

# ACADEMIC CURRICULA

**Professional Elective Courses**

**ELECTRONICS AND COMMUNICATION ENGINEERING**

**Regulations - 2018**

**SRM INSTITUTE OF SCIENCE AND TECHNOLOGY**

**(Deemed to be University u/s 3 of UGC Act, 1956)**

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18ECE201J	Course Name	PYTHON AND SCIENTIFIC PYTHON	Course Category	E	Professional Elective				L	T	P	C
										2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	<i>Understanding the python language construct and apply them for scientific computation</i>	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	<i>Apply python vector ,list and plot concept to solve curve fitting</i>	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	<i>Applying Dictionary concept to model Polynomials</i>																		
CLR-4 :	<i>Create insights to difference equation based system model and solving them with python</i>																		
CLR-5 :	<i>Analyze Monte Carlo Simulation for computing Probabilities</i>																		
CLR-6 :	<i>Create insights to the concepts and programming of SciPy, numpy, matplotlib to solve scientific problem</i>																		
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>																			
CLO-1 :	<i>Restate python language to compute formula and scientific problem</i>	1	60	60	H	-	-	-	M	-	-	-	-	-	-	-	-	-	L
CLO-2 :	<i>Translate mathematical models and system using difference equations</i>	1	60	60	H	M	-	-	M	-	-	-	-	-	-	-	-	-	L
CLO-3 :	<i>Examine time sequence concept for generation and processing of audio signal by python</i>	2	60	60	M	-	-	H	M	-	-	-	-	-	-	-	-	-	M
CLO-4 :	<i>Demonstrate python language to solve Polynomials</i>	2	60	60	M	H	-	-	M	-	-	-	-	-	-	-	-	-	L
CLO-5 :	<i>Apply python language construct to compute probability by Monte Carlo Simulation ,game design and dynamic random motion creation</i>	2	60	60	H	-	H	-	M	-	-	-	-	-	-	-	-	-	H
CLO-6 :	<i>Solve statistical analysis , correlation coefficient analysis , Solving equations- Linear least squares solutions and signal processing problems using SciPy, numpy, matplotlib</i>	2	60	60	-	M	-	-	H	-	-	-	-	-	-	-	-	-	H

Duration (hour)		Solving Simple Formula And Scientific Problem	Plots, Array and Difference Equation Modelling	File I/O, Polynomials and Web Programming	Random Process and Game Programming	SciPy ,Numpy and Signal Processing
		12	12	12	12	12
S-1	SLO-1	<i>Computing with Formulas- Using a Program as a Calculator</i>	<i>Vectors, Mathematical Operations on Vectors, Vector Arithmetics and Vector Function</i>	<i>Reading Data from File- Line by Line, Reading a Mixture of Text and Numbers</i>	<i>Drawing Random Numbers- Uniformly Distributed Random Numbers</i>	<i>SciPy, numpy, matplotlib</i>
	SLO-2	<i>Using Variables, Formatting Text and Numbers</i>	<i>Arrays in Python Programs-Using Lists for Collecting Function Data</i>	<i>Making Dictionaries</i>	<i>Computing the Mean and Standard Deviation</i>	<i>Basic array methods in numpy, Changing the shape of an array</i>
S-2	SLO-1	<i>Celsius-Fahrenheit Conversion,</i>	<i>Curve Plotting-The SciTools and Easyviz Packages</i>	<i>Dictionary Operations</i>	<i>The Gaussian or Normal Distribution- Drawing a Random Element from a List</i>	<i>Maximum and minimum values</i>
	SLO-2	<i>Evaluating Standard Mathematical Functions, Type Conversion</i>	<i>Plotting a Single Curve, Decorating the Plot, Plotting Multiple Curves, Controlling Line Styles</i>	<i>Polynomials as Dictionaries, File Data in Dictionaries, File Data in Nested Dictionaries</i>	<i>Drawing random interger</i>	<i>Reading and writing an array to a file</i>
S 3-4	SLO-1	<i>Lab 1:programming on formula and Standard Mathematical Functions- Evaluate a Gaussian function,</i>	<i>Lab 4: Curve Plotting</i>	<i>Lab 7: reading student marks file into a dictionary data with the student name as key and computing the average grades</i>	<i>Lab 10: real card games</i>	<i>Lab 13: numpy file reading and data analysis</i>
	SLO-2	<i>Compute the air resistance on a football</i>				
S-5	SLO-1	<i>Complex Numbers, Complex</i>	<i>Numerical Python Arrays manipulations</i>	<i>Strings- Common Operations on Strings</i>	<i>Computing Probabilities- Principles of</i>	<i>Statistical methods in numpy</i>

		Arithmetic's in Python			Monte Carlo Simulation	
	SLO-2	Input Data-Reading Keyboard Input-Reading from the Command Line	Higher-Dimensional Arrays- Two-Dimensional Numerical Python Arrays	Reading Coordinates	Throwing Dice, Rolling Two Dice game	Statistical methods in numpy
S-6	SLO-1	Making Modules, Collecting Functions in a Module File	Matrix Objects	Reading Data from Web Pages- About Web Pages	Drawing Balls from a Hat	Histograms
	SLO-2	Using Modules	Mathematical Models Based on Difference Equations- Interest Rates	Access Web Pages in Programs- Reading Pure Text Files,	Simple Games- Guessing a Number	Solving equations- Linear least squares solutions- Beer-Lambert Law
S 7-8	SLO-1	Lab 2: program on Making Modules and using them	Lab 5: Animating a Function-temperature on earth	Lab 8:reading web temperature text file into Dictionaries and computing average Temperature	Lab 11: Simple Games	Lab 14: the correlation coefficient between pressure and temperature
	SLO-2					
S-9	SLO-1	While loops and for loops	The Factorial as a Difference Equation	Extracting Data from an HTML Page	Random Walk in One Space Dimension	One-Dimensional Fast Fourier Transforms
	SLO-2	Lists and list manipulation	Growth of a Population, Payback of a Loan, Making a Living from a Fortune	Writing a Table to File, Reading and Writing Spreadsheet Files	Basic Implementation, visualization and Computing Statistics of the Particle Positions	Matplotlib basics- Plotting on a single axes object, scatter plot, Bar charts and pie charts
S-10	SLO-1	Loops with List Indices, Nested Lists	Logistic Growth, Programming with Sound Writing Sound to File, Reading Sound from File,	Representing a Function as a Class and manipulation	Random Walk in Two Space Dimensions	Choosing the Length of the DFT
	SLO-2	Tuples, Functions, Lambda Functions, If Tests	Playing Many Notes	Bank Accounts as class, A Class for Solving ODEs	Basic Implementation, visualization and Computing Statistics of the Particle Positions	Filters in Signal Processing
S 11-12	SLO-1	Lab 3: Programming on list and loops	Lab 6: Sound generated by formula and difference equation	Lab 9: Programming on class	Lab 12: Random Walk in One Space Dimension or Two Space Dimensions	Lab 15: Numpy signal processing
	SLO-2					

Learning Resources	1. Hans Petter Langtangen, "A Primer on Scientific Programming with Python", Springer, 2000. 2. Christian Hill, "Learning Scientific Programming with Python", Cambridge University Press, 2015.	3. Juan Nunez-Iglesias, Stéfan van der Walt, and Harriet Dashnow Elegant SciPy Te Art of Scientific Python, O'Reilly Media, 2017.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers														
Experts from Industry				Experts from Higher Technical Institutions						Internal Experts				
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com				1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu						1. Dr. P. Vijayakumar , SRMIST				
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com				2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in										
Course Code	18ECE202T	Course Name	MICRO- AND NANO-FABRICATION TECHNOLOGIES			Course Category	E	Professional Elective			L	T	P	C





		Technique	high current Inplants	junction Bipolar Transistor	
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Learning Resources	1. Sorab. K. Gandhi, "VLSI Fabrication and Principles", McGraw Hill, 2005 2. Sami Franssila, "Introduction to Microfabrication", Wiley Publications, 2010 3. Richard C. Jaeger, "Introduction to Microelectronic Fabrication", Prentice hall, 2002 4. Ivor Brodie & Julius J. Muray, "The Physics of Micro/ Nano- Fabrication" Springer, 1992	5. Bo Cui, "Recent advances in Nanofabrication Techniques and Applications", InTech Publisher, 2011 6. A G Davies and J M T Thompson, "Advances in Nanoengineering Electronics, Materials and Assembly", Imperial College Press, 2007 7. Michael Pycraft Hughes, "Nanoelectromechanics in Engineering and Biology", by CRC Press LLC, 2003
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		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	40%	-	40%	-	40%	-	40%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	20%	-	20%	-	20%	-	20%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE203T	Course Name	SEMICONDUCTOR DEVICE MODELING	Course Category	E	Professional Elective				L	T	P	C
										3	0	0	3

Pre-requisite Courses	18ECC102J	Co-requisite Courses	Nil	Progressive Courses	Nil								
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil								

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the properties of semiconductor materials				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Understand the mechanisms that occur in a PN junction				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Understand the characteristics and modeling of BJT																							
CLR-4 :	Understand the modeling aspects of MOSFET																							
CLR-5 :	Identify the effects of MOSFET scaling and special MOSFETs																							
CLR-6 :	Understand the fundamental physical processes of semiconductor devices to meet the challenge of these dynamic fields.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	H	H	-	H	-	-	-	-	-	-	-	-	-	-	-		
CLO-1 :	Identify and Choose semiconductor materials for various applications							2	60	60	H	H	-	H	-	-	-	-	-	-	-	-	-	H
CLO-2 :	Interpret the characteristics of Junction devices							2	60	60	H	H	-	H	-	-	-	-	-	-	-	-	-	H
CLO-3 :	Modify and model the BJT parameters for better performance							2	60	60	H	-	-	H	-	-	-	-	-	-	-	-	-	H
CLO-4 :	Evaluate and optimize the performance of MOSFET							2	60	60	H	-	-	H	-	-	-	-	-	-	-	-	-	H
CLO-5 :	Build new devices with small channel							2	60	60	H	H	-	H	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Explain the equations, approximations and techniques available for deriving a model with specified properties, for a general device characteristic with known qualitative theory				2	60	60	H	H	-	H	-	-	-	-	-	-	-	-	-	-	H		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Electron, Hole Densities In Equilibrium: Distribution of quantum states in energy band	PN Junction under thermal equilibrium: Built in potential, concept of space charge layer	Current components, Basic BJT parameters,	MOS diode	Scaling of MOSFETS
	SLO-2	Fermi – Dirac Statistics	Problem Solving	Limitations on the junction voltage	Operation of Ideal MOS diode (at VGB >0)	Effect of Gate voltage on carrier mobility
S-2	SLO-1	Electron concentration conduction band	Distribution of electric filed and potential within the space charge layer for abrupt junctions at Zero bias	Capacitances in a BJT,	Operation of ideal MOS diode (at VGB <0)	Effect of Drain voltage on carrier mobility
	SLO-2	Hole concentration Valence band	Distribution of electric filed and potential within the space charge layer for abrupt junctions at Zero bias	Switching of BJT	Operation of ideal MOS diode with and without oxide charge	Effect of Drain voltage on carrier mobility
S-3	SLO-1	Carrier concentration in intrinsic semiconductors	Distribution of electric filed and potential within the space charge layer for linearly graded junctions at Zero bias	Ebers-Moll model	Effects of mobile Ionic charges	Channel length modulation
	SLO-2	Position of Fermi level in extrinsic semiconductors	Distribution of electric filed and potential within the space charge layer for linearly graded junctions at Zero bias	Problem Solving	Problem Solving	Breakdown and punch through
S-4	SLO-1	Ionization of impurities, Equilibrium electron and hole concentration	PN Junction under applied bias: Depletion layer capacitance in an abrupt PN junctions	Early effect (CB & CE)	Oxide charges and Interface states	Sub threshold current
	SLO-2	Problem Solving	Problem Solving	Operation of BJT at high frequencies: Charge control	C-V Characteristics	Sub threshold current

				model		
S-5	SLO-1	Fermi level at thermal equilibrium	Depletion layer capacitance with arbitrary doping profiles	Small signal equivalent circuit.	Problem Solving	Short channel effects
	SLO-2	Problem Solving	Static current voltage characteristics of PN junction,	Problem Solving	Threshold voltage of MOSFET	Short channel effects
S-6	SLO-1	Excess Carriers: Generation and recombination of carriers	Current-voltage relationship in an infinitely long diode,	Design of high frequency transistors	Bulk charge model	Meyer's model
	SLO-2	Mobility of carriers	Quasi Fermi level under bias condition	Problem Solving	Problem Solving	Small signal model
S-7	SLO-1	Charge transport in semiconductors: Drift current	Current –voltage relation in practical diodes having finite lengths	Second order effects in BJT: Non-uniform doping in the base	Square law method (Level 1 in SPICE)	MOSFET scaling
	SLO-2	Hall effect	Ideality factor	Non-uniform doping in the base	Square law method (Level 1 in SPICE)	Non-uniform doping in channel
S-8	SLO-1	Diffusion current	Transient analysis: Time variation of stored charge	Variation of $\beta$ with collector current	Level 3 model in SPICE	SOI MOSFET
	SLO-2	Problem Solving	Problem Solving	High injection in collector	BSIM Models	SOI MOSFET
S-9	SLO-1	Current density equations	Reverse recovery of a diode, charge storage capacitance	Heavy doping effects in the emitter	Comparison of Models	Buried channel MOSFET
	SLO-2	Current density equations	Problem Solving	Emitter crowding in bipolar transistors	Comparison of Models	Fin FET

Learning Resources	1. Nandita Das Gupta, Amitava Das Gupta, Semiconductor devices, modeling and Technology, Prentice Hall of India, 2004 2. Philip. E. Allen Douglas, R. Hoberg, CMOS Analog circuit Design, 2 <sup>nd</sup> ed., Oxford Press, 2002	3. S.M. Sze, Semiconductor Devices-Physics and Technology, John Wiley and Sons, 1985. 4. Kiat Seng Yeo, Samir R.Rofail, Wang-Ling Gob, CMOS/BiCMOS VLSI-Low Voltage, Low Power, Pearson 2003
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Course Code	18ECE204J	Course Name	ARM-BASED EMBEDDED SYSTEM DESIGN	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECC203J	Co-requisite Courses	Nil	Progressive Courses	18ECE305J, 18ECE306J
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/ Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Explore software development tools of ARM processor	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Acquire knowledge about peripherals for ARM chip such as A/D, PWM	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Obtain exposure towards timers and serial interfacing.				H	-	M	L	-	-	-	-	-	-	-	-	H	-	-
CLR-4 :	Explore effective use of memory; network interfacing, Ethernet and wireless protocol supports				-	-	H	-	-	-	-	-	-	-	-	-	H	-	-
CLR-5 :	Address ARM processor based audio signal processing.				H	-	-	-	-	-	-	-	-	-	-	-	-	H	-
CLR-6 :	Develop ARM Cortex-M based embedded systems for networking and signal processing applications.				L	-	M	H	-	-	-	-	-	-	-	-	-	-	H
					L	-	H	M	-	-	-	-	-	-	-	-	-	H	-
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>																			
CLO-1 :	Relate "mbed" software and C language application for ARM Cortex-M processors.	1	65	60															
CLO-2 :	Develop codes to interface A/D converter, PWM generation and digital input / output.	2	65	60															
CLO-3 :	Experiment with program System timer, serial interface and LCD display.	2	65	60															
CLO-4 :	Summarize the use of memory and program network interface.	2	65	60															
CLO-5 :	Analyze audio signal processing applications on embedded platform.	3	65	60															
CLO-6 :	Identify the use of "mbed" software pack on ARM Cortex-M processor for networking and simple signal processing.	3	65	60															

Duration (hour)		Cortex-M processor 15	Peripheral Interfacing-I 15	Peripheral Interfacing-II 15	Network Interfacing 15	Audio Signal Processing 15
S-1	SLO-1	Introducing embedded systems and mbed	Starting to Program Digital Input and Output	Introducing Synchronous Serial Communication	Memory organization	An Introduction to Digital Audio
	SLO-2	Introducing embedded systems and mbed	Voltages as Logic Values	I2C bus	Memory organization	USB MIDI on the mbed
S-2	SLO-1	ARM Cortex assembly language basics.	Introducing Analog output Data Conversion	Communicating With I2C-Enabled Sensors	Using Data Files With the mbed	Digital Audio Processing
	SLO-2	ARM Cortex assembly language basics.	Digital Output on the mbed	Asynchronous Serial Data Communication	Example mbed Data File Access	Digital Audio Filtering Example
S 3-4	SLO-1	Lab-1: Assembly language program, simulation -1	Lab 4: A/D conversion program	Lab 8: Multinode I2C Bus	Lab 10: Data logging	Lab 13: Audio signal generation
	SLO-2					
S-5	SLO-1	Cortex-M processor architecture and Basics : Programming exercises	Digital Input and Output.	LCD interfacing	Using External SD Card Memory With the mbed	Delay/Echo Effect
	SLO-2	Cortex-M processor architecture and Basics : Programming exercises	Digital Input and Output.	Using the mbed TextLCD Library	Using External USB Flash Memory With the mbed	Working With Wave Audio Files
S-6	SLO-1	Development Environment using the mbed	Switching Larger DC Loads	Time and Tasks in Embedded Systems	Introduction to Internet Communication	High-Fidelity Digital Audio With the mbed
	SLO-2	Development Environment using the mbed	Switching Larger DC Loads	Responding to External Events	The Ethernet Communication Protocol	High-Fidelity Digital Audio With the mbed
S 7-8	SLO-1	Lab 2: Assembly language program, simulation-2	Lab 5: Mini Project: Letter Counter	Lab 8: A/D output on LCD	Lab 11: Ethernet Communication	Lab 14: Model lab examination
	SLO-2					



S-9	SLO-1	Keil IDE and Debugging tools	Another Form of Analog Output: Pulse Width Modulation	An Introduction to Timers	Introducing Wireless Data Communication	Summary on Digital Audio and Digital Signal Processing
	SLO-2	Keil IDE and Debugging tools	Pulse Width Modulation on the mbed	Using the mbed Timer	Wireless Data Communication : Bluetooth and Zigbee	Summary on Digital Audio and Digital Signal Processing
S-10	SLO-1	C- language review	Design of PWM problem	Using the mbed Timeout and Ticker	Local Area Network Communications With the mbed	Review and discussions
	SLO-2	Embedded C , introduction	Design of PWM problem	The Real-Time Clock	Using RPC	Review and discussions
S 11-12	SLO-1	Lab 3: Parallel port programming, simulation	Lab 6: PWM waveform generation	Lab 9: Experimenting Interrupts, Timers	Lab 12: RPC Communication through ethernet	Lab 15: Final lab examination
	SLO-2					

Learning Resources	1. Tim Wilmshurst, "Fast and effective embedded system design, Applying the ARM mbed", ARM Education Media, 2018. 2. Andrew Sloss, Dominic Symes, Chris Wright, "ARM System Designers Guide: Designing and optimizing System Software", The Morgan Kaufmann Series in Computer Architecture and Design, 2004.	3. Theory/Lab teaching materials, "Efficient embedded system design kit", ARM Education media.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, <a href="mailto:kumaranuj.anii@gmail.com">kumaranuj.anii@gmail.com</a>	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, <a href="mailto:meena68@annauniv.edu">meena68@annauniv.edu</a>	1. Mr. Nivash. S, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, <a href="mailto:hariharasudhan.v@jci.com">hariharasudhan.v@jci.com</a>	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, <a href="mailto:venkat@niot.res.in">venkat@niot.res.in</a>	2. Prof. V. Natarajan, SRMIST

Course Code	18ECE205J	Course Name	FPGA-BASED EMBEDDED SYSTEM DESIGN	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECC203J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Explore high volume embedded systems which are function specific	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Relate FPGA knowledge to design circuits	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Select Xilinx FPGA IDE and design practice	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Recall FPGA platforms	Expected Attainment (%)	Design & Development
CLR-5 :	Examine FPGA system design and practical issues		Analysis, Design, Research
CLR-6 :	Develop designs using FPGAs/PSoCs for specific embedded modules and low-power designs		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	List Micro controller subsystems	2	60	65	H	-	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-2 :	Build system design with PSoCs	3	60	65	-	-	H	-	M	-	-	-	-	-	-	-	-	H	-
CLO-3 :	Classify Platform FPGAs	2	60	65	-	-	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-4 :	Make use of FPGA architecture design	3	60	60	-	-	H	-	-	-	-	-	-	-	-	-	-	H	-
CLO-5 :	Utilize Platform FPGA designs	3	60	60	-	-	H	-	M	-	-	-	-	-	-	-	-	H	-
CLO-6 :	Develop simple FPGA based systems	3	60	60	L	-	H	-	M	-	-	-	-	-	-	-	-	H	-

Duration (hour)	Basics of Peripherals	PSoC Design	Xilinx Virtex 5 IDE	Platform FPGA Designs	Designing Simple FPGA based Systems
	15	15	15	15	15
S-1	SLO-1 Embedded systems performance criteria - Interrupts	PSoC3/5 architecture overview	Design challenges, life cycle	Design quality: correctness, reliability, resilience.	Communication: Coprocessor model
	SLO-2 Embedded systems performance criteria - Interrupts	PSoC3 architecture details and 8051 instructions	Metrics: measures of success	Modules and interfaces	Network on chip model
S-2	SLO-1 Embedded systems performance criteria - DMA	Interrupts and interrupt lines	Spectrometer example using Xilinx IDE	Abstraction and state,	Transfer of state
	SLO-2 Latency and its problems	Interrupt priority and nesting	Spectrometer example using Xilinx IDE	Cohesion and coupling and control flow graph	Practical issues: profiling issues
S 3-4	SLO-1 Lab 1: Embedded sensors and sensing -1	Lab 4: PSoC Design -1	Lab 7: VHDL, Verilog Practice session -1	Lab 10: Sample design implementation	Lab 13: On-chip memory access, FIFOs
	SLO-2				
S-5	SLO-1 Embedded system subsystems: A/D conversion	The concept of memory and its connectivity to CPU	Xilinx Virtex 5 IDE	Origin of Platform FPGA Designs	Spatial design: Principles of parallelism
	SLO-2 Digital ports & its current capacity	Different DMA modes	Xilinx Virtex 5 IDE	Platform FPGA components	Granularity, degree of parallelism
S-6	SLO-1 Introduction to other digital interfaces	Clocking system: Internal master oscillator	PLD basics	Adding to platform FPGA systems	Spatial organizations
	SLO-2 Introduction to other digital interfaces	IMO, and sleep/wake up modes	FPGA configurations	Assembling custom compute cores	Spatial organizations
S 7-8	SLO-1 Lab 2: Embedded sensors and sensing - 2	Lab 5: PSoC Design -2	Lab 8: VHDL, Verilog Practice session -2	Lab 11: Building base systems	Lab 14: Model lab examination
	SLO-2				

S-9	SLO-1	Sensors and sensing principles. Optical, capacitive sensors	Clock distribution	Various slices in Virtex 5	Software design :root file system, cross-developmental tools	Managing bandwidth: Balancing
	SLO-2	Magnetic, RF sensors	Power management: Internal regulators	Various slices in Virtex 5	Monitors and boot loaders	Khan process network
S-10	SLO-1	Processing: Mathematical views.	Types of reset	Bit stream	Overview of partitioning platform	Platform FPGA bandwidth techniques
	SLO-2	Programmable logic and mixed signal design fundamentals	Intro to PSoC creator IDE	Programming FPGA	Analytical solution to partitioning	On-chip, off-chip memory
S 11-12	SLO-1	Lab 3: Programmable logic design	Lab 6: PSoC Design - 3	Lab 9: Sample design implementation	Lab 12: Creating IP core	Lab 15: Final lab examination

Learning Resources	1. Robert Ashby, "Designers guide to the Cypress PSoC", Cypress Semiconductors, 2005. 2. Edward H. Currie and David Van Ess, "PSoC3/5 Reference Book", Cypress Semiconductor, 2010.	3. Sass and Schmidt, "Embedded system design with Platform FPGAs", Morgan Kaufmann, 2010. 4. Theory/Lab Session Teaching Materials, ARM Educational Media.
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Learning Assessment											
	Bloom'sLevel of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Prof. V. Natarajan, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2.

