2		0 7	0	М	-	-	-	-	-	-	-	-	-	-		L-	L	М
CLO-2:	Identify the basic principles and human factors for person with disabilities					1, 2	2 8	0 7	0	М	-	-	-	-	-	-	-	-	-	-	-	L		-
CLO-3:	, , ,				S	1,2	2 8	0 7	0	-	М	-	-	-	-	-	-	-	-	-	-	L	L	-
CLO-4:	Analyze the assistive technology tools and its usage in hearing impairments persons				S	2,3	3 8	0 7	0	М	L	L	-	-	-	-	-	-	-	-	М	-	L	Μ
CLO-5:	Analyze the assistive technology tools and its usage in visual and sensory impairments persons					2,3	3 8	0 7	0	М	L	L	-	-	-	-	-			-	М	-	L	М
CLO-6:	Identify the basic assistive	tify the basic assistive technology tools for activities of daily living						0 7	0	-	М	М	L	-	-	-	-	-	-	-	L	-	L	Μ

Durati	on (hour)	Universal Principles and Human factors	Assistive Technology for Communication, Deafness and hearing impairments	Assistive Technology for Visual and Dual sensory impairments and daily living	Augmentative Technology for Prosthetic and Orthopedics	Technology for mobility, seating and
		9	9	9	9	9
S-1	SLO-1	Augmentative and alternative communication (AAC) and Assitive technology (AT) software	Hearing functional assessment	Anatomy of eye, Image formations in eye	Anatomy of upper & lower extremities	Basic assessment and evaluation for mobility
3-1	SLO-2	Evaluation of AAC and AT software	Surgical and non surgical hearing aids	Categories of visual impairment	Classification of amputation types	Mobility devices
	SL0-1	Technical and user considerations	Devices to improve hearing	Artificial vision implants	Prosthesis prescription	Wheel chair :seating assessment
S-2	SLO-2	Quality resources on AAC and AT	Implants: Cochlear implant	Cortical and retinal implants	Hand and arm replacement	Interventions in seating system
	SLO-1	Evaluation of quality resources	Bone anchored hearing aids	External visual devices	I litterent types of models	Biological aspects of tissue health
S-3	SLO-2	Universal principles in AAC and AT	Assistive listening devices	Low and High technology to improve mobility	externally powered limb prosthesis	Support surface classification
S-4	SLO-1	Evidence based practice in AT	Electronic communication aids	Electronic Travel Aids(ETA)	Foot orthosis	Optimum seated posture
	SLO-2	Human factors in evaluation of AT	Analog and digital recorders	Low and High technology for reading and writing	Pediatric orthoses	Types of wheelchairs : Manual wheel chairs

	SLO-1	Environmental and social factors	Assistive listening devices	Auditory information display	Wrist-hand orthosis	Power wheelchairs
S-5	SLO-2	Psychological factors influencing the use of technology	Devices to improve communication	AT for dual sensory impairments	feedback in orthotic system	Power assisted wheelchairs
•	SLO-1	Various Physiological influencing factors	Design constraints in designing Adapted mouse	AT for leisure and recreation	Components of upper limb prosthesis	Control systems, navigation in virtual space by wheelchairs
S-6	SLO-2	Sensory and Motor factors	Smart pen- technology	Activities of daily living (ADL)	Components of lower limb prosthesis	Control systems, navigation in virtual space by wheelchairs
	SLO-1	ow technology :Communication displays Keyboard variations for differently abled		Daily living aids	Lower extremity- and upper extremity-orthoses	EOG based voice controlled wheelchair
S-7	SLO-2	Object communication displays, Communication Boards	Modifying existing technology	AT in Home	Intelligent prosthesis	BCI based wheelchair
	SLO-1	Principles of high technology assistive devices	Voice recognition and word prediction software	Technology for writing	functional electrical stimulation	Wheel chair standards & tests
S-8	SLO-2	Difference in high and medium technology	Communication devices	Alternative devices for safety	Electric Electronic Stimulation	Wheel chair standards & tests
	SLO-1	Picture exchange communication system	Smart phones, Cell phones and videophones	Orientation & navigation Aids	Fuzzy logic expert system for automatic tuningof myoelectric prostheses	Wheel chair transportation
S-9	SLO-2	Issues and considerations for low and hightech tools	Visual devices using sign	Alert systems	Fuzzy logic expert system for automatic tuningof myoelectric prostheses	Mobility device Accessories

