

ACADEMIC CURRICULA

Professional Elective Courses

ELECTRICAL AND ELECTRONICS ENGINEERING

Regulations - 2018

Volume – 4 (6)

(Detailed Syllabus for Third & Fourth Year Courses)



SRM
INSTITUTE OF SCIENCE & TECHNOLOGY
(Deemed to be University u/s 3 of UGC Act, 1956)

SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18EEE301T	Course Name	OPTIMIZATION TECHNIQUES IN POWER ELECTRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Introduce and classify different conventional optimization techniques.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Understand the fundamentals of genetic algorithm and to apply appropriate algorithm for Power Electronic Applications.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Outline the concept of particle swarm optimization and apply it in Power Electronic applications.							H	-	-	-	-	-	-	-	-	-	-	-	-	-	H	H	-
CLR-4 :	Introduce other modern optimization algorithms for engineering applications.							H	H	H	H	-	-	-	-	-	-	-	-	-	-	H	H	-
CLR-5 :	Extend multi objective optimization techniques to Power Electronics							H	H	H	H	-	-	-	-	-	-	-	-	-	-	H	H	-
CLR-6 :	Introduce the concept of optimization design for Power Electronic Applications							H	H	H	H	-	-	-	-	-	-	-	-	-	-	H	H	-
								H	H	H	H	-	-	-	-	-	-	-	-	-	-	H	H	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Categorize optimization problems and its techniques based on constraints and variables				1	75	75																	
CLO-2 :	Correlate Genetic algorithm with various power electronic application.				2	75	75																	
CLO-3 :	Interpret Particle swarm optimization and develop hybrid algorithm for power electronic applications				3	75	75																	
CLO-4 :	Gain knowledge about other modern optimization algorithms and integrate them for power electronic applications				3	75	75																	
CLO-5 :	Formulate multi objective optimization algorithm for power electronic applications.				3	75	75																	
CLO-6 :	Apply optimization techniques in modelling Power Electronic applications				3	75	75																	

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to optimization Design vector – design constraints – constraint surface	Introduction – Genetic Algorithm Encoding – Methods for GA	Particle Swarm Optimization Fundamental principle	Bacterial foraging-Chemotaxis, Swarming Operation of Bacterial foraging	Multiobjective optimization Concept of pareto optimality
S-2	SLO-1 Objective function – objective function surfaces	Fitness function	Velocity updating in PSO -Algorithm	Bees colony algorithm-Behavior of Honey bee swarm	Classical Methods – Weighted sum method,
	SLO-2 Classification of optimization problem	Maximization & Minimization	Algorithm for PSO	Algorithm for Bee colony optimization	ε-constraint method
S-3	SLO-1 Single variable optimization - optimality conditions	Genetic operators	PSO – Parameter Selection	Differential evolution-Initialization, Mutation	Weighted metric methods,
	SLO-2 Single variable (unconstrained optimization) – Exhaustive search method	Crossover	Pseudocode	Recombination, Selection	Benson method.
S-4	SLO-1 Successive quadratic estimation method	Mutation	Implementation & Convergence issues in PSO	Ant colony optimization-Introduction	Multi objectiveGA
	SLO-2 Newton Raphson method	Parent Selection Roulette wheel selection	Advanced operators of PSO	Algorithm for Ant colony optimization	Fitness assignment
S-5	SLO-1 Multi variable optimization – optimality conditions (unconstrained)	Stochastic universal selection,	Meta-Optimization- Behavioral parameters	Cuckoo Search Optimization	Sharing function
	SLO-2 Simplex search method	Tournament selection	Algorithm for Meta-Optimization	Algorithm for Cuckoo search Optimization	Convergence criterion
S-6	SLO-1 Cauchy's method	Rank selection	Applications of PSO	Firefly optimization-Working Principle	NSGA-II
	SLO-2 Steepest descent method	Issues in GA implementation	Harmonics Elimination in Inverters	Algorithm for Firefly optimization	Convergence criterion
S-7	SLO-1 Multivariable optimization (Constrained) Kuhn – Tucker Conditions	Applications of GA	Applications of PSO	Flower Pollination optimization- Introduction	Applications: Design of AC – DC Grid connected converter using Multi objective optimization

	SLO-2	Penalty Function Method	Passive Filter design using GA	PSO for single phase PWM Inverters	Algorithm for Flower pollination optimization	Algorithm for Design of AC – DC Grid connected converter
S-8	SLO-1	Method of Multipliers	Parameter tuning of DC-DC converter using genetic algorithm	Control of Dc-DC converters using PSO	Grey Wolfe optimization-Introduction	Multi objective optimization of power converters (NSGA-II)
	SLO-2	Linearized search Technique – Frank Wolfe method	Tuning of PI Controllers for Power electronic converters	Feedback controller design for boost converters	Algorithm for Grey Wolfe Optimization	Algorithm for Multi objective optimization of power converters
S-9	SLO-1	Non-Linearized Search Technique – Reduced gradient method	MPPT in Renewable Energy systems	HybridofGAandPSO	Comparison of various algorithms	Multi objective optimization for design and tuning of PID controllers
	SLO-2	Quadraticprogramming	Genetic Algorithm for MPPT	Algorithm for hybrid GA and PSO for selective harmonic elimination in VSI fed drives	Benchmark functions	Algorithm for Multi objective optimization for design and tuning of PID controllers

Learning Resources	<ol style="list-style-type: none"> 1. Singiresu Rao S. <i>Engineering Optimization–Theory and Practice</i>, John Wiley & Sons, Inc., New Jersey, 2009. 2. Kalyanmoy Deb, <i>Multi-objective Optimization using Evolutionary Algorithms</i>, Wiley India Private Limited, 2010 3. Kalyanmoy Deb, <i>Optimization of Engineering Design</i>, Prentice Hall of India, second Edition, 2012. 4. Jizhong Zhou, <i>Optimization of Power System Operation</i>, IEEE Press, Second Edition, 2015. 5. Xin - She Yang, <i>Nature Inspired Optimization algorithms</i>, Elsevier, 2014. 6. Chee Peng Lim, Lakhmi C. Jain, Satchidananda Dehuri, <i>Innovations in Swarm Intelligence</i>, Springer, Berlin, Heidelberg, 2009. 7. Design of AC – DC Grid connected converter using Multi objective optimization, <i>Electrical Control & Communication Engineering</i>, 2014 8. https://engineering.purdue.edu/~sudhoff/ee630/Lecture09.pdf 9. https://link.springer.com/content/pdf/10.1007%2F978-3-540-74205-0_68.pdf
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr.S.Paramasivam, Danfoss, Industries Pvt Ltd, paramsathya@yahoo.com	Dr. R.Subha. Sir MVIT, subha.mvit@gmail.com	Mrs.Uthra.R, SRMIST
Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	Dr.C.Nayanatara, Sri Sairam Engineering College, nayanathara.eee@sairam.edu.in	Dr.D.Suchitra, SRMIST

Course Code	18EEE302T	Course Name	FINITE ELEMENT ANALYSIS FOR ELECTRICAL MACHINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)															
CLR-1 :		Illustrate the basic concepts of CAD and its design consideration					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :		Derive the output equation of DC and AC machines					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :		Compute the torque and force for rotating and linear actuators								H	M	M	-	-	-	-	-	-	-	-	-	-	H	M	-
CLR-4 :		Analyze the finite element method in solving electromagnetic field problem								H	H	M	M	-	-	-	-	-	-	-	-	-	H	M	-
CLR-5 :		Enumerate the design concept of CAD in mathematical modelling								H	M	H	M	-	-	-	-	-	-	-	-	-	H	H	-
CLR-6 :		Build the models of electrical machines								H	H	M	M	M	-	-	-	-	-	-	-	-	H	M	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:					1	75	75	2	75	75	3	75	75	3	75	75	3	75	75	3	75	75	
CLO-1 :		Understand the basic design of electrical machines and the need for CAD					1	75	75	2	75	75	3	75	75	3	75	75	3	75	75	3	75	75	
CLO-2 :		Make use of output equation for calculate main dimension of DC and AC machines					2	75	75	H	M	M	-	-	-	-	-	-	-	-	M	M	-		
CLO-3 :		Deduce the electromagnetic field equations for actuators					3	75	75	H	H	H	M	-	-	-	-	-	-	-	H	M	-		
CLO-4 :		Examine the mathematical and physical basis of finite element method					3	75	75	H	M	H	M	-	-	-	-	-	-	-	H	H	-		
CLO-5 :		Apply the design concept of CAD in mathematical modelling					3	75	75	H	H	M	M	M	-	-	-	-	-	-	H	M	-		
CLO-6 :		Develop the models of switched reluctance motor and rotating actuators					3	75	75	H	H	M	M	M	-	-	-	-	-	-	H	M	-		

Duration (hour)	9	9	9	9	9
S-1	SLO-1	CAD and its objectives	Maxwell's Equations	Finite element method	Organization of CAD package
	SLO-2	Conventional design procedure of machines	Integral form and differential form	Assumptions in FEM	Pre-processor
S-2	SLO-1	Output equation of DC machines.	Significance of field equations,	Electromagnetic field equations in Finite element	Solver
	SLO-2	Specific loading values for DC machines	Electromagnetic equation-integral and differential form	Finite difference method	Post-processor in CAD package
S-3	SLO-1	Output equation of AC machines	Magnetic vector potential	Finite difference method for calculation of magnetic field in a linear medium	Applications of finite element analysis
	SLO-2	Specific loading values for AC machines	Scalar potential form	Assumptions in linear medium	Considerations in problem modeling
S-4	SLO-1	Factors affecting the size of rotating machines	Energy stored in electromagnetic field	Finite difference method for calculation of magnetic field in a non-linear medium	Stator and rotor model
	SLO-2	Specific loadings and its dependent factors	Energy stored in current carrying coil	Assumptions in non-linear medium	Model replication and air gap discretisation
S-5	SLO-1	Variation of output and losses with dimension	Energy functional	Stiffness matrix	Post-processing of results-flux and flux linkage
	SLO-2	Separation of main dimensions	Assumptions in energy functional	FEM and FDM functions	Numerical and graphical results using processors
S-6	SLO-1	Limitations of conventional methods of design	Electromechanical energy conversion	FEM-mathematical basis	Analytical calculation

	SLO-2	Need for field analysis based design	Classification of electromechanical energy conversion	FEM- physical basis	Terminal inductance calculation.	Geometric modeling of C-core
S-7	SLO-1	Outline of finite element analysis	Force and torque calculation from energy	Energy functional	Co-energy calculation.	Design of doubly excited rotating actuator
	SLO-2	Necessity of FEA	Force and torque calculation from co-energy	Non-linear energy functional	Force and torque calculation	Design procedure and its assumptions
S-8	SLO-1	Computers in finite element analysis	Singly excited linear and rotating actuator	Discretization	Virtual work method	Design procedure of SRM
	SLO-2	Graphical users of FEA	Doubly excited rotating actuator	Shape function	Maxwell's stress tensor method	Geometric modeling
S-9	SLO-1	Engineering Optimisation	Force calculation on a current carrying conductor	Shape triangle calculation	Bil method	Material assigning
	SLO-2	Optimisation Methodology	Torque calculation on a current carrying conductor	Comparison of Finite difference and finite element method	Boundary conditions	Design of Switched reluctance motor by CAD package

Learning Resources	1. Silvester and Ferrari, <i>Finite Elements for Electrical Engineers</i> , Cambridge University press, 2012. 2. S.R.H. Hoole, <i>Computer - Aided, Analysis and Design of Electromagnetic Devices</i> , Elsevier, New York, Amsterdam, London, 1989. 3. S. Salon, <i>Finite Element Analysis of Electrical Machines</i> , Springer, 1995. 4. Nicola Bianchi, <i>Electrical Machine Analysis Using Finite Elements</i> , 1st Edition, CRC Press, 2005. 5. https://www.classcentral.com/course/edx--finite-element-method-fem-analysis-and-applications-4064
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Bhaskarsahu, Schneider Electric Ltd, Bhaskar.sahu@schneider-electric.com	1. Dr. K. S. Swarup, IITM, ksswarup@iitm.ac.in	1. Dr. M. Arun Noyal Doss, SRMIST
2. Mr. A.Kannan, Seshasayee paper and board limited akannan@sbppapers.com	2. Dr. R.Ramesh, CEG, rramesh@annauniv.edu	2. Dr. C. Subramani, SRMIST

Course Code	18EEE303T	Course Name	POWER CONVERTER ANALYSIS AND DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Enrich the knowledge on design aspects of phase controlled converters	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Standards & Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-2 :	Acquire knowledge in DC-DC converters and its performance				H	H	M	M	H	-	-	-	-	-	-	-	M	H	-			
CLR-3 :	Enrich the knowledge of flyback back converter and its design				H	H	M	M	H	-	-	-	-	-	-	-	M	H	-			
CLR-4 :	Acquire knowledge on the design techniques of the inverters				H	H	M	M	H	-	-	-	-	-	-	-	M	H	-			
CLR-5 :	Understand the concept of resonant converters and role of reactive elements in UPS				H	H	M	M	H	-	-	-	-	-	-	-	M	H	-			
CLR-6 :	Gain knowledge on power converter analysis and design				H	H	M	M	H	-	-	-	-	-	-	-	M	H	-			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Design single phase and three phase rectifiers	3	75	75																		
CLO-2 :	Understand the analysis and design aspects of DC-DC converters	3	75	75																		
CLO-3 :	Design flyback back converter and its various topologies	3	75	75																		
CLO-4 :	Design the inverter for various applications	3	75	75																		
CLO-5 :	Apply the knowledge on design concepts of resonant converters and UPS	3	75	75																		
CLO-6 :	Analyze and Design power converters	3	75	75																		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to single phase controlled converter (rectifier)	Introduction to isolated and non isolated DC-DC converters.	Introduction - Linear versus switch mode power supplies.	Introduction to inverters for single phase application	Introduction to resonant converters
	SLO-2	Working principle of single phase full converter	Principles of step down converters and step up converters	Functional circuit blocks of an offline switches	Introduction to inverters for three phase application	Classification of resonant converters
S-2	SLO-1	Analysis of single phase controlled rectifier for R load	Introduction to buck , boost converters	Classification of Basics switch mode DC-DC converters:	Selection of switching devices	Quasi resonant converters: Operating principle
	SLO-2	Analysis of single phase controlled rectifier for RLload and RLE load	Buck boost converters	Switch mode DC-DC converters: Operating principles	Introduction to IPM modules	Load resonant converters
S-3	SLO-1	Introduction to three phase controlled converters	Analysis of Buck converter	Flyback converters: operating principle	PWM techniques for inverter	Series Resonant switch converters
	SLO-2	Operation & principle of three phase controlled rectifier	Buck converter Design	Forward Converter: operating principle	Impact of PWM techniques on inverter performance	Parallel Resonant switch converters
S-4	SLO-1	Analysis of three phase controlled rectifier for R Load	Analysis of boost converter	Half-Bridge converters and, SMPS : Operating principle	Protection circuits for switches	Concept of Zero Voltage Switching
	SLO-2	Analysis of three phase controlled rectifier for RL Load	Boost converter design	Full Bridge Converters : operating principle	Snubber circuit design	Concept of Zero Current Switching
S-5	SLO-1	Selection of converter components for specified load	Analysis of buck-boost converter	Push-Pull Converter and its working	Thermal design considerations	Multi resonant converters
	SLO-2	Design of filter circuit for single phase controlled rectifier	Buck-Boost converter design	SMPS with multiple outputs	Heat sink design	Zero Voltage Transition converters
S-6	SLO-1	Design of filter circuit-three phase	Introduction to SEPIC converter	Magnetic design: Properties of magnetic	Multilevel Inverter(MLI) concept	UPS: offline UPS, Online UPS

		converter		cores		
	SLO-2	Importance of driver circuits	Introduction to CUK converter	High frequency inductor and transformer design	Classification of MLI	Filters: Voltage filters
S-7	SLO-1	Pulse generation circuits	Analysis of SEPIC converter	Selection of output filter capacitor	Design of MLI	Series-parallel resonant filters, filter without series capacitors,
	SLO-2	Design of driver circuits	Analysis of CUK converter	Selection of switches	Pulse Width Modulation for MLI	Current filter, DC filters
S-8	SLO-1	Power factor study – Improvement techniques	Thermal design: temperature control	Snubber circuit design	Influence of PWM on inverter performance	Design of inductor and transformé of power electronic applications
	SLO-2	Harmonic analysis study	Heat sink design	Design of driver circuits.	PWM for low inverter loss	Selection of capacitors.
S-9	SLO-1	Simulation of fully controlled converters	Simulation of basic DC- DC converters	Simulation of isolated dc dc converter	Simulation of a typical three phase inverter	Simulation of resonant and quasi resonant converter
	SLO-2	Demonstration of a fully controlled converter for R , RL loads	Demonstration of DC DC converters	Demonstration on Closed Loop Control of SMPS	Demonstration on a three phase inverter	Demonstration of resonant converters

Learning Resources	<ol style="list-style-type: none"> Robert W. Erickson and Dragan Maksimovic, Fundamentals of Power Electronics, 3rd Ed., Springer (India) Pvt. Ltd., 2011. Abraham I. Pressman, Keith Billings, and Taylor Morey, Switching Power Supply Design, 3rd Ed., McGraw-Hill Professional, 1 May 2009 Rashid M.H., Power Electronics Circuits, Devices and Applications, Prentice Hall India, Third Edition, New Delhi, 2004. V. Ramanarayanan, Switched Mode Power Conversion, 2007 	<ol style="list-style-type: none"> Umanand L and Bhatt S R, Design of Magnetic Components for Switched Mode Power Converters, Wiley Eastern Publication, 2009. Ned Mohan, Tore M. Undeland, William P. Robbins, Power Electronics Converters, Applications, and Design", 3rd Edition, Wiley India Pvt Ltd, 2010. Simon Ang, Alejandro Oliva, Power-Switching Converters, Second Edition, CRC Press, Taylor & Francis Group, 2010 https://nptel.ac.in/courses/108108036/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	1. Dr. Chandrasekaran Subramanian , NIT Hamirpur, chandru@nith.ac.in	1.Dr. R. Sridhar, SRMIST
2. Mr.J.Sassikumar, Philips India Pvt Ltd, sassikumar.jj@gmail.com	2.Dr.R.Ramesh, CEG, rramesh@annauniv.edu	2. Dr. K. Mohanraj, SRMIST

Course Code	18EEE304T	Course Name	SWITCHED MODE POWER CONVERSION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Review the basics of the power semiconductor devices and their requirements for the design of SMPC.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Explain the advantage of Switched mode Power supply over linear power Supply and the design of basic switched mode DC-DC converters.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Illustrate the need of derived / isolated converters and the working of various types of derived converters.																							
CLR-4 :	Introduce the control and compensating schemes for the design of SMPS and the procedure to be followed in the design of magnetic components.																							
CLR-5 :	Demonstrate the use of resonant converters to implement the Zero voltage and Zero current switching concepts.																							
CLR-6 :	Learn the basics and steady state operation of efficient switched mode power conversion and control techniques, including component design.																							
Course Learning Outcomes (CLO):					At the end of this course, learners will be able to:																			
CLO-1 :	Determine the selection criteria of power semiconductor devices, evaluation of losses and their basic heat sink design.				1	75	75	H	-	-	-	-	-	-	-	-	-	-	-	M	H	-		
CLO-2 :	Design the basic switched-mode converters for the given design specifications.				2	75	75	H	M	M	L	-	-	-	-	-	-	-	-	M	H	-		
CLO-3 :	Understand the steady state analysis and working of the Derived DC-DC isolated Converters.				2	75	75	H	M	M	L	-	-	-	-	-	M	-	-	M	H	-		
CLO-4 :	Analyze of Control and Compensating network for SMPS, design high frequency inductor and transformers to be used with SMPS.				3	75	75	H	M	M	L	-	-	-	-	-	M	-	-	M	H	-		
CLO-5 :	Analyze the working principle of resonant converters and understand the importance of Zero voltage and Zero current switching.				2	75	75	H	M	M	L	-	-	-	-	-	M	-	-	M	H	-		
CLO-6 :	Become proficient with the analysis and design of Switched-Mode Converters, including selection of components based on the specification.				2	75	75	H	M	M	L	-	-	-	-	-	M	-	-	M	H	-		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to switched mode power conversion	Basic concepts of Switched Mode power converters.	DC-DC converters with isolation.	Reactive elements in Power Electronic Systems	Basic resonant circuit concepts
	SLO-2	Industrial relevance of switched mode power conversion	Generalized comparison between switched mode and linear voltage regulator.	Requirement for isolation in the switch-mode converters	Design constraints of reactive elements in Power Electronic Systems	SMPS using resonant circuit
S-2	SLO-1	Requirements of power conversion system	DC-DC converters circuit elements, operating principles	Power circuit of flyback converters	Design of inductor, transformer and capacitors for power electronic applications	Resonant switch converters – Introduction
	SLO-2	Requirements of high performance modern power conversion system	DC-DC converters Characteristics	Steady-state analysis of flyback converters	Filter inductor design constraints, Transformer design constraints	Resonant switch converters – principle of operation
S-3	SLO-1	Review of power diodes, Schottky diodes, power MOSFETs & IGBTs	Operation and steady state performance of Buck Converter in continuous-conduction mode (CCM)	Power circuit of push-pull converters	Modeling of power converters	Buck converter with zero current switching
	SLO-2	Introduction to power semiconductor devices for SMPS	Buck converter - Discontinuous-conduction mode (DCM) and boundary between CCM and DCM operation	Steady-state analysis of push-pull converters	Generalized State Space Model of the switching power converter	Steady state conversion ratio – Buck converters
S-4	SLO-1	Recent developments in power devices	Operation and steady state performance of Boost Converter in continuous-	Power circuit of forward converters	Transfer Function of switching power converters	Boost converter with zero voltage switching

			conduction mode (CCM)			
	SLO-2	New devices: GaN & SiC for switch mode power supplies	Boost converter - Discontinuous-conduction mode (DCM) and boundary between CCM and DCM operation	Steady-state analysis of forward converters	EMI and filter design problem	Steady state conversion ratio – Boost converters
S-5	SLO-1	Gate drive basics	Operation and steady state performance of Buck - Boost Converter in continuous-conduction mode (CCM)	Power circuit and steady-state analysis of half-bridge DC-DC converters	Closed loop control of switching power converters	Series resonant DC-DC converters – principle
	SLO-2	Gate drive requirements	Buck - Boost Converter Discontinuous-mode (DCM) and boundary between CCM and DCM operation	Power circuit and steady-state analysis of full bridge DC-DC converters	Selection of controller parameters for converters	Series resonant DC-DC converters – Analysis and operation
S-6	SLO-1	Switching performance and snubber design	Operation and performance of Cuk Converters	Magnetic circuits in isolated topologies	Feedback compensators for converters	Parallel resonant DC-DC converters – principle
	SLO-2	Turn-on and Turn-off snubber	Operation and performance of SEPIC Converters	Utilization of Magnetic circuits in isolated topologies	Design of feedback compensators	Parallel resonant DC-DC converters – Analysis and operation
S-7	SLO-1	Selection of devices	Inductors current ripple design considerations	Comparison of different isolated topologies	Effect of parasitics on the switching converter design	Resonant DC link converters – principle
	SLO-2	Basic heat sink design for the devices	Output voltage ripple design considerations	Selection criteria of different isolated topologies	Stray inductance and inductive coupling effects	Resonant DC link converters – Analysis and operation
S-8	SLO-1	Sources of losses in SMPS	Effect of parasitic elements	Recent advancements of DC –DC converters (current mode, voltage mode)	Digital Control of power converter	Comparison of resonant converter configurations
	SLO-2	Conduction/Switching losses	Choice of switching frequency	Recent advancements of DC –DC converters (multiple output, high frequency output)	Quantization issues in digitally controlled power converters	Selection criteria of resonant converter configurations
S-9	SLO-1	Losses and efficiency in converters	Comparisons of DC –DC converter configurations	Applications of DC-DC converters	Practical issues in controller design	Applications of Resonant converters
	SLO-2	Realistic converter models	Selection criteria of DC –DC converter configurations	Seminar on Recent advancements and applications of DC –DC converters	Seminar on practical issues in controller design for power converters	Seminar on recent advancements and applications of Resonant converters
Learning Resources	<ol style="list-style-type: none"> 1. Ned Mohan, Tore M. Undeland, William P. Robbins, <i>Power Electronics Converters, Applications, and Design</i>, 3rd Edition, Wiley India Pvt Ltd, 2010. 2. Abraham I. Pressman, Keith Billings, and Taylor Morey, <i>Switching Power Supply Design</i>, 3rd Ed., McGraw-Hill Professional, 1 May 2009. 3. Umanand L and Bhatt S R, <i>Design of Magnetic Components for Switched Mode Power Converters</i>, Wiley Eastern Publication, 2009. 4. S.N.Singh, <i>Electric power generation, transmission and distribution</i>, 2nd ed., PHI, 2011 5. https://nptel.ac.in/courses/108108036/ 					

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Sairajagopal Chandramouli, Armstrong Fluid technology, Canada, bbalaji231@gmail.com	1. Dr B. Chitti Babu, IIITDM Kancheepuram, bcbabu@iiitdm.ac.in	1. Dr L.Padmavathi, SRMIST
2.Jidhun K Murali, Project Engineer, CDAC, Trivandrum, jidhunkm@gmail.com	2. Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	2.Dr R Sridhar, SRMIST

Course Code	18EEE305T	Course Name	DESIGN OF ELECTRICAL MACHINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC204J, 18EEEC205J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Enrich the students with basic principles and characteristics of various types of electrical machines.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Examine the design of armature and field systems for D.C. machines.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Outline the core, windings and cooling systems of transformers																					
CLR-4 :	Analyze the design of stator and rotor of induction machines																					
CLR-5 :	Understand the design of stator and rotor of synchronous machines and study their thermal behavior.																					
CLR-6 :	Understand the overall design of electrical machines																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Understand the mmf calculation and thermal rating of various types of electrical machines.				2	80	75	H	H	H	H	L	-	-	L	-	-	-	-	M	M	L
CLO-2 :	Design DC machine parts such as armature, field, commutator and brushes.				3	80	75	H	H	H	H	L	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Acquire knowledge on the design of transformers and its operating characteristics.				3	80	75	H	H	H	H	L	-	-	-	-	-	-	-	M	M	-
CLO-4 :	Interpret the induction motor stator and rotor design equations and magnetic leakage calculations.				3	80	75	H	H	H	M	L	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Design the components of synchronous motor				3	80	75	H	H	H	H	L	-	-	-	-	-	-	-	M	M	-
CLO-6 :	Design the components of DC and AC machines				3	80	75	H	H	H	H	L	-	-	L	-	-	-	-	M	M	L

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Major considerations, Design factors and limitations in machine design	Output Equation of DC machine	KVA output for single transformers	Output equation of three phase induction motor	Output equation of synchronous machine
	SLO-2	Limitations in machine design	Classification of magnetic materials	KVA output for three phase transformers	Main dimensions of induction motor	Main dimensions and pole constructions in synchronous machine
S-2	SLO-1	Electrical Engineering Materials introduction	Choice of Specific Electric Loading	Window space factor	Choice of Specific Electric Loading	Choice of Specific Electric and Magnetic Loading
	SLO-2	Electrical Engineering Materials classification	Choice of Specific Magnetic Loading	Core area factor	Choice of Specific Magnetic Loading	Influence of runaway speed
S-3	SLO-1	Magnetic Circuits Calculations	Problems with main dimensions	Design problems of core dimension for single phase transformer	Problems with main dimensions	Problems in main dimensions including runaway speed
	SLO-2	Problems under MMF Calculation	Problems with specific loading	Design problems of window dimension for single phase transformer	Problems with specific loading	Problems in main dimensions including pole constructions
S-4	SLO-1	Carter's Coefficient and net length of iron	Selection of number of poles	Design of core and winding	Influence of Length of air gap	Short Circuit Ratio (SCR) and Effect of SCR on machine performance
	SLO-2	Problems under net length of Iron	Design problems including pole design	Design problems in core and winding	Design problems including air gap length	Estimation of length of air gap
S-5	SLO-1	Real and Apparent flux densities	Armature Design procedure	Design of three phase transformer winding	Selecting rotor slots of squirrel cage machines	Problems in MMF
	SLO-2	Problems based on real and apparent flux densities	Problems in designing of armature	Problems on three phase transformer design	Design procedure of rotor bars, slots and end ring	Problems in SCR and air gap length
S-6	SLO-1	Temperature gradients in cores and conductors	Design of Commutator	Temperature rise in Transformers	Design procedure of slots	Armature design in synchronous machine

	SLO-2	Thermal resistivity of winding	Design of brushes	Transformer Tank design Procedure	Design procedure of end ring	Problems in armature design
S-7	SLO-1	Problems in temperature gradients	Problems in designing of commutator	Transformer Cooling tube design Procedure	Design problems in squirrel cage rotor	Procedure for Estimation of air gap length
	SLO-2	Problems in thermal resistivity	Problems in designing of brushes	Transformer Cooling tube design problems	Design procedure for wound rotor	Problems in air gap length
S-8	SLO-1	Indian Standard Specification for conductor, transformer	Computer Aided Design of DC machines – Main dimensions	Computer Aided Design of transformer-Core design	Computer Aided Design of three phase induction motor – Main dimension, stator design, squirrel cage rotor design	Overall design of stator
	SLO-2	International Electro- Technical commission Publications 34-1, 34-2	Computer Aided Design of DC machines –number of poles	Computer Aided Design of transformer-winding design	Computer Aided Design of three phase induction motor –squirrel cage rotor design	Overall design of rotor
S-9	SLO-1	Computer Aided Design introduction and uses	CAD – Armature design	CAD – Tank design	Design practices with software tools for stator design	CAD – Stator design
	SLO-2	Different approaches in Computer Aided Design	CAD – Field design	CAD – Cooling tube design	Design practices with software tools for rotor design	CAD – Rotor design

Learning Resources	<ol style="list-style-type: none"> 1. Sawhney, A.K., A Course in Electrical Machine Design, Dhanpat Rai & Sons, New Delhi, 1984. 2. Deshpande, M. V., Design and Testing of Electrical Machine Design, Wheeler Publications, 2010 3. Sen, S.K., Principles of Electrical Machine Designs with Computer Programmes, Oxford and IBH Publishing Co. Pvt. Ltd., New Delhi, 1987. 4. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-685-electric-machines-fall-2013/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr. A.Kannan, Seshasayee paper and board limited akannan@sbppapers.com	1. Dr.Chandramohan, CEG, Anna University. c_dramo@annauniv.edu	1. Dr. C. Subramani, SRMIST
2. Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	2. Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	2. Dr. Arun Noyal Doss, SRMIST

Course Code	18EEE306T	Course Name	SPECIAL ELECTRICAL MACHINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Acquire knowledge on Stepper motor and its characteristics				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the concepts of switched reluctance motor and its control.					Expected Proficiency (%)																	
CLR-3 :	Gain knowledge on Permanent magnet DC and BLDC Motors					Expected Attainment (%)																	
CLR-4 :	Analyze the working principle , operation and control of permanent magnet synchronous motor																						
CLR-5 :	Gain knowledge on the basics of various application based motors																						
CLR-6 :	Understand the overall concepts of various special electrical machines																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Analyze the working and control of Stepper moor				3	75	75	H	M	-	-	-	-	-	-	-	-	-	-	H	H	-	
CLO-2 :	Illustrate the operation and characteristics of SRM				2	75	75	H	-	-	-	-	-	-	-	-	-	-	-	L	L	-	
CLO-3 :	Interpret knowledge on PMDC and BLDC motors for real time applications.				2	75	75	H	-	-	-	-	-	-	-	-	-	-	-	L	L	-	
CLO-4 :	Evaluate the performance of PMSM				3	75	75	H	M	-	-	M	-	-	-	-	-	-	-	H	H	-	
CLO-5 :	Understand the characteristics of application based motors				2	75	75	H	-	-	-	-	-	-	-	-	-	-	-	L	L	-	
CLO-6 :	Summarize the characteristics of various special electrical machines.				2	75	75	H	M	-	-	M	-	-	-	-	-	-	-	M	M	-	

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Stepper motor	Introduction to Switched reluctance motor.	Construction of PMDC motor	Construction, and types of PMSM
	SLO-2	Variable reluctance motor-Construction-Single Stack	Elementary operation of SRM	Principle of Working PMDC motor	Operation of PMSM
S-2	SLO-1	Single Stack-Modes of Excitation-single phase	Machine topology	Moving Coil motors	EMF equation of PMSM
	SLO-2	Half Step On mode	Operation of Linear SRM	Printed coil motors	Torque equation of PMSM
S-3	SLO-1	Multi Stack Motor-Construction	Non Linear Analysis of SRM	Shell type motor	Voltage equation of PMSM
	SLO-2	Modes of Excitation	Torque Production -SRM	BRUSHLESS –Classification of BLDC motor	Phasor diagram
S-4	SLO-1	Hybrid stepper Motor-construction-working	Voltage and torque equation of SRM	Construction and operation of BLDC MOTOR	Performance Characteristics Characteristics of PMSM
	SLO-2	Types of Stepper motors-single phase stepper motor-Disc magnet type-Claw tooth stepper motor	Converter Circuit For SRM With Bifilar Winding	Equivalent Circuit And Torque Equation	Control of PMSM-Vector control
S-5	SLO-1	Torque Equation Of stepper Motor	Split Link Circuit -SRM	Performance Characteristics of BLDC motor	Self control of PMSM
	SLO-2	Windings in stepper motor-Unipolar and Bipolar winding	C- Dump Circuit-SRM	BRUSHLESS –Classification of BLDC motor	Microprocessor based control of PMSM
S-6	SLO-1	Static Characteristics of stepper Motor	Converter topology - N + 1, (N +1) diodes	Construction and operation of BLDC MOTOR	Sensorless control of PMSM

	SLO-2	Dynamic Characteristics of stepper Motor	Control Of SRM -Rotor Position Sensor-Optical Position	Electronic commutation -180° with magnetic arc and 120° with square wave phase currents -star connection	POWER controllers - PMSM	Control of Linear Induction Motor
S-7	SLO-1	Open loop Control of Stepper motors	Hall Effect Sensing	Electronic commutation -180° with square wave phase currents and 120° with magnetic arc -Delta connection	Operation of PMSM using DC-AC Converter with 120° Mode	Linear Reluctance motor- Construction
	SLO-2	Closed loop Control of Stepper motors	Current Regulators-Hysteresis	Control of BLDC motor	Operation of PMSM using DC-AC Converter with 180° Mode	Linear Reluctance motor – working Principle
S-8	SLO-1	Microprocessor –based control of stepper motor	Voltage –PWM type regulators	Microprocessor based control of BLDC motor	Modelling of PMSM Using simulator tool	Linear Reluctance motor Applications
	SLO-2	Problem Solving- torque- stepper motor	Microprocessor Based Control Of SRM	Comparison-Conventional and BLDC	Problem Solving - torque-PMSM	Ac Servo motors
S-9	SLO-1	Problem Solving- step angle-stepper motor	Advantages of SRM over other machines	Sensor -less Control of BLDC Motors	Problem Solving - speed- PMSM	Construction and Working
	SLO-2	Applications of Stepper Motors	Applications of SRM motors	Applications of BLDC Motors	Applications of PMSM	Torque speed characteristics of servomotor

Learning Resources	<ol style="list-style-type: none"> 1. T.J.E. Miller, Permanent Magnet and Reluctance Motor Drives, Clarendon Press, Oxford. 2. T. Kenjo, Stepping Motors and Their Microprocessor Controls, Clarendon Press London, 2000. 3. R.Krishnan, Switched Reluctance Motor Drives – Modeling, Simulation, Analysis, Design and Application, CRC Press, New York, 2005. 4. P.P. Acamley, Stepping Motors – A Guide to Motor Theory and Practice', Peter Perengrinus London, 4th edition 2001. 5. D.P.Kothari and I.J.Nagrath, Electric machines, Tata Mc Graw hill publishing company, New Delhi, Third Edition, 2004. 6. https://www.coursera.org/learn/motors-circuits-design
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. M.Jayakumar, Danfoss, Industries Pvt Ltd., jaya.kumar@danfoss.com	1. Dr Bindu G R, Government College of Engineering, Kerala, bgr100@gmail.com	1. Ms. S.Vijayalakshmi, SRMIST
2. Mr. A.Kannan, Seshasayee paper and board limited akannan@sbppapers.com	2. Dr.Booma.N, Jerusalem College of Engineering, Chennai, booma_nagarajan@yahoo.com	2. Dr.ArunNoyal Doss, SRMIST

Course Code	18EEE401T	Course Name	SOLID STATE DRIVES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the basics of electric drives			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Explain the working of converter/ chopper fed DC drives			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Design controllers for closed loop operation of DC motor drive						H	M	M	-	-	-	-	-	-	-	-	-	M	M	-
CLR-4 :	Acquire knowledge on operation and performance of induction motor drives						H	M	M	M	M	-	-	-	-	-	-	-	M	M	-
CLR-5 :	Enumerate the different control strategies of synchronous motor drive						H	M	M	M	-	-	-	-	-	-	-	-	M	M	-
CLR-6 :	Expose the students to various power converters associated with DC and AC drives						H	M	M	M	M	-	-	-	-	-	-	-	M	M	-
							H	M	M	M	M	-	-	-	-	-	-	-	M	M	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																				
CLO-1 :	Enrich the basics of electric drives, multi-quadrant operation			2	75	75															
CLO-2 :	Study and analyze the operation of four quadrant chopper / rectifier and solve simple problems			3	75	75															
CLO-3 :	Model closed loop DC motor drive and design the current and speed controllers			3	75	75															
CLO-4 :	Analyze the power electronic converter used for the speed control of induction motor drives			3	75	75															
CLO-5 :	Analyze the various control schemes for the speed control of synchronous motor drives			3	75	75															
CLO-6 :	Analyse the operation of DC and AC drives			3	75	75															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	ElectricDrives: Classification, advantages	Review of emf, torque and speed equations	Closed loop control of DC drive	Review of induction motor torque-speed characteristic
	SLO-2	Components of electric drive	Review of torque-speed characteristics of DC machine	Separately excited DC motor transfer function	Equivalent circuit of Induction motor
S-2	SLO-1	Thermal loading	Conventional speed control techniques	Modelling closed loop speed control of DC drive using armature voltage control	Conventional speed control techniques- Stator side control
	SLO-2	Thermal model of motor for heating and cooling	Armature and field side control	Block diagram of closed loop speed control of DC drive	Rotor side control
S-3	SLO-1	Classes of duty cycle	DC chopper control strategy	Modelling closed loop speed control with inner current controller(P)	Inverter control techniques: three-phase PWM generation
	SLO-2	Determination of motor rating – Continuous and intermittent duty	Constant and variable frequency control strategies	Block diagram of closed loop speed control with inner current controller(P)	Sinusoidal modulation
S-4	SLO-1	Simple problems on power rating estimation with Continuous and intermittent duty	Chopper fed dc motor for speed control- One, two quadrant operation	Modelling closed loop speed control with inner current controller(PI)	Introduction to vector control
	SLO-2	Determination of motor rating – short time duty	Chopper fed dc motor for speed control- four quadrant operation	Block diagram of closed loop speed control with inner current controller(PI)	Vector control of Induction motor drives
S-5	SLO-1	Determination of motor rating – intermittent periodic duty	Harmonics and ripple in motor current	Modelling closed loop speed control of DC drive with load torque disturbance	Conventional space vector modulation.
	SLO-2	Frequency of operation subjected to intermittent loads	Effect on motor performance	Block diagram of closed loop speed control of DC drive with load torque	SVPWM for three phase VSI

				disturbance		
S-6	SLO-1	Equations governing motor load dynamics	Single phase full converter fed separately excited DC motor	Modelling DC series motor	Introduction to FPGA	Recap of single and three phase cycloconverters
	SLO-2	Steady state stability at various operating points on Speed –Torque curve	Steady state analysis of the drive–continuous conduction	Block diagram of DC series motor	PWM pulse generation using FPGA	Cycloconverter fed synchronous motor
S-7	SLO-1	Multi-quadrant Operation	Single phase full converter fed separately excited DC motor	System response with filters	Squirrel cage induction motor: constant V/f control of induction motor	Comparison of VSI and CSI fed drives
	SLO-2	Real time example for four quadrant operation	Steady state analysis of the drive–discontinuous conduction	Phase locked loop control	Steady-state performance analysis based on equivalent circuit.	CSIfed synchronous motor
S-8	SLO-1	Components of Load Torques	Three phase full converter fed separately excited DC motor drive	Design of speed controller	Impact of rotor resistance on speed torque characteristics – rotor resistance control	Permanent magnet synchronous motor
	SLO-2	Nature and Classification of Load Torques	Steady state analysis of the drive - continuous conduction.	Simple problems	Derivation for equivalent resistance	Closed loop control of PMSM
S-9	SLO-1	Need for closed loop control	Introduction to software simulation of DC drives.	Design of current controller	Slip power	Simulation of induction motor characteristics
	SLO-2	Closed loop speed control of drives	Chopper based simulation	Simple problems	Slip power recovery schemes - Kramer's drive, Scherbius drive	Introduction to software simulation of AC drives.