Course Code	18ECE207J	Course Name	REAL TIME OPERATING SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18CSS101J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Summarize concepts of C, assembly programming and IDE.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Acquire knowledge of programming, the peripherals.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Outline different RTOS principles				M	-	-	-	-	-	-	-	-	-	-	-	H	-	-		
CLR-4 :	Infer various advanced RTOS principles				-	-	-	H	M	-	-	-	-	-	-	-	H	-	-		
CLR-5 :	Develop sample projects using application programming				-	-	-	H	M	-	-	-	-	-	-	-	H	-	-		
CLR-6 :	Inspect how OS can be implemented on ARM processor.				L	-	-	-	L	-	-	-	-	-	-	-	-	-	H		
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		2	65	60	L	-	-	H	M	-	-	-	-	-	-	-	H	-	-		
CLO-1 :	Recall microprocessor instruction sets and their use.	1	65	60																	
CLO-2 :	Construct codes in assembly and C for embedded applications.	2	65	60																	
CLO-3 :	Illustrate the concepts and requirements of RTOS, in general basic OS principles.	2	65	60																	
CLO-4 :	Analyze the use RTOS in embedded programming	2	65	60																	
CLO-5 :	Apply the knowledge in related sample use cases.	3	65	60																	
CLO-6 :	Develop processor based embedded systems along with RTOS implementation.	2	65	60																	

Duration (hour)		Cortex-M processor & 'C'	Peripheral Programming in 'C'	Concepts of RTOS	RTOS Implementation	RTOS Applications
		15	15	15	15	15
S-1	SLO-1	Cortex-M processor architecture	Parallel I/O programming	Introduction to RTOS	Process management	Real time systems: Data acquisition system
	SLO-2	Cortex-M processor architecture	Sample programs	Introduction to RTOS	Dynamic linking and loading	Real time systems: Data acquisition system
S-2	SLO-1	ARM Cortex assembly language – part1	Interrupt processing basics	Concurrent programming	Spin-lock semaphore, cooperative scheduling	Performance metrics
	SLO-2	ARM Cortex assembly language – part2	System tick; periodic interrupts	Thread fundamentals	Thread rendezvous	Examples and discussions
S 3-4	SLO-1	Lab 1: Arm Assembly language programming	Lab 4: Interrupts and timers in C and assembly	Lab 7: Simple thread programming in RTOS – Wave form simulation	Lab 10: Semaphore implementation experiment in RTOS	Lab 13: Any application program using RTOS.
	SLO-2					
S-5	SLO-1	ARM Cortex microcontroller interface standards	UART programming	Shared resources and Critical sections	FIFO & Little's theorem	Solid state disk
	SLO-2	IDE software tools	UART programming	Consumer producer problem	Three semaphore implementation	Flash device driver
S-6	SLO-1	Pointers in C	Digital signal time measurement	Switching threads	Thread sleeping	SD card interface
	SLO-2	Arrays, structures and unions, Linked lists	Use of timers and compare, capture registers.	Profiling the OS	Deadlocks, monitors	Communication systems with Ethernet
S 7-8	SLO-1	Lab 2: C & assembly programming using Keil IDE and kit	Lab 5: Debugging hardware with target board – UART interface programming	Lab 8: Multi threaded application in RTOS – LED blinking with multi threads	Lab 11: Multi threaded application with Communication -1	Lab 14: Model lab examination
	SLO-2					



S-9	SLO-1	Embedded debugging tools in Keil IDE	SSI interface	Semaphores and implementation	Fixed scheduling	Application layer protocols for embedded systems
	SLO-2	Embedded debugging example with simulation	SSI programming with interrupt	Operations on semaphores	Fixed scheduling	CoAP, MQTT
S-10	SLO-1	Memory management -1	Analog I/O; A/D converter interfacing	Resource sharing	Kahn process networks	Discussions & Reviews
	SLO-2	Memory management -2	OS considerations of I/O devices	Thread Communications	Review	Discussions & Reviews
S-11-12	SLO-1	Lab 3: Practice: C & assembly programming using Keil IDE and kit	Lab 6: Debugging hardware with target board – Analog I/O programming	Lab 9 : Multi threaded application in RTOS, with semaphores	Lab 12: Multi threaded application with Communication -2	Lab 15: Final Lab Examination
	SLO-2					

Learning Resources	1. Jonathan Valvano, "Real time operating systems for ARM Cortex-M Microcontrollers, Embedded systems - Volume 3", ARM Educational Media, 2017. 2. Andrew Sloss et al, "ARM system developers guide", Elsevier, 2004.	3. Quing Li, "Real time techniques for embedded systems", CMP Books, 2003. 4. K.C. Wang, "Embedded and Real time operating systems", Springer, 2017. 5. Theory/Lab Session teaching materials, "RTOS kit", ARM Educational media
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE301J	Course Name	CMOS ANALOG IC DESIGN	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECC206J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Identify Analog IC Design process flow and IC biasing	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Analyze the operation and frequency response of CMOS single stage amplifiers	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Analyze operation and frequency response of the Differential amplifiers and Op-amp				H	H	-	-	H	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Create insights to the concepts of noises in amplifiers				H	H	-	-	H	-	-	-	-	-	-	-	-	-	-
CLR-5 :	Utilize the concepts of oscillators and switched capacitor circuits				H	H	-	-	H	-	-	-	-	-	-	-	-	-	-
CLR-6 :	Use commercial design tools for schematic entry, simulation, and layout				H	-	-	-	H	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		2	60	60	-	H	-	-	-	-	-	-	-	-	-	H	-	-	-
CLO-1 :	Identify IC Biasing concepts	2	60	60	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Analyze Single stage amplifiers	2	60	60	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Analyze Differential Amplifiers and Op-amp	2	60	60	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Identify the noises in Amplifiers	2	60	60	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Identify oscillators and switched capacitors circuits	2	60	60	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Solve practical and state of the art analog IC design problems to serve VLSI industries.	2	60	60	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)		12	12	12	12	12
S-1	SLO-1	IC Design Philosophy : Introduction to MOSFET scaling	CMOS Single stage Amplifiers: Analog Design Octagon	Differential Amplifier: MOS Differential Pair- Operation with Common mode input	Noise in Amplifiers: Statistical characteristics of noise	Oscillators: General Considerations
	SLO-2	Analog IC design process flow, Typical values of IC MOSFET parameters	Common Source stage with resistive load	Operation with differential input	Statistical characteristics of noise-contrn	Ring oscillators
S-2	SLO-1	IC Biasing: MOSFET current source	CS stage with diode connected load	Small signal operation of MOS differential pair- Differential gain	Types of Noises- Thermal Noise, flicker noise	LC oscillators
	SLO-2	Effect of the output resistance of the current source load	CS stage with current source load	Common mode gain, CMRR	Noise Model- MOSFET, Resistor	Cross coupled oscillators
S-3-4	SLO-1	Lab 1: Basic MOS Circuits: MOSFET as a switch & Inverter using HSPICE	Lab 4: Common source amplifier with resistive load and diode connect load	Lab 7: Differential amplifier	Lab 10: Noise analysis and a measure of noise figure in CS, CG and CD amplifier	Lab 13: Switched capacitor circuits
	SLO-2					
S-5	SLO-1	Basic MOSFET current mirror-operation	CS stage with triode load	Differential amplifier with current source load	Representation of noise in circuits	One port oscillators
	SLO-2	Study on the effects which deviates performance of the current mirror	CS stage with source degeneration	Cascode Differential amplifier	Representation of noise in circuits-Contrn	Colpitt oscillator
S-6	SLO-1	Cascode Current mirror	Source Follower	Frequency response of the differential amplifier	Noise Analysis of CS stage	Voltage Controlled oscillators
	SLO-2	Cascode Current mirror- contrn. and problem solving	Common gate stage	Frequency response of the differential amplifier- contrn.	Noise Analysis of CD stage	Voltage Controlled oscillators-contrn

S 7-8	SLO-1	Lab 2: Basic MOS current mirror, Current mirror circuit to overcome the channel length modulation effect	Lab 5: Common gate amplifier and Source follower	Lab 8: One stage op-amp	Lab 11: Ring oscillator	Lab 14: Pre and Post layout simulation of CMOS inverter using Cadence EDA (Virtuoso tool)
	SLO-2					
S-9	SLO-1	Wilson MOS current mirror	Cascode Amplifier	Multistage Amplifiers: Performance parameters of Op-Amp	Noise Analysis of CG stage	Switched Capacitors circuits: Basic principles
	SLO-2	MOS current steering circuits	Folded Cascode amplifier	One stage op-amp	Noise Analysis of Cascode stage	Sampling switches
S-10	SLO-1	Band gap reference circuits	Frequency response of CS amplifier	Two stage op-amp	Noise Analysis of Differential amplifier	Switched capacitor amplifier
	SLO-2	Band gap reference circuits-contrn.	Frequency response of CS amplifier - Contrn	Two stage op-amp with gain boosting	Noise Bandwidth, Noise Figure Concepts	Switched capacitor integrator
S 11-12	SLO-1	Lab 3: Cascode current mirror, Wilson current mirror	Lab 6: Cascode amplifier	Lab 9: Two stage op-amp	Lab 12: Voltage Controlled oscillators	Lab 15: Pre and Post layout simulation of CMOS Amplifier using Cadence EDA (Virtuoso tool)
	SLO-2					

Learning Resources	1. Adel S. Sedra, Kenneth C. Smith, "Microelectronic Circuits-Theory and Applications" – 6 <sup>th</sup> Edition, Oxford University Press, 2011. 2. Behzad Razavi, "Design of Analog CMOS Integrated Circuits", Mc Graw Hill, 2001	3. Allen Holberg, "CMOS Analog Circuit Design", Oxford University Press, 2004 4. Gray, Meyer, Lewis, Hurst, "Analysis and Design of Analog Integrated Circuits", 4 <sup>th</sup> edition, Willey International, 2002.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Mr. Manikandan AVM, SRMIST

Course Code	18ECE302T	Course Name	MEMS TECHNOLOGIES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Identify the characteristics and various technology adopted in MEMS fabrication	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the electrical and mechanical phenomenon used in MEMS design		
CLR-3 :	Analyze how to apply electrostatic and thermal principles in MEMS components design		
CLR-4 :	Study the application of piezoresistive, piezoelectric principle and the design of microfluidic devices		
CLR-5 :	Classify the application of polymer in MEMS application, also to explore the principle and application of optical, and RF MEMS devices		
CLR-6 :	Study the MEMS Packaging and testing methodologies		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Interpret the knowledge of MEMS devices principles and microfabrication techniques	1	60	60	H	-	-	-	-	-	-	-	-	-	-	-	L	-	-
CLO-2 :	Explain the essential concepts of electrical and mechanical applicable to MEMS.	1	60	60	H	-	-	-	-	-	-	-	-	-	-	-	L	-	-
CLO-3 :	Demonstrate the electrostatic and thermal sensing principles and actuating technique.	2	60	60	H	M	L	-	-	-	-	-	-	-	-	-	L	-	H
CLO-4 :	Model MEMS devices using piezoresistive, piezoelectric and magnetic sensing and actuating technique and microfluidic devices	2	60	60	L	H	-	-	-	-	-	-	-	-	-	-	M	-	H
CLO-5 :	Infer the application of polymers material used in MEMS application, also understand the design of optical and RF MEMS components.	2	60	60	L	-	H	-	-	-	-	-	-	-	-	-	M	-	H
CLO-6 :	Predict suitable MEMS packaging and testing methods.	2	60	60	L	M	H										M	-	H

Duration (hour)	Introduction to mems and micro fabrication	Electrical and mechanical concepts of mems	Electrostatic and thermal principle sensing and actuation	Piezoresistive, piezoelectric and magnetic principle sensors and actuator	Polymer, optical, rf mems and its application
	9	9	9	9	9
S-1	SLO-1 History of MEMS Development	Conductivity of semiconductors	Electrostatic sensing - Parallel plate capacitor	Piezoresistive sensors -piezoresistive sensor material	Polymers in MEMS- polyimide,SU-8, Liquid crystal polymer (LCP )
	SLO-2	Problems on conductivity of semiconductors	Problems on electrostatic sensing		
S-2	SLO-1 Characteristics of MEMS – Miniaturization,	Crystal plane and orientation- Single crystal Si (FCC, Miller Indices and notation, crystal planes & characteristics, flats & wafer identification)	Electrostatic actuation Parallel plate capacitor	Stress in flexural cantilever and membrane	Polymers in MEMS- PDMS, PMMA , Parylene, Fluorocarbon
	SLO-2 Microelectronics integration - Mass fabrication with precision		Problems on electrostatic actuation		
S-3	SLO-1 Miniaturization and scaling	Stress and strain - definition , Relationship between tensile stress and strain	Electrostatic sensing and actuation- Application - Inertial, pressure and tactile sensor	Piezoelectric sensing and actuation- piezoelectric material properties	Optical MEMS-passive MEMS optical components-lenses-mirrors
	SLO-2 Sensors and Actuators- Energy domains and example devices for each				
S-4	SLO-1 Micro fabrication process - Bulk and Surface Micromachining	Stress and strain - definition , Relationship between tensile stress and strain	Electrostatic sensing and actuation- Application - parallel plate actuator comb drive	Quartz - PZT-	Actuation for active optical MEMS.
	SLO-2			PVDF -ZnO -Applications	
S-5	SLO-1 Silicon based MEMS processes- processing anisotropic wet etching	Flexural beam bending analysis under single loading condition	Problems on electrostatic sensing and actuation	Magnetic actuation- Principles- Deposition of magnetic materials	RF MEMS: Switches



	SLO-2	Isotropic wet etching				
S-6	SLO-1	Dry etching (plasma etching, ion milling, RIE, DRIE)	Types of beam, longitudinal strain under pure bending	Thermal sensing and Actuators- sensors and actuators based on thermal expansion	Design and fabrication of magnetic coil	RF MEMS - Filters, oscillators
	SLO-2	Photolithography,				
S-7		Thin film deposition -sputtering, evaporation,	Deflection of beam- Spring constant	Thermocouples	Microfluidics – Concepts of fluid mechanics	MEMS Packaging
		Thin film deposition - LPCVD, PECVD	Problems: Deflection of beam- Spring constant	Thermal resistors		
S-8	SLO-1	Thin film deposition - sputtering, evaporation, LPCVD, PECVD	Torsional deflection, intrinsic stress	Application of thermal sensors – Inertial, Flow, Infrared.	Microfluidics –Application: Channels, valves	MEMS Testing
	SLO-2	Thin film deposition - plating, spin-on				
S-9	SLO-1	New material and fabrication processing techniques	Resonance and quality factor	Problems on thermal sensing and actuation	Microfluidics – Application valves	Reliability issues in MEMS packaging
	SLO-2	Points of consideration for processing structural and sacrificial material.				

Learning Resources	1. Chang Liu, "Foundations of MEMS", Second Edition, Pearson , 2017 2. Tai-Ran Hsu, MEMS & Microsystem Design and Manufacturing, McGraw Hill Education (India) 1 <sup>st</sup> Edition , 2015. 3. Gaberiel M. Rebiz, "RF MEMS Theory, Design and Technology", John Wiley & Sons, 2010.	4. Microsystem Design - by S. Senturia; Publisher: Springer. 5. Charles P. Poole and Frank J. Owens, "Introduction to Nanotechnology", John Wiley & Sons, 2009. 6. Julian W.Gardner and Vijay K Varadhan, "Microsensors, MEMS and Smart Devices", John Wiley & sons, 2013. 7. Fundamentals of Microfabrication - by M. Madou; Publisher: CRC Press; 2 edition.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. P. Eswaran, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE303T	Course Name	NANOELECTRONIC DEVICES AND CIRCUITS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC102J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Identify the need and effects of device miniaturization	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the principles of nano devices	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Learn about new devices at nano scale				H	M	-	-	-	-	-	-	-	-	-	-	-	-	M
CLR-4 :	Create insights to the concepts of nano CMOS circuits				H	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-5 :	Analyze the design considerations of the circuits				H	-	-	-	H	-	-	-	-	-	-	-	-	-	H
CLR-6 :	Utilize the design procedure in circuits				H	H	-	-	-	-	-	-	-	-	-	-	-	-	H
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		2	80	70	H	-	-	-	M	-	-	-	-	-	-	-	-	M	
CLO-1 :	Realize the importance of scaling of devices.	2	85	75	H	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-2 :	Identify the difference of nano devices from conventional devices.	2	75	70	H	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-3 :	Analyze the performance measures of various devices	2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	
CLO-4 :	Choose appropriate application of the device	2	85	75	H	-	-	-	M	-	-	-	-	-	-	-	-	-	
CLO-5 :	Understand the design considerations of nano circuits	2	80	70	H	M	-	-	-	-	-	-	-	-	-	-	M	-	M
CLO-6 :	Apply the design concepts of nano circuits in real time applications	2	80	70	H	M	-	-	-	-	-	-	-	-	-	-	M	-	M

Duration (hour)		Introduction to Nano Devices	Silicon MOSFETs- Novel Materials and Alternative Concepts	Nano Devices – Principles and Techniques	Nano- CMOS scaling Problems and Implications	Mixed Signal Circuit Design
		9	9	9	9	9
S-1	SLO-1	MOS transistor- A First Glance at the Device	SOI MOSFET, partially depleted	Classical transport: classical resistance and conductance	Design Methodology in the Nano-CMOS Era	Design Considerations – Device Modeling
	SLO-2	The MOS Transistor under Static Condition	Fully depleted SOI	Quantum ballistic transport: quantum Resistance and conductance	Innovations needed to continue performance scaling -	Passive Components
S-2	SLO-1	MOS Transistor Capacitances- Channel Capacitance	Strained channel MOSFET,	Coulomb blockade effect	Sub-100-nm Scaling Challenges- Back-End-of-Line Challenges (Metallization)-	Design Using Thin Oxide Devices – Design Using Thick Oxide Devices
	SLO-2	Junction Capacitance	Hi-k gate dielectric, Metal gate electrode	Single Electron Transistor	Interconnect scaling-copper wire technology	Low-Voltage Techniques
S-3	SLO-1	The Actual MOS Transistor—Some Secondary Effect	Double gate MOSFET	Performance of the single-electron transistor	Low –k dielectric challenges-future global interconnect technologies	Design Procedures
	SLO-2	Challenges in Nanoscale MOSFETs	FinFET	SET technology and Field effect transistors	Front-End-of-Line Challenges (Transistors)-Quantum effects model	Electrostatic Discharge Protection
S-4	SLO-1	Scaling of transistor dimensions	Tunnel Effect	Carbon Nano Tube(CNT)	Polysilicon gate , Metal gate electrodes,	Multiple-Supply Concerns
	SLO-2	Moore's law	Tunneling through a potential barrier	Electronic properties of CNT	Direct tunneling gate leakage-Parasitic capacitance	Noise Isolation
S 5-6	SLO-1	Short Channel Effects (SCE) : Sub-threshold Conduction,	Potential energy profiles for material interfaces	Geometrical structure, Electronic structure of CNT Transport properties	Reliability concerns	Guard Ring Structures Isolated NMOS Devices
S-7	SLO-1	Drain Induced Barrier Lowering	Metal -insulator, metal -semiconductor	CNTFET, comparison of Si MOSFET with	Process Control Reliability	Epitaxial Material versus Bulk Silicon –

