

ACADEMIC CURRICULA

Professional Core Courses

ELECTRICAL & ELECTRONICS ENGINEERING

Regulations - 2018

SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18EEEC201J	Course Name	ANALYSIS OF ELECTRIC CIRCUITS	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	18EES101J	Co-requisite Courses		Progressive Courses	
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Analyze real-time circuits using mesh and nodal analysis and network reduction	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Utilize solutions of AC circuits including series and parallel resonance	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Utilize network theorems on DC & AC circuits	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Examine circuits at transient condition	Expected Attainment (%)	Design & Development
CLR-5 :	Solve 3 phase circuits, coupled and tuned circuits		Analysis, Design, Research
CLR-6 :	Enrich the concepts of AC and DC circuits using different analysis		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Analyze circuit parameters, analyze circuits using mesh and nodal analysis and network reduction	3	75	75	H	H	-	-	-	-	-	-	M	M	-	-	M	M	-
CLO-2 :	Evaluate solution methods of AC circuits including series and parallel resonance	3	75	75	H	H	-	-	M	-	-	-	M	M	-	-	M	M	-
CLO-3 :	Calculate solutions of network theorems for DC and AC circuits	3	75	75	H	H	-	-	-	-	-	-	M	M	-	-	M	M	-
CLO-4 :	Analyze the transients of RLC circuits	3	75	75	H	H	M	-	M	-	-	-	M	M	-	-	M	M	-
CLO-5 :	Analyze 3 phase circuits, coupled, tuned circuits and two port networks.	3	75	75	H	H	M	-	-	-	-	-	M	M	-	-	M	M	-
CLO-6 :	Evaluate AC and DC circuits under different cases	3	75	75	H	H	M	-	M	-	-	-	M	M	-	-	M	M	-

Duration (hour)	15	15	15	15	15
S-1	SLO-1	Introduction to two terminal circuit passive elements	Introduction to AC circuits	Superposition theorem in DC circuits	Introduction: Exponentially increasing functions
	SLO-2	Characteristics of two terminal circuit passive elements	Phasors	Problems in Superposition theorem in DC circuits	Exponentially Decreasing functions
S-2	SLO-1	Circuit Reduction Techniques	Impedance	Superposition theorem in AC circuits	RL free circuits
	SLO-2	Problems in Circuit Reduction Techniques	Admittance	Problems in Superposition theorem in AC circuits	RL Driven circuits
S-3	SLO-1	Combination of Sources	Calculation of Power and Power Factor	Reciprocity theorems in AC circuits	Transients in RL circuit with DC excitation
	SLO-2	Source Transformation	Problems in Power and Power Factor	Problems in Reciprocity theorems in AC circuits	Transients in RL circuit with AC excitation
S-4-5	SLO-1	Lab 1: Circuit reduction and basic laws	Lab 4: Determine Power and Power Factor	Lab 7: Verify Superposition and Reciprocity Theorems	Lab 10: Analyze Time domain of RL transient circuit
	SLO-2				
S-6	SLO-1	Mesh current analysis of DC circuits with dependent sources	Steady state analysis of RL circuits	Thevenin's theorem in DC circuits	RC free circuits
	SLO-2	Problems in Mesh current analysis of DC circuits with dependent sources	Steady state analysis of RC circuits	Norton theorem in DC circuits	RC driven circuits
S-7	SLO-1	Mesh analysis in DC circuits with	Steady state analysis of RLC circuits	Thevenin's theorem in AC circuits	Transients in RC circuit with DC excitation
					Analysis of tuned circuits

		current sources				
	SLO-2	Problems in Mesh analysis in DC circuits with current sources	Phasor diagram of RLC circuits	Problems in Thevenin's theorem in AC circuits	Transients in RC circuit with AC excitation	Problems in tuned circuits
S-8	SLO-1	Nodal Voltage analysis of DC circuits with dependent sources	Series resonance circuits	Norton's theorem in AC circuits	Laplace transforms	Introduction to Two port networks
	SLO-2	Problems in Nodal Voltage analysis of DC circuits with dependent sources	Problems in Series resonance circuits	Problems in Norton's theorem in AC circuits	Transform impedance	Analysis of Two port networks
S 9-10	SLO-1	Lab 2: Mesh analysis in DC circuits	Lab 5: Real time Data Acquisition	Lab 8: Verify Thevenin's and Norton's theorems	Lab 11: Analyze Time domain of RC transient circuit	Lab 14: Analysis in tuned circuits
	SLO-2	Supernode method for mesh analysis	Parallel resonance circuits	Millman's theorem in AC circuits	Transients in RLC circuit with DC excitation	Impedance parameters
S-11	SLO-1	Problems in Supernode method for mesh analysis	Problems in Parallel resonance circuits	Problems in Millman's theorem in AC circuits	Problems in Transients in RLC circuit with DC excitation	Problems in impedance parameters
	SLO-2	Nodal analysis in DC circuits with voltage sources	Mesh analysis in AC circuits	Maximum Power Transfer Theorem in DC circuits	Transients in RLC circuit with AC excitation	Admittance parameters
S-12	SLO-1	Problems in Nodal analysis in DC circuits with voltage sources	Problems in Mesh analysis in AC circuits	Problems in Maximum Power Transfer Theorem in DC circuits	Problems in Transients in RLC circuit with AC excitation	Problems in admittance parameters
	SLO-2	Supernode method for nodal analysis	Nodal analysis in AC circuits	Maximum Power Transfer Theorem in AC circuits	Circuit transients using Laplace transform	Hybrid parameters
S-13	SLO-1	Problems in Supernode analysis	Problems in Nodal analysis in AC circuits	Problems in Maximum Power Transfer Theorem in AC circuits	Problems in Circuit transients using Laplace transform	Inverse Hybrid parameters
S 14-15	SLO-1	Lab 3: Nodal analysis in DC circuits	Lab 6: Study of series and parallel resonance circuits	Lab 9: Verify maximum power transfer theorem	Lab 12: Analyze Time domain of RLC transient circuits	Lab 15: Determine hybrid parameters

Learning Resources	1. Sudhakar A, Shyam Mohan S.P, Circuits and Networks Analysis and Synthesis, 4th ed., Tata McGraw Hill, 2010 2. William H. Hayt, Jack E. Kemmerly, Steven M. Durbin, Engineering circuit analysis, 8th ed., McGraw Hill, 2012 3. Jegatheesan R, Analysis of Electric Circuits, McGraw Hill, 2014	4. John Bird, Electric circuit theory and technology, 5th ed., Taylor and Francis, 2013 5. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-071j-introduction-to-electronics-signals-and-measurement-spring-2006/lecture-notes/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers											
Experts from Industry				Experts from Higher Technical Institutions				Internal Experts			
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2.Mr. Muralikrishna, National Instruments, emkkrishnan@gmail.com				2. Dr. B. ChittiBabu, IITD, Kanchipuram, chittibabu@gmail.com				2. Dr. J. Preetha Roselyn, SRMIST			
Course	18EEEC202T	Course	ELECTROMAGNETIC THEORY				Course	C	Professional Core		
									L	T	P
											C

Code		Name		Category		3	1	0	4
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Pre-requisite Courses		Co-requisite Courses		Progressive Courses	
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Utilize the concepts of Electromagnetic theory for practical applications	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Utilize knowledge about the static electric field and its applications.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Utilize knowledge on static magnetic field	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Utilize parameters involved in time varying field and Maxwell's equations	Expected Attainment (%)	Design & Development
CLR-5 :	Enrich in the field of Electromagnetic waves		Analysis, Design, Research
CLR-6 :	Create a mindset to solve various engineering problems in the field of electromagnetism		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Identify the basic laws of electromagnetics and coordinate systems	2	80	75	M	M	-	-	-	-	-	-	M	M	-	-	M	M	-
CLO-2 :	Solve the Electric field parameters for simple configuration under static condition	3	80	75	H	H	M	L	-	-	-	-	M	M	-	-	M	M	-
CLO-3 :	Examine the Magnetic field for simple configuration under static condition	3	80	75	H	H	M	L	-	-	-	-	M	M	-	-	M	M	-
CLO-4 :	Extend the basics of electromagnetic theory on time varying electric and magnetic field	3	80	75	H	H	M	L	M	-	-	-	M	M	-	-	M	M	-
CLO-5 :	Analyze propagation of electromagnetic waves	3	80	75	H	H	M	L	-	-	-	-	M	M	-	-	M	M	-
CLO-6 :	Apply electromagnetic concepts to solve real time problems	3	75	75	H	H	M	L	M	-	-	-	M	M	-	-	M	M	-

Duration (hour)	12	12	12	12	12
S-1	SLO-1	Vector analysis for three-dimensional Euclidean space	Current density, Ohms Law in point form	Fundamentals of Magnetostatics (B, H)	Faraday's law of Electromagnetic induction
	SLO-2	Stokes and Divergence theorem	Continuity of current equation	Magnetic field due to straight conductor	Motional and transformer EMF
S-2	SLO-1	Three orthogonal coordinate systems – Cartesian system	Boundary conditions of perfect dielectric materials	B and H for a circular loop	Displacement current and conduction current
	SLO-2	Cylindrical and spherical coordinate system	Boundary condition between conductor and dielectric, conductor and free space.	Magnetic field due to infinite sheet of current.	Point form of Maxwell's equation, Integral form of Maxwell's equations
S-3	SLO-1	Conversion from one coordinate to another coordinate system	Permittivity of dielectric materials	Magnetic materials, permeability	Phasor representation of time harmonic field
	SLO-2	Solutions of Coulomb's law	Dielectric strength and dielectric polarization	Magnetic dipole	Energy in quasi-stationary Electromagnetic Fields
S-4	SLO-1	Tutorial: Quantitative analysis of coordinate system	Tutorial: Quantitative analysis of boundary condition problem	Tutorial: Quantitative analysis of B and H calculations	Tutorial: Quantitative analysis of Maxwell's Equation
	SLO-2	Fundamentals of electrostatics	Capacitance of a two-wire line.	Magnetization and Magnetic susceptibility	Magnetic Potential
S-5	SLO-1	Electric field intensity (E) and flux density (D) due to point, line and surface charge	Solution of Laplace and Poisson's equation	Magnetic field in multiple media – Boundary conditions	Potential for time varying fields
	SLO-2	Electric field intensity (E) and flux density (D) due to point, line and surface charge	Solution of Laplace and Poisson's equation	Magnetic field in multiple media – Boundary conditions	Potential for time varying fields
S-6	SLO-1	D and E for volume charge distribution	Applications of Laplace and Poisson's equation	Magnetic potential – Scalar and Vector potential. Magnetic diffusion	MagNet software
	SLO-2	Electric field due to dipole	Uniqueness theorem	Magnetic force and stress tensor	MagNet software for 3D electromagnetic

					field simulations	
S-7	SLO-1	Applications of Gauss law's	Duality theorem	Inductance calculation for a solenoid and toroid	Case study on real time applications of Maxwell's equations	Goos-Hanchen's effect
	SLO-2	Electric Potential and its calculation for different configurations	Method of images	Inductance of a coaxial cable	Problems on time varying field	Snell's law
S-8	SLO-1	Tutorial: Quantitative analysis for D, E and potential calculation	Tutorial: Quantitative analysis of capacitance calculations and Laplace equations	Tutorial: Quantitative analysis of magnetic boundary conditions	Tutorial: Quantitative analysis of Poynting vectors and magnetic potential	Tutorial: Quantitative analysis of Electromagnetic boundary conditions
	SLO-2					
S-9	SLO-1	Force on a moving charge and differential current element	Sketches of fields and field plotting.	Inductance derivation for two wire transmission line	Case study of Parallel Particle Tracing for Steady-State and Time-Varying Flow Fields	Reflection coefficient
	SLO-2	Magnetic field and induced emf in rotating machines	Finite difference method (FDM)	Problems on Inductance calculations	Applications of Poynting theorem	Transmission coefficient
S-10	SLO-1	Multipole concept	FDM to a solution of region and boundary conditions	Energy density in magnetic field	Electromagnetic Wave Equations	Quantitative analysis of wave parameters
	SLO-2	Multipole of electrostatic expansion	Quantitative analysis of FDM	The finite element analysis- an introduction	Solutions of Helmholtz's equation	Brewster angle
S-11	SLO-1	Quadrupole and octupole	Method of moment for Electrostatic field	Finite element method (FEM) for magnetostatic field	Prototype using the concept of EM theory	Critical angle
	SLO-2	Example for multipole expansion	Case study on dust cloud ignition caused by static electricity	Case study on super conducting disk in an external magnetic field.	Minor Project presentation	Case study on fault calculations using EM wave equations
S-12	SLO-1	Tutorial: quantitative analysis of force, current and torque	Tutorial: Quantitative analysis of Electrostatic field calculations	Tutorial: quantitative analysis of magnetostatic field	Tutorial: quantitative analysis of electromagnetic field	Tutorial: Quantitative analysis of EM wave coefficients
	SLO-2					

Learning Resources	1. William Hayt, <i>Engineering Electromagnetics</i> , 7 th ed., McGraw Hill, 2014 2. Matthew. N.O. Sadiku, <i>Elements of Electromagnetics</i> , 4 th ed., Oxford University Press, 2010 3. David J. Griffiths, <i>Introduction to Electrodynamics</i> , 4 th ed., Pearson publication, 2013	4. Joseph A Edminister, <i>Theory and Problem of Electromagnetics</i> , Schaum's outline series McGraw Hill, 2006 5. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-632-electromagnetic-wave-theory-spring-2003/index.htm
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers																
Experts from Industry				Experts from Higher Technical Institutions					Internal Experts							
1. Dr. S. Paramasivam, Danfoss, Industries Pvt Ltd, paramsathya@yahoo.com				1. Dr. K. S. Swarup, IIT Madras, ksswarup@iitm.ac.in					1. Mrs. R. Rajarajeswari, SRMIST							
2. Mr.J. Sasikumar,Philips India Limited, Chennai				2. Dr. A. Venkadesan, NIT, Pondicherry, venkadesan@nitpy.ac.in					2. Mrs. D. Anitha, SRMIST							
Course	18EEEC203J	Course	DIGITAL SYSTEM DESIGN					Course	C	Professional Core			L	T	P	C