Learning Resources	1. G.K. Dubey, <i>Fundamentals of Electrical Drives</i> , CRC Press, 2 nd edition, 2015 2. Ion Boldea, S. Anasar, <i>Electric Drives</i> , Third edition, CRC Press 2016. 3. R. Krishnan, <i>Electric Motor Drives: Modeling, Analysis and Control</i> , Prentice Hall, 2001 4. S.K. Pillai, <i>Analysis Of Thyristor Power-Conditioned Motors</i> , Universities press, 2005	5. G.K. Dubey, <i>Power Semiconductor Controlled Drives</i> , Prentice Hall, 1989. 6. W. Leonhard, <i>Control of Electric Drives</i> , Springer Science & Business Media, 2001. 7. P.C. Sen, <i>Thyristor DC Drives</i> , A Wiley-Interscience Publication 8. https://nptel.ac.in/courses/108104011/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.S.Paramasivam, Danfoss, Industries Pvt Ltd., paramsathya@yahoo.com	1. Dr.R.Subha., Sir MVIT, Bangalore, subha.mvit@gmail.com	1. Ms.D.Anitha, SRMIST
2. Mr. A.Kannan, Seshasayee paper and board limited akannan@sbppapers.com (machines)	2. Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	2. Dr.K.Mohanraj, SRMIST

Course Code	18EEE402T	Course Name	MODELLING AND ANALYSIS OF ELECTRICAL MACHINES	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	18EEC204J, 18EEC205J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Illustrate the reference frame theory	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Formulate the concept of modelling of DC machines	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand the theoretical model of synchronous machine				H	H	-	-	-	-	-	-	-	-	-	-	M	H	-
CLR-4 :	Derive the mathematical model of poly phase induction machines				H	H	H	M	M	-	-	-	-	-	-	-	M	H	-
CLR-5 :	Explain the generalized theory model of a single phase induction machine				H	H	H	M	H	-	-	-	-	-	-	-	M	H	-
CLR-6 :	Derive the mathematical model of DC and AC machines				H	H	H	M	H	-	-	-	-	-	-	-	M	H	-
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>					H	H	H	M	H	-	-	-	-	-	-	-	M	H	-
CLO-1 :	Outline the basics of rotating reference frame- synchronously and arbitrarily rotating reference frame transformation	1	75	75															
CLO-2 :	Interpret the modelling of DC machines for dynamic and steady state operation	2	75	75															
CLO-3 :	Construct the mathematical modelling of three phase synchronous machine	3	75	75															
CLO-4 :	Inspect the mathematical model of poly phase induction machine for electrical simulation studies	3	75	75															
CLO-5 :	Apply the generalized theory concept for the modelling of single phase induction machine	3	75	75															
CLO-6 :	Develop a mathematical model of different types of DC and AC machines	3	75	75															

Duration (hour)	s	9	9	9	9	9
S-1	SLO-1	Theory of transformation	Introduction to DC machine	Introduction to Three phase synchronous machine	Three phase induction machine- Types	Development of generalized theory
	SLO-2	Different reference frames	Back EMF equation	RMF, MMF waveform	MMF waveform	The general machine representation
S-2	SLO-1	Various sign conventions	Speed, torque equations	Winding model	Equivalent circuit	Sign Conventions
	SLO-2	Reference frame transformations	Terminal voltage equations	Modelling assumptions	Winding model	Voltage equations of a general machine
S-3	SLO-1	Illustration of how a transformation can result in constant inductances	DC machine types	Sign convention	Modelling assumptions	Flux linkage equations of a general machine
	SLO-2	Concept of stationary reference frame	Separately excited, self-excited-Equivalent circuits	Stator voltage equations in abc coordinates	Sign convention	Torque equation of a general machine
S-4	SLO-1	Illustration of transformation of stationary circuit variables	Speed - torque characteristics	Rotor voltage equations in abc coordinates	Stator voltage equations in abc coordinates	Illustration of application of generalized theory-DC machine model
	SLO-2	Concept of synchronously rotating reference frame	Electromechanical model of DC machine	Stator flux linkage equations in abc coordinates	Rotor voltage equations in abc coordinates, Induction machine: torque equations in abc	DC machine model-voltage and flux linkage equations
S-5	SLO-1	Concept of arbitrarily rotating reference frame	State equations of armature current and speed of DC motor	Rotor flux linkage equations in abc coordinates	Stator flux linkage equations in abc coordinates	DC machine model-Torque equation
	SLO-2	Transformation: stationary circuit variables to arbitrary reference frame	State-space model of DC machines	Stator self-inductance calculation	Rotor flux linkage equations in abc coordinates	Existing theories for explanation of single phase Induction motor operation, revolving field theory
S-6	SLO-1	Illustration of transformation of stationary	Transfer function model of DC machines	Stator to rotor Mutual-inductance	Stator self-inductance calculation	MMF and Flux waves, Torque

		circuit variables-Resistive elements		calculation		components
	SLO-2	Illustration of transformation of stationary circuit variables-Inductive elements	Steady state response of DC machines	Rotor to Stator Mutual-inductance calculation	Stator to rotor and Rotor to Stator, Mutual-inductance calculation	Application of generalized theory to single-phase induction motor
	SLO-1	Illustration of transformation of stationary circuit variables-Capacitive elements	Dynamic characteristics of DC machines	Rotor self –inductance calculation	Rotor self –inductance calculation	Voltage equations of single-phase induction machine
S-7	SLO-2	Transformations between reference frames x and y	The effect on speed for simultaneous change in input voltage and load torque of DC machine	Park's transformation	Reference frame transformation	Flux linkage equations single-phase induction motor
	SLO-1	Transformation of a balanced set to an arbitrarily rotating reference frame (ARF)	Calculation of efficiency and starting torque of DC separately excited machine.	Voltage equations in dqo reference frame (Park's equations)	Voltage equations in arbitrary reference frame	Torque equation of single-phase induction motor
S-8	SLO-2	Numerical example of transformation to arbitrary reference frame	Calculation of speed of DC machine from steady state equations	Flux linkage equations in (dqo) rotor reference frame	Flux linkage equations arbitrary reference frame,	Equivalent circuit of single phase induction machine
	SLO-1	Transformation to a synchronously rotating reference frame (SRF), Balanced steady-state phasor relationships	Calculation of armature torque and load torque of DC separately excited machine	Synchronous machine torque equations in abc and dq variables, Steady state equations in dq variables	Induction machine: torque equations in reference frame variable, Steady state equations in dq variables	Numerical example to illustrate steady-state computation of single phase induction machine
S-9	SLO-2	Summary – various reference frames	Computer simulation of DC machine dynamics using transfer function	Steady State analysis of Synchronous machine using simulation software	Computer simulation of induction motor dynamics in arbitrary reference frame	Validation of single phase induction machine model using simulation software

Learning Resources	<ol style="list-style-type: none"> 1. Paul C. Krause, Oleg Wasykczuk, Scott D. Sudhoff, Analysis of Electric Machinery and Drive Systems, IEEE Press, Third Edition, 2013. 2. R. Ramanujam, Modeling & Analysis of electrical machines."lk International Publishing House, New Delhi, 2018. 3. P. S. Bimbhra, Generalized theory of Electrical Machines, Khanna Publishers, Sixth Edition, 1995. 4. R. Krishnan, Electric Motor Drives: Modelling, Analysis and Control, Prentice Hall of India, 2002. 5. Ned Mohan. Advanced electric drives: analysis, control, and modeling using MATLAB/Simulink, John Wiley & sons; 2014. 6. Bernard Adkins, The General Theory of Electrical Machines, Imperial College of Science and Technology, 1974. 7. https://nptel.ac.in/courses/108106023/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers											
Experts from Industry				Experts from Higher Technical Institutions				Internal Experts			
1. Dr. Sharon Ravichandran, ABB Ltd., Chennai, sharonravi87@gmail.com				1. Prof. K.Shanthi Swarup, IITM, Chennai, ksswarup@iitm.ac.in				1. Mr. D. Maharajan, SRMIST			
2. Dr.V.P.Boopathi, Powersys., Chennai, Boopathivp@gmail.com				2. Prof. R.P.Kumudini Devi, Anna University, kumudini@annauniv.ac.in				2. Dr. M. Arun Noyal Doss. SRMIST			

Course Code	18EEE403T	Course Name	HYBRID ELECTRIC VEHICLES	Course Category	E	Professional Elective	L	T	P	C
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	SLO-2	Configurations of Series HEV	Basic battery modeling: Static and dynamic electric circuit model	Four quadrant operation of DC-DC converter	Permanent magnet motor based vector control operation –Control	Need of Charging Station Selection (CSS) server
S-6	SLO-1	Concept of Parallel HEV	Battery charging control	Flyback converter	SRM drives – Configuration	Smart grid technologies
	SLO-2	Configurations of Parallel HEV (Mechanical Coupling)	Battery charging control	Cell balancing converters: Active and Passive balancing methods	SRM drives –Converter and modes of operation	Smart grid technologies: Applications and Benefits
S-7	SLO-1	Configurations of Parallel HEV (Torque Coupling)	Ultra-capacitor: Symmetrical and asymmetrical – Introduction and Operation	Wireless Charging –Inductive Charging	Types of starters for motors in EV	Smart meter
	SLO-2	Configurations of Parallel HEV (Speed Coupling)	Ultra-capacitor modeling	Wireless Charging –Conductive Charging	Diagnosing starter faults	Smart meter: Purpose and benefits
S-8	SLO-1	Power train components	Operation of flywheel and fuel cell	Advanced charging system technology	Advanced starting system technology	Smart charger
	SLO-2	Vehicle model	Operation of hydraulic energy storage system	New developments in charging systems	New developments in starting systems	Smart charger: Purpose and benefits
S-9	SLO-1	EV power train component sizing	Simulation of battery model	Simulation of any PE converter for EV	Simulation and implementation of PE converter fed drives for EVs	Technical talk on any new emerging trend in EVs
	SLO-2	EV power train component sizing	Simulation of ultra-capacitor model	Simulation of any PE converter for EV	Simulation and implementation of PE converter fed drives for EVs	Technical talk on any new emerging trend in EVs

Learning Resources	<ol style="list-style-type: none"> 1. M. Ehsani, Y. GAO, and A. Emadi, <i>Modern Electric, Hybrid Electric, and Fuel Cell Vehicles: Fundamentals, Theory, and Design</i>, Second Edition, CRC Press, ISBN: 978-1-4200-5398-2, Aug. 2009. 2. Iqbal Hussain, <i>Electric & Hybrid Vehicles – Design Fundamentals</i>, Second Edition, CRC Press, 2011. 3. Sheldon S. Williamson, <i>Energy Management Strategies for Electric and Plug-in Hybrid Electric Vehicles</i>, Springer, 2013. 4. Chris Mi, M. AbulMasrur, David Wenzhong Gao, <i>Hybrid Electric Vehicles Principles and Applications with Practical Perspectives</i>, Wiley Publication, 2011. 5. Tom Denton, <i>Automobile Electrical and Electronic Systems</i>, Elsevier, Butterworth – Heinemann, Third Edition, 2004 6. https://nptel.ac.in/courses/108103009/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S.Archana, Valeo Pvt Ltd, archana.arc19@gmail.com	1. Dr.G.Uma, CEG, uma@annauniv.edu	1.Dr. U. Sowmmiya, SRMIST
2. Mr. Kopaka Chaitanya, Valeo Pvt Ltd, chaitu.239@gmail.com	2.Dr.S.Hosimin Thilagar, CEG, shthilagar@gmail.com	2.Dr. A.Rathinam, SRMIST

Course Code	18EEE307T	Course Name	SOLAR PHOTOVOLTAIC SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Learn the fundamental principle and fabrication of PV cell				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Study about PV characteristics and MPPT algorithms				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Utilize the various components and installation of standalone PV system							H	M	M	-	-	-	M	-	M	-	-	-	-	-	H	M	-
CLR-4 :	Study about the PV integration with utility grid							H	M	M	M	-	-	H	H	M	M	-	-	-	-	H	M	M
CLR-5 :	Know net metering and applications of Photovoltaic systems							H	M	M	M	-	-	-	-	-	-	-	-	-	-	H	H	-
CLR-6 :	Model a solar photovoltaic system							H	M	M	M	-	-	-	-	-	-	-	-	-	-	H	M	-
								H	M	M	M	M	-	M	H	M	M	-	-	-	-	H	M	M
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understand the basics of PV energy conversion and cell fabrication				2	80	75																	
CLO-2 :	Acquire knowledge about PV module and MPPT techniques				3	80	75																	
CLO-3 :	Design stand-alone PV system				3	80	75																	
CLO-4 :	Analyze grid connected PV system				3	80	75																	
CLO-5 :	Develop a PV system for various applications				3	80	75																	
CLO-6 :	Design a photovoltaic on grid and off grid system				3	80	75																	

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Global energy scenario	I-V,PV characteristics of a PV	Classification of PV systems	Grid Interactive PV System.
	SLO-2	Indian energy scenario	Modelling of PV	Central Power Station System , Distributed PV System	Principle components in Grid –PV system
S-2	SLO-1	Historical development of PV	Short Circuit, Open Circuit and peak power parameters	Stand alone PV System	Classification of Grid Tie Inverters
	SLO-2	Photovoltaic cell technologies	Datasheet study, Cell efficiency	Components of standalone PV connected system	Working Central inverter, String Inverter, Micro Inverter.
S-3	SLO-1	Basics of energy from sun: Insolation, irradiance, Solar constant	Effect of irradiation and temperature	Charge controllers	Grid-connected single phase PV inverter schemes
	SLO-2	Insolation variation with time of day, Earth centric viewpoint and declination	Shading impacts ,Fill factor	Batteries	Grid-connected PV control
S-4	SLO-1	Solar geometry	Solar PV Module and its parameters	Inverter control topologies	Power processing schemes based on single string, multi-string
	SLO-2	Description of the solar spectrum	Specifications of Solar PV Module	Stand-alone connection of PV modules to a battery and load	AC module technologies
S-5	SLO-1	Sun position, sun path diagrams, solar and clock times	Parallel and series connections. Identical cells Non-identical cells connection	Energy storage alternatives for PV systems.	Sizing the inverter
	SLO-2	Solar radiation measurements, resource of solar data.	Protecting cells in series and parallel, Interconnecting modules	Storage batteries, lead-acid, nickel-cadmium, nickel-metal-hydrate and lithium type batteries.	PV system sizing, efficiency
S-6	SLO-1	Photovoltaic effect - Principle of direct	Estimation and Measurement of PV	Small storage systems employing ultra	Transformer less inverter topologies for
					Need for Metering, Types of metering
					Concepts in Grid Tie systems
					Net metering and its importance
					Net metering benefits, policies
					PV potential and facilities in rural areas
					Electrifying rural and remote areas using PV
					Introduction to hybrid PV system
					Smart grid
					Case studies on Solar PV Power Plant
					Survey on existing solar PV system
					Design and Development of PV vehicle

		solar energy conversion into electricity in a solar cell system.	Module Power	capacitors, charging and discharging properties	grid connected PV applications	charging system
	SLO-2	Semiconductor properties semiconductor physics	Selection of PV Module, Interfacing PV modules to loads	Modeling of batteries load estimation, battery sizing	Centralized grid-connected three-phase inverters for large PV installations	PV powered lighting, Solar Lantern, LED for building etc
S-7	SLO-1	Solar cell - p-n Junction, Solar cell- basic structure	PV cell simulation	Design and Installation of a standalone PV system	Design related issues; grounding, dc arcing, islanding	PV water pumping, DC and AC pump drive
	SLO-2	Solar cell materials ,its properties and construction	Simulation of PV cells in series and parallel.	Mechanical Considerations for PV installation	Harmonic content, reactive power, wiring issues,electro-magnetic interference	PV applications in aircraft, power satellites.
S-8	SLO-1	Types of solar cells :crystalline, multi-crystalline, thin film silicon solar cells, etc	Maximum power point concept	Trouble shooting of Standalone Solar PV System	Interfacing with the power grid economic considerations	Socio-economic and environmental impacts of PV system
	SLO-2	Commercial Si solar cells, recent development in materials used for solar cell	Power conditioning and maximum power point tracking	Maintenance of Solar PV System	Energy yield of grid connected PV installation- Cost and Investment	PV in portable devices
S-9	SLO-1	Solar cells fabrication	MPPT basic Algorithms overview	Safety in installation of Solar PV System	Modeling of stand-alone and grid-connected PV systems	Impact of high PV penetration in power system
	SLO-2	Process involved solar cell fabrication technologies	MPPT algorithms based on buck- and boost-converter topologies	Codes and standards Related to PV Systems: National Electric Code(NEC) and IEEE Standard 1547	Simulation of stand-alone and grid-connected PV systems	Markets for photovoltaic systems

Learning Resources	1. Chetan Singh Solanki., Solar Photovoltaic: Fundamentals, Technologies and Application, PHI Learning Pvt., Ltd., 2nd edition 2011. 2. Rai, G.D., Solar Energy Utilization, Khanna Publishers, N. Delhi, 2010.	3. R. Messenger, J. Ventre, Photovoltaic Systems Engineering, CRC Press 3rd edition, 2010. 4. Sukhatme S.P., Solar Energy, Tata McGraw Hills P Co., 3rd Edition, 2008. 5. https://nptel.ac.in/courses/117108141/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Dr.P.Kanagavel, NIWE, Chennai, pkanagavel.niwe@nic.in		1. P.Thamizhazhagan, University college of Engineering, Panruti, thamizhme@gmail.com
2. Mr.Jason Manoraj , L&T Technology Services Limited, Bengaluru, Karnataka, jasonmanoraj@gmail.com		2. Dr. Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekr.ac.in
		Internal Experts
		1. Ms A.Lavanya, SRMIST
		2. Dr.R.Sridhar, SRMIST

Course Code	18EEE308T	Course Name	ENERGY MANAGEMENT SYSTEM AND SCADA	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
		1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-1 :		Impart knowledge on energy management and its planning			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-2 :		Understand the efficient usage of electric energy for motor driven system						H	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLR-3 :		Identify the strategies and control of energy management systems						H	M	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLR-4 :		Expose to the concept of supervisory control and data acquisition						H	M	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLR-5 :		Familiarize about Power System Automation and application of SCADA in power systems.						H	-	-	-	-	-	-	-	-	L	-	-	-	-	M	M	L
CLR-6 :		Understand the concept of Energy management and SCADA						H	M	-	-	-	-	-	-	-	L	-	-	-	-	M	M	L
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			2	75	75																	
CLO-1 :		Understand the values, importance, principles and effective utilization of energy			2	75	75																	
CLO-2 :		Apply energy efficient schemes for motor under varying loads			2	75	75																	
CLO-3 :		Implement the energy management control strategies			2	75	75																	
CLO-4 :		Analyze the Functions and features of SCADA			3	75	75																	
CLO-5 :		Infer the Applications and Standards of SCADA			2	75	75																	
CLO-6 :		Apply the knowledge of Energy management and SCADA in Industries			2	75	75																	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Value of Energy Management	Power supply of an electrical motor driven system	Introduction to Energy management systems(EMS)	Introduction of SCADA	Introduction to Power System Automation
	SLO-2	Total Quality Management	Effects of Unbalanced Voltages on The Performance of Poly-phase Squirrel-Cage Induction Motors	Usage of EMS	SCADA Systems	Benefits of Power System Automation
S-2	SLO-1	Energy Management Profession	Glossary of frequently occurring motor terms	Direct Digital Control	Evolution of SCADA	Functional structure of Power System Automation
	SLO-2	Energy Management skills	Design , Load types and torque of motor	Objectives of an EMCS using DDC	Objectives of SCADA	Architecture For Power System Automation
S-3	SLO-1	Principles of Energy Management	Power factor of motor	Hardware used in Energy management systems	Benefits of SCADA	Classification of Power System Automation- Substation Automation
	SLO-2	Some Suggested Principles of Energy Management	Benefits and correction of power factor	Advantages of Hardware used in Energy management systems	SCADA in Process Control	Classification of Power System Automation- Distribution Automation
S-4	SLO-1	Introduction to Energy Management Program	Electric motor design to operate at varying load conditions	Software used in Energy management systems	Usage of SCADA	Implementation Of Power System Automation Using SCADA
	SLO-2	Components of Comprehensive Energy Management Program	Determining Electric Motor Operating Loads	Effectiveness of the Software Control Logic	Real-Time Monitoring and Control using SCADA	Implementation Of Power System Protection Using SCADA
S-5	SLO-1	Organizational Structure	Power meter to measure unit operation	Control Strategies	Functions of SCADA	SCADA Based Model for Automation
	SLO-2	Energy manager , Team and Employees	Selection of Equipment for Power Measurement and Surveys	Routines of Control Strategies	SCADA Applications	SCADA Based Model Digital Protection
S-6	SLO-1	Energy Policy Objectives and	Slip measurement of motor	Justification of Energy Management	SCADA Hardware	Introduction to Applications of SCADA

		Accountability		Control Systems(EMCSs)		
	SLO-2	Energy Policy Reporting and Training	Amperage Readings	EMCSs Functions	SCADA Hardware Functions	SCADA Applications in Power Systems:
S-7	SLO-1	Energy Planning	Amperage Readings of Electric motor	EMCS opportunity	RTU Standards	Expected Benefits of SCADA for Power Systems
	SLO-2	Audit Planning	Electric Motor efficiency	EMCS for an building	Difference between PLC and RTU	SCADA for Power Utility Network
S-8	SLO-1	Educational Planning	Comparing Motors based on efficiency	EMCS Retrofit	Features of SCADA	Components of SCADA Applications
	SLO-2	Strategic Planning	Sensitivity of Load To Motor Rpm	New Construction EMCS	Software of SCADA	Introduction to IEC 61850 Standard for SCADA
S-9	SLO-1	Energy Reporting	Motor Performance Management Process(MPMP)	System Integration	Protocols of SCADA, DNP (Distributed Network Protocol)	Intelligent Electronic Devices (IEDs)
	SLO-2	Energy Ownership	How To Start MPMP	Specifics of Software Logic	Protocols of SCADA, IEC (International Electro Technical Commission)	Substation Automation System (SAS) using IED:

Learning Resources	<ol style="list-style-type: none"> Wayne C. Turner, Steve Doty, Energy Management Hand book, The Fairmont Press, 6th Edition, 2007 Green, J. N, Wilson, R, Control and Automation of Electric Power Distribution Systems, Taylor and Francis, 2007 NPTEL Online Courses, Energy Management Systems and SCADA, IIT Madras. Link : "https://nptel.ac.in/courses/108106022/12"
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.P.Kanakavel, NIWET, kanagavel.niwet@nic.in	1. Dr. S. Arul Daniel, NIT Trichy, daniel@nitt.edu	1. Dr.S.Vidyasagar, SRMIST
2. Mr. Tripathi patro, visam pvt ltd, btp@visom.co.in	2. Dr. P. Somasundaram, CEG, Anna University, mpsomasundaram@annauniv.edu	2. Dr.V.Kalyanasundaram, SRMIST

Course Code	18EEE309T	Course Name	DISTRIBUTED ENERGY RESOURCES	Course Category	E	Professional elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the basic operation of non conventional energy sources				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain the knowledge about PV system				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Acquire the knowledge of wind power Generation																					
CLR-4 :	Explain the energy production from Biomass and OTEC																					
CLR-5 :	Describe the working of Battery, Flywheel, Ultra Capacitors, micro-turbines																					
CLR-6 :	Acquire the Knowledge of Nonconventional energy sources																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Describe the basic operation of PV,wind,Fuel cell, Micro turbine, Biomass, Tidal power generation				1	75	75	H	-	-	-	-	-	M	-	-	-	-	-	M	M	L
CLO-2 :	Develop the knowledge of PV collector types and know the technical parameters				2	75	75	H	M	-	-	-	-	M	-	-	-	-	-	M	M	L
CLO-3 :	Distinguish different types of wind turbine and know the technical parameters				2	75	75	H	M	-	-	-	-	M	-	-	-	-	-	M	M	L
CLO-4 :	Summarize the functions of Biomass and OTEC				1	75	75	H	-	-	-	-	-	M	-	-	-	-	-	M	M	L
CLO-5 :	Realize the functions of Battery, Flywheel, Ultra Capacitors, micro-turbines				2	75	75	H	-	-	-	-	-	M	-	-	-	-	-	M	M	L
CLO-6 :	Develop the knowledge of the fundamental operation of unconventional energy sources				2	75	75	H	M	-	-	-	-	M	-	-	-	-	-	M	M	L

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Definition, Concepts of Non Conventional Energy Sources	Definition, Solar radiation data	Energy available from wind	Biomass Resources
	SLO-2	Limitations of Non Conventional Energy Sources	Solar energy conversion in to heat	General formula, Lift and drag etc	Biofuels
S-2	SLO-1	Energy needs of India, and energy consumption patterns	Solar Radiation Measurement	Basis of Wind energy conversion	Biomass Conversion Routes
	SLO-2	Worldwide Potentials of these sources.	Types of Measurement	Basic components of wind energy conversion	Combustion, Gasification
S-3	SLO-1	Energy efficiency and energy security	Flat plate and Concentrating collectors	Effect of density, Frequency variances,	Anaerobic Digestion
	SLO-2	Energy and its environmental impacts	Principle of natural and forced convection	Angle of attack, Wind speed	Pyrolysis
S-4	SLO-1	Technical impact of Distributed generation	Energy Storage of PV system	Choice of generators	Cogeneration
	SLO-2	Economical impact of Distributed generation	Case studies of Solar thermal systems for residential water heating	Turbine rating, electrical load matching	Biogas plants
S-5	SLO-1	Concept of distributed generations, topologies, selection of sources	Industrial heating	Variable speed operation	Energy recovery from Urban waste
	SLO-2	Regulatory standards/ framework	Solar power generation	Maximum power operation	Energy recovery from liquid waste
S-6	SLO-1	Definition of Distributed Generation	Concept of Maximum Power Point Tracking	Control systems, system design features,	Types of Biomass plant
	SLO-2	Classification of Distributed Generation	Types of MPPT	Windmill rotors, Horizontal axis	Performance analysis of Biomass
S-7	SLO-1	DG installation classes	DC Power Conditioning Converters	Vertical axis rotors	Testing Biomass systems
					Applications

	SLO-2	Security issues in DG implementations.	Types of converter	Induction type generators,	Thermal applications	Fuel Cells – Principle of Operation
S-8	SLO-1	Distributed Generation Impact on Coordinated Relay Protection	AC Power Conditioning –Inverters	Working principle of wind power plant	Power generation	Performance characteristics
	SLO-2	Classification of NCES, Solar, Wind,	Types of inverter	Determination of torque coefficient	Principles of tidal and wave power generations	Applications
S-9	SLO-1	Geothermal, Biomass, Ocean energy sources,	Testing of PV systems	Standalone connected operations	Open cycle OTEC	Micro-turbines- Principle -of Operation
	SLO-2	Comparison of these energy sources	Type of testing of PV system	Grid connected operations	Closed cycle OTEC	Advantages and Disadvantages of Microturbine

Learning Resources	<ol style="list-style-type: none"> 1. Rai, G.D., Non Conventional sources of Energy, Khanna Publishers, 5th Edition, 2016. 2. Rao. S. & Pamlekar Dr.B.B. Energy Technology, Khanna Publishers, 3rd Edition, 2016 3. Khan. B.H, Non-Conventional Energy Resources, The McGraw Hills, Second edition, 2016. 4. D.P.Kothari, Renewable Energy Sources and Emerging Technologies, PHI Learning Private Limited, 4th Edition 2011. 5. Bansal NK, Kleeman and Meliss M, Renewable energy sources and conversion Techniques, Tata Mc Graw Hill, 1990. 6. https://www.toppr.com/guides/physics/sources-of-energy/non-conventional-sources-of-energy/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Dr. Bhaskarsahu, Schneider Electric Ltd, Bhaskar.sahu@schneider-electric.com		1. Dr. K. S. Swarup, IITM, ksswarup@iitm.ac.in
2. Dr.P.Kanakavel, NIWET, pkanagavel.niwet@nic.in		2. Dr. R.Ramesh, CEG, rramesh@annauniv.edu
		Internal Experts
		1.Dr.D.Sattianadan, SRMIST
		2.Dr.K.Vijayakumar, SRMIST

	SLO-2	Micro-turbines- Principle of Operation	Purpose and Limitations	Peak Shaving Potential of a Microgrid	Static VAR Compensators	Solution methods
S-7	SLO-1	Biomass- Biomass Resources, Biofuels	Energy storage elements - Batteries	Operating modes of DG- Grid connected	Harmonic Filters	Economic impact of DG
	SLO-2	Biomass Conversion Technologies	Principle of operation	Operating modes of autonomous mode	Microgrid Operation Strategies	Barriers to DG Development
S-8	SLO-1	Energy recovery from Urban waste	Ultra-capacitors	Concept of reverse power flow	MicroGrids and Traditional Power	Configuration of SCADA
	SLO-2	Energy recovery from liquid waste	Principle of operation	Distributed Generation Impact on Coordinated Relay Protection	System Economics	Energy Management System
S-9	SLO-1	Principles of tidal and wave power generations	Flywheels	Adaptive relaying	Case Studies : Microgrid Economics	Active distribution networks Distributed control system (DCS)
	SLO-2	Open cycle OTEC and closed cycle OTEC	Principle of operation	Fault Limiters	Economic Issues Between MicroGrids and the Bulk Power Systems	Impact of EV on micro grid

Learning Resources	<ol style="list-style-type: none"> 1. Amirnaser Yezdani, and Reza Iravani, Voltage Source Converters in Power Systems: Modeling, Control and Applications, IEEE John Wiley Publications, 2009. 2. Dorin Neacsu, Power Switching Converters: Medium and High Power, CRC Press, Taylor & Francis, 2006. 3. Chetan Singh Solanki, Solar Photo Voltaics, PHI learning Pvt. Ltd., New Delhi, 2009. 4. J.F. Manwell, Wind Energy Explained, theory design and applications, J.G. McGowan Wiley publication, 2002. 5. D. D. Hall and R. P. Grover, Biomass Regenerable Energy, John Wiley, New York, 1987. 6. S. Chowdhury, S.P. Chowdhury, Microgrids and Active Distribution Networks, IET renewable energy series 6 7. https://www.powermag.com/the-smart-grid-and-distributed-generation-better-together/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Bhaskarsahu, Schneider Electric Ltd, Bhaskar.sahu@schneider-electric.com	1. Dr.S.Senthilkumar, NIT Trichy, skumar@nitt.edu	1.Dr.D.Sattianadan, SRMIST
2. Dr.P.Kanakavel, NIWET, pkanagavel.niwet@nic.in	2. Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	2.Dr.K.Vijayakumar, SRMIST

Course Code	18EEEE405T	Course Name	POWER ELECTRONICS IN RENEWABLE ENERGY SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Educate the students on contemporary development in renewable energy studies	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-2 :	Design and analyze the power converters for PV applications				H	M	M	-	-	M	-	M	-	-	-	-	-	-	H	M	-	
CLR-3 :	Understand the significance of the power converters for wind energy conversion system				H	M	M	-	M	-	M	-	-	-	-	-	-	-	H	M	-	
CLR-4 :	Create insights into the concept of fuel energy system and its power conditioning system				H	M	M	-	M	-	M	-	-	-	-	-	-	-	H	H	-	
CLR-5 :	Enrich the concept of hybrid renewable energy systems and multiport converters				H	-	-	-	-	-	M	-	-	-	-	-	-	-	H	M	-	
CLR-6 :	Create overall structure for integrating renewable electricity on the grid				H	M	M	-	M	-	M	-	-	-	-	-	-	-	H	M	-	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Acquire knowledge on renewable energy sources and their characteristics	2	80	75																		
CLO-2 :	Select and design the components of a power converter for PV system	3	80	75																		
CLO-3 :	Propose an appropriate power converter for wind energy conversion system	3	80	75																		
CLO-4 :	Choose a suitable converter topology for fuel cell-based energy system	3	80	75																		
CLO-5 :	Analyze various hybrid energy system for various applications	3	80	75																		
CLO-6 :	Design the building blocks of the renewable energy conversion system	3	80	75																		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Present scenario of renewable energy sources in India	Photovoltaic system components	Components of a wind energy conversion system	Basic overview of fuel cell currently under development	Need for Hybrid Systems
	SLO-2	Solar, wind, ocean, Biomass, Fuel cell and geothermal resources.	Factor influencing output	Site selection consideration	Applications and markets- Portable and stationary application	Types of Hybrid system
S-2	SLO-1	Factors influencing the amount of GHG emission	Types of PV system	Wind generators-Introduction	Fuel cell design levels: The unit cell, the stack, and the system	wind-diesel hybrid system
	SLO-2	Impacts of renewable energy generation on environment	Stand-alone PV system and grid connected PV system	Classification of wind generators	Types of fuel cell and its comparative study	PV-Diesel hybrid system
S-3	SLO-1	Basic principle of photovoltaic Energy Conversion	PV and IV characteristics	Power output performance characteristics	Chemical reaction in various fuel cell	PV-hydro hybrid system
	SLO-2	PV materials	Modeling of PV system	Modeling of wind energy conversion system	Components of fuel cell- Electrolytes and catalyst	Biomass-PV-diesel hybrid system
S-4	SLO-1	Issues associated with the tapping of solar energy	Factors to be considered for the selection of inverter and batteries for solar energy conversion	Matrix converters	Thermodynamic and electrochemical principles of hydrogen fuel cell	Economic, technical and sustainability issues involved in the integration of hybrid renewable energy systems
	SLO-2	Limitations of solar power	Sizing the solar arrays	Limitations in the operation of matrix converter.	High temperature fuel cell	Current status of solar-wind hybrid renewable energy system
S-5	SLO-1	Wind resource assessment	Batteries for solar panel	Synchronized operation with grid supply	Fuel cell power system	Hybrid system characteristics
	SLO-2	Wind energy pattern for a particular location	Various aspects of battery sizing	Harmonic distortion	MPPT techniques for fuel cell	Various power quality issues hybrid renewable power system
S-6	SLO-1	Basic principle of wind energy	DC power conditioning converters	Standards used for grid integration- Grid	Design consideration of power	Merits of Hybrid RES over the isolated

		conversion		connection requirement of renewable power system.	electronics converters for fuel cell system	RES
	SLO-2	Power in wind –Betz limit	AC Power conditioning converters	Disturbances from power conditioning devices on the power grid- Power quality issues	Power conversion and control strategies	Case studies on wind-PV maximum power tracking system
S-7	SLO-1	Net metering concept	Basic non-isolated converters	Problems in grid integrated WECS	Issues in fuel cell power conditioning system	Multi-port DC-DC converter
	SLO-2	Repowering concept	Isolated dc-dc converters	Impact of wind power penetration in power grid	Fuel cell power conditioning for electric power applications	Flux additive dc-dc converter
S-8	SLO-1	Hydrogen energy system	Converter dynamics and control	Design and optimization of renewable energy system	High gain dc-dc converters for fuel cell based electric vehicle	Hybrid controller
	SLO-2	Hydrogen energy to generate electric power	Bidirectional inverter system	Simulation software for distributed generation power system	Operating principles of high gain dc-dc converter	Major features of hybrid system.
S-9	SLO-1	Working principle of fuel cell	Simulation of PV and IV characteristics	Simulation of Sizing, and analysis of WECS	Reliability study on fuel cell	Merits and demerits of various renewable energy technologies
	SLO-2	Fuel cell characteristics	Simulation of Sizing, and analysis of photovoltaic systems.	Simulation of power electronic converters for WECS	Recent research in fuel cell technology	Application of various renewable energy technologies.

Learning Resources	1. Rashid .M. H, Power Electronics Hand book, Academic press, Second edition, 2006. 2. Gray, L. Johnson, Wind energy system, prentice hall linc, 1995 3. Fuchs, Ewald F., Masoum, Mohammad A.S, Power Conversion of Renewable Energy Systems, 978-1-4419-7978-0, springer, 2011.S.N.Singh, Electric power generation, transmission and distribution, 2 nd ed., PHI, 2011 4. Erickson, Robert W., Maksimovic, Dragan Fundamental of Power electronics, springer, 2001. 5. https://nptel.ac.in/courses/108108034/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.P.Kanagavel, Additional Director, R & D, NIWE, Government of India, pkanagavel.niwe@nic.in	1.Dr. Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekr.ac.in	1. Dr.J.Divya Navamani, SRMIST.
2. Mr.Jason Mano Raj, Consultant, L& T Technical services, Bangalore jasonmanoraj@gmail.com	2.Dr.P.Thamizhagan, EEE department, University college of Engineering, Panruti, thamizhme@gmail.com	2.Dr.R.Sridhar, SRMIST

Course Code	18EEE406T	Course Name	WIND AND SOLAR ENERGY SYSTEM	Course Category	E	Professional Elective	L	T	P	C
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	SLO-2	Latitude angle	Issues in the stand alone solar system	Solar pond	Stall control	Grid related problems
S-8	SLO-1	Longitude angle	Types of losses in solar panel.	Water pumping	Schemes for maximum power extraction.	Wind generator controlling techniques
	SLO-2	Zenith angle	Solar Photovoltaic power plant.	Domestic lighting	Site Selection	Issues in hybrid of solar and wind power
S-9	SLO-1	Concentrating collectors.	Net metering concept	Grid connected PV systems	Environmental aspects	Different schemes
	SLO-2	Advantages and disadvantages of solar	Design :Panel requirements for a particular load	Challenges in Grid connected solar PV	Solidity	AC voltage controllers

Learning Resources	<ol style="list-style-type: none"> 1. Rai, G.D., Non-Conventional sources of Energy, 5th Edition, Khanna Publishers, 2016 2. Khan. B.H, Non-Conventional Energy Resources, 2nd Edition, The McGraw Hills, 2016 3. Rai, G.D., Non-Conventional sources of Energy, 5th Edition, Khanna Publishers, 2016. 4. Khan. B.H, Non-Conventional Energy Resources, 2nd Edition, The McGraw Hills, 2016. 	<ol style="list-style-type: none"> 5. Thomas Ackermann, Wind Power in Power Systems, John Wiley & Sons, Ltd, 2005 6. Mukund R. Patel, Wind and Solar Power Systems, CRC Press, 1999 7. Muhammed H. Rashid, "Power Electronics Handbook" Academic Press, Second 8. Bansal N K, Kleeman and Meliss, "Renewable energy sources and conversion Techniques, Tata McGraw hill, 1990. 9. https://onlinecourses-archive.nptel.ac.in/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Manjunath rao, Alstrom,manjunath.rao1103@gmail.com	1. Dr.S.Senthilkumar, NIT Trichy, skumar@nitt.edu	1. Dr. K.Saravanan, SRMIST
2. Mr.Srinath rao, Alstrom,sreenath.rao@alstrom.com	2. Dr. S. Ramareddy, Jerusalem College of Engineering,srr.victory@gmail.com	2. Dr.R.Sridhar, SRMIST

Course Code	18EEE310T	Course Name	ENERGY CONSERVATION AND AUDITING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the current energy scenario and energy conservation.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Familiarize the basics of energy and its forms	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Outline the concepts of energy management and audit				H	M	-	-	-	-	-	H	-	-	-	-	-	-	H
CLR-4 :	Discuss the methods of improving energy efficiency in different electrical machines				H	M	-	-	-	-	-	-	-	-	-	-	M	M	-
CLR-5 :	Describe the methods of improving energy efficiency in different industrial systems				H	H	-	-	-	-	-	-	-	-	-	-	M	M	-
CLR-6 :	Obtaining wide knowledge about energy management procedures in industrial system				H	H	-	-	-	-	H	H	-	-	-	-	H	M	H
					H	H	M	-	-	-	-	-	-	-	H	-	H	M	-
					H	H	M	-	-	-	M	H	-	-	H	-	H	M	H
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Relate the energy scenario and energy conservation	2	80	75															
CLO-2 :	Explain about various energies and its conversions	3	80	75															
CLO-3 :	Implement the procedure for energy audit	3	80	75															
CLO-4 :	Assess the energy efficiency in electrical components	3	80	75															
CLO-5 :	Assess the energy efficiency in industrial system	3	80	75															
CLO-6 :	Apply energy saving concepts in electrical system	3	80	75															

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Energy Classifications	Forms of energy	Energy management	Introduction to energy policy, synopsis of National energy policies in India, EC Act 2001.	Air condition and refrigeration
	SLO-2	Primary energy consumption	Energy conversion, Grades	Energy audit - types	ISO-50001, PDCA, PAT scheme	Diesel Generator
S-2	SLO-1	Indian energy scenario	Electrical energy	Conservation opportunities	BEE & State Development Agencies & EESL Programmes	Energy Efficiency in Building
	SLO-2	World energy scenario	Electrical energy conversion	Conservation opportunities	Ujala & SEEP Programs	Energy Efficiency in Building
S-3	SLO-1	Energy needs	Electricity Tariff – M.D.,	Energy costs, bench marking	Municipal & Agriculture DSM Initiatives	Savings opportunities in HVAC
	SLO-2	Energy pricing	Electrical Tariff T.O.D., P.F	Energy performance	Standards and Labelling Programme EEC initiatives in Other Sectors	Fans and blowers
S-4	SLO-1	Energy sector reforms	Electrical Tariff – two-part tariff and others	System efficiencies	Energy tariffs	Conservation opportunities
	SLO-2	Green house, climate change	Numerical Examples on electrical basics	Energy substitution	Energy Instrument	Pumps - CASE STUDY
S-5	SLO-1	Future effects	Numerical Examples on electrical tariff	Audit instruments	Energy Instrument	Control strategies
	SLO-2	Energy security	Thermal energy– temperature, pressure	Facility as an energy system	Measurement of harmonics	Conservation opportunities
S-6	SLO-1	Energy conservation	Heat transfer	Preparing process flow	Harmonics Analyzer	Cooling Tower -performance
	SLO-2	Material and energy balance	Latent heat, super heat	Energy efficiency in electrical system	Power quality analyzer, Thermal Imaging camera, Thermocouple	Efficient system operation
S-7	SLO-1	Energy balance calculations	Humidity	Electric motor, compressor, pump.	Hot wire anemometer, Energy meter.	Efficient system operation
	SLO-2	Restructuring energy sector	Conduction / convection / radiation / evaporation	Power factor improvement, Load management.	Combustion analyzer, Airflow meter, Ultrasonic leak detector	Validation of energy saving using application software
S-8	SLO-1	Energy strategy	Units and conversion – pressure, power,	Numerical Examples on power factor	Occupancy sensors,	Energy saving opportunities