				CNTFET		
	SLO-2	Velocity Saturation, Hot electrons	Metal –insulator -metal junctions	FeFET	Lithographic Issues	Decoupling
S-8	SLO-1	Emergence of new materials,	Tunneling Diode	Principle of Spintronics	Mask Data Explosion	Power Busing
	SLO-2	Hi-k materials and its issues	Resonant Tunneling diode	Spin valves, SpinFET	New Breed of Circuit	Integration Problems
S-9	SLO-1	Metal gate, copper interconnect and	Three-terminal resonant tunneling devices	Magnetic Tunnel Junctions	Physical Design – Modeling Challenges	Corner Regions
	SLO-2	Low-k interlayer dielectric	Inverter and logic OR gates based on RTD	MRAM	Need for Design Methodology Changes	Neighboring Circuitry

Learning Resources	<ol style="list-style-type: none"> <li>1. Rainer Waser (Ed.), "Nanoelectronics and Information Technology", Wiley-VCH, Third, Completely Revised and Enlarged Edition, 2012.</li> <li>2. Jan M. Rabaey, Anantha Chandrakasan, and Borivoje Nikolic, "Digital Integrated Circuits 2<sup>nd</sup> edition", Pearson, 2000.</li> <li>3. Ban P. Wong, Anurag Mittal, YuCao, Gren Starr, "Nano- CMOS Circuit and Physical Design", John Wiley and sons Publication, 2005</li> </ol>	<ol style="list-style-type: none"> <li>4. George W. Hanson, "Fundamentals of Nanoelectronics", Prentice Hall, 20073.Karl Goser, Peter Glösekötter, Jan Dienstuhl, "Nanoelectronics and Nanosystems", Springer, 2004</li> <li>5. Vladimir V. Mitin, Viatcheslav A. Kochelap, Michael A. Stroscio, "Introduction to Nanoelectronics: Science, Nanotechnology, Engineering, and Applications", Cambridge University Press, 2012</li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	40%	-	40%	-	40%	-	40%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	20%	-	20%	-	20%	-	20%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE304T	Course Name	MICROWAVE INTEGRATED CIRCUITS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC105T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Create the insights of microwave circuits	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Analyze matching networks and filter design																							
CLR-3 :	Identify and implement amplifiers and oscillators																							
CLR-4 :	Layout the types of mixers and control circuits																							
CLR-5 :	Understand techniques used to fabricate and measurement of MICs																							
CLR-6 :	Introduce Analyze and realize microwave circuits and its techniques																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understand the different types of MICs, different MIC devices and parameters to be used in MICs	1	60	60																				
CLO-2 :	Determine the concept of frequency parameters, ZY smith chart and its interpretation in the analysis and design of matching circuits	2	60	60																				
CLO-3 :	Explain the design of Amplifiers and Oscillators	1	60	60																				
CLO-4 :	Classify the different Mixer types and Microwave diodes	2	60	60																				
CLO-5 :	Categorize micro fabrication of MIC devices and measurement techniques of MICs	2	60	60																				
CLO-6 :	Apply fabrication and measurement techniques to MIC devices	2	60	60																				
					Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3					
					H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	M				
					L	H	-	M	-	-	-	-	-	-	-	-	-	-	-	M				
					H	-	-	L	-	-	-	-	-	-	-	-	-	-	-	H				
					H	-	-	L	-	-	-	-	-	-	-	-	-	-	-	H				
					H	-	-	M	-	-	-	-	-	-	-	M	-	-	-	M				
					H	-	-	L	-	-	-	-	-	-	-	M	M	-	-	M				

Duration (hour)		Introduction to MIC	Matching Circuits	Microwave Amplifiers and Oscillators	Mixers and Microwave Diodes	MIC Measurement Techniques
		9	9	9	9	9
S-1	SLO-1 SLO-2	Introduction to MICs	Circuit Representation of two port RF/Microwave Networks	Introduction to amplifiers Stability considerations in active networks	Introduction to Mixers	Microwave Integrated Circuits : Introduction to SOC, SOP
S-2	SLO-1 SLO-2	Frequency Bands Lumped versus Distributed Circuits	Low Frequency Parameters High Frequency Parameters	Gain Consideration in Amplifiers	Mixer Types	MIC Materials.
S-3	SLO-1 SLO-2	Behavior of finite length transmission lines	Transmission Matrix	Noise Consideration in active networks	Conversion Loss	Hybrid versus Monolithic MICs
S-4	SLO-1 SLO-2	General Characteristics of PC Boards	ZY Smith Chart	Broadband Amplifier design Low Noise Amplifier Design	SSB Mixers DSB Mixers	Multichip Module Technology
S-5	SLO-1 SLO-2	Transmission Lines on PC Boards	ZY Smith Chart	Introduction to oscillators	Design of Mixers: Single Ended Mixers	Fabrication Techniques
S-6	SLO-1 SLO-2	Passives made from Transmission Lines	Design of Matching Circuits using Lumped Elements	Oscillator versus Amplifier Design	Single Balanced Mixers	Miniaturization techniques
S-7	SLO-1 SLO-2	Resonators	Design of Matching Circuits using Lumped Elements Matching Network Design using Distributed Elements	Oscillation conditions	Sub Harmonic Diode Mixers	Test fixture measurements
S-8	SLO-1 SLO-2	Combiners and Splitters	Matching Network Design using Distributed Elements	Design and stability considerations of Microwave Transistor Oscillators.	Microwave Diodes	Probe station measurements
S-9	SLO-1	Couplers	Filter design	Design and stability considerations of	Phase Shifters and PIN Diode	Thermal and cryogenic



SLO-2			Microwave Transistor Oscillators.	Attenuators	measurements
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Learning Resources	1. Thomas H.Lee, "Planar Microwave Engineering", Cambridge University Press, 2004 2. Matthew M. Radmanesh, "Radio Frequency and Microwave Electronics", Pearson Education, II Edition 2002 3. Guillermo Gonzalez, "Microwave Transistor Amplifiers – Analysis and Design", II Edition, Prentice Hall, New Jersey. 4. Ravender Goyal, "Monolithic MIC; Technology & Design", Artech House, 1989. 5. Gupta K.C. and Amarjit Singh, "Microwave Integrated Circuits", John Wiley, New York, 1975.	6. Hoffman R.K. "Handbook of Microwave Integrated Circuits", Artech House, Boston, 1987. 7. Ulrich L. Rohde and David P.N., "RF / Microwave Circuit Design for Wireless Applications", John Wiley, 2000. 8. C. Gentili, "Microwave Amplifiers and Oscillators", North Oxford Academic, 1986. 9. Samuel. Y. Liao, "Microwave Circuit Analysis and Amplifier Design", Prentice Hall. Inc., 1987.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Dr. T. Ramarao, SRMIST

Course Code	18ECE305J	Course Name	ARM -SOC	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECE204J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire knowledge on hardware architecture of ARM Cortex-M core	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Explore the AHB architecture	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Select AHB peripherals for interfacing				-	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLR-4 :	Experiment with high speed peripherals				-	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLR-5 :	Develop applications with CMSIS				-	L	-	H	M	-	-	-	-	-	-	-	-	H	-
CLR-6 :	Understand and learn to use ARM Cortex-M processor architecture, and device level programming.				-	L	-	H	M	-	-	-	-	-	-	-	H	-	-
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLO-1 :	Explain hardware and register architecture of ARM Cortex-M based processors	1	65	60	-	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-2 :	Classify AHB and its signals	1	65	60	-	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-3 :	Choose and program high speed peripherals	2	65	60	-	-	-	H	M	-	-	-	-	-	-	-	H	-	-
CLO-4 :	Assess high speed peripherals with case study.	3	65	60	-	L	-	H	M	-	-	-	-	-	-	-	-	H	-
CLO-5 :	Interpret program device driver and create libraries.	3	65	60	-	-	-	H	-	-	-	-	-	-	-	-	-	H	-
CLO-6 :	Survey system programming of ARM Cortex-M based processor.	2	65	60	-	L	-	H	M	-	-	-	-	-	-	-	H	-	-

Duration (hour)		ARM Cortex-M architecture	ARM Internal bus	ARM peripherals	SOC programming	Case studies
		12	12	12	12	12
S-1	SLO-1	Introduction to Programmable SoC	AMBA 3 AHB Lite architecture	AHB UART peripheral	Programming an SOC using C	Graphics LCD interfacing
	SLO-2	Introduction to Programmable SoC	AMBA 3 AHB Lite architecture	AHB UART peripheral	language Programming an SOC using C language	Graphics LCD interfacing
S-2	SLO-1	ARM architecture	AMBA 3 AHB Lite architecture	AHB UART peripheral	APB Bus	Board support package
	SLO-2	ARM architecture	AMBA 3 AHB Lite architecture	AHB UART peripheral	APB Bus	Board support package
S 3-4	SLO-1	Lab-1:ARM Keil IDE usage – sample ARM program.	Lab 4: Study of AHB peripheral	Lab 7: Multinode I2C Bus	Lab 10: Making a device driver	Lab 13: Case study – 2
	SLO-2					
S-5	SLO-1	ARM Register architecture	AHB SRAM controller	AHB timer	ARM CMSIS	Ethernet interfacing
	SLO-2	ARM Register architecture	AHB SRAM controller	AHB timer	ARM CMSIS	Ethernet interfacing
S-6	SLO-1	ARM assembly language	AHB SRAM controller	AHB-APB bridge	Device drivers	Ethernet interfacing
	SLO-2	ARM assembly language	Review and discussions	AHB-APB bridge	Device drivers	Ethernet interfacing
S 7-8	SLO-1	Lab 2: Assembly language programming of ARM processor using Keil IDE	Lab 5: ARM memory management	Lab 8: Application of timers	Lab 11: Using CMSIS	Lab 14: Model lab examination
	SLO-2					
S-9	SLO-1	ARM Cortex-M Architecture -1	AHB VGA peripheral	Fast GPIO programming	Application programming	Student Seminar / discussions
	SLO-2	ARM Cortex-M Architecture -1	AHB VGA peripheral	Fast GPIO programming	Application programming	Student Seminar / discussions
S-10	SLO-1	ARM Cortex-M Architecture -2 (pipelines)	AHB VGA peripheral	Interrupt mechanism of ARM	Case study - 1	Student Seminar / discussions
	SLO-2	ARM Cortex-M Architecture -2	AHB VGA peripheral	Interrupt mechanism of ARM	Case study - 2	Student Seminar / discussions
S 11-12	SLO-1	Lab 3: Parallel port programming	Lab 6: Graphics application	Lab 9: Experimenting Interrupts, Timers	Lab 12: Study of USB interface	Lab 15: Final lab examination
	SLO-2					

Learning Resources	1. Steve Furber, "ARM System on a Chip Architecture – 2 <sup>nd</sup> Edition", Pearson Education, 2000.	4. "AMBA -3 AHB Lite Protocol", ARM Limited, 2003.
	2. "AMBA -3 APB Protocol", ARM Limited, 2003.	5. Theory/Lab teaching materials, "Introduction to SoC kit", ARM Education media, 2018.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2.

Course Code	18ECE306J	Course Name	ARM BASED DIGITAL SIGNAL PROCESSING	Course Category	E	Professional Elective				L	T	P	C
										2	0	2	3

Pre-requisite Courses	18ECE204J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Explore the concepts of DSP, discrete time signals and its properties.			
CLR-2 :	Apply transforms in solving digital signal processing			
CLR-3 :	Develop FIR filters for various applications			
CLR-4 :	Make use of IIT filters for various applications			
CLR-5 :	Experiment with adaptive filter techniques			
CLR-6 :	Test for DSP in embedded ARM Cortex-M processor platform			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Recall theory and application of discrete time signals			
CLO-2 :	Solve problems using Z-transforms, DFT and FFT.			
CLO-3 :	Analyze FiR filter concepts and implement in C.			
CLO-4 :	Inspect IIR filter concepts and implement in C			
CLO-5 :	Appraise adaptive filter design theory, methods and its uses.			
CLO-6 :	Apply the theory and implementation aspects of DSP in ARM Cortex-M based processor platform.			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
	H											H		
	H			M								H		
	L		H	M									H	
	L		H	M									H	
	M		H	L										H
			H	M								H		

Duration (hour)		Basics of digital signals 12	Transforms for DSP 12	FIR filters 12	IIR filters 12	DSP applications 12
S-1	SLO-1	DT Signals-basics properties & Operations on DT signals	Z-Transform Properties	Design of Finite Impulse Response Filters-Symmetric and Antisymmetric FIR filters	Frequency Response and Characteristics of Analog Filters	Introduction-Steepest Descent Method-Least Mean Squares Method
	SLO-2	DT Signals-basics properties & Operations on DT signals	Z-Transform Properties	Design of Finite Impulse Response Filters-Symmetric and Antisymmetric FIR filters	Frequency Response and Characteristics of Analog Filters	Introduction-Steepest Descent Method-Least Mean Squares Method
S-2	SLO-1	DT systems-Properties of DT Systems – LTI system	Inverse Z-Transform-solving Difference Equation	Design of Linear- Phase FIR filters Using window methods	IIR Filter Design by Impulse Invariance	Adaptive Filters: Prediction and System Identification
	SLO-2	DT systems-Properties of DT Systems – LTI system	Inverse Z-Transform-solving Difference Equation	Design of Linear- Phase FIR filters Using window methods	IIR Filter Design by Impulse Invariance	Adaptive Filters: Prediction and System Identification
S 3-4	SLO-1	Lab 1: Introduction- Keil MDK-ARM application development Environment.	Lab 4: LTI System Implementation	Lab 7: Filter Structures in the CMSIS-DSP Library	Lab 10: IIR Filter Structures in the CMSIS-DSP Library	Lab 13: CMSIS Implementation of the LMS and Normalized LMS methods
	SLO-2					
S-5	SLO-1	Convolution and Correlation	DFT-review; problems	Design of Linear- Phase FIR filters Using window methods	Design of Butterworth filter using Bilinear Transformation	Adaptive Filters: Equalization and Noise Cancellation
	SLO-2	Convolution and Correlation	DFT-review; problems	Design of Linear- Phase FIR filters Using window methods	Design of Butterworth filter using Bilinear Transformation	Adaptive Filters: Equalization and Noise Cancellation
S-6	SLO-1	CT-to DT Conversion Sampling Theorem in the Time Domain	DIT-FFT Radix 2 butterfly derivation - problems	Design of Optimum Equiripple Linear-Phase FIR filters	Chebyshev Filter Designs based on the Bilinear Transformation	Adaptive Filters: Adaptive FIR Filter
	SLO-2	CT-to DT Conversion Sampling Theorem in the Time Domain	DIT-FFT Radix 2 butterfly derivation - problems	Design of Optimum Equiripple Linear-Phase FIR filters	Chebyshev Filter Designs based on the Bilinear Transformation	Adaptive Filters: Adaptive FIR Filter
S 7-8	SLO-1	Lab 2: Digital Signals-operations on	Lab 5: Calculating the DFT-FFT	Lab 8: FIR Filter Design	Lab 11: IIR Filter Design	Lab 14: Model Practicals



	SLO-2	Digital Signals				
S-9	SLO-1	Sampling Theorem in the Frequency Domain-Aliasing	Filtering in the FD-Circular & Convolution	Design of Optimum Equiripple Linear-Phase FIR filters	Chebyshev Filter Designs based on the Impulse Invariance	Review, Problems and Discussions
	SLO-2	Sampling Theorem in the Frequency Domain-Aliasing	Filtering in the FD-Circular & Convolution	Design of Optimum Equiripple Linear-Phase FIR filters	Chebyshev Filter Designs based on the Impulse Invariance	Review, Problems and Discussions
S-10	SLO-1	Reconstruction in the Frequency Domain & time Domain	Filtering in the FD-Linear Convolution	Filter Design using Software	Filter Design using Software	Review, Problems and Discussions
	SLO-2	Reconstruction in the Frequency Domain & time Domain	Filtering in the FD-Linear Convolution	Filter Design using Software	Filter Design using Software	Review, Problems and Discussions
S	SLO-1	Lab 3: A-D & D-A conversion-Changing the Sampling Frequency	Lab 6: Filtering in the Frequency Domain	Lab 9: Implementing a FIR Filter using Different Structures	Lab 12: Implementing a Filter using Different Structures	Lab 15: University practicals
11-12	SLO-2					

Learning Resources	1. Cem Unsalan, M. Yerkın Yucel, H. Deniz Gurham, "Digital Signal Processing Using ARM Cortex-M based microcontrollers, Theory and Practice", ARM Education Media, 2018.	2. Theory/Lab teaching materials, ARM Educational Media.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Prof. V. Natarajan, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Mr. U. Hari, SRMIST

Course Code	18ECE307J	Course Name	APPLIED MACHINE LEARNING	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	<i>Understanding the Machine Learning concept and types</i>	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	<i>Analyze the ML algorithm performance by Learning Curve and error</i>	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	<i>Applying ML algorithm for solving practical problems</i>				H	-	M	-	-	-	-	-	-	-	-	-	-	-	H
CLR-4 :	<i>Create insights to the concepts and programming of supervised and unsupervised ML methods</i>				H	-	-	H	L	-	-	-	-	-	-	-	-	-	H
CLR-5 :	<i>Analyze and understand the working principle and model development of Evolutionary Learning</i>				H	-	-	M	L	-	-	-	-	-	-	-	M	-	H
CLR-6 :	<i>Create insights to the concepts and programming of Reinforcement learning</i>				H	-	-	M	L	-	-	-	-	-	-	-	M	-	H
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		2	60	60	H	-	-	M	L	-	-	-	-	-	-	-	M	-	H
CLO-1 :	<i>Explain Genetic Algorithm for evolutionary learning</i>	2	60	60	H	-	-	M	L	-	-	-	-	-	-	-	M	-	H
CLO-2 :	<i>Use reinforcement learning</i>	2	60	60	H	-	-	M	L	-	-	-	-	-	-	-	M	-	H
CLO-3 :	<i>Apply linear model of linear regression and SVM for classification problem</i>	2	60	60	H	-	-	M	L	-	-	-	-	-	-	-	M	-	H
CLO-4 :	<i>Experiment neural network and CNN for classification problem</i>	2	60	60	H	-	-	M	L	-	-	-	-	-	-	-	M	-	H
CLO-5 :	<i>Demonstrate Decision Trees, clustering For classification problem</i>	2	60	60	H	-	-	M	L	-	-	-	-	-	-	-	M	-	H
CLO-6 :	<i>Analyze probability model of Bayesian decision theory and HMM for classification problem</i>	2	60	60	H	-	-	M	L	-	-	-	-	-	-	-	M	-	H

Duration (hour)		Introduction to Machine Learning and Linear Model	Multiplayer Perceptrons and Decision Tree	Clustering, SOM and HMM	Bayes Network, Reinforcement Learning and CNN	Genetic Algorithm and Application of ML
		12	12	12	12	12
S-1	SLO-1	<i>Introduction to Machine learning: Types of Machine Learning - Supervised Learning – Unsupervised, Learning</i>	<i>Multiplayer, Perceptrons</i>	<i>Clustering</i>	<i>Bayesian decision theory</i>	<i>The Genetic Algorithm</i>
	SLO-2	<i>Reinforcement learning, The Curse of dimensionality</i>	<i>Multiplayer, Perceptrons</i>	<i>K-Means clustering</i>	<i>Bayesian decision theory</i>	<i>The Genetic Algorithm</i>
S-2	SLO-1	<i>Bias and Variance, Learning Curve</i>	<i>Multiplayer, Perceptrons</i>	<i>Hierarchical clustering</i>	<i>Bayesian estimation</i>	<i>Facial Expression Recognition</i>
	SLO-2	<i>Classification, Error and noise, linear regression</i>	<i>Multiplayer, Perceptrons</i>	<i>Agglomerative clustering</i>	<i>Bayes network</i>	<i>Human Emotion Research</i>
S-3,4	SLO-1	<i>Lab 1: Linear Regression</i>	<i>Lab 4: Multiplayer, Perceptrons</i>	<i>Lab 7: K-Means clustering</i>	<i>Lab 10: Bayes Network</i>	<i>Lab 13: Genetic Algorithm</i>
	SLO-2	<i>Support Vector Machines</i>	<i>Example of using MLP</i>	<i>Vector Quantization</i>	<i>Reinforcement learning</i>	<i>Facial Expression Recognition System</i>
S-5	SLO-1	<i>Support Vector Machines</i>	<i>Example of using MLP</i>	<i>Vector Quantization</i>	<i>Reinforcement learning</i>	<i>Facial Expression Recognition System</i>
	SLO-2	<i>Support Vector Machines</i>	<i>Example of using MLP</i>	<i>The Self-Organizing Feature Map</i>	<i>Reinforcement learning</i>	<i>Speech Emotion Recognition</i>
S-6	SLO-1	<i>Support Vector Machines</i>	<i>Example of using MLP</i>	<i>The Self-Organizing Feature Map</i>	<i>Reinforcement learning</i>	<i>Speech Emotion Recognition</i>
	SLO-2	<i>Support Vector Machines</i>	<i>Example of using MLP</i>	<i>The Self-Organizing Feature Map</i>	<i>Reinforcement learning</i>	<i>Speech Emotion Recognition</i>
S-7,8	SLO-1	<i>Lab 2: Support Vector Machines</i>	<i>Lab 5: MLP application</i>	<i>Lab 8: SOFM</i>	<i>Lab 11: Reinforcement learning</i>	<i>Lab 14: Speech Emotion Recognition Basic classification</i>
	SLO-2	<i>Basics of neural network</i>	<i>Decision Trees- classification</i>	<i>HMM</i>	<i>Understanding Convolutions</i>	<i>Neural Network Multi-Layer Perceptron Modeling For Surface Quality Prediction in Laser Machining</i>
S-9	SLO-1	<i>Perceptrons</i>	<i>Regression tree,</i>	<i>HMM</i>	<i>Understanding Convolutions</i>	<i>Neural Network Multi-Layer Perceptron Modeling For Surface Quality Prediction in Laser Machining</i>
	SLO-2	<i>Perceptrons</i>	<i>Regression tree,</i>	<i>HMM</i>	<i>Understanding Convolutions</i>	<i>Neural Network Multi-Layer Perceptron Modeling For Surface Quality Prediction in Laser Machining</i>

S-10	SLO-1	LINEAR SEPARABILITY	Pruning, rule from tree and data	HMM	CNN Building Blocks	Machine Learning in Cybersecurity- Supervised Learning for Misuse/Signature Detection
	SLO-2	Perceptrons and introduction to Multiplayer, Perceptrons	Multivariate tree	HMM	CNN Building Blocks	Machine Learning in Cybersecurity- Supervised Learning for Misuse/Signature Detection
S-11,12	SLO-1	Lab 3: Perceptrons	Lab 6: Decision Trees	Lab 9: HMM	Lab 12: CNN	Lab 15: Mini project
	SLO-2					

Learning Resources	1. Ethem Alpaydin, "Introduction to Machine Learning", 3 <sup>rd</sup> edition, MIT Press, 2014.	5. Yagang Zhang, "Application of Machine Learning", Published by In-Tech, 2010.
	2. Stephen Marsland, "Machine Learning –An Algorithmic Perspective", 2 <sup>nd</sup> edition, CRC Press, 2015.	6. Starter Bundle, "Deep Learning: A Practitioner's Approach", O'Reilly Media, 2017.
	3. Sumeet Dua and Xian Du, "Data Mining and Machine Learning in Cybersecurity", CRC Press, 2011.	7. Dr. Adrian Rosebrock, "Deep Learning for Computer Vision with Python", Packt Publisher, 2018.
	4. Aurélien Géron Hands-On Machine Learning with Scikit-Learn and TensorFlow: Concepts, Tools, and Techniques to Build Intelligent Systems. O'Reilly Media, 2017.	8. Ankur A Patel, "Hands-On Unsupervised Learning Using Python: How to Build Applied Machine Learning Solutions from Unlabeled Data", O'Reilly media, 2019.