Code		Name		Category		3	0	2	4
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Pre-requisite Courses	18EES101J	Co-requisite Courses		Progressive Courses	
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Utilize digital systems				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-2 :	Utilize combinational logic circuits																						
CLR-3 :	Design and implement sequential logic circuits																						
CLR-4 :	Implement different logic functions using transistor and MOSFET																						
CLR-5 :	Analyze the types of PLD's and VHDL programming																						
CLR-6 :	Analyze and design digital logic circuits																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Simplify Boolean expression				2	75	75	H	M	M	M	-	-	-	-	M	M	-	-	L	M	-	
CLO-2 :	Solve problems in combinational logic circuits				3	75	75	H	M	M	M	-	-	-	-	M	M	-	-	L	M	-	
CLO-3 :	Construct sequential circuits for given requirement and verify them in laboratory				3	75	75	H	M	M	M	-	-	-	-	M	M	-	-	L	M	-	
CLO-4 :	Analyze IC characteristics operation of logic gates and their families				2	75	75	H	M	L	L	-	-	-	-	M	M	-	-	L	M	-	
CLO-5 :	Implement digital circuit using PLA, PAL, PROM. Write programs using VHDL				3	75	75	H	L	L	L	L	-	-	-	M	M	-	-	M	M	-	
CLO-6 :	Apply the concepts of digital systems and experimentally validate them				3	75	75	H	M	M	M	L	-	-	-	M	M	-	-	L	M	-	

Duration (hour)		15	15	15	15	15
S-1	SLO-1	Minterms, Canonical SOP form	Binary multiplier	Introduction to latches/Flip flop	Introduction to asynchronous sequential circuit	Memory organization and operation
	SLO-2	Simplification of switching function using K maps-SOP method	Binary divider	Flip flop: SR flip flop	Steps involved in design of asynchronous sequential circuit	Classification of memories ROM, PROM, EPROM, RAM
S-2	SLO-1	Simplification of Incompletely specified function using K maps- SOP method	Arithmetic logic unit (ALU)	Flip flops: D flip flop	Merger graph	Content addressable memory, Charge decoupled device memory
	SLO-2	Simplification of switching function with Don't care using K maps-SOP method	Elementary ALU design	Flip flops: JK & T flip flops	Problems in design of asynchronous sequential circuit	Commonly used memory chips
S-3	SLO-1	Maxterms, Canonical POS form	Multiplexer	Realization of D, JK, T flip flops using SR flip flops	Cycles	Programmable Logic Array(PLA)
	SLO-2	Simplification of switching function using K maps-POS method	Implementation of Boolean expression using multiplexer	Realization of D flip flop using T flip flop, Realization of T flip flop using D flip flop, Realization of JK flip flops using D flip flop	Critical and non-critical Races, Hazards	Implementation of Boolean function using PLA
S 4-5	SLO-1	Lab 1: Simplification of switching function using K maps and implementation using logic gates	Lab 4: Realization of MUX, Realization of Boolean expression using MUX	Lab 7: Realization of one flip flop using another flip flop	Lab 10: Design and implementation of Hazard free circuit	Lab 13: Realize Boolean algebra using PLA
	SLO-2					
S-6	SLO-1	Quine-McCluskey method for 4 variable problem	Demultiplexer	Design of synchronous sequential circuits-Moore Model using D flip flop	Problems in design of asynchronous sequential circuit including races	Programmable Array Logic (PAL)
	SLO-2	Quine-McCluskey method for4 variable problem with Don't care	Implementation of Boolean expression using demultiplexer	Design of synchronous sequential circuits-Moore Model using JK flip flop	Analysis of asynchronous sequential circuits	Implementation of Boolean function using PAL

S-7	SLO-1	Quine-McCluskey method for 5 variable problem	Decoders,	Design of synchronous sequential circuits- Moore Model using T flip flop	Analysis of asynchronous sequential machines with latches	Complex programmable logic device (CPLD), FPGA
	SLO-2	Quine-McCluskey method for 5 variable problem with Don't care	BCD to 7 segment decoders, drivers for display devices	Design of synchronous sequential circuits- Mealy Model using D flip flop	Asynchronous up Counters, Asynchronous down Counters design	Introduction to VHDL programming
S-8	SLO-1	Adder: Half adder, Full adder	Encoder	Design of synchronous sequential circuits- Mealy Model using JK flip flop	Design of asynchronous up/down counter	VHDL design flow
	SLO-2	Subtractor: Half subtractor, Full subtractor	Priority encoder	Design of synchronous sequential circuits- Mealy Model using T flip flop	Design of asynchronous MOD-n Counter	VHDL types and operators
S-9-10	SLO-1	Lab 2: Realization of combinational circuits: Half adder, Full adder, Half subtractor, Full subtractor	Lab 5: Design of BCD to 7 segment decoders	Lab 8: Design and implementation of synchronous sequential circuits	Lab 11: Design of asynchronous Counters	Lab 14: Verification of gates using FPGA
	SLO-2					
S-11	SLO-1	Parallel binary adder and parallel binary subtractor	Parity generator	Analysis of synchronous sequential circuits using D, T flip flops	Digital logic families: Characteristics of Digital logic families	Structural and Behavioral Modelling
	SLO-2	Parallel adder/subtractor	Parity checker	Analysis of synchronous sequential circuits using JK flip flop	TTL Logic, Schottky TTL Logic, CMOS Logic	Data flow Modelling
S-12	SLO-1	Carry look ahead adder	Code Converter: Binary to Grey	Synchronous counters: up, down, up-down counters	ECL logic	Packages, subroutines
	SLO-2	BCD adder	Code Converter: Grey to Binary	MOD-n, Random counters	Interfacing CMOS with TTL	Test bench
S-13	SLO-1	Magnitude Comparator for 1,2-bit Comparator	Code Converter: BCD to Excess 3	Shift registers, Serial to parallel converter, Parallel to serial converter, Universal shift register	Tristate logic	Simple VHDL program: Combinational logic circuits
	SLO-2	Magnitude Comparator for 4-bit Comparator	Code Converter: Excess 3 to BCD	Ring counter, Johnson counter	Comparison between various logic circuits	Simple VHDL program: counters
S-14-15	SLO-1	Lab 3: Realization of BCD adder and 2-bit	Lab 6: Realization of Code Converters	Lab 9: Design of Synchronous Counters, Design of shift registers and ring counters	Lab 12: Mini Project Presentation: Realization of digital control circuits	Lab 15: Verification of Combinational logic circuits using FPGA
	SLO-2	Magnitude Comparator				

Learning Resources	1. M. Morris Mano, Michael D. Ciletti, Digital Design: With an Introduction to Verilog HDL, VHDL and System Verilog, 6 th ed., Pearson, 2018	3. Charles H. Roth, Lizy K. John, Digital System Design Using VHDL, 2 nd ed., Cengage learning, 2012 4. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science
	2. Thomas L. Floyd, Digital Fundamentals, 11 th ed., Pearson India, 2014	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers										
Experts from Industry	Experts from Higher Technical Institutions									
	Internal Experts									

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2. Mr. Muralikrishna, National Instruments, emkkrishnan@gmail.com	2. Dr. B. ChittiBabu, IITD, Kanchipuram, chittibabu@gmail.com	2. Ms. D. Anitha, SRMIST



Course Code	18EEEC204J	Course Name	ELECTRICAL MACHINES I	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	18EES101J	Co-requisite Courses		Progressive Courses	
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Analyze the characteristics of different types of DC generators	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Identify the working, starting and speed control of DC motors	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Analyze transformers and derive its equivalent circuit	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Test DC machines and transformers as per standard practice	Expected Attainment (%)	Design & Development
CLR-5 :	Model DC machines		Analysis, Design, Research
CLR-6 :	Analyze the performance of the DC machine and transformer		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Analyze the principle and fundamentals of DC generator	2	75	75	H	L	-	-	-	-	-	-	M	M	-	-	M	M	-
CLO-2 :	Analyze the principle and fundamentals of DC motor	2	75	75	H	L	-	-	-	-	-	-	M	M	-	-	M	M	-
CLO-3 :	Identify the different types of transformers and analyze its performance using equivalent circuit	2	75	75	H	M	-	-	-	-	-	-	M	M	-	-	M	M	-
CLO-4 :	Investigate and interpret the performance of DC machines and transformers performing suitable tests	3	75	75	H	M	-	-	-	-	-	M	M	M	-	-	M	M	M
CLO-5 :	Analyze DC machines by mathematical modeling	3	75	75	H	M	L	L	L	-	-	-	M	M	-	-	M	M	-
CLO-6 :	Evaluate characteristics of transformers, DC Machines and evaluate their performance by applying various testing methods	3	75	75	H	M	L	L	L	-	-	L	M	M	-	-	M	M	L

Duration (hour)		15	15	15	15	15
S-1	SLO-1	Energy in magnetic system	Torque equation of DC motor	Transformers: Types and Construction	Testing of DC machines: Brake test	Modeling of dc machines: Basic two pole DC machine
	SLO-2	Field energy and mechanical force	Emf equation of DC motor	Principle of operation, emf equation	Swinburne's test	Analysis of DC machine using Primitive two axis machine equation
S-2	SLO-1	Single excited systems	Voltage equation of various types of DC motor	Ideal transformer and Practical transformer on no load	Problems in Swinburne's test	Modelling of voltage equation
	SLO-2	Multiple excited systems	Current equation of various types of DC motor	Practical transformer on load	Retardation test	Modelling of torque equation
S-3	SLO-1	Torque and Force equations	Speed equation and regulation of DC motor	Equivalent circuit of transformer	Hopkinson's test	Mathematical model of separately excited DC machine
	SLO-2	Energy conversion via electric fields	Power flow in DC motor, Losses & efficiency	Transformer regulation, losses, efficiency	Problems in Hopkinson's test	Problems in mathematical model of separately excited DC machine
S 4-5	SLO-1	Lab 1: Demo on Single & Multiple excited systems	Lab 4: Load test on DC motors	Lab 7: Load test on single-phase transformer	Lab 10: Swinburne's test and Hopkinson's test on DC machine	Lab 13: Study of impulse test in transformer
	SLO-2					
S-6	SLO-1	Dynamic equation of electromechanical systems	Review of mechanical starter- 3-point starter	Phasor diagram of transformer	Open circuit test on single phase transformer	Mathematical model of shunt connected DC machine
	SLO-2	DC generator- lap and wave winding, Major considerations in design of windings	4-point starter, 2-point starter	EMF in power transformers	Short circuit test on single phase transformer	Problems in mathematical model of shunt connected DC machine
S-7	SLO-1	DC generator-EMF equation-circuit model	Electronic soft starters for DC motor with	All day efficiency, Per unit representation of	Sumpner's test	Mathematical model of series connected

			energy saving	transformer		DC machine
	SLO-2	Methods of excitation	Speed control: Field control, Armature control	Three phase transformers connections, Scott connection	Equivalent circuit, efficiency and regulation from OC & SC test	Problems in mathematical model of series connected DC machine
S-8	SLO-1	Losses in DC generator	Speed control: voltage control	Phasing of transformer	Equivalent circuit, efficiency and regulation from Sumpner's test	Mathematical model of compound connected DC machine
	SLO-2	Power flow in DC generator, efficiency	Problems in DC motors	Parallel operation of single phase and three phase transformers	Problems in OC & SC test	Problems in Mathematical model of compound connected DC machine
S-9-10	SLO-1	Lab 2: Open circuit and load characteristics of Separately Excited DC generator	Lab 5: Speed Control of DC Motor: Field control, Armature control	Lab 8: Load test on three phase transformer	Lab 11: Open circuit and short circuit test and Sumpner's test on single phase transformer	Lab 14: Study of zero sequence impedance and noise level test in transformer
	SLO-2					
S-11	SLO-1	Effect of armature flux on field flux in DC generator	Speed control: Thyristor control	Auto transformer	Routine test on transformer	Time domain model of shunt connected DC machine
	SLO-2	Use of compensating windings, Ampere-Turns calculations	Speed control: Converters control	Tap changing transformers- tertiary winding	Dielectric and parametric test on transformer	State equations of shunt connected DC machine
S-12	SLO-1	Commutation in DC generator, construction of commutator,	Speed control: choppers control	Variable frequency transformer, audio frequency transformer	Type test on transformer	Problems in state equations of shunt connected DC machine
	SLO-2	Methods to improve commutation	Braking of DC motors	Phase shifting transformer, dry type transformer	Temperature rise and impulse test on transformer	Time domain model of permanent magnet DC machine
S-13	SLO-1	Voltage and current equation, Residual voltage, Critical Resistance	Permanent magnet DC motor	Grounding transformer, traction transformer	Unbalance current, magnetic balance test on transformer	State equations of permanent magnet DC machine
	SLO-2	Problems in DC generator	Problems in speed control	Welding transformer, rectifier transformer	Zero sequence impedance and noise level test on transformer	Problems in state equations of permanent magnet DC machine
S-14-15	SLO-1	Lab 3: Open circuit and load characteristics of Self Excited DC generator	Lab 6: Speed Control of DC Motor: Thyristor, converter and chopper control	Lab 9: Parallel operation of single phase and three phase transformers	Lab 12: IEC/IEEE standard practice on transformer testing	Lab 15: Simulation of separately and self-excited DC machine
	SLO-2					

Learning Resources	1. D. P. Kothari, I. J. Nagrath, <i>Electrical Machines</i> , 5 th ed., Tata-McGraw Hill, 2017 2. A. E. Fitzgerald, C. Kingsley, <i>Electric Machinery</i> , 6 th ed., McGraw Hill Education, 2013 3. Paul C. Krause, Oleg Waszynszuk, Scott D. Sudhoff, <i>Analysis of electric machinery and Drive systems</i> 3 rd ed., IEEE Series, John Wiley & Sons, 2013 4. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination(50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. S. Paramasivam, Danfoss Industries Pvt Ltd, paramsathya@yahoo.com	1. Dr. D. Devaraj, Kalasalingam Academy of Research and Education, deva230@yahoo.com	1. Dr. C. S. Boopathi, SRMIST
2. Mr. Muralikrishna, National Instruments, emkrishnan@gmail.com	2. Dr. B. ChittiBabu, IIITD, Kanchipuram, chittibabu@gmail.com	2. Dr. K. Vijayakumar, SRMIST



Course Code	18EEEC205J	Course Name	ELECTRICAL MACHINES II	Course Category	C	Professional Core			
						L	T	P	C
						3	0	2	4

Pre-requisite Courses	18EES101J	Co-requisite Courses		Progressive Courses	
Course Offering Department	Electrical and Electronics Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Identify the need of rotating magnetic field in three phase induction motor and draw its equivalent circuit	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Evaluate performance of three phase induction motor using circle diagram, identify its starting, speed control methods	Thinking (Bloom)	Proficiency (%)	Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning				
CLR-3 :	Develop an equivalent circuit of single phase induction motor and explain the operation of single phase AC machines																		
CLR-4 :	Construct an equivalent circuit and phasor diagram of an alternator and obtain its voltage regulation																		
CLR-5 :	Analyze the working and characteristics of salient pole alternator and synchronous motor																		
CLR-6 :	Utilize the construction, operation and performance of AC machines																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Analyze the working of three phase induction motor, its torque slip characteristics and hence obtain its equivalent circuit	2	75	75	H	H	M	-	-	-	-	-	M	M	-	-	L	M	-
CLO-2 :	Identify the starting and speed control methods of three phase induction motor and evaluate its performance	3	75	75	H	H	M	-	-	-	-	-	M	M	-	-	M	M	-
CLO-3 :	Analyze the different single phase AC machines and model a single-phase induction motor	3	75	75	H	M	L	-	-	-	-	-	M	M	-	-	L	M	-
CLO-4 :	Model alternators and compute its voltage regulation	3	75	75	H	H	M	-	-	-	-	-	M	M	-	-	L	M	-
CLO-5 :	Identify the operation and control of salient pole alternator and synchronous motor	2	75	75	H	L	L	-	-	-	-	-	M	M	-	-	M	M	-
CLO-6 :	Analyze the performance of an AC machine by modeling and by carrying out laboratory experiments	3	75	75	H	M	M	-	-	-	-	-	M	M	-	-	L	M	-