	SLO-2	Air pollution	Units and conversion - energy units	Numerical Examples on power factor	Energy efficient lighting controls	Energy saving opportunities
S-9	SLO-1	Energy conservation act	Numerical example on energies	Numerical examples on harmonics	Energy saving potential of technology	Assessment of cooling towers
	SLO-2	Extracted features of the act	Numerical example on energies	Numerical examples on harmonics	Case study on energy saving technologies	Assessment of cooling towers

Learning Resources	1. Guide books for National Certification Examination for Energy Manager / Energy Auditors Book-1, General Aspects (www.aipnpc.org/GuideBooks.aspx) 2. Guide books for National Certification Examination for Energy Manager / Energy Auditors Book-3, Electrical Utilities (www.aipnpc.org/GuideBooks.aspx)	3. S. C. Tripathy, Utilization of Electrical Energy and Conservation, McGraw Hill, 1991. 4. Success stories of Energy Conservation by BEE, New Delhi (www.bee-india.org). 5. Chopra S.K, Energy Policy for India, Oxford & IBH Publishing, ISBN 812041604X 6. Alagiri, Dhandapani, Energy Security in India, icfai university press, ISBN8131404617
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. P.Dharmalingam, Former Director, NPC	Dr.M.Premalatha , Professor, DEE,NIT-Trichy, latha@nitt.edu	Mr.D.Ravichandran,SRMIST
Mr.J.Sathyanarayanan,Senior engineer, Southern Railway, Railwayengineer1990@gmail.com	Dr.Ruben sudhakar D, Assist. Prof.Grade-I,DEE, NIT-Trichy rubensudhakar@nitt.edu	Dr.C.Naveen,SRMIST

Course Code	18EEE311T	Course Name	INDUSTRIAL POWER SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the wiring system for residential ,commercial and industrial consumers	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire knowledge on standard methodologies for measuring energy in the workplace and energy audit instruments.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Acquire knowledge about Electrical distribution system design aspects of industrial and commercial buildings				H	M	M	M	-	-	-	L	-	-	-	-	M	L	L
CLR-4 :	Comprehend power quality issues and power factor correction				H	M	M	L	-	-	-	-	-	-	-	-	M	M	L
CLR-5 :	Describe the various techniques in industrial automation				H	M	L	L	-	-	-	M	-	-	-	-	M	M	-
CLR-6 :	Acquire knowledge on the methodologies and technologies of industrial automation				H	-	-	-	-	-	-	-	-	-	-	-	M	M	-
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		2	80	75	H	M	M	L	M	-	-	-	-	-	-	-	M	M	-
CLO-1 :	Design the different components of wiring system	3	80	75	H	M	M	L	-	-	-	-	-	-	-	-	M	M	L
CLO-2 :	Analyze the concept of energy audit and different loads	3	80	75	H	M	L	L	-	-	-	M	-	-	-	-	M	M	-
CLO-3 :	Evaluate and design of distribution system and address different Communication systems in industries	3	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-4 :	Address the different power quality problem and various methods of power factor correction	2	80	75	H	M	M	L	M	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Identify, monitor and control using PLC and SCADA	3	80	75	H	M	M	L	M	-	-	M	-	-	-	-	M	M	L
CLO-6 :	Analyze the problem pertaining to power management and automation in industries																		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	LT system wiring components	System approach and End use approach to efficient use of Electricity	Electrical System Design	Overview of power quality	Computer controlled systems Insulation coordination and Automation
	SLO-2	Selection of cables,wires,switches	Energy auditing: Types and objectives	Distribution System Design	Various issues in power quality	Modeling of system
S-2	SLO-1	Selection of distribution box.	Audit instruments- ECO assessment	Electrical Design Aspects of Industrial Buildings	Various standards of voltages	Simulation of switching surges
	SLO-2	Metering system	Economic methods	Commercials Buildings – Design aspects	Voltage sag-Definition and types	Capabilities; voltage acceptance criteria
S-3	SLO-1	Tariff structure	Specific energy analysis	Electrical Safety	System Data for power quality	Insulation coordination case study
	SLO-2	Protection components	Minimum energy paths	Earthing Practices at various voltage levels	Voltage Drop Calculations	Methods of minimizing switching transients
S-4	SLO-1	Fuse ,MCB inverse current characteristics	Electric motors	IS Code for earthing	Computer- Aided Analysis	Study role of Basic PLC
	SLO-2	Isolator ,Relay,MPCB	Energy efficient controls and starting efficiency	Distribution Automation System : Necessity, System Control Hierarchy	Power factor correction studies	Role of an automation
S-5	SLO-1	Electric shock and safety practices	Motor Efficiency	Basic Distribution Management System Functions	Introduction to over voltages	Advantages of process automation
	SLO-2	Types of Residential system	Load Analysis	Integration of Distributed Generation	Description and Modeling	PLC based control system design , Panel metering
S-6	SLO-1	Types of commercial wiring system	Variable speed drives	Custom Power components in distribution systems-	Acceptance Criteria-Frequency Scan Analysis	Introduction to SCADA
	SLO-2	Genaral rules for wiring system	Pumps and Fans-Efficient Control strategies	Distribution system Performance	Voltage Magnification Analysis	Common System Components

S-7	SLO-1	Guide lines for installation	Optimal selection and sizing	Reliability calculations	Sustained Over voltages	Various functions of SCADA System for distribution automation
	SLO-2	Load calculation	Optimal operation and Storage	Communication Systems for Control and Automation	Switching Surge Analysis	SCADA Architecture
S-8	SLO-1	Sizing of wire	Electric Energy Scenario	Wireless Communications	Back-to-Back Switching	Various control of SCADA System
	SLO-2	Rating of main switch and distribution board	Demand Side Management-Industrial Load Management	Wired Communications	KVAR calculation	Supervision and Control in SCADA
S-9	SLO-1	Earthing system calculation	Load Curves-Load Shaping Objectives-Methodologies-Barriers	DA Communication Protocols	Types of compensation	HMI, RTU and Supervisory Stations
	SLO-2	Requirements of commercial installation	Classification of Industrial Loads- Load Modelling; Electricity pricing	Architectures and user interface	Over view of compensation	Trends in SCADA, Security Issues

Learning Resources	1. H. Joshi, Residential Commercial and Industrial Systems, McGraw Hill Education, 2008.	4. Ra 5. James Northcote – Green, Robert Wilson, Control and Automation of Electrical Power Distribution Systems, CRC Press, New York, 2007.
	2. DONALD BEEMAN, Industrial Power Systems Handbook, McGRAW-HILL BOOK COMPANY, INC Rasamy Natarajan, Computer-Aided Power System Analysis, Marcel Dekker Inc., 2002 3. S.L. Uppal and G.C. Garg, Electrical Wiring, Estimating & Costing, Khanna publishers, 2008	5. Turan Gonen: .Electric Power Distribution System Engineering. McGraw Hill Company. 1986 6. M.V 7. James Northcote – Green, Robert Wilson, Control and Automation of Electrical Power Distribution Systems, CRC Press, New York, 2007.

Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
Total		100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1.Mr.Srinath rao, Alstrom,sreenathr.rao@alstrom.com		1.Dr. P. Somasundaram, CEG, Anna University, mpsomasundaram@annauniv.edu
2.Mr.Manjunath rao, Alstrom,manjunath.rao1103@gmail.com		2.Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in
		Internal Experts
		1.Dr.V.Kalyanasundaram,SRMIST
		2.Dr.S.Vidyasagar, SRMIST

Course Code	18EEE312T	Course Name	FLEXIBLE AC TRANSMISSION SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Outline the fundamentals of FACTS controllers	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Discuss shunt and series compensation techniques and its objectives	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the concept of TCSC controllers	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Learn basic idea of voltage and phase angle regulator in power system	Expected Attainment (%)	Design & Development
CLR-5 :	Familiarize the concept of versatile FACTS controllers		Analysis, Design, Research
CLR-6 :	Create overall structure of facts controllers and application of FACTS controller		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Summarize the concepts of FACTS controllers	1	80	75	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-2 :	Categorize the shunt and series compensation techniques used in facts controllers and its objectives	2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Examine the operation of TCSC and application of TCSC	2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-4 :	Relate the various application of phase shift transformer and phase angle regulator	2	80	75	H	-	-	-	-	-	-	M	M	-	-	-	H	H	-
CLO-5 :	Gain knowledge the basic concept of STATCOM, UPSC and its application	2	80	75	H	-	-	-	M	-	-	-	-	-	-	-	H	M	-
CLO-6 :	Design a suitable FACTS controller to compensating of real and reactive power using FACTS devices	2	80	75	H	-	-	-	M	-	-	-	M	M	-	-	H	M	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Electrical Transmission Network	Introduction to passive compensation	Need for variable series compensation	Phase shifting transformer
	SLO-2	HVDC Vs HVAC	Objectives of shunt and series compensation	TCSC: Basic and practical module	Configurations of SPST
S-2	SLO-1	Conventional Control Mechanisms- Automatic Generation Control (AGC)	Introduction to Single-phase and three phase-Thyristor controlled Reactor (TCR)	Net reactance offered by TCSC,	Objectives of voltage and phase angle regulators
	SLO-2	Excitation Control-Transformer Tap-Changer Control-Phase-Shifting Transformers	The 12-Pulse TCR	Operation of TCSC: Basic principle	Real and reactive power of voltage and phase angle regulators
S-3	SLO-1	System compensation	Analysis of single phase TCR	X-I and V-I characteristics of TCSC	Applications of Phase Angle Regulator
	SLO-2	Analysis of Uncompensated Transmission system	SVC configurations- Fixed Capacitor	Different modes of Operation Explain TCSC	Approaches to Thyristor controlled voltage regulators
S-4	SLO-1	Necessity of FACTS controller	Thyristor-Controlled Reactor and its operating characteristics	Different modes of operation Explain MSC	Approaches to phase angle regulators
	SLO-2	Load and system Compensation	Operating Characteristics without Voltage Control	Analysis of TCSC	Continuously Controllable Thyristor Tap changers
S-5	SLO-1	Comparison between Series-Connected and Shunt-Connected Compensating Voltages	Operating Characteristic With Voltage Control	Analysis of TSSC	Thyristor Tap Changer with Discrete Level Control
	SLO-2	Modeling long transmission line	SVC voltage control operation	Capability Characteristics (single and multi-module TCSC) TCSC losses	Improvement of Transient Stability

S-6	SLO-1	Real and reactive power flows in AC system	Q-V characteristics	TCSC applications	Power Oscillation Damping	UPFC: basic module -capabilities
	SLO-2	Symmetrical lossless line Midpoint compensation	Thyristor Switched Capacitor (TSC)-operation-	Modelling of TCSC for Stability Studies	Basic Issues in the Damping of Low Frequency Oscillations in Large Power Systems	UPFC Modes of operation
S-7	SLO-1	Surge Impedance Loading	Practical switching strategy V-I characteristics of TSC	Power flow enhancement	System Modelling for Small Signal Stability	Applications
	SLO-2	Classification of FACTS controllers controllable parameters	(TSC)-operation -VI characteristics	Variable reactance model for transient stability study	Damping of Power Oscillations Using Series FACTS Controllers	Introduction to Generalized unified power flow controller (GUPFC)
S-8	SLO-1	Applications of FACTS	(TCR)-operation -VI characteristics	TCSC: Open loop current control	Damping of Power Oscillations Using Shunt FACTS Controllers	Inter line power flow controller (IPFC)
	SLO-2	Relative Power Carrying Capability of AC and DC Transmission Lines	Advantages of slope in SVC dynamic characteristics	TCSC: closed loop current control	Switching Converter-Based Voltage and Phase Angle Regulators	Configuration of IPFC
S-9	SLO-1	The Impact of Distributed Generation	SVC Applications	Power flow incorporating with SVC and TCSC	Hybrid Phase Angle Regulators	Application
	SLO-2	The Effect of Electricity Deregulation	Enhancement of steady state and transient stability	Mitigation of Subsynchronous Resonance with TCSC	A Case Study of Damping Controllers in UPFC	Simulation of SVC and TCSC with SMIB system

Learning Resources	1. Mohan Mathur, R. & Rajiv K. Varma, Thyristor Based FACTS Controller for Electrical Transmission Systems, Wiley Interscience Publications, 2011. 2. Narain G. Hingorani & Laszlo Gyugyi, Understanding FACTS – Concepts & Technology of Flexible AC Transmission Systems, Standard Publishers, New Delhi, 2011.	3. Yong Hua Song and Allan T. Johns Flexible Ac Transmission Systems (FACTS), The Institution of Engineering and Technology 2008 4. https://nptel.ac.in/courses/108107114/ 5. https://npti.gov.in/flexible-ac-transmission-system
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Manjunath rao, Alstrom,manjunath.rao1103@gmail.com	1.Dr.D.Devaraj, Dean-Academic,Kalasalingam Academy of Research and Education, d.devaraj@klu.ac.in	1. Mr.D.Maharajan, SRMIST
2.Dr. T. Prakash, TNEB, Mt. Road, prakash.thyagarajan@tnebnet.org	2. Dr. S. Ramareddy, Jerusalem College of Engineering,srr.victory@gmail.com	2. Mr.V.Kubendran, SRMIST

Course Code	18EEE313T	Course Name	HIGH VOLTAGE ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Outline the concepts of over voltages and Insulation Co-ordination on power system						1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Discuss the solid, liquid and gaseous dielectrics with its relevance to application of high voltages.						Thinking (Bloom)	Proficiency (%)	Attainment (%)	Engineering Knowledge	Analysis	Development	Design,	Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Team Work	Communication	Management & Finance	Life Long Learning				
CLR-3 :	Understand the concept of generation of high voltages																								
CLR-4 :	Familiarize the concept on the measurement of high voltages and currents																								
CLR-5 :	Describe the testing of high voltage equipments and its application.																								
CLR-6 :	Create overall understanding of various types of overvoltages, high voltage generation, measurement and testing																								

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																				
CLO-1 :	Gain knowledge on overvoltage protection and the importance on insulation co-ordination levels.			2	80	75	H	-	-	-	-	-	M	-	-	-	-	-	-	M	-
CLO-2 :	Understand the basics of dielectrics and its breakdown process on high voltage application			2	80	75	H	M	L	L	-	-	M	-	-	-	-	-	M	M	-
CLO-3 :	Acquire knowledge on high voltage generation			2	80	75	H	M	L	L	-	-	-	-	M	M	-	-	M	M	-
CLO-4 :	Gain knowledge on measurement of high voltage generation			2	80	75	H	M	L	L	-	-	-	H	-	-	-	-	M	M	M
CLO-5 :	Demonstrate the testing procedures of high voltage equipment and its application			3	80	75	H	M	-	-	-	-	-	H	-	-	-	-	M	M	H
CLO-6 :	Summarize the scenarios of over voltages and applications of high voltage equipments for generation ,measurement and testing			3	75	75	H	M	L	L	L	-	M	H	M	M	-	-	M	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Causes of over voltages	Gaseous breakdown in uniform and non-uniform fields	Generation of high DC voltages – Half-wave and full-wave rectifier circuits	HVDC measurement techniques Series Resistance microammeter	Testing of High voltage electrical apparatus
	SLO-2	Effects of overvoltages on power system	Conduction and breakdown in gases-Ionization process	Voltage doubler circuits	Resistance potential divider	Technical terms definition for high voltage testing
S-2	SLO-1	Parameters of lightning strokes	Townsend's current growth equation in the presence of secondary processes	Voltage multiplier circuits	Generating voltmeter	Testing procedures on insulators-Power frequency tests
	SLO-2	Characteristics of lightning strokes-Direct, indirect strokes and backflashover	Townsend's Criterion for breakdown	Van de Graff generator	Measurement of high A.C and impulse voltages-	Impulse tests
S-3	SLO-1	Origin of Switching overvoltages	Experimental determination of Townsend's coefficients	Generation of high alternating voltages	Series Impedance voltmeters	Testing procedures on bushings-Power frequency tests
	SLO-2	Characteristics of Switching overvoltages	Breakdown in electronegative gases	Cascaded transformer	Series capacitance voltmeter	Thermal test
S-4	SLO-1	Impact of switching surges in EHV and UHV systems	Time lags for breakdown	Resonant transformer-Series connection	Capacitance potential dividers and capacitance voltage transformers	Testing procedures on isolators
	SLO-2	Control of overvoltages due to switching overvoltages	Streamer Breakdown mechanism in gases	Resonant transformer-Parallel connection	Potential Transformer, Electrostatic voltmeter,	Short-circuit test
S-5	SLO-1	Causes of power frequency overvoltages in EHV and UHV systems	Paschen's law-Derivation	Generation of high frequency alternating voltages- Advantages	Peak reading ac voltmeter-Series capacitor, peak voltmeter	Testing procedures of cables-Preparation of cables-Dielectric power test
	SLO-2	Remedial measures adopted in EHV and UHV systems	Practical Considerations in using gases for insulation purposes	Tesla coil equivalent circuit	Digital peak voltmeter	High voltage test and Partial discharge test
S-6	SLO-1	Protection against Lightning overvoltages	Vacuum breakdown	Generation of impulse voltages-Standard	Measurement of high dc, ac and impulse	Testing procedures of transformers-e

		and switching surges of short duration-Ground wires		impulse waveshapes	voltages -Sphere gap measurement	overvoltage test, Partial discharge test
	SLO-2	Protection of transmission lines against over voltages-Ground rods and counter-poise wires	Liquid as insulators-Electrical properties	Waveshape Control Parameters	Factors influencing the spark over voltage of sphere gaps	Impulse testing of transformers-Procedures-Detection and location of fault
S-7	SLO-1	Protective devices-Rod gap, Expulsion gap	Conduction and breakdown in pure and commercial liquids	Multistage impulse generator-Marx circuit	Resistance Potential divider for impulse voltage measurements	Testing procedures of surge diverters
	SLO-2	Protector tubes, Surge arrester	Breakdown mechanisms in solid dielectrics-Intrinsic and Electromechanical breakdown	Marx circuit -simulation	Capacitance potential dividers for impulse voltage measurements	Radio Interference Measurements – Measurement of Radio Interference voltage
S-8	SLO-1	Principles of Insulation Coordination-Ideal requirements of a protective device	Breakdown mechanisms in solid dielectrics-Intrinsic and Electromechanical breakdown	Generation of impulse current-Definition-Circuits for producing impulse current waves	Measurement of high DC, AC and impulse measurements-High DC currents-DC current transformer-Hall generators	RIV measurement circuit
	SLO-2	Surge diverters, Equipment insulation level and insulation co-ordination of substation	Thermal breakdown, solid breakdown used in practice	Generation of rectangular current pulses	Measurement of high frequency and impulse currents- Resistive shunts	Non-destructive testing of materials and measurement of direct current resistivity
S-9	SLO-1	Insulation level at substation with protective zones	Breakdown in composite dielectrics-properties	Circuits for producing switching surge voltages	Rogowski coils, Magnetic links, Faraday Generator	Measurement of dielectric constant and loss factor. Partial discharge measurements
	SLO-2	Insulation Coordination in EHV and UHV systems	Mechanism of breakdown in composite dielectrics	Tripping and control of impulse generators- Trigatron gap	Cathode Ray Oscillographs for Impulse voltage and current measurements	Application of high voltage engineering in food processing and bio-medical industry

Learning Resources	1. Naidu.M.S, and Kamaraju, High Voltage Engineering, Tata McGraw Hill, 2014. 2. Wadhwa.C.L, High Voltage Engineering New age international publishers Ltd.-New Delhi 2010. 3. Ravindra Arora, Wolfgang Mosh, High Voltage and Electrical Insulation Engineering, Wiley-IEEE Press 2011.	4. G.V. Barbosa –Canovas, Pulsed electric fields in food processing: Fundamental Aspects and applications, CRC Publisher Edition March 2001. 5. H. L. M. Lelieveld and Notermans.S, et.al., Food preservation by pulsed electric fields: From research to application, Woodhead Publishing Ltd. October 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr. S. Paramasivam, Danfoss Industries Pvt. Ltd., paramsathya@yahoo.com	1.Dr. R. Sarathi, IITM, Chennai, sarathi@ee.iitm.ac.in	1.Dr. S. Padmini, SRMIST
2.Mr.srinath rao, Alstrom,sreenathr.rao@alstrom.com	2.Dr. P. Valsalal, Anna University , valsalal@annauniv.edu	2.Dr. A.Rathinam, SRMIST

Course Code	18EEE314T	Course Name	POWER QUALITY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the characterization of electric power quality	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Study the sources of power quality events such as voltage sag, short and long duration variations	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Explain the reduction of PQ problems using custom power devices and harmonic filters																		
CLR-4 :	Impart knowledge on various methods of power quality monitoring																		
CLR-5 :	Illustrate the power quality issues in distributed generation																		
CLR-6 :	Understand Power Quality events, Measuring equipments and their impact on Distributed Generation																		
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		1	75	75	H	-	-	-	-	-	-	M	-	-	-	-	-	-	M
CLO-1 :	Describe the causes and effects of power quality problems and categorize the various electrical power quality issues in power systems																		
CLO-2 :	Identify the power quality major events like voltage sag, interruptions and harmonics																		
CLO-3 :	Design and simulate the custom power devices and harmonic filters																		
CLO-4 :	Interpret in usage of various PQ measuring instruments																		
CLO-5 :	Identify the various power quality issues in solar system and wind energy conversion system																		
CLO-6 :	Analyze PQ issues in wind and solar energy system and utilize the monitoring equipments for PQ events	3	75	75	H	L	L	L	M	-	M	M	-	-	-	-	M	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to power distribution system	Sources of Sag and Interruptions	Fundamentals of harmonics	Introduction to Power Quality monitoring	Introduction to Distributed Generation Technologies
	SLO-2	Power quality: concepts and definition	Classification of Voltage sag	Sources of harmonics	Power Quality Monitoring considerations	Resurgence of DG
S-2	SLO-1	Characterization of Transients	Estimating Voltage Sag performance – Area of Vulnerability, Equipment sensitivity to voltage sags	Definitions: Average value - RMS value - True power factor - phase sequence - Fourier series	Perspective of Power Quality Measuring equipments	Perspectives on DG benefits
	SLO-2	Causes and effects of Transients	Transmission system sag performance evaluation, Utility distribution system sag performance evaluation	Numerical example for harmonic analysis	Overview of Power Quality measurement equipments	Perspectives on Interconnection
S-3	SLO-1	Characterization, causes and effects of Short duration variations – interruptions	Fundamental principles of protection	Voltage and current distortions, Harmonics indices - (THD and TDD)	Power Quality Measurement Equipment: Power line disturbance analyzer	Interface to the Utility System
	SLO-2	Characterization, causes and effects of Short duration variations – Sags and Swells	Solutions of voltage sag at the end user level	Harmonics standards (IEEE, IEC)	Spectrum analyzer and Harmonic analyzer,	Various types of electrical system interfaces
S-4	SLO-1	Characterization of Long duration variations	Voltage sag and interruption indices	Harmonics sources from commercial load	Flicker meters	Power Quality issues of DG
	SLO-2	Causes and effects of Long duration variations	Basic Reliability evaluation techniques	Harmonics sources from industrial nonlinear load	Disturbance analyzer	Various types of Power Quality issues affected by DG
S-5	SLO-1	Characterization of Voltage imbalance	Motor-Starting sags	Effect of harmonics distortion	Transducer requirements	Operating conflicts

		and Waveform distortion				
	SLO-2	Causes and effects of Voltage imbalance and Waveform distortion	Motor-starting methods	Impact on capacitors, transformers, motors, teleCommunications, energy and demand metering	Demonstration of harmonic analyzer	Description of Operating conflicts results in Power Quality problems
S-6	SLO-1	Characterization of Voltage fluctuation and Power Frequency variations	Utility System Fault-Clearing Issues	Devices for controlling Harmonics - Inline choke	Assessment of Power Quality Measurement Data	DG on Low-Voltage Distribution networks
	SLO-2	Causes and effects of Voltage fluctuation and Power Frequency variations	Overview of Transient Faults	Zig Zag transformer	Off-line and On-line Power quality data assessment	Integration techniques for DG on networks
S-7	SLO-1	CBEMA	Overview of Permanent Faults	Harmonic filters: Passive, Active and Hybrid filters	Application of Intelligent Systems to power quality monitoring	Siting DG
	SLO-2	ITI curves	Voltage sag Mitigation methods	Design of filters - simulation	Design of expert systems for monitoring applications	Discussion on optimal DG siting problem
S-8	SLO-1	Introduction to Power Quality standards	Mitigation of sag - Dynamic Voltage Restorer (DVR)	Harmonic analysis	Requirements on industry Power Quality monitoring applications	DG Interconnection standards
	SLO-2	International Standards of Power Quality	Principle and configuration of DVR	Illustration of Harmonic analysis with an Industry case study	Web based Power Quality monitoring system	Interconnection requirements
S-9	SLO-1	Introduction to Power Quality events	Mitigation of sag - Distribution static synchronous compensator (DSTATCOM)	Seminar on Harmonic analysis	Power Quality monitoring standards	Power Quality issues in grid integrated Solar system
	SLO-2	Computer simulation of Power Quality events	Principle and configuration of DSTATCOM	Recent advancement in Harmonic distortion analysis	IEEE 1159 and IEC 61000-4-30	Power Quality issues in grid connected wind energy conversion system

Learning Resources	1. Roger C. Dugan, Mark Mc Granaghan, Surya Santoso, H.Wayne, H. Wayne Beaty, <i>Electrical Power Systems Quality</i> , Tata McGraw Hill, Third edition, 2012. 2. Math H J Bollen, <i>Understanding Power Quality Problems: Voltage Sags and Interruptions</i> , IEEE Press, New York, 2000.	3. Arindam Ghosh, <i>Power Quality Enhancement Using Custom Power Devices</i> , Kluwer Academic Publishers, 2002. 4. G.T.Heydt, <i>Electric Power Quality</i> , Stars in a Circle Publications, second edition, 1994. 5. https://nptel.ac.in/courses/108106025/Power%20quality_in_power_distribution_systems.pdf .
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Learning Assessment											
	Bloom'sLevel of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.K.Karthikeyan, ABB India Ltd., k.karthikeyan@in.abb.com	1. Dr.B.Chitti Babu, IIITDM Kanchipuram, bcbabu@iiitdm.ac.in	1. Dr.R.Ramya, SRMIST
2. Mr.Manjunath rao, Alstrom,manjunath.rao1103@gmail.com	2. Dr.K.Selvi, Thiagarajar College of Engineering, Madurai, kseee@tce.edu	2. Mr.D.Ravichandran, SRMIST

Course Code	18EEE315T	Course Name	SMART GRID	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Describe the architecture of smart grid, standards and policies				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Examine the issues with renewable energy integration and energy management system				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Enrich the students with knowledge on measurement techniques in smart grid																					
CLR-4 :	Understand power system studies in smart grid																					
CLR-5 :	Acquire knowledge on Communication networks and security challenges																					
CLR-6 :	Understand the management and control of smart grid																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			1	2	3	H	L	-	-	-	-	M	H	-	-	-	-	M	H	M
CLO-1 :	Understand the smart grid architecture and standards				2	80	75	H	L	-	-	-	-	M	H	-	-	-	-	M	H	M
CLO-2 :	Analyze the issues with renewable energy integration				2	80	75	H	M	-	-	M	-	-	-	-	-	-	-	M	H	-
CLO-3 :	Apply measurement techniques in smart grid				1	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	H	M
CLO-4 :	Explain the power system studies in smart grid				1	80	75	H	L	-	-	M	-	M	H	-	-	-	-	M	H	M
CLO-5 :	Summarize Communication networks and security issues																					
CLO-6 :	Apply management and control strategies in smart grid																					

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Evolution of Electric Grid	Necessity of renewable power generation	Importance of measurement in smart grid	Basics of load flow studies	Role of Communication infrastructures in smart grid
	SLO-2	Definitions and Need for Smart Grid	Benefits of renewable generation in smart grid	Measurement parameters in smart grid	Extended load flow studies in smart grid	Types of Communication infrastructures
S-2	SLO-1	Basics of smart grid	Importance of PV system	Introduction to Smart Meters	Necessity of voltage stability analysis	Elements of data Communication networks
	SLO-2	Comparison of Power grid with Smart grid power system	Grid integration issues of PV system	Block diagram of smart meters	Voltage stability analysis in smart grid	Standards of data Communication networks
S-3	SLO-1	Smart grid components	Importance of wind system	Communication infrastructure for smart metering	Importance of state estimation	Wired networks in smart grid
	SLO-2	Smart grid drivers/functions	Grid integration issues of wind system	Communication protocols for smart metering	Approach of smart grid to state estimation	Wireless networks in smart grid
S-4	SLO-1	Opportunities, challenges and benefits	Basics of energy storage system	Basics of AMI drivers	Necessity of optimization techniques	Functional groups of smart grid Communications
	SLO-2	Functions of Smart Grid Components	Operation of independent Large-Scale Battery Storage system	Benefits of AMI drivers	Optimization techniques in smart grid-case study	Types of Communications in smart grid
S-5	SLO-1	Wholesale energy market in smart grid	Necessity of Battery management system	Necessity of WAMS network	Different intelligent techniques	Characterization of smart grid data
	SLO-2	Advantages of building integrated and distributed power systems	Types of Battery management system in smart grid	Wide area measurement system in smart grid	Applications of computational intelligence in smart grid	Secure data management in smart grid
S-6	SLO-1	Approach to smart grid interoperability standards	Necessity of energy management system	Introduction to Phasor measurement units	Transmission system automation	Applications of smart grid data

	SLO-2	IEEE standards for Smart Grid	Energy management system in smart grid	Architecture of Phasor measurement units	Components of transmission system automation	Impact of bad data in smart grid data
S-7	SLO-1	International policies in Smart Grid	Basics of demand side management	Communications in PMUs	Distribution system automation	Data cleaning in smart grid data
	SLO-2	National and International Initiatives in Smart Grid	Demand side management in smart grid	Implementation of dynamic visualization system for real time power system data	Components of Distribution system automation	Smart grid network interoperability
S-8	SLO-1	Operation of smart grid	Basics of demand response	Smart buildings in smart grid	PHEV in distribution network	Basics of cyber security
	SLO-2	Control strategies of smart grid	Demand response issues in smart grid	Components in smart buildings	Charging strategies in PHEV	Cyber security issues in smart grid
S-9	SLO-1	Basics of microgrid	Study of power quality parameters	ASHRAE standard for smart buildings	Discharging strategies in PHEV	Types of cyber attacks
	SLO-2	Micro grid importance in smart grid	Power quality issues associated with renewable energy in smart grid	Multi agent systems in smart grid	Impact of PHEV on the grid	Mitigation approach to cyber security attacks

Learning Resources	<ol style="list-style-type: none"> 1. James Momoh, Smart Grid: Fundamentals of design and analysis, John Wiley & sons Inc, IEEE press 2012. 2. Janaka Ekanayake, Nick Jenkins, Kithsiri Liyanage, Jianzhong Wu, Akihiko Yokoyama, Smart Grid: Technology and Applications, John Wiley & sons inc, 2012. 3. Fereidoon P. Sioshansi, Smart Grid: Integrating Renewable, Distributed & Efficient Energy, Academic Press, 2012. 4. Clark W.Gellings, The smart grid: Enabling energy efficiency and demand response, Fairmont Press Inc, 2009. 5. Kenneth C.Budka, Jayant G.Deshpande, Marina Thottan, and Communication networks for smart grids, Springer, 2014. 6. https://onlinecourses.nptel.ac.in/noc18_ee42/course
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Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Apply	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Analyze										
	Evaluate										
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Sudharsan, L&T, sudharsand@Intecc.com	1. Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekr.ac.in	1. Dr.J.Preetha Roselyn, SRMIST
2. Dr.K.Karthikeyan, ABB India Ltd., k.karthikeyan@in.abb.com	2. Dr. R.Ramesh, CEG, rramesh@annauniv.edu	2. Dr.K.Vijayakumar, SRMIST

Course Code	18EEE316T	Course Name	VEHICULAR POWER SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the importance of electric transportation system and the basics of electric vehicle components and design				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Acquire knowledge on battery technologies in transportation				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Gain knowledge on charging and starting systems in vehicular application							H	L	L	-	-	-	-	-	-	-	-	-	-	-	L	L	-
CLR-4 :	Explain the importance of fuel cell and application							H	M	H	-	-	-	-	-	-	L	-	-	-	-	H	M	-
CLR-5 :	Examine the working and control of electric propulsion systems							H	-	M	-	-	-	-	-	-	L	-	-	-	-	H	M	-
CLR-6 :	Create overall structure of vehicular power system							H	L	M	-	-	-	-	-	-	L	-	-	-	-	M	M	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Examine on different transportation development strategies and architecture of hybrid drive train				2	80	75																	
CLO-2 :	Understand the construction, working and maintenance of battery				2	80	75																	
CLO-3 :	Summarize the charging and starting systems principle, diagnosing and advancements in automotive				2	80	75																	
CLO-4 :	Interpret the fuel cell structure, operation, types and characteristics of fuel cell technology				2	80	75																	
CLO-5 :	Outline different electric drives and its control techniques				2	80	75																	
CLO-6 :	Understand a vehicle's power system using components like energy storage system and power converters				2	80	75																	

Duration (hour)	9	9	9	9	9
S-1	SLO-1	History of modern transportation	Introduction to energy storage systems	Requirements of charging system	Structure and operation of fuel cell
	SLO-2	Importance of different transportation development strategies to future oil supply	Battery requirements for HEVs, PHEVs and EVs	Charging system principles	Types of fuel cell (PAFC and PEM)
S-2	SLO-1	History of hybrid electric vehicles	Working principle and construction of lead-acid, nickel cadmium	Alternators basics and working	Types of fuel cell (MCFC and SOFC)
	SLO-2	History of electric vehicles	Working principle and construction of nickel cadmium	Charging circuits basics and working	Types of fuel cell (DMFC, AFC and ZAFC)
S-3	SLO-1	Social and environmental importance of hybrid and electric vehicles	Working principle and construction of nickel metal hydride	Charging system testing instruments	Fuel cell based power processing systems introduction
	SLO-2	Key challenges of hybrid and electric vehicles	Working principle and construction of lithium ion batteries	Diagnosing charging system faults	Benefits of power processing systems
S-4	SLO-1	Specifications of PHEVs, BEVs, EVs and HEVs	Properties of battery	New developments in charging systems	Important properties of fuel cells for vehicles
	SLO-2	The future of electric vehicles	Characteristics of battery	Advanced charging systems	Alternate fuels for fuel cell vehicles
S-5	SLO-1	Requirement of drive train	Maintenance of battery	Requirements of starting systems	Fuel cost and fuel economies comparison
	SLO-2	Sizing of components in drive train	Visual inspection of battery	Starter motors and its circuits	Comparison of characteristics of fuel cells
S-6	SLO-1	Series configuration of HEVs	Battery testing instruments	Inertia starter and pre-engaged starter	Fuel cell based drive trains

	SLO-2	Parallel configuration of HEVs	Diagnosing battery faults	Permanent magnet starter, integrated starter generator and electronic starter	Comparison of BEV, DHFC/EV and DMFC/EV	Implementing control techniques for BLDC motor drive
S-7	SLO-1	Power split configuration of HEVs	Introduction to supercapacitor	Starting system testing instrument	Transition from diesel to fuel cell engines	Sensorless control for BLDC drive introduction
	SLO-2	Merits and Demerits of different HEV configurations	Introduction to flywheel	Diagnosing in starting system faults	Fuel cell/battery hybrid power system	Different control techniques for BLDC drive introduction
S-8	SLO-1	Vehicle dynamics	Advanced battery technology	Advanced starting system technology	Fuel cell in domestic application	Switched reluctance motor drives principle of operation
	SLO-2	Problems using vehicle dynamics	Developments in electrical storage	New developments in starting systems	Fuel cell in industrial application	Analysis of switched reluctance motor drives performance
S-9	SLO-1	Modelling electric vehicle range	Case studies on battery technologies	Case studies in charging and starting systems	Case studies on fuel cell technologies	Control techniques of switched reluctance motor drive
	SLO-2	Problems under vehicle travel range	Software implementation of battery and its applications	Software implementation of charging and starting systems	Software implementation of fuel cell and its applications	Implementing control techniques for switched reluctance motor drive

Learning Resources	<ol style="list-style-type: none"> 1. A. Emadi, M. Ehsani and John M. Miller, Vehicular Power Systems, Marcel Dekker, New York, 2004. 2. Ion Boldea and S.A Nasar, Electric drives, CRC Press, 2005. 3. Sandeep Dhameja, Electric Vehicle Battery Systems, Newnes, 2002. 4. Chris Mi, M. Abul Masrur, David Wenzhong Gao, Hybrid Electric Vehicles: Principles and Applications with Practical Perspectives, Wiley, 2011. 5. Iqbal Husain, Electric and Hybrid Vehicles: Design Fundamentals, CRC Press, 2nd Edition, 2010. 6. https://www.diyguru.org/course/electric-vehicle/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Sambath, TANGEDCO, Tamilnadu, eses.eng@gmail.com	1. Dr. Chandramohan, CEG, Anna University, c_dramo@annauniv.edu	1. Mrs. A. Geetha, SRMIST
2. Mr. Sudharsan, L&T, sudharsand@Intecc.com	2. Dr. P. Somasundaram, CEG, Anna University, mpsomasundaram@annauniv.edu	2. Dr. C. Subramani, SRMIST

Course Code	18EEE407T	Course Name	POWER SYSTEM HARMONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																	
CLR-1 :	Understand the fundamentals and standards of harmonics	1	2	3	Thinking (Bloom)	Proficiency (%)	Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Study the various sources of harmonics							Engineering Knowledge	Analysis	Development	Design,	Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Team Work	Communication	Management & Finance	Life Long Learning						
CLR-3 :	Enumerate the effects of harmonics in various equipments																								
CLR-4 :	Classify the methods of power system harmonics mitigation																								
CLR-5 :	Explore the approach of harmonics system study																								
CLR-6 :	Develop an overall knowledge about harmonics in power system																								

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Identify the harmonic indices and study the characteristics of harmonics	2	80	75	H	-	-	-	-	-	-	H	-	-	-	-	-	-	H
CLO-2 :	Understand the level of harmonics in equipments and devices	3	80	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Familiarize the harmonics effects in critical loads and equipments	3	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-4 :	Study and compare the various filters used for harmonics mitigation	3	80	75	H	H	M	-	-	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Simulate the harmonics analysis in a low/medium voltage system	3	80	75	H	H	M	M	-	-	-	-	-	-	-	-	M	M	-
CLO-6 :	Design a harmonic mitigation for the industrial and commercial applications	3	80	75	H	H	M	M	-	-	-	M	-	-	-	-	M	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction	Traditional sources	Harmonics effects – Thermal losses	Harmonics Filters	Harmonics modeling of system components - Generator,
	SLO-2	Basics of harmonic theory	Transformers	Copper, core and dielectric losses	Passive filters	Harmonics modeling of Shunt capacitors
S-2	SLO-1	Representation of Harmonics	Rotating machines	Harmonics effects on power system equipment	Single tuned filters	Harmonics modeling of Loads
	SLO-2	Fourier series – coefficients	Arc furnaces	Capacitor bank	Double tuned filters	Harmonics modeling of Induction motor
S-3	SLO-1	Fourier transform	Modern sources	Transformers	Damped filters	Harmonics modeling of Transformer with network
	SLO-2	Discrete Fourier transform (DFT)	Power electronics devices	Neutral grounding overloading	Detuned filters	Harmonics modeling of Transformer with different configuration
S-4	SLO-1	Fast Fourier transform (FFT)	Rectifiers	Rotating machines	Series tuned filter design	Harmonics modeling of Transmission line model
	SLO-2	Examples of harmonic estimation using FFT	A.C. Regulators	Pulsating torque	Impedance plot of series tuned filter design	Harmonics modeling of Transmission line with network
S-5	SLO-1	Characteristics of harmonics in power system – Symmetry	Power converters – Six pulse converters	Power electronics devices	Second order damped filters	Examples – transmission line
	SLO-2	Phase sequence	Six pulse converters - Analysis	Power converters	Impedance plot of second order damped filter design	Examples – Problems on load
S-6	SLO-1	Voltage and current distortion factors - Total harmonic distortion (THD)	Twelve pulse converters	Harmonics on power system protection	Active filters	Harmonics analysis using spread sheet