Learning Assessment"											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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		Internal Experts
		1. Dr. P. Vijayakumar, SRMIST

Course Code	18ECE220T	Course Name	ADVANCED MOBILE COMMUNICATION SYSTEMS	Course Category	E	Professional Elective				L	T	P	C
										3	0	0	3

Pre-requisite Courses	18ECC301T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Gain knowledge about the latest Standards from 3G to 5G systems.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Introduce the concepts of OFDM systems and standards.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Study the basics of MIMO system and the impact of different channel models on it.				H	-	M	M	-	-	-	-	-	-	-	-	H	-	M
CLR-4 :	Understand the techniques of cognitive radio spectrum sensing and sharing				M	-	H	M	-	-	-	-	-	-	-	-	M	-	H
CLR-5 :	Study the techniques of Millimeter wave communication				H	-	M	H	-	-	-	-	-	-	-	-	M	-	H
CLR-6 :	Apply the knowledge gained to various Advanced Mobile Communication Systems				M	-	M	H	-	-	-	-	-	-	-	-	M	-	H
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>																	M		H
CLO-1 :	Apply the architecture and functionalities of 3G and 4G systems	2,3	85	80															
CLO-2 :	Understand the concepts of OFDM and it issues	2,3	80	85															
CLO-3 :	Understand the MIMO communication systems	2,3	85	80															
CLO-4 :	Understand the principle of Cognitive Radio Techniques	2,3	80	75															
CLO-5 :	Acquire the concept of millimeter wave communication	2,3	85	80															
CLO-6 :	Able to analyze the Advance Mobile communication systems																		

Duration (hour)		Advanced cellular mobile Communication systems	Multicarrier modulation technique-OFDM	MIMO systems	Cognitive Spectrum management	Millimeter wave Communication
		9	9	9	9	9
S-1	SLO-1	Overview of the legacy 3GPP cellular systems	Introduction to OFDM	Introduction to MIMO	Cognitive transceiver Introduction	Millimeter Wave Characteristics
	SLO-2	Overview of the legacy 3GPP cellular systems	Multicarrier Modulation Introduction	Introduction to MIMO Channel Capacity	Cognitive transceiver architecture	Introduction to Channel Performance at Mm wave Communication
S-2	SLO-1	WiMAX systems: Introduction	Multicarrier Modulation	MIMO Channel Estimation	Interweaving	Channel Performance at Mm wave Communication
	SLO-2	WiMAX systems: Architecture	Cyclic Prefix	MIMO Channel Estimation	Principle of interweaving	Modulation for Millimeter Wave Communication
S-3	SLO-1	WiMAX systems: Architecture	Channel model	MIMO Spatial Multiplexing	Principle of interweaving	Modulation for Millimeter Wave Communication
	SLO-2	WiMAX systems : Frame structure	SNR	MIMO Spatial Multiplexing	Introduction to Spectrums	Millimeter wave transmitter
S-4	SLO-1	WiMAX systems : Frame structure	SNR Performance	V- BLAST 2	Types of Spectrum	Millimeter wave Receiver
	SLO-2	WiMAX systems : Applications	SNR Problems	V- BLAST 2	Spectrum sensing	Millimeter wave Antenna
S-5-6	SLO-1	LTE systems: Introduction	OFDM Introduction	MIMO Diversity	Advantages of Spectrum sensing	Introduction Mm wave Communications
	SLO-2					
S-7	SLO-1	LTE systems: Architecture	OFDM Issues	MIMO Diversity	Disadvantages of Spectrum sensing	Emerging applications of Mm wave Communications
	SLO-2	LTE systems: Architecture	OFDM Issues	Alamouti	Disadvantages of Spectrum sensing	Emerging applications of Mm wave



						Communications
S-8	SLO-1	LTE systems: Frame structure	PAPR	Alamouti	Spectrum Management	Millimeter Wave Standards.
	SLO-2	LTE systems: Frame structure	Frequency and timing	OSTBC	Spectrum Management	Introduction to Millimeter Wave Standards.
S-9	SLO-1	LTE systems: applications	Frequency offset issues.	MIMO :OFDM system Introduction	Spectrum Management	Development of Millimeter Wave Standards.
	SLO-2	LTE systems: applications	Timing offset issues.	MIMO :OFDM system	Spectrum Management	Development of Millimeter Wave Standards.

Learning Resources	<ol style="list-style-type: none"> <li>1. Andrea Molisch, "Wireless Communication", Cambridge University Press, 2<sup>nd</sup> edition, 2013.</li> <li>2. Theodore Rappaport, "Wireless Communication: Principle and Practice", Prentice Hall, 2<sup>nd</sup> edition, 2014.</li> <li>3. Kao-Cheng Huang, Zhaocheng Wang, "Millimeter Wave Communication System", Wiley-IEEE Press, 2<sup>nd</sup> edition, 2011.</li> <li>4. Ezio Biglieri, "MIMO Wireless Communications", Cambridge University Press, 1<sup>st</sup> edition, 2007.</li> <li>5. Arslan, Hüseyin, ed. Cognitive radio, software defined radio, and adaptive wireless systems. Springer Science &amp; Business Media, 2007.(263-284)</li> <li>6. Thomas W.Rondeau, Charles W. Bostain, "Artificial Intelligence in Wireless Communication", ARTECH HOUSE .2009 {pp1-51}</li> <li>7. Andrew Goldsmith, Wireless Communications, Cambridge University Press, 2005.</li> <li>8. Mischa Dohler, Jose F. Monserrat Afif Osseiran " 5G Mobile and Wireless Communication Technology", Cambridge University Press 2016.</li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Code	18ECE221T	Course Name	RADAR AND NAVIGATIONAL AIDS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC205J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	<i>Get introduced to basics of Radar System</i>	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	<i>Impart the knowledge of different types of Radar</i>	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	<i>Analyze the various detection schemes</i>				H	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	<i>Understand the Radar transmitters and Receivers</i>				-	-	-	-	-	-	-	-	-	H	-	-	M	-	-
CLR-5 :	<i>Understand the fundamentals of navigation system</i>				H	H	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-6 :	<i>Acquire knowledge on theoretical concepts and analysis techniques related to different types of Radar and various navigational aids</i>				H	M	-	-	-	-	-	-	-	M	-	-	M	-	-
					H	H	-	-	-	-	-	-	-	H	-	-	-	-	H
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>																			
CLO-1 :	<i>Gain knowledge about Radar theory and Range equation</i>	2	80	70															
CLO-2 :	<i>Apply Doppler principle to Radars and hence understand the working principle of different types of Radar</i>	2	85	75															
CLO-3 :	<i>Gain knowledge on Radar signal detection methods and propagation as related to Radars</i>	2	75	70															
CLO-4 :	<i>Acquire information about Radar transmitters and Radars</i>	2	85	80															
CLO-5 :	<i>Understand principles of navigation , in addition to approach and landing aids as related to navigation</i>	2	85	75															
CLO-6 :	<i>Understand the principle of operation of Radar in the detection of different types of targets and various navigational aids</i>	2	85	75															

Duration (hour)		Introduction To Radar Equation 9	MTI And Pulse Doppler Radar 9	Detection Of Signals In Noise 9	Radar Transmitter And Receiver 9	Radio Navigation 9
S-1	SLO-1	Introduction-Basic Radar	Introduction to Doppler Radar	Detection of Signals in Noise -Detection Criteria	Radar Transmitters and Receivers.	Introduction - Four methods of Navigation .- Positioning- Errors in Direction Finding
	SLO-2	Radar Frequencies -Applications of Radar	Introduction to MTI Radar	Probabilities of Detection and False Alarm	Linear Beam Power Tubes-Reflex Klystron	Line of sight Distance measurement
S-2	SLO-1	The Simple form of Radar Equation	Delay –Line Cancellers	Matched Filter Receiver	Linear Beam Power Tubes-TWT	Terrestrial Radio Navigation systems
	SLO-2	Tutorials	Delay –Line Cancellers	Derivation of Matched filter frequency response	Solid State RF Power Sources	Radio transmission and Reception
S-3	SLO-1	Radar Block Diagram	Doppler Filter Banks	Automatic Detector	Magnetron - Crossed Field Amplifiers	System design considerations-System Performance Parameters
	SLO-2	Receiver Noise	Digital MTI Processing	Constant-False-Alarm Rate Receivers	Magnetron - Crossed Field Amplifiers	The Loop Antenna - Adcock Direction Finders
S-4	SLO-1	Signal-to-Noise Ratio	Block Diagram of Digital MTI Doppler Signal Processor	Signal Management	Other RF Power Sources	Direction Finding at Very High Frequencies - Automatic Direction Finders
	SLO-2	Integration of Radar Pulses	Moving Target Detector - Limitations to MTI Performance	Propagation Radar Waves- Atmospheric Refraction	Other aspects of Radar Transmitter	VHF Omni Directional Range(VOR) - VOR Receiving Equipment - Range and Accuracy of VOR
S-5	SLO-1	Radar Cross Section of Targets-Simple Targets	Pulse Doppler Radar	Standard propagation	The Radar Receiver	Hyperbolic Systems of Navigation-Loran
	SLO-2	Radar Cross Section of Targets-Complex Targets Transmitter Power	High, Medium and Low prf Doppler	Nonstandard Propagation	Receiver noise Figure	Loran-C

S-6	SLO-1	Radar cross Section Fluctuations	Other Doppler Radar Topics	Ambiguity Diagram	Receiver noise Figure	The Decca Navigation System -Decca Receivers
	SLO-2	Swerling Target Model	Tracking with Radar	Ambiguity Diagram	Super heterodyne Receiver	Range and Accuracy of Decca
S-7	SLO-1	Transmitter Power	Mono pulse Tracking	Pulse compression	LNA and Mixers	TACAN
	SLO-2	Pulse Repetition Frequency	Two Coordinate amplitude comparison monopulse tracking	Linear FM pulse compression	Duplexers	TACAN Equipment
S-8	SLO-1	Antenna Parameters	Conical Scan and Sequential Lobing	Binary Phase Coded pulse compression	Receiver Protectors	Case study on Airborne Tactical networks-Instrument Landing System
	SLO-2	System losses-Microwave plumbing loss, Antenna loss, Signal Processing loss	Limitations to Tracking Accuracy	Questionnaire	Receiver Protectors	Case study on Airborne Tactical networks-Instrument Landing System
S-9	SLO-1	System losses-Doppler processing, Collapsing, Operator loss, propagation Effects	Case study on weather radars	Introduction to clutter	Radar Displays	Introduction to satellite Radio Navigation-
	SLO-2	Other Radar Equation Considerations	Case study on weather radars	Surface Clutter Radar equation	Surprise Test	Navstar Global Positioning System (GPS)

Learning Resources	1. Merrill I. Skolnik, "Introduction to Radar Systems", 3rd Edition Tata Mc Graw-Hill 2008	5. Mark, Richards.A, "Fundamentals of radar signal processing", Mc-Graw Hill, Electronic Engineering, 1st Edition, 2005.
	2. R.B. Underdown and David Cockburn, "Ground Studies for Pilots: Radio Aids", sixth Edition, Blackwell Publishing, 2011.	6. Jenny L. Reed, Aaron D. Lanterman, John M. Trostel, "Tutorial: Weather Radar: Operation and Phenomenology", IEEE Aerospace and Electronic Systems Magazine, Vol: 32, 7, 2017.
	3. Myron Kayton, Walter R.Fried, "Avionics Navigation Systems", second Edition, Wiley- India Edition, 2010.	7. Bow-Nan Cheng, Frederick J. Block, B. Russ Hamilton, David Ripplinger, Chayil Timmerman, Leonid Veytser, and Aradhana Narula-Tam, "Design Considerations for Next-Generation Airborne Tactical Networks, IEEE Communications Magazine , May 2014.
	4. N.S.Nagaraja, "Elements of Electronic Navigation Systems", 2nd Edition, TMH, 2000.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com		1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in
		Internal Experts
		1. Mrs. S. Vasanthadev Suryakala, SRMIST

Course Code	18ECE222T	Course Name	ADHOC AND SENSOR NETWORKS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Utilize the Ad hoc Networks and its various routing protocols	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn the MAC Layer and the concept of Quality of Service	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Analyze energy management in Ad hoc Networks				-	-	-	-	-	-	H	-	-	-	-	M	-	-	-
CLR-4 :	Identify insights of Sensor network				-	-	-	H	-	-	-	H	-	-	-	-	-	-	M
CLR-5 :	Analyze various aspects Hybrid networks and routing configuration				-	-	-	H	-	-	-	-	-	-	-	-	-	-	M
CLR-6 :	Expose to the different types of adhoc network routing protocols and sensor networks				-	-	-	H	-	-	-	-	-	-	-	-	-	-	M
					-	-	-	-	-	-	-	-	-	-	-	H	-	-	M
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		1	60	70	1	60	65	1	60	65	1	60	65	1	60	65	1	60	65
CLO-1 :	Express about Ad hoc Networks and various routing protocols used in Ad hoc networks	1	60	70	1	60	65	1	60	65	1	60	65	1	60	65	1	60	65
CLO-2 :	Discuss the various functional areas such as MAC Layer and QOS	1	60	65	1	60	65	1	60	65	1	60	65	1	60	65	1	60	65
CLO-3 :	Interpret the energy management protocols in Ad hoc Networks	1	60	65	1	60	65	1	60	65	1	60	65	1	60	65	1	60	65
CLO-4 :	Explain about the Sensor network and its associated protocols.	1	60	65	1	60	65	1	60	65	1	60	65	1	60	65	1	60	65
CLO-5 :	Describe about the hybrid networks and its routing protocols.	1	60	65	1	60	65	1	60	65	1	60	65	1	60	65	1	60	65
CLO-6 :	Paraphrase the various types of adhoc networks and sensor networks	1	60	65	1	60	65	1	60	65	1	60	65	1	60	65	1	60	65

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Cellular and Ad hoc Wireless Networks	Quality of service in Ad hoc wireless networks, Real-Time Traffic support	Energy Management-Needs	Sensor Networks, Applications. Comparison with Ad hoc network,	Hybrid wireless network, Introduction, classification
	SLO-2	Applications of Ad hoc Wireless Networks	Issues and challenges in providing QoS	Classifications of Energy Management Schemes	Issues, challenges in designing sensor network Sensor Network Architecture	Multi-hop cellular network (MCN) Architecture
S-2	SLO-1	Issues in Ad hoc Wireless Networks	Classifications of QoS solutions	Battery Management Scheme-Overview,	Layered Architecture, Clustered Architecture	Mobile assisted data forwarding (MADF) Architecture
	SLO-2	MAC Protocol for Ad hoc Networks Issues in Designing and Design Goals	MAC Layer solution-cluster TDMA, IEEE 802.11e, DBASE	Data link layer solution-Lazy packet scheduling scheme,	Data Dissemination, Flooding, Gossiping, Rumor Routing, Sequential Assignment Routing	Hybrid wireless Network (HWN) Architecture
S-3	SLO-1	Classifications of MAC protocols-Floor Acquisition Multiple Access protocols	Network Layer solution-QOS routing protocols,	Battery Aware MAC protocol	Cost field approach	Routing in Hybrid wireless network Base assisted ad hoc routing (BAAR)
	SLO-2	Collision Avoidance Time Allocated Protocol	Ticket Based QOS Routing protocols,	Network Layer solution	Data Gathering, Direct Transmission, Binary scheme	Operation of BAAR protocol
S-4	SLO-1	Routing Protocol for Ad hoc wireless network-Classification	Predictive location based QOS routing	Transmission Power Management Schemes-Data link layer solution	Chain Based Three level scheme	Base driven multi-hop bridging protocol(BMBP)-Message used
	SLO-2	Table driven Routing Protocols-Wireless Routing Protocol	QOS frame work	Dynamic power adjustments policies, Distribute topology control Algorithm	MAC protocols for sensor Networks-Self organizing MAC, CSMA Based MAC	BMBP procedure
S-5	SLO-1	On demand routing protocols-Dynamic Source Routing protocol	QOS models	Construct distributed power control loop, Centralized Topology control Algorithm	Location discovery-Indoor and sensor network localization	Issues in pricing Multi-Hop wireless networks
	SLO-2	Multicast Routing Architecture Reference	QOS Resource Reservation Signaling	Network layer solution-common power	Quality of Sensor Networks-coverage,	Pricing in Multi-Hop wireless WANs



		model		protocol		
S-6	SLO-1	Tree Based Routing	INSIGNIA-QOS framework	Minimum power consumption Technique	Exposure	Pricing in Ad hoc Wireless Networks
	SLO-2	Mesh Based Routing	Operation of INSIGNIA framework, Advantages and disadvantages	Minimum battery cost Routing	Recent Trends in Sensor Networks- Energy Efficient Design, synchronization	Power control scheme in Hybrid Wireless Networks, Issues in using variable power in IEEE 802.11
S-7	SLO-1	Energy Efficient Multicasting-Routing protocols	INORA-Coarse feedback scheme,	Higher Layer solution	Transport Layer Issue	Power optimization scheme
	SLO-2	Cluster Adaptation of Multicast protocols	Class based fine feedback scheme	System power management scheme, Processor power management	Security-Localized Encryption and Authentication protocols (LEAP)	Load Balancing in Hybrid Wireless Networks
S-8	SLO-1	Multicast with QOS Guarantees-Real Time Multicasting Protocols	SWAN-Model	Power saving Mode Power Aware Multi-Access Signaling	Intrusion Tolerant Routing in Wireless Sensor Network (INSENS)	Preferred Ring Based Routing Scheme
	SLO-2	Priority Scheduling Protocols	Advantages and Disadvantages	Addition of separate signaling scheme	Real – Time communication	Preferred inner Routing Scheme(PIRS)
S-9	SLO-1	Application Dependent Multi Cast Routing-Role Based,	Proactive RTMAC framework	Device power Management Scheme-Low Power Design of Hardware	SPEED Protocol	Preferred outer Ring Routing Scheme (PORS)
	SLO-2	Content Based, Location Based	Advantages and Disadvantages	Hard Disk Drive (HDD) power consumption	RAP protocols	Preferred Destination/Source Ring Based Routing Scheme

Learning Resources	1. Siva Ram Murthy C., Manoj B.S, Ad hoc Wireless Networks – Architectures and Protocols, 2 <sup>nd</sup> ed., Pearson, 2004	3. C.K.To, Ad hoc Mobile Wireless Networks, 7 <sup>th</sup> ed., Pearson, 2002 4. Thomas Brag, Sebastin Buettlich, Wireless Mesh Networking, 3 <sup>rd</sup> ed., O'Reilly Publishers, 2007
	2. Feng Zhao, LeonidasGuibas,Wireless Sensor Networks, 1 <sup>st</sup> ed., Morgan Kaufman Publishers, 2004	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE223T	Course Name	SATELLITE COMMUNICATION AND BROADCASTING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC205J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the orbital and functional principles of satellite communication systems				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Architect, interpret, and select appropriate technologies for implementation of specified satellite communication systems																							
CLR-3 :	Analyze and evaluate a satellite link and suggest enhancements to improve the link performance																							
CLR-4 :	Select an appropriate modulation, multiplexing, coding and multiple access schemes for a given satellite communication link																							
CLR-5 :	Specify, design, prototype and test analog and digital satellite communication systems as per given specifications																							
CLR-6 :	Utilize the concepts in optical communication for the understanding of engineering and technology																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Expected Proficiency (%)	Expected Attainment (%)																		
CLO-1 :	Demonstrate the principles, concepts and operation of satellite communication systems				2	60	65	M	-	-	-	-	-	-	H	-	-	-	-	-	-	-	-	-
CLO-2 :	Discuss about the satellite orbits, link design, link availability and interference				2	60	65	-	-	M	-	-	-	H	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Analyze the concepts of Satellite systems in relation to other terrestrial systems				2	65	65	-	-	M	-	-	-	H	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Illustrate the performance of various channel access schemes for satellite communication				2	60	65	-	-	M	-	-	-	H	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Explain the applications of satellites and compression standards adopted in satellite communication				2	60	65	-	-	M	-	-	-	H	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Analyze the Satellite communication and Broadcasting systems.				2	60	65	-	-	M	-	-	-	H	-	-	-	-	-	-	-	-	-	-