Duration (hour)		15	15	15	15	15
S-1	SLO-1	Review of poly phase distributed AC winding, Production of EMF	Construction of circle diagram for 3-phase induction motor	Constant magnetic field, Pulsating magnetic field	Alternators- Constructional features and types, Short pitch and full-pitch coils	Salient pole synchronous machine
	SLO-2	Flux and mmf waves in induction motor	Performance calculation from circle diagram	Alternating current in winding with spatial displacement	Concentrated and distributed winding, Coil span factor, Winding distribution factor	Blondel's two reaction theory
S-2	SLO-1	Constructional details of three-phase induction motor	Problems in circle diagram	Magnetic field produced by single winding-fixed current and alternating current	Air gap MMF distribution with fixed current	Phasor diagram using X_d , X_q
	SLO-2	Principle of operation of three-phase induction motor	Determination of maximum quantities from circle diagram	Pulsating fields produced by spatially displaced windings	Air gap MMF distribution with sinusoidal current	Slip test, Voltage regulation using slip test
S-3	SLO-1	Slip, Effect of slip on rotor parameters	Need for speed control	Windings spatially shifted by 90 degrees	EMF equation of alternator	Power output of Salient pole synchronous machine
	SLO-2	Torque equation, Starting torque equation, Maximum torque	Speed control of three-phase induction motor: Stator side	Addition of pulsating magnetic fields	Armature reaction, Alternator on load, phasor diagram	Problems in voltage regulation
S-4-5	SLO-1	Lab 1: Load test on 3 phase induction motor	Lab 4: Speed control of three-phase induction motor: stator side	Lab 7: Demo of spatially displaced windings	Lab 10: Load test on 3 phase alternators	Lab 13: Determination of X_d and X_q of salient pole machine
	SLO-2					
S-6	SLO-1	Torque-slip characteristics, Generation and breaking region in Torque-slip characteristics	Speed control of three-phase induction motor: rotor side	Constructional detail of single phase induction motor	Equivalent circuit and phasor diagram	Synchronous motor: Principle of operation, Methods of starting
	SLO-2	Starting characteristics of 3 phase induction motor. Effect of Rotor resistance	Speed control by solid state devices	Double revolving field theory	Synchronous Impedance, voltage regulation	Torque and power equations

		on Torque-slip characteristics				
S-7	SLO-1	Power Stages	Necessity of Starters	Torque equation	Pre-determination of voltage regulation using EMF method	Synchronous motor on load, Synchronous motor on constant excitation variable load
	SLO-2	Relation between rotor input, rotor copper losses and rotor output	Types of starters	Torque- speed characteristics	Problems in EMF method	Synchronous motor on constant load variable excitation, 'V', inverted 'V' curves
S-8	SLO-1	Problems in power stages	Induction generator, Self-excited Induction generator	No load blocked rotor tests	Pre-determination of voltage regulation using MMF method	Synchronous condenser, Hunting and its suppression
	SLO-2	No load and blocked rotor tests	Doubly-Fed Induction generator	Equivalent circuit	Problems in MMF method	Short circuit transient in synchronous machine
S-9-10	SLO-1	Lab 2: No load and blocked rotor test on 3-phase squirrel cage induction motor	Lab 5: Speed control of three-phase induction motor on rotor side	Lab 8: No load and blocked rotor test on 1-phase induction: To draw equivalent circuit	Lab 11: Voltage regulation of alternators by EMF and MMF methods	Lab 14: Determination of 'V' and inverted 'V' curves in synchronous motor
	SLO-2	Steady state analysis-Equivalent circuit	Harmonics in induction motor	Making single phase induction self-starting	Pre-determination of voltage regulation using ZPF method	Capability curves in synchronous machine
S-11	SLO-1	Motor efficiency, rotor efficiency	Crawling, Cogging	Shaded pole induction motor	Problems in ZPF method	Positive, Negative and Zero sequence reactance of synchronous machines
	SLO-2	Equivalent circuit from No load and blocked rotor tests	Electric Braking: Regenerative braking, Plugging Braking	Linear Induction motor, Universal motor	Pre-determination of voltage regulation using ASA method	Synchronous induction motor
S-12	SLO-1	Problems in no load and blocked rotor test	Electric Braking: AC, DC dynamic braking	Reluctance motor	Problems in ASA method	Brushless DC motor
	SLO-2	Double cage rotor	Slip power recovery scheme	AC series motor, Repulsion motor	Parallel operation of alternators, Load sharing	Permanent Magnet Synchronous Motor
S-13	SLO-1	Equivalent circuit of double cage rotor, Performance calculation	Difference in starting and blocked rotor characteristics	Stepper motor	Voltage and frequency control, Synchronization to infinite bus-bar	Tacho generator
	SLO-2	Lab 3: No load and blocked rotor test on 3-phase slip ring induction motor	Lab 6: Characteristics of 3 phase Induction generator	Lab 9: Load test on single phase induction motor	Lab 12: Voltage regulation of alternators by ZPF method, Synchronization and parallel operation of alternators	Lab 15: Determination of Positive, Negative and Zero sequence reactance of synchronous machines

Learning Resources	1. H. Wayne Beaty & Jame. L. Kirtley Jr, Electric Motor Handbook, McGraw-Hill, USA, 1 st Edition, 1998 2. M.G. Say, The Performance and Design of Alternating Current machines, Tata-McGraw Hill, 1 st Edition, 2004	3. J. B. Gupta, Theory & Performance of Electrical Machines, 15 th ed., S. K. Kataria & Sons, 2015 4. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-685-electric-machines-fall-2013/index.htm
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination(50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Muralikrishna, National Instruments, emkkrishnan@gmail.com	2. Dr. R. Ramesh, CEG, rramesh@annauniv.edu	2. Dr. K. Vijayakumar, SRMIST



Course Code	18EEEC206J	Course Name	ANALOG ELECTRONICS	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	18EES101J	Co-requisite Courses		Progressive Courses	
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Know the basic amplifier circuits.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Acquire knowledge on different power amplifiers.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Construct different waveform generating circuits.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Discuss the basics of operational amplifiers.	Expected Attainment (%)	Design & Development
CLR-5 :	Understand different analog to digital and digital to analog converters		Analysis, Design, Research
CLR-6 :	Design amplifier circuits using transistor and operational amplifiers.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Analyze the amplifier circuits using small signal model and hybrid model	2	75	75	H	H	H	H	-	-	L	-	M	M	-	-	M	H	-
CLO-2 :	Recognize the different power amplifiers	2	75	75	H	H	H	H	-	-	-	-	M	M	-	-	M	H	-
CLO-3 :	Design oscillators and multivibrators.	3	75	75	H	H	H	M	-	-	-	-	M	M	-	-	M	M	-
CLO-4 :	Apply different operational amplifiers.	2	75	75	H	M	M	-	-	-	-	-	M	M	-	-	M	M	-
CLO-5 :	Evaluate filters and converter circuits	3	75	75	H	H	H	M	H	-	-	-	M	M	-	-	M	M	-
CLO-6 :	Demonstrate electronic modern tools in various electronic fields.	2	75	75	H	H	H	M	M	-	L	-	M	M	-	-	M	M	-

Duration (hour)	15	15	15	15	15
S-1	SLO-1 BJT -Biasing methods -Base bias, base bias with emitter feedback	Power amplifiers: Types. Determine efficiency for class A, B power amplifier	Oscillators and classification of oscillators	Introduction to Linear Integrated Technology	Filters basics and types
	SLO-2 Base bias with collector feedback and voltage divider bias	Frequency response of RC coupled class A amplifier	Design and Analysis of RC Phase shift oscillator	Fabrication process for Integrated Circuits	Design of I and II Order LPF
S-2	SLO-1 Emitter bias using BJT in CE configuration	Frequency response of Transformer coupled class A amplifier.	Operation of Hartley's oscillator	Dc characteristics of op amp and input bias current.	Design of I Order HPF
	SLO-2 Transistor biasing stability using BJT in CE configuration	Operation of Class B push pull power amplifier	Analysis of Hartley's oscillator	Input offset voltage, Thermal Drift	Design of II Order HPF
S-3	SLO-1 Operation of BJT as an amplifier	Operation of Differential amplifier	Operation of Armstrong oscillator	AC characteristics of op-amp and Frequency Compensation	Design of BPF and BRPF
	SLO-2 CE, CB, CC Amplifier –Evaluation of h-parameters	Analysis of Differential amplifier	Operation of UJT Relaxation oscillator	Slew rate	Switched variable filters and state variable filters.
S 4-5	SLO-1 Lab 1: Determination of hybrid parameters of a CE amplifier.	Lab 4: Determination of gain of an amplifier.	Lab 7: RC Phase shift oscillator	Lab 10: and AC characteristics of IC 741 Op-amp	Lab 13: Design of Low pass and High Pass Filters.
	SLO-2				
S-6	SLO-1 Small signal analysis of CE Amplifier	Self-biased active load differential amplifier	Operation of Cross Coupled oscillator	Inverting amplifier and Non-inverting amplifier	Oscillators- Wein bridge Oscillator using IC 741.
	SLO-2 Small signal analysis of CB and CC amplifier	Source degenerated common source amplifier	Integrators	Summer and Subtractor.	Amplitude control and Quadrature Control Oscillator
S-7	SLO-1 Large signal analysis of CE Amplifier	Classification of class C power amplifiers	Differentiators	Voltage follower and	Introduction to simple MOSFET based op-

			(Tuned amplifiers)		ac amplifiers	amp circuits.
	SLO-2	Large signal analysis of CB and CC amplifier.	Frequency response of Single, Double and Staggered Tuned Class C power amplifier	Schmitt trigger	V to I and I to V converters	Analog to Digital converters, classification. Counter and Sigma Delta type ADC.
S-8	SLO-1	JFET – Common source (CS) amplifier - operation	Cascode and Cascade circuits	Multivibrator, Classification Operation of Astable Multivibrator	Instrumentation amplifier	Successive approximation type ADC
	SLO-2	CS Amplifier – small signal analysis	Feedback amplifiers – Barkhausen criterion and Types of feedback amplifier	Analysis of Astable Multivibrator	Log and Antilog amplifiers	Digital to Analog converters and Pulse width modulator DAC
S 9-10	SLO-1	Lab 2: Analysis of JFET amplifier	Lab 5: Frequency response of RC coupled amplifier	Lab 8: Astable Multivibrator	Lab 11: Applications of op-amp	Lab 14: Wein bridge oscillator using IC 741.
	SLO-2	JFET – Common Drain (CD) Amplifier – operation	Analysis of voltage series feedback amplifier	Operation of Monostable Multivibrator.	Comparators and classification of comparators	R -2R Ladder DAC
S-11	SLO-2	Small signal analysis of MOSFET	Analysis of voltage shunt feedback amplifier	Analysis of Monostable Multivibrator.	Applications of Comparators : Summer, Subtractor, Voltage follower	Binary coded DAC
	SLO-1	Biasing of MOSFET	Analysis of current series amplifier	Operation of Bistable Multivibrator.	Basics of IC 555 Timer and Pin Details	Case study: Minor project on any advanced application based circuit using IC 741 or IC 555 Timer or IC 723.
S-12	SLO-2	CD Amplifier – small signal analysis	Analysis of current shunt feedback amplifier	Analysis of Bistable Multivibrator.	Astable operation using IC 555 Timer with applications	Case study: Minor project on any advanced application based circuit using IC 741 or IC 555 Timer or IC 723.
S-13	SLO-1	Problems on biasing of circuits.	Problems on power amplifiers.	Voltage and time-based circuits.	Monostable operation using IC 555 Timer with applications	Case study: Minor project on any advanced application based circuit using IC 741 or IC 555 Timer or IC 723.
	SLO-2	Problems on hybrid parameters	Problems on feedback amplifiers	Series and shunt voltage regulator	Voltage regulator using IC 723	
S 14-15	SLO-1	Lab 3: Analysis of MOSFET amplifier	Lab 6: Frequency response of Class C Power amplifier	Lab 9: Transistor series voltage regulator	Lab 12: Voltage Regulator Using IC 723	Lab 15: R -2R Ladder DAC
	SLO-2					

Learning Resources	1. Jacob Millman, Christos C. Halkias, Satyabrata Jit, Millman's Electronic Devices and Circuits, 4 th ed., Tata McGraw Hill, 2015 2. Boylestead, Nashelsky, Electronic Devices and Circuit Theory, 11 th ed., Pearson, 2015 3. David A. Bell, Electronic Devices and Circuits, 5 th ed., Prentice Hall, 2004 4. Sergio Franco, Design with operational amplifiers and Analog Integrated circuits, 5 th ed., McGraw-Hill, 2014 5. Roy Choudhary and Shail Jain, Linear Integrated Circuits, 4 th ed., New Age International Publishers, 2014 6. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-002-circuits-and-electronics-spring-2007/syllabus/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination(50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. B. Niranjithkumar, BEL, Chennai., niranjithkumarb@bel.co.in				2. Dr. S. Kamalakannan, Anna University, kamalakannan1612@gmail.com				2. Dr. K. Mohanraj, SRMIST			
Course	18EEEC207J	Course	ELECTRICAL AND ELECTRONICS MEASUREMENTS AND				Course	C	Professional Core		
									L	T	P
											C

Code		Name	INSTRUMENTATION	Category		3	0	2	4
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Pre-requisite Courses		Co-requisite Courses		Progressive Courses	
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Utilize the knowledge of various types of measuring instruments, DC and AC bridge.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Utilize the working of analog meters for power, energy and harmonic measurements	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Utilize different measuring and display devices	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Compare the measurement of non- electrical quantities.	Expected Attainment (%)	Design & Development
CLR-5 :	Analyze the functions of biomedical instruments and data acquisition system		Analysis, Design, Research
CLR-6 :	Utilize the knowledge about measurements, measuring instruments for practical applications		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Solve the problems in measuring instruments and bridges	3 75 75	H L - - L - - M M - - L M -
CLO-2 :	Apply the different analog meters for power, energy and harmonic measurements.	2 75 75	H L - - - - - M M - - L M -
CLO-3 :	Design the operation of different measuring and display devices	2 75 75	H L - - - - - M M - - L L -
CLO-4 :	Identify the measurement of non- electrical quantities.	2 75 75	H - - - L - - - M M - - L L -
CLO-5 :	Describe the working of biomedical instruments and data acquisition system	2 75 75	H - - - - - - - M M - - L M -
CLO-6 :	Interpret the acquired knowledge of measuring instruments	2 75 75	H L - - L - - - - M M - - L M -