	SLO-2	Real, Reactive and Apparent power	Twelve pulse converters - Analysis	Unexpected relay operation	Characteristics of active filters	Analysis of harmonics analysis using spread sheet
S-7	SLO-1	Distortion power; Power factor	Inverters	Harmonics effects on consumer equipment	Other methods of mitigation	Simulation of harmonics analysis
	SLO-2	Total influence factor (TIF) and I*T Product	Cycloconverters	UPS	Transformer connection	Harmonics resonance
S-8	SLO-1	Voltage THD limits – IEEE standards	Thyristor controlled reactors	Lighting loads	Network topology reconfiguration	Simulation of harmonics filters
	SLO-2	Voltage THD limits – IEC standards	Static VAR compensator	Electronics devices	Increase of supply mode stiffness	Analysis of simulation output of harmonics filters
S-9	SLO-1	Current THD limits – IEEE standards	Effect of transformer connection on harmonics	Harmonic interference with Communication	Harmonic cancellation through use of multi pulse converters	Case study
	SLO-2	Current THD limits – IEC standards	Star-Delta and Delta-Star	Microwave links, telephone interference	Series reactor as harmonic attenuator elements	Analysis of Case study

Learning Resources	1. Power system harmonics ,Fundamentals, Analysis and filter design – George J. Wakileh – Reprinted 2010 2. Power system harmonics, J. Arrillaga and N.R.Watson 1998 – Reprinted 2000 3. Power system harmonics, Francisco_De_La_Rosa – 2006	4. Electrical power system quality, R C Dugan, Mark F.Mcgranaghan, Surya Santoso, H.Wayne Beaty 5. Harmonics analysis software user manual 6. https://web.ecs.baylor.edu/faculty/grady/Understanding_Power_System_Harmonics_Grady_April_2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. K. Karthikeyan, ABB Ltd., k.karthikeyan@in.abb.com	Dr.B.Chitti Babu, IIIT, bcbabu@iiitdm.ac.in	Mr. D.Ravichandran, SRMIST, ravichandran.d@ktr.srmuniv.ac.in
Dr. Swaroop Gajare, Power Systems Technologies, Eaton Research Labs	Dr. M.M. Rajan Sing ravel, NIT, rajan.singaravel@nitpy.ac.in	Dr. M. Senthilkumar, SRMIST, senthilkumar.mu@ktr.srmuniv.ac.in

Course Code	18EEE408T	Course Name	HVDC AND EHVAC SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	i	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Outline the concepts of Extra High Voltage transmission systems				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Explain the general background and operational concepts in EHVAC Transmission Systems				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Give idea about the factors affecting EHV transmission and the protection of EHV lines							H	-	-	-	-	-	M	L	-	-	-	-	-	M	M	L	
CLR-4 :	Impart knowledge about HVDC Transmission systems							H	M	M	-	-	-	-	-	-	-	M	-	-	-	M	M	-
CLR-5 :	Expose to the concept of harmonics and basis of protection for HVDC Systems.							H	-	-	-	-	-	-	-	M	M	-	-	-	-	M	M	-
CLR-6 :	Know the detailed background of extra high voltage AC transmission and high voltage DC transmission							H	M	M	-	M	-	M	L	M	M	-	-	H	M	L		
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						2	80	75	H	M	M	-	-	-	-	-	-	-	-	-	M	M
CLO-1 :	Understand the basic concepts of Extra High Voltage Transmission.				3	80	75	H	M	M	-	-	-	-	-	-	-	-	M	M	-			
CLO-2 :	Analyze the general background of EHVAC Transmission Systems				3	80	75	H	M	M	-	-	-	M	L	-	-	-	M	M	L			
CLO-3 :	Acquire knowledge in operational concepts and protection in EHVAC Transmission Systems				3	80	75	H	-	-	-	-	-	-	-	M	-	-	M	M	-			
CLO-4 :	Infer the significance of HVDC Transmission and its modern trends and applications.				3	80	75	H	M	M	-	M	-	-	-	-	-	-	M	M	-			
CLO-5 :	Gain idea in the general principle of HVDC control and harmonic elimination in HVDC Systems				3	80	75	H	M	M	-	M	-	-	-	-	-	-	M	H	-			
CLO-6 :	Interpret the operational concepts of high voltage AC and DC transmission				3	80	75	H	M	M	-	M	-	M	L	M	M	-	-	H	M	L		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Brief Description of Energy Sources	Power handling capacity of AC transmission line	Effects of corona	Choice of HVDC Transmission	Pulse number
	SLO-2	Development of Energy sources	Line losses of AC transmission line	Attenuation of travelling waves due to corona loss	Basic outline of HVDC Transmission	Choice of Converter Configuration
S-2	SLO-1	Introduction to EHV transmission	Introduction to mechanical considerations in transmission line performance	Generation of audible noise	Comparison of Economics, Technical Performance of DC power Transmission	Introduction to Graetz circuit
	SLO-2	Standard Voltage levels of Transmission systems	Types of vibrations and oscillations	Characteristics and its limitations of audible noise	Comparison of Reliability of DC power Transmission	Simplified analysis of Graetz circuit
S-3	SLO-1	Hierarchical levels for Transmission systems	Concept of bundled conductors	Generation of corona pulses	Description of HVDC transmission system	Concept of HVDC link Control
	SLO-2	Costs of Transmission Lines And Equipment	Properties of Bundled conductors	Properties of corona pulses	Types of HVDC links	Principles of HVDC link control
S-4	SLO-1	Necessity for EHV transmission	Surface voltage gradient on single conductor bundles	Limits for radio interference fields	Components of a Converter station	DC Breaker – Basic concepts of DC circuit interruption
	SLO-2	Challenges involved in EHV transmission	Derivation of Surface voltage gradient on single conductor bundles	Evaluation of radio interference using Cigre Formula	Description of a Converter station	DC Breaker – Characteristics and Application
S-5	SLO-1	Operational Aspects of EHV AC transmission	Surface voltage gradient on double conductor bundles	Concept of RL filter to block corona energy	Basic concepts of multi-terminal HVDC system.	AC Filter – Criteria of design
	SLO-2	Electrical characteristics of EHV cables	Derivation of Surface voltage gradient on double conductor bundles	Design of RL filter	Types and potential applications of multi-terminal HVDC system.	AC Filter – Ratings of filter components and protection of filters
S-6	SLO-1	Gas insulated EHV transmission lines	Basic concepts of reactive power	Interference to TV reception from EHV	Effects of proximity of ac and dc	DC Filter – Criteria of design

			compensation	lines	transmission lines	
	SLO-2	Properties of SF ₆ gas	Principles of shunt compensation	Discharges from an EHV line causing television interference	HVDC transmission based on Voltage Source Converters	DC Filter –Hybrid active filter for DC filtering
S-7	SLO-1	Effect of Power-Frequency Magnetic Fields on Human Health	Principles of series compensation	Concept of lightning strokes	Merits of HVDC System	Protection Against Over Currents, Over Voltages
	SLO-2	Effect of High Electro Static Field on Humans, Animals, and Plants	Sub-synchronous resonance in compensated lines	General principles of the lighting protection problem	Limitations of HVDC System	Protection Systems in HVDC Substation
S-8	SLO-1	Introduction to line parameters	Counter measures for Sub-synchronous resonance problem	Arresters used for EHV systems	Applications of HVDC transmission	Necessity of simulation of a dynamic system
	SLO-2	Determination of resistance of EHV lines	Improvement of system performance due to reactive power compensation.	Protective characteristics of lightning arresters	Modern Trends in HVDC transmission	Tools for simulation of a dynamic system
S-9	SLO-1	Determination of inductance of EHV lines	Comparison of Overhead and Underground lines	Operating characteristics of lightning arresters	Seminar on case Studies of HVDC links in the world- I	Digital Dynamic Simulation of Converters
	SLO-2	Determination of capacitance of EHV lines	Examples of Giant power pools in the world	Insulation Coordination based on lightning	Seminar on case Studies of HVDC links in the world- II	Digital Dynamic Simulation of DC Systems

Learning Resources	1. Rakosh Das Begamudre, Extra High Voltage AC Transmission Engineering, Fourth Edition , New Age International(P) Limited,Publishers.,2011 2. Padiyar K.R., HVDC Power Transmission Systems, Third Edition,New Age International (P) Limited Publishers.,2015.	3. Chakrabarti. A , M.L.Soni,P.V.Gupta,U.S.Bhatnagar, PowerSystem Engineering, DhanpatRai& Co., 2010. 4. Sunil S.Rao, Switchgear Protection and Power Systems,13 th edition, Khanna Publishers,2008. http://www.nptelvideos.com/course.php?id=480
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr.K.Karthikeyan, ABB India Ltd., k.karthikeyan@in.abb.com	1. Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekgjr.ac.in	1. Ms. E. Annie Grace, SRMIST
2. Mr.Senthilkumar,ATI,rskrd1962@gmail.com	2.Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	2. Dr. S. Padmini, SRMIST

Course Code	18EEE409T	Course Name	POWER SYSTEM DYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :		Enumerate the significance of stability study and its classification			H	H	-	-	-	-	-	-	-	-	-	-	M	M	-
CLR-2 :		Explain the concept of detailed modelling of synchronous machine for stability studies			H	H	L	H	H	-	-	-	-	-	-	-	M	M	-
CLR-3 :		Understand and model the various excitation system			H	H	L	H	H	-	-	-	-	-	-	-	M	M	-
CLR-4 :		Examine the small-signal stability study of single-machine infinite bus (SMIB) system			H	H	H	H	H	-	-	-	-	H	-	-	M	M	-
CLR-5 :		Discuss the Sub-synchronous oscillations and countermeasures for small-signal stability			H	H	H	H	-	-	-	-	-	-	-	-	M	M	-
CLR-6 :		Develop the mathematical model of synchronous machine and assessment of small-signal stability			H	H	H	H	H	-	-	-	-	H	-	-	M	M	-
Course Learning Outcomes (CLO):		Level of Thinking (Bloom)																	
		1	2	3															
CLO-1 :		Explain the basics of stability analysis and its types	1	75	75														
CLO-2 :		Apply the idea of Park's transformation and express the voltage and flux linkage equation, torque and power equation of synchronous machine in rotor reference frame.	3	75	75														
CLO-3 :		Describe the excitation system, types and its modelling for stability studies	3	75	75														
CLO-4 :		Analyze the small-signal stability for the SMIB system with classical model of synchronous machine	3	75	75														
CLO-5 :		Infer Sub-synchronous oscillations and the enhancement methods of small-signal stability	3	75	75														
CLO-6 :		Design the mathematical model of synchronous machine and evaluate the small-signal stability	3	75	75														

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction –Basic elements of power system	Introduction to Three phase synchronous machine	Excitation system requirements	Small-signal stability of dynamic Systems	Introduction to Sub-synchronous oscillations
	SLO-2	Structure of power system-power system control	RMF, MMF waveform	Basic functions of Excitation system	Local, finite and global stability	Turbine-generator torsional characteristics
S-2	SLO-1	Operating states of power system and control strategies	Winding model	Elements of an excitation system	Linearization	Structure of typical lumped mass shaft system model
	SLO-2	Normal design contingencies	Modelling assumptions,	Control functions of an excitation system	State-space representation	Shaft model representation
S-3	SLO-1	System design for stability	Sign convention	Protective functions of an excitation system	Mathematical analysis of stability	Equations of inertia constant-Torsional stiffness-Damping coefficient
	SLO-2	Classifications of stability	Stator voltage equations in abc coordinates	Types of Excitation System (ES)	Eigen properties of the state matrix	Derive the Shaft system equations between turbine and generators
S-4	SLO-1	The stability phenomena: small-signal and transient stability	Rotor voltage equations in abc coordinates	DC excitation system-(DC1A)	Eigenvalues of the state matrix	Computation of damping and stiffness coefficient for a five mass model system
	SLO-2	Basic assumptions made in stability studies	Stator flux linkage equations in abc coordinates	DC excitation system with amplidyne	Eigenvectors, participation factor, modal matrices	Computation of each shaft section torque for a five mass model system
S-5	SLO-1	Rotor dynamics and the swing equation	Rotor flux linkage equations in abc coordinates	AC Excitation system	Eigenvalues and stability-trajectory behaviour	Torsional natural frequencies
	SLO-2	Transient stability- Illustrate with Single machine connected to infinite bus (SMIB) system	Stator self-inductance calculation	Field-Controlled Alternator Rectifier ES	Mode shape and participation factor.	Example of torsional characteristics of coal-fired unit with static exciter

S-6	SLO-1	Numerical problem on transient stability analysis of SMIB system	Stator to rotor Mutual-inductance calculation	Stationary rectifier based AC Exciter	Controllability and observability-concept of complex frequency	Small-signal stability enhancement-methods
	SLO-2	Power versus rotor angle curve, Power-rotor angle equations-(during a fault, after fault clearing and removal of the faulted circuit)- Numerical problem	Rotor to Stator Mutual-inductance, Rotor self –inductance calculation	Alternator-supplied controlled-rectifier ES	State-space form of Synchronous machine's swing equation	Different types of Power system stabilizers (PSS)- Need of PSS
S-7	SLO-1	Transient stability assessment of SMIB system by Equal-Area Criterion	Park's transformation	Rotating type- Brush less Excitation system	Case study on small signal stability analysis of Single-Machine Infinite Bus (SMIB) with classical machine model	Stabilizers based on shaft speed signal
	SLO-2	Computation of Critical clearing angle-critical clearing time-Numerical problem	Voltage and flux linkage equations in dqo reference frame (Park's equations)	Static Excitation system	Block diagram representation of SMIB system	Delta-P-Omega stabilizer
S-8	SLO-1	Introduction to Voltage stability	Steady state analysis-voltage, Current, and flux linkage relationships.	Potential-source controlled rectifier-static type excitation system	Calculation of synchronizing torque coefficient, system matrix, eigenvalues and participation factor	Frequency based stabilizer, Digital stabilizer
	SLO-2	Voltage collapse- Illustrate with two bus radial system	Phasor representation-Steady state equivalent circuit.	Modelling and computer simulation of excitation system	The effect of damping torque in the stability of SMIB system with classical machine model	Enhancement of stability by Excitation control design
S-9	SLO-1	Large disturbance and small disturbance	Simplified model (constant flux linkage)- Classical machine model.	Detailed excitation system model- DCIA	Speed and rotor angle time response of SMIB system with classical machine model	Exciter gain, Phase-lead compensation, stabilizing signal washout, Stabilizer gain-Stabilizer limits
	SLO-2	Voltage stability- Mid-term and Long-term stability	Steady State analysis of Synchronous machine using simulation software	AC1A and AC4A model of excitation system	Synchronous machine model using suitable simulation software	General observation on excitation control design

Learning Resources	<p>1. P.Kundur, Power System Stability and Control, McGraw Hill Inc, New York, 1995.</p> <p>2. R.Ramanujam, Power System Dynamics: Analysis and Simulation, PHI Publishers, Delhi, 2nd edition 2013.</p> <p>3. M.A.Pai and W.Sauer, Power System Dynamics and Stability, Pearson Education Asia, India, 2002.</p>	<p>4. K.R.Padiyar, Power System Dynamics, Stability & Control, 2nd Edition, B.S. Publications, Hyderabad, 2002.</p> <p>5. P.M Anderson and A.A Fouad, Power System Control and Stability, Iowa State University Press, Ames, Iowa, 1978.</p> <p>6. https://nptel.ac.in/courses/108102080/</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr. Sharon Ravichandran, ABB Ltd., Chennai,sharonravi87@gmail.com	1. Prof. K.Shanthi Swarup, IITM, Chennai, ksswarup@iitm.ac.in	1.Mr. D. Maharajan, SRMIST
2.Dr.V.P.Boopathi, Powersys., Chennai,Boopathivp@gmail.com	2.Prof. R.P.Kumudini Devi, Anna University, kumudini@annauniv.ac.in	2.Dr. D. Sattianandan, SRMIST

Course Code	18EEE410T	Course Name	MODERN POWER SYSTEM ANALYSIS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC303T	Co-requisite Courses	NIL	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Explain the numerical method involved in for optimal power flow analysis				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyse the significance of contingency analysis and power system security states				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Outline the concepts of distribution system																					
CLR-4 :	Understand and analyze the different concepts of stability																					
CLR-5 :	Demonstrate the concepts of state estimation of power systems																					
CLR-6 :	Evaluate the overall analysis of power system problems starting from transmission to distribution																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)															
CLO-1 :	Acquire the knowledge on the numerical methods of optimal power flow analysis				3	75	75	H	M	M	M	M	-	-	-	-	-	-	-	M	M	-
CLO-2 :	Analyse the concepts of power system security				3	75	75	H	M	M	M	M	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Familiarize the knowledge on distribution system and its application				3	75	75	H	M	M	M	M	-	-	-	-	-	-	-	M	M	-
CLO-4 :	Categorize the study of stability analysis				3	75	75	H	M	M	M	-	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Gain knowledge on the concept of state estimation in power systems				3	75	75	H	L	L	-	-	-	-	-	-	-	-	-	M	M	-
CLO-6 :	Create ,design and analyze the power system issues starting from transmission to distribution				3	75	75	H	M	M	M	M	-	-	-	-	-	-	-	M	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Formulation of power flow problem	Overview of security analysis	Basic concepts of stability	Introduction - Primary distribution systems	Need for state estimation
	SLO-2	Solution through Newton-Raphson method	Need for Power system Security	Classifications of stability	Types of primary distribution systems	Basic methods of state estimation
S-2	SLO-1	Problems solving- Newton-Raphson method	Factors affecting power system security	Small signal stability of a single machine infinite bus system	Secondary distribution systems	Comparison of power flow and state estimation problems
	SLO-2	Fast decoupled power flow solutions	Introduction to Contingency analysis	Small signal stability-solving numerical	Types of Secondary distribution systems	Least Square State Estimation
S-3	SLO-1	Problems solving-Fast Decoupled method	Contingency analysis-Addition and removal of one line	Transient stability-Runge kutta method	Ring main distribution systems	Weighted Least Square State Estimation
	SLO-2	Comparison of Load flow methods	Computation of bus impedance matrix from bus admittance matrix	Runge kutta method - Solving numericals	Ring main distribution systems-solving numerical	State estimation from Non-linear measurements
S-4	SLO-1	Power flow studies-simulation	Problem solving-contingency analysis	Runge kutta method - Solving numericals	Load flow of radial distribution networks-solving numerical	Static state estimation for power systems
	SLO-2	Power flow studies-simulation	Problem solving-contingency analysis	Runge kutta method - Solving numericals	Load flow of radial distribution networks - solving numerical	Weighted Least Square State Estimation –solving numericals
S-5	SLO-1	DC power flow solutions	Calculation of new bus voltage due to addition and removal of one line-simulation	Transient stability- Simulation	General design characteristics of distribution system	Detection of bad measurements
	SLO-2	AC-DC power flow model	Solving numericals	Voltage stability	Primary distribution system - design	Identification of bad measurements
S-6	SLO-1	Optimal Power Flow-Introduction	Linear sensitivity factors	Transmission characteristics	Primary distribution system - design	Detection and identification of bad measurements

	SLO-2	Gradient method	Problem solving-Linear sensitivity factors	Transmission characteristics	Voltage, scheme and feeder size selection	Solving numerical
S-7	SLO-1	Problem solving-Gradient method	Problem solving-Linear sensitivity factors	Generator characteristics	Secondary distribution system - design	Network observability
	SLO-2	Newton's method	AC power flow method	Generator characteristics	Lamp flicker-Origin	Problem solving Network observability
S-8	SLO-1	Security constrained optimal power flow	Problem solving-AC power flow method	Load characteristics	Types of flicker and remedial measures	Pseudo measurements
	SLO-2	Optimal generation scheduling	Contingency selection	Load characteristics	Design of capacitors to distribution systems	State estimation including Phasor measurement units
S-9	SLO-1	Problem solving-optimal generation scheduling	Contingency ranking	Characteristics of reactive compensating devices.	Design of capacitors to distribution systems-solving numerical	State estimation including Phasor measurement units
	SLO-2	Optimal unit commitment	Security analysis and contingency evaluation	Typical scenario of voltage collapse	Design of capacitors to distribution systems-solving numerical	Application of state estimation in power system in load forecasting

Learning Resources	<ol style="list-style-type: none"> 1. Pai M.A. and Dheeman Chatterjee, Computer Techniques in Power System Analysis, Mc Graw Hill Education (India) Private Limited, New Delhi, 2016. 2. John.J.Grainger, William D. Stevenson, Jr, Power System Analysis, Mc Graw Hill Education (India) Private Limited, New Delhi, 2015. 3. Allen Wood J. and Bruce.F. Wollenberg, Power Generation Operation and Control, 2nd Edition, John Wiley & Sons, New York, 1996. 4. Prabha Kundur, Power system stability and control, Electrical power research institute-power system engineering series. 5. Mukhtar Ahmad, Power System State Estimation, Lap Lambert Acad Publishers, 2013.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr.V.P.Boopathi, Powersys., Chennai, Boopathivp@gmail.com	1.Dr. K. S. Swarup, IITM, Chennai, ksswarup@iitm.ac.in	1.Dr. S. Padmini, SRMIST
2.Dr. T. Prakash, TNEB, Mt. Road, prakash.thyagarajan@tnebnet.org	2.Dr. P. Somasundaram, Anna University, mpsomasundram@annauniv.edu	2.Dr. K. Vijayakumar, SRMIST

Course Code	18EEE411T	Course Name	POWER SYSTEM DEREGULATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning				
		1	2	3					
CLR-1 :	Understand the basics of deregulation and economics of power system	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development		
CLR-2 :	Learn Unit commitment, optimal power flow and its constraints				Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics
CLR-3 :	Understand the activity of GENCO and independent system operator				Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1
CLR-4 :	Get familiarized with the various transmission services				PSO - 2	PSO - 3			
CLR-5 :	Gain knowledge on the role of security and congestion management in deregulated power system.								
CLR-6 :	Create overall restructuring of power system starting from generation to power transmission and distribution								
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:							
CLO-1 :	Illustrate the basics of deregulation in conventional power system	2	75	75	H	H	-		
CLO-2 :	Use the concept of Unit commitment, optimal power flow in electric power system	2	75	75	H	H	-		
CLO-3 :	Apply the knowledge on the various role of ISO in deregulated environment	2	75	75	H	M	-		
CLO-4 :	Analyze various transmission system problems	2	75	75	H	M	-		
CLO-5 :	Utilize the basic role of security and congestion management and its solutions	3	75	75	H	M	M		
CLO-6 :	Analyze the power system generation and transmission losses with various components in deregulated system	3	75	75	H	M	M		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction- Deregulation	Optimal Power Flow problem model	Operational planning activities of ISO	Embedded cost based transmission pricing	Introduction to Congestion,
	SLO-2	Structure of a deregulated electricity system	Limits on Real and Reactive power flow	Single Auction Market	Postage stamp method	Reasons for transfer capability limitation
S-2	SLO-1	Different entities in deregulated electricity markets	OPF Examples (quantitative analysis)	Double Auction Market	MW mile method(quantitative analysis)	Importance of congestion management
	SLO-2	Power system Deregulation in different countries	Characteristic features of OPF & its applications	ISO in Pool markets	Incremental cost based transmission pricing	Features of congestion management
S-3	SLO-1	Competitive electricity markets	Unit commitment in conventional electricity market	ISO in Bilateral markets	Short run marginal cost based method	Classification of congestion management methods
	SLO-2	Benefits from a competitive electricity market	UC Constraints	Operational planning activities of GENCO	Long run marginal cost based method	Calculation of ATC
S-4	SLO-1	Classification of electricity markets	Price based Unit commitment Design in deregulated electricity market	GENCO in pool and bilateral markets	Revenue Reconciliation	Economic instruments for Handling congestion
	SLO-2	Pool co and Bilateral Markets	Constraints in price based Unit commitment	Market participation issues	Transmission open access and pricing mechanisms in various countries	Congestion pricing methods
S-5	SLO-1	Effects of deregulation	Competitive bidding., strategic bidding	Power exchange	Cost components of Transmission System Operator (TSO)	Market splitting
	SLO-2	Pre dispatch and instantaneous dispatch	Parameters affecting bidding strategies	Market operations	Transfer capability on open access transmission system	Counter trade

S-6	SLO-1	Review of Economic Load Dispatch problem (ELD)	Formation of power pools	Market power- standard cost	Developments in international transmission pricing	Transmission rights
	SLO-2	Constraints in ELD problem	Economic Exchange of Energy	Price forecasting	Transmission Security management in deregulated environment	Inter zonal congestion management
S-7	SLO-1	Economic Load Dispatch problem In Deregulation	Multi area Joint Dispatch (quantitative analysis)	Power wheeling	Scheduling of spinning reserves in deregulated electric market	Intra zonal congestion management
	SLO-2	Economic Load Dispatch problem (quantitative analysis)	Energy Brokerage system	Types of wheeling transactions	Introduction of ancillary services	Price area congestion management
S-8	SLO-1	Conditions for optimum	Role of Independent system operator (ISO),	Transmission open access and types	Types of Ancillary services	Capacity alleviation method
	SLO-2	Significance of Lagrange Multipliers	Types of electricity market	Cost components in transmission	Classification of ancillary services	Contingency reserve services
S-9	SLO-1	Security constrained Economic dispatch	Structure of UK Electricity deregulated market	Pricing of power transactions	Ancillary services management in various countries	Indian electricity act
	SLO-2	Preventive and corrective rescheduling	Structure of Nordic Electricity deregulated market	Ideal Wheeling Rate	Interruptible load options for security management	Indian power exchange

Learning Resources	<ol style="list-style-type: none"> 1. KankarBhattacharya, Operation of Restructured Power Systems, Kluwer academic publishers, 2001. 2. Mohammad Shahidehpoura and Muwaffaq A Iomoush, Restructured Electric Power System operation trading and volatility, Macscl Dekker Inc,2001 3. Zaccour.G. Deregulation of Electric Utilities, Kluwer academic publishers, 1998 . 4. Xiao ping Zhang, Restructured Electric Power Systems: Analysis of Electricity Markets with Equilibrium Models, IEEE press, 2010 5. THE ELECTRICITY ACT, 2003, http://www.cercind.gov.in/Act-with-amendment.pdf 6. https://nptel.ac.in/courses/108101005/.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.S.Sambath, TANGEDCO,Tamilnadu, eses.eng@gmail.com	1.Dr. M.P.Selvan, NIT Trichy, selvanmp@nitt.edu	Mr. K.Selvakumar, SRMIST
2. Mr.Sudharsan, L&T, sudharsand@Intecc.com	2.Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekr.ac.in	Dr.K.Vijayakumar, SRMIST

Course Code	18EEE317T	Course Name	SYSTEM THEORY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Model and represent the systems in state variable form					Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Understand the need of controllability and observability						Expected Proficiency (%)				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Provide adequate knowledge in the phase plane analysis						Expected Attainment (%)				H	H	M	M	-	-	-	-	-	-	-	-	M	M	-
CLR-4 :	Give a basic knowledge in describing function analysis										H	H	M	M	-	-	-	-	-	-	-	-	M	M	-
CLR-5 :	Educate on stability analysis of systems using Lyapunov's theory										H	H	M	M	-	-	-	-	-	-	-	-	M	M	-
CLR-6 :	Create a mindset to model and analyze the system stability using system theory concepts										H	H	M	M	-	-	-	-	-	-	-	-	M	M	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																							
CLO-1 :	Apply the state space method to model Linear and Nonlinear system					3	75	75		H	H	M	M	-	-	-	-	-	-	-	-	M	M	-	
CLO-2 :	Test the controllability and observability of the system					3	75	75		H	H	M	M	-	-	-	-	-	-	-	-	M	M	-	
CLO-3 :	Apply the concepts of phase plane analysis to linear and Nonlinear system					3	75	75		H	H	M	M	-	-	-	-	-	-	-	-	M	M	-	
CLO-4 :	Formulate the Describing function for Nonlinear system					3	75	75		H	H	M	M	-	-	-	-	-	-	-	-	M	M	-	
CLO-5 :	Determine the stability of Nonlinear system using Lyapunov and Variable- Gradient Method					3	75	75		H	H	H	H	-	-	-	-	-	-	-	-	M	M	-	
CLO-6 :	Apply system theory concepts to model and analyze real time system					3	75	75		H	H	H	H	-	-	-	-	-	-	-	-	M	M	-	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Concept of State-tate equation for Dynamic Systems	Concept of Controllability & Observability	Features of linear and non-linear systems	Basic concepts of describing functions	Introduction to Stability Analysis of Nonlinear System
	SLO-2	Time invariance and linearity- Non uniqueness of state model	Controllability Test for Time Varying and Time In varying Case: Minimum Energy Control	Common physical non-linearity's	Describing Function and Harmonic Balance	Equilibrium Points
S-2	SLO-1	State Diagram	Observability test for Time Varying and Time In- varying system	Methods of linearizing non-linear systems	Describing function analysis of nonlinear systems	Stability in the sense of Lyapunov
	SLO-2	Physical System: Linear Continuous Time model	Principle of Duality	Introduction to phase portraits	Importance of Describing Function	BIBO Stability
S-3	SLO-1	Physical System: Nonlinear system Model	Controllability of State model in Jordan Canonical Form	Concept of phase portraits	Derivation of describing functions for Hysteresis non-linearity	Stability of Linear Time Invariant Systems
	SLO-2	Local Linearization of Nonlinear Model	Observability of State model in Jordan Canonical Form	Singular points	Derivation of describing functions for Dead zone non-linearity	Problem Solving to find stability of Linear Time Invariant System
S-4	SLO-1	Solution of Nonlinear Continuous Time State Equation	Controllability and Observability Canonical Forms of State mode	Existence of Limit cycles	Basics of Backlash non-linearity	Introduction to Nonlinear Continuous Time Autonomous Systems
	SLO-2	Runge Kutta Method	Controllable Subspace, Unobservable Subspace	Use of Limit cycle in control system	Derivation of describing functions for Backlash non-linearity	Equilibrium Stability of Nonlinear Continuous Time Autonomous Systems
S-5	SLO-1	Solution of Linear Time Varying Continuous Time State Equation	Canonical Decomposition Theorem	Construction of phase portraits	Derivation of describing functions for Ideal Relay non-linearity	Basics of the Direct Method of Lyapunov
	SLO-2	The Homogeneous Solution	Input- Output Maps from State Model for Linear and Nonlinear System	Problem solving in phase portraits	Derivation of describing functions for Hysteretic Relay non-linearity	Direct Method of Lyapunov for Linear Continuous-Time Autonomous

						Systems
S-6	SLO-1	Evaluation of State Transition Matrix	Output Controllability	Phase plane analysis of linear System	Basics of Saturation non-linearity	Finding Lyapunov Functions for Nonlinear Continuous Time Autonomous Systems
	SLO-2	Non Homogeneous Solution	Dead-beat Controller	Problem solving in Phase plane for linear system	Derivation of describing functions for Saturation non-linearity	Krasovskii Method of Stability Analysis
S-7	SLO-1	Solution of Linear Time In-varying Continuous Time State Equation	Reducibility of Linear System	Phase plane analysis of Nonlinear System	General Conditions for stability of Nonlinear system	Finding Lyapunov Functions for Nonlinear Continuous Time Autonomous Systems
	SLO-2	Evaluation using Similarity Transform	Reducibility of Nonlinear System	Problem solving in Phase plane for Non-linear system	Describing function Conditions for stability of Nonlinear system	Variable- Gradient Method
S-8	SLO-1	Solution of Linear Time In-varying Continuous Time State Equation	Linear System Realizations: Phase Variable Canonical Form	Isocline method	Possibilities of Oscillations occurrence in Non Linear System	Transients in Non Linear System
	SLO-2	Evaluation using Cayley Hamilton Technique	Nonlinear System Realizations: Phase Variable Canonical Form	Importance of Isocline Method in Non Linear control system	Stability analyses of oscillations in Nonlinear system	Use of Lyapunov to Estimate Transients
S-9	SLO-1	Solution of Linear Time In-varying Continuous Time State Equation	Linear System Realizations: Jordan Canonical Form	Basics of Inverted Pendulum	Introduction to DC Motor Model	Stability Analysis Case Study related with Power Engineering Application
	SLO-2	Evaluation using Inverse Laplace Transform	Nonlinear System Realizations: Jordan Canonical Form	Example of Nonlinear System: Inverted Pendulum on a Cart	Describing function analysis of DC Motor with Permanent Magnet	Stability Analysis Case Study related with Power Engineering Application

Learning Resources	<ol style="list-style-type: none"> 1. Katsuhiko Ogata, Modern Control Engineering, 5th ed., Prentice Hall, 2017. 2. M. Gopal, Modern Control System Theory, 3rd ed., New Age International, 2014. 3. Marquez Horacio J Marquez, Nonlinear Control Systems: Analysis and Design, 2nd ed., Wiley Publications, 2012. 4. Zoran Vukic, Ljubomir Kuljaca, Dali Donlagic and Sejid Tesnjak, Nonlinear Control Systems, Marcel Dekker Inc, 2007. 5. Richard C.Dorf, Robert H.Bishop, Modern control system theory, 13th ed., Pearson Education Ltd, 2016. 6. https://www.edx.org/course/introduction-state-space-control-mitx-6-302-1x
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30 %	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40 %	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30 %	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Ms.R.Vijayalakshmi, C2C Engineering, vijayalakshmi@c2cengineering.co.in		Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu
2. Dr. S. Paramasivam, Danfoss, Industries Pvt Ltd, paramsathya@yahoo.com		Dr. A. Venkadesan, NIT, Pondicherry, venkadesan@nitpy.ac.in
		Internal Experts
		Dr.R. Narayanamoorthi, SRMIST
		Dr.N. Chellammal, SRMIST

Course Code	18EEE318T	Course Name	ROBUST CONTROL SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Introduce the basics of Robust control principles				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Solve the various problems in linear systems different stabilization methods				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Compute the performance of linear systems by the measured parameters																					
CLR-4 :	Understand the performance and limitations of Feedback control																					
CLR-5 :	Identify the solutions for H^∞ control and μ Synthesis																					
CLR-6 :	Create a overall structure for Robust control system																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Understand the basics of Robust control principles				2	80	75	H	M	M	-	-	-	-	-	-	-	-	-	H	M	-
CLO-2 :	Calculate the parameters of Linear systems by using different stabilization methods				3	80	75	H	H	M	M	M	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Analyze the performance of linear systems by the measured parameters				3	80	75	H	H	H	M	-	-	-	-	M	-	-	-	H	M	-
CLO-4 :	Acquire knowledge on Observer, Feedback control systems				3	80	75	H	M	H	M	-	-	-	-	M	M	-	-	H	H	-
CLO-5 :	Analyze the basics of H^∞ control and μ Synthesis and its solution				3	80	75	H	H	M	M	-	-	-	-	M	M	-	-	H	M	-
CLO-6 :	Design a Robust control system for Real time Control Applications				3	80	75	H	H	M	M	M	-	-	-	M	M	-	-	H	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction Engineering Background of RobustControl	Introduction Fundamentals ofLinearSystem	Introduction to Stabilization ofLinearSystems	Introduction to Performance Limitation ofFeedbackControl	Introduction to H^∞ Control & μ Synthesis
	SLO-2	A Brief History of RobustControl	Structural Properties ofDynamicSystem	StateFeedback	PoissonIntegralFormula	ControlProblem and H^∞ Control Norm
S-2	SLO-1	Methodologies of RobustControl	Stability - Bounded-InputBounded-OutputStability	Observer - Full-OrderObserver	All-Pass and Minimum-PhaseTransferFunctions	Input–OutputRelationofTransferMatrix's H^∞ Norm
	SLO-2	Small-GainApproach	InternalStability	MinimalOrderObserver	Limitation on Achievable Closed-loopTransferFunction	Disturbance Control andWeightingFunction
S-3	SLO-1	Positive Real Method	Pole–Zero Cancellation	Parametrization ofStabilizingControllers	InterpolationCondition	LMI Solution 1: VariableElimination
	SLO-2	LyapunovMethod	StabilizabilityandDetectability	Generalized FeedbackControl System	Analysis ofSensitivityFunction	LMI Solution 2: VariableChange
S-4	SLO-1	Robust Regional PolePlacement	Problem solving session	Problem solving session	IntegralRelation	Problem solving session
	SLO-2	GainScheduling	LinearFractionalTransformation	ParametrizationofControllers	Problem solving session	Design of Generalized Plant andWeighting Function
S-5	SLO-1	Problem solving session	SystemPerformance	YoulaParametrization	Bode Integral RelationonSensitivity	μ Synthesis
	SLO-2	Basics of Linear Algebra and Function Analysis	TestSignals	Structure ofClosed-LoopSystem	BodePhase Formula	Definition of μ andItsImplication
S-6	SLO-1	Trace, Determinant, Matrix Inverse, and BlockMatrix	Steady-StateResponse & TransientResponse	Structure of2-Degree-of-Freedom Systems	Limitation ofReference Tracking	Propertiesof μ
	SLO-2	Problem solving session	Comparison of Open-Loop andClosed-LoopControls	Implementation of 2-Degree-of-Freedom	1-Degree-& 2 Degree of-FreedomSystem	D–K IterationDesign
S-7	SLO-1	Linear VectorSpace	Problem solving session	SystemPerformance	Relation between Time Domain and FrequencyDomainProperties	RegionalPolePlacement

	SLO-2	Norm and Inner Product of Vector	Basics of Convex Analysis and LMI	Problem solving session	Parseval's Theorem	Convex Region and Its Characterization
S-8	SLO-1	Linear Subspace	Convex Set and Convex Function	Test Signals	Fourier Transform and Inverse Fourier Transform	Condition for Regional Pole Placement
	SLO-2	Matrix and Linear Mapping	Control Problem and LMI	Steady-State Response	KYP Lemma	Composite LMI Region
S-9	SLO-1	Eigenvalue and Eigenvector	Interior Point Method	Transient Response	Problem solving session	Problem solving session
	SLO-2	Problem solving session	Problem solving session	Problem solving session	Case Study: Stabilization of a Unicycle Robot	Case Study: Transient Stabilization of a Power System

Learning Resources	<ol style="list-style-type: none"> 1. Kang zhi liu, Yu Yao, Robust Control – Theory and Applications, Wiley Publications, 2016. 2. T. Glad and L. Ljung, Control Theory: Multivariable and Non-linear methods, Taylor and Francis, London, 2009. 3. S. Skogstad and I. Postlethwaite, Multivariable Feedback Control, John Wiley and Sons, 2005. 4. B. Burl, Linear Optimal Control H₂ and H_∞ Methods, Addison Wesley, California, US. 1999. 5. K. Zhou, J. C. Doyle and K. Glover, Robust and Optimal Control, Prentice-Hall, 1999 6. Online Course: https://swayam.gov.in/ 7. NPTEL: Control Engineering, Robust Control Systems. https://nptel.ac.in/courses/108103007/8
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Venkatarao Ryali, Electromechanical Control Systems Lab at GE Global Research, Bengaluru.	1. Dr. S.K. Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	1. Mr. S. Senthilmurugan, SRMIST
2. Mr. Pugazhendhi K, Control & Instrumentation at ENMAS GB POWER SYSTEMS PROJECTS LTD. Chennai,	2. Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	2. Ms R. Rajarajeswari, SRMIST

Course Code	18EEE319T	Course Name	FUNDAMENTALS OF ROBOTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1	Understand the concepts and basic structure of Robots	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2	Recognize the basics of end effectors and drive systems	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3	Enrich the students on the basics of Robotic manipulator and understand the kinematics of serial manipulators				H	H	M	L	-	-	-	-	-	-	-	-	M	M	-
CLR-4	Analyze the basics of Sensors and its various applications in Robots.				H	H	H	M	-	-	-	-	-	-	-	-	H	M	-
CLR-5	Design the Algorithms for mobile Robot navigation.				H	H	H	M	-	-	-	-	-	-	-	-	H	M	-
CLR-6	Utilize the concepts in robotics for the understanding of automation technology				H	H	H	H	-	-	-	-	-	-	-	-	H	M	-
					H	H	H	H	-	-	-	-	-	-	-	-	H	M	-
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>																			
CLO-1	Interpret the basic structure of Robots and apply it to design the Robots.	2	75	75															
CLO-2	Acquire knowledge about end effectors and actuators systems	3	75	75															
CLO-3	Select robotic manipulator and understand the kinematics of serial manipulators	2	75	75															
CLO-4	Select and implement the sensors for various applications in Robots.	3	75	75															
CLO-5	Develop the algorithms for mobile Robot navigation.	3	75	75															
CLO-6	Apply the concepts of robotics in real time applications	3	75	75															

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Robotics: Definition Advantage and disadvantage of robots	Robot Drives- Actuators	Matrix representation	Robot Sensors	Localization
	SLO-2	History of robotics	Actuators selection.	Fixed – reference frame	Selection of sensor	Path Planning
S-2	SLO-1	Classification of robots	Characteristics of actuating system	Representation of frame at the origin of a fixed-reference frame	Contact and touch sensor	Examples of localization system
	SLO-2	Robot components,	Comparisons of actuating system	Representation of frame in a fixed reference frame	Tactile sensor	Brief representations
S-3	SLO-1	Robot characteristics	Electric Actuators: DC motor	Representation of rigid body	Gripping force sensing	Brief considerations
	SLO-2	Co-ordinate systems	Brushless DC motor	Robot Kinematics - Position analysis	Slip sensing	Mobile robot localization using practical filters
S-4	SLO-1	Robot reference frame	Hydraulic actuators	Representation of a pure transformation	Proximity sensor	Map representations
	SLO-2	Degrees of freedom	Pneumatic actuators	Representation of combined transformation	Range sensor	Map considerations
S-5	SLO-1	Configuration space	Robot end effectors	Calculation of transformations	Light sensors	Simultaneous planning localization and mapping (SLAM)
	SLO-2	Operational space	Classification of end-effectors	Transformations relative to the rotating frame	Pressure sensors	Path planning
S-6	SLO-1	Robots as mechanisms	Drive system for grippers	Inverse transformation matrix	Strain gauge based force-torque sensors	Path planning challenges
	SLO-2	Robot configurations-cartesian	Mechanical grippers	Inverse transformation matrix of the universe, robot, hand and end effectors frame	Position sensor	Types of Path planning algorithms
S-7	SLO-1	Robot configurations- cylinder	Magnetic grippers	Forward kinematics-2 DOF of kinematics analysis	Displacement sensor	Robotics applications with examples
	SLO-2	Robot configurations- polar	Vacuum grippers	Forward kinematics-3 DOF of kinematics analysis	Sensors-Vision systems	Material handling: Pick and place operation