Duration (hour)	Satellite Orbit	Link Design	Space and Earth Segment	Multiple Access Techniques for Satellite Communication	Broadcast and Services
	9	9	9	9	9
S-1	SLO-1 Satellite Orbit	Link Design	Space Segment	Concepts of Multiple Access techniques, types	Concept of Broadcasting satellites
	SLO-2 Kepler's law	EIRP	Basic concept of space segmen	Single Access	Direct Broadcasting Satellite
S-2	SLO-1 Earth - Orbiting satellites terms	Transmission Losses	Power Supply	Pre assigned FDMA	Orbital Spacing
	SLO-2 Types of satellites	Link Power Budget equation	Altitude control	Demand Assigned FDMA	Power ratings
S-3	SLO-1 Orbital elements	System Noise	Station keeping	SPADE system	Frequency and polarization
	SLO-2 Orbit Perturbations	Carrier to noise ratio	Thermal Control	TWT amplifier operation	Transponder Capacity
S-4	SLO-1 Inclined Orbits	Types of FEC	TT&C Subsystems	Downlink analysis	Bit rate
	SLO-2 Sun synchronous orbits	Computer-Aided Design	Antenna subsystem	TDMA	MPEG
S-5	SLO-1 Constellation:Geo stationary satellites	Uplink	Transponders	Reference bursts	Forward Error Correction
	SLO-2 Non geostationary constellation	Saturation flux density, input backoff	Wideband Receiver	Preamble, Postamble	Outdoor Unit
S-6	SLO-1 Launching of Geostationary satellites	Down Link	Earth Segment	Carrier recovery	Indoor Unit
	SLO-2 Launch vehicle Types	Output backoff, TWTA output	Basic concept of Earth segment	Network synchronization	Downlink Analysis
S-7	SLO-1 Antenna Look angles	Effects of rain	Receive only home TV system	Pre assigned TDMA	Uplink Analysis
	SLO-2 Sun transit outage	Inter modulation Noise	Community antenna TV system	Demand assigned TDMA	Satellite Mobile services
S-8	SLO-1 Solving Problems	Solving Problems	Solving Problems	CDMA	VSAT
	SLO-2 Solving Problems	Solving Problems	Solving Problems	Direct Sequence Spread Spectrum , CDMA throughput	GPS
S-9	SLO-1 Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems
	SLO-2 Solving Problems	Solving Problems	Solving Problems	Solving Problems	Solving Problems

Learning Resources	1. Dennis Roddy, "Satellite Communications", Tata Mc-Graw Hill Publications, 4th Edition, 13th Reprint, 2014 2. TIMOTHY PRATT, CHARLES BOSTIAN JERMEY ALLNUTT, Satellite Communications, John Wiley, Singapore, 2nd Edition, reprint 2013.	3. MadhavendraRichharia, Leslie David, "Satellite Systems for Personal Applications Concepts and Technology", Wiley-Blackwell, 1st Edition, 2010. 4. Louis J. IppolitoJr, "Satellite Communications Systems Engineering", John Wiley and Sons , Ltd, Publication, 1st Edition, 2008
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE225T	Course Name	INFORMATION THEORY AND CODING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MAB203T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/ Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Introduce source coding in information theory	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Impart the fundamentals of error control coding techniques and their applications	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Address the noisy channel coding problem				-	H	-	-	-	-	-	-	-	-	-	-	-	-	M
CLR-4 :	Assess the performance of both block and convolutional coding schemes in different practical situations				-	H	-	-	-	-	-	-	-	-	-	-	-	-	M
CLR-5 :	Derive Shannon's fundamental channel capacity results				-	H	-	-	-	-	-	-	-	-	-	-	-	-	M
CLR-6 :	Know about channel and impairments channel and how to mitigate them				-	H	-	-	-	-	-	-	-	-	-	-	-	-	M
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)															
CLO-1 :	Illustrate about various source coding schemes				2	65	70												
CLO-2 :	Apply variable length codes for source coding				2	65	70												
CLO-3 :	Apply linear block codes for error detection and correction				2	65	70												
CLO-4 :	Apply convolution codes for performance analysis & cyclic codes for error detection and correction.				2	65	70												
CLO-5 :	Analyze the channel performance using Information theory				2	65	70												
CLO-6 :	Analyze any type of channel and select coding techniques to improve channel performance				2	65	70												

Duration (hour)		Source coding 9	Variable-Length Codes 9	Error Detecting and Error Correcting Codes 9	Convolutional Codes 9	Entropy and Channel Capacity 9
S-1	SLO-1	Introduction to Information theory	Unique decoding	Hamming codes Generation	Convolutional codes introduction	Entropy
	SLO-2	Model of signaling system	Rules and construction of Unique decoding	Hamming code checking	Convolutional codes generation	Mathematical properties
S-2	SLO-1	Block Diagram	Instantaneous codes	Hamming weight	Convolutional encoder	Entropy and coding
	SLO-2	Mathematical models for information sources	Construction of Instantaneous codes	Hamming distance	Encoder for different rates	System entropies
S-3	SLO-1	Encoding a source alphabet	The Kraft's inequality	Minimum distance decoding	Code tree formation	Mutual information
	SLO-2	Source coding	Shortened block codes	Linear block codes Generator polynomial	Code tree formation	Example Problem solving- Mutual information
S-4	SLO-1	ASCII code	The McMillan's Inequality	Linear block codes Generation	State diagram generation	Shannon-Fano coding
	SLO-2	Code Formation for an information	Huffman codes	Linear block codes Decoding	State diagram generation for different rates	Example Problem solving- Shannon-Fano coding
S-5	SLO-1	Radix r code	Huffman codes -special cases	Example Problem solving- Linear block codes	Trellis diagram for decoding convolutional codes	Classification of channels
	SLO-2	Different examples for different 'r'	Extensions of a code	Cyclic codes Generator polynomial	Trellis diagram for decoding convolutional codes	Channel Capacity
S-6	SLO-1	Simple parity checks – Generator	Huffman codes Radix r	Cyclic codes Generation	Maximum likelihood decoding of convolutional codes	Calculation of channel capacity
	SLO-2	Simple parity Checker	Example Problem solving in Huffman	Cyclic codes Decoding	Maximum likelihood decoding of	Types of channel



			coding		convolutional codes	
S-7	SLO-1	CRC codes-Generation	Example Problem solving in Huffman coding-special cases	Example Problem solving -Cyclic codes	Sequential decoding of convolutional codes-	Conditional mutual information
	SLO-2	CRC codes-Checking	Noise in Huffman coding probabilities	Example Problem solving- Syndrome calculation	Sequential decoding of convolutional codes	Random encoding
S-8	SLO-1	Single parity checks	Use of Huffman codes	Block encoders	Applications of Viterbi decoding	Average random code
	SLO-2	Double parity checks	Hamming coding	Block Decoders	Viterbi decoding	Fano bound
S-9	SLO-1	Miscellaneous codes	Example Problem solving in Hamming coding	Assignment Problems in Linear Block codes	Turbo codes	Converse of Shannon's theorem
	SLO-2	Problems in source coding with different radix and parity	Assignment Problems in Huffman and Hamming coding	Assignment Problems in Cyclic codes	Assignment Problems in Convolutional codes	Assignment Problems in Channel capacity and mutual information

Learning Resources	1. Kennedy, "Electronic Communication systems", McGraw Hill, 4th Ed., 1999 2. Daniel Costello, and Shu Lin, "Error Control coding fundamentals and applications", Prentice Hall Inc, 1983 3. Hamming, Richard W, "Coding and Information Theory", Prentice Hall Inc., NJ, 1986.	4. Proakis J. G., "Digital Communications", McGraw Hill Inc., 4th Edition, NY, 2001. 5. Simon Haykin, "Communication System", Wiley, 2008
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE226T	Course Name	OPTICAL COMPONENTS, SYSTEMS AND NETWORKS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Understand the basics working principle of optical fibers, fiber modes configurations and structures.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn the various optical source materials, LED structures, quantum efficiency, Laser diodes. To learn the fiber optical network components, switches, EDFA, SOA.																							
CLR-3 :	Acquire the basic knowledge of fiber optical receivers such as PIN APD diodes, noise performance in photo detector, receiver operation and configuration.																							
CLR-4 :	Get the knowledge on optical wave guides modulators and other signal degradation factors																							
CLR-5 :	Understand the basic working principle of WDM, DWDM etc..																							
CLR-6 :	Understand, the basic optical networks and their applications																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	2	80	70	Problem Analysis	H	M	-	-	-	-	-	-	-	-	-	-	H	-	H
CLO-1 :	Familiarize with the fundamentals of light transmission through fiber																							
CLO-2 :	Understand how signal degrades inside the fiber due to physical effects and externally due to various factors like alignment, splicing and connectorization																							
CLO-3 :	Understand the operation of optical sources, amplifiers and detectors and thereby build transmitter and receiver circuits																							
CLO-4 :	Familiarize with optical measurements for performance analysis																							
CLO-5 :	Design a basic optical communication system																							
CLO-6 :	Acquire fundamental concepts on multichannel system and related components				Level of Thinking (Bloom)	2	80	70	Design & Development	H	M	-	-	-	-	-	-	-	-	-	-	H	-	M

Duration (Hour)		Optical Fibers and transmission characteristics	Optical Sources, Amplifier and Transmitter	Optical Detectors and receivers	Optical modulators, switches and OEICs	Optical Communication systems
		9	9	9	9	9
S-1	SLO-1	Elements of Optical fiber Communication, Optical spectral bands	Introduction to Luminescence: Photo, electro, cathodo, injection luminescence	Photo detection principle	Electro optic modulators	Point to point links
	SLO-2	Optical fiber structure, Light Propagation in Optical fibers: Ray theory, Total Internal reflection, Skew rays, Fiber types: SI, GI, MM, SM	Plasma display, LCD	Photoconductor,	Acousto optic modulators	Digital and analog systems design considerations
S-2	SLO-1	Overview of Modes, Cutoff wavelength and V number,	LED: Choice of material,	Noise in photoconductors, SNR	Interferometry modulators	Digital link design,
	SLO-2	Problems on v-number	LED Structures; Surface and Edge emitters,	Response time	Semiconductor optical amplifiers	Links power budget
S-3	SLO-1	Wave Equations for Step index fiber, Modal equation, Modes in SI fibers	Quantum efficiency and power, LED Characteristics	Problems on response time and SNR	Optical switching and logic devices	Rise time budget
	SLO-2	Problems on V-number, modes	Problems on LED quantum efficiency	Problems on Photoconductor	Problems on modulators	Overview of analog links
S-4	SLO-1	Special Fibers introduction, Polarization Maintaining fibers,	Semiconductor Laser Diode, Operating principles,	Photodiode: PIN Photodiode	Optical switching	Radio over fibers
	SLO-2	Photonic Crystal fibers, Dispersion compensated fiber	Emission absorption and radiation	Avalanche photodiode	Logic devices	Key link parameters
S-5	SLO-1	Attenuation Introduction	Population inversion	Detector performance parameters	Hybrid integration	Multichannel systems
	SLO-2	Material Adsorption, Scattering, bending and core cladding losses	Optical feed-back, Threshold condition	Detectors for long wavelength operation	Monolithic integration	Need for multiplexing
S-6	SLO-1	Problems	External Quantum efficiency, LASER	Wavelength selective detection	Comparison of hybrid and	Operating principle of WDM

			Characteristics		monolithic	
	SLO-2	Overview of Signal dispersion in fibers	Problems on LASER quantum efficiency	Fundamental receiver operation	Slab waveguides	Operating principle of DWDM
S-7	SLO-1	Dispersion limitations, Intermodal dispersion	Single mode Laser: VCSEL	Front end amplifier and decision circuit	Strip waveguides	WDM components
	SLO-2	Intra-Modal dispersion: Material dispersion,	Introduction to Fiber Amplifiers	Functional block diagram of receiver circuit	Guided wave devices	Couplers/splitters
S-8	SLO-1	Waveguide dispersion and PMD	EDFA	Measurement standards, basic test equipment	Active filters	Isolators and circulators
	SLO-2	Problems on Dispersion	SOA	Optical spectrum analyzer	Problems	Machzender interferometer
S-9	SLO-1	Non linear effects : Non linear scattering, Kerr effects	Modulation characteristics and Driver circuits	Optical power meter	Integrated Transmitter	Fabry perot filters
	SLO-2	Fiber alignment and Joint Loss, Fiber Splices Optical fiber connectors, Expanded Beam Connectors	Functional block diagram of a Transmitter module	OTDR	Integrated Receivers	Optical MEMS

Learning Resources	<ol style="list-style-type: none"> <li>1. Gerd Keiser, "Optical Fiber Communication" McGraw –Hill International, Singapore, 3<sup>rd</sup> edition, 2000</li> <li>2. J. Wilson and JF B Hawkes "Optoelectronics – An Introduction" 3<sup>rd</sup> Edition Pearson Education Taiwan Ltd 2010</li> <li>3. Pallab Bhattachara "Semiconductors Optoelectronics Devices", 2<sup>nd</sup> Edition, Prentice Hall of India Pvt Ltd, New Delhi, 2009.</li> <li>4. Jasprit Singh "Optoelectronics- An Introduction to Materials and Devices", Mc Graw Hill Education India 2014.</li> <li>5. S C Gupta "Optoelectronics Devices and systems", 2<sup>nd</sup> Edition, Prentice Hall of India, 2015.</li> </ol>	<ol style="list-style-type: none"> <li>6. S O Kasap "Optoelectronics and Photonics: Principles and practices", 2<sup>nd</sup> Edition Person Education International, 2012.</li> <li>7. Rajiv Ramaswami, Kumar N. Sivarajan, "Optical Networks A practical perspective", 2<sup>nd</sup> edition, Elsevier, 2004</li> <li>8. Djafar K. Mynbaev, Lowell L. Scheiner, "Fiber-Optic Communications Technology", 1<sup>st</sup> edition, Pearson Education, 2001.</li> <li>9. John Powers, "An Introduction to Fiber optic Systems", 2<sup>nd</sup> edition, Irwin-McGraw Hill, 1999.</li> <li>10. J.Gowar, "Optical Communication System", 2<sup>nd</sup> edition, Prentice Hall of India, 2001.</li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com		1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in
		Internal Experts
		1. Dr. B. Ramakrishna, SRMIST
		2. Dr. Shanthi Prince, SRMIST

Course Code	18ECE320T	Course Name	SOFTWARE DEFINED NETWORKS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC303J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	<i>Understanding SDN- Evolution</i>	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	<i>Understanding The Control Plane, Data Plane of SDN</i>	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	<i>Analyze and understand various SDN controller</i>				H	-	M	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	<i>Create insights to the standard OpenFlow for SDN</i>				H	-	-	-	-	-	-	-	-	-	-	-	-	-	M
CLR-5 :	<i>Understand the Network Programmability for SDN and SDN Open Source</i>				H	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-6 :	<i>Understand the Application of SDN and role of SDN in 5G</i>				H	-	M	-	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		1	65	65	H	-	M	-	-	-	-	-	-	-	-	-	-	-	-
CLO-1 :	<i>Explain about the SDN architecture and its benefits</i>	1	65	65	H	-	-	-	-	-	-	-	-	-	-	-	-	-	M
CLO-2 :	<i>Discuss about SDN controllers</i>	1	65	65	H	-	-	-	-	-	-	-	-	-	-	-	-	-	M
CLO-3 :	<i>Express about the programming of SDN elements</i>	1	65	65	H	-	-	-	-	-	-	-	-	-	-	-	-	-	M
CLO-4 :	<i>Interpret NVF for next generation networks and 5G</i>	1	65	65	H	-	-	-	-	-	-	-	-	-	-	-	-	-	M
CLO-5 :	<i>Describe about the possible applications of SDN</i>	1	65	65	H	-	M	-	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	<i>Discuss about the standard OpenFlow</i>	1	65	65	H	-	M	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)		Basics of SDN	SDN Devices and Controller	OpenFlow, Programmability and Management Interface	SDN Application and Use Case	SDN Implementation and Mobile Networks
		9	9	9	9	9
S-1	SLO-1	<i>Introduction to SDN- Evolution of Switches and Control Planes , Cost</i>	<i>How SDN Works- Fundamental Characteristics of SDN</i>	<i>OpenFlow Overview- The OpenFlow Switch, The OpenFlow Controller,</i>	<i>SDN in the Data Center - Data Center Definition, Data Center Demands</i>	<i>SDN Open Source-Chapter-Specific Terminology , Open Source Licensing Issues</i>
	SLO-2	<i>Introduction to SDN - SDN Implications for Research and Innovation</i>	<i>SDN Operation, SDN Devices</i>	<i>The OpenFlow Protocol, The OpenFlow Protocol</i>	<i>Tunneling Technologies for the Data Center.</i>	<i>Profiles of SDN Open Source Users, OpenFlow Source Code,</i>
S-2	SLO-1	<i>Need of SDN- Data Center Innovation,</i>	<i>SDN Controller</i>	<i>OpenFlow 1.0 and OpenFlow Basics- Ports and Port Queues, Flow Table, Packet Matching,</i>	<i>Path Technologies in the Data Center Ethernet Fabrics in the Data Center</i>	<i>Switch Implementations ,Controller Implementations SDN Applications</i>
	SLO-2	<i>Need of SDN- Data Center Needs</i>	<i>SDN Applications ,Alternate SDN Methods</i>	<i>Actions and Packet Forwarding, Messaging Between Controller and Switch</i>	<i>SDN Use Cases in the Data Center</i>	<i>Simulation, Testing, and Tools, OpenStack, Example: Applying SDN Open Source.</i>
S-3	SLO-1	<i>Genesis of SDN- The Evolution of Networking Technology</i>	<i>General Concepts of SDN Controller</i>	<i>Example: Controller Programming Flow Table ,Example: Basic Packet Forwarding, Example: Switch Forwarding Packet to Controller</i>	<i>Open SDN versus Overlays in the Data Center</i>	<i>SDN Futures-Current State of Affairs</i>
	SLO-2	<i>The Genesis of SDN- forerunners of SDN</i>	<i>VMware</i>	<i>OpenFlow 1.3 Additions and OpenFlow Limitations</i>	<i>Real-World Data Center Implementations</i>	<i>Potential Novel Applications of Open SDN</i>
S-4	SLO-1	<i>The Genesis of SDN- software</i>	<i>Nicira</i>	<i>Introduction to Network Programmability and</i>	<i>SDN in Other Environments - Wide Area Networks. Service</i>	<i>Role of SDN in 5G- Drawback of</i>



		Defined Networking is Born, Sustaining SDN Interoperability		The Management Interface	Provider and Carrier Networks	hardware-based network functions., Network Functions Virtualization (NFV) and Software Defined Networking (SDN) in 5G
	SLO-2	Open Source Contributions, Legacy Mechanisms Evolve Toward SDN , Network Virtualization	VMware/Nicira	The Application-Network Divide	Campus Networks, Hospitality Networks	Optimization models that aim at finding the optimal design for a mobile core network based on SDN and NFV
S-5	SLO-1	The Control Plane, Data Plane	OpenFlow-Related	Modern Programmatic Interfaces- Publish and Subscribe Interfaces, XMPP	Mobile Networks. In-Line Network Functions,	SDN and NFV Mobile Network Architectures
	SLO-2	Moving Information Between Planes, Separation Importance	Mininet , NOX/POX	Google's Protocol Buffers , Thrift , JSON	Optical Networks	Dimensioning and Resource Allocation Problems
S-6	SLO-1	Distributed Control Planes- IP and MPLS, Creating IP Underlay, Convergence Time	Trema, Ryu	I2RS 143 Modern Orchestration- OpenStack	SDN vs. P2P/Overlay Networks	Mobile Core Network Architecture
	SLO-2	Load Balancing , High Availability, Creating the MPLS Overlay, Replication	Big Switch Networks/Floodlight,	CloudStack, puppet	SDN Applications- reactive versus Proactive Applications, Analyzing Simple SDN Applications ,	SDN Mobile Core Network Architecture
S-7	SLO-1	Centralized Control Planes- Logical Versus Literal	Layer 3 Centric, L3VPN	Introduction to Network Function Virtualization, Virtualization and Data Plane I/O	A Simple Reactive Java Application, Background on Controllers	NFV Mobile Core Network Architecture
	SLO-2	ATM/LANE , Route Servers	Path Computation Element Server	Services Engineered Path	Using the Floodlight Controller, Using the OpenDaylight Controller, Using the Cisco XNC Controller, Using the Hewlett-Packard Controller.	Data Plane Function Chains Analysis
S-8	SLO-1	Introduction to OpenFlow- Wire Protocol	Path Computation Element Server	Service Locations and Chaining	Witch Considerations, Creating Network Virtualization Tunnels, Offloading Flows in the Data Center, Access Control for the Campus, Traffic Engineering for Service Providers	Control Plane Function Chains Analysis
	SLO-2	Replication , FAWG (Forwarding Abstraction Workgroup)	Plexxi Plexxi Affinity	Non-ETSI NFV Work- Middlebox Studie	SDN Use Cases- Use Cases for Bandwidth Scheduling	Requirements & challenges of SDN and NVF In 5G
S-9	SLO-1	Configuration and Extensibility, Architecture	Cisco OnePK	Embrane/LineRate	Big Data and Application Hyper-Virtualization for Instant CSPF	Existing Solutions
	SLO-2	Hybrid Approaches , Ships in the Night , Dual Function Switches	Relation to Idealized SDN Framework	Platform Virtualization	Use Cases for Input Traffic Monitoring, Classification, and Triggered Action	Future directions
Learning Resources		<ol style="list-style-type: none"> <li>1. Software Defined Networks: A Comprehensive Approach by Paul Goransson and Chuck Black, Morgan Kaufmann Publications, 2014</li> <li>2. SDN - Software Defined Networks by Thomas D. Nadeau &amp; Ken Gray, O'Reilly, 2013</li> <li>3. Cho, Hsin-Hung, et al. "Integration of SDR and SDN for 5G." IEEE Access 2 (2014): 1196-1204.</li> <li>4. Bouras, Christos, Anastasia Kollia, and Andreas Papazois. "SDN &amp; NFV in 5G: Advancements and challenges." Innovations in Clouds, Internet and Networks (ICIN), 2017 20th Conference on. IEEE, 2017.</li> <li>5. Arsany Basta; Andreas Blenk; Klaus Hoffmann; Hans Jochen Morper; Marco Hoffmann; Wolfgang Kellerer, Towards a Cost Optimal Design for a 5G Mobile Core Network Based on SDN and NFV,, IEEE Transactions on Network and Service Management, 2017, Volume: 14, Issue: 4 ,Pages: 1061 - 1075</li> </ol>				