Learning Resources

Oliver Wendt, Raymond W Quist, Lyle L Lloyd, "Assistive Technology: Principles and Applications for Communication Disorders and Special Education", Emerald group publishing Ltd, 1st Edition, 2011.
 Albert Cook, Janice Polgar, "Assistive Technologies -Principles and Practice", Mosby, 4th Edition, 2015.

Albert Cook, Janice Polgar, "Assistive Technologies -Principles and Practice", Mosby, 4th Edition, 2015.
 Rory A, Cooper, Hisaichi Ohnabe, Douglas A, Hodson, "An Introduction to Rehabilitation Engineering", CRC press,

Ist Edition, 2006.
4. Marion A Hersh, Michael A, Johnson, "Assistive Technology for Visually impaired and blind people", Springer, 1st Edition, 2008

5. Brownsell, Simon, et al.. A systematic review of lifestyle monitoring technologies, Journal of telemedicine and telecare 17.4 (2011): 185-189

6. Marion. A. Hersh, Michael A. Johnson, Assistive Technology for visually impaired and blind, 1st ed., Springer Science & Business Media, 2010

7. Kenneth J. Turner, Advances in Home Care Technologies: Results of the match Project, 1st ed., Springer, 2011 8. Pascal Verdonck, Advances in Biomedical Engineering, 1st ed., Elsevier, 2009

Learning Ass	sessment										
	Bloom's Level		Final Examination (50% weightage)							
	of Thinking	CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3	(15%)	CLA – 4 (10%)#	,	5 5,
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	100 %				0 %	10	0 %	100 %		

[#] CLA - 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Course Code	18BME471T	Course Name	MACHINE LEARNING AND DEEP LEA	ARNING TECHNIQUES IN MEDICINE		ourse		Е				Profes	sional	Electiv	⁄e				3	T 0	P C 0 3
Pre-required Course Off	ses Neural Network	Data Book / Codes/Standards		gress ourse		Nil															
Course Offering Department Biomedical Engineering Data Book / Codes/Standards Course Learning Rationale (CLR): The purpose of learning this course is to:							ng					Progr	am Le	arning	g Outo	omes	(PLO)				
CLR-1 : CLR-2 :	Understand the applicati		earning and types of learning algorithms		1	2	3		1 2	3	4	5	6	7	8	9	10	11	12	13 1	4 15
CLR-3:	Gain knowledge in multi	ariate data handi			(Bloom)	(%) /	t (%)		dge	ent						Work		9			
CLR-4: CLR-5:	Learn about the clustering Know the techniques to		sess the learning algorithms		mg (B	Proficiency (Attainment (%)		nowle	els elopme	'n,	Isage	ure			Team M	o	Finance	Learning		
CLR-6:	Apply deep learning tech	niques in biomed	lical field		Thinking	d Prof			Ying K	& Development	, Design, ch	Tool L	& Culture	nent & ability		∞ర	ınicat	∞ŏ	g Lear		
Course Lea	arning Outcomes (CLO)	At the e	nd of this course, learners will be able to:		Level of	Expected F	% Expected		Engineering Knowledge	Design 8	Analysis, D. Research	Modern Tool Usage	Society	Environment & Sustainability	Ethics	Individual	Communication	Project Mgt.	Life Long		PSO - 2
CLO-1:	Explain what are the dit	erent types of lea	arning algorithm		1, 2	80			И -		-	-	-		-	-	-	-	-	-	
CLO-2:					1, 2	80	70		И -	-	-	-	-	-	-	-	-	-	-	M ·	
CLO-3:					2	80	70		- N		-	-	-	-		-	-	-	-	М	-
CLO-4:					1	80	70			Н	•	•	-	-	-	-	-	-	М	- /	Λ -
CLO-5:					1	80	70			-	-		-	-	-	-	-	-	М	-	
CLO-6:	O-6: Apply the machine and deep learning algorithms for concept related to image analysis				1,2	80	70			-	-	-	-	-	-	-	-	-	L	-	