Duration (hour)	15	15	15	15	15
S-1	SLO-1	Functional elements of instrument	Special type of transformers -Current Transformer	Construction and working of synchro scope – Western type	Methods of pressure measurements-Dead-weight gauges and Manometers
	SLO-2	Static characteristics of measurement	Potential Transformer- Measurement of voltage	Nalder-Lipman type	Pressure measuring system
S-2	SLO-1	Dynamic characteristics of measurement	Principle of operation, construction, Torque equation of induction type single phase energy meter	General principle and performance equations of Ballistic Galvanometer	Elastic transducer, Vibrating cylinder
	SLO-2	Errors in measurement	Three phase energy meter	D'Arsonval Galvanometer	Resonant transducer.
S-3	SLO-1	Kelvin's Double Bridge, measurement of Low value of Resistances	Creeping adjustments, testing of energy meters	General principle and working of Hall effect sensors	Measurement of Flow: Flow visualization from Pitot-static tube, Yaw tube.
	SLO-2	Wheat -stone Bridge, measurement of Medium value of Resistances.	Calibration of energy meter using direct loading.	Encoder-Laser based methods.	Positive displacement method, Obstruction methods.
S 4-5	SLO-1	Lab 1: Measurement of R, L and C using bridge circuit	Lab 4: Measurement of power and energy	Lab 7: Measurement of liquid flow rate	Lab 10: Measurement of water level using capacitive Transducer
	SLO-2				
S-6	SLO-1	Maxwell's Inductance Bridge, Measuring Unknown value of Inductance	Digital energy meter	Graphical methods of measurement: Cathode ray oscilloscope	Drag effect methods, hot-wire anemometers.
	SLO-2	Anderson's Bridge, measurement of Un known value of Inductance.	Net metering	Digital storage oscilloscope	Measuring Devices: Vacuum and sound
S-7	SLO-1	Schering's Bridge measurement of Un	Measurement of reactive power using	Storage devices: Strip chart recorder	McLeod gauge, Knudsen gauge

		known value of Capacitance.	wattmeter in single phase circuit.			
	SLO-2	Principle of operation of Thermal type instruments	Measurement of reactive power using wattmeter in Poly phase circuits	X-Y recorder	Diaphragm and ionization gauges	Respiratory instrumentation – Mechanism of respiration, spirometry
	SLO-1	Principle of operation, construction, working of single phase power factor meter	Measurement of Volt Ampere reactive power using VAR meter	Principle of operation and applications of Phase sequence indicator	Motion measurement-Fundamentals standards.	Working of different types of Pacemakers
	SLO-2	Three phase power factor meter	Principle of operation, and construction of Maximum demand indicator	Principle of operation and applications of Display devices: LED, LCD, Dot matrix display	Temperature measurement using Liquid in glass thermometers	Applications of Pacemakers
S	SLO-1					
9-10	SLO-2	Lab 2: Power factor measurement	Lab 5: Measurement of power and energy	Lab 8: Measurement of harmonics using Power quality analyser.	Lab 11: Measurement of temperature to estimate the response time using temperature measuring instruments	Lab 14: Study of Pacemaker Module
	SLO-1	Solving Problems in error measurements	Solving Problems in single phase energy meter	Solving Problems in Phase sequence indicator.	Solving Problems in transducers	Interfacing instruments –General purpose interfacing bus (GPIB)
	SLO-2	Solving Problems in bridge circuits	Solving Problems in three phase energy meter	Solving Problems in Galvanometer	Solving Problems in Pressure measurement.	Working of GPIB Hardware Components
	SLO-1	Principle of operation, construction, Torque equation of Dynamometer type instruments	Frequency meters, Electrical resonance type	Measurement of LCD screen size	Measurement of Pressure thermometers	GPIB / SCPI Programming Elements and specifications
	SLO-2	Principle of operation of Rectifier type instruments	Frequency meters - Mechanical Resonance Type.	Operation of an analogue actuator: the DC Servo motor	Properties of analogue sensors for temperature	Interfacing instruments –USB
	SLO-1	Principle of operation and applications of Digital voltmeter.	Principle of operation of spectrum analyser	Radio frequency identification (RFID) reader	Properties of analogue sensors for pressure	Instrumentation for medical imaging
	SLO-2	Principle of operation and applications of Digital Multimeter.	Principle of operation of Harmonic analyser	Data loggers	Laser based measurement of liquid temperature	Instrumentation for Therapeutic Devices
S	SLO-1					
14-15	SLO-2	Lab 3: Demo on Universal bridge	Lab 6: Demo on Frequency meter	Lab 9: Identification of phase sequence using Synchroscope	Lab 12: Study of temperature and pressure sensor	Lab 15: Analysis of Instrumentation for medical imaging

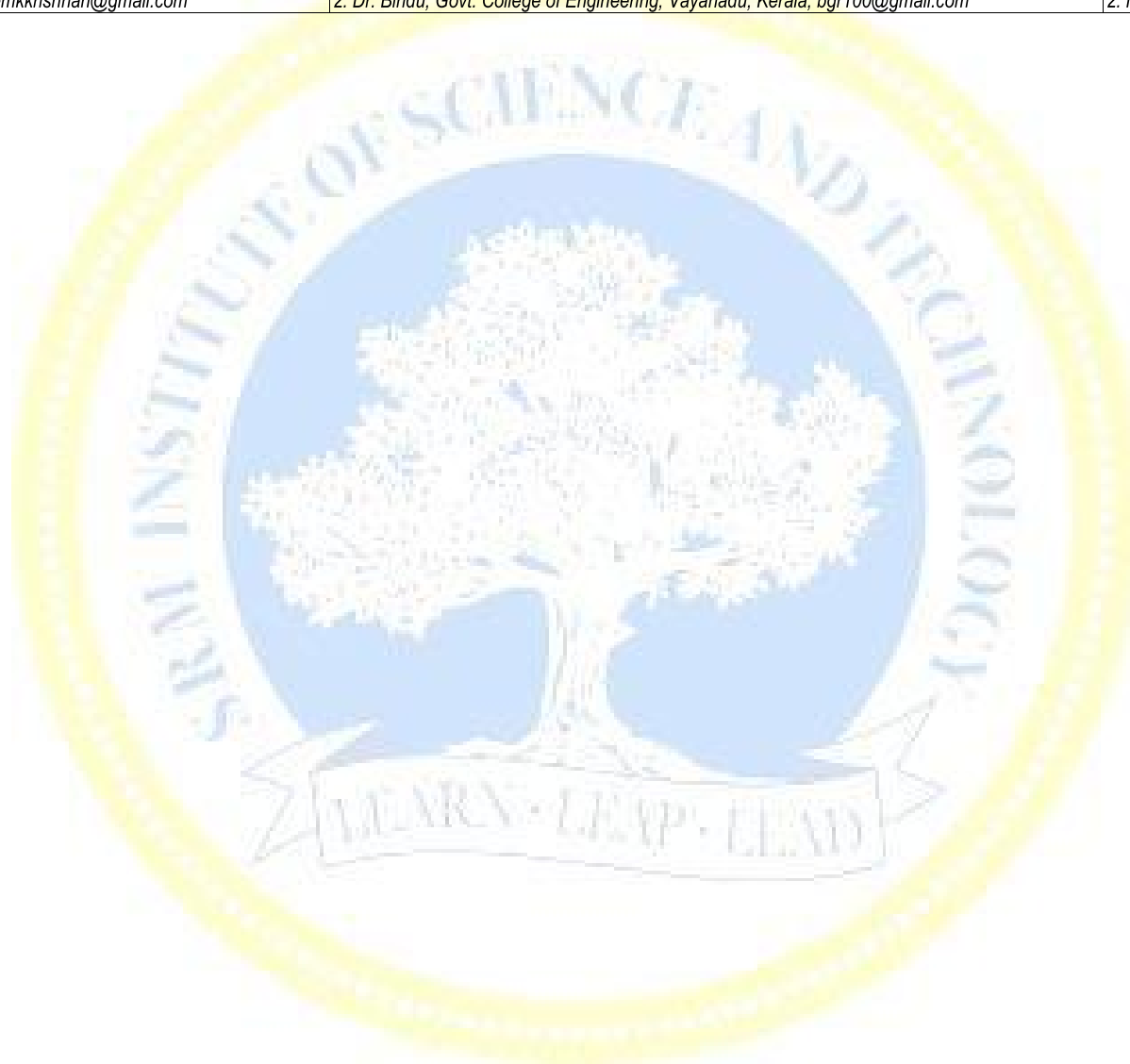
Learning Resources	1. Ernest O Doebelin, Dhanesh N Manik, Measurements Systems Application and Design, 5 th ed., McGraw Hill, 2006 2. Sawhney A. K, A Course in Electrical and electronic Measurement and Instrumentation, Dhanpat Rai & Sons, 2015 3. Rajendra Prasad, Electrical Measurements & Measuring instruments, 10 th ed., Khanna Publishers, 1989	4. Albert D Halfride & William D Cooper, Modern Electronic Instrumentation and Measurement Techniques, Pearson, 2015 5. John G Webster, Medical instrumentation: Application and design ,4 th ed., Wiley, 2010 6. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination(50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers

Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. A. Thiyagarajan, TANGEDCO, athiyagu3177@yahoo.com.	1. Dr. S. Senthilkumar, NIT, Trichy, skumar@nitt.edu	1. Ms. C. Anuradha, SRMIST
2. Mr. Muralikrishna, National Instruments, emkrishnan@gmail.com	2. Dr. Bindu, Govt. College of Engineering, Vayanadu, Kerala, bgr100@gmail.com	2. Ms. S. Vijayalakshmi, SRMIST



Course Code	18EEC208T	Course Name	GENERATION, TRANSMISSION AND DISTRIBUTION	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses		Co-requisite Courses		Progressive Courses	
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Utilize the basics of electric power generation, transmission and distribution	1	1
CLR-2 :	Solve the various transmission line parameters for single and three phase transmission system	2	2
CLR-3 :	Analyze the performance of transmission line and to learn the different voltage compensation techniques	3	3
CLR-4 :	Utilize insulators, cables and estimate the string efficiency	4	4
CLR-5 :	Analyze the basics of substation components and DC distribution systems	5	5
CLR-6 :	Create overall structure of power system starting from generation to power transmission and distribution	6	6
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Engineering Knowledge
CLO-1 :	Identify the layout of various energy sources and its economics of power generation	2	H
CLO-2 :	Calculate the line parameter for single and multi-phase power transmission system	3	H
CLO-3 :	Compute the performance of various types of transmission lines	3	H
CLO-4 :	Acquire knowledge on insulators, cables and evaluate stress and sag	3	H
CLO-5 :	Identify the substation components and compute the DC distribution systems	3	H
CLO-6 :	Design a power system using components like generators, transmission lines and distributors	3	H
		Expected Proficiency (%)	Problem Analysis
		Expected Attainment (%)	Design & Development
			Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Sources of energy	Calculate Resistance in a single-phase transmission line	Analyze performance of short line	Classify insulators for transmission and distribution purpose	Classification, major components of substations, Bus-bar arrangements
	SLO-2 Structure of power system	Calculate Inductance in a single-phase transmission line	Analyze performance of medium transmission line (end condenser method)	Voltage distribution in insulator string	Substation bus schemes- single bus, double bus with double breaker
S-2	SLO-1 Basic layout of PV power generation	Calculate Capacitance in a single-phase transmission line	Calculate efficiency, regulation of voltage for medium line by end condenser method	Improvement of string efficiency	Double bus with single breaker
	SLO-2 Basic layout of wind power generation	Calculate Inductance and capacitance of three phase transmission lines	Analyze Performance of medium line using T method	Calculation of voltage distribution and string efficiency	Main and transfer bus schemes
S-3	SLO-1 Basic layout of Ocean Thermal Energy Conversion (OTEC)	Calculate Inductance and capacitance in a Symmetrically spaced conductor	Calculation of efficiency and regulation of voltage for medium line by T method	Testing of insulators	Double bus-bar scheme with bypass isolators
	SLO-2 Types of OTEC	Calculate inductance and capacitance in an Unsymmetrical spaced conductor (transposed)	Analyze Performance of medium line using π method	Construction features of LT and HT cables, Insulation resistance	Introduction to substation earthing
S-4	SLO-1 Basic layout of Biomass power plant	Calculate inductance of Single circuit lines	Calculation of efficiency and regulation of voltage for medium line by π method	Calculate Capacitance, dielectric stress	Substation safety
	SLO-2 Load curve & Load duration curve	Calculate capacitance of Single circuit lines	Analyze Performance of long line using Rigorous method	Grading cables	Qualitative treatment to neutral grounding
S-5	SLO-1 Calculation of total power generation	Calculate inductance in double circuit lines	Ferranti effect – surge impedance	Fault in underground cables	Feeders, service mains and distributors

	SLO-2	Load, demand and diversity factors	Calculate capacitance in double circuit lines	Attenuation constant and phase constant	Location of fault in underground cables	DC Distribution
S-6	SLO-1	Plant capacity and plant use factors	Calculate inductance in Stranded and bundled conductors	Real power flow in transmission lines	Tan δ and power loss	Types of DC distributors
	SLO-2	Calculation of Plant capacity and plant use factors	Calculate capacitance in Stranded and bundled conductors	Reactive power flow in transmission lines	Thermal characteristics of cables	Quantitative analysis of radial distribution fed at one end
S-7	SLO-1	Choice of type of generation, choice of size and number of units	Application of self GMD	Power circle diagrams	Calculate Stress of towers with equal heights	Quantitative analysis of radial distribution fed at both the ends
	SLO-2	Cost of energy generated	Application of mutual GMD	Receiving end power circle diagrams for finding the maximum power transfer	Calculate Sag of towers with equal heights	Quantitative analysis of Ring main distribution
S-8	SLO-1	Tariffs	Skin and Proximity effect	Series compensation	Calculate Stress of towers with unequal heights	Design of rural distribution, planning and design of town electrification schemes
	SLO-2	Types of tariffs	Inductive interference, Corona	Shunt compensation	Calculate Sag of towers with unequal heights	Kelvin's law for the design of feeders and limitations
S-9	SLO-1	Transmission systems	Implementation of distribution system using software	Seminar Presentations on ABCD constants	Effect of wind on overhead transmission line	Smart grid
	SLO-2	Distribution systems	Implementation of distribution system using software	Seminar Presentation on surge impedance loading	Effect of ice loading on overhead transmission line	Power system restructuring