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. P. Vijayakumar, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE321T	Course Name	RF AND MICROWAVE SEMICONDUCTOR DEVICES	Course Category	E	Professional Elective				L	T	P	C
										3	0	0	3

Pre-requisite Courses	18ECC102J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Study microwave semiconductor materials and to understand the fundamental of electronic components under microwave signal	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn about microwave components and devices that are used in modern microwave radar and communication systems				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3			
CLR-3 :	Know the characteristics and operation of microwave transistor.																					
CLR-4 :	Know the fundamentals of RF power transistors and challenges																					
CLR-5 :	Discuss the main issues and challenges encountered in developing the products at microwave frequencies																					
CLR-6 :	Acquire deep understanding of development of RF and modern semiconductor devices																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Understand the properties of Semiconductor Junction Diodes under microwave signals	3	80	75	H	-	-	H	-	-	-	-	-	-	-	-	-	H	-	-		
CLO-2 :	Analyze the development of negative resistance characteristics in tunnel diode and transit time devices	3	80	70	H	-	-	M	-	-	-	-	-	-	-	-	-	H	-	-		
CLO-3 :	Characterize the microwave components and circuits in terms of their performance parameters	3	75	70	H	-	-	H	-	-	-	-	-	-	-	-	-	H	-	H		
CLO-4 :	Compare the characteristics of RF power transistors	3	80	75	H	-	-	M	-	-	-	-	-	-	-	-	-	M	-	-		
CLO-5 :	Appreciate IC packaging issues and challenges involved at microwave frequencies	3	80	70	H	-	H	-	-	-	-	-	-	-	-	-	-	H	-	M		
CLO-6 :	Understand the concepts of RF and semiconductor devices and apply in the design of electronic systems.	3	80	70	H	H	-	-	-	-	-	-	-	-	-	-	-	H	-	H		

	Semiconductor P-N Junction		Negative Resistance and Transit Time Devices		Microwave BJT Transistors		HEMT Transistors and RF Power Transistor		RF Package Design and Development	
Duration (hour)	9		9		9		9		9	
S-1	SLO-1	Review of properties of semiconductors	Negative Resistance Devices		Microwave Transistor		Introduction to HEMT		Introduction to RF Package	
	SLO-2	Review of properties of semiconductors	Negative Resistance Devices		High frequency limitations of BJT		Short channel effects		Introduction to RF Package	
S-2	SLO-1	Transient and ac behavior of p-n junctions	Tunnel Diode, Tunneling process in p-n junction		Microwave bipolar transistors – introduction		Device operation		Thermal Management	
	SLO-2	Transient and ac behavior of p-n junctions	V-I characteristics and device performance		Microwave bipolar transistors – operation		Device operation		Thermal Management	
S-3	SLO-1	Effect of doping profile on the capacitance of p-n junctions	MIS tunnel diodes		Hetero junction bipolar transistors		Device design		Mechanical Design	
	SLO-2	Effect of doping profile on the capacitance of p-n junctions	V-I characteristics and device performance		Basic principle of operation		Scaling issues		Mechanical Design	
S-4	SLO-1	Noise in p-n junctions	Backward Diode		Kirk effect		Material Systems for HEMT Devices		Package electrical and electromagnetic Modeling	
	SLO-2	Noise in p-n junctions	V-I Characteristics		High frequency response		GaAs HEMT		Package electrical and electromagnetic Modeling	
S-5	SLO-1	Varactor diode	Transferred Electron Devices		MESFET		InP HEMT		Design verification	
	SLO-2	Construction and Operation of Varactor Diode	Impact ionization		Principle of operation		Technology comparisons		Design verification	

S-6	SLO-1	Applications of Varactor Diode	IMPATT	Properties of semiconductor materials used in MESFET	Technology comparisons	Materials testing
	SLO-2	Schottky effect	Small-signal analysis of IMPATT diodes	MESFET Technology	Introduction of RF power transistor	Reliability testing
S-7	SLO-1	Schottky barrier diode	TRAPATT, BARITT Diodes	MESFET Modeling	Figure of Merit for RF Power Transistor	Computer integrated Manufacturing
	SLO-2	Applications of Schottky Diode	Two-valley model of compound semiconductors	I-V Characteristics	Common RF power devices	Computer integrated Manufacturing
S-8	SLO-1	Hetero junctions	VD-E characteristics	High frequency performance	Material properties	Thermal modeling
	SLO-2	Hetero junctions	Gunn Effect, modes of operation	MISFET-Introduction	State-of-the-art-wide bandgap microwave transistor data	Thermal analysis of resistance networks
S-9	SLO-1	Construction and operation of microwave PIN diode	Small-signal analysis of Gunn diode	Operating characteristics of MISFET	Challenges to production	Introduction to computer aided design
	SLO-2	Applications	Power-frequency limit.	Operating characteristics of MISFET	Challenges to production	Benefits, limitations and applications of CAD

Learning Resources	1. Golio, M., "RF and Microwave Semiconductor Devices Handbook", CRC Press (2002).	3. Glover, I.A., Pennoek, S.R. and Shepherd P.R., "Microwave Devices, Circuits and Sub-Systems", 4th Ed., John Wiley & Sons (2005)
	2. Sze, S.M., and Ng, K.K., "Physics of Semiconductor Devices", 3rd Ed., Wiley-Interscience (2006).	4. Liao, S.Y., "Microwave Devices and Circuits", 4th Ed., Pearson Education (2002).

#### Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#		Theory	Practice
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
Total		100 %		100 %		100 %		100 %		100 %	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	



Course Code	18ECE322T	Course Name	OPTOELECTRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC102J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Identify the working and nature of optical wave				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Identify the working and nature of optical semiconductors																							
CLR-3 :	Analyze the working principles of different photonic sources																							
CLR-4 :	Analyze the working principles of different photonic detectors																							
CLR-5 :	Create knowledge about various optoelectronic applications																							
CLR-6 :	Familiarize the concepts of optoelectronic integrated circuits																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Review the basics of optics, optical semiconductors				2	85	80	H	H	-	-	-	-	-	-	-	-	-	-	-	M	-	-	-
CLO-2 :	Understand the working principle of different photonic sources				4	85	75	H	H	H	H	-	-	-	-	-	-	-	-	-	M	L	-	H
CLO-3 :	Familiarize the principle and operation of various detectors				4	85	75	H	H	H	H	-	-	-	-	-	-	-	-	-	M	L	-	H
CLO-4 :	Acquire knowledge of various optoelectronic modulators and switches				4	80	70	H	H	-	-	-	-	-	-	-	-	-	-	-	M	-	-	-
CLO-5 :	Explore the concepts of optoelectronic integrated circuits and components				4	80	70	H	-	H	-	-	-	-	-	-	-	-	-	-	M	L	-	-
CLO-6 :	Design and analyze the working of different components in optical system and use it for various applications.				4	80	70	H	H	H	H	-	-	-	-	-	-	-	-	-	M	-	-	H

Duration (hour)		Wave nature of light and semiconductor optics	Semiconductor photon sources and display devices	Semiconductor photon detectors	Optoelectronic modulators, interconnects and switches	Optoelectronic integrated circuits (oeic) and applications
		9	9	9	9	9
S-1	SLO-1	Light Waves In A Homogeneous Medium- Plane electromagnetic wave, Maxwell's wave equation	LED Principles- Homojunction LED, Heterostructure LED	Principle of Photo Detection	Electro-Optic Modulator: Principles, Electro optic effect	Introduction
	SLO-2	Refractive Index And Dispersion- Sellmeier equation and diamond, Cauchy equation and diamond	Quantum Well High Intensity LEDs	The PIN Photodiode	Single waveguide electro optic modulators	Need For Integration
S-2	SLO-1	Polarization Of Light	LED Materials and Structures	Avalanche Photodiode- Principles, Structures	Dual channel waveguide electro optic modulator	Slab and stripe waveguides
	SLO-2	Snell's law and Total internal reflection	LED Efficiencies and Luminous Flux	Responsivity, Efficiency	Electro optic modulator employing reflection or Diffraction	Basic IO structural elements
S-3	SLO-1	Reflection And Refraction	Manufacturing Process and Applications	Heterojunction Photodiodes	Integrated Optical Modulators: Phase and polarization modulation	IO devices: Optical disk read head
	SLO-2	Solving problems	Solving Problems	Schottky Junction Photodetectors	Mach Zehnder modulator, Coupled waveguide modulator	OIC temperature sensor
S-4	SLO-1	Superposition And Interference Of Waves	LASER: Threshold Condition	Solving problems	Acousto-Optic Modulator: Principles, Acousto optic effect, Raman nath and Bragg type modulators	IO high voltage sensor
	SLO-2	Diffraction Principles- Fraunhofer diffraction, Diffraction Grating	Emission and Absorption of Radiation	Solving problems	Performance characteristics, Acousto optic frequency shifters	IO chemical sensor

S-5	SLO-1	Overview Of Semiconductors	Population Inversion	Metal-Semiconductor, Metal Photodiode	Solving problems	IO wavelength meters and spectrum analyzers
	SLO-2	Interaction of Photons With Charge Carriers	Principle of the Laser Diode	Phototransistors	Solving problems	RF Spectrum Analyzer
S-6	SLO-1	Hole Pair Formation And Recombination	Heterostructure Laser Diodes	Array Detectors	Faraday Rotation	Monolithic Wavelength-Multiplexed Optical Source
	SLO-2	Absorption In Semiconductors	Device Fabrication	Photoconductive detectors	Optical Isolators	Analog-To-Digital Converter
S-7	SLO-1	Effect Of Electric Field On Absorption	Solving problems	Noise In Photodetectors	Nonlinear Optics	Integrated-Optic Doppler Velocimeter
	SLO-2	Absorption In Quantum Wells	Display Device: Photo Luminescence	Noise In Photodetectors	Second Harmonic Generation	Guided Wave Devices
S-8	SLO-1	Radiation In Semiconductors	Cathode Luminescence, Electro Luminescence	Solving problems	Optical Interconnects	Guided Wave Devices
	SLO-2	Solving Problems	Injection Luminescence	Solving problems	Optical gates	OEIC: Transmitter
S-9	SLO-1	Heterojunctions	Plasma Displays	Charge Coupled Devices (CCD)	Photonic Switches	OEIC: Receiver
	SLO-2	Heterojunctions	LCD, Numeric Displays	Charge Coupled Devices (CCD)	Solving problems	OEIC phased array antenna driver

Learning Resources	1. Kasap, "Optoelectronics & Photonics: Principles & Practices", 2nd edition, Pearson Education, 2013.	4. Robert G. Hunsperger, "Integrated Optics- Theory And Technology", Springer, 2009
	2. Pallab Bhattacharya "Semiconductor Optoelectronic Devices", 2nd Edition, Prentice Hall of India Pvt. Ltd, New Delhi, 2009.	5. J. Wilson and J F B Hawkes "Optoelectronics- An Introduction", 3rd edition, Pearson Education Taiwan Ltd, 2010.
	3. B. E. A. Saleh and m.c. Teich, "Fundamentals Of Photonics," 2nd edition, John Wiley & Sons, Inc. 2007.	6. A Ghatak and K Thyagarajan, "Introduction to Fiber Optics", Cambridge University Press 2006.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	40%	-	35%	-	35%	-	40%	-
	Understand										
Level 2	Apply	40%	-	40%	-	35%	-	35%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	20%	-	30%	-	30%	-	20%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com		1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in
		Internal Experts
		1. Ms. Ramya A, SRMIST

Course Code	18ECE323T	Course Name	ADVANCED OPTICAL COMMUNICATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC302J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																													
CLR-1 :	Introduce the advanced features of Fibers and light wave system				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	2	Problem Analysis	3	Design & Development	4	Analysis, Design, Research	5	Modern Tool Usage	6	Society & Culture	7	Environment & Sustainability	8	Ethics	9	Individual & Team Work	10	Communication	11	Project Mgt. & Finance	12	Life Long Learning	13	PSO - 1	14	PSO - 2	15	PSO - 3
CLR-2 :	Illustrate the basics of light wave system and multichannel system																																				
CLR-3 :	Understand the various dispersion compensation techniques																																				
CLR-4 :	Gain the information on advanced RoF Systems																																				
CLR-5 :	Improve the knowledge about the characterization of the Visible Light Communication																																				
CLR-6 :	Utilize the concepts in optical communication for the understanding of engineering and technology																																				
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Expected Proficiency (%)	Expected Attainment (%)																															
CLO-1 :	Explain the concept of wave propagation and dispersion in single-mode fibers, loss and nonlinear of fiber and fiber design and fabrication.				2	80	70	H	H	M	H	H	-	L	-	-	H	-	-	H	-	-	H	M	H												
CLO-2 :	Apply the concept of optical transmitter and receiver in single-mode semiconductor lasers, light-emitting diodes, transmitter design and receiver design				2	85	75	H	H	M	H	H	-	L	-	-	H	-	-	H	-	-	H	M	H												
CLO-3 :	Demonstrate the concept of long-haul systems, computer-aided design, WDM light wave systems, WDM Components, time-division, subcarrier and code division multiplexing				2	75	70	H	H	M	H	H	-	L	-	-	H	-	-	H	-	-	H	M	H												
CLO-4 :	Explain the loss and dispersion managements in EDFA - Raman amplifiers, dispersion compensating fibers Fiber Bragg gratings, dispersion-equalizing filters and optical phase conjugation				2	85	80	H	H	M	H	H	-	L	-	-	H	-	-	H	-	-	H	M	H												
CLO-5 :	Apply the concept of advanced light wave system in demodulation schemes sensitivity degradation mechanisms and impact of nonlinear effects				2	85	75	H	H	M	H	H	-	L	-	-	H	-	-	H	-	-	H	M	H												
CLO-6 :	Apply their idea in Optical communication module				2	80	70	H	H	M	H	H	-	L	-	-	H	-	-	H	-	-	H	M	H												

Duration (hour)		Optical fibers and lightwave systems	Lightwave systems and multichannel systems	Loss management and dispersion management	Radio over fiber systems	Optical wireless Communication
		9	9	9	9	9
S-1	SLO-1	Geometrical-Optics Description	System Architectures	Compensation of Fiber Losses	Trends in Wireless Communications	Free-space optical wireless Communication
	SLO-2	Wave Propagation	Working Principles	Erbium-Doped Fiber Amplifiers les	Basic Transmission problems and solutions	Free-space optical OFDM Communication
S-2	SLO-1	Dispersion in Single-Mode Fibers	Design Guidelines	Raman Amplifiers	Regulation	Wireless optical CDMA Communication systems
	SLO-2	Dispersion Induced Limitations	Long-Haul Systems	Optical Signal-To-Noise Ratio	Standardization	Comparison of Free-space optical OFDM & CDMA Communication
S-3	SLO-1	Fiber Losses	Sources of Power Penalty	Electrical Signal-To-Noise Ratio	System concepts for the central processing of signals	Indoor wireless optical Communication
	SLO-2	Nonlinear Optical Effects	Forward Error Correction	Receiver Sensitivity and Q Factor	Wireless Trends	Outdoor wireless optical Communication
S-4	SLO-1	Fiber Design and Fabrication	Types of FEC	Role of Dispersive and Nonlinear Effects	Architecture options,	Heterogeneous optical networks (HONs)
	SLO-2	Multicore fibers	Computer-Aided Design	Periodically Amplified Lightwave Systems	Global centralized Architecture	System Performance

S-5	SLO-1	Multiclad fibers advantages and its applications	WDM DWDM	Dispersion Problem Its Solution	FUTON scenarios Optical Infrastructure	VLC System Model Advantages and its applications
	SLO-2					
S-6	SLO-1	Advanced Modulation Formats	Light wave Systems	Dispersion-Compensating Fibers	Concepts of Radio over Fiber systems	(RF) sensor network system
	SLO-2	Demodulation Schemes	WDM Components	Fiber Bragg Gratings	Features of RoF	Advantages and its applications
S-7	SLO-1	Shot Noise	System Performance Issues	Dispersion Equalizing Filters	Categories RoF systems	(FSO) sensor network system
	SLO-2	Bit-Error Rate	Time-Division Multiplexing	Optical Phase Conjugation	Performances RoF systems	Advantages and its applications
S-8	SLO-1	Sensitivity Degradation Mechanisms	Subcarrier Multiplexing	Channels at High Bit Rates	Applications of RoF Technology	Recent Advancement in Optical Wireless Communication
	SLO-2	Impact of Nonlinear Effects	Code-Division Multiplexing	Electronic Dispersion Compensation	Advantages of RoF Technology	Advantages and its applications
S-9	SLO-1	Recent Progress	Solving Problems	Solving Problems	Solving Problems	Solving Problems
	SLO-2	Ultimate Channel Capacity	Solving Problems	Solving Problems	Solving Problems	Solving Problems

Learning Resources	1. Nathan J. Gomes, Paulo P. Monteiro and Atilio Gameiro "Next Generation wireless Communications using Radio over Fiber" John Wiley & Sons, Ltd, 2012 2. G.P. Agarwal, Fiber optic Communication systems, 4nd Ed, John Wiley & Sons, New York, 2010	3. ShlomiAron, John R. Barry, George K. Karagiannidis, Robert Schober, Murat Uysal, "Advanced Optical Wireless Communication Systems" Cambridge University Press, 2012 4. Shlomi Amon, "Visible light Communication", Cambridge University Press, 2015
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. C.T. Manimegalai, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	



Course Code	18ECE240T	Course Name	WAVELETS AND SIGNAL PROCESSING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC104T	Co-requisite Courses	Nil	Progressive Courses	18ECE341T
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Summarize about multi resolution analysis and wavelet signal processing				Level of Thinking (Bloom)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Identify the families of wavelets required to apply the transformation to various real time applications					Expected Proficiency (%)																		
CLR-3 :	Discuss about discrete systems that employs wavelet transformation						Expected Attainment (%)																	
CLR-4 :	Outline various filter banks of discrete systems used in wavelet transformation																							
CLR-5 :	Analyze various real time applications that employs filter banks																							
CLR-6 :	Acquire knowledge about wavelet transforms, types and applications of multiresolution analysis																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Discuss about multi resolution analysis for discrete signals				2	80	75	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLO-2 :	Summarize the families of wavelets				1,2	80	70	H	H	-	-	-	-	-	-	-	-	-	-	H	-	-		
CLO-3 :	Identify Discrete wavelet transform				2	75	70	H	-	M	-	-	-	-	-	-	-	-	-	H	-	M		
CLO-4 :	Analyze and design filter banks				3	80	75	M	M	M	-	-	-	-	-	-	-	-	-	M	-	-		
CLO-5 :	Utilize wavelet transformations on various applications				3	80	70	H	-	M	-	-	-	-	-	-	-	-	-	H	-	-		
CLO-6 :	Provide an outline about wavelet transforms, types and applications of multiresolution analysis				2	80	70	H	-	M	L	-	-	-	-	-	-	-	-	H	M	H		
								M	H	-	-	-	-	-	-	-	-	-	-	M	-	-		

Duration (hour)		Multiresolution Analysis (MRA)	Families of wavelets	Discrete Wavelet Transform (DWT)	Filter banks	Applications
		9	9	9	9	9
S-1	SLO-1	Introduction to multiresolution/ multiscale analysis	Orthogonal	Discretization in steps	Introduction to Variants of the wavelet transform	Transient analysis
	SLO-2	Introduction to multiresolution/ multiscale analysis	Orthogonal	Discretization in steps	Introduction to Variants of the wavelet transform	Transient analysis
S-2	SLO-1	Time-frequency analysis and wavelets	Biorthogonal wavelets	Discretization of scale	Implementational structures	Singularity detection
	SLO-2	Time-frequency analysis and wavelets	Biorthogonal wavelets	Discretization of scale	Implementational structures	Singularity detection
S-3	SLO-1	Piecewise constant approximation	Daubechies' family of wavelets	Generalized filter bank	The wavepacket transform	Biomedical signal processing applications
	SLO-2	Piecewise constant approximation	Daubechies' family of wavelets	Generalized filter bank	The wavepacket transform	Biomedical signal processing applications
S-4	SLO-1	Haar wavelet	Daubechies' family of wavelets	Discretization of translation	Computational efficiency in realizing filter banks	Efficient signal design and realization
	SLO-2	Haar wavelet	Conjugate Quadrature Filter Banks (CQF) and their design	Discretization of translation	Computational efficiency in realizing filter banks	Efficient signal design and realization
S-5	SLO-1	Building up the concept of dyadic Multiresolution Analysis (MRA)	Conjugate Quadrature Filter Banks (CQF) and their design	Generalized output sampling	Computational efficiency in realizing filter banks	Wavelet based modulation and demodulation
	SLO-2	Building up the concept of dyadic Multiresolution Analysis (MRA)	Conjugate Quadrature Filter Banks (CQF) and their design	Generalized output sampling	Polyphase components	Wavelet based modulation and demodulation
S-6	SLO-1	Relating dyadic MRA to filter banks	Data compression	Discretization of time/ space (independent variable)	Polyphase components	Applications in mathematical approximation
	SLO-2	Relating dyadic MRA to filter banks	Data compression	Discretization of time/ space	Polyphase components	Applications in mathematical