		Machine Learning - Introduction	Parametric models and Multivariate Methods	Unsupervised learning	Machine learning Experiments	Deep learning Application
Duratio	on (hour)	9	9	9	9	9
S-1	SLO-1	Bayesian decision theory, Classification	Parametric Methods	Clustering	Design and Analysis of Machine Learning Experiments	Regularization, Normalizing inputs
	SLO-2	Bias and Variance	Maximum Likelihood Estimation	Mixture Densities	cost-sensitive learning	Weight Initialization for Deep Networks
0.0	SLO-1	Bayes' Estimator	Bernoulli Density	k-Means Clustering	Experiment	Numerical approximation of gradients
S-2	SLO-2	Losses and risks	Multinomial Density	vector quantization	strategies of experimentation	Gradient checking, Gradient Checking Implementation
0.0	SLO-1	Discriminant Functions	Parametric Classification-Regression	leader cluster algorithm	factorial design	Mini-batch gradient descent
S-3	SLO-2	Utility Theory	Bias/Variance	leader cluster algorithm	Response Surface Design	Exponentially weighted averages
S-4	SLO-1	Value of information	Model Selection Procedures	Expectation-Maximization Algorithm	Randomization, replication, blocking, pairing	Classical Supervised Tasks with Deep Learning
5-4	SLO-2	Bayesian networks	Validation techniques, Minimum lengthdescription, Bayesian model selection	Mixtures of Latent Variable Models	Guidelines for Machine Learning Experiments	Brain MRI Age Classification
٥.	SLO-1	Influence Diagrams	Multivariate Data	Supervised Learning after Clustering	Choice of Factors and Levels	Image Denoising
S-5	SLO-2	Association Rules	Parameter Estimation	Hierarchical Clustering	Choice of Experimental Design, Performingthe Experiment	Image Denoising

S-6	SLO-1	Machine learning applications-learning associations,	Estimation of Missing Values	Choosing the Number of Clusters	Statistical Analysis of the Data	Analysis of medical images
3-0	SLO-2	classification, regression,	Multivariate Normal Distribution	Nonparametric Methods	Cross-Validation and Resampling Methods	Analysis of medical images
0.7	SLO-1	unsupervised learning, reinforcement learning	Multivariate Methods- Multivariate Data	Instance-based memory-based learning	K-Fold Cross-Validation	Automatic Interpretation of Carotid Thickness
S-7	SLO-2	Supervised learning-examples	Parameter Estimation	Nonparametric Density Estimation	5x2 Cross-Validation	Automatic Interpretation of Carotid Thickness
C 0	SLO-1	Regression, Noise, learning multiple classes	Principal Components Analysis	Kernel Estimator	Bootstrapping	3-D Brain Tumor Segmentation
S-8	SLO-2	Probably Approximately Correct (PAC) learning	Eigen faces and Eigen digits	k-Nearest Neighbor Estimator	Measuring Classifier Performance	3-D Brain Tumor Segmentation
S-9	SLO-1	Vapnik-Chervonenkis (VC) dimension	reconstruction error, Karhunen-Lève expansion	Generalization to Multivariate Data	Interval Estimation	Convolutional NN for Real time 2D/3DRegistration
3-9	SLO-2	Exercises	Multidimensional scaling, Linear discriminant Analysis	Nonparametric Classification	Comparing Multiple Algorithms	Convolutional NN for Real time 2D/3DRegistration

	1.	Tony J. Cleophas and Aeilko H. Zwinderman, "Machine Learning in Medicine - a Complete Overview",
Laamaina		Springer,2015
Learning	2.	Sunila Gollapudi, S., "Practical Machine Learning", Packt Publishing Ltd.2016
Resources	2	Applied Doop Learning: A Cose Board Approach to Understanding Doop Neural Naturals By Umberta