S-8	SLO-1	Robot configurations- articulate	Adhesive grippers	Inverse kinematics- 2 DOF of kinematics analysis	Low level vision sensing and digitizing	Palletizing and depalletizing
	SLO-2	Robot wrist mechanism	Selection criteria for grippers	Inverse kinematics- 3 DOF of kinematics analysis	Vision cameras	Machine loading and unloading
S-9	SLO-1	Precision and accuracy of robot	Gripper force analysis and design	Euler angles	Charge coupled device line scan sensor	Welding. A sensor based joystick controlled teleoperated manipulator
	SLO-2	Simple problems in precision and accuracy of robot	Simple problems in Gripper	Issues in inverse kinematics	Applications of robotics vision system	A sensor based joystick controlled teleoperated manipulator

Learning Resources	1. S. R. Deb & Sankha Deb, Robotics Technology and Flexible Automation, 2 nd ed., Tata Mcgraw Hill, 2010.	4. Mikell. P. Groover, Industrial Robotics Technology, Programming and Applications", 3 rd ., McGraw Hill Co, 2008.
	2. Niku, Saeed, Introduction to robotics", 2 nd ed., John Wiley & Sons, 2010.	5. https://www.edx.org/learn/robotics
	3. John J. Craig, Introduction to Robotics: Mechanics and Control, 4 th , Addison Wesley, 2018.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr. K. Ashwin, Embedded engineer, Bosch India, ashwinstringed@gmail.com	1.Dr. S. Ramareddy, Jerusalem College of Engineering, srr.victory@gmail.com	1.Mr.A.Dominic Savio, SRMIST
2.Mr.Uday kumar, KPIT, udaykumar2495@gmail.com	2.Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	2.Dr.K.Mohanraj, SRMIST

Course Code	18EEE320T	Course Name	SIGNALS AND SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:					Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Categorize the different types of continuous and discrete time signals						1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Classify the various types of continuous and discrete systems						Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Perform the discrete Fourier transform on signals									H	H	L	L	L	-	-	-	-	-	-	-	-	H	M	-
CLR-4 :	Perceive the digital IIR filters									H	H	L	L	L	-	-	-	-	-	-	-	-	H	M	-
CLR-5 :	Realize the digital FIR filters									H	H	M	M	-	-	-	-	-	-	-	-	-	H	M	-
CLR-6 :	Acquire knowledge on identification and creation of signals and systems									H	H	H	H	L	-	-	-	-	-	-	-	-	H	M	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																							
CLO-1 :	Identify the continuous and discrete time signals						2	80	75	H	H	L	L	L	-	-	-	-	-	-	-	H	M	-	
CLO-2 :	Distinguish the various types of continuous and discrete systems						2	80	75	H	H	L	L	L	-	-	-	-	-	-	-	H	M	-	
CLO-3 :	Assess the Discrete Fourier transform on signals						2	80	75	H	H	M	M	-	-	-	-	-	-	-	-	H	M	-	
CLO-4 :	Develop the digital IIR filters						3	80	75	H	H	H	H	L	-	-	-	-	-	-	-	H	M	-	
CLO-5 :	Design the digital FIR filters						3	80	75	H	H	H	H	L	-	-	-	-	-	-	-	H	M	-	
CLO-6 :	Evaluate the various types of signals and systems						3	80	75	H	H	H	H	L	-	-	-	-	-	-	-	H	M	-	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Analog signals, discrete time signals and digital signals	Continuous time systems	System representation through differential equations	Design procedure of Analog Butterworth Filter	Design procedure of FIR filter by window technique
	SLO-2	Deterministic and random signals	Discrete time systems	System representation through difference equations	Design of Analog Butterworth Filter	Rectangular and Hamming windows
S-2	SLO-1	Periodic and aperiodic signals	Memory less and memory systems	Realization of discrete time systems: Direct form - I	Design procedure of Analog Chebyshev Filter	Hanning and Blackmann Windows
	SLO-2	Energy and power signals	Causal and non-causal systems	Realization of discrete time systems: Direct form - II	Design of Analog Chebyshev Filter	Kaiser window
S-3	SLO-1	Even-odd signals	Linear and non-linear systems	Realization of discrete time systems: Cascade form	Bilinear transform technique	Design of low pass FIR filter: Calculation of window coefficients
	SLO-2	Causal and non-causal signals	Time variant and time invariant systems	Realization of discrete time systems: Parallel form	Quantitative treatment of Bilinear transform technique	Design of low pass FIR filter: Calculation of filter coefficients
S-4	SLO-1	Standard continuous time signals: Unit step and Impulse signals	Stable and unstable systems	Discrete Fourier Transform (DFT)	Impulse invariance technique	Design of high pass FIR filter: Determination of window coefficients
	SLO-2	Standard continuous time signals: Sinusoidal and Exponential signals	FIR and IIR systems	Calculation of DFT	Quantitative treatment of Impulse invariance technique	Design of high pass FIR filter: Determination of filter coefficients
S-5	SLO-1	Standard discrete time signals: Unit step and Impulse signals	Recursive and non-recursive systems	DFT properties: Linearity, Periodicity, Circular convolution	Design of IIR Butterworth digital filters using bilinear transform technique	Design of band pass FIR filter: Calculation of window coefficients -
	SLO-2	Standard discrete time ignals: Sinusoidal and Exponential signals	System properties via the impulse response: Causality	DFT properties: Time reversal, Circular time shift, Parseval's theorem	Design of IIR Chebyshev digital filters using bilinear transform technique	Design of band pass FIR filter: Calculation of filter coefficients
S-6	SLO-1	Transformations of the independent	System properties via the impulse	DFT using DIT-FFT algorithm	Design of IIR Butterworth digital filters	Design of band stop FIR filter:

		variable: Addition, Multiplication and Shifting	response: Memory		using impulse invariance technique – Self study	Determination of window coefficients – Seminar
	SLO-2	Transformations of the independent variable: Scaling and Reversal	Relation between continuous and discrete time systems	Calculation of DFT using DIT-FFT	Design of IIR Chebyshev digital filters using impulse invariance technique – Self study	Design of band stop FIR filter: Determination of filter coefficients – Seminar
S-7	SLO-1	Sampling and Sampling Theorem	Continuous time convolution	DFT using DIF-FFT algorithm	Realization of IIR Butterworth digital filters	Realization of FIR filters: Transversal realization structure
	SLO-2	Quantization and Coding	Quantitative treatment of Continuous time convolution	Calculation of DFT using DIF-FFT algorithm -Assignment	Realization of IIR Butterworth digital filters	Realization of FIR filters: Linear phase realization structure
S-8	SLO-1	Aliasing	Discrete time convolution	Inverse DFT	Need of Pre-warping	Realization of FIR filters: Polyphase realization structure
	SLO-2	Effects of Aliasing	Quantitative treatment of Discrete time convolution	Calculation of IDFT	Pre warping – Frequency transformation in digital domain	Realization of FIR filters: Cascade structure
S-9	SLO-1	Simulation on continuous time signals	Simulation on Continuous time systems	Circular convolution	Simulation on digital IIR Butterworth filters	Simulation on digital FIR low and high pass filters
	SLO-2	Simulation on discrete time signals	Simulation on discrete time systems	Quantitative treatment of Circular convolution -Assignment	Simulation on digital IIR Chebyshev filters	Simulation on digital FIR band pass and band stop filters

Learning Resources	1. H. P. Hsu, Signals and systems, Schaum's series, McGraw Hill Education, 2010. 2. S. Haykin and B. V. Veen, Signals and Systems, John Wiley and Sons, 2007. 3. A. V. Oppenheim and R. W. Schaffer, Discrete-Time Signal Processing, Prentice Hall, 2009. 4. M. J. Robert, Fundamentals of Signals and Systems, McGraw Hill Education, 2007.	5. B. P. Lathi, Linear Systems and Signals, Oxford University Press, 2009. 6. A. V. Oppenheim, A. S. Willsky and S. H. Nawab, Signals and systems, Prentice Hall India, 1997. 7. J. G. Proakis and D. G. Manolakis, Digital Signal Processing: Principles, Algorithms, and Applications, Pearson, 2006. 8. https://extension.ucsd.edu/courses-and-programs/signals-and-systems
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Sharon Ravichandran, ABB Ltd., Chennai, sharonravi87@gmail.com	1. Dr. M.Jaya Bharata Reddy, NIT, Trichy, jbreddy@nitt.edu	1. Dr.K.Mohanraj, SRMIST
2. Mr.Sabari Ramanan, Manager, Siemens, Chennai, sabari.pm@siemens.com	2. Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	2. Dr.A.Rathinam, SRMIST

Course Code	18EEE412T	Course Name	ADVANCED CONTROL THEORY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Educate on the basic concepts of multivariable control system					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Understand the design concepts in model predictive control techniques					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO-1	PSO-2	PSO-3	
CLR-3 :	Provide adequate knowledge on preliminary concepts in Adaptive control schemes								H	H	M	M	-	-	-	-	-	-	-	-	-	M	M	-
CLR-4 :	Provide knowledge on Variable Structure control techniques								H	H	H	H	-	-	-	-	-	-	-	-	-	M	M	-
CLR-5 :	Educate on different optimal control practices								H	H	M	M	-	-	-	-	-	-	-	-	-	M	M	-
CLR-6 :	Create a mindset to use the advanced control techniques in complex system								H	H	M	M	-	-	-	-	-	-	-	-	-	M	M	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Formulate the Multivariable control techniques to Multiple parameter system					3	75	75																
CLO-2 :	Apply the model predictive control strategy to linear and Nonlinear systems					3	75	75																
CLO-3 :	Articulate the basic adaptive control technique to a system					3	75	75																
CLO-4 :	Design the sliding mode control to a dynamic system					3	75	75																
CLO-5 :	Analyze and design the optimal control techniques for linear and Nonlinear systems					3	75	75																
CLO-6 :	Apply the advanced control techniques in real time problems					3	75	75																

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Basics of Classical Feedback Control	Introduction to Model Predictive control	Introduction to adaptive control	Introduction to Sliding Mode Control	Introduction to Optimal Control
	SLO-2	Introduction to multivariable control systems	MPC Strategy, Historical perspectives.	Effects of process variations	Properties of Sliding Motion	Importance of Optimal Control
S-2	SLO-1	Transfer functions for MIMO systems	MPC Elements: Prediction Model	Introduction to Adaptive control schemes	Pseudo Sliding With a Smooth Control	Basics of Parameter Optimization
	SLO-2	Negative Feedback Control system in MIMO system	MPC Elements: Objective Function	Types of Adaptive Control Schemes	State Space Approach in Sliding Mode	Parameter Optimization in Optimal Control
S-3	SLO-1	Multivariable frequency response analysis	Model forms for model predictive control Forms	Adaptive control problem	Sliding Mode Control: Problem Statement	Performance Index in Optimal Control
	SLO-2	Directions in Multivariable Systems	Dynamic Matrix Control	Non-parametric identification	Existence Solution and Equivalent Control	Constraints in Optimal Control
S-4	SLO-1	Introduction to multivariable system mapping-poles & zeros	Model predictive control Forms	Deterministic Self Tuning Regulators	Properties of Sliding Motion	Calculus of variance in Optimal Control
	SLO-2	Singular value decomposition	Model Algorithmic Control	Pole Placement in Adaptive Control	Properties of Sliding Motion	Basic Concepts, Functions in optimal Control
S-5	SLO-1	Limitations On Performance In MIMO Systems:: Functional controllability	Model predictive control Forms	Indirect Self Tuning Regulators	The reachability Problem in Sliding Mode Control	Optimum of a Function
	SLO-2	Limitations imposed by time delays	Predictive Functional Control	Continuous Time Self tuners	Single input Control Structure	Optimum of a Functional
S-6	SLO-1	Limitations On Performance In MIMO Systems	Generalized Predictive Control	Introduction to Stochastic Tuning Regulators	Unit Vector Approach: Existence in Ideal Sliding Mode	The basic variational Problem
	SLO-2	Limitations imposed by RHP zeros	Introduction and Formulation of	Predictive Self Tuning Regulators	Description of the sliding Motion by Unit	Second Variation Problem

			Predictive Control		Vector Approach	
S-7	SLO-1	Trade-offs in MIMO feedback design	Introduction to Multivariable Model Predictive Control	Stochastic Adaptive Problem	Introduction to types of Sliding Mode Design Approach (Qualitative)	Introduction to linear quadratic optimal control system
	SLO-2	Traditional LQG and LQR problems	Generalized Model of Multivariable Predictive Control	Dual Control in stochastic Predictive Control	Introduction to types of Sliding Mode Design Approach (Quantitative)	Linear quadratic optimal control system Model
S-8	SLO-1	Introduction to linear quadratic regulation (LQR) control	Constrained Model Predictive Control	Introduction to Auto Tuning of Controller	Direct Eigen Structure Assignment Approach (Qualitative)	Finite Time Linear Quadratic Regulator
	SLO-2	Robustness properties of LQR control	Constraint General Form, Example	PID Controller Auto Tuning	Direct Eigen Structure Assignment Approach (Quantitative)	Problem Formulation in Finite Time Linear Quadratic Regulator
S-9	SLO-1	Introduction to H_2 control	Introduction to Robust Model Predictive Control - Application	Introduction to Gain Scheduling - Application	Introduction to higher order sliding mode control	Introduction to LQR system for general performance Index
	SLO-2	Introduction to H_∞ control	Introduction to Robust Model Predictive Control - Application	Introduction to Gain Scheduling - Application	Problems in Higher order sliding mode control	Introduction to LQR system for general performance Index

Learning Resources	1. Sigurd Skogestad and Ian Postlethwaite, <i>Multivariable Feedback Control: Analysis and Design</i> , 2ed (WILEY-Interscience), 2014. 2. Eduardo F. Camacho, Carlos Bordons Alba, <i>Model Predictive Control</i> , Springer, 2013. 3. Karl J.Astrom and Bjorn Wittenmark, <i>Adaptive Control</i> , Pearson Education, 2nd Edition, 2013.	4. C Edwards, S Spurgeon <i>Sliding Mode Control: Theory And Applications</i> , CRC Press, 1998. 5. Donald E. Kirk, <i>Optimal Control Theory: An Introduction</i> , Prentice – Hall networks series, New Jersey, 2012. 6. https://www.cranfield.ac.uk/courses/short/energy-and-power/advanced-control-systems
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30 %	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40 %	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30 %	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Ms.R.Vijayalakshmi, C2C Engineering, vijayalakshmi@c2cengineering.co.in	1.Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	1.Dr.R. Narayanamoorthi, SRMIST
2.Dr. S. Paramasivam, Danfoss Industries Pvt.Ltd, paramsathya@yahoo.com	2. Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	2.Dr.N. Chellammal, SRMIST

Course Code	18EEE413T	Course Name	DISTRIBUTED CONTROL SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Learn the architecture, Organization and operation of PLC, SCADA and Distributed Control System (DCS)				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Impart knowledge about basic controllers and DCS controller Configuration				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Know the importance of Alarm features in DCSs																					
CLR-4 :	Impart adequate knowledge onMaintenance and Troubleshooting procedures of DCS																					
CLR-5 :	Learn the basics of Advanced Process Controllers in DCSs and Latest trends related to DCS																					
CLR-6 :	Gain Knowledge about basic DCS controllers Alarm system management and advanced process controllers																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Familiarize the concepts and abstractions of distributed systems and their limitations				2	80	75	H	L	L	L	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :	Obtain the knowledge of basic controllers and DCS controller Configuration				2	80	75	H	L	L	-	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Enrich the knowledge of Alarm features of DCS				2	80	75	H	L	M	L	-	-	-	-	-	-	-	-	M	L	-
CLO-4 :	Analyse the system for the awareness of the issues and procedures to perform DCS Maintenance and Troubleshooting				3	80	75	H	H	M	M	-	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Acquire the basics of Advanced Process Controllers in DCSs and Latest trends related to DCS				3	80	75	H	H	H	H	-	-	-	-	-	-	-	-	M	M	-
CLO-6 :	Evaluate and specify DCSs to ensure efficient and optimum operation of Plant				3	80	75	H	H	M	M	-	-	-	-	-	-	-	-	M	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Programmable Logic Controller (PLC) – brief overview	Introduction to basic controller, Identification of the controller boards	Alarm system management: An alarm system, Functions of the plant or process operator	Introduction to Distributed control system reporting, Operation of advanced DCS using multi-screen display	Advanced Process Controllers: Feed forward Control
	SLO-2	Block Diagram of PLC	Discrete and logic control, Sequential and batch control	Functions of an alarm system, An effective alarm system	Cross screen invocation and linking	Cascade Control
S-2	SLO-1	An overview of SCADA systems: Introduction and Basics of SCADA system	Basic DCS controller configuration: Introduction and Control modes	Design overview	Alarm reporting, generation and acceptance	Statistical Process Control
	SLO-2	SCADA key features	Tracking and initialization in control slots used for cascade control	Human and ergonomic factors	Different types of logs and reports configurable on a DCS	Basics of advanced process control and optimization
S-3	SLO-1	Remote terminal units (RTUs)	Control functions	Structure of a good alarm system	Introduction to Distributed control system (DCS) configuration	Latest DCS Trends: Monitoring and control in the Field
	SLO-2	Typical requirements for an RTU system	Control algorithms	Safety integrity level (SIL)	System/project tree structure, DCS system database	Industrial Internet
S-4	SLO-1	PLCs used as RTUs and Consideration and benefits of SCADA system	Sequential Controllers for Batch Processing	Definition of strategy, Strategy for alarm system design	Configuration of control functions	Internet of Things
	SLO-2	DCS versus SCADA terminology	Defining equipment procedures	Strategy for alarm system maintenance and management at the site/plant, Generation of minimum design documentation for each alarm	Configuration of operator/monitoring functions	Mobile and remote devices
S-5	SLO-1	SCADA software package	Phase logic programming	Measurement of the alarms, Field measurements for deriving alarms	Configuration of system hardware structure	Cloud Processing Monitoring and control in the Cloud

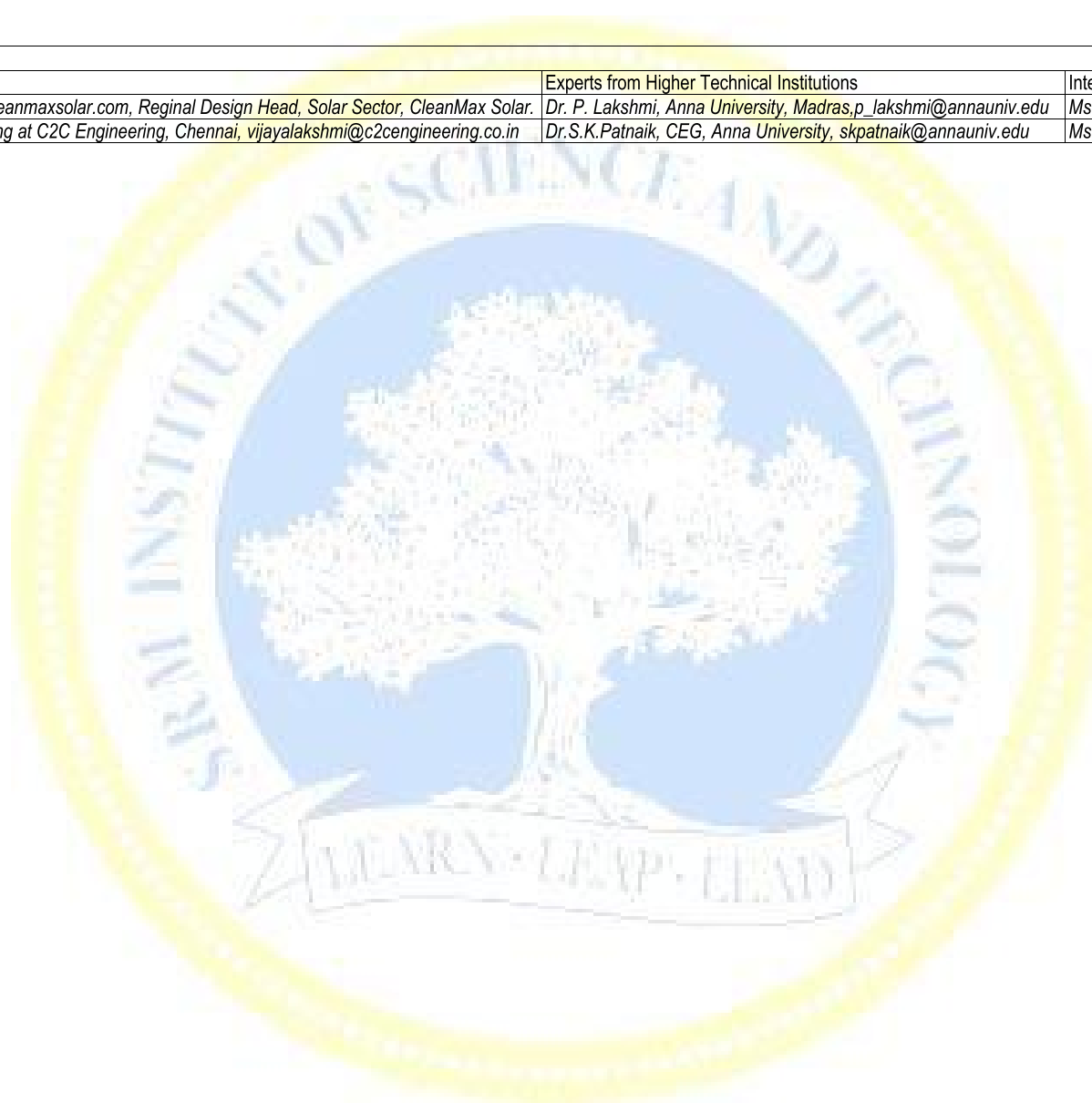
	SLO-2	Hardware, software, system interfacing	Phase logic interface	Hardware for alarm processing, Alarm displays	Configuration of system software	Typical DCS and SCADA systems: Honeywell Plant Scape system
S-6	SLO-1	Overview of Distributed Control Systems: Introduction and Basic concepts of Distributed Computing	Logic block functions in advanced controller	Testing of alarms, Generation of various types of alarms	Documentation and Commissioning	Foxboro I/A series DCS
	SLO-2	Evolution of Distributed Computing System	DCS controller configuration	Selection of alarm settings	Introduction to Maintenance & Troubleshooting	Delta system
S-7	SLO-1	Present market trends in DCS	Introduction to Communications for DCS & SCADA systems: Purpose and Basic Communications principles	Setting alarm priority	Maintenance requirements of system and system elements	Citect
	SLO-2	Basic DCS specification	Balanced and unbalanced transmission lines	Design of field sensors for generating alarms	Requirements for in-built diagnostic and maintenance routines	Wonderware
S-8	SLO-1	General description of a commercial DCS	4 EIA-232 interface standards (CCITT V.24 interface standard)	Logical processing of alarms	Requirement for installation of UPS system	Distributed control system applications: Use of DCS in oil and gas processing environment
	SLO-2	Advantage of DCS systems	The EIA-485 interface standard	Design of alarm list displays	Recovery of a DCS following power outage	Use of DCS in pulp and paper environment
S-9	SLO-1	DCS selection criteria	Interoperability, ModBus protocol	Measurement of performance	Proper troubleshooting methods, identify typical Communication malfunctions and faults, Identifying failures, malfunctions, and faults	Use of DCS in petroleum-refining environment
	SLO-2	DCS architecture	HART protocol, The promise of FieldBus and DeviceNet and Benefits	Usefulness of alarms	Diagnostics of Communication faults	Distributed control systems project implementation

Learning Resources	<ol style="list-style-type: none"> 1. Michael P. Lukas, Distributed Control Systems: Their Evaluation and Design, Van Nostrand Reinhold Co., 1986. 2. Boyer, S.A. SCADA: Supervisory Control and Data Acquisition. 4th Edition. International Society for Automation, Raleigh, USA, 2010. 3. Gene F. Franklin, J.David Powell, Abbas Emami, Feedback Control of Dynamic Systems, Naeini, Pearson 4. Srinivas Medida, Pocket Guide on Industrial Automation, For Engineers and Technicians, IDC Technologies. 5. Bela G. Liptak, Process Measurement and Analysis, Instrument Engineers' Handbook Fourth Edition, CRC Press. 6. Richard L. Shell, Ernest L. Hall, Handbook of Industrial Automation, University of Cincinnati Cincinnati, Ohio, 2000. 7. Practical Distributed Control Systems (DCS) for Engineers and Technicians, Revision 6.1, IDC Technologies. 8. www.isa.org
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Kranti kumar Chittiprolu, krantikumar.ch@cleanmaxsolar.com , Reginal Design Head, Solar Sector, CleanMax Solar.	Dr. P. Lakshmi, Anna University, Madras, p_lakshmi@annauniv.edu	Ms. T.M. Thamizh Thentral, SRMIST
Ms. Vijayalakshmi Ramani, Head-Engineering at C2C Engineering, Chennai, vijayalakshmi@c2cengineering.co.in	Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	Ms. R. Rajarajeswari, SRMIST



Course Code	18EEE414T	Course Name	CONTROL SYSTEM DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Gain knowledge on stability using frequency domain methods				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyze state space analysis of mechanical systems																							
CLR-3 :	Impart knowledge on controllability/observability of control systems																							
CLR-4 :	Outline the concept and design of robust control systems																							
CLR-5 :	Examine stability of nonlinear autonomous systems by state space methods																							
CLR 6 :	Gain knowledge on the design, control and analysis of Linear and non-linear system.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Apply frequency domain methods for stability analysis				2	80	75	H	H	L	L	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :	Evaluate linear dynamical systems by state space methods				3	80	75	H	H	M	M	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-3 :	Determine controllability/observability by rank test				3	80	75	H	H	L	L	-	-	-	-	-	-	-	-	-	-	L	L	-
CLO-4 :	Design robust control system for real time system				3	80	75	H	H	L	L	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-5 :	Analyse stability of nonlinear autonomous systems by state space methods				2	80	75	H	M	L	L	-	-	-	-	-	-	-	-	-	-	L	L	-
CLO 6 :	Design of compensators to analyse the system stability and performance of Control system.				3	80	75	H	H	L	L	-	-	-	-	-	-	-	-	-	-	M	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Design of Feedback Control Systems	Introduction to Design of State Variable Feedback Systems	Introduction to Controllability and Observability	Introduction to Robust control system	Lyapunov's stability
	SLO-2	Approaches to System Design	Advantages of State Space Representation	Conditions for Controllability and Observability	Review of norms for signals and systems	Stability of Autonomous Systems
S-2	SLO-1	Cascade Compensation Networks	State-space Equations	Algebraic definitions for Controllability and Observability	Review of Nyquist Criterion and Classical Stability Margin	Stability of linear and non-linear autonomous systems
	SLO-2	System Design Using Integration Networks	State model of LTI and SISO linear systems	Full-state feedback control design	The small Gain Theorem and Applications of Small Gain Theorem to the Robust Control	Lyapunov's indirect method
S-3	SLO-1	Design procedure for Phase-Lead network Using the Bode Diagram	State space representation using physical variables	Need for Observer	Robust control systems and system sensitivity	Lyapunov's direct method
	SLO-2	Design example: Phase-Lead design for different types system	State space representation using phase variables	Structure and properties of observer	System sensitivities to parameter perturbations	Optimal control positive definite function
S-4	SLO-1	Design procedure for Phase-Lead network Using the root locus	State space models of DC motor	Integrated full-state feedback and observer	Analysis of robustness	Optimal control negative definite function
	SLO-2	Design example: Phase-Lead design for different types system	State space models of inverted pendulum	Pole placement for single-output systems	System with uncertain parameters of robust control system	Positive semi-definite functions
S-5	SLO-1	Design procedure for Phase-Lag network Using the Bode Diagram	Decomposition of Transfer Functions-Direct Decomposition	Compensator design by separation principle	Considerations in design of robust control system Design	Negative semi-definite functions
	SLO-2	Design example: Phase-Lag design for different types of system	Cascade and parallel Decomposition	Reference inputs	Design of robust PID controlled systems	Lyapunov stability criteria

S-6	SLO-1	Design procedure for Phase-Lag network Using the root locus	Similarity Transformation	Types of observer	Robust internal mode control systems	Introduction to optimal control
	SLO-2	Design example: Phase-Lag design for different types system	Solution of state equations	Compensator design using full order observer	Design of internal mode control systems	Riccati Equation
S-7	SLO-1	Design on the Bode Diagram Using Analytical Methods	Computation of the State Transition Matrix by infinite series method	Optimal control systems	Loop shaping necessary and sufficient conditions.	Linear Quadratic Regulator
	SLO-2	System design using analytical technique	Computation of the State Transition Matrix by Laplace transformation	Determination of optimal control systems	Robust stability test.	Lasalle's invariance principle
S-8	SLO-1	Systems with a Pre-filter	Computation of the State Transition Matrix by Cayley-Hamilton Theorem	Optimal system with control energy consideration	Robust performance test.	Instability Theorem
	SLO-2	Design for Deadbeat Response	Computation of the State Transition Matrix by Canonical Transformation	Disturbances and tracking systems	Design Examples: the pseudo quantitative feedback system	Design Examples-Linear Harmonic Oscillator
S-9	SLO-1	System design using control design software	Computation of the State Transition Matrix by Sylvester's method	Design Examples-Automatic test system	Robust Control Systems using Control design software	Design Examples-Non-Linear Spring mass system with Damper
	SLO-2	Sequential design of disk drive read system	Transfer Function from the State-Model	Diesel Electric Locomotive control system	Sequential design of disk drive read system	Design Example-Pendulum with and without friction

Learning Resources	<ol style="list-style-type: none"> 1. Richard C. Dorf and Robert H. Bishop, <i>Modern Control Systems</i>, Prentice Hall, Upper Saddle River, NJ, 2001 2. Katsuhiko Ogata, <i>Discrete Time Control Systems</i>, Pearson 3. Gene F. Franklin, J. David Powell, Abbas Emami, <i>Feedback Control of Dynamic Systems</i>, Naeini, Pearson 4. Bernard Friedland, <i>Control System Design: An Introduction to State-Space Methods</i> (Dover Books on Electrical Engineering), Dover Publications Inc., 2005. 5. Steen Toffner-Clausen, <i>System Identification and Robust Control</i>, Springer Verlag London Limited 1996. 6. R.M. Murray, Z. Li, S.S. Sastry, <i>A Mathematical Introduction to Robotic Manipulations</i>, CRC Press, 1993. 7. http://nptel.ac.in/courses/108103007/16
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Sharon Ravichandran, ABB Ltd., Chennai, sharonravi87@gmail.com	1. Dr. P. Lakshmi, Anna University, Madras, p_lakshmi@annauniv.edu	1. Ms. T.M. Thamizh Thentral, SRMIST
2. Ms. Vijayalakshmi Ramani, Head-Engineering at C2C Engineering, Chennai, vijayalakshmi@c2cengineering.co.in	2. Dr. S.K. Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	2. Ms. R. Rajarajeswari, SRMIST

Course Code	18EEE415T	Course Name	DIGITAL CONTROL SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EEEC301J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Enrich the students on the basics of time domain analysis	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Explain the procedure for stability analysis	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Outline the concepts of state space model, controllability and observability				H	M	M	-	-	-	-	-	-	-	-	-	H	M	-
CLR-4 :	Gain knowledge on the design of classical compensators				H	M	M	M	M	-	-	-	-	-	-	-	M	M	-
CLR-5 :	Understand the concepts of formulation and evaluation of regulators and filters				H	M	M	M	-	-	-	-	-	-	-	-	H	M	-
CLR-6 :	Create overall control system structure for industrial applications				H	M	M	M	M	-	-	-	-	-	-	-	H	M	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Gain knowledge on Z transform techniques	2	80	75															
CLO-2 :	Interpret the knowledge of sampling and design of controllers	3	80	75															
CLO-3 :	Illustrate modelling and state variable analysis	3	80	75															
CLO-4 :	Analyze the effects of compensators	3	80	75															
CLO-5 :	Design of regulators and filters for practical system	3	80	75															
CLO-6 :	Design a control system and analyze the stability of the real time system	3	80	75															

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Basic components of a control system	Introduction to sampling	Introduction to state variable model	Compensator design	Introduction- Pole placement
	SLO-2	Classification of control systems	Sampled data control systems	State variable concepts, First , second companion forms	Compensating networks types: Cascade and feedback	State observers
S-2	SLO-1	Elements of an automatic control system	Sampled signal flow graph	Various canonical forms	Cascade Lead compensator design using Bode plot	Controller Design by State Feedback
	SLO-2	Applications of control system	Sampling time and frequency domain description aliasing, hold operation,	Jordan canonical models	Problems related to lead compensators	Stability improvement by state feedback
S-3	SLO-1	Introduction to Z-transform	Mathematical modeling of sampling process and analysis	Analysis-state space models	Cascade Lag compensator design using Bode plot	Necessary and sufficient condition for arbitrary pole placement
	SLO-2	Z-transform Concept	First order hold, factors limiting the choice of sampling rate, reconstruction.	Problems related to state space model	Problems related to lag compensators	State regulator design
S-4	SLO-1	Properties of Z-transform	Sampling and reconstruction of continuous time signals	Discrete state variable models	Problems related to lead- lag compensators	Design of state observers
	SLO-2	Z-transform relation with Laplace transform	Stability analysis of discrete system	Elementary principles.	Digital implementation of lead and lag controllers	Full Order Observer Design
S-5	SLO-1	Inverse z-Transforms and Problems	Jury stability test	Characteristic equation, state transition matrix	Design of digital control systems with deadbeat response	Reduced Order Observer Design
	SLO-2	Mapping of s-plane to z-plane	Bi-linear transformation	Solution to discrete state equation	Practical issues with deadbeat response design	Evaluation of State Feedback Gain Matrix
S-6	SLO-1	Pulse transfer function	Problems related to stability analysis	Stability of discrete state space models	Sampled data control systems with	State feedback with integral control

	SLO-2	Pulse transfer function of closed loop system	Digital PID controllers.	Cayley -Hamilton theorem	deadbeat response Introduction to software tools used in control system for compensator design	Digital control system with state feedback.
S-7	SLO-1	Introduction to the representation of discrete time systems	PID tuning and its importance	Controllability and observability	Coding in simulation software	Linear Quadratic Regulator (LQR) design
	SLO-2	Time response of discrete time systems	Techniques of controller tuning	Analysis of Controllability and observability	Exercises for solving problems related to compensators design	Formulation of LQR problem-
S-8	SLO-1	Time response specifications	Manual tuning Zeigler-Nichols method based on open loop and closed loop responses	Stability- Lyapunov stability theorem	Software implementation using microprocessors and microcontrollers	Optimal estimation- Kalman filter
	SLO-2	Application of the z transform for discrete time signals and systems.	Application of controllers used for control system	Analysis of Lyapunov stability	Microcontroller based temperature control systems	Solution to continuous and discrete systems - Design examples.
S-9	SLO-1	Problems related to time response for standard test signals	Controller design using root locus	Systems with dead time	Speed control of motor load system	Introduction to optimal control
	SLO-2	Problems related to time domain specifications	Root locus based controller design using software tools	Problems related to controllability and observability	Microcontroller based motor speed control systems.	Parameter optimization

Learning Resources	1. B. C. Kuo, Digital Control Systems, Oxford University Press, 2/e, Indian Edition, 2012. 2. Richard C Dorf and Robert H Bishop, Modern Control Systems, 13th edition, Pearson Education, 2016.	3. M. Gopal, Digital Control and State Variable Methods, Tata Mcgraw Hill, 2/e, 2017. 4. Norman S Nise, Control Systems Engineering, 7th edition, Wiley, 2015. 5. https://nptel.ac.in/courses/108103008/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Sharon Ravichandran, ABB Ltd., Chennai, sharonravi87@gmail.com	1. Mr.P.Thamizhazhagan, Associate Professor, University college of Engineering, Panruti, thamizhme@gmail.com	1. Ms.A.Lavanya SRMIST
2. Mr.Jason Manoraj , L&T Technology Services Limited, Bengaluru, Karnataka, jasonmanoraj@gmail.com	2. Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	2. Dr. Raja Vikram SRMIST

Course Code	18EEE321T	Course Name	PHOTONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Introduce the basics principles of photonics				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Solve the various problems in Light beams and Variable polarization																							
CLR-3 :	Analyze the performance of surface and cavity nanophotonics																							
CLR-4 :	Understand the process and performance of Multiphoton																							
CLR-5 :	Analyze the basics of Electromagnetic duality, Slow and fast light principles																							
CLR-6 :	Create a over all structure for Photonics system																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understand the basics of photonics principles				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :	Calculate the parameters of Light beams and Variable polarization				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-3 :	Compute the performance of surface and cavity nanophotonics				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-4 :	Acquire knowledge on Multiphoton process				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	H	H	-
CLO-5 :	Identify the solutions for slow and fast light				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-6 :	Design a Photonics system for Real Time Applications				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Photon in Perspective	Light Beams with Spatially Variable Polarization	Surface and Cavity Nanophotonics	Multiphoton Processes	Lighting Principles
	SLO-2	Photon Localization	Poincare Modes of Beams	Basic Formalism	Molecular Two-Photon Absorption: Basic Principles	Introduction to Slow and Fast Light
S-2	SLO-1	Wavefunction	Polarization Singularities	Dipole Emitter Near Edge	Molecular Two-Photon Fluorescence	Mechanisms of Slow Light
	SLO-2	The Quantum Vacuum	Quantum Optics	Quantum Correlations	Applications and Future Prospects	Physics with Slow and Fast Light
S-3	SLO-1	Virtual Photons	Open Systems: Inputs and Outputs	Entanglement	Orbital Angular Momentum	Some Applications of Slow and Fast Light
	SLO-2	Structured Light	Photon Counting	Wedge Cavities	Historical Introduction	Fundamental Limits on Slow Light
S-4	SLO-1	Photon Number Fluctuations	Cavity	Quantum Electrodynamics	Creating Beams with OAM	Attosecond Physics
	SLO-2	Photon Number Phase	Circuit QED	Molecular QED: Principle of Minimal Electromagnetic Coupling	Micro-Manipulation through the Use of OAM	Attosecond Streaking Spectroscopy of Atoms and Solids
S-5	SLO-1	The Reality of Photonics	Squeezed Light	Multipolar Hamiltonian	Beam Transformations	Time-Resolved Photoemission from Atoms
	SLO-2	Coherence and Statistical Optics	Salient Features of Squeezed States	One-Photon Absorption	Measuring Beams with OAM	Streaked Photoemission from Solids
S-6	SLO-1	Classical Theory of Optical Coherence in the Space-Time Domain	Detection	Emission of Light: Spontaneous and Stimulated Processes	OAM in Classical Imaging	Attosecond Streaking from Nanostructures
	SLO-2	Classical Theory of Optical Coherence in the Space-Frequency Domain	Preparation	Linear Light-Scattering:	OAM in Nonlinear and Quantum Optics	Attosecond Physics
S-7	SLO-1	Cross-Spectrally Pure Optical Fields	Applications in Quantum Information	The Kramers–Heisenberg Dispersion Formula	Electromagnetic Duality Transformations in Optics	Attosecond Streaking Spectroscopy of Atoms and Solids

	SLO-2	Polarization Properties of Stochastic Beams	Electromagnetic Theory of Materials	Chiroptical Effects	Symmetries and Operators	Attosecond Streaking Spectroscopy of Solids
S-8	SLO-1	Remarks on Partially Coherent	Macroscopic Viewpoint	Two-Photon Absorption	Electromagnetic Duality	Introduction to Photoemission
	SLO-2	Partially Polarized	Constitutive Dyadic	Nonlinear Light-Scattering: Sum-Frequency and Harmonic Generation	Optical Helicity	Time-Resolved Photoemission from Atoms
S-9	SLO-1	Beams Basics of Quantum Theory of Optical Coherence	Linear Materials	Resonance Energy Transfer	Electromagnetic Duality Symmetry	Streaked Photoemission from Solids
	SLO-2	Polarization of singularities	Nonlinear Materials	Van der Waals Dispersion Energy	Duality Symmetry in Piecewise Homogeneous and Isotropic Media	Attosecond Streaking from Nanostructures

Learning Resources	1. David L. Andrews, <i>Photonics, Volume 1: Fundamentals of Photonics and Physics</i> , Wiley, 2015. 2. <i>Lasers-Theory and Applications- Ghatak and Thyagarajan</i> , McMillan (2010) 3. <i>Optoelectronic devices and systems- S C Gupta</i> , Prentice Hall India (2008) 4. <i>Understanding Fiber optics- J Hecht</i> , Pearson Edu. Inc (2006)	5. <i>Light Emitting Diodes-E Fred Scheubert</i> , Cambridge University Press,(2003) 6. <i>Photonic switching technology - H T Mouftah, J M H Elmirghani</i> - IEE Press (1999). 7. Online Course: IITM-NPTEL – Introduction to Photonics. https://nptel.ac.in/courses/108106135/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Danrajpurkar, Founder, Danano Photonics, Bengaluru, dananophotonics.com	1.Dr.S.Selladurai, Physics, CEG, Anna University, ssdurai@annauniv.edu	1.Dr.Junaid masud Iascar, SRMIST
2.Mr.Satish Bhaker, Director, Sun Photonics, Newdelhi, info@sun-photonics.com	2.Dr.A.Mujeeb, International School of Photonics, CUSAT, mujeeb@cusat.ac.in	2.S.Senthilmurugan, SRMIST