Learning Resources	1. D.P. Kothari, I.J. Nagrath Power System Engineering Mc Graw-Hill Publishing company limited, New Delhi, 2 nd ed., 2008	3. Luces M. Fualkar berry, Walter Coffe Electrical Power Distribution and Transmission, Pearson Education, 2007
	2. C. L. Wadwa, Electric Power Systems, 7 th ed., New Age International Publishers, 2016	4. S.N.Singh, Electric power generation, transmission and distribution, 2 nd ed., PHI, 2011 5. https://ocw.mit.edu/courses/electrical-engineering-and-computer-science

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

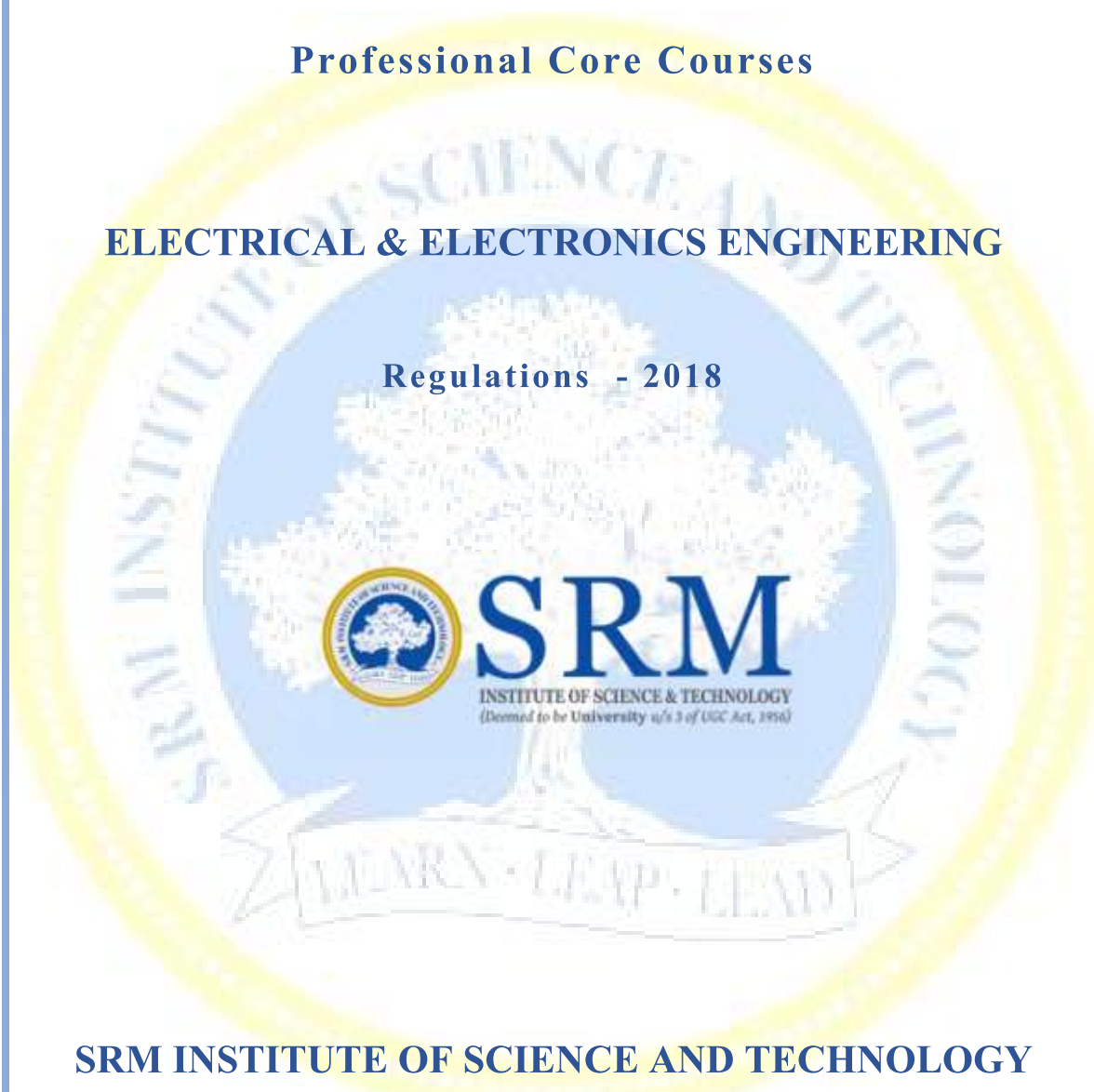
Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Dr. Bhaskarsahu, Schneider Electric Ltd, bhaskar.sahu@schneider-electric.com		1. Dr. K. S. Swarup, IITM, ksswarup@iitm.ac.in
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		Internal Experts
		1. Mr. P. Suresh, SRMIST
		2. Dr. D. Sattianadan, SRMIST

ACADEMIC CURRICULA

Professional Core Courses

ELECTRICAL & ELECTRONICS ENGINEERING

Regulations - 2018



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18EEEC301J	Course Name	CONTROL SYSTEMS	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Educate the students on mathematical model of a physical system.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Provide knowledge on time domain response and stability of a system.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Explain the concept of frequency domain using mathematical and graphical approach				H	H	M	M	-	-	-	-	M	M	-	-	M	H	-
CLR-4 :	Design various controller / compensator to meet system requirement.				H	H	M	H	M	-	-	-	M	M	-	-	H	H	-
CLR-5 :	Understand the concept of state space analysis.				H	H	H	H	M	-	-	L	M	M	-	-	H	H	L
CLR-6 :	Gain knowledge on the design, control and analysis of physical system.				H	H	M	M	M	-	-	-	M	M	-	-	M	H	-
CLR-6 :	Gain knowledge on the design, control and analysis of physical system.				H	H	H	H	M	-	-	L	M	M	-	-	H	H	L
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)															
CLO-1 :	Interpret a physical system in s domain representation.	3	75	75															
CLO-2 :	Analyze the use of time domain specification and stability in real time application.	3	75	75															
CLO-3 :	Apply various techniques to understand the frequency response of a system	3	75	75															
CLO-4 :	Articulate the concept of tuning and design a controller for the given system.	3	75	75															
CLO-5 :	Comprehend the state and test the controllability, observability of a system.	3	75	75															
CLO-6 :	Analysis the system stability and performance of physical system.	3	75	75															

Duration (hour)	15	15	15	15	15
S-1	SLO-1	Classification of control systems.	Introduction to time domain analysis.	Introduction to frequency domain analysis.	Need for controller design and in systems
	SLO-2	Terminology of automatic control systems.	Standard test signals ; Response of first order systems to standard test signals	Frequency response plots of dynamic systems.	Important for compensation in system.
S-2	SLO-1	Principles and effects of feed forward control systems.	Step response of second order systems in detail	Frequency response measurements, Performance specifications in the frequency domain.	Effects of P,PI Controller.
	SLO-2	Principles and effects of feedback control systems.	Different damping conditions.	Log magnitude and phase diagrams.	Effect of PID Controller.
S-3	SLO-1	Transfer functions SISO & MIMO	Transient response analysis.	Determination of Frequency domain specifications.	Classical PID controller
	SLO-2	Transfer functions for simple electrical, mechanical and electro mechanical systems	Time domain specification.	Phase margin and Gain margin	PID controller tuning using Zigler – Nichols tuning rules.
S 4-5	SLO-1	Lab 1: Determination of transfer function parameter of DC motor	Lab: 4Generating standard test signals.	Lab 7: Frequency response characteristics of second order system.	Lab 10: Design, determination of transfer function and frequency response for lag, lead network.
	SLO-2				Lab 13: State space model for classical transfer function and design and tuning a PID controller.

Duration (hour)		15	15	15	15	15
S-6	SLO-1	Tutorial: Formation of transfer functions of mechanical translational and rotational system.	Steady state response; Steady state error.	Stability Analysis using Bode Plots	Feedback compensation –Lead compensation	Relationship between state equation and transfer functions.
	SLO-2	Tutorial: Formation of electrical analogy of mechanical translational and rotational system.	Static & dynamic error coefficients	Procedure for plotting bode plot. .	Lag compensation	Conversion of state space to transfer function.
S-7	SLO-1	Block diagram algebra.	Effects of additional Pole on the Second-Order System Response	Tutorial – Bode plot problem	Compensator design in frequency domain using bode plot	Solution of state equation;
	SLO-2	Representation by Signal flow graph	Effects of additional Zero on the Second-Order System Response	Stability margin on the bode plot.	Design procedure.	State Transition Matrix and it's Properties
S-8	SLO-1	Tutorial: Block diagram reduction direct method..	Routh Hurwitz criterion	Nyquist (Polar) Plot	Tutorial - Compensator design	Importance of controllability and observability.
	SLO-2	Tutorial: Block diagram reduction use by Mason's gain formula.	Stability condition and its limitation.	Gain phase plot.	Achieved desired system specification.	Tutorial: Formation of controllability and observability matrix
S-9-10	SLO-1	Lab 2: Determination of transfer function parameter of AC servo motor.	Lab 5: Step response characteristics of second order system.	Lab 8: Stability analysis of second order system using time and frequency domain approach.	Lab 11 Stability analysis of add a pole / zero and lag lead compensator.	Lab 14: Analysis of twin rotor multi input multi output system.
	SLO-2					
S-11	SLO-1	Linear Approximations of Physical Systems.	Properties of the Root Loci	Nyquist stability criterion	Pole zero cancellation design:	Pole zero cancellation for uncontrollability system.
	SLO-2	Linearization of nonlinear systems	Construction of root loci	Stability analysis using nyquist plot.	Notch filter	Design for controllable system.
S-12	SLO-1	Poles and zeros of a transfer function	Tutorial – Root locus	Relations between closed loop and open loop frequency response.	Minor loop feedback control.	Tutorial –Pole placement of state feedback system.
	SLO-2	Graphical evaluation	Gain limitation for stability condition.	M and N circle	Advantages and Applications	Design for pole placement approach.
S-13	SLO-1	BIBO Stability and its important	Effects of adding poles on the root loci.	Time response analysis use by Simulink/ program software.	Case Study: IEC61131 Standards	Case study: State space analysis of electric vehicle charging system.
	SLO-2	Location of poles and stability.	Effects of adding zeros on the root loci.	Frequency response analysis use by Simulink/ program software.	Programming language for industrial automation.	Analysis the system response.
S-14-15	SLO-1	Lab 3: Performance analysis of a motor driving a load through a gear train.	Lab 6. Plotting root locus of a transfer function using a simulator tank level estimation control.	Lab 9: Modeling and control analysis of simple electric network	Lab 12: Effect of feedback on disturbance and PID control design.	Lab 15: Design of speed control of DC motor drive.
	SLO-2					

Learning Resources	1. I J Nagarath and M.Gopal, Control systems Engineering, New age international publication , 6 th Edition, 2017.	5. K.P.Ramachandran, Control Engineering, Wilky India Private Limited, 1 st Edition, 2011.
	2. FaridGolnaraghi, Benjamin C. Kuo, Automatic Control Systems, McGraw-Hill Professional, 10 th Edition, 2017.	6. Graham C.Goodwin, Stefan F. Graebe, Mario E. Salgado, Control system design ,Pearson Education, 2 nd Edition,2001.
	3. Katsuhiko Ogata,Modern control engineering, Pearson publication, 5 th Edition, 2017.	7. .B.S.Manke, Control System Design, Khanna publisher, 5 th Edition,2014.
	4. Stefani, shahian, savant, Hostetter, Design of Feedback control systems, Oxford university press, 4 th Edition,2014,	8. Online course material: Plat form- NPTEL, Author – Prof . S.D Agashe, IIT Bombay, Web link: https://nptel.ac.in/syllabus/108101037/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Ms.Vijayalakshmi Ramani, Head-Engineering at C2C Engineering, Chennai, vijayalakshmi@c2cengineering.co.in	1. Dr.S.K.Patnaik, CEG, Anna University, skpatnaik@annauniv.edu	1.Mr. A.Sureshkumar, SRM IST
2. Mr.Senthilkumar,ATI,rskrd1962@gmail.com,	2. Dr. S. Ramareddy, Jerusalem College of Engineering,srr.victory@gmail.com.	2.Dr.N.Chellammal, SRMIST

Course Code	18EEEC302J	Course Name	POWER ELECTRONICS	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards			Nil

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Emphasize on basics of various power devices	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Furnish adequate knowledge about the application of power devices in rectifier circuits	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Educate the students on various DC-DC converters and their design				H	M	-	-	M	-	-	-	M	M	-	-	M	M	-
CLR-4:	Illustrate the types and working of DC-AC converters				H	H	M	M	M	-	-	-	M	M	-	-	M	M	-
CLR-5:	Describe the classification of AC-AC converters and their working				H	H	M	M	M	-	-	-	M	M	-	-	M	M	-
CLR-6:	Provide basic knowledge on different industrial applications of power electronic converters				H	M	-	-	M	-	-	-	M	M	-	-	M	M	-
					H	M	M	M	M	-	-	-	M	M	-	-	M	M	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Understand and analyze the characteristics of different power devices	2	75	75															
CLO-2:	Comprehend the operation of AC-DC converters and design a converter of specific range	3	75	75															
CLO-3:	Apply the concept of chopper principle and design a DC-DC converter.	3	75	75															
CLO-4:	Articulate the concept of DC-AC conversion and model an inverter	3	75	75															
CLO-5:	Analyze the function of AC-AC converters	2	75	75															
CLO-6:	Acquire and analyze various applications of power electronic circuits	3	75	75															

Duration (hour)	15	15	15	15	15
S-1	SLO-1 Introduction to Power processing	Single phase full controlled rectifiers with R, RL load	Principles of chopper circuits	Principles of power VSI and CSI inverters	Step down Cycloconverter
	SLO-2 Construction - Principle of operation of Power diodes	Estimation of average & RMS load voltage, RMS load current and input power factor for full controlled rectifiers	Control Strategies in chopper circuits	Single phase voltage source inverter under various loading conditions	Step up Cycloconverter
S-2	SLO-1 Dynamic characteristics of Power diodes	Single phase full controlled rectifiers with RLE load	Multi- quadrant operation of chopper	Working of three phase inverter circuits in 180 degree mode of conduction	Three phase to single phase Cycloconverter
	SLO-2 Construction - Principle of operation of SCR- Dynamic characteristics of SCR	Estimation of average & RMS load voltage	Types of commutation	Determination of RMS ,average values of line and phase voltage	Three phase to three phase cyclo converter
S-3	SLO-1 Construction - Principle of operation of TRIAC, GTO	Estimation of RMS load current and input power factor	Forced commutated chopper : Voltage commutated choppers	Working of three phase inverter circuits in 120 degree mode of conduction	Introduction to matrix converter
	SLO-2 Dynamic characteristics of GTO	Problems in rectifier circuits	Forced commutated chopper : Current commutated choppers	Determination of RMS ,average values of line and phase voltage	Operation of matrix converter
S 4-5	SLO-1 Lab 1: R-RC Triggering Circuits ; UJT Triggering Circuits; HWR-FWR HWR-FWR	Lab 4: Single phase half controlled bridge rectifier with resistive and inductive loads	Lab 7: Control of DC Voltage in chopper circuits using Time ratio & pulse width control	Lab 10: Three phase DC-AC converter for different types of loads	Lab 13: Single Phase cycloconverter
S-6	SLO-1 SCR: turn-on, methods	Three phase full controlled rectifiers with R load	Load commutated chopper	Introduction to Current source inverter	AC Voltage regulator