4. Deep Learning for Medical Image Analysis, edited by S. Kevin Zhou, Hayit Greenspan, Dinggang Shen , Academia Press, 2017 5. Deep Learning, An MIT Press book, Ian Goodfellow and Yoshua Bengio and Aaron Courville

Sunila Gollapudi, S. , "Practical Machine Learning", Packt Publishing Ltd.2016 Applied Deep Learning: A Case-Based Approach to Understanding Deep Neural Networks, By Umberto http://www.deeplearningbook.org
6. Introduction to Deep Learning: From Logical Calculus to Artificial Intelligence, By Sandro Skansi, Springer, 2018 Michelucci, Delaware corporation, 2018

Learning Asse	essment					. (500)					
	Bloom's Level				ontinuous Learning Asso					Final Examination	(50% woightage)
		CLA – 1	(10%)	CLA – 2	(15%)	CLA – 3	(15%)	CLA – 4 (10%)#	i iliai Examination	(30 % Weightage)
	of Thinking	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Total	100 %		0 %	10	0 %	100	100 %		0 %	

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. Anbuselvan T, General Manager – Sales, Wipro GE Healthcare Pvt. Ltd., Tamil Nadu, Srilanka & Maldive	Dr. S. Poonguzhali, Professor, Centre for Medical Electronics, Anna University	1. Mrs. A Bhargavi Haripriya, SRMIST

Cauraa Cada	18BME472T	Course Norse	VIDTI	IAL DEALITY IN HEALTH CADE		Course Category				Е	Professional Elective				L	Т	Р	С				
Course Code	16BIVIE4721	Course Name	VIRTO	IAL REALITY IN HEALTH CARE					Course Category				E		Professional Elective				3	0	2	4
Pre-requisir Courses Course Offering	3	Nil	MII NII						gressiv Courses				Ni	1	Nil							
Course Learnin	g Rationale (CLR):	The purpose of	of learning this course is t	fo:		L	Learnin	q					Progra	am Leari	ing Ou	comes (I	PLO)					
	nderstand the sensors in vir	tual reality systems	- V		1	1	2	3	1	2	3	4	5	6	8	9	10	11	12	13	14	15
	nderstand the techniques in						_	+										Se				
	nderstand the techniques in		and viewing		_		Proficiency	nent		S			l ool Usage	d)		۶	_	Finance	р			
	ain knowledge in techniques				Thinking		je	Attainm		Analysis	it Sign.		n n	Culture ent &	>	Team	Communication	— ĕ	earning			
	ain knowledge in auditory a						P	Att	ge ge	∖na		- اے	<u> </u>	징불	<u></u>	∞ŏ	<u>8</u> .	±.				
CLR-6: Un	nderstand the various input	sensors, visual and a	uditory aspects of virtual	reality systems	_ t	Ê	Expected (%)	Expected (%)	Engineering Knowledge	Æ	% mdo	Research		∞ ⊭	nat	ndividual	Ę	Project Mgt.	Long	←	7	က
					<u></u>	(Bloom)) ec) oec	gine	Problem	Design Develop	Sec.	Modern	Society	Sustair	ndivid Nork	E	jeci	2	Ö	Ö	Ö
	g Outcomes (CLO):		of this course, learners	will be able to:	Le	(B	% <u>X</u>	% Ex	교조	Prc	De	Re	<u> </u>	So	S E	i Pu	ပိ	Pro	Life	PSO	PSO	PSO
	Explain the terms and the va		sed in VR		1,.		80%	70%	M	-		-	-	-	-	-	-	-	-	М		
	Analyze the visual aspects o				2		80%	70%	М	-		-	-	-	-	-	-	-	-	М		
	Demonstrate the various ted	, ,	,		2		80%	70%	М	-		-	-	-	-	-	-	-	-		L	
	Explain the various haptic se			·	2		80%	70%	М	-		-	-	-	-	-	-	-	-	М		
	xplore the various auditory				2	_	80%	70%	М	-		-	-	-	-	-	-	-	-	М		
CLO-6 : D	Describe and explain the val	rious components of V	/irtuality reality systems		2	2 8	80%	70%		L		-	-	-	-	-	-	-	-	М		