Course Code	18EEE322T	Course Name	PRINCIPLES OF BIOMEDICAL INSTRUMENTATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the physiological system of the body				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Have an in depth knowledge on the devices for physiological process measurements in the human body				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Acquire knowledge on the measurement of non-electrical parameters in the human body							H	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	L
CLR-4 :	Enrich the students on the basic concepts of medical imaging, telemetry techniques and their applications							H	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLR-5 :	Expose the students to medical assisting and therapy equipments							H	-	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-
CLR-6 :	Create overall structure of biomedical instrumentation starting from physiological system to measurements and assisting equipments							H	-	-	-	-	-	-	-	-	L	-	-	-	-	H	M	L
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			1	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	L		
CLO-1 :	Explain the various systems of the human body				2	80	75	H	-	-	-	-	-	-	L	-	-	-	-	M	M	L		
CLO-2 :	Use electrodes and transducers for physiological process measurements in the human body				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-		
CLO-3 :	Measure the non-electrical quantities of the human body				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-		
CLO-4 :	Recognize the applications of medical imaging and telemetry techniques				2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-		
CLO-5 :	Relate the medical assisting and therapy equipments				2	80	75	H	-	-	-	-	-	-	L	-	-	-	-	H	M	L		
CLO-6 :	Identify the physiological systems of the body along with various measurements and assisting equipments				2	80	75	H	-	-	-	-	-	-	L	-	-	-	-	M	M	L		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Physiological systems of the body	Electrode theory	Measurement of blood pressure- direct method	X-ray machine	Need for Cardiac pacemakers
	SLO-2	Cells and their structure	Needle and wire electrode	Measurement of blood pressure-indirect method	Physical parameters for X- ray detectors	External pacemakers: Types: Vetricular asynchronous , synchronous and inhibited pacemaker
S-2	SLO-1	Characteristics of living organisms	Surface and micro electrode	Introduction to the measurement of blood flow	Digital radiography	Atrial synchronous and sequential ventricular inhibited pacemaker
	SLO-2	General characteristics of a human cell	Metal micropipette electrode	Electromagnetic blood flow meter	Diagnostic ultrasound	Implantable pacemaker
S-3	SLO-1	Nernst equation	Resistive transducers, thermistor, strain gauge	Ultra sound blood flow meter	Echocardiography	Need for defibrillator
	SLO-2	Bioelectric potential	Inductive and capacitive transducer	Laser Doppler blood flow meter	Computer tomography	DC defibrillator
S-4	SLO-1	Electrical characteristics of the human cell	Basic recording system, direct writing recorder, Ink jet recorder	Dye dilution method of cardiac output measuring techniques	CT system components	Implantable defibrillator
	SLO-2	Bioelectric potential propagation	Potentiometric recorder , Digital recorder and instrumentation type recorder	Thermal dilution method of cardiac output measuring techniques	Patient dose in CT Scanners	Mechanics of respiration
S-5	SLO-1	Cardiovascular system	Lead system of electrocardiogram	Heart rate measurement	Principles of Magnetic resonance Imaging systems	Artificial ventilation
	SLO-2	Blood circulation	Standard bipolar leads and unipolar leads	Measurement of heart sounds	Basic MRI components	Types of ventilators: Pressure limited ventilator
S-6	SLO-1	Heart and its mechanical activities	Recording methods of electrocardiogram	Gas analysers	Image reconstruction techniques	Volume limited and servo controlled ventilators

	SLO-2	Electrical potentials generated within the heart	Typical waveforms of electrocardiogram	Blood gas analyser	Position Emission Tomography	Pressure volume flow diagram
S-7	SLO-1	Physiology of the respiratory system	Electromyography	Oximetry	Single Photon Emission Computed Tomography	Kidney machine, Artificial kidney
	SLO-2	Respiratory volumes and capacities	Measurement of conduction velocity	Ear oximeter	Thermography	Dialyzers, Types: Parallel flow dialyzer
S-8	SLO-1	Anatomy of the nervous system	Electroretinography	Pluse oximeter	Biotelemetry	Coil hemodialyzer, Hollow fiber hemodialyzer
	SLO-2	Excitation and inhibition potentials	Electrogastrography	Skin reflection oximeter	Wireless telemetry	Diathermy
S-9	SLO-1	Muscle action	Electroculography	Spirometry	Single channel telemetry system	Endoscopes
	SLO-2	Sensory system	Pneumotachography	Measurement of lung volume	Multichannel wireless telemetry system	Lasers in biomedical field

Learning Resources	1. Leslie Cromwell, Fred. J. Weibell and Ench Apleiffer, Biomedical Instrumentation and measurements Prentice Hall of India, 2 nd ed., 2004	3. C.Raja Roa & .K Guha, Principles of medical electronics and biomedical instrumentation, Universities press, 2001
	2. Kandpur R.S, Handbook of Biomedical Instrumentation, Tata McGraw Hill, 2 nd ed., 2011	4. G.Webster, Medical Instrumentation Application and Design, 3 rd ed., Wiley India edition, 2009. 5. https://swayam.gov.in/nd1_noc19_bt28/preview ,NPTEL Online Course-Bioelectricity

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Manjunath rao, Alstrom,manjunath.rao1103@gmail.com	1. Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gceekjr.ac.in	1. Dr.Y.Jeyashree, SRMIST
2. Mr.Srinath rao, Alstrom,sreenathr.rao@alstrom.com	2. Dr. S. Ramareddy, Jerusalem College of Engineering,srr.victory@gmail.com	2. Mrs. R.Uthra, SRMIST

Course Code	18EEE323T	Course Name	AUTOMOTIVE ELECTRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Co-requisite Courses	Progressive Courses
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards

Course Learning Rationale (CLR):	The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Enrich the students on the basics of batteries			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the concepts of battery starting system			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Introduce the different methods of charging systems for batteries						H	M	M	M	-	-	-	-	-	-	-	-	M	L	-
CLR-4 :	Learn the fundamentals of Automotive Electronic devices						H	M	M	L	-	-	-	-	-	-	-	-	M	M	-
CLR-5 :	Understand different sensors and actuators used in automotive systems						H	M	L	L	-	-	-	-	-	-	-	-	M	M	-
CLR-6 :	Get idea about real time automotive electronic systems						H	-	-	-	-	-	-	-	-	-	-	-	M	M	-
							H	M	M	L	-	-	-	-	-	-	-	-	M	M	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																				
CLO-1 :	Analyze the concept of batteries & it's working			3	80	75															
CLO-2 :	Gain knowledge on the concepts of battery starting system			2	80	75															
CLO-3 :	Familiarize the principles of charging system for batteries			2	80	75															
CLO-4 :	Acquire knowledge on automotive Electronics			2	80	75															
CLO-5 :	Enhance the use of sensors and actuators in the field of automotive systems			2	80	75															
CLO-6 :	Apply the idea in real time automotive electronics			3	80	75															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Batteries and Accessories : Principle of lead acid battery	Starting System- introduction	Charging System - introduction	Introduction to Automotive Electronics
	SLO-2	Batteries and Accessories : construction of lead acid battery	Starting System - Condition at starting	Charging System - Generation of direct current	Fundamentals of Automotive Electronics
S-2	SLO-1	Characteristics of battery	Behaviour of starter during starting	Evaluating state of battery health	Current trends in automotive electronic engine management system
	SLO-2	Rating capacity and efficiency of batteries	Advantages and disadvantages	Fundamental in battery testing	Electric power Braking systems
S-3	SLO-1	Various tests on batteries	Series motor and its characteristics for starting system	Battery testing - Capacity	Electromagnetic interference suppression
	SLO-2	Visual inspection and voltage testing	Shunt motor and its characteristics for starting system	Battery testing – internal resistance	Electromagnetic compatibility
S-4	SLO-1	Lighting system: insulated and earth return system	Principle and construction of starter motor	Battery testing – self discharging quantity	Electronic dashboard instruments
	SLO-2	Vehicle circuits and systems	Cranking motor construction	Factors for degradation and ageing process	Onboard diagnostic system
S-5	SLO-1	Earthing system: Types	Working of different starter drive units	Measurement methods of battery	Security and warning system
	SLO-2	Head light and side light	Care and maintenances of starter motor	Direct measurement method	Nano-electromechanical devices
S-6	SLO-1	LED lighting system	Starter switches	Indirect measurement method	Engine Ignition
	SLO-2	Control of LED lighting system	Optoelectronic devices- solar cells	Battery Maintenance	Fuel Injection
S-7	SLO-1	Horn system	Photodiodes	New developments on battery charging system	Collision Avoidance Systems
					Various types of electric motors

	SLO-2	Wiper system and trafficator	Laser Diodes	Rate of charging	Safety Controls	Piezoelectric force generators
S-8	SLO-1	Maintenance on batteries	Light Absorption and Emission	Depth of charging	Security Alarms	Automatic transmission control systems
	SLO-2	Charging on batteries	Optical Fiber	Depth of discharging	Transmission Controls	Stepper motors
S-9	SLO-1	Health monitoring of batteries	Surface-Emitting Lasers	SoC and SoH	Navigation System	Relays- Types
	SLO-2	Battery monitoring methods	Array Lasers	Downfall modes	Applications of Automotive Electronics	Thermal Relay

Learning Resources	1. William B. Ribbens, <i>Understanding Automotive Electronics</i> , 5th Edition, Butterworth, Heinemann Woburn, 2009. 2. Tom Denton, <i>Automobile Electrical and Electronics System</i> , Elsevier, Third Edition, 2008. 3. Judge. A.W., <i>Modern Electrical Equipment of Automobiles</i> , Chapman & Hall, London, 2010.	4. Judge. A.W., <i>Modern Electrical Equipment of Automobiles</i> , Chapman & Hall, 2 nd Edition London, 1992. 5. Vinal. G.W., <i>Storage Batteries</i> , John Wiley & Sons Inc., 4 th Edition New York, 1985. 6. https://onlinecourses-archive.nptel.ac.in/ .
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	1. Dr. M.P.Selvan, NIT Trichy, selvanmp@nitt.edu	1. Mr.R.Palanisamy, SRMIST
2. Mr.Senthilkumar, ATl, rskrd1962@gmail.com	2. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	2. Dr.C.Subramani, SRMIST

Course Code	18EEE324T	Course Name	ANALOG AND DIGITAL COMMUNICATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	i		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand various analog Communication techniques.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Impart knowledge on data and pulse Communication techniques.	Thinking (Bloom)	Proficiency (%)	Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Explain various digital Communication techniques																		
CLR-4 :	Illustrate source and Error control coding																		
CLR-5 :	Gain knowledge on multi-user radio Communication																		
CLR-6 :	Apply the analog and digital Communication concepts in Communication industries																		

Course Learning Outcomes (CLO):	<i>At the end of this course, learners will be able to:</i>	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	<i>Gain knowledge on basics of analog Communication techniques</i>	2	80	75	H	M	M	-	-	-	-	-	-	M	-	-	L	-	-
CLO-2 :	<i>Analyze data and pulse Communication techniques</i>	2	80	75	H	M	M	L	-	-	-	L	-	M	-	-	-	L	L
CLO-3 :	<i>Summarize digital Communication techniques</i>	2	80	75	H	L	-	-	-	-	-	-	-	M	-	-	-	-	-
CLO-4 :	<i>Interpret Source and Error control coding.</i>	2	80	75	H	M	M	L	-	-	-	L	-	M	-	-	-	L	L
CLO-5 :	<i>Understand multi-user radio Communication</i>	3	80	75	H	L	-	-	-	-	-	-	-	L	-	-	-	-	-
CLO-6 :	<i>Acquire the overall knowledge on analog and digital Communication</i>	3	80	75	H	H	M	L	-	-	-	L	-	M	-	-	L	L	L

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Analog Communication:Introduction to Fourier Series	Pulse and data Communication:Introduction to Pulse Communication	Digital Communication:Introduction to digital Communication	Source coding and Error Control Coding: Introduction to coding	Multi-user radio Communication: Global System for Mobile Communications (GSM)
	SLO-2	Fourier Series Properties and applications	Introduction to Data Communication	Analog Communications versus digital Communications	Entropy and Properties of coding	Overview of GSM
S-2	SLO-1	Introduction to Fourier Transform	Pulse Amplitude Modulation (PAM)	Conversion of analog signal to digital form	Binary Symmetric Channel	Code division multiple access (CDMA)
	SLO-2	Fourier Transform properties	Pulse Time Modulation (PTM)	Baseband signal, band pass signal	Binary Erase Channel	Overview of CDMA
S-3	SLO-1	Modulation – Types	Pulse code Modulation (PCM)	Digital Communication systems – Functional description	Source Coding Theorem	Cellular Concept
	SLO-2	Need for Modulation	Differential pulse code modulation	Block diagram of digital Communications	Lossless data Compression Algorithms	Frequency Reuse
S-4	SLO-1	Noise: Source of Noise	Pulse position modulation(PPM)	Signal processing operations in digital Communications	Shannon fano coding	Channel Assignment
	SLO-2	External Noise, Internal Noise	Comparison of various Pulse Communication System (PAM – PTM– PCM)	Quantitative analysis of modulation schemes	Huffman Coding	Handover Techniques
S-5	SLO-1	Amplitude Modulation Theory	Data Communication: Introduction to Data Communication	Amplitude Shift Keying (ASK), Frequency Shift Keying (FSK)	Algorithm and Problem in Shannon fano coding	Overview of Multiple Access Schemes
	SLO-2	Frequency spectrum of AM wave	History of Data Communication	Phase Shift Keying (PSK)	Algorithm and Problem in Huffman Coding	Types of Multiple access

S-6	SLO-1	Double Sideband (DSB) Suppressed Carrier (SC)	Standards Organizations for Data Communication	BPSK	Error Control Coding	IEEE802.11: Wireless LANs Using CSMA/CA
	SLO-2	Conventional AM	Data Communication Circuits	QPSK	Error detection	WLAN Fundamentals
S-7	SLO-1	Single Sideband Modulation (SSB)	Data Communication codes	Principles of MSK	Parity	Cellular Digital Packet Network
	SLO-2	Vestigial Sideband (VSB) Modulation	Error Control, Hardware	Principles of QAM	Redundancy	Overview of cellular digital packet network
S-8	SLO-1	Quadrature Amplitude Modulation	Serial Interfaces	Quadrature Amplitude Modulation (QAM) – 8 QAM	Error correction	Satellite Communication
	SLO-2	Concept synthesis for AM	Parallel interfaces	Quadrature Amplitude Modulation (QAM) -16 QAM	Forward Error Correction	Satellite Networking
S-9	SLO-1	Theory of Frequency and Phase Modulation	Data Modems – Asynchronous Modem	Bandwidth Efficiency	Application, Convolution Codes	Bluetooth
	SLO-2	Comparison of Analog Communication Systems (AM – FM – PM)	Synchronous Modem	Comparison of various Digital Communication System (ASK – FSK – PSK – QAM)	Block Codes	Bluetooth Applications

Learning Resources	1. Wayne Tomasi, <i>Advanced Electronic Communication Systems</i> , 6th Edition, Pearson Education, 2009 2. Simon Haykin and Michael Moher, <i>Communication Systems</i> , 5th Edition, John Wiley and Sons, Inc., New York, 2009 3. Blake, <i>Electronic Communication Systems</i> , Thomson Delmar Publications, 2002. 4. Martin S. Roden, <i>Analog and Digital Communication System</i> , 3rd Edition, PHI, 2002 5. https://nptel.ac.in/courses/117105143/ 6. https://nptel.ac.in/courses/117105144/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Senthilkumar,ATI,rskrd1962@gmail.com	1.Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	1.Mr. D. Selvabharathi, SRMIST
2.Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	2.Dr. S. Ramareddy, Jerusalem College of Engineering,srr.victory@gmail.com	2.Dr. M. Jagabar Sathik, SRMIST

Course Code	18EEE325T	Course Name	WAVELET TRANSFORM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	<i>The purpose of learning this course is to:</i>			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Introduce the learners to wavelets- its relevant fundamentals and significance			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Establish the theory behind construction of wavelets using software tools			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Gain knowledge on the details of discrete wavelet transform						H	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-4 :	Expose the students to the conceptual aspect of multi resolution analysis						H	M	L	-	-	-	-	-	-	-	-	-	M	M	-
CLR-5 :	Illustrate data compression /extraction and signal processing applications using wavelet transform						H	M	L	-	M	-	-	-	-	-	-	-	M	M	-
CLR-6 :	Introduce wavelet functions, the advancements in technology and applications						H	M	L	-	M	-	-	-	-	-	-	-	H	H	-
							H	M	L	-	M	-	-	-	-	-	-	-	H	H	-
Course Learning Outcomes (CLO):	<i>At the end of this course, learners will be able to:</i>																				
CLO-1 :	Understand the theory and mathematics behind wavelet transform			1	75	75															
CLO-2 :	Apply the coding for construction of Daubechies and other wavelet functions			2	75	75															
CLO-3 :	Analyze use of wavelets and discrete wavelet transform for filter bank design.			2	75	75															
CLO-4 :	Analyze use of wavelets for filter design and multi resolution analysis			2	75	75															
CLO-5 :	Use software for various wavelet transform based applications			3	75	75															
CLO-6 :	Evaluate existing and new wavelet transform based applications			3	75	75															

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Wavelets- General introduction	Construction of wavelets	Discrete wavelet transform(DWT) for filter design	Multi resolution analysis (MRA) - Formal definition	Audio compression – Audio masking
	SLO-2	Fields of applications, Heisenberg's un certainty	Relationship between two scale sequences	Signal decomposition- Analysis	Need for multi resolution based image analysis	Standards specifying sub band implementation
S-2	SLO-1	Classical wavelets, Wavelet packets, Local trigonometric bases, Multiwavelets, 2G Wavelets	Relationship between reconstruction and decomposition sequences	Filtering /Frequency response	Multi resolution spaces	Image compression
	SLO-2	Gaussian, Morlet, Daubechies, Mexican Hat, Symlets, Coiflets, Complex, Biorthogonal spline wavelets.	Construction of semi orthogonal spline wavelets	Decimation (Down sampling)	Orthogonal decomposition	The JPEG standard (ITU - T.81)
S-3	SLO-1	Wavelet transform – Translation	Construction of ortho- normal wavelets	Signal reconstruction- Synthesis	Bi orthogonal and Semi orthogonal decomposition	Spatial oriented tree (SOT) code and Generalized self-similarity tree (GST)
	SLO-2	Wavelet transform -Scaling and Shifting Operation	Shannon scaling function	Filtering and Stretching (Up sampling)	Two scale relations	Embedded zero tree wavelet (EZW) code
S-4	SLO-1	Continuous wavelet transform	Meyer scaling function	Computing input co- efficient	A wavelet basis for MRA	Huffman code
	SLO-2	Discrete wavelet transform	Battle- Lemarie scaling function	Lattices and Lifting	Functional subspace relation between scaling and wavelet functions	Run length encoding
S-5	SLO-1	Mathematical prelude – Fourier transform	Daubechies scaling function	Vanishing moments	Scaled and translated version of wavelet functions	Set partitioning in hierarchical tree (SPIHT)
	SLO-2	Parseval Plancherel theorem, Convolution, Dilation and its inverse...	Graphical display – Iteration method	Perfect reconstruction filter banks- Introduction	Wavelet series	Embedded block coding with optimized truncation (EBCOT)

S-6	SLO-1	Continuous time frequency representation of signals	Spectrum method	Spectral domain analysis of a 2 channel PR filter bank	PR banks- Coding tutorial - I	Médical Imaging
	SLO-2	The windowed Fourier transform	Eigen value method	Analysis and Synthesis	PR banks- Coding practice exercises-I	Other applications
S-7	SLO-1	Signal spaces	Daubechies wavelet construction-Coding tutorial - I	Quadrature mirror filter (QMF) approach	PR banks- Coding tutorial - II	Audio compression -Simulation using software tools – Tutorial
	SLO-2	Ortho-gonality and Ortho-normality in brief	Coding practice exercises	Half band filter (HBF) approach	PR banks- Coding practice exercises	Audio compression -Simulation using software tools – Practice
S-8	SLO-1	Haar wavelet and scaling function	Daubechies wavelet construction-Coding tutorial- II	Time domain analysis	PR banks- Coding tutorial - III	Image compression -Simulation using software tools – Tutorial
	SLO-2	Triangle scaling function	Coding practice exercises	PR filter requirements	PR banks- Coding practice exercises	Image compression -Simulation using software tools – Practice
S-9	SLO-1	Short time Fourier transform -Coding tutorial	Daubechies wavelet construction-Coding tutorial- III	Bi-orthogonal filter bank	PR banks- Coding practice tutorial- IV	Image compression -Simulation using software tools – Tutorial
	SLO-2	Coding practice exercises	Coding practice exercises	Simple problems(Qualitative) for practice	PR banks- Coding practice exercises	Image compression -Simulation using software tools – Practice

Learning Resources	1. K. P. Soman, K. I. Ramachandran ,N. G. Resmi, Insights Into Wavelets: From Theory to Practice, Third edition, PHI Learning Pvt. Ltd. 2010.	3. Raguveer M Rao and Ajit S Bopardikar, Wavelet Transforms – Introduction and Applications, Pearson Education, 2008 S. Burns, A Ramesh, A Gopinath and Haitao Guo, Introduction to Wavelets and Wavelet Transform, Prentice Hall Inc.1998.
	2. J. C. Goswami and A. K. Chan, Fundamentals of Wavelets: Theory, Algorithms and Applications, John Wiley and Sons, 2011.	4. https://nptel.ac.in/courses/103106114/48

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Dr. S. Paramasivam, Danfoss Industries Pvt. Ltd, paramsathya@yahoo.com	1.Dr R. Selvarasu, Adama Science and Technology University, Ethiopia, selvarasunaveen@gmail.com	1.Ms K Subha Sharmini, SRMIST
2.Mr.Ravikumar A R, PayPal, ravikumar.venkataramani@gmail.com	1.Dr A. Venkadesan, NIT,Pudhucherry, Karaikkal, venkadesan@nitpy.ac.in , avenkyeee@gmail.com	2.Dr K Mohanraj, SRMIST

Course Code	18EEE326T	Course Name	ADVANCED CMOS DEVICES AND TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
		1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-1 :	Enrich the students to have basic knowledge in CMOS technology and scaling	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning							
CLR-2 :	Upgrade the students with the knowledge on design of CMOS devices				H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	L	H	-	-
CLR-3 :	Buildup knowledge on fabrication and isolation of advanced CMOS				H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	H	M	-	-
CLR-4 :	Outline the concept of layout dependent effect, bench marking and interconnects				H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	H	M	-	-
CLR-5 :	Understand the basic of lithography and manufacturability				H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	H	H	-	-
CLR-6 :	Upgrade the knowledge in Nano CMOS devices				H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	H	H	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)																
CLO-1 :	Describe the operation of CMOS devices and scaling technology	2	80	75																			
CLO-2 :	Interpret how modern CMOS devices are designed for better power performance	3	80	75																			
CLO-3 :	Perceive knowledge on basic fabrication process flow steps of advanced CMOS devices and isolation	3	80	75																			
CLO-4 :	Advance knowledge on layout dependent effect, bench marking and interconnects	3	80	75																			
CLO-5 :	Infer knowledge about advanced lithography and manufacturability	3	80	75																			
CLO-6 :	Gain knowledge to develop new improved CMOS devices	3	80	75																			

Duration (hour)		9	9	9	9	9
S-1	SLO-1	History of silicon technology	Mobility enhancement techniques	Fabrication issues	Compact modeling of analog process	Basics of sub wavelength lithography
	SLO-2	Review of CMOS scaling, moore's law	Gate dielectric material	Process integration	Digital benchmarking of models	Advanced lithography
S-2	SLO-1	Junction diode	High K material and Material selection	Atomic layer integration	Layout dependent effects	Design for manufacturability (DFM)
	SLO-2	MOS capacitor	Electronic structure of transition metal and rare earth metals	Metal organic chemical vapor deposition	Metallization	Economic motives for DFM
S-3	SLO-1	Circuit considerations	Band gap energies	Physical vapor deposition	Gate electrodes	Lithographic techniques and tools for advanced technology nodes
	SLO-2	CMOS latch-up	Band off-set energies	Etching	Reduction in device parasitics	Optical proximity correction
S-4	SLO-1	MOS transistor classical models	Bond iconicity and dielectric constant	Fabrication of drain and source	Test structures for characterization	Lithography limited yield
	SLO-2	Threshold voltage and V-I characteristics	Carrier effective masses	Ultra shallow junctions	Characterization variation effects on scaling	Catastrophic failures
S-5	SLO-1	Short channel effects	Thermal stability	Isolation techniques	Dopant activation methods	Lithography driven DEM solutions
	SLO-2	Drain induced barrier lowering	Disorders and defects	Device, well and dielectric isolation	Device isolation pitch	Classical approach
S-6	SLO-1	Gate leakage current	Extrinsic defects	Integration challenges	Interconnects	Printability checkers
	SLO-2	Tunneling	High -K / Si Interface traps	Dopant activation methods	Limits of interconnects	ASIC cell optimization
S-7	SLO-1	Sub-threshold conduction	Fermi level pinning	Reduction of parasitics	Current interconnect technologies	Case study on emerging technology
	SLO-2	Short channel modifications	Progress integration of high K gate dielectrics and metal gates	Types of stress elements	Optical interconnects	Applications of advanced CMOS devices
S-8	SLO-1	Features and uniqueness of MOS transistors	Effect of stress	Strained isolation oxide	Scaling of device isolation	Challenges of advanced CMOS devices
	SLO-2	MOS in Deca-Nano meters	Strain on the band structure of silicon	Ultra shallow junction resistance	Layout dependent effect	CMOS technology design for mobile

S-9	SLO-1	Device structure and channel engineering	Effect of gate length on stress effect	Solution to shallow junction resistance problem	Characterization	applications CMOS technology designed for wireless applications
	SLO-2	Source , drain and gate stack engineering	Mobility enhancements in strained silicon MOSFETS	Fermi level pinning effect of strain to improve the CMOS performance	Test structures used for characterization	Special MOS devices

Learning Resources	1. J. M. Pimbley, M. Ghezzi, H. Parks, <i>Advanced CMOS Process Technology</i> , Academia Press, 2012. 2. HeiWong, <i>Nano-CMOS Gate Dielectric Engineering</i> , CRC, 2012.	3. S. Deleonibus, <i>Electronic Devices Architectures for the Nano-CMOS Era</i> , Jenny Stanford, 2009. 4. B. Wong, F. Zach, V. Moraz, A. Mittal, G. Starr, A. Kahng, <i>Nano-CMOS Design for Manufacturability</i> , Wiley, 2009. 5. http://www.ee.iitb.ac.in/~slodha/advanced-cmos-devices/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Akash Neel Dey, Grey Orange Pvt. Ltd, akash.d@greyorange.sg	1. Dr. E. S. Sreeraj, NIT-Goa, sreeraj@nitgoa.ac.in	1. Dr. R. Femi, SRMIST
2. Mr. Prakhar Kumar Verma, Xilinx India, prakhar10692@gmail.com	2. Dr. Pravin Mane, BITS-Pilani, pravinmane@goa.bits-pilani.ac.in	2. Dr. M. Jagabar Sathik, SRMIST

Course Code	18EEE327T	Course Name	SENSORS AND TRANSDUCERS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Expose the students to various sensors and transducers for measuring quantities.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Emphasize the general background and operational concepts in sensors and transducers																							
CLR-3 :	Elicit the characteristics of inductive and capacitive transducers.																							
CLR-4 :	Examine the advances in sensor technology.																							
CLR-5 :	Facilitate the application of microsensors and actuators																							
CLR-6 :	Analyse the performance of various sensors and transducer																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLO-1 :	Enumerate the basics of sensors and transducers				2	75	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
CLO-2 :	Summarize the underlying principles and performance of different sensors				2	75	75	H	H	-	-	-	-	-	M	-	-	-	-	-	-	M		
CLO-3 :	Acquire knowledge on the basic conditioning circuits for inductive and capacitive transducers				2	75	75	H	H	-	-	-	-	-	M	-	-	-	-	-	-	M		
CLO-4 :	Upgrade the knowledge in sensor technology				2	75	75	H	-	-	-	-	-	-	M	-	-	-	-	-	-	M		
CLO-5 :	Attain a broad area of knowledge in Micro sensors and Actuators				2	75	75	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-		
CLO-6 :	Predict correctly the expected performance of various sensors and transducers				2	75	75	H	H	-	-	-	-	-	M	-	-	-	-	H	M	M		

Duration (hour)		9	9	9	9	9
CVVVS-1	SLO-1	General concepts of measurement systems	Resistive Transducers	General factors governing the design of self-inductance transducer	Piezoelectric transducer	Introduction to Micro sensor
	SLO-2	Terminologies of measurement systems	Principle of operation, construction details	Variable inductance transducer	Hall Effect transducers	Transducers and its interface standard
S-2	SLO-1	Transducer classification based on principle of transduction	Potentiometer ,Characteristics	Linear Variable Differential Transformer	Magnetostrictive transducers	Evolution of micro-fabrication
	SLO-2	Flow rate sensing elements	Applications of potentiometer	Expression for mutual inductance variation	Fiber optic Sensors	Evolution of Micro system and Microelectronics
S-3	SLO-1	Classification of errors	Loading effect	Rotary variable differential transformer	Geiger counters	The multidisciplinary nature of MEMS, Miniaturization
	SLO-2	Error Analysis	Strain Gauge, Types of Strain gauges	Applications of LVDTs	Scintillation detectors.	Applications of micro systems in automotive, and health care
S-4	SLO-1	Units and standards of measurements	Applications of Strain gauges	Output input relationship	Film sensor	Applications of micro systems in aerospace, and teleCommunication fields
	SLO-2	General input and output configuration	Gauge Factor	Microsyn Transducer	Magneto elastic sensor	Biomedical sensors
S-5	SLO-1	Analog & digital modes of operation	Load cells	Control type Synchro system	Digital displacement sensors	Biosensors
	SLO-2	Null & deflection methods	Torque measurement using strain gauges.	Resolvers classification and application	Proximity sensors	Chemical sensors
S-6	SLO-1	Methods of correction for interfering & modifying inputs	Pressure measurement using strain gauges	Capacitive Transducer	Pneumatic sensors	Optical sensors
	SLO-2	Static characteristics of a measurement	Measurement of Linear Velocity	Variable Area Type Capacitive	Semiconductor sensor	Pressure sensors

		system		Transducers		
S-7	SLO-1	Dynamic characteristics of a measurement system	Resistance Thermometers	Variable Air Gap type Capacitive Transducers	Smart sensors	Acoustic wave sensors
	SLO-2	Statistical analysis of measurement data	Thermocouples	Variable dielectric constant type	Radiation sensors	Microactuators
S-8	SLO-1	Electric Transducer	Thermistors	Sensitivity factors	Pyroelectric type	Actuators using thermal forces
	SLO-2	Advantages of Electric Transducer	Thermistor material, shape, ranges and accuracy specification	Nonlinearity factors	Digital encoding Transducer	Actuators using shape memory alloy
S-9	SLO-1	Transducer actuating mechanism	Hotwire anemometers	Advantages of capacitive transducer	Photo optic Transducer	Actuators using piezoelectric crystals
	SLO-2	Factors influencing the choice of transducer	Temperature compensation	Applications of capacitive transducer	Environmental Monitoring sensors (Water Quality & Air pollution)	Actuators using electrostatic forces

Learning Resources	1. Sawhney. A.K, A Course in Electrical and Electronics Measurements and Instrumentation, 19th Edition, DhanpatRai & Company Private Limited, 2014. 2. Doebelin. E.A, Measurement Systems – Applications and Design, Tata McGraw Hill, New York, 2007..	3. PatranabisD, Sensors and Transducers, Prentice Hall of India, 2010. 4. Joh. 4.P, Bentley, Principles of Measurement Systems, III Edition, Pearson Education, 2000 5. https://nptel.ac.in/courses/112103174/3
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	1. Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	Ms. S.Lourdu Jame,SRMIST
2. Mr.Senthilkumar,ATI,rskrd1962@gmail.com	2.Dr. S. Arul Daniel, NIT Trichy, daniel@nitt.edu	Dr.S.Padmini, SRMIST

Course Code	18EEE416T	Course Name	MEDICAL ELECTRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Create knowledge on physiological system of the human body	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn the various biomedical sensor and amplifiers	Thinking (Bloom)	Proficiency (%)	Attainment (%)	Engineering Knowledge	Analysis	Development	Design,	Tool Usage	Culture	Ethics & Sustainability	Team Work	Communication	Finance & Learning					
CLR-3 :	Identify the bio potential electrodes used for ECG, EEG, EOG and ENG measurements																		
CLR-4 :	Understand the various analysis techniques of bio signals and data acquisition systems																		
CLR-5 :	Expose the students to various medical application using optical electronics																		
CLR-6 :	Demonstrate the physiological system, its measurements and application of electronics in the medical field																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Describe the physiological system of the body	2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	-	M	-
CLO-2 :	Use the biomedical sensor and amplifiers	3	80	75	H	-	-	-	H	-	-	L	L	-	-	-	L	M	L
CLO-3 :	Recognize the biopotential electrodes used for ECG, EEG, EMG, ERG and EOG measurements	2	80	75	H	-	-	-	-	-	-	-	-	-	-	-	L	M	-
CLO-4 :	Apply and analyze bio signals and data acquisition system for biomedical application	3	80	75	H	-	-	-	H	-	-	-	L	-	-	-	L	M	-
CLO-5 :	Interpret the various medical application using optical electronics	2	80	75	H	-	-	-	-	-	-	L	-	-	-	-	H	M	L
CLO-6 :	Identify the human body physiological system along with various measurements and application of electronics in the medical field	3	80	75	H	-	-	-	H	-	-	L	L	-	-	-	H	M	L

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to the physiological system of the body	Sensor parameters	Electrode-electrolyte interface	Introduction to bio signal analysis	Introduction to medical application using optical electronics
	SLO-2	Cardiovascular system	Physical principle of sensing	Electrode types: Surface metal plate electrode	Analog and digital method	Charge coupled devices
S-2	SLO-1	Respiratory system	Strain gauge, Piezo electric transducer	Needle and wire electrode	Types of analog to digital converters	Interline transfer
	SLO-2	Parts of respiratory system	Load cell, pitot tube	Micro electrode	Flash type ADC	Fiber optics introduction
S-3	SLO-1	Nervous system	High impedance charge output	Electrocardiography: Lead system for recording ECG	Types of digital to analog converters	Fiber optics classification
	SLO-2	Structure of neuron and phenomenon of impulse transmission	Linear variable differential transformer	ECG measurement	Successive approximation DAC	Features of optical fibers
S-4	SLO-1	Sources of biomedical signals	Hall effect magnetic sensor	Electro cardio graph	Signal to noise improvement	Analysis of optical fiber
	SLO-2	Basic medical instrumentation system	Optical encoder	Electroencephalography: Signal sources	Amplitude measurements	The step-index fiber
S-5	SLO-1	Performance requirements of medical instrumentation system	Accelerometer	Placement of electrodes	Signal recovery	Graded index fiber
	SLO-2	Intelligent medical instrumentation system	RTD	EEG recording modes	Data acquisition	CT Scanners
S-6	SLO-1	Use of microprocessors in medical instruments	Thermistor	Electroencephalograph	Sample and hold conversion	Sectional imaging
	SLO-2	The microprocessor	Thermocouple	Electromyography: EMG electrodes	ECG acquisition	Digital imaging
S-7	SLO-1	The microcontroller	Sensor interfacing	Electromyograph	EMG acquisition	Endoscope

	SLO-2	Interfacing of analog signals to microprocessors	Driving bridges	Determination of conduction velocities in motor nerves	EOG acquisition	Digital X rays
S-8	SLO-1	PC based medical instruments	Signal conditioning amplifiers	Quantity of electricity associated with muscle contraction	EEG acquisition	Medical sensors from fiber optics
	SLO-2	General constraints in design of medical instrumentation systems	Instrumentation amplifiers	Electrical activity of EOG signal	ERG acquisition	Fiber optics for circulatory system
S-9	SLO-1	Regulations of medical devices	Isolation amplifiers	Electroretinograph	Pattern recognition	Fiber optics for respiratory system
	SLO-2	Types of standards	Simulation of pressure sensor	Electrooculograph	Simulation of flash type ADC	Lasers in biomedical field

Learning Resources	<ol style="list-style-type: none"> 1. Leslie Cromwell, Fred. J. Weibell and Ench Apleiffer, <i>Biomedical Instrumentation and measurements</i> Prentice Hall of India, 2nd ed., 2004 2. Kandpur R.S, <i>Handbook of Biomedical Instrumentation</i>, Tata McGraw Hill, 2nd ed., 2011 3. C.Raja Roa & .K Guha, <i>Principles of medical electronics and biomedical instrumentation</i>, Universities press, 2001 4. Rinaldo J. Perez, <i>Design of medical electronic devices</i>, Academic press 2002 5. https://swayam.gov.in/nd1_noc19_bt28/preview ,NPTEL Online Course-Biomedical nanotechnology
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	1.Dr. S. Ramareddy, Jerusalem College of Engineering, srr.victory@gmail.com	1. Dr.Y.Jeyashree, SRMIST
2. Mr.senthilkumar, ATi, rskrd1962@gmail.com	2.Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekr.ac.in	2. Mrs. R.Uthra, SRMIST

Course Code	18EEE417T	Course Name	ADVANCED SEMICONDUCTOR DEVICES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Outline the aspects of electrical properties of semiconductors			
CLR-2 :	Learn about diode fabrication, properties, and characterization			
CLR-3 :	Provide the fundamentals of MOSFET fabrication and scaling laws			
CLR-4 :	Enrich the knowledge on structure quantum effects and development of advanced transistor devices			
CLR-5 :	Upgrade knowledge on basic principle of operation of LED and solar cell			
CLR-6 :	Understand the characteristics, operation and limitations of semiconductor devices			

Learning				Program Learning Outcomes (PLO)														
1	2	3		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Thinking (Bloom)	Proficiency (%)	Attainment (%)		Engineering Knowledge	Problem Analysis	Design & Development	Design, Research & Innovation	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Management & Finance	Life Long Learning			

Course Learning Outcomes (CLO):		Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLO-1 :	Enrich the knowledge on semiconductor material, properties and classical semiconductor devices	2	80	75	H	L	L	L	-	-	-	-	-	-	-	-	H	H	-
CLO-2 :	Interpret the fabrication and characterization of PN diode	3	80	75	H	L	L	L	-	-	-	-	-	-	-	-	M	H	-
CLO-3 :	Perceive knowledge on advanced MOSFET devices, characteristics, application and fabrication	3	80	75	H	L	L	L	-	-	-	-	-	-	-	-	H	H	-
CLO-4 :	Gain knowledge of hetero structure, quantum effect and transport in the development of advanced transistor devices	3	80	75	H	L	L	L	-	-	-	-	-	-	-	-	L	M	-
CLO-5 :	Infer knowledge on optoelectronics, solar cell and photovoltaic	3	80	75	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-6 :	Gain knowledge to develop new semiconductor devices	3	80	75	H	L	L	L	-	-	-	-	-	-	-	-	M	H	-

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Semiconductor materials	Structure of PN junction diode	Metal oxide semiconductor transistor structure	Bipolar transistor structure
	SLO-2	Electrons and holes	Zero applied bias	Working of two terminal MOS structure	Principle and modes of operation
S-2	SLO-1	Crystal structures	Reverse applied bias	Inversion channel MOSFET	Minority carrier distribution
	SLO-2	Atomic bonding and bond models	Fabrication process	MOSFET Scaling effect	Low frequency common base current gain
S-3	SLO-1	Equilibrium and non-equilibrium	Non uniform doped junction	Electrical and DC MOSFET characteristics	Nonlinear effects
	SLO-2	Imperfections and Impurities in Solids	Equilibrium electrical properties of a PN junction	Capacitance - voltage characteristics	Equivalent circuit models
S-4	SLO-1	Statistical distribution	PN junction current	Current-voltage characteristics	Frequency limitations
	SLO-2	Drift and diffusion	DC electrical characteristics	Fabrication of MOSFET	Hetero structure and Quantum well
S-5	SLO-1	Generation and recombination	Small signal model of PN junction	Small signal analysis	Super lattice and modulation
	SLO-2	Principles of Quantum mechanics	Small signal characteristics	Frequency limitations	Two dimensional electron gas (2DEG)
S-6	SLO-1	Schrodinger's Wave Equation	Diode switching transients	Switching properties and circuit applications	Coulomb blockade effect, quantized transport
	SLO-2	Extensions of the wave theory to atoms	Generation and recombination current	CMOS technology	Large signal switching
S-7	SLO-1	Quantum theory of solids	Charge storage	Gallium nitride (GaN) and Silicon Carbide (SiC) based devices	Ballistic transport and Quantum capacitance

	SLO-2	Allowed and forbidden energy bands	Junction breakdown	Tunneling field effect transistor (TFET)	High electron mobility transistor (HEMT)	Optical switches and amplifiers
S-8	SLO-1	Electrical conduction in solids	Tunnel diode	Thin film transistor (TFT)	Modulation doped FET (MODFET)	Active nano crystalline devices
	SLO-2	Semiconductor in equilibrium	Schottky diode	Junction gate field effect transistor (JFET)	Single electron and hetero junction transistor	Nano electronics
S-9	SLO-1	Carrier transport phenomena	Metal-semiconductor junctions	Nonlinear effects	Ballistic transistor	Applications of nano electronics
	SLO-2	Non-equilibrium excess carriers in semiconductors	Hetero junctions	Threshold voltage modifications	Poly silicon emitter and silicon-germanium transistor	Organic semiconductors

Learning Resources	1. Donald A. Neamen, <i>Semiconductor Physics and Devices: Basic Principles</i> , Fourth Edition, McGrawHill, 2012. 2. Streetman, S. K. Banerjee, <i>Solid State Devices</i> , Ed. 6, Prentice Hall, 2006.	3. S.M. Sze, Kwok K. Ng, <i>Physics of Semiconductor Devices</i> , Third Edition, Wiley, 2007 4. Chih-Tang Sah, <i>Fundamentals of Solid-State Electronics</i> , World Scientific, 1996. 5. http://www.ioffe.ru/SVA/NSM/Semicond/index.html
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Prakhar Kumar Verma, Xilinx India,, prakhar10692@gmail.com	1. Dr. E. S. Sreeraj, NIT-Goa, sreeraj@nitgoa.ac.in	1. Dr. R. Femi, SRMIST
2. Mr. Akash Neel Dey, Grey Orange Pvt. Ltd, akash.d@greyorange.sg	2. Dr. Dipankar Pal, BITS-Pilani, dipankarp@goa.bits-pilani.ac.in	2. Dr. M. Jagabar Sathik, SRMIST

Course Code	18EEE418T	Course Name	MOBILE COMMUNICATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Educate on Cellular Concepts and Wireless Standards			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the Statistical Multipath Channel Models.			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Provide adequate knowledge on Digital Modulation & Multiple Access Schemes						H	M	-	-	-	-	-	M	-	-	-	-	H	M	M
CLR-4 :	Give a basic knowledge in Capacity of Wireless Channels						H	M	-	-	-	-	-	-	-	-	-	-	H	M	-
CLR-5 :	Educate on Multiple Antennas & Space Time Communications						H	M	-	-	-	-	-	-	-	-	-	-	H	L	-
CLR-6 :	Create overall understanding of cellular concepts, multiple antennas and space time Communication.						H	M	-	-	-	-	-	M	-	-	-	-	H	M	M
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:						H	M	-	-	-	-	-	M	-	-	-	-	H	M	M
CLO-1 :	Gain Knowledge in the concepts of cellular Communication.			1	80	75															
CLO-2 :	Comprehend the statistical multipath channel models			2	80	75															
CLO-3 :	Infer the various schemes in the digital modulation and multiple access			2	80	75															
CLO-4 :	Identify the capacity of wireless channels			2	80	75															
CLO-5 :	Recognize the concepts on multiple antennas & space time Communications			3	80	75															
CLO-6 :	Gain Knowledge on the overall Communication process involved in cellular Communication.			3	80	75															

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Evolution of Mobile Radio Communication	Signal propagation	Multiple access schemes-FDMA (Frequency Division Multiple Access)	Capacity in Additive White Gaussian Noise Channel
	SLO-2	Cellular Telephone Systems-Cell structures	Propagation mechanism- reflection,	Non-linear effects in FDMA	Capacity of flat fading channels-Channel and System Model
S-2	SLO-1	Frequency Reuse	Refraction	TDMA (Time Division Multi Access)	Channel and Distribution Information Known
	SLO-2	Example Problems in Frequency Reuse	Diffraction	Efficiency of TDMA and number of channels in TDMA system	Channel side information at receiver
S-3	SLO-1	Improving Coverage and Capacity in Cellular Systems-Cell Splitting	Scattering	Spread spectrum multiple access: CDMA (Code-Division Multiple Access)	Shannon (Ergodic) Capacity
	SLO-2	Sectoring	Large scale signal propagation	Hybrid FDMA/CDMA(FCDMA)	Capacity with outage
S-4	SLO-1	Repeaters for Range Extension	Lognormal Shadowing	SDMA(Space Division Multiple Access)	Channel side information at transmitter and receiver
	SLO-2	A Microcell Zone Concept	Small-Scale Fading and Multipath -Small-Scale Multipath Propagation	Modulation schemes- BPSK (Binary Phase-shift keying)	Shannon Capacity
S-5	SLO-1	Channel assignment Strategies	Doppler shift, Parameters of Mobile Multipath Channels	Spectrum and Bandwidth of BPSK	Zero-Outage capacity and channel inversion
	SLO-2	Handoff Strategies - Prioritizing Handoffs	Types of Small-Scale Fading	QPSK (Quadrature Phase Shift Keying), Spectrum and Bandwidth of QPSK Signals	Outage capacity
S-6	SLO-1	Practical Handoff Considerations	Statistical multipath channel models	QPSK Transmission and Detection	Truncated Channel Inversion
	SLO-2	Interference and System Capacity	Narrowband Wideband Fading Models	Offset QPSK	Capacity with receiver Diversity

S-7	SLO-1	Channel Planning for Wireless Systems	Power delay profile	$\pi/4$ QPSK	Capacity comparisons	System examples- GSM
	SLO-2	Adjacent Channel Interference	Average and RMS delay spread	$\pi/4$ QPSK transmission and detection techniques	Channel and System Model	EDGE
S-8	SLO-1	Power Control for Reducing Interference- Power control of Cellular Circuits	Coherence bandwidth and Coherence time	QAM (quadrature amplitude modulation)	Capacity of frequency selective fading channels	GPRS
	SLO-2	Wireless Standards: Overview of 2G	Flat and Frequency selective fading	MSK (minimum-shift keying) and GMSK (Gaussian minimum shift keying)	Time Invariant Channels	IS-95
S-9	SLO-1	3G cellular standards	Slow and fast fading	Multicarrier Modulation	Time Varying Channels	CDMA 2000
	SLO-2	Channel Planning for Wireless Systems	Average fade duration and Level crossing rate	OFDM (Orthogonal Frequency-Division Multiplexing)	Optimal Power allocation of Block Frequency -Selective Fading	WCDMA.