Duration (hour)		15	15	15	15	15
	SLO-2	SCR: turn-off methods	Working of three phase full controlled rectifiers with R load for various firing angle	Introduction to isolated and Non-isolated topologies	Auto sequential current source inverter	Active power line conditioner
S-7	SLO-1	Over voltage protection:	Three phase full controlled rectifiers with RL load	Basic non-isolated topologies: Characteristics of Buck converter	Single pulse width modulation technique	UPS
	SLO-2	Over current protection	Working of three phase full controlled rectifiers with RL load for various firing angle	Derivation of voltage gain of Buck converter	Multiple pulse width modulation technique	SMPS
S-8	SLO-1	Gate Protection	Estimation of average & RMS load voltage,	Basic non-isolated topologies: Characteristics of Boost converter	Sinusoidal pulse width modulation technique (Unipolar , bipolar schemes)	HVDC systems
	SLO-2	Design of Snubber circuits	Estimation RMS load current and input power factor	Derivation of voltage gain of Boost converter	Introduction to space vector pulse width modulation	Types of HVDC systems
S-9-10	SLO-1	Lab 2: Characteristics of SCR; TRIAC	Lab 5: Three phase fully controlled rectifier with resistive load	Lab 8: Study of forced commutation techniques using chopper circuits	Lab 11: Generation of PWM signals using Sine PWM technique to trigger switches in a three phase inverter	Lab 14: A.C. voltage controllers with R and RL loads
	SLO-2					
S-11	SLO-1	Construction - Principle of operation of Power MOSFET	Single phase semi converter- Construction, working	Steady-State Equivalent Circuit Modeling of dc-dc converters- Losses and Efficiency	Voltage control of inverters	Tap changing of transformers
	SLO-2	Dynamic characteristics of Power MOSFET	Estimation of average & RMS load voltage of single phase semi converter	Resonant converters	Harmonics study and its reduction techniques	Electronic ballast
S-12	SLO-1	Construction - Principle of operation of Power IGBT	Three phase semi converter –Construction	Characteristics of CUK converter	Multilevel inverters: Introduction, Types	Induction heating
	SLO-2	Dynamic characteristics of Power IGBT	Working of three phase converter for different firing angles	Derivation of voltage gain of CUK converter	Working of cascaded seven level Inverter	Light dimmer
S-13	SLO-1	Loss calculation (Switching, conduction and leakage losses)	Estimation of average & RMS load voltage of three phase semi converter	Characteristics of SEPIC converter	Working of Diode clamped five level Inverter	Role of power converters in PV systems
	SLO-2	Problems in calculation of losses of various power devices	Effect of source inductance in full converter	Derivation of voltage gain of SEPIC converter	Working of flying capacitor five level Inverter	Role of power converters in Electric vehicles
S-14-15	SLO-1	Lab 3: Characteristics of MOSFET, IGBT	Lab 6: Three phase semi converter	Lab 9: : case study : Design and Model a Buck-Boost converter a) using real time software b) using discrete components for specific condition	Lab 12: Case study :Design a Single phase DC-AC converter to drive a 0.5 hp Single phase induction motor	Lab 15: Case study Design and analyze a fully controlled rectifier to feed a --- kW inverter using discrete components
	SLO-2					
Learning Resources	1. Mohan N, Undeland T M, and Robbins W P, Power Electronics - Converters, Applications and Design, Third Edition, John Wiley & Sons, Inc., New York, 2017. 2. Rashid M H, Power Electronics, Circuits, Devices and Applications, Prentice Hall Pearson Education, Inc., Fourth Edition 2014. 3. P.S.Bimbhra, Power Electronics, Khanna Publishers, New Delhi, Fifth edition 2012; Reprint 2014 4. M.D.Singh, K.B.Khanchandani, Power Electronics, Tata McGraw Hill, New Delhi, 2nd Edition,, 2006 5. https://nptel.ac.in/downloads/108105066/					

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Prakash G- Lead, CoreEL Technologies , Bangalore, prakash.g@coreel.com	1. Dr.S.Senthilkumar, NIT,Trichy;skumar@nitt.edu	1. Dr.N. Chellammal, SRMIST
2. Mr. Pramod Kumar N,CoreELTechnologies, Bangalore	2. Dr.G.Uma, CEG, Anna University, uma@annauniv.edu	2. Dr.R.Sridhar, SRMIST

Course Code	18EEEC303T	Course Name	POWER SYSTEM ANALYSIS	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the modeling of power system	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Examine power flow analysis using numerical techniques	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Evaluate the behavior of the power system under symmetrical fault conditions				H	H	L	-	-	-	-	-	-	-	-	-	M	M	-
CLR-4 :	Evaluate the behavior of the power system under unsymmetrical fault conditions				H	H	L	-	M	-	-	-	-	-	-	-	M	M	-
CLR-5 :	Discuss the stability issues of power system under transient condition				H	H	L	-	-	-	-	-	-	-	-	-	M	M	-
CLR-6 :	Understand the mathematical modeling and analysis of power system				H	M	L	-	-	-	-	-	-	-	-	-	M	M	-
					H	H	L	-	-	-	-	-	-	-	-	-	M	M	-
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Summarize the basics of power system components, formation of network graphs and bus admittance matrix	2	80	75															
CLO-2 :	Solve numerical methods in the application of power flow studies	3	80	75															
CLO-3 :	Analyze the impact of symmetrical faults	3	80	75															
CLO-4 :	Analyze different types of unsymmetrical faults	3	80	75															
CLO-5 :	Examine transient stability analysis and solve numerical methods for transient stability	3	80	75															
CLO-6 :	Analyze the power system under normal and fault conditions	3	80	75															

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Power scenario in India	Necessity of power flow studies	Symmetrical short circuit on Synchronous Machine	Introduction to symmetrical components	Introduction to stability studies
	SLO-2	Power system components	Bus classification	Steady state, transient and sub transient reactances	Sequence voltages and currents	Illustration of steady state stability limit
S-2	SLO-1	Per unit representation	Formulation of Power Flow problems	Study of symmetrical faults in power system	Sequence impedances and networks	Synchronizing power co-efficient
	SLO-2	Single line diagram	Power flow solution using Gauss Seidel method (algorithmic steps)	Numericals in short circuit in synchronous generator	Zero sequence networks	Review of mechanics and swing equation
S-3	SLO-1	Per unit quantities	Handling of Voltage controlled buses	Bus Impedance matrix by building algorithm (without mutual coupling) (algorithmic steps)	Types of unsymmetrical faults	Representation of swing curves
	SLO-2	p.u impedance diagram	Power flow solution using Gauss Seidel method excluding PV buses (quantitative analysis)	Bus Impedance matrix by building algorithm (without mutual coupling) (quantitative analysis)	Fault conditions for single line to ground fault	Power-Angle equation
S-4	SLO-1	Network graph	Conditions for PV buses	Bus Impedance matrix by building algorithm (including mutual coupling) (algorithmic steps)	Fault conditions for line to line fault	Equal area criterion
	SLO-2	Bus incidence matrix	Power flow solution using Gauss Seidel method including PV buses (quantitative analysis)	Bus Impedance matrix by building algorithm (including mutual coupling) (quantitative analysis)	Fault conditions for double line to ground fault	Impact of sudden load increase in synchronous motor
S-5	SLO-1	Primitive parameters	Impact of acceleration factor in convergence	Symmetrical fault analysis using Thevenin's theorem	Single line to ground fault and line to line fault in generator terminals	Illustrations of equal area criterion under different system conditions

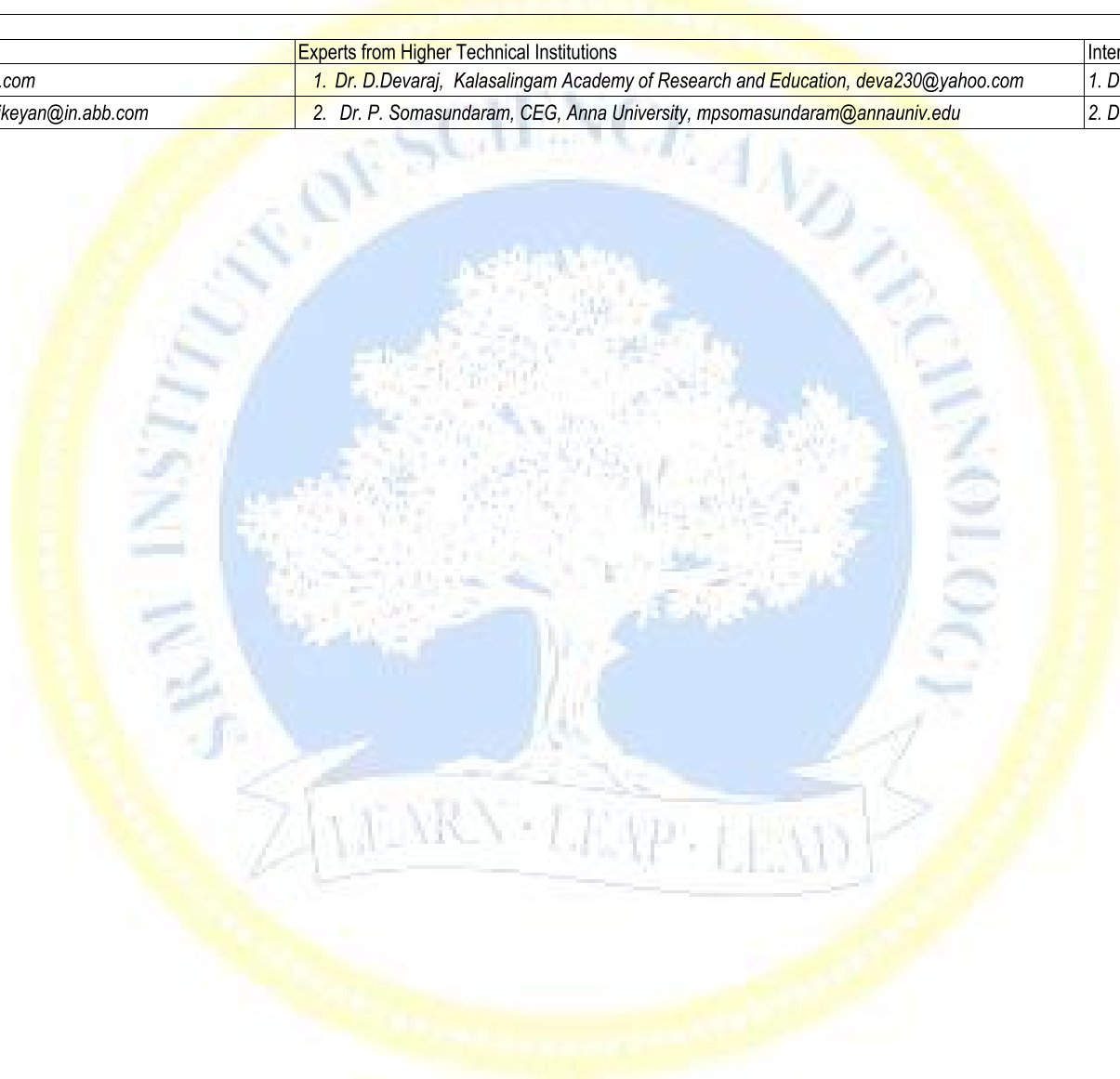
Duration (hour)		9	9	9	9	9
	SLO-2	Graph and oriented graph	Power flow solution including acceleration factor	Symmetrical fault analysis using Thevenin's theorem (numericals)	Double line to ground fault in generator terminals	Derivation of Critical clearing angle and time
S-6	SLO-1	Links and trees	Algorithmic steps of Power Flow Solution by Newton Raphson method	Derivation of Bus voltages due to current injection	Assumptions for system representation	Derivation of Critical clearing angle and time (quantitative analysis)
	SLO-2	Bus admittance matrix using singular transformation method without mutual coupling	Power Flow Solution by Newton Raphson method (quantitative analysis)	Calculation of bus voltages and line currents	Formation of positive, negative and zero sequence networks	Classical step-by-step solution of the swing curve (theoretical approach)
S-7	SLO-1	Bus admittance matrix using singular transformation method without mutual coupling (quantitative analysis)	Algorithmic steps of Power Flow Solution by Fast Decoupled method	Symmetrical fault analysis through bus impedance matrix (theoretical approach)	Bus impedance matrices of positive, negative and zero sequence networks	Classical step-by-step solution of the swing curve (numerical approach)
	SLO-2	Bus admittance matrix using singular transformation method including mutual coupling	Power Flow Solution by Fast Decoupled method (quantitative analysis)	Symmetrical fault analysis through bus impedance matrix (quantitative analysis)	Analyzing Single line to ground fault and line to line fault with fault impedance	Algorithmic steps of swing equation using Runge Kutta method
S-8	SLO-1	Representation of off nominal transformer	Derivation of Power flow in lines	Short circuit level /Fault level	Analyzing double line to ground fault with fault impedance	Numeric solution of swing equation using Runge Kutta method (quantitative analysis)
	SLO-2	Numerical problems in off nominal transformer	Numerical solution of Power flow in lines	Fault level and short circuit MVA (numericals)	Analyzing unsymmetrical fault occurring at any point in a power system	Algorithmic steps of swing equation using modified Euler's method
S-9	SLO-1	Formation of bus admittance matrix for large scale system (Theoretical approach)	Derivation of slack bus power and line losses	Current limiting reactors	Unsymmetrical fault analysis using bus impedance matrices (algorithmic)	Numeric solution of swing equation using modified Euler's method
	SLO-2	Formation of bus admittance matrix for large scale system (quantitative analysis)	Numerical solution of slack bus power and line losses	Design of circuit breakers based on fault analysis	Unsymmetrical fault analysis using bus impedance matrices (quantitative analysis)	Factors affecting transient stability