				(independent variable)		approximation
S-7	SLO-1	A review of discrete signal processing	Fingerprint compression standards	Going from piecewise linear to piecewise polynomial	The lattice structure	Applications to the solution of some differential equations.
	SLO-2	A review of discrete signal processing	Fingerprint compression standards	Going from piecewise linear to piecewise polynomial	The lattice structure	Applications to the solution of some differential equations.
S-8	SLO-1	Elements of multirate systems	JPEG-2000 standards	The class of spline wavelets	Solving Problems	Solving Problems
	SLO-2	Elements of multirate systems	JPEG-2000 standards	The class of spline wavelets	Solving Problems	Solving Problems
S-9	SLO-1	Two-band filter bank design for dyadic wavelets.	Solving problems	A case for infinite impulse response (IIR) filter banks	The lifting scheme.	Solving Problems
	SLO-2	Two-band filter bank design for dyadic wavelets.	Solving problems	A case for infinite impulse response (IIR) filter banks	The lifting scheme.	Solving Problems

Learning Resources	<ol style="list-style-type: none"> <li>1. M. Vetterli, J. Kovacevic, <i>Wavelets and Subband Coding</i>, Prentice Hall, 1995</li> <li>2. S. Mallat, <i>A Wavelet Tour of Signal Processing</i>, 2<sup>nd</sup> ed., Academic Press, 1999</li> <li>3. P.P. Vaidyanathan, <i>Multirate Systems and Filter Banks</i>, Pearson Education, 1993</li> <li>4. C.S.Burrus, Ramesh A. Gopinath, and Haitao Guo, <i>Introduction to Wavelets and Wavelet Transforms: A Primer</i>, Prentice Hall, 1997</li> </ol>	<ol style="list-style-type: none"> <li>5. Gilbert Strang, Truong Nguyen, <i>Wavelets and Filter Banks</i>, 2<sup>nd</sup> ed., Wellesley-Cambridge Press, 1998.</li> <li>6. Ingrid Daubechies, <i>Ten Lectures on Wavelets</i>, SIAM, 1992</li> <li>7. Howard L. Resnikoff, Raymond O. Wells, "Wavelet Analysis: The Scalable Structure of Information", Springer, 1998</li> </ol>
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#### Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

#### Course Designers

Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. Sabitha Gauni, SRM IST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE241J	Course Name	SIGNAL PROCESSING FOR AUDITORY SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
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S 7-8	SLO-1	Lab 2: Convert into a wave file, plot the speech signal, and spectrogram plot	Lab 5: Short-time Fourier transform magnitude spectrum	Lab 8: Estimation of pitch period using harmonic product spectrum	Lab 11: Estimation of sound in vocal tract	Lab 14: Speech production mechanism
	SLO-2	Visualization	Zero crossing Rate	Linear Predictive analysis of speech	Vocal tract transfer function of vowels	Detecting beats, rhythm, meter
S-9	SLO-1	Sound generation	Zero crossing Rate	Linear Predictive analysis of speech	Vocal tract transfer function of vowels	Recognizing pitch – melody
	SLO-2	Speech production mechanism	Silence Discrimination using ZCR and energy	Autocorrelation method, Covariance method	Effect of nasal coupling	Auditory streaming
S-10	SLO-1	Speech production mechanism	Silence Discrimination using ZCR and energy	Solution of LPC equations	Excitation of sound in vocal tract	Tonality and context – algorithms
	SLO-2	Speech production mechanism	Lab 6: (i) Linear prediction magnitude spectrum (ii) Estimation of formant frequencies using linear prediction	Lab 9: Pitch and duration modification using time-domain pitch synchronous overlap and add (TD-PSOLA) method	Lab 12: Sound vibrations	Lab 15: Study of Feature extraction and SVM classifier

Learning Resources	1. Ian McLaughlin, <i>Applied Speech and Audio processing, with MATLAB examples</i> , 1 <sup>st</sup> ed., Cambridge University Press, 2009 2. Ben Gold, Nelson Morgan, Dan Ellis, Wiley, <i>Speech and Audio Signal Processing: Processing and Perception of Speech and Music</i> , 2 <sup>nd</sup> ed., John Wiley & Sons, 2011	3. Lawrence Rabiner, B.H. Juang, <i>Fundamentals of Speech Recognition</i> , 2 <sup>nd</sup> ed., Prentice-hall, 1993 4. Ken Pohlmann, <i>Principles of Digital Audio</i> , 6 <sup>th</sup> ed., McGraw-Hill, 2007 5. A.R. Jagan, <i>Speech and Audio Signal Processing</i> , PHI Learning Pvt. Ltd, 2016
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	



Course Code	18ECE242J	Course Name	PATTERN RECOGNITION AND NEURAL NETWORKS	Course Category	E	Professional Elective				L	T	P	C
										2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	18ECE340T
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Learn the concepts of pattern recognition				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Analyze few parameter estimation methods for pattern recognition				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Acquire knowledge on the fundamental neural networks							L	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Apply the neural network recurrence for pattern recognition studies							-	-	-	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-5 :	Utilize the practical applications of neural networks in pattern recognition							-	-	-	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-6 :	Understand the pattern and apply neural network based learning algorithm to analyze the data from real world applications							-	-	M	-	M	-	-	-	-	-	-	-	-	-	L	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			1	80	70	L	L	-	-	-	-	-	-	-	-	-	-	-	-	-		
CLO-1 :	Demonstrate the fundamentals of recognition of patterns, regularities in data and classifiers				1	80	70	-	-	-	M	-	-	-	-	-	-	-	-	-	-	-		
CLO-2 :	Review the error estimation, such as definitions, test-set error estimation and training-set error estimation				1	80	70	-	-	-	M	-	-	-	-	-	-	-	-	-	-	H		
CLO-3 :	Discuss the neuron model and fundamentals on learning algorithms				2	75	70	-	-	-	M	-	-	-	-	-	-	-	-	-	-	-		
CLO-4 :	Realize the error model and calculate the deviation with back propagation networks				2	80	70	-	-	M	-	-	-	-	-	-	-	-	-	M	-	H		
CLO-5 :	Review the applications of neural networks in the area of pattern recognition				2	80	70	-	-	M	-	-	-	-	-	-	-	-	-	-	-	H		
CLO-6 :	Analyze a variety of pattern classification techniques to real-world problems such as document analysis and recognition.				2	80	70	-	-	M	-	M	-	-	-	-	-	-	-	L	-	-		

		Introduction To Pattern Recognition	Parameter Estimation Methods	Introduction to Neural Networks	ANN for Classification and Regression	ANN for Organization and Recognition
Duration (hour)		12	12	12	12	12
S-1	SLO-1	Introduction to Statistical Pattern Recognition	Introduction to parameter estimation	Introduction to neural networks	Introduction to Hopfield networks	Self-organizing map
	SLO-2	Overview of Pattern Classifiers	Maximum-Likelihood estimation	Neuron model	Hop-field network- architecture	SOM algorithm
S-2	SLO-1	Process of Classifier Design, Decision making theory	Maximum a Posteriori estimation	Learning methods of ANN, Supervised, Unsupervised and reinforced	Recurrent networks	Learning vector quantization
	SLO-2	Bayesian decision making	Bayesian estimation	Basic learning rules of ANN-	Sample recurrent network structure	Kohonen self-organizing map
S 3-4	SLO-1	Lab1: Digitization of analog signals	Lab4: Programs on Estimation	Lab 7: Logic gate function description with Hebb rule	Lab 10: Programs on training a Hopfield network	Lab 13: programs on orthogonality and evaluating input and output for association
	SLO-2					
S-5	SLO-1	Bayes Classifier	Unsupervised learning and clustering	McCulloch pitt neuron	Associative memories- Introduction:	Feature selection
	SLO-2	Bayes Classifier for minimizing Risk	Clustering vs. Classification-Supervised vs. unsupervised	Problems on McCulloch pitt	Auto and hetero associative memory	Feature map classifier, applications
S-6	SLO-1	Estimating Bayes Error	Criterion functions for clustering Algorithms for clustering	Hebb learning rule	Bi directional memories	Architecture of Adaptive Resonance Theory
	SLO-2	Effect of sample size in estimation	K-Means clustering	Problems on Hebb learning rule	XOR problem	ATR1 algorithm
S 7-8	SLO-1	Lab 2: Program to count the white pixels from the image	Lab 5: Loading a data set and selecting predictive features	Lab 8: Evaluating function with different learning rules	Lab 11: Programs on Auto and hetero association of memory	Lab 14: Character Recognition
	SLO-2					
S-9	SLO-1	Minimax Classifiers	Hierarchical methods of clustering	Single layer perceptron architecture Training algorithm	Back-propagation Algorithm	ART2 algorithm - Training

	SLO-2	Neymann Classifiers	Comparison of methods, cluster distance and validation	Multilayer perceptron	Counter propagation networks-architecture	ART2- network architecture
S-10	SLO-1	Pearson Classifiers	Sequential Pattern Recognition	Adaline architecture	Simulated annealing	Hand written digit recognition
	SLO-2	Applications	Sequential Pattern Recognition	Madaline architecture	Boltzmann machine	Character recognition networks
S 11-12	SLO-1	Lab3: Analysis of a data set with classifiers	Lab 6: Programs on clustering technique	Lab 9 : XOR problem with Perceptron network	Lab 12: Evaluation of error in BPN	Lab 15: Mini Project

Learning Resources	1. Christopher M. Bishop, Pattern Recognition and Machine Learning, Springer Verlag, 2016 2. Dionisis Cavouras , S.Theodoridis , K. Koutroumbas , A. Pikrakis , An Introduction to Pattern Classification: A Matlab Approach, Elsevier Science Publishing Co Inc, 2010 3. Martin T.Hagan, Neural network design, Cengage publications, 2010 4. Simon O. Haykin, Neural Network and Learning Machines, 3 <sup>rd</sup> ed., Pearson Education, 2009 5. Ke-Lin Du ,M. N. S. Swamy, Neural Networks and Statistical Learning, Publisher Springer, 2014 6. Kosko B, Neural Networks and Fuzzy Systems: A dynamical system approach to machine intelligence, Prentice Hall, 2009
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. A. Ruhan Bevi, SRM IST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE243J	Course Name	DIGITAL IMAGE AND VIDEO PROCESSING	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECC204J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Introduce the fundamentals of image processing and transforms				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Discuss the concepts of image enhancement and restoration				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3		
CLR-3 :	Acquire knowledge on image compression and segmentation methods							L	-	-	M	-	-	-	-	-	-	-	-	-	H	M	-	-
CLR-4 :	Summarize basics of video processing							H	H	-	H	H	-	-	-	-	-	-	-	-	H	M	-	H
CLR-5 :	Apply motion estimation methods in video processing							M	M	-	H	H	-	-	-	-	-	-	-	-	H	-	-	M
CLR-6 :	Utilize the concepts of image and video processing for practical applications							H	M	-	H	H	-	-	-	-	-	-	-	-	H	-	-	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Demonstrate the basics of digital image processing fundamentals and transforms				1,2	80	70	L	-	-	M	-	-	-	-	-	-	-	H	M	-	-		
CLO-2 :	Design 2D filters and apply it for image enhancement and restoration				3	80	70	H	H	-	H	H	-	-	-	-	-	-	H	M	-	H		
CLO-3 :	Apply image compression and segmentation methods on digital images				3	80	65	M	M	-	H	H	-	-	-	-	-	-	H	-	-	H		
CLO-4 :	Define the video formation techniques				2	80	70	H	M	-	H	H	-	-	-	-	-	-	H	-	-	M		
CLO-5 :	Compile various motion techniques used in video coding				2	75	65	H	M	-	H	H	-	-	-	-	-	-	H	-	-	H		
CLO-6 :	Apply the concepts of digital image, video processing and their applications				2,3	80	70	M	-	-	-	-	-	-	-	-	-	-	-	M	-	M		

Duration (hour)		Digital Image Fundamentals and Image Transforms	Image Enhancement and Restoration	Image Compression and Segmentation	Basic Steps of Video Processing	2D Motion Estimation
		12	12	12	12	12
S-1	SLO-1	Origin of digital image processing	Some basic intensity transformation functions – image negatives, log transformations	Fundamentals of image compression-coding redundancy, spatial and temporal redundancy	Analog video signals, standard	2D motion estimation – Optical flow – 2D motion vs. apparent motion
	SLO-2	Fundamental steps in digital image processing	Piecewise linear transformation functions	Irrelevant information, measuring image information	Digital video signal, standard, Digital video processing	Correspondence and optical flow
S-2	SLO-1	Components of an image processing system	Histogram equalization, Matching	Image compression model, Lossless compression, Huffman coding	Time varying image formation models – 3D motion models	Occlusion problem
	SLO-2	Structure of human eye, Image formation	Local Histogram Processing	Arithmetic Coding, Run length coding	Rigid motion in Cartesian, Homogenous coordinates	Aperture problem, 2D motion field models
S- 3-4	SLO-1	Lab 1: To learn MATLAB software and its basic commands for image processing	Lab 4: Histogram Modifications	Lab 7: Run length coding	Lab 10: Wavelet coding	Lab 13: Convert video into frames and process them
	SLO-2					
S-5	SLO-1	Brightness adaptation and discrimination	Using histogram statistics for image enhancement	Lossy compression - Transform coding	Deformable motion	Block motion models- translational block motion
	SLO-2	Basic concepts in sampling and Quantization , Representing digital images	Smoothing linear filters	Wavelet coding	Geometric image formation	Generalized/ Deformable block motion
S-6	SLO-1	Neighbors of a pixel, Adjacency, Connectivity, Regions and Boundaries	Order statistics nonlinear filters	Image segmentation – detection of isolated points, line detection	Perspective projection	Block matching criteria, Matching procedures
	SLO-2	Distance Measures, A simple image	Sharpening spatial filters	Edge models, Basic edge detection	Photometric image formation	Hierarchical motion estimation

		formation model				
S- 7-8	SLO-1	Lab 2: Fourier analysis of image	Lab 5: Image smoothing and sharpening	Lab 8: Basic edge detection operations	Lab 11: JPEG Compression	Lab 14: Filtering video signals
	SLO-2					
S-9	SLO-1	Fourier transform of sampled functions	Combined spatial enhancement methods	Region based segmentation – region growing	Photometric effects of 3D motion	Gradient based optimization
	SLO-2	Sampling theorem, Aliasing, Obtaining the DFT from the Continuous Transform of a Sampled Function	Homomorphic filtering, A model of image degradation/ restoration process	Region splitting and merging	Observation noise, Sampling structures of analog, digital video	Steepest Descent method
S-10	SLO-1	Properties of 2D DFT – Relationship between spatial and frequency interval, Translation and Rotation, Periodicity, symmetric properties	A model of image degradation/ restoration process, Noise models	Spatial, frequency domain techniques	2D fourier transform relations, Intra frame filtering- LMMSE filtering	Newton Raphson method, Transform coding, 3D waveform coding
	SLO-2	DWT, DCT	Singular value decomposition	Texture based segmentation	Median and weighted median filtering, Motion detection based filtering	Local vs. Global minima, Predictive coding
S- 11 - 12	SLO-1	Lab 3: Image filtering	Lab 6: Singular value decomposition	Lab 9: Repeat/Revision of experiments	Lab 12: Region based image segmentation	Lab 15: Mini project
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> <li>1. Rafael C Gonzalez, Richard E Woods, "Digital Image Processing"- 3rd Edition, Pearson Education 2008.</li> <li>2. Yao wang, Joem Ostarmann and Ya – quin Zhang, "Video processing and Communication ", 1st edition , PHI</li> <li>3. M. Tekalp , "Digital video Processing", Prentice Hall International</li> </ol>	<ol style="list-style-type: none"> <li>4. A.K. Jain, "Fundamentals of Digital Image Processing". Pearson education</li> <li>5. William K Pratt, "Digital Image Processing", John Wiley (2001).</li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. S. Dhanalakshmi, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Mrs. S. Latha, SRMIST



Course Code	18ECE244J	Course Name	DSP SYSTEM DESIGN	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	18ECC204J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	IEEE 1641-2010, IEEE 754, IEEE Standard. 1149.1		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire knowledge on Floating and Fixed point Processor such as TMS320C6X for complex signal	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn and code TMS320C6x Assembly level programming for real time signal processing applications	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Design and coding DSP algorithm such as FFT, DFT, Convolution, IIR and FIR filters in TMS320C6x																		
CLR-4 :	Gain knowledge on advance filter concepts and filter signal noise using Filter Bank, adaptive filters and analyzes such filters for high end designing.																		
CLR-5 :	Design DSP system for real time applications.																		
CLR-6 :	Utilize the concept of DSP for Engineering and Technology																		
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>																			
CLO-1 :	Demonstrate the knowledge on DSP architecture and instruction sets of TMS320C6X	2	75	70	H	-	H	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Review the assembly programming knowledge using TMS320C6x	1	75	70	-	H	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-3 :	Apply the program concepts of DSP algorithm such as FFT, DFT, Convolution, IIR and FIR filters in TMS320C6x	2	75	70	-	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Analyze on Filter Banks and adaptive filters and analyze such filters.	2	75	70	-	H	-	-	H	-	-	-	-	-	-	-	-	L	-
CLO-5 :	Review the knowledge on DSP system design based applications.	1	75	70	-	-	-	-	H	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Apply the concept of DSP for real time applications	2	75	70	-	-	-	-	H	-	-	-	-	-	-	-	-	M	M

Duration (hour)		TMS320C6X Architecture 15	TMS3206X Assembly Language 15	Frequency Transforms 15	Digital Filters 15	DSP Applications 15
S-1	SLO-1	Architecture of TMS320C6X	TMS320C6X Assembly Language Operations	Digital filtering using the DFT	Filter banks – Decimation,	Dual tone Multi-Frequency (DTMF) Signaling
	SLO-2	Pipeline CPU	Individual Instruction Descriptions	Convolution and correlation	Inverse Decimation	Software Defined Radio (SDR)
S-2	SLO-1	VelociTI, Functional Units,	Arithmetic operations, ,	Fast Fourier Transform –DIT	Perfect Reconstruction	QAM Transmitter and QAM Receiver
	SLO-2	Addressing modes,	Logical operations,	Fast Fourier Transform –DIT	Analysis of M-Band filter Banks	Miscellaneous Projects--FSK Modem
S-3	SLO-1	Lab1: Generation of sequences (functional & random) (Matlab)	Lab 7: MAC operation using various addressing modes	Lab 13: Spectrum analysis using DFT(Matlab)	Lab 19: FIR Implementation using TMS Processor	Lab 25: Equalization (Matlab)
	SLO-2	Lab 2: Correlation(Matlab)	Lab 8: MAC operation using various addressing modes	Lab 14: FFT Implementation(DSP processor)	Lab 20: FIR Implementation using TMS Processor	Lab 26: Equalization (Matlab)
S-5	SLO-1	TMS320C6X Instruction Sets,	Memory data operations	Fast Fourier Transform –DIF	Orthogonality and Biorthogonality in Filter banks	U-Law for Speech Companding,
	SLO-2	Assembler directives	Conditional Operations	Fast Fourier Transform DIF	QMF Filter banks and	Acoustic Direction Tracker
S-6	SLO-1	Multichannel Buffered Serial Ports	Floating Point –Data type operations,	IFFT	CQF Filter Banks	MultirateFilter, Neural Network for Signal Recognition
	SLO-2	Memory Considerations –Constraints	Floating Point –Data type operations	FIR filters	Transmultiplexers;	PID Controller, Four-Channel Multiplexer for Fast Data Acquisition
S-7	SLO-1	Lab 3: Linear Convolution (Matlab)	Lab 9: MAC operation using various addressing modes	Lab 15: FIR filter design-Windowing Techniques(Matlab)	Lab 21: IIR implementation using TMS processor	Lab 27: Real time audio signal processing with Processor
	SLO-2	Lab 4 :Circular convolution(Matlab)	Lab 10: Linear convolution(DSP	Lab 16: FIR filter design-Windowing	Lab 22: IIR implementation using TMS	Lab 28: Real time audio signal

	SLO-2		processor)	Techniques(Matlab)	processor	processing with Processor
S-9	SLO-1	Instruction Operation and Execution notations	Fixed- Point Operations,	FIR filters	Structures and Programming Examples for Noise cancellation	Video Line Rate Analysis
	SLO-2	Overview of IEEE Standard single and Double Precision formats ,	Fixed- Point Operations	IIR filter	Adaptive Filters-Adaptive filters in DSP simulation software's and TMS320C6x	DSP System Design
S-10	SLO-1	Q-format Number Representation on Fixed Point DSPs, Finite Word length effects on Fixed point DSPS	Pipeline Operations overview	IIR filter	Software simulation of FIR	MP3 Player
	SLO-2	Floating point number representation, , Overflow and Scaling	Interrupts-overview.	FIR and IIR filter design using TMS320C6x	IIRFilters and Filter banks	DSP Automotive application
S-11	SLO-1	Lab 5: Study of architecture of Digital Signal Processor	Lab 11: Circular convolution(DSP processor)	Lab 17: IIR filter design-Bilinear and Impulse Invariance Technique(Matlab)	Lab 23: Multirate filters	Lab 29: Real time audio signal processing with Processor
	SLO-2	Lab 6: Study of architecture of Digital Signal Processor	Lab 12: Waveform generation(DSP processor)	Lab 18: IIR filter design-Bilinear and Impulse Invariance Technique(Matlab)	Lab 24: Finite Word Length Effect	Lab 30: Real time audio signal processing with Processor

Learning Resources	1. B Venkataramani, M Bhaskar, "Digital Signal Processors: Architecture, Programming and Applications", TMH Publishers, 2nd edition, 2017 2. Paulo S. R.DinizEduardo A. B. da Silva and Sergio L. Netto, "Digital Signal Processing System Analysis and Design", Cambridge University Press, 2nd Edition.2010	3. Nasser Kehtarnavaz, Namjin Kim, "Digital Signal Processing System-Level Design Using LabVIEW", Newgen Elsevier Publication, 2nd edition, 2014 4. RulphChassaing - "DSP Applications Using C and the TMS320C6x DSK" John Wiley & Sons, Inc. 2002. 5. Nasser Kehtarnavaz, "Real-Time Digital Signal ProcessingBased on the TMS320C6000", Newnes, 2005.
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#### Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
Level 2	Apply Analyze	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
Level 3	Evaluate Create	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Total	100 %		100 %		100 %		100 %		-	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	Dr. S. Dhanalakshmi, Assoc. Professor, SRMIST