Learning Resources	1. Andrea Goldsmith, Wireless Communications, Cambridge University Press, 2005.	3. David Tse and Pramod Viswanath, Fundamentals of Wireless Communication, Cambridge University Press, 2005.
	2. Theodore Rappaport, Wireless Communications: Principles and Practice, 2nd edition, Prentice Hall, 2001.	4. Rishi Kappal and Milind Pande, Nex Gen Mobile Communication, Mc Graw, 2015. 5. https://www.youtube.com/playlist?list=PL1A4AFAC7AC1909C9

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Mr. C. Madesh, Bharti Airtel, madesh.c@airtel.com		1. Dr. G. Lakshmi Narayanan, NIT, Trichy, laksh@nitt.edu
2. Mr. K. Muniyandi, Omantel TeleCommunication, muniyandi.kannadasan@omantel.com		2. Dr. G. Thavasi Raja, NIT Trichy, thavasi@nitt.edu
		Internal Experts
		1. Mr. T. Vigneswaran, SRMIST
		2. Dr. M. Jagabar sathik, SRMIST

Course Code	18EEE419T	Course Name	SATELLITE COMMUNICATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Educate on Elements of Satellite Communications and Orbital Aspects	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-2 :	Understand the role of Satellite Link				H	M	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-	
CLR-3 :	Provide adequate knowledge on Modulation for Satellite Links				H	M	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-	
CLR-4 :	Extend knowledge on Multiple Access for Satellite Links				H	H	-	-	-	-	-	-	-	-	-	-	-	-	M	H	-	
CLR-5 :	Enlighten the Error Control For Digital Satellite Links				H	H	-	-	-	-	-	-	-	-	-	-	-	-	H	H	-	
CLR-6 :	Educate various concepts in Satellite Communication				H	H	-	-	-	-	-	-	-	-	-	-	-	-	H	H	-	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Gain knowledge on elements of satellite Communications and the concepts of Satellite Orbits	1	80	75																		
CLO-2 :	Relate the role of Satellite Link	2	80	75																		
CLO-3 :	Infer the necessity of Modulation for Satellite Links	2	80	75																		
CLO-4 :	Interpret the Multiple Access For Satellite Links	2	80	75																		
CLO-5 :	Inspect Error Control For Digital Satellite Links	3	80	75																		
CLO-6 :	Gain Knowledge on various concepts related to Satellite Communication	3	80	75																		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Satellite systems-Attitude and Orbit Control System(AOCS)	Basic Transmission Theory	Frequency modulation, Waveform Equation for FM	Frequency Division Multiple Access (FDMA)	Error detection and correction
	SLO-2	Telemetry, Tracking, Command and Monitoring (TTC&M)	Example Problems in Transmission Theory	Bandwidth of FM Signals: Carson's Rule	Inter Modulation, Inter Modulation Example	Channel Capacity
S-2	SLO-1	Power Systems, Communication Subsystems	System noise temperature	Baseband S/N Ration for FM Signals	Calculation of C/N with Intermodulation	Error Control Coding
	SLO-2	Satellite Antennas	Calculation of System noise temperature	Pre-emphasis and de-emphasis	Time Division Multiple Access (TDMA)	Linear and Cyclic Block Codes
S-3	SLO-1	Transmission and Multiplexing	Noise figure and Noise Temperature	Analog FM Transmission by satellite	Bits, Sample and Channels	Golay Codes
	SLO-2	Modulation Multiple access-advnt of Digital satellite Communications	G/T ratio for Earth Stations	Television Signals	TDMA Frame Structure	Performance of Block Error Correction Codes
S-4	SLO-1	The Equations of the Orbit	Design of Downlink	S/N Rations for FM Video Transmission	Synchronization in TDMA Networks	Convolution Codes
	SLO-2	Locating the Satellite in the Orbit	Link Budgets	FM Threshold, SCPC FM Links	Transmitter Power in TDMA Networks	Implementation of Error Detection on Satellite Links
S-5	SLO-1	Orbital elements	Design of Uplink	Concept of FM Squared of transmitting analog satellite audio	Satellite Switched TDMA	Concatenate Coding
	SLO-2	Look angle Determination- The Sub-satellite point	Limits on link performance	Digital Transmission	On-board Processing	Interleaving
S-6	SLO-1	Elevation angle Calculation	Design of Satellite links for specified	Baseband Digital Signals,	Baseband Processing Transponders	Turbo Codes

			(C/N)			
	SLO-2	Azimuth angle Calculation	Overall (C/N) ₀ with Uplink and Downlink Attenuation	Base Band Transmission of Digital Data	Satellite Switched TDMA with Onboard Processing	Repetition Codes
S-7	SLO-1	Geostationary orbit	Uplink and Downlink Attenuation in Rain	Band-pass Transmission of Digital Data	Concept of Pre-assignment	Cyclic Codes
	SLO-2	Visibility	Uplink attenuation and (C/N) _{up} , Downlink attenuation and (C/N) _{dn}	Analysis of Digital Transmission	Demand Access Multiple Access (DAMA)	Basic of Convolution codes
S-8	SLO-1	Orbital perturbations Longitudinal Changes: Effects of the Earth's Oblateness	Satellite Design for Specific Performance	Digital Modulation	Random Access	Catastrophic Convolutional Code
	SLO-2	Inclination Changes: Effects of the Sun and the Moon	Satellite Communication Link Design Procedure	Digital Demodulation	Packet Radio Systems and Protocols	Performance of block error correction codes
S-9	SLO-1	Orbit Determination	Propagation effects and their Impact on Satellite-Earth Links Quantifying Attenuation and Depolarization: Rain and Ice effects	Digital transmission of Analog signals PCM	Code Division Multiple Access (CDMA)	Implementation of Error Detection on Satellite Links.
	SLO-2	Orbital effects in Communication system performance	Prediction of Rain Attenuation	DPCM and DM	CDMA Capacity	Example Problem on Error Detection on Satellite Links

Learning Resources	1. Dennis Roddy, <i>Satellite Communications</i> , 4 th Edition, Mc Graw-Hill, 2017. 2. Timothy Pratt, Charles W Bostian, and Jeremy Allnutt, <i>Satellite Communications</i> , John Wiley and Sons, New Delhi, 2008 3. Tri T Ha, <i>Digital Satellite Communications</i> , Tata McGraw Hill, New Delhi, 2010. 4. Richaria M, <i>Satellite Communication Systems Design Principles</i> , McGraw Hill, Inc., New York, 1999. 5. https://www.isro.gov.in/applications/satellite-Communication
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. C. Madesh, Bharti Airtel, madesh.c@airtel.com	1. Dr. G. Lakshmi Narayanan, NIT, Trichy, laksh@nitt.edu	1. Mr. T. Vigneswaran, SRMIST
2. Mr. K. Muniyandi, Omantel TeleCommunication, muniyandi.kannadasan@omantel.com	2. Dr. G. Thavasi Raja, NIT Trichy, thavasi@nitt.edu	2. Dr. A. Rathinam, SRMIST

Course Code	18EEE420T	Course Name	EMBEDDED SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)																
CLR-1 :		Illustrate the concept of embedded system.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :		Discuss the various Embedded Controllers with its Interfacing Components				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :		Explain the different Embedded System protocol layers and bit configurations.							H	-	-	-	-	-	-	-	-	-	-	-	-	-	M	-	
CLR-4 :		Understand the basics of the RTOS, its challenges and issues.							H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	M	-
CLR-5 :		Impart knowledge on the programming skills and execute the different programs using Embedded C							H	M	M	M	-	-	-	M	-	-	-	-	-	-	H	M	M
CLR-6 :		Understand the concept of embedded system and develop code for real time applications							H	M	H	H	H	-	-	M	-	-	M	-	-	-	-	H	M
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				1	75	75	H	M	H	H	H	-	-	M	-	-	-	-	H	M	M		
CLO-1 :		Understand the fundamentals of Embedded System				2	75	75	H	M	H	H	H	-	-	M	-	-	-	-	M	M	-		
CLO-2 :		Comprehend the various bus and interfacing components in digital controller.				3	75	75	H	M	H	H	H	-	-	M	-	-	-	-	M	M	-		
CLO-3 :		Implement the embedded networking concept and various bus protocols				3	75	75	H	M	H	H	H	-	-	M	-	-	-	-	M	M	-		
CLO-4 :		Analysis the concept of RTOS, the challenges and issues in RTOS.				3	75	75	H	M	H	H	H	-	-	M	-	-	-	-	M	M	-		
CLO-5 :		Develop the embedded system programs for different Real Time applications				3	75	75	H	M	H	H	H	-	-	M	-	-	-	-	H	M	M		
CLO-6 :		Design and development of Embedded coding for electrical engineering applications				3	75	75	H	M	H	H	H	-	-	M	-	-	-	-	H	M	M		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction To Embedded System: Embedded system,	Memory system mechanisms - Various memory systems	Serial Bus Communication protocols	Message Queues	Programming for LED Display
	SLO-2	Functional building block of embedded system	CPU bus - Memory devices - I/O devices	RS232 standard – RS422,RS 485	Mailboxes and Pipes	Embedded C Seven Segment Display
S-2	SLO-1	Characteristics of embedded system applications	Component interfacing Interrupt – Handler	Characteristics of RS232, RS422, RS423 and RS485	Time functions - Events	Communication Protocols:-I ² C initialization and formation
	SLO-2	Reliability, life time, power consumption	Saving and Restoring the content - Disabling Interrupts.	CAN Bus with control word registers	Memory Management	Programming using embedded C
S-3	SLO-1	Challenges in embedded system design	The Shared data Problem – Shared data bug	Serial Peripheral Interface (SPI)	Interrupt Routine in RTOS Environment.	Programming Using SPI Protocols.
	SLO-2	Optimizing the Power Dissipation, reliability, upgradability	Atomic and Critical sections – Interrupt Latency	Inter Integrated Circuits (I ² C)	Design Using RTOS : Design Principles – Short Interrupt Routines	Programming for CAN Bus Protocols
S-4	SLO-1	Embedded system design processes.	Embedded Software Architecture : Round – Robin and other cycles	ZigBee	RTOS Tasks – Tasks for Priority	Commercial Applications: Washing Machine,
	SLO-2	Characteristics of embedded system applications	Round-Robin with interrupts– A Communication Bridge as an Example	Bluetooth with various protocol	Tasks for Encapsulation	Vending machine with flow diagram
S-5	SLO-1	Types of embedded system with examples	Characteristics – Functions – Queue – Scheduling	Interfacing Protocols- GPIB	Creating and Destroying tasks	Laser Printer, underground tank monitor,
	SLO-2	Performance & Design issues	Various Queue and scheduling methods	FIREWIRE(IEEE 1394 standard)	Avoidance - Tank Monitoring System	Cordless Bar, Code Scanner
S-6	SLO-1	Performance & Design issues –	Software development process	Universal Serial Bus (USB)	Design as example – Time Scheduling	Power Electronics Applications:

		Throughput – Response – Testability – Debuggability – Reliability – Memory space – Program Installation	Architecture – Assembly and compiling Linking and loading, programme flow	Need for device drivers	Embedded Programming and Communication Protocols: Introduction	Operation of DC/DC Converter Embedded C programming for DC-DC Converter pulse generation.
	SLO-2					
	SLO-1	Power Consumption – Processor Hogs – Cost	Basic compilation techniques	Real Time Operating Systems : Tasks and Task states	Importance of Communication protocol and types of protocols	Introduction to 180Degree mode Three phase inverter
S-7	SLO-2	Small size and weight, Real time/reactive operation, End-product utility, System- level requirements	Program optimization	Tasks and Data share	Embedded C Programming for 8051	Various mode of operation and switching sequence
	SLO-1	Embedded System Architecture : Computer architecture taxonomy	Difference between task and process Multiple tasks	Shared data problems – Re-entrancy- Reentrancy Rules	Various programming language and advantage of embedded C	Programming for Three phase 180° Mode Inverter PWM pulse generation
S-8	SLO-2	Harvard , von Neumann, and hybrid architectures	Multiple processes with simple example	Semaphores and Shared data	Syntax, variable initialization and assigning a port address	Applications of Three phase inverter
	SLO-1	CPUs, various processing unit and control units	Embedded Networking: Introduction, I/O ports	RTOS Semaphores	Header file inclusions, condition loop,	Basic concept of induction motor drive and speed control of V/F method
S-9	SLO-2	Programming input and output, Supervisor mode, Exceptions & Traps, Co - processors	Different type of buses	Initializing semaphores Reentrancy and Semaphores – Multiple semaphores	Simple programme using embedded C	Controller Implementation for induction motor drive applications

Learning Resources	<ol style="list-style-type: none"> Wayne Wolf, Computers as Components: Principles of Embedded Computer Systems Design, The Morgan Kaufmann Series in Computer Architecture and Design, Elsevier Publications, 2008. Rajkamal, Embedded Systems – Architecture, Programming and Design, Tata McGraw-Hill Publishing Company Ltd., New Delhi, 3rd Edition 2010. Sriram V Iyer, Pankaj Gupta, Embedded Real-time Systems Programming, Tata McGraw-Hill Publishing Company Ltd, New Delhi, 1st Edition 2017 David E.Simon, An Embedded Software Primer, Pearson Education, 1999. Muhammad Ali Mazid, The 8051 Microcontrollers & Embedded Systems, Pearson, 2008 Kenneth Ayala, The 8051 Microcontroller & Embedded Systems using Assembly and C with CD https://nptel.ac.in/courses/108102045/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers			
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts	
1. Mr. P.Pangayaselvan, Embedded Engineer, Verizon Technologies, vpangayaselvan@yahoo.co.in	1. Dr. S.Moorthi, NIT, Trichy, srimoorthi@nitt.edu	1. Dr. M.Jagabar Sathik, SRMIST	
2. Mr. V.Suresh, Vi-Microsystem, Chennai	2. Dr.M.Manimara Boopathi, Vel Tech University	2. Dr.A.Rathinam, SRMIST	

Course Code	18EEE421T	Course Name	VLSI DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Illustrate the MOS fabrication technologies and understand the electrical properties of MOS, CMOS and Bi CMOS circuits				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Describe CMOS technology-specific layout rules in the placement and routing of transistors and interconnect and to verify the functionality, timing, power, and parasitic effects				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Describe the various parameters and its characteristics of CMOS technology																					
CLR-4 :	Identify the real-time VLSI tools and its applications																					
CLR-5 :	Interpret the various testing methods, design tools and chip-level design techniques																					
CLR-6 :	Construct the digital logic gate using VLSI design tools																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						H	-	-	-	-	-	-	-	-	-	-	-	-	M	-
CLO-1 :	Understand the steps for MOS fabrication technologies and analyze electrical behavior of MOS, CMOS and Bi CMOS circuits.				2	75	75	H	-	-	-	-	-	-	-	-	-	-	-	-	M	-
CLO-2 :	Draw the layout of integrated circuits following design rules				2	75	75	H	-	-	-	-	-	-	-	-	-	-	-	-	M	-
CLO-3 :	Analyze the different CMOS technology and its characteristics				3	75	75	H	H	H	H	M	-	-	-	-	-	-	-	M	H	-
CLO-4 :	Develop the coding for FPGA				3	75	75	H	H	H	H	M	-	-	-	-	-	-	-	H	H	-
CLO-5 :	Design a VLSI project having a set of objective criteria and design constraints				3	75	75	H	H	H	H	H	-	-	-	-	-	-	-	H	H	-
CLO-6 :	Design a digital components and basic logic gates circuits using VLSI tools				2	75	75	H	H	H	H	H	-	-	-	-	-	-	-	H	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to IC Technology–MOS	VLSI circuit design processes: MOS Layers- Mask Layout, Layer contact mask layout representation	Gate level design: Transmission Gates	Introduction to design tools FPGAs (Xilinx 4000series)–Features and basic details of FPGA	Design Approach
	SLO-2	Introduction to IC Technology -PMOS	Coloured Stick Diagrams:- capabilities and limitations of stick diagram	Gate level design: Alternate gate circuits	Various functional block diagram with merits and demerits	VLSI Design Flows & Design Verification
S-2	SLO-1	Introduction to IC Technology NMOS, CMOS	Types of Design Rules VLSI circuit design	Basic circuit concepts: Sheet Resistance RS	Different syntax of fpga coding and variables	Design methods, Design capture tools
	SLO-2	Introduction to IC Technology Bi-CMOS Historical Perspective& Bi-CMOS technologies.	Layout of circuit diagram	Concept of RS in MOS	Simple basic programme	Design Flow, Design Languages, High-level Synthesis (HLS)
S-3	SLO-1	Basic electrical properties: Basic Electrical Properties of MOS Circuits:	Layer Representations	Area Capacitance Units, Calculations, Delays	CPLDs (Xilinx 9500series)- Features and basic details	Design Verification Tools
	SLO-2	Basic electrical properties: Basic Electrical Properties of Bi-CMOS Circuits:	Example of layer presentation	Estimation of Delay and INVERTER DELAYS Estimation of CMOS inverter delay Rise & Fall time estimation	Various functional block diagram with merits and demerits	Various Steps of verifications with one example
S-4	SLO-1	Ids-Vds relationships	CMOS Design rules for wires	Capacitance Modeling Driving large Capacitive Loads	Different syntax of CPLDs coding and variables	CMOS Testing:- Fault models, Test pattern generation
	SLO-2	Ids-Vds its characteristics	Layout Design rules & Lambda (λ)	Sizing Factor (s) , Inverter gain, Delay Optimization Problem	Simple basic programme	Need for testing:- Physical defects
:S-5	SLO-1	MOS characteristics - transistor threshold Voltage, W_o	Design rules of Contacts	Wiring Capacitances, Fan-in and fan-out	Programmable Array Logic: introduction and applications	Test Principles, Design Strategies for test

	SLO-2	MOS characteristics -gm, gds characteristics	Design rules of Transistors	Effect of Capacitive Loading, Propagation Delay in Timing Diagrams	Operation and logic with simple problem	Fault Modeling, Design-for-Testability
S-6	SLO-1	Basic design parameters:- Figure of merit, Pass transistor	Layout Diagrams for NMOS Inverters and Gates	Choice of layers. SUBSYSTEM DESIGN: Shifters,	Design Approach with various steps	Chip-level Test Techniques
	SLO-2	MOS Transistor circuit model, Latch-up in CMOS circuits	Example layout of basic logic gates	Choice of layers. Adders, ALUs	Fuse mapping examples	Moving test up the flowFlop Factor
S-7	SLO-1	Characteristics of NMOS Inverter, Various pull ups	Layout Diagrams :-CMOS Inverters and Gates	Choice of layers. Multipliers	Multiplier logic	System-level Test Techniques
	SLO-2	Resistive Load, Inverter with N type MOSFET Load	Example layout of CMOS inverters	Choice of layers. Parity generators	Alternate representation of high Fan-in structures	Characterization Test, Functional Board Testing, In-circuit testing
S-8	SLO-1	CMOS Inverter circuit operation	Scaling of MOS circuits	Comparators, Zero/One Detectors	Parameters influencing low power design	Layout Design for Improved Testability
	SLO-2	CMOS and complex CMOS logic circuit	Figure(s) of Merit (FoM) for scaling, Scaling factors for device parameters	Example of problems	Dynamic Power Consumption, Leakage power dissipation	Bridge Fault Model, Bridge Fault Simulation, Test Generation for Bridge Fault
S-9	SLO-1	Performance of the BiCMOS Inverter	Implications of scaling on design of Scaling	High-Density Memory Elements	Low Power Strategies: Sources of Power Dissipation	Observability and controllability
	SLO-2	Power Consumption, Designing BiCMOS Digital Gates	Limitations of Scaling	Bitline IO Circuit, SRAM	Degrees of Freedom, Supply Voltage Scaling, Ultra Low Power System Design	False Path problem

Learning Resources	1. K. Eshraghian Eshraghian. D. A.Pucknell, Essentials of VLSI Circuits and Systems,, Edition II PHI, 2009. 2. Modern VLSI Design: Ip - Based Design 4th Edition, 2015, PHI. 3. Basic VLSI Design, 2009, reprint 2017, PHI	3. N.H.E Weste, K.Eshraghian, Principals of CMOS VLSI Design, 2nd ed., Addison Wesley, 1993. 4. Neil Weste, David Harris, CMOS VLSI Design: A Circuits and Systems Perspective ,4th Edition, 2011 5. http://nptel.ac.in/courses/117106092/#
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1 Mr.V.Pangayselvan. Aricent Technologies, Senior analyst, Chennai, pangaya.v@aricent.com	1. Dr. Shady Abdel Aleem. Higher Institute of Engineering, Mathematical, Physical and Engineering Sciences Department, Cairo, Egypt. engyshady@ieee.org	1. Dr. M.Jagabar Sathik, SRMIST
2.Mr. M.Sathisk Kumar, Senior Manager and Programme Specialist, ORCALE DB ,Bangalore	2. Dr. B.Moorthy, Associate professor, NIT Trichy	2. Dr.A.Rathinam, SRMIST

Course Code	18EEE328T	Course Name	DATA STRUCTURES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :		Illustrate the basic concepts of data structures, Search techniques and their algorithms			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :		Educate with the basic knowledge of stacks and queues			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :		Discuss the concepts of linked lists																					
CLR-4 :		Impart knowledge on trees and its algorithm																					
CLR-5 :		Outline the basics of sorting and graph																					
CLR-6 :		Create an overall knowledge of different data structure algorithms																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	H	H	M	-	-	-	-	-	-	-	-	H	M	-		
CLO-1 :		Implement and analyze the different searching algorithms						H	H	M	-	-	-	-	-	-	-	-	-	-	M	M	-
CLO-2 :		Employ different stacks and queues algorithms						H	H	M	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-3 :		Analyze the different linked list algorithms						H	M	M	-	-	-	-	-	-	-	-	-	-	H	H	-
CLO-4 :		Determine the time and computation complexity in Binary tree and AVL tree						H	H	M	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-5 :		Develop an algorithm for graph and compare the performance of sorting methods						H	H	M	-	-	-	-	-	-	-	-	-	-	H	M	-
CLO-6 :		Develop application using data structure algorithms						H	H	M	-	-	-	-	-	-	-	-	-	-	H	M	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Basic Terminologies	Array implementation of Stack ADT	Singly linked lists	Basic Tree Terminologies	Basic Terminologies of Graph
	SLO-2	Elementary Data Organizations	Stack ADT operations with example	Singly linked lists - Representation in memory	Basic Tree Operations	Representations of Graph
S-2	SLO-1	Abstract data type	Application of Stack: Infix to Postfix Conversion	Algorithm of Traversing operation	Binary Tree operations	Graph traversal algorithms - breadth first search with example
	SLO-2	Abstract data type Example	Infix to Postfix Conversion Algorithm	Algorithm of Searching operation	Algorithm of Binary Tree operations	Graph traversal algorithms - depth first search with example
S-3	SLO-1	Data Structure Operations	Application of Stack: Evaluation of postfix expression	Insertion into linked list	Binary Search Tree - operations - insertion	Prims Minimum spanning tree algorithm
	SLO-2	Types of Data Structure Operations	Evaluation of postfix expression Algorithm	Algorithm of Insertion into linked list	Algorithm of Binary Search Tree - insertion	Prims Minimum spanning tree algorithm - Example
S-4	SLO-1	Analysis of an Algorithm	Application of Stack: Balancing symbols	Deletion from linked list	Binary Search Tree - operations - deletion	Kruskal's Minimum spanning tree algorithm
	SLO-2	Applications: Analysis of an Algorithm	Balancing symbols Algorithm with example	Algorithm of Deletion from linked list	Algorithm of Binary Search Tree - deletion	Kruskal's Minimum spanning tree algorithm – Example
S-5	SLO-1	Asymptotic Notations	Queue ADT- OperationsIntroduction	Linked representation of Stack	Binary tree traversal	Bubble sort
	SLO-2	Properties of Asymptotic Notations	Queue ADT- Operations Examples	Linked representation of Stack - Example	Binary tree traversal - inorder, preorder, postorder	Bubble sort – Example
S-6	SLO-1	Time-Space trade off	Simple Queue- Operations	Linked representation of Queue	Example of Binary tree traversal	Insertion Sort algorithm
	SLO-2	Time-Space trade off Example	Algorithm of Simple Queue – Operations with examples	Linked representation of Queue - Example	Applications of Binary Trees	Insertion Sort algorithm – Example

S-7	SLO-1	Linear Search Technique	Circular Queue - Operations	Doubly linked list	AVL Tree- operations: Rotations	Selection Sort algorithm
	SLO-2	Linear Search Technique Example	Algorithm of Circular Queue - Operations	Operations on Doubly linked list	AVL Tree- operations: Rotations - Example	Selection Sort algorithm – Example
S-8	SLO-1	Complexity analysis of Linear Search Technique	Example of Circular Queue - Operations	Example of Doubly linked list	AVL Tree- operations: Insertion	Merge sort algorithm
	SLO-2	Example of Linear Search Technique	Priority Queue - Operations	Circular Linked List	AVL Tree- operations: Insertion - Example	Merge sort algorithm – Example
S-9	SLO-1	Binary Search Technique	Algorithm of Priority Queue - Operations	Circular Linked List algorithms	AVL Tree- operations: Deletion	Quick sort algorithm
	SLO-2	Complexity analysis of Binary Search Technique	Example of Priority Queue - Operations	Circular Linked List example	AVL Tree- operations: Deletion – Example	Quick sort algorithm – Example

Learning Resources	1. Aaron M.Tenenbaum, Yedidiah Langsam and Moshe J.Augenstein, Data Structures Using C, Seventh Edition, 2009, Pearson Education in South Asia.	3. https://www.youtube.com/watch?v=coxWfcz_slk&list=PLrjkTql3jnm8ikiQlelHrMYCaBfkBkFYR&index=1 4. Mark Allen Weiss, “Data Structures and Algorithm Analysis in C++”, Third Edition, 2009, Pearson Education in South Asia.
	2. G A Vijayalakshmi Pai, Data Structures and Algorithms - Concepts, Techniques and Applications, Tata McGraw-Hill Publishing Company Limited, 2008.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1.Mr.Balachandrasekar.K,CTS,dyaksha@gmail.com		1.Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in
2.Mr. Tripathi patro,visam pvt ltd,btp@visom.co.in		2.Dr. M.P.Selvan, NIT Trichy, selvanmp@nitt.edu
		Internal Experts
		1. Dr.R.Annie Uthra, SRMIST
		2. Mr.P.Kanakaraj, SRMIST

Course Code	18EEE329T	Course Name	COMPUTER SYSTEM ARCHITECTURE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Acquire knowledge about the modern computer organization technologies				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Educate the students' on machine instructions																							
CLR-3 :	Explain the modern Acorn RISC Machine (ARM) Instruction set																							
CLR-4 :	Impart knowledge about the interfacing devices																							
CLR-5 :	Identify potential of memory unit																							
CLR-6 :	Educate the students' onadvances in computer technology																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Expected Proficiency (%)	Expected Attainment (%)																		
CLO-1 :	Understand the concepts of modern computer organization				2	75	75	Problem Analysis	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLO-2 :	Analyze the machine instruction concept and operation				2	75	75	Design & Development	H	H	M	L	-	-	-	-	-	-	-	-	M	M	-	
CLO-3 :	Examine and solve issues related to Acorn RISC Machine (ARM) Instruction set				2	75	75	Analysis, Design, Research Modern Tool Usage Society & Culture Environment & Sustainability Ethics Individual & Team Work Communication Project Mgt. & Finance Life Long Learning PSO - 1 PSO - 2 PSO - 3	H	H	M	L	-	-	-	-	-	-	-	-	M	M	-	
CLO-4 :	Describe the operation of input and output units				2	75	75		H	H	M	L	-	-	-	-	-	-	-	-	M	M	-	
CLO-5 :	Examine and solve issues related to memory mapping techniques				2	75	75		H	H	M	L	-	-	-	-	-	-	-	-	M	M	-	
CLO-6 :	Acquire knowledge on the recent trends in computer technologies				2	75	75		M	H	M	L	-	-	-	-	-	-	-	-	M	M	-	
					2	75	75		H	H	M	L	-	-	-	-	-	-	-	-	M	M	-	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Computer types	Numbers ,arithmetic operations and characters	Memory access and data transfer	Accessing I/O devices	Semiconductor RAM memories
	SLO-2	Functional units of computer architecture	Memory locations	Acorn RISC Machine(ARM)- Registers	Interrupts	Read only memories
S-2	SLO-1	Operational concepts	Memory addresses	Arithmetic and logic instructions	ARM Interrupt structure	Speed size and cost
	SLO-2	Bus structures	Addressing mode	Branch Instructions	Direct memory access	Mapping techniques
S-3	SLO-1	Software Performance	Instructions and sequencing	Setting condition codes	Buses-Synchronous bus	Hit rate and miss penalty
	SLO-2	Performance and metrics	Assembly language	Loop program	Asynchronous bus	Caches on the processor chip
S-4	SLO-1	Compiler	Basic input/output operations	Pseudo instructions	Interface circuits-Serial port	Virtual memories
	SLO-2	Uniprocessors to multiprocessors	Subroutines	Byte sorting	Parallel port	Memory management requirements
S-5	SLO-1	Operations and operands	Logic instructions	Linked list insertion subroutines	Standard I/O interfaces	Second storage system
	SLO-2	Representing instructions	Branch Instructions	Linked list deletion subroutines	PCI buses	Memory hierarchy
S-6	SLO-1	Logical operations	Execution of a complete instruction	Data hazards	Universal serial bus	Memory technologies
	SLO-2	Control operations	Addition algorithm	Instruction hazards	Overview of parallelism	Cache basics
S-7	SLO-1	Multiple bus organization	Subtraction algorithm	Influence on instruction sets	Instruction-level-parallelism	Measuring cache performance
	SLO-2	Hardwired control	Multiplication algorithm	Data path and control considerations	Parallel processing challenges	Improving cache performance
S-8	SLO-1	Micro programmed control	Division algorithm	Performance considerations of pipelining	Flynn's classification	Virtual memory
	SLO-2	Multi computers	Floating Point operations	Overview of data path control	Hardware multithreading	Translation Lookaside Buffer
S-9	SLO-1	Multiprocessors	Sub-word parallelism	Pipelined datapath and control	Analysis of parallelism methods	Direct Memory Access
	SLO-2	Nano programming	Write-through and Write-back cache write method	Exception handling	Multi-core computing in parallelism	Interrupts

Learning Resources	1. M. Morris R. Mano Computer System Architecture, Pearson publishers, 3rd Edition, 2007. 2. Carl hamachar Computer Architecture and Organization, Tata McGraw hill, 5 th edition, 2015.	3. David A. Patterson Computer Organization and Design MIPS Edition: The Hardware/Software Interface (The Morgan Kaufmann Series in Computer Architecture and Design) Morgan Kaufmann; 5 edition 2013. 4. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Balachandrasekar.K, CTS, dyaksha@gmail.com	1.Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	1.Mr.S.George Fernandez, SRMIST
2.Mr.Ravikumar A R, PayPal, ravikumar.venkataramani@gmail.com	2.Dr. S. Ramareddy, Jerusalem College of Engineering, srr.victory@gmail.com	2.Ms.R.Rajarajeswari, SRMIST

Course Code	18EEE330T	Course Name	COMPUTER NETWORKING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the protocols of modern networking technologies				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Educate the students' on data format& data transfer at high speed Communication				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Explain the modern transport layer technologies																					
CLR-4 :	Identify advances in technology that may solve the actual limitations with existing networks																					
CLR-5 :	Impart knowledge about modern technologies used in application layer																					
CLR-6 :	Educate the students on network security																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Acquire knowledge about the protocols of modern networking technologies				2	75	75	H	H	M	L	-	-	-	M	-	-	-	-	H	M	M
CLO-2 :	Analyze the physical properties and performance characteristics of Communication media				2	75	75	H	H	M	L	-	-	-	M	-	-	-	-	H	M	M
CLO-3 :	Examine and solve issues related to congestion management				2	75	75	H	H	M	L	-	-	-	M	-	-	-	-	H	H	M
CLO-4 :	Describe the importance of reliability and quality of service, for error recovery, traffic differentiation and prioritization.				2	75	75	H	H	M	L	-	-	-	M	-	-	-	-	H	H	M
CLO-5 :	Develop an appreciation of the theory of common application layer.				2	75	75	H	H	M	L	-	-	-	M	-	-	-	-	H	M	M
CLO-6 :	Acquire knowledge about the network security system.				2	75	75	H	H	M	L	-	-	-	M	-	-	-	-	H	M	M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	<i>Historical perspective of computer networking</i>	<i>Theoretical basis for data Communication</i>	<i>Overview of Transport layer</i>	<i>Causes of errors on data transmission</i>	<i>Traditional applications</i>
	SLO-2	<i>Theoretical models of network architecture</i>	<i>Guided transmission media</i>	<i>Elements of transport protocol</i>	<i>Impact of errors on data transmission</i>	<i>Electronic Mail</i>
S-2	SLO-1	<i>Practical models of network architecture</i>	<i>Bounded type transmission mode</i>	<i>Functions of transport layer</i>	<i>Single bit errors</i>	<i>Simple Mail Transfer Protocol</i>
S-3	SLO-2	<i>Introduction to ISO</i>	<i>Unbounded type transmission mode</i>	<i>Addressing modes</i>	<i>Burst errors</i>	<i>POP3</i>
	SLO-1	<i>ISO OSI Seven-layer model</i>	<i>Magnetic Media</i>	<i>Service point addressing</i>	<i>Need for error detection</i>	<i>Web Services</i>
S-4	SLO-2	<i>TCP protocol</i>	<i>Issues with magnetic media</i>	<i>Segmentation process</i>	<i>Error detection strategies</i>	<i>Http</i>
	SLO-1	<i>IP protocol</i>	<i>Need for cable transmission modeS</i>	<i>Reassembling process</i>	<i>Overview of error correction</i>	<i>Multimedia</i>
S-5	SLO-2	<i>Comparison of OSI and TCP/IP reference models</i>	<i>Twisted Pair cable</i>	<i>User datagram protocol</i>	<i>Error correction strategies</i>	<i>Domain Name System</i>
	SLO-1	<i>Synchronous transfer mode protocol</i>	<i>Baseband Coaxial Cable</i>	<i>Reliable byte stream</i>	<i>Parity Checks</i>	<i>Simple Network Management Protocol</i>
S-6	SLO-2	<i>Asynchronous transfer mode protocol</i>	<i>Broadband Coaxial Cable</i>	<i>Connection management</i>	<i>Block sum Check</i>	<i>File Access and Management</i>
	SLO-1	<i>Frame relay protocol</i>	<i>Narrowband ISDN</i>	<i>Causes of Congestion</i>	<i>Sliding window protocol</i>	<i>Overview of Network security</i>
S-7	SLO-2	<i>Frame Relay and the OSI Reference Model</i>	<i>Broadband ISDN</i>	<i>Retransmission</i>	<i>Elementary data link protocol</i>	<i>Cryptography</i>
	SLO-1	<i>Digital subscriber line technology</i>	<i>Microwave transmission</i>	<i>Congestion Control</i>	<i>Protocol identification</i>	<i>Symmetric key algorithm</i>
S-8	SLO-2	<i>Variation in DSL technology</i>	<i>Electromagnetic Spectrum</i>	<i>Flow control</i>	<i>Protocol verification</i>	<i>Public key algorithm</i>
	SLO-1	<i>2G technology</i>	<i>Radio transmission</i>	<i>Performance issues</i>	<i>Forward error control</i>	<i>Digital signature</i>
S-8	SLO-2	<i>3G,4G technology</i>	<i>Fiber optics</i>	<i>Quality of service</i>	<i>Backward error control</i>	<i>Management of public keys</i>