Learning Resources	1. John.J.Grainger, William D. Stevenson, Jr., Power System Analysis, McGraw Hill Education (India) Private Limited, New Delhi, 2015. 2. William D. Stevenson, Jr., Elements of Power System Analysis, McGraw Hill Education (India) Private Limited, New Delhi, 4 th Edition, 2014. 3. Nagarath I.J. and Kothari D.P., Modern Power System Analysis, 4 th Edition, McGraw Hill Education (India) Private Limited, New Delhi, 2011	4. Hadi Sadat, Power System Analysis, McGraw Hill Education (India) Private Limited, New Delhi, 2 nd Edition, 2002. 5. Pai M.A. and Dheeman Chatterjee, Computer Techniques in Power System Analysis, McGraw Hill Education (India) Private Limited, New Delhi, 3 rd Edition, 2014. 6. https://nptel.ac.in/courses/108105067/1
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Sudharsan, L&T, sudharsand@Intecc.com	1. Dr. D.Devaraj, Kalasalingam Academy of Research and Education, deva230@yahoo.com	1. Dr.J.Preetha Roselyn, SRMIST
2. Dr.K.Karthikeyan, ABB India Ltd., k.karthikeyan@in.abb.com	2. Dr. P. Somasundaram, CEG, Anna University, mpsomasundaram@annauniv.edu	2. Dr. D. Suchitra, SRMIST



Course Code	18EEEC304J	Course Name	MICROCONTROLLERS	Course Category	C	Professional Core										L	T	P	C					
						3	0	2	4															
Pre-requisite Courses		Nil	Co-requisite Courses	Nil	Progressive Courses		Nil																	
Course Offering Department		Electrical and Electronics Engineering		Data Book / Codes/Standards		Nil																		
Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the architecture and instruction set of 8051			1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-2 :	Familiarize with the programming modes of the SFRs in8051			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3			
CLR-3 :	Introduce 8051 programming in C																							
CLR-4 :	Outline the features of PIC microcontroller, its architecture and instruction set.																							
CLR-5 :	Explain the architecture of ARM Processor and its instruction set.																							
CLR-6 :	Acquire knowledge on microcontrollers and their applications.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Summarize and program 8051 microcontrollers			1	75	75	H	M	M	M	M	-	-	-	M	M	-	-	M	M	-			
CLO-2 :	Program the SFRs according to the given requirements			3	75	75	H	M	M	M	M	-	-	-	M	M	-	-	H	H	-			
CLO-3 :	Interface the various peripherals with 8051 and program 8051 using C			3	75	75	H	M	M	M	M	-	-	-	M	M	-	-	H	H	-			
CLO-4 :	Decipher the given problem and develop simple programs using PIC microcontrollers			3	75	75	H	M	M	M	-	-	-	-	M	M	-	-	H	H	-			
CLO-5 :	Analyze and develop simple programs using ARM processor for simple applications.			3	75	75	H	M	M	M	M	-	-	-	M	M	-	-	H	H	-			
CLO-6 :	Update their knowledge on microcontrollers and program them for real time applications			3	75	75	H	M	M	M	M	-	-	-	M	M	-	-	H	H	-			
Duration (hour)		15	15	15	15	15																		
S-1	SLO-1	Evolution of Microprocessors, Microcontrollers and Computers	Counters & timers: modes of operation	Introduction to interfacing peripheral devices	Introduction to PIC 16F84A microcontroller	The ARM processor -features																		
	SLO-2	Comparison of Microprocessor and Microcontroller	TMOD register	8255 PPI – Pin diagram and architecture	Applications of PIC 16F84A	Applications of ARM processors																		
S-2	SLO-1	Overview of 8-bit / 16-bit / 32-bit microprocessors and microcontrollers	TCON register	8255 PPI – Modes of operation	Architecture overview of PIC 16F84A	Architecture overview of ARM processor																		
	SLO-2	CISC and RISC architectures	Serial data transmission/ reception: modes	8279 keyboard interface - Pin diagram and architecture	PIC 16F84A - Block diagram	ARM processor - Block diagram																		
S-3	SLO-1	8051 – pin diagram	SCON register	8279 keyboard interface - modes of operation	Working register	The ARM programmer's model																		
	SLO-2	8051 - Internal Block Diagram	PCON register	LCD interfacing	Status register	ARM Current Program Status Register																		
S-4-5	SLO-1	Lab 1: Introduction to 8051 microcontroller	Lab 4: Boolean and logical operations (bit & byte level logical operations) using 8051 microcontroller	Lab 7:8 bit ADC using 8051 microcontroller	Lab 10:: Transfer data serially between two kits	Lab 13:DC motor speed measurement and control.																		
	SLO-2																							
S-6	SLO-1	8051 - architecture	Internal Interrupts	Parallel and serial ADC interface	File selection register	ARM exceptions																		
	SLO-2	Internal memory organization	External Interrupts	DAC interface	Indirect data addressing register	Introduction to Thumb instructions																		
S-7	SLO-1	Register banks, PSW	IE register	Sensor interfacing	memory organization- Program memory	Pipeline ARM organization (3,5 stage)																		
	SLO-2	Ports	IP register	Stepper motor interfacing	Data memory	ARM instruction set: data processing instructions – arithmetic operations																		

S-8	SLO-1	Classification of instruction set	Clock circuit	DC motor interfacing and PWM	Watch dog timer	data processing instructions –bitwise logical, register movement & comparisons operations
	SLO-2	Addressing modes	RESET circuit	RTC interfacing	Power down/ sleep mode	Data transfer instructions – single load/store
S-9-10	SLO-1	Lab 2:Arithmetic operation using 8051 microcontrollers	Lab 5:Square root computation	Lab 8:8 bit DAC using 8051 microcontroller	Lab 11: Internal interrupt generation	Lab 14: Basic ARM ALP(32-bit addition, subtraction, multiplication)
S-11	SLO-1	Instruction set - Data transfer,	Semiconductor memory -Types	Introduction to 8051 programming in C	PIC 16F84A parallel ports	Data transfer instructions – multiple load/store
	SLO-2	Instruction set - Logical operations, data exchange	Memory address decoding	Data types for 8051 C	Clock and oscillator circuits	Data transfer instructions –swap
S-12	SLO-1	Instruction set - arithmetic operations	8031/51 Interfacing with External ROM and RAM	I/O programming and logical operations in 8051 C	Instruction set – Arithmetic instructions	Control flow instructions – Branch, conditional branch
	SLO-2	Instruction set – Call, return	Pins PSEN, EA	Accessing code ROM space in C	logic instructions	Control flow instructions –jump
S-13	SLO-1	Instruction set – bit jump	Data memory space	Programming timers in 8051C	Instruction set – test and skip instructions	AMBA bus architecture
	SLO-2	Instruction set – byte jump	Problems on external memory interfacing	Calculation of time delays	jump instructions	ARM development tools – ARMulator
S-14-15	SLO-1	Lab 3:Sorting data, Code conversion using 8051 microcontroller	Lab 6:: Delay generation using an on-chip timer using 8051 microcontrollers.	Lab 9:8279 Keyboard & display using 8051 controllers.LCD Display using 8051	Lab 12: Stepper motor control using 8051	Lab 15:Basic ARM binary sorting
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Muhammad. Ali.Mazidi, the 8051 Microcontroller and Embedded Systems: Second edition, Pearson Education Limited, 2013. 2. K. J. Ayala, 8051 Microcontroller, Delmar Cengage Learning, 3rd edition,2007. 3. Subrata Ghoshal, 8051 Microcontroller Internals, Instructions, Programming and Interfacing, Second edition, Pearson Education Asia, 2014. 4. John Peatman, Design with PIC Microcontrollers,PearsonEducationAsia, 8th impression 2009 	<ol style="list-style-type: none"> 5. SteveFurber, ARM System-on-chip architecture, PearsonEducation, India, 2000. 6. Tim Wilmshurst, Designing Embedded Systems with PIC Microcontrollers: Principles and applications, Published by Elsevier, 2010 7. https://nptel.ac.in/courses/117104072/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Roosefart Mohan, Nelcast Limited, Chennai, roosefart@gmail.com	1. Dr.R.Subha, Sir MVIT, Bangalore, subha.mvit@gmail.com	1. Dr.D. Suchitra, SRMIST
2.Mr.Muralikrishna, National Instruments, emkkrishnan@gmail.com	2. Dr. A. Venkadesan, NIT, Puducherry, venkadesan@nitpy.ac.in	2. Ms. D. Anitha, SRMIST

Course Code	18EEEC305T	Course Name	POWER SYSTEM PROTECTION	Course Category	C	Professional Core	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand the principles of modern power system protection	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Enumerate the various protection schemes	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Acquire the knowledge of protection of Generator, Transformer and Busbar protection system				H	-	-	-	-	-	-	M	-	-	-	-	M	M	M
CLR-4 :	Understand the various types of digital protection and relay coordination				H	H	-	-	-	-	-	-	-	-	-	-	M	M	-
CLR-5 :	Describe the protection of switchgears in sub-station and its relay setting calculations				H	H	-	-	M	-	-	-	-	-	-	-	H	H	-
CLR-6 :	Gain an overall knowledge of power system protection concepts in various applications				H	H	-	-	-	-	-	-	-	-	-	-	M	M	-
					H	H	-	-	M	-	-	M	-	-	-	-	H	H	M
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Recognize the power system protection basics and standards	2	80	75															
CLO-2 :	Employ various protective schemes and needed instruments	3	80	75															
CLO-3 :	Explain the various equipment protection and its characteristics	3	80	75															
CLO-4 :	Familiarise various relay algorithms and applications of digital protection	3	80	75															
CLO-5 :	Analyse the use of protection and switchgears	3	80	75															
CLO-6 :	Apply power system protection concepts in real time environment	3	80	75															

Duration	9	9	9	9	9
S-1	SLO-1	Introduction to power system protection	Over current protection	Transformer protection	Introduction to Digital relays - Numerical relays
	SLO-2	Basic requirements	Characteristics of over current protection	Differential protection	Functional blocks of numerical relay
S-2	SLO-1	Main components of protections	Over current protection coordination	Percentage biased differential protection	Numerical over current relay algorithm
	SLO-2	Functions of protection	Relay setting calculation	Differential protection scheme for various types of three phase transformé	Numerical over current relay Flow chart
S-3	SLO-1	IEC – IEEE standards for protection	Numerical problems for over current setting	Numerical problems for differential protection	Numerical differential relay algorithm
	SLO-2	ANSI standards for protection	Numerical problems for over current setting	Numerical problems for differential protection	Numerical differential relay Flow chart
S-4	SLO-1	Zone of protection - overlapping	Directional over current relay	Magnetizing inrush current and harmonics restraint method	Numerical distance relay algorithm
	SLO-2	Primary – back up protection	Charcateristics of directional over current relay	Over fluxing protection, Incipient fault protection - Buchholz Relay	Numerical distance relay Flow chart
S-5	SLO-1	Unit, Non – Unit protection	Principle of distance protection	Alternator protection	Fibre Optic based relaying
	SLO-2	Applications of unit, non-unit protection	Charcateristics of distance relay	stator protection	Fibre optic relay Functions - application
S-6	SLO-1	Other types of protection schemes	Simple impedance, Reactance and Mho relay	Rotor protection	Wide Area Protection - functions
					Fuses – Types
					Construction of fuse
					Fuse characteristics
					Applicaion of fuse
					Theory of current interruption,
					Arc quenching – Interruption theories
					Recovery and Restriking voltages
					RRRV
					Types of circuit breakers -Bulk oil, Minimum oil circuit breakers
					Functions - applications
					Air break, Air blast circuit breakers

Duration		9	9	9	9	9
	SLO-2	Applications of protection schemes	Characteristics of impedance relay	Protection against abnormal condition - unbalanced loading, Over-speeding	Introduction to simulation of relay coordination	Functions - applications
S-7	SLO-1	Current Transformer for protection	Three step distance protection	Loss of excitation	Applications of digital signal processing tool for protection	Sulphur hexafluoride (SF6) and Vacuum circuit breakers
	SLO-2	Characteristics – numerical problems	Application of three step distance protection	Loss of prime mover	Functional blocks DSP	Applications of SF6 and vacuum circuit breakers
S-8	SLO-1	Voltage Transformer for protection	Carrier aided protection	Bus bar protection scheme	AI techniques to power system protection	Comparison of circuit breakers
	SLO-2	Characteristics of current transformer	Main components of carrier aided protection	Types of bus bar protection	Applications Of artificial intelligence in protection	Testing of circuit breaker
S-9	SLO-1	Electromechanical relays – construction	Bus bar protection scheme	Protection against over voltage - diverters,	Digital protection - Introduction to RTDS	Circuit breakers rating
	SLO-2	Relay operation - application	Types of bus bar	Lightning arrestor	Digital substation	Relay setting calculation and its operation

Learning Resources	1. Badriram & Vishwakarma, Power System Protection, Tata McGraw-Hill Education, 10th reprint, 2015	5. Bhavesh R. Bhalja, R. P. Maheshwari, Nilesh Chothani, oxford university press, Second Edition, 2018
	2. Paithankar Y. G., S. R. Bhide., Fundamentals of power system protection', PHI Learning Pvt. Ltd., 10th reprint, 2010.	6. A. Kalam, D.P. Kothari, Power System Protection and Communication, New Age Science Ltd, 2009.
	3. J. Lewis Blackburn & Thomas J. Domin, Protective Relaying - Principles and Applications, Fourth Edition, CRC Press.	7. Paul M. Anderson, Power System Protection, IEEE press series on Power Engineering, 1999.
		8. https://nptel.ac.in/courses/108101039/

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Understand										
	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Analyze										
	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. Swaroop Gajare, Lead Engineer, Power Systems Technologies, Eaton Research Labs, swaroopgajare@eaton.com	2. Dr. P. Raja, NIT Tiruchirappalli, praja@nitt.edu	2. Dr. M. Senthilkumar, SRMIST

Course Code	18EEEC401J	Course Name	POWER SYSTEM OPERATION AND CONTROL	Course Category	C	Professional Core	L	T	P	C
							3	0	2	4

Pre-requisite Courses	18EES101J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Understand the control methods of frequency in power system	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Understand voltage control methods in power system	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Formulate the economic operation of power system				H	H	M	L	H	-	-	M	M	-	-	-	M	M	M
CLR-4:	Discuss the different methods to reduce losses and cost in power system				H	H	M	L	H	-	-	M	M	-	-	-	M	M	M
CLR-5:	Develop knowledge on operation and control strategies of power system				H	H	M	L	H	-	-	-	M	-	-	-	M	M	-
CLR-6:	Summarize the operation and control of power system				H	H	M	H	H	-	-	-	M	-	-	-	M	M	-
					H	H	M	L	H	-	-	M	M	-	-	-	M	M	M
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	Analyze frequency control in single area and two area system	3	75	75															
CLO-2:	Model excitation systems and develop methods of voltage control	3	75	75															
CLO-3:	Examine numerical methods of economic dispatch	3	75	75															
CLO-4:	Solve unit commitment and optimal power flow problem	3	75	75															
CLO-5:	Analyze the functions of modern energy control centre on monitoring, data acquisition and control	3	75	75															
CLO-6:	Evaluate the strategies of operation and control	3	75	75															