Course Code	18ECE245T	Course Name	ADAPTIVE SIGNAL PROCESSING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC204J	Co-requisite Courses	Nil	Progressive Courses	18ECE342T
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Have an insight on basics of random processes	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge on the applications of adaptive filters	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Have an introduction on LMS techniques				H	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-4 :	Analyze the types of LMS algorithm				-	M	-	-	-	-	-	-	-	-	-	-	-	-	M
CLR-5 :	Have an introduction on RLS algorithm				-	H	H	-	-	-	-	-	-	-	-	-	-	-	-
CLR-6 :	Understanding on need and design of adaptive filters using different algorithms				-	M	-	-	-	-	-	-	-	-	-	-	-	M	-
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		1	85	70	-	-	H	-	-	-	-	-	-	-	-	-	M	-	-
CLO-1 :	Review the basics of statistical signal processing	1	85	70	-	-	H	-	-	-	-	-	-	-	-	-	M	-	-
CLO-2 :	Understand the need for adaptive filters and learn the design of it.	1	85	70	-	-	H	-	-	-	-	-	-	-	-	-	M	-	-
CLO-3 :	Demonstrate the knowledge on LMS algorithms and constraints associated with it.	2	85	75	-	-	H	-	-	-	-	-	-	-	-	-	M	-	-
CLO-4 :	Determine the variants of LMS algorithm and design of lattice structures	2	85	75	-	-	M	-	-	-	-	-	-	-	-	-	M	-	-
CLO-5 :	Analyze knowledge on design of RLS filters and others aspects of filter design	2	85	75	-	-	M	-	-	-	-	-	-	-	-	-	M	-	-
CLO-6 :	Understand the applications of adaptive signal processing and algorithms in designing the adaptive filters	1	85	75	-	-	H	-	-	-	-	-	-	-	-	-	M	-	-

Duration (hour)		Introduction to Stochastic Process	Adaptive Filters	Least Mean Square Algorithm	Variants of LMS Algorithm And Lattice Structures	Recursive Least Square Algorithm
		9	9	9	9	9
S-1	SLO-1	Introduction to random process	Introduction to adaptive filters	Least mean square algorithm	Sign LMS algorithm	Recursive adaptive filters
	SLO-2	Variables, vectors	Block diagram of adaptive structure with shift variant filter	Derivation	Normalized LMS	Principle of RLS algorithm
S-2	SLO-1	Ensemble averages	Properties of adaptive filter	Properties of LMS adaptive filters	Leaky LMS	FIR RLS filter algorithm
	SLO-2	Time averages	Error sequence generation in adaptive filters	Properties of LMS adaptive filters	Block LMS	Derivation
S-3	SLO-1	Stationarity and Stationary random process	Channel Equalization- Block diagram of Communication system with Channel equalization	Complex LMS algorithm	FFT based implementation of block LMS	Sliding window RLS
	SLO-2	Wide sense stationarity	Echo cancellation	Convergence of LMS algorithm	FFT based implementation of block LMS	Derivation
S-4	SLO-1	Power Spectral Density	Concept of adaptive noise cancelling	Learning curve for adaptive filters	Comparison of variants on LMS for some practical problem	Comparing variants of RLS using MATLAB program
	SLO-2	Properties of PSD	Beam forming with pilot signals	Sample MATLAB program for LMS convergence and plotting learning curve	Comparison of variants on LMS for some practical problem	Comparing variants of RLS using MATLAB program
S-5	SLO-1	Sample problems on WSS random process	System modeling using adaptive filters	Performance analysis of LMS adaptive filters by varying step size (MATLAB)	Lattice filters introduction	Kalman filters
	SLO-2	Sample problems on WSS random process	System Identification structure	Performance analysis of LMS adaptive filters by varying step size (MATLAB)	Advantages of Lattice structures	Kalman filters

S-6	SLO-1	Filtering of random process	System inversion using adaptive filters	Weight error correlation matrix	Forward linear prediction	Sample problems on RLS algorithms
	SLO-2	Filtering of random process	Interference cancellation in multi sensor systems	LMS misadjustment definition	Forward linear prediction	Sample problems on RLS algorithms
S-7	SLO-1	Autocorrelation Structures	Minimization of mean square error	Effects of misadjustment factor	Backward linear prediction	Non linear adaptive filters
	SLO-2	Covariance Structures	Derivation on MMSE	Sample problems for designing adaptive filters using LMS	Backward linear prediction	Introduction to Neural networks
S-8	SLO-1	Eigen value decomposition	Steepest Descent algorithm	Sample problems on step size	Reflection coefficients of forward and backward predictors	Neural networks and multilayer perceptrons
	SLO-2	Eigen value analysis of autocorrelation matrices	Linear prediction example	Sample problems on step size	Relation between forward and backward prediction coefficients	Neural networks and multilayer perceptrons
S-9	SLO-1	Ergodicity	Wiener filters	Stability analysis of LMS algorithms	Properties of Lattice structures	Adaptive IIR filtering
	SLO-2	Ergodic random process	Optimization solution in wiener filters	Stability analysis of LMS algorithms	Updating predictor coefficients	Adaptive IIR filtering

Learning Resources	<ol style="list-style-type: none"> <li>1. S. Haykin, Adaptive Filter Theory, Prentice-Hall, 4-th edition, 2001.</li> <li>2. Ali H. Sayed, Fundamentals of Adaptive Filtering, John Wiley, 2003.</li> <li>3. D. Manolakis, V. Ingle, S. Kogan, Statistical and Adaptive Signal Processing: Spectral Estimation, Signal Modeling, Adaptive Filtering and Array Processing, McGraw Hill, 1999.</li> </ol>	<ol style="list-style-type: none"> <li>4. B. Widrow, S. Stearns, Adaptive Signal Processing, Prentice-Hall, 1985</li> <li>5. Monson H. Hayes, Statistical Digital Signal Processing and Modeling, Edition: 1st, 2008.</li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	Dr. S. Dhanalakshmi, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	



Course Code	18ECE340T	Course Name	MACHINE PERCEPTION WITH COGNITION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECE242J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	<i>Have an insight on image and color fundamentals</i>	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	<i>Analyze the various shapes and regions for the image description</i>	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	<i>Acquire knowledge on the texture analysis of an image</i>				H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	<i>Identify the relation between the templates to match the image requirements</i>				-	H	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-5 :	<i>Know the practical applications of computer vision in images understanding</i>				-	-	-	M	-	-	-	-	-	-	-	-	-	-	M
CLR-6 :	<i>Have an insight on image and color fundamentals</i>				-	-	M	-	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		2	80	75	-	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-1 :	<i>Demonstrate the fundamentals of image and color models</i>	2	85	75	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	<i>Understand the basic shapes and region based image modeling</i>	2	85	70	-	-	-	M	-	-	-	-	-	-	-	-	-	-	M
CLO-3 :	<i>Analyze the various textures for image synthesis</i>	2	85	75	-	-	M	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	<i>Discuss the objects based on template relations</i>	2	85	70	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	<i>Apply the image understanding knowledge for image recognition</i>	2	85	70	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-6 :	<i>Review the principles of image modeling and synthesis with image recognition</i>	2	85	70	-	-	-	M	-	-	-	-	-	-	-	-	M	-	-

Duration (hour)		Learning Unit / Module 1 Basic Audio Processing 12	Learning Unit / Module 2 Human Auditory System 12	Learning Unit / Module 3 Speech Signal Analysis in Time Domain 12	Learning Unit / Module 4 Speech Signal Analysis in Frequency Domain 12	Learning Unit / Module 5 Speech and Audio processing applications 12
S-1	SLO-1	Review of Image processing methods	Binary Shape analysis	Representing textures	Finding objects by voting on relation between templates	Face detection
	SLO-2	Review of Image processing methods	Binary Shape analysis	Representing textures	Interest points, Simple voting, Voting on raltions.	Face detection
S-2	SLO-1	Introduction to image formation	Connectedness	Extracting image Structure with filter banks	Relational reasoning using probabilistic framework	Face recognition
	SLO-2	Introduction to image formation	Object labeling and counting	Extracting image Structure with filter banks	Growing Assemblies Incrementally, Detection, Pruning	Face recognition
S-3	SLO-1	Image models	Size filtering	Representing texture using statistics of filter output	Frames and probability models	Eigen faces
	SLO-2	Camera models	Distance functions	Representing texture using statistics of filter output	Representing coordinate frames	Active appearance
S-4	SLO-1	Sample programs for reading images, understanding pixels	Skeletons and thinning	Analysis using oriented pyramids	Using probability model for detecting the frames	3D shape models of face surveillance
	SLO-2	Sample programs for reading images, understanding pixels	Deformable shape analysis	Laplacian pyramids	Building probability models for frame invariant	3D shape models of face surveillance
S-5	SLO-1	Shadows	Boundary tracking procedures	Filters in the spatial frequency domain	Classifiers to prune search	Foreground separation
	SLO-2	Color representation	Boundary tracking procedures	Filters in the spatial frequency domain	Identifying acceptable assemblies	Background separation

S-6	SLO-1	Human color perception	Shape models	Oriented pyramids	Sample examples for prune search	Particle filters
	SLO-2	Human color perception	Shape recognition	Oriented pyramids	Hidden Markov model	Particle filters
S-7	SLO-1	Image color	Centroidal profiles	Synthesizing textures for rendering	Computing, Maximizing parameters	Champer matching, tracking and occlusions
	SLO-2	Image color	Handling occlusions	Synthesizing textures for Homogeneity	Varieties of HMM	Champer matching, tracking and occlusions
S-8	SLO-1	Handling Color Images (MATLAB)	Boundary descriptors	Synthesis by sampling local models	Background subtraction	Combining views from multiple cameras
	SLO-2	Handling Color Images (MATLAB)	Boundary descriptors	Synthesis by sampling local models	Sample programs on background subtraction	Human gait
S-9	SLO-1	Surface Color	Region descriptors	Shape from texture planes	Hough transform	Constructing 3D models from image sequences
	SLO-2	Surface Color	Region descriptors	Texture from shape planes	Sample problems on Hough transforms	Scene modeling from registered and unregistered images

Learning Resources	<ol style="list-style-type: none"> <li>1. E. R. Davies, "Computer &amp; Machine Vision", Fourth Edition, Academic Press, 2012.</li> <li>2. R. Szeliski, "Computer Vision: Algorithms and Applications", Springer 2011.</li> <li>3. Simon J. D. Prince, "Computer Vision: Models, Learning, and Inference", Cambridge University Press, 2012</li> <li>4. Mark Nixon and Alberto S. Aquado, "Feature Extraction &amp; Image Processing for Computer Vision", Third Edition, Academic Press, 2012</li> <li>5. D. L. Baggio et al., "Mastering OpenCV with Practical Computer Vision Projects", Packt Publishing, 2012</li> <li>6. Jan Erik Solem, "Programming Computer Vision with Python: Tools and algorithms for analyzing images", O'Reilly Media, 2012.</li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE341T	Course Name	MULTIMEDIA COMPRESSION TECHNIQUES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECE240T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Summarize probability models and discuss on coding theory	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Implement lossless compression	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Discuss on Lossy data compression	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Apply the encoding methods	Expected Attainment (%)	Design & Development
CLR-5 :	Carry out the Compression Techniques and their applications		Analysis, Design, Research
CLR-6 :	Summarize probability models and discuss on coding theory		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of	Expected	Expected	Engineering	Problem	Design &	Analysis/	Research	Modern	Society &	Environm	Sustaina	Ethics	Individual	Commun	Project M	Life Long	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Summarize the fundamental concepts of probability model and to state the practical limits specified by coding theory				1,2	85	80	H																L
CLO-2 :	Outline rate-distortion theory and to discuss about efficient information transfer mechanism				2	85	75	H	H	M													L	H
CLO-3 :	Show the fundamental approaches towards lossy image compression				1,2	80	75	H	M	L												M	M	H
CLO-4 :	Analyze image, video and audio in the frequency domain to identify important components to be encoded				2	80	70	H	M	M	H											H	H	H
CLO-5 :	Analyze the Applications of various compression techniques				3	80	70	M	M	L	H											H	L	M
CLO-6 :	Examine various data compression and encoding methods				3	85	80	H	M	M												H	M	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	The discrete memory less information source	Mathematical Preliminaries for Lossless Compression	Rate distortion function	Vector Quantization	Transform Coding: Introduction, Karhunen-Loeve transform, Image compression – EZW, SPIHT, JPEG 2000- Analysis/Synthesis Schemes.
	SLO-2	Kraft inequality; optimal codes	Mathematical Preliminaries for Lossless Compression	Rate distortion function	LBG algorithm	Karhunen-Loeve transform
S-2	SLO-1	Source coding theorem-Entropy	Huffman Coding	Properties of RD	Tree structured VQ	Karhunen-Loeve transform
	SLO-2	Joint Entropy and Conditional Entropy	Huffman Coding	Properties of RD	Structured VQ	Discrete cosine transform,
S-3	SLO-1	Relative Entropy	Optimality of Huffman codes	Calculation of RD for the binary source and the Gaussian source	Variations of VQ	Discrete cosine transform,
	SLO-2	Mutual Information	Extended Huffman Coding	Calculation of RD for the binary source and the Gaussian source	Gain shape VQ	Discrete Walsh Hadamard transform
S-4	SLO-1	Chain Rules	Adaptive Huffman Coding	Rate distortion theorem	Mean removed VQ	Discrete Walsh Hadamard transform
	SLO-2	Data-Processing Inequality	Arithmetic Coding	Rate distortion theorem	Classified VQ	Quantization and coding of transform coefficients
S-5	SLO-1	Fano's Inequality Symmetric Channels	Adaptive Arithmetic coding	Converse of the Rate distortion theorem	Multistage VQ	Quantization and coding of transform coefficients
	SLO-2	Fano's Inequality Symmetric Channels	Run Length Coding	Quantization problem	Adaptive VQ	JPEG
S-6	SLO-1	Properties of Channel Capacity, Jointly Typical Sequences	Dictionary Techniques	Scalar Quantization- Uniform Quantizer	Trellis coded quantization Transforms.	JPEG
	SLO-2	Properties of Channel Capacity, Jointly Typical Sequences	Lempel Ziv coding	Scalar Quantization- Uniform Quantizer	Trellis coded quantization Transforms.	MDCT

S-7	SLO-1	Channel Coding Theorem	Applications	Adaptive Quantization	Basic algorithm	MDCT
	SLO-2	Channel Coding Theorem	Predictive Coding	Adaptive Quantization	Prediction in DPCM	Image compression – EZW-Analysis/Synthesis Schemes
S-8	SLO-1	Fano's Inequality	Prediction with Partial Match	Non-uniform Quantization	Prediction in DPCM	Image compression – SPIHT-Analysis/Synthesis Schemes
	SLO-2	Fano's Inequality	Burrows Wheeler Transform	Non-uniform Quantization	Adaptive DPCM	Image compression – JPEG 2000-Analysis/Synthesis Schemes
S-9	SLO-1	Converse to the Coding Theorem	Dynamic Markov Compression	Entropy coded Quantization	Adaptive DPCM	Audio coding:-MPEG audio coding
	SLO-2	Converse to the Coding Theorem	Dynamic Markov Compression	Entropy coded Quantization	Delta Modulation	Audio coding:-MPEG audio coding

Learning Resources	1. K. Sayood, "Introduction to Data Compression", 3 <sup>rd</sup> Edition, Morgan Kaufmann Publishers, 2006. 2. N. Jayant and P. Noll, "Digital Coding of Waveforms: Principles and Applications to Speech and Video", ISBN10 0132119137, Prentice Hall, USA, 1984. 3. D. Salomon, "Handbook of Data Compression", 5 <sup>th</sup> Edition, Springer-Verlag London Limited 2010.	4. Ze.Nian. Li and M.S. Drew, "Fundamentals of Multimedia", 2 <sup>nd</sup> Edition, Pearson Education (Asia) Pvt. Ltd., 2004. 5. M.Rabbani: "Digital image compression techniques", 1 <sup>st</sup> Edition, SPIE Press Book, 1991.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Mrs. K. Harisudha, SRMIST



Course Code	18ECE342T	Course Name	ACOUSTICAL SIGNAL PROCESSING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECE245T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	ISO/TC 43/SC 1, ISO/TC 43/SC 2		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Discuss physics behind sound equations, characteristics of sound in various mediums.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	2	Problem Analysis	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Describe human auditory system and hearing function.																							
CLR-3 :	Express acoustic echo in a mathematical form, and to control or cancel echo that arises due to using various algorithm.																							
CLR-4 :	Summarize the various types of transducers used for acoustic measurements																							
CLR-5 :	Analysis of transducers for various applications of acoustics.																							
CLR-6 :	Discuss physics behind sound equations, characteristics of sound in various mediums.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Expected Proficiency (%)	Expected Attainment (%)																		
CLO-1 :	Summarize the basics of acoustic and to paraphrase the mechanism like Transmission, Reflection, Absorption under various mediums				1,2	80	80	M	-	-	-													M
CLO-2 :	Explain human auditory system and hearing				1,2	85	75	M	-	-	-												M	H
CLO-3 :	Illustrate acoustic echo, noise control and cancel echo using various algorithms.				2	85	75	H	H	H	-											M	M	H
CLO-4 :	Demonstrate various types of transducers used for acoustic measurements				2	85	80	H	M	M	M											H	M	H
CLO-5 :	Outline on the various applications of acoustics.				2,3	85	70	H	-	-	H											H	M	M
CLO-6 :	Outline speech processing analysis in different environment				2	85	80	H	M	H	H	H										H	H	M

Duration (hour)		Basics of Acoustic Engineering	Auditory System and Hearing	Acoustic Echo and Noise control	Transducers for Acoustic Measurements	Applications of Acoustics
		9	9	9	9	9
S-1	SLO-1	Introduction to acoustic	Anatomy of the auditory systems	Human Perception of Echoes	Fundamental properties of Transducers	Architectural acoustics – Sound in enclosures
	SLO-2	Introduction to acoustic	Anatomy of the auditory systems	Human Perception of Echoes	Fundamental properties of Transducers	Reverberation time
S-2	SLO-1	Harmonic Plane Waves	Physiology of the auditory systems	Echo Problem	Condenser Microphones	Sound absorption materials
	SLO-2	Harmonic Plane Waves	Physiology of the auditory systems	Echo Problem	Condenser Microphones	Measurements of acoustic output in living rooms
S-3	SLO-1	Energy Density	Function of the auditory systems	Adaptive Filters for Echo Cancellation	Dynamic Pressure Microphones	Acoustic Factors in architectural design
	SLO-2	Energy Density	Function of the auditory systems	Adaptive Filters for Echo Cancellation	Dynamic Pressure Microphones	Environmental acoustics – Introduction
S-4	SLO-1	Acoustic Intensity	Physiological measures	LMS algorithm	Dynamic Pressure Microphones	Weighted sound level
	SLO-2	Specific Acoustic Impedance	Physiological measures	NLMS algorithm	Dynamic Pressure difference Microphone	Speech interference
S-5	SLO-1	Spherical Waves	Physiological measures	Least Squares Algorithms	Dynamic Pressure difference Microphone	Highway noise
	SLO-2	Spherical Waves	Auditory processing models	Least Squares Algorithms	Piezo ceramic accelerometer	Aircraft noise rating
S-6	SLO-1	Decibel Scales	Auditory processing models	Recursive Least Squares Algorithms	Piezo ceramic accelerometer	Virtual Sound--
	SLO-2	Rays and Waves	Auditory processing models	Recursive Least Squares Algorithms	Piezo ceramic accelerometer	Sound localization cues
S-70	SLO-1	Transmission-Incidence	Auditory processing models	Affine Projection algorithm	Laser Doppler velocimeter	Synthetic 3D Audio
	SLO-2	Transmission-Incidence	Auditory processing models	Affine Projection algorithm	Laser Doppler velocimeter	Synthetic 3D Audio
S-8	SLO-1	Reflection	Speech Intelligibility	Noise cancellation using Affine Projection algorithm	Laser Doppler velocimeter	Seismology- Signal Model in seismic processing

	SLO-2	Absorption	Speech Intelligibility	Noise cancellation using Affine Projection algorithm	Capacitive sensors	Optical sensor Signal Model in seismic processings
S-9	SLO-1	Viscosity	Signal processing in hearing aids	Fast Affine Projection Algorithm (FAP).	Capacitive sensors	Underwater and Oceanographic acoustics
	SLO-2	Thermal conduction	Signal processing in hearing aids	Fast Affine Projection Algorithm (FAP)	Capacitive sensors	Inverse Problems in underwater acoustics

Learning Resources	1. Lawrance E Kinseler, <i>Fundamental of Acoustic</i> , Wiley 4 <sup>th</sup> Edition. 2. Steven L. Gay, Jacob Benesty, <i>Acoustic Signal Processing for TeleCommunication</i> , Springer; 2001 edition (March 31, 2000)	3. Havelock, David; Kuwano, Sonoko, Vorländer, Michael (Eds.), <i>Handbook of Signal Processing in Acoustics</i> , Springer; 2008 edition.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	--	30 %	--	30 %	--	30 %	--	30 %	--
	Understand										
Level 2	Apply	40 %	--	40 %	--	40 %	--	40 %	--	40 %	--
	Analyze										
Level 3	Evaluate	20 %	--	30 %	--	30 %	--	30 %	---	30 %	--
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Code	18ECE343T	Course Name	AUTOMATIC SPEECH RECOGNITION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECE241J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Summarize the basic Techniques of Speech Recognition				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3
CLR-2 :	Analyze the different Statistical models