S-9	SLO-1	Wi-Fi technology	Microwave Transmission	Application requirements	Statistical analysis of the effectiveness of error detection code	Communication security
	SLO-2	Wi-MAX technology	Comparison of transmission medium	Design issues with transport layer	Statistical analysis of the effectiveness of error correction code	Social issues

Learning Resources	1. Andrew S. Tanenbaum, Computer Networks, 4 th edition, Prentice Hall, 2003.	3. James F. Kurose, Computer networking : a top-down approach, 6 th ed. Pearson publishers.
	2. William Stallings, Data and Computer Communications, 5 th edition, PHI, 2005.	4. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
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	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Ravikumar A R, PayPal,ravikumar.venkataramani@gmail.com	1. Dr. A. Venkadesan, NIT Puducherry, venkadesan@nitpy.ac.in	1. Mr.George Fernandez.S, SRMIST
2. Mr.Balachandrasekar.K,CTS,dyaksha@gmail.com	2.Dr Subhransu Sekhar Dash, Government College of Engineering, Keonjhar, Subhransudash_fee@gcekr.ac.in	2. Dr.J.Divyanavamani, SRMIST

Course Code	18EEE331T	Course Name	INTERNET OF THINGS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Outline the basic architectural overview of IoT .	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Enable the students to differentiate between IoT and M2M.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Enrich the knowledge about IoT platforms and design methodology				H	-	-	-	H	-	-	-	-	-	-	-	H	M	H
CLR-4 :	Examine the various hardware platforms of IoT				H	-	-	-	M	H	-	-	-	-	-	-	M	M	M
CLR-5 :	Acquire the concept of IoT in application sectors.				H	-	-	-	M	H	-	M	-	-	-	-	H	M	M
CLR-6 :	Enable the students to acquire the basic knowledge of IoT architecture, various platforms and applications.				H	-	-	-	M	H	-	-	H	-	-	H	H	M	M
					H	-	-	-	M	H	-	M	H	-	-	H	H	M	M
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>																			
CLO-1 :	Understand the issues and design challenges in IoT architecture	1	75	75															
CLO-2 :	Gain knowledge on M2M and IoT	1	75	75															
CLO-3 :	Interpret about various network topologies and design methodologies	1	75	75															
CLO-4 :	Analyze on hardware platforms relevant to IoT.	2	75	75															
CLO-5 :	Apply knowledge of IoT in various applications.	2	75	75															
CLO-6 :	Understand IoT platforms, interfacing and applications.	2	75	75															

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Definitions of IoT	M2M towards IoT - the global context,	IoT platforms	IoT Physical Devices & Endpoints	Case Studies- IoT Design and Cloud incorporation
	SLO-2	Functional requirements of IoT.	Game changers	IoT platforms design methodology	Basic building blocks of an IoT Device	Introduction to IoT Design
S-2	SLO-1	Building an IoT architecture- SOA based architecture	M2M to IoT - building an architecture	IoT design methodology - Purpose & Requirements Specification, Process Specification	Exemplary Device: Raspberry Pi	Home Automation – smart lighting, smart appliances
	SLO-2	API oriented architecture	Main design principles and needed capabilities	Domain Model Specification, Information Model Specification	Linux on Raspberry Pi	Intrusion detection, Smoke /Gas detectors
S-3	SLO-1	Physical things of IoT- Things in IoT,	IoT architecture outline	Service Specifications, IoT Level Specification, Functional View Specification	Raspberry Pi Interfaces - serial	Cities –Smart Parking, Smart Lighting, Smart Roads
	SLO-2	IoT Protocols	Standard considerations	Operational View Specification, Device & Component, Application development.	Raspberry Pi Interfaces - SPI, I2C	Structural health Monitoring, Surveillance, Emergency Response
S-4	SLO-1	Logical Design of IoT - IoT functional Blocks,	Introduction to M2M	IoT Design methodology-case study on IoT system for Weather Monitoring	Programming Raspberry Pi with Python – controlling LED with Raspberry pi	Environment - Weather Monitoring, Air Pollution Monitoring
	SLO-2	Communication model, Communication APIs	Difference between IOT and M2M	Case study on IOT system for Weather Monitoring	Programming Raspberry Pi with Python – interfacing an LED and switch with Raspberry pi	Noise Pollution Monitoring, Forest Fire Detection, River Floods Detections
S-5	SLO-1	IoT enabling technologies- wireless sensor networks	Software defined networking (SDN)	Python data types	Programming Raspberry Pi with Python- interfacing a light sensor with Raspberry Pi	Energy - Smart grids , Renewable Energy Systems, Prognostics

	SLO-2	Cloud Computing	Network function visualization (NFV) for IOT.	Python data structures.	Other IoT Devices- pcDuino, BeagleBone Black	Retail - Inventory Management, Smart Payment, Smart Vending Machines
S-6	SLO-1	IoT enabling technologies - Embedded Systems,	Needs for IoT system management	Logical Design using Python- control flow	Other IoT Devices - Cubieboard	Smart Vending Machines
	SLO-2	Big data analytics	Simple Network Management Protocols (SNMP)	Logical Design using Python - functions	Controlling LED with Raspberry Pi	Logistics - Route Generation and scheduling, Fleet Tracking
S-7	SLO-1	IoT enabling technologies - Communication protocols for IoT,	Limitations of SNMP	Logical Design using Python - modules	Controlling LED with Myrio	Shipment Monitoring, Remote Vehicle Diagnostics
	SLO-2	Embedded systems	Network operator requirements	Logical Design using Python - packages	Interfacing an LED and Switch with Raspberry Pi	Agriculture - Smart irrigation, Green House Control
S-8	SLO-1	IoT levels and deployment templates- level 1, level 2, level 3	Network configuration protocol (NETCONF) layer	Logical Design using Python - file handling,	Interfacing an LED and Switch with Myrio	Industry – Machine Diagnosis and prognosis
	SLO-2	IoT levels and deployment templates- level 4, level 5, level 6	YANG data modelling language.	Logical Design using Python - date/time operations, classes	Interfacing a Light Sensor (LDR) with Raspberry Pi Other IoT Devices - BeagleBone Black,	Indoor Air Quality Monitoring
S-9	SLO-1	IoT data management and Analytics- IoT and the cloud	IoT system management with NETCONF - YANG	Python Packages of Interest for IoT - JSON, XML	Interfacing a temperature and humidity sensors with Raspberry Pi Other IoT Devices -BeagleBone Black	Health and lifestyle - Health and fitness Monitoring
	SLO-2	IoT data management and Analytics- Real time analytics in IoT and Fog computing	NETOPEER	Python Packages of Interest for IoT - XML	Interfacing a temperature and humidity sensors with Raspberry Pi Other IoT Devices -BeagleBone Black	Wearable Electronics

Learning Resources	<ol style="list-style-type: none"> 1. Arshdeep Bahga, Vijay Madisetti, <i>Internet of Things – A hands-on approach</i>, Universities Press, 2015 2. Jan Holler, Vlasios Tsiatsis, Catherine Mulligan, Stamatis Karnouskos, David Boyle, <i>From Machine-to-Machine to the Internet of Things: Introduction to a New Age of Intelligence</i>, Elsevier, 1st Edition ,2014 3. Rajkumar Buyya , James Broberg, Andrzej Goscinski, <i>Cloud Computing Principles and Paradigms</i>, Wiley, 1st Edition 2014. 4. Honbo Zhou, <i>The Internet of Things in the Cloud: A Middleware Perspective</i> , CRC Press 2013. 5. Soyata, Tolga, <i>Enabling Real-Time Mobile Cloud Computing through Emerging Technologies</i>, IGI Global, 2015 6. https://www.cse.wustl.edu/~jain/cse570-15/ftp/iot_prot/index.html
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Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Muralikrishna, National Instruments, emkkrishnan@gmail.com	1. Dr.D.Devaraj, Dean (Academics), Kalasalingam Academy of Research and Education, deva230@yahoo.com	1. Mrs.C.Nithya, SRMIST
2. Mr. Ravikumar A R, PayPal, ravikumar.venkataramani@gmail.com	2. Dr.B.ChittiBabu, IIITD, Kanchipuram, chittibabu@gmail.com	2. Dr.J.Preetha Roselyn, SRMIST

Course Code	18EEE332T	Course Name	PRINCIPLES OF OBJECT ORIENTED PROGRAMMING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Explain the basics of OOPS	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Demonstrate and develop the concepts of C++				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	Illustrate the importance of the advancements in C++				H	-	-	-	-	-	-	-	-	-	-	-	M	M	-			
CLR-4 :	Explain the basics of JAVA				H	M	M	L	M	-	-	-	-	-	-	-	M	M	-			
CLR-5 :	Elaborate the advanced features of JAVA				H	H	H	M	M	-	-	-	-	-	-	-	M	M	-			
CLR-6 :	Discover the basics of C++ and JAVA				H	L	L	L	M	-	-	-	-	-	-	-	M	M	-			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			3	75	75	H	H	H	H	M	-	-	-	-	-	-	M	M	-	
CLO-1 :	Identify the basic concepts of OOPS	2	75	75	H	-	-	-	-	-	-	-	-	-	-	-	-	M	M	-		
CLO-2 :	Classify and utilize the concepts of C++	3	75	75	H	M	M	L	M	-	-	-	-	-	-	-	-	M	M	-		
CLO-3 :	Develop potential applications from the advancements in C++	3	75	75	H	H	H	M	M	-	-	-	-	-	-	-	-	M	M	-		
CLO-4 :	Discover the basics of JAVA	3	75	75	H	L	L	L	M	-	-	-	-	-	-	-	-	M	M	-		
CLO-5 :	Apply and analyze the advanced features of JAVA	3	75	75	H	H	H	H	M	-	-	-	-	-	-	-	-	M	M	-		
CLO-6 :	Design and develop applications based on C++ and JAVA	3	75	75	H	H	M	M	M	-	-	-	-	-	-	-	-	M	M	-		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Need of Object-Oriented Programming	Introduction to Classes	Pointers	Java platform features-Data types, Key words, Scoping rules	Finalize() method
	SLO-2	Characteristics of Object-Oriented Languages	Introduction to Objects	Pointers with arrays and functions	Automatic Type Conversion, Type Casting and Arrays	Finalize() method: Implementation
S-2	SLO-1	Introduction to the principles of object-oriented programming	Class fundamentals	Virtual Functions	Java platform features	Overloading methods
	SLO-2	Data Types, Variables	Structure of class	Friend Functions	Data types, Key words, Scoping rules	Constructors
S-3	SLO-1	Constants - Type Conversion	Declaring objects	Programs using pointers and arrays	Operators Precedence	Nested classes
	SLO-2	Basic Program Construction	Simple object creation	Programs using functions	Associativity, Expression	Inner classes
S-4	SLO-1	Operators	Objects and messages	Introduction to STL: Containers, Algorithms	Enhanced for loop, switch statements	Potential problems with methods and classes
	SLO-2	Constants, Strings, Expressions and Data types	Constructors and its types	Introduction to STL: Iterators	Handling Strings	Potential problems with constructors and classes
S-5	SLO-1	Library Functions	Destructors	Potential problems with STL: Containers, Algorithms	Declaring objects	Packages
	SLO-2	Loops and Decisions	Passing arguments to Functions	Potential problems with STL: Iterators	Assigning object reference variable	Interfaces
S-6	SLO-1	Structures	Passing Objects as Function arguments	Encapsulation	Methods & Method Signatures	Potential programs with packages
	SLO-2	Functions : Simple Functions	Returning values from Functions	Implementation of Encapsulation	Method returning Values, Method with parameters	Potential programs with interfaces
S-7	SLO-1	Passing arguments, Returning values	Returning Objects from Functions	Polymorphism	Variable arguments in Java	Event handling
	SLO-2	Reference Arguments	Operator Overloading	Operator and method overloading	I/O Basics: Byte stream & Character	Errors and Exception handling

S-8	SLO-1	Recursion, Inline Functions	Inheritance: Basics	Event handling	Stream Getting user input: Reading console input & Writing console output,	Introduction to Threads
	SLO-2	Default Arguments	Inheritance: Method overriding from operator overriding	Errors and Exception handling	Reading and Writing files-new file system	Multithreaded programming
S-9	SLO-1	Storage Classes	Potential programming using functions, constructors and destructors	Potential programs using encapsulation, polymorphism	Constructors: Default Constructor,	Potential programs using threads
	SLO-2	Arrays – Strings	Potential programming using overloading and inheritance	Potential programs using exception handling	Parameterized constructor	Potential programs using multithreads

Learning Resources	1. D Deitel, C++ How to Program, 6th edition, PHI publication, 2008. 2. R. Subburaj, Object Oriented Programming With C++ , Vikas Publishing House, New Delhi, Revised Edition, 2013 3. Bjarne Stroustrup ,The C++ Programming Language, 4th Edition, Addison Wesley, 2015	4. Herbert Schildt, The Complete Reference (Fully updated for jdk7), Oracle press Ninth Edition, 2014. 5. Deitel & Deitel, Java How to Program, Prentice Hall, 10th Edition, 2016. 6. Herbert Schildt, Java: A Beginner's Guide, Sixth Edition, Oracle Press, 2014. 7. https://docs.oracle.com/javase/tutorial
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr.Balachandrasekar.K,CTS,dyaksha@gmail.com	1.Dr.P.Ganesh Kumar, Anna University, ganesh23508@gmail.com	1.Dr. U. Sowmmiya, SRMIST
2.Mr.Ravikumar A R, PayPal,ravikumar.venkataramani@gmail.com	2.Dr.N.Sripriya, SSN College of Engineering, sripriyan@ssn.edu.in	2.Dr. G. Niranjana, SRMIST

Course Code	18EEE422T	Course Name	MODERN OPTIMIZATION TECHNIQUE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical & Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Introduce and classify different conventional optimization techniques.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the fundamentals of genetic algorithm and to apply appropriate algorithm for Engineering optimization problems				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Outline the concept of particle swarm optimization and its hybrid approach to Engineering applications																					
CLR-4 :	Interpret other modern optimization algorithms for engineering applications																					
CLR-5 :	Extend optimization techniques to multi objective optimization																					
CLR-6 :	Introduce the concept of optimization design for Engineering problems																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Categorize optimization problems and its techniques based on constraints and variables				1	75	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Apply Genetic algorithm for various Engineering application				2	75	75	H	H	M	M	-	-	-	-	-	-	-	-	H	H	-
CLO-3 :	Utilize Particle swarm optimization to Engineering applications				3	75	75	H	M	M	M	-	-	-	-	-	-	-	-	H	H	-
CLO-4 :	Gain knowledge about other modern optimization algorithms				3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	H	H	-
CLO-5 :	Formulate multi objective optimization algorithm for various applications				3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	H	H	-
CLO-6 :	Apply optimization techniques in modelling Engineering problems				3	75	75	H	H	H	H	-	-	-	-	-	-	-	-	H	H	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to optimization	Introduction – Genetic Algorithm	Particle Swarm Optimization	Bacterial foraging-Chemotaxis, Swarming	Multiobjective optimization
	SLO-2	Classification of optimization problem	Encoding – Methods for GA	Fundamental principle	Operation of Bacterial foraging	General form of MOOP
S-2	SLO-1	Single variable optimization – optimalityconditions	Fitness function	Velocity updating in PSO	Bees colony algorithm-Behavior of Honey bee swarm	Pareto optimality
	SLO-2	Single variable (unconstrained optimization) – Exhaustive search method	Maximization & Minimization	Algorithm for PSO	Algorithm for Bee colony optimization	Dominance test
S-3	SLO-1	Successive quadratic estimation method	Genetic operators – Crossover	PSO – Parameter Selection	Differential evolution-Initialization, Mutation	Classical Methods – Weighted sum method, ε -constraint method
	SLO-2	Newton method	Single point crossover, Two-point crossover	Pseudocode	Recombination, Selection	Weighted metric methods, Benson method.
S-4	SLO-1	Multi variable optimization – optimality conditions	Uniform Crossover, Arithmetic Crossover	Implementation & Convergence issues in PSO	Ant colony optimization-Introduction	Multi objectiveGA
	SLO-2	Multi variable optimization (unconstrained) – Simplex search method	Mutation	Advanced operators of PSO	Algorithm for Ant colony optimization	Fitnessassignment
S-5	SLO-1	Cauchy’s method	Parent SelectionMethods	Meta-Optimization-Behavioral parameters	Simulated Annealing optimization-Components and control parameters	Sharing function
	SLO-2	Steepest Descent Method	Rank selection, Roulette wheel selection, Stochastic universal selection, Tournament selection	Algorithm for Meta Optimization	Algorithm for Simulated Annealing	Convergence criterion
S-6	SLO-1	Multivariable optimization (Constrained	Issues in GA implementation	Application of PSO	Firefly optimization-Working Principle	NSGA-II-Fitness assignment

		Kuhn – Tucker Conditions				
	SLO-2	Transformation Method –Method of Multipliers	Applications of GA –Filter design	Harmonics Elimination	Algorithm for Firefly optimization	Sharing Function
S-7	SLO-1	Linearized search Technique	Automatic Load Frequency Control (ALFC)	Applications of PSO	Flower Pollination optimization-Introduction	Dynamic neighborhood PSO-Introduction
	SLO-2	Frank Wolfe method	Automatic Voltage Regulation (AVR)	Maximum Power Point Tracking	Algorithm for Flower pollination	Algorithm for Dynamic neighborhood PSO
S-8	SLO-1	Non-Linearized Search Technique	Evolutionary Algorithm	Application of PSO	Grey Wolfe optimization-Introduction	Vector evaluated PSO
	SLO-2	Reduced gradient method	Evolutionary Programming	Reactive power control using PSO	Algorithm for Grey Wolfe optimization	Applications – Economic load Dispatch
S-9	SLO-1	Quadratic programming-Objective Function	Evolutionary Strategy-Non-Recombinative strategy	Hybrid Algorithm of GA and PSO	Comparison of various algorithms	Unit Commitment,
	SLO-2	Algorithm	Recombinative strategy	GA and PSO operators	Benchmark functions	Robot Path Planning

Learning Resources	<ol style="list-style-type: none"> 1. Singiresu Rao S, <i>Engineering Optimization–Theory and Practice</i> by John Wiley & Sons, Inc., New Jersey, 2009. 2. Kalyanmoy Deb, <i>Muti-objective Optimization using Evolutionary Algorithms</i>, Wiley India Private Limited, 2010 3. Kalyanmoy Deb, <i>Optimization of Engineering Design</i>, Prentice Hall of India, second Edition, 2012. 4. Jizhong Zhou, <i>Optimization of Power System Operation</i>, IEEE Press, Second Edition, 2015. 5. Xin - She Yang, <i>Nature Inspired Optimization algorithms</i>, Elsevier, 2014. 6. Chee Peng Lim, Lakhmi C. Jain, Satchidananda Dehuri, <i>Innovations in Swarm Intelligence</i>, Springer, Berlin, Heidelberg, 2009. 7. https://engineering.purdue.edu/~sudhoff/ee630/Lecture09.pdf
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Paramasivam, Danfoss, Industries Pvt Ltd, paramsathya@yahoo.com	1. Dr. R. Subha, Associate Prof. Sir MVIT, subha.mvit@gmail.com	1. Mrs. Uthra.R, SRMIST
2. Mr. Sudharsan, L&T, sudharsand@Intecc.com	2. Dr. B. K. Panigrahi, IIT Delhi, bkpanigrahi@ee.iitd.ac.in	2. Dr. D. Suchitra, SRMIST

Course Code	18EEE423T	Course Name	NEURO FUZZY AND GENETICS PROGRAMMING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																	
		1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-1 :	Acquire knowledge on neural network.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge																	
CLR-2 :	Understand the neural network algorithms for pattern classification and regression problems							Problem Analysis																	
CLR-3 :	Introduce the basics of fuzzy logic and its reasoning.							Design & Development																	
CLR-4 :	Study the architecture of Fuzzy logic controller and neuro-fuzzy based systems.							Analysis, Design, Research																	
CLR-5 :	Develop the knowledge on genetic algorithm for optimization problems							Modern Tool Usage																	
CLR-6 :	Demonstrate the application of neural network, fuzzy logic and Genetic algorithm in real world							Society & Culture																	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						Ethics																	
CLO-1 :	Illustrate the working of various learning algorithms of Neural network.				3	75	75	Individual & Team Work																	
CLO-2 :	Develop and analyze neural networks for pattern classification and pattern association.				3	75	75	Communication																	
CLO-3 :	Apply fuzzy logic and reasoning to handle uncertainty and solve engineering problems				3	75	75	Project Mgt. & Finance																	
CLO-4 :	Develop the process of approximate reasoning using Fuzzy logic controller and Neuro-Fuzzy Modeling.				3	75	75	Life Long Learning																	
CLO-5 :	Formulate a mathematical background to carry out optimization using genetic algorithm.				3	75	75	PSO - 1																	
CLO-6 :	Design and perform experiments on real life problems using Neural network, Fuzzy logic and Genetic algorithm				3	75	75	PSO - 2																	
								PSO - 3																	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Biological Neurons and Their Artificial Models	Pattern Association-Hebb rule	Introduction to Fuzzy Logic, Uncertainty based Information	Introduction to Fuzzy Reasoning	Difference between Traditional optimization Algorithms and genetic algorithm
	SLO-2	Models of Artificial Neural Networks, Architectures	Delta Rule for pattern association	Chances / randomness versus Fuzziness	Fuzzy rule generation. Aggregation Operations	The basic operation of genetic algorithm
S-2	SLO-1	Setting Weights, Activation functions, Learning Processes	Hetero associative memories - Architecture-Algorithm	Classical/crisp set	Fuzzy Logic controller- Basic block	Pseudo code of GA
	SLO-2	Learning Paradigms-Supervised, Unsupervised and reinforcement Learning	Example Problem-Application	Properties and operations of classical set	Knowledge Base-Rule base-Inference system-Importance	Schema theorem
S-3	SLO-1	McCulloch-Pitt Neuron	Auto associative memories -Architecture-Algorithm	Fuzzy set- Representation of fuzzy sets	Fuzzification	Encoding operation
	SLO-2	Linear Separability	Example Problem-Application-Storage Capacity	Properties and Operations of Fuzzy Sets	Assignment of membership functions	Binary, Octal, Hexadecimal , Permutation and Tree encoding
S-4	SLO-1	ANN training Algorithms-Training rules	Iterative Associative Net- Discrete Hopfield Network -Energy Function	Measure of Fuzziness and Inaccuracy of fuzzy set	Defuzzification Methods-Weighted Average method	Importance of Selection and Reproduction operators of GA
	SLO-2	Hebb rule-Algorithm -Application	Continuous Hopfield Network-Energy Function	Cartesian Product- Fuzzy Relations- Composition of fuzzy Relations	Centroid method, Center of sums, Mean max method	Selection operators of GA-Roulette Wheel, Tournament selection, Boltzmann selection and Rank Selection
S-5	SLO-1	Perceptrons-Algorithm	Bidirectional associative memories- Architecture (BAM)	Fuzzy Max-Min Composition	Introduction to Architecture of Mamdani Type Fuzzy Control Systems	Crossover operators of GA-Single point

	SLO-2	Application of Perceptron algorithm	BAM Algorithm-Analysis	Fuzzy Max-Product Composition	Fuzzy Reasoning approach	Two point-multiple point-Uniform crossovers
S-6	SLO-1	Delta Rule	Competitive Learning Networks-Basics	Types of fuzzy sets-Terms of fuzzy sets	Takagi and Sugeno's approach	Mutation operators of GA
	SLO-2	Derivations--Adaline Algorithm	Kohonen Self organizing Maps-Algorithm	Types of Membership Function distributions	Introduction to Fuzzy Clustering	Sample Problem to demonstrate the working of GA
S-7	SLO-1	Back Propagation Algorithm-Derivation	Learning Vector Quantization (LVQ)	Classical Logic, Multivalued Logics	Fuzzy Knowledge Based Systems for real world applications.	GA convergence analysis
	SLO-2	Sample problem for BPN	LVQ-Architecture-Algorithm	Fuzzy Propositions	Design of controllers using Simulation Software	Application of Genetic Algorithm.
S-8	SLO-1	Radial Basis Function Networks-Basics	Basic architecture of Adaptive Resonance Theory (ART)	Fuzzy Qualifiers	Hybrid Model implementing Fuzzy and Neuro	Hybrid Algorithms using GA
	SLO-2	Algorithm of RBF	Basic Operation of ART	Linguistic Variables, Linguistic Hedges	Adaptive Neuro-Fuzzy Inference Systems	Basics of GA-Fuzzy Logic, GA-Neural Network
S-9	SLO-1	Multilayer Perceptron Model	Applications of Artificial Neural Networks.	Introduction to basic Fuzzy Arithmetic	Architecture of adaptive neuro fuzzy Hybrid Learning Algorithm	GA-Fuzzy-Neural Network
	SLO-2	Madaline	Design of controllers using Simulation Software	Extension Principle.	Learning Methods that Cross-fertilize ANFIS and RBFN	Case study on real time application using Neuro/Fuzzy/Genetics

Learning Resources	<ol style="list-style-type: none"> 1. Laurene Fausett., <i>Fundamentals of Neural Networks-Architecture, Algorithms and Application</i>, Prentice Hall International, First edition, 1994. 2. Timothy J.Ross, <i>Fuzzy Logic with Engineering Applications</i>, John Wiley and sons Ltd. publication, Fourth edition, 2016. 3. Kalyanmoy Deb, <i>Optimization for Engineering Design: Algorithms and Examples</i>, Prentice Hall of India, second edition, 2012. 4. David E. Goldberg, <i>Genetic Algorithms in search, optimization and machine learning</i>, Pearson Education Inc, First edition, 1989. 	<ol style="list-style-type: none"> 5. Anderson, James A., <i>An Introduction to Neural Networks</i>, Prentice Hall of India, ISBN: 978-81-203-13514, 2008. 6. Zimmerman H.J, <i>Fuzzy set Theory-and its applications</i>, Kluwer Academic Publishers, second edition, 1991. 7. Hertz J. Krogh, R.G. Palmer, <i>Introduction to the Theory of Neural Computation</i>, Addison- Wesley, ISBN 9780201515602, 1991. 8. G.J. Klir & B. Yuan, <i>Fuzzy Sets & Fuzzy Logic</i>, Prentice Hall of India, 2006, ISBN: 978-81-203-1136-7 9. http://www.myreaders.info/html/soft_computing.html
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Roosefart Mohan, Nelcast Limited, Chennai, roosefart@gmail.com	1. Dr. R.Subha, Associate Prof. , Sir MVIT, subha.mvit@gmail.com	1. Dr. D.Suchitra,, SRMIST
2.Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	2. Dr. C.Nayanatara, Shri Sairam Engineering College, nayanatara.eee@sairam.edu.in	2. Dr.J.Preetha Roselyn, SRMIST

Course Code	18EEE424T	Course Name	ARTIFICIAL INTELLIGENCE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Impact the knowledge on AI and its different Heuristic solution strategies				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Provide adequate knowledge on the technology of knowledge-based agents and Game Playing																							
CLR-3 :	Describe the different planning approaches																							
CLR-4 :	Discuss the different learning algorithms																							
CLR-5 :	Understand the basics of machine learning algorithm																							
CLR-6 :	Create an overall knowledge of different artificial intelligence approaches																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Illustrate the concept of AI and different Heuristic methodologies				2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-	
CLO-2 :	Recall different technologies in knowledge-based agents and Game Playing				2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	M	M	-	
CLO-3 :	Analyze the different planning approaches				2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-	
CLO-4 :	Apply the different learning algorithms for real time systems				2	80	75	H	M	-	-	-	-	-	-	-	-	-	-	-	H	H	-	
CLO-5 :	Implement the machine learning algorithm for clustering and regression				2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-	
CLO-6 :	Utilize a perfect artificial intelligence approach for different applications				2	80	75	H	H	-	-	-	-	-	-	-	-	-	-	-	H	M	-	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Artificial Intelligence (AI)	Games as Search Problems	The Planning Problem	Representing Knowledge in an Uncertain Domain	Types of Machine Learning: Supervised Learning Reinforcement
	SLO-2	The Foundations of AI	Optimal Decisions in Games	Planning with State-Space Search	The Semantics of Bayesian Networks	Unsupervised Learning Reinforcement
S-2	SLO-1	The History of AI	Alpha-Beta Pruning	Partial-Order Planning, Planning Graphs	Efficient Representation of Conditional Distributions	Over fitting and linear regression
	SLO-2	The State of the Art	Imperfect Decisions, State-of-the-Art Game Programs	Planning with Propositional Logic	Exact Inference in Bayesian Networks	Learning Curve
S-3	SLO-1	Structure of Intelligent Agents	Knowledge-Based Agents	Analysis of Planning Approaches	Approximate Inference in Bayesian Networks	Parametric vs. non-parametric models
	SLO-2	Problem-Solving Agents	The Wumpus World	Hierarchical Task Network Planning	Relational and First-Order Probability Models	Linear models
S-4	SLO-1	Formulating Problems	Logic, Propositional Logic	Planning and Acting in Nondeterministic Domains	Forms of Learning	Bayesian hierarchical clustering
	SLO-2	Searching for Solutions	Reasoning Patterns in Propositional Logic	Conditional Planning	Supervised Learning	Clustering datapoints and features
S-5	SLO-1	Uninformed Search Strategies	Effective propositional inference	Execution Monitoring and Re-planning	Learning Decision Trees	K-Means clustering
	SLO-2	Informed (Heuristic) Search Strategies	Agents Based on Propositional Logic	Continuous Planning	Ensemble Learning	K-Medoids clustering
S-6	SLO-1	Heuristic Functions	Syntax and Semantics of First-Order Logic	Multi-Agent Planning	A Logical Formulation of Learning	Neural network Representation
	SLO-2	Local Search Algorithms	Unification and Lifting	Acting under Uncertainty	Knowledge in Learning	Perceptrons, Feed forward networks
S-7	SLO-1	Optimization Problems	Forward Chaining	Basic Probability Notation	Explanation-Based Learning	Back Propagation Algorithms
	SLO-2	Local Search in Continuous Spaces	Backward Chaining	The Axioms of Probability	Learning Using Relevance Information	Recurrent networks

S-8	SLO-1	Online Search Agents	Resolution, Ontological Engineering	Inference Using Full Joint Distributions	Inductive Logic Programming	Linear Regression
	SLO-2	Constraint Satisfaction Problems	Categories and Objects	Independence	Statistical Learning	Logistic Regression
S-9	SLO-1	Backtracking Search for CSPs	Mental Events and Mental Objects	Bayes' Rule and Its Use	Learning with Complete Data	Maximum Likelihood estimation (least squares)
	SLO-2	Local Search for Constraint	The Internet Shopping World	The Wumpus World Revisited	Learning with Hidden Variables: The EM Algorithm	Online learning and stochastic optimization

Learning Resources	1. Stuart Russell and Peter Norvig, <i>Artificial Intelligence – A Modern Approach</i> , Pearson Education Press, 2010.	4. Kevin P. Murphy, <i>Machine Learning: A Probabilistic Perspective</i> , MIT Press, 2012.
	2. Kevin Knight, Elaine Rich, B. Nair, <i>Artificial Intelligence</i> , McGraw Hill, 2008.	5. Stephen Marsland, <i>Machine Learning – An Algorithmic Perspective</i> , CRC Press, 2009.
	3. George F. Luger, <i>Artificial Intelligence</i> , Pearson Education, 2001.	6. https://www.youtube.com/playlist?list=PL6EE0CD02910E57B8 .

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1.Mr. Tripathi patro,visam pvt ltd,btp@visom.co.in	1.Dr.P.Ganesh Kumar, Anna University, ganesh23508@gmail.com	1.Dr.J.Preetha Roselin, SRMIST
2.Mr.Balachandrasekar.K,CTS,dyaksha@gmail.com	2.Dr. C.Nayanatara, Shri Sairam Engineering College, nayanatara.eee@sairam.edu.in	2.Mr.P.Kanakaraj, SRMIST

Course Code	18EEE425T	Course Name	FUNDAMENTALS OF BIG DATA ANALYTICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Introduce big data and its role in various domains	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Learn and analyze the big data analytical tools																							
CLR-3 :	Introduce Hadoop and its components																							
CLR-4 :	Implement Map Reduce technique																							
CLR-5 :	Study the security concerns of big-data																							
CLR-6 :	Create an overall knowledge in big data with different environment																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLO-1 :	Familiarize with applications of Big Data Analytics in various domains	1	80	75	H	-	-	-	-	-	-	-	M	-	-	-	-	H	M	M				
CLO-2 :	Practice open source big data analytical tools	2	80	75	H	H	H	H	H	-	-	-	M	-	-	-	-	M	M	M				
CLO-3 :	Install and operate the open source Distributed File System Hadoop	2	80	75	H	H	M	M	H	-	-	-	-	-	-	-	-	H	M	-				
CLO-4 :	Solve simple problems using Map Reduce Technique	2	80	75	H	H	M	M	H	-	-	-	-	-	-	-	-	H	H	-				
CLO-5 :	Analyze the log file in security aspects	2	80	75	H	H	M	M	-	-	-	-	H	-	-	-	-	H	M	H				
CLO-6 :	Design a big data platform for different applications	2	80	75	H	H	M	M	M	-	-	-	M	-	-	-	-	H	M	M				

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to Big Data Platform	Data Analytics Lifecycle	History of Hadoop	Developing a Map Reduce Application	Introduction to Security Analytics
	SLO-2	Challenges of Conventional Systems	Overview of Data Analytics Lifecycle	Hadoop Distributed File System	How MapReduce Works	Challenges in Security Analytics
S-2	SLO-1	Intelligent data analysis	Successful Analytics Project	Components of Hadoop	Unit Tests	Concepts in Data Analytics
	SLO-2	Nature of Data	Key Roles for a Successful Analytics Project	Analyzing the Data with Hadoop	Unit Tests with MapReduce Unit	Techniques in Data Analytics
S-3	SLO-1	Analytic Processes and Tools	Background of Data Analytics Lifecycle	Scaling Out, Hadoop Streaming	Test Data	Data for Security Analysis
	SLO-2	Industry Examples of Big Data	Global Innovation Network and Analysis	Design of HDFS	Local Tests	Analysis in Everyday Life
S-4	SLO-1	Web Analytics	Case Study: Global Innovation Network and Analysis	Java Interfaces to HDFS Basics	Anatomy of a Map Reduce Job Run	Scenarios in Intrusion
	SLO-2	Big Data and Marketing	Introduction to R	Data Flow, Hadoop I/O	Classic MapReduce	Challenges in Intrusion
S-5	SLO-1	Fraud and Big Data	Introduction to SQL	Data Integrity	YARN	Incident Identification
	SLO-2	Risk and Big Data	Charts	Compression, Serialization	Failures in Classic MapReduce	Analysis of Log File
S-6	SLO-1	Credit Risk Management	Graphs	Avro, File Based Data Structures	Failures in YARN	Loading the Data
	SLO-2	Big Data and Algorithmic Trading	Data tools	Pig, Hive	Job Scheduling	Simulation
S-7	SLO-1	Big Data and Healthcare	Statistical Methods	Hbase	Shuffle and Sort	Security Process
	SLO-2	Big Data in Medicine	Clustering	Data Model and Implementations	Task Execution	Access Analytics
S-8	SLO-1	Advertising and Big Data	Association Rules Regression	Hbase Clients, Hbase Examples	MapReduce Types	Security Analysis

	SLO-2	Different advertising in Big Data	Classification	Praxis, Cassandra	MapReduce Formats	Security Analysis with Text Mining Security Intelligence
S-9	SLO-1	Big Data Technologies	Time Series Analysis	Cassandra Data Model	MapReduce Features	Security Breaches
	SLO-2	Classification of different technologies in Big Data	Text Analysis	Cassandra Clients, Cassandra Examples	Hadoop environment	Security Breaches Examples

Learning Resources	1. David Dietrich, Barry Heller and Beibei Yang, <i>Data Science and Big Data Analytics: Discovering, Analyzing, Visualizing and Presenting Data</i> , Reprint 2015, EMC Education Services, Wiley, ISBN:9788126556533. 2. Tom White, <i>Hadoop: The Definitive Guide, Third Edition</i> , O'reilly Media, 2012.	3. https://www.tutorialspoint.com/big_data_analytics/index.htm 4. https://www.youtube.com/playlist?list=PLFW6lRTa1g813lyYHLRP_bWJEKQDeEcSP 5. Mark Allen Weiss, <i>Data Structures and Algorithm Analysis in C++, Third Edition</i> , 2009
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Code	18EEE426T	Course Name	FUNDAMENTALS OF CLOUD COMPUTING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
		1	2	3	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-1 :		Outline cloud computing and its model						Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-2 :		Explain the cloud-enabling technology and its applications						H	-	-	-	-	-	-	-	-	-	-	-	-	H	M	-
CLR-3 :		Educate on different cloud computing architectures						H	H	M	M	M	-	-	L	-	-	-	-	-	M	M	L
CLR-4 :		Understand the cost metrics and cloud management						H	-	-	-	-	-	-	-	-	-	-	-	-	H	M	-
CLR-5 :		Provide adequate knowledge in cloud security						H	H	M	M	-	-	-	M	-	-	-	-	-	H	H	M
CLR-6 :		Create application by utilizing cloud platforms						H	H	M	M	M	-	-	M	-	-	M	-	-	-	H	M
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			1	80	75																
CLO-1 :		Recall the basic concepts of cloud computing and its model			1	80	75																
CLO-2 :		Acquire knowledge on the cloud enabling technologies and its applications			2	80	75																
CLO-3 :		Illustrate the basic concepts of cloud computing architecture			1	80	75																
CLO-4 :		Analyze the cost metrics and recall the concepts of cloud management			2	80	75																
CLO-5 :		Realize the security threats in cloud			2	80	75																
CLO-6 :		Design a perfect cloud platform for different applications			2	80	75																

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Cloud	Key Drivers to Adopting the Cloud	Requirements of Cloud computing architecture	Cost Metrics	Infrastructure Security
	SLO-2	Overview of Cloud	Examples of Key Drivers to Adopting the Cloud	Introduction to Cloud computing architecture	Pricing Models	The Network Level Infrastructure Security
S-2	SLO-1	Basic Concepts of Cloud	The Impact of Cloud Computing	Workload Distribution Architecture	Business Cost Metrics	The Host Level Infrastructure Security
	SLO-2	Basic Terminology of Cloud	The Impact of Cloud Computing on Users	Example	Cloud Usage Cost Metrics	The Application Level Infrastructure Security
S-3	SLO-1	Goals	Broadband Networks	Resource Pooling Architecture	Cost Management	Data Security and Storage
	SLO-2	Benefits	Internet Architecture	Example	Considerations of Cost Management	Aspects of Data Security
S-4	SLO-1	Risks	Data Center Technology	Dynamic Scalability Architecture	Service Quality Metrics	Data Security Mitigation
	SLO-2	Challenges	Virtualization Technology	Example	Different types of Service Quality Metrics	Provider Data
S-5	SLO-1	Cloud service provider	Web Technology	Elastic Resource Capacity Architecture	SLA	Provider Data Security
	SLO-2	Cloud service consumer	Multitenant Technology	Example	SLA Guidelines	Encryption
S-6	SLO-1	Cloud Characteristics	Service Technology	Service Load Balancing Architecture	Identity and Access Management	Hashing
	SLO-2	Issues in Cloud Computing	Different Applications of Cloud Computing	Example	Trust Boundaries	Digital Signature
S-7	SLO-1	Cloud Computing	Healthcare	Cloud Bursting Architecture	IAM	Public Key Infrastructure (PKI)
	SLO-2	Grid Computing	Energy systems	Example	IAM Challenges	Example
S-8	SLO-1	Comparative study of Cloud Computing and Grid Computing	Transportation systems	Elastic Disk Provisioning Architecture	Relevant IAM Standards for Cloud Services	Single Sign On (SSO)
	SLO-2	Cloud Service Models	Manufacturing industry	Example	Relevant IAM Protocols for Cloud Services	Kerberos authentication - One-time password

S-9	SLO-1	IaaS, PaaS and SaaS	Education	Redundant Storage Architecture	IAM Practices in the Cloud	Example
	SLO-2	Cloud Deployment Models	Mobile Communication	Example	Cloud Authorization Management	Cloud Based Security Groups

Learning Resources	1. Thomas Erl, Zaigham Mahmood, Richardo Puttini, <i>Cloud Computing: Concepts, Technology & Architecture</i> , Fourth Printing, Prentice Hall/Pearson PTR, 2014, ISBN: 9780133387520.	4. Arshdeep Bahga, Vijay Madisetti, <i>Cloud Computing: A Hands-On Approach</i> , University Press, 2016, ISBN: 9780996025508.
	2. Tim Mather, Subra Kumaraswamy, Shahed Latif, <i>Cloud Security and Privacy: An Enterprise Perspective on Risks and Compliance</i> , O'Reilly Media, Inc., Computers - 338 pages. 3. https://www.youtube.com/channel/UUCK73enkjQNDwdBqMyaMtRg/videos	5. K.Chandrasekaran, <i>Essentials of Cloud Computing</i> , Chapman and Hall/CRC Press, 2014, ISBN 9781482205435. 6. Thomas Erl, Robert Cope, Amin Naserpour, <i>Cloud Computing Design Patterns</i> , Prentice Hall/Service Tech Press, Pearson, 2015, ISBN: 978-0133858563.

Learning Assessment											
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	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
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		1. Mrs.P.Akilandeswari, SRMIST
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