Duration (hour)	15	15	15	15	15
S-1	SLO-1 Basic concepts of operation and control of power system	Need for voltage control	Input-output characteristics of thermal units and Heat rate Curve	Statement of Unit Commitment problem	Operating strategies
	SLO-2 Plant and system level control	Requirement of reactive power	Input-output characteristics of Cost Curve.	Problem constraints	Control Strategies under abnormal state
S-2	SLO-1 Interaction of AVR and ALFC loops	DC Excitation system with amplidyne voltage regulator	Optimum generation allocation neglecting network losses and inequality constraints	Priority List method	Concept of modern control centre: monitoring, data acquisition and control
	SLO-2 Speed load characteristics	Field controlled alternator rectifier excitation	Optimum generation allocation neglecting network losses and inequality constraints-numerical approach	Priority List method-numerical approach	Introduction to SCADA system
S-3	SLO-1 Modelling of speed governing mechanisms	Static Excitation systems	Optimum generation allocation neglecting network losses and including inequality constraints	Dynamic programming to unit commitment problem	Components of SCADA system
	SLO-2 Regulation of two alternators in parallel	Brushless AC Excitation systems	Optimum generation allocation neglecting network losses and including inequality constraints- numerical approach	Algorithmic steps of Dynamic programming	Applications of SCADA in power systems
S 4-5	SLO-1 Lab 1: Real time data acquisition of electrical parameters	Lab 4: Development of voltage controllers using simulation tool	Lab 7: Economic dispatch neglecting losses	Lab 10: Unit commitment using priority method	Lab 13: Study of SCADA systems
S-6	SLO-1 Concept of Control area	Schematic diagram of brushless excitation system	Loss Coefficients	Dynamic programming-numerical approach	PLC architecture and communication links

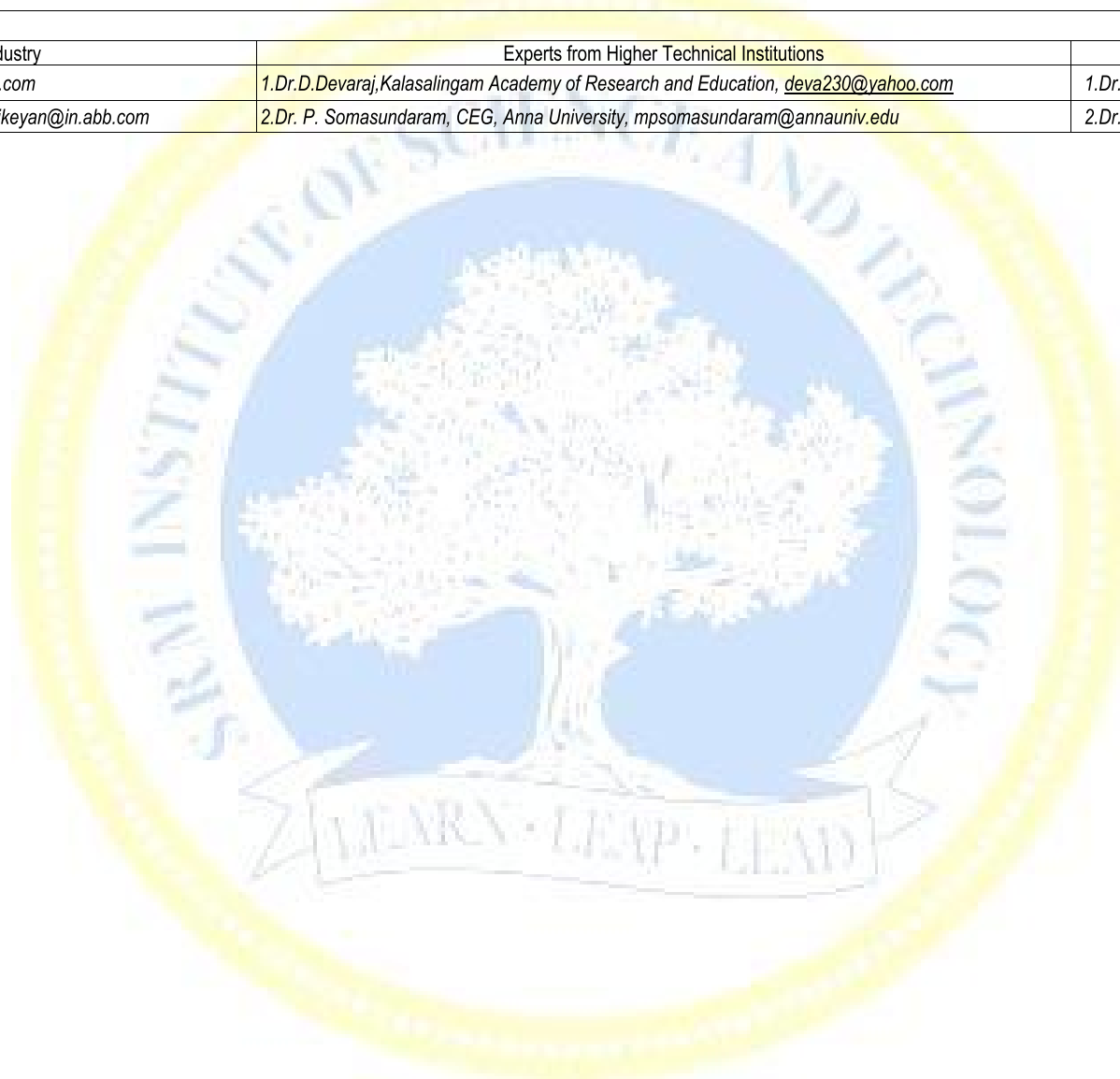
Duration (hour)		15	15	15	15	15
	SLO-2	Closing ALFC loop	Modelling of AVR and Exciter	Transmission line loss formula	Lagrange Relaxation method	State estimation by weighted least square method
S-7	SLO-1	Static response of single area system-uncontrolled case	Modelling of synchronous generator	Incremental cost of received power	OPF problem formulations	State estimation by weighted least square method-numerical approach
	SLO-2	Dynamic response of single area system-uncontrolled case	Static performance of AVR loop	Penalty factors	Constraints in OPF problem	Wide area monitoring systems
S-8	SLO-1	Proportional plus integral controller	Dynamic response of AVR loop	Base point and Participation factor method	Gradient method of OPF problem	Introduction to phasor measurement units
	SLO-2	Static response of single area system-controlled case	Stability compensation and stability analysis using Bode Plot	Base point and Participation factor method-numerical approach	Gradient method of OPF problem-numerical approach	Comparison of SCADA with PMU
S-9-10	SLO-1	Lab 2: Automatic Load frequency control in single area system using simulation tool	Lab 5: Stability analysis of AVR loop	Lab 8: Economic dispatch including losses	Lab 11: Gradient method of OPF problem	Lab 14: State estimation using weighted least square method
	SLO-2	Dynamic response of single area system-controlled case	IEEE Excitation models	Economic dispatch by gradient method	Linear programming OPF	PMU architecture
S-11	SLO-1	Modelling of tie line	Voltage drop/rise in transmission lines	Economic dispatch by gradient method-numerical approach	Newton method of OPF	Levels of PDC
	SLO-2	Modeling of Two area frequency control	Methods of voltage control- shunt capacitors, shunt reactors	Objectives and constraints in Security constrained economic dispatch	Security Constrained OPF-objectives	Mathematical formulation of optimal placement of PMUs
S-12	SLO-1	Block diagram representation of two area system	Methods of voltage control- FACTS devices	Security constrained economic dispatch using linear programming	Security Constrained OPF-constraints	Optimal placement of PMU using linear programming
	SLO-2	Static response of two area system	Methods of voltage control- tap changing transformer	Economic dispatch added to LFC control	Introduction to multi objective OPF	Need for Integration of Distributed generation
S-13	SLO-1	Dynamic response of two area system	Numerical approach in tap changing transformer	Hydrothermal scheduling neglecting network losses –long term	Formulation of combined active and reactive power dispatch	Control and operation of distributed generation
	SLO-2	Lab 3: Automatic Load frequency control in two area system using simulation tool	Lab 6: Study of voltage control techniques	Lab 9:Economic dispatch using gradient method	Lab 12: Study of numerical methods of OPF problem	Lab 15: Performance characteristics of Solar PV system and study of PV emulator

Learning Resources	1. Olle.I.Elgerd, <i>Electric Energy systems theory- An Introduction</i> , Tata Mc Graw Hill publishing Ltd, New Delhi, 27 th reprint, 2007. 2. I.J.Nagrath and D.P.Kothari, <i>Power system engineering</i> , Tata Mc Graw Hill publishing Ltd, 2 nd edition, 2007.	3. Allen J.Wood and Bruce F. Woollenburg, Gerald B.Sheble, <i>Power generation, operation and control</i> , 3 rd edition, John Wiley and sons, 2013. 4. Prabha Kundur, <i>Power system stability and control</i> , Tata Mc Graw Hill publishing Ltd, New Delhi, 1 st edition, 2006 5. https://nptel.ac.in/courses/108101040/
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Sudharsan, L&T, sudharsand@Intecc.com	1.Dr.D.Devaraj, Kalasalingam Academy of Research and Education, deva230@yahoo.com	1.Dr.J.Preetha Roselyn, SRMIST
2. Dr.K.Karthikeyan, ABB India Ltd., k.karthikeyan@in.abb.com	2.Dr. P. Somasundaram, CEG, Anna University, mpsomasundaram@annauniv.edu	2.Dr.R.Jegatheesan, SRMIST



Course Code	18EEEC350T	Course Name	COMPREHENSION	Course Category	C	Professional Core	L	T	P	C
							0	1	0	1

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electrical and Electronics Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire skills to solve real world problems in analyzing the electric circuits, analog and digital electronics				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire skills to solve real world problems in electromagnetic theory, power electronics and control system							Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Modern Tool Usage	Society & Culture	Environment & Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Acquire skills to solve real world problems in electrical machines, measurements and Instrumentation																					
CLR-4 :	Acquire skills to solve real world problems in Generation, Transmission and Distribution networks and its analysis																					
CLR-5 :	Acquire skills to solve real world problems in microcontrollers and its applications																					
CLR-6 :	Acquire skills to solve real world problems for competitive examinations in Electrical and Electronics Engineering																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			3	85	80	H	H	H	H	-	L	L	L	L	L	-	L	H	H	M
CLO-1 :	Practice and gain confidence and competence to solve problems in analyzing the electric circuits, analog an ,digital electronics				3	85	80	H	H	M	M	-	L	L	L	L	L	-	L	H	H	M
CLO-2 :	Practice and gain confidence and competence to solve problems in electromagnetic theory, power electronics and control system				3	85	80	H	H	M	M	-	L	L	L	L	L	-	L	H	H	L
CLO-3 :	Practice and gain confidence and competence in electrical machines, measurements and Instrumentation				3	85	80	H	H	M	M	-	L	L	L	L	L	-	L	H	H	M
CLO-4 :	Practice and gain confidence and competence in Generation, Transmission and Distribution networks and its analysis				3	85	80	H	H	H	H	-	L	L	L	L	L	-	L	H	H	L
CLO-5 :	Practice and gain confidence and competence in microcontrollers and its applications				3	85	80	H	H	M	M	-	L	L	L	L	L	-	L	H	H	L
CLO-6 :	Practice and gain confidence and competence to solve problems for competitive examinations in Electrical and Electronics Engineering				3	85	80	H	H	M	M	-	L	L	L	L	L	-	L	H	H	L

Duration (hour)	3	3	3	3	3
S-1	SLO-1	Tutorial on AC and DC circuits	Tutorial on Electric Field, Dielectric concepts, Maxwell Equation	Tutorial on Transformers, generators and motors	Tutorial on ac and dc transmission concepts and distribution systems
	SLO-2	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-2	SLO-1	Tutorial on characteristics of diode, amplifiers and OPAMP	Tutorial on semiconductor power devices, rectifier and inverter operation	Tutorial on bridges and potentiometer	Tutorial on per unit quantities and load flow methods
	SLO-2	Problem Solving	Problem Solving	Problem Solving	Problem Solving
S-3	SLO-1	Tutorial on combinational and sequential logic circuit	Tutorial on Controllers, transient and steady state analysis of LTI systems	Tutorial on phase, time and frequency measurement	Tutorial on protection methods and circuit breakers
	SLO-2	Problem Solving	Problem Solving	Problem Solving	Problem Solving

Learning Resources	1.	Jegatheesan R, Analysis of Electric Circuits, McGraw Hill, 2014	9.	R.S.Goankar, Microprocessor Architecture Programming and Applications with the 8085, 6th edition, Penram International Publishing (India) Pvt.Ltd, 2013.
	2.	Jacob Millman, Christos C.Halkias, SatyabrataJit, Millman's Electronic Devices and Circuits, 4th ed., Tata McGraw Hill, 2015	10.	C. L. Wadwa, Electric Power Systems, 7th ed., New Age International Publishers, 2016
	3.	M. Morris Mano, Michael D. Ciletti, Digital Design: With an Introduction to Verilog HDL, VHDL and System Verilog, 6th ed., Pearson, 2018	11.	https://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-071j-introduction-to-electronics-signals-and-measurement-spring-2006/lecture-notes/
	4.	William Hayt, Engineering Electromagnetics, 7th ed., McGraw Hill, 2014	12.	https://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-632-electromagnetic-wave-theory-spring-2003/index.htm
	5.	Mohan N, Undeland T M, and Robbins W P, Power Electronics - Converters, Applications and Design, Third Edition, John Wiley & Sons, Inc., New York, 2017	13.	https://nptel.ac.in/downloads/108105066/
	6.	I J Nagarath and M.Gopal, Control systems Engineering, New age international publication, 6th Edition, 2017.		

7. J. B. Gupta, <i>Theory & Performance of Electrical Machines</i> , 15th ed., S.K.Kataria & Sons, 2015	14. Online course material: Plat form- NPTEL, Author – Prof . S.D Agashe, IIT Bombay, Web link: https://nptel.ac.in/syllabus/108101037/
8. A.K.Sawhney, <i>A Course in Electrical and Electronic Measurements and Instrumentation</i> , Dhanpat Rai & Co, 2012.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (100% weightage)								Final Examination	
		CLA – 1 (20%)		CLA – 2 (30%)		CLA – 3 (30%)		CLA – 4 (20%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	-	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	-	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	-	-
	Create										
	Total	100 %		100 %		100 %		100 %		-	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr.Senthilkumar,ATI,rskrd1962@gmail.com,	2. Dr. S. Ramareddy, Jerusalem College of Engineering,srr.victory@gmail.com.	2. Mr. V. Pradeep, SRMIST