		Input Periphery	Visual Aspects- I	Visual Aspects - II	Haptic Aspects	Auditory Aspects and applications
Duration	n (hour)	9	9	9	9	9
	SLO-1	Definition of Virtual Reality (VR)	Computer graphics, building blocks	Light Sources and Reflection	Haptic sense and perception	Auditory Sense and Perception
S-1	SLO-2	Presence and Immersion, Need for training in medicine	Visual sense and perception	Point light, directional light, spot light	Tactile receptors,	interaural level differences
S-2	SLO-1	Principles of VR, Main components	Human eye, photoreceptors, color vision	Ambient light, diffuse reflection, specular reflection,	Kinesthetic receptors,	Design of Auditory Displays
	SLO-2	Problems in VR	RGB color space, liquid crystal display	Viewing projections	Psychophysics	Headphones
•	SLO-1	Human Actuators , Input Modalities	color spaces, subtractive model	Image projection in the thin lens cameramodel	Haptic Display Technology	Mono, Stereo, and Surround Loudspeaker Systems
S-3	SLO-2	Position and movement recording	HSV color space	Depth of field in thin lens camera model	Kinematic principles, serial and parallel	Auditory Rendering
S-4	SLO-1	Resistive sensors, Capacitive sensors	Depth Perception, monocular cues	Projection in pinhole camera	Actuation principles	Olfactory and Gustatory Aspects
0-4	SLO-2	Inductive sensors, Ultrasound and opticalmethods	Oculomotor cues,	Early depiction of a Camera Obscura	Shape memory alloys	wearable olfactory display devices
	SLO-1	Position and movement measuring systems	binocular cues	Perspective projection	Electroactive Polymers	Gustatory Sense and Perception
S-5	SLO-2	Desktop systems, body mounted systems	Visual Display technology	2D mapping in the yz-plane	Piezoelectric Actuators	Virtual Reality for Rehabilitation
S-6	SLO-1	Contact free and remote systems	Stereoscopic rendering	Orthographic projection	Control Principles of Haptic Displays	Virtual Reality Supported Physiotherapy
0 0	SLO-2	Eye tracking systems	Display hardware	Orthographic projection onto image plane	Terminology	Gait Rehabilitation,

S-7	SLO-1	Force and torque recording	Virtual reality displays	Surface Shading	Admittance and Impedance Control Architectures	Robot-Assisted Gait Training	
3-7	SLO-2	Sound and speech recording	Cave Automatic Virtual Environment	Flat Shading	Stability, Passivity and safety of Haptic Displays	Motivation for Robot Aided Arm Therapy	
	SLO-1	Physiological data recording	Head mounted displays	Gouraud Shading	Ground- and Wall-Mounted Systems	Virtual Reality Applications with ARMin	
S-8	SLO-2	Bioelectrical signal	Rendering in computer graphics	Phong Shading	Tactile and Portable systems	Wheelchair Mobility and Functional ADLTraining	
S-9	SLO-1	Blood pressure measurements, pulse oximetry, skin conductance	Object representations	Advanced Rendering Techniques, RayTracing	Haptic Rendering	VR Based surgical simulator and itscomponents	
3-9	SLO-2	Respiratory measurements	Geometry transformations (basics)	Radiosity, Visual Displays in Medical VR	Penalty method, Haptic Displays in MedicalVR	VR for Surgical planning	

Learning Resources		Robert Riener, Matthias Harders, "Virutal Reality in Healthcare" Springer, 2012. Wadee Alhalabi "Virtual Reality Implementation in Healthcare Settings", Medical Information Science Reference, 2017	3. 4.	Lynne Edgar, "Virtual Reality: Future of Health Care" ,iUniverse, 2003. James Roland, "Virtual Reality and Medicine", ReferencePoint Press, Incorporated, 2018.	
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Learning Ass	essment											
	DI		Final Franciscotion	(F00/!= st====)								
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	Total 100 % 100 %		100 %				100 %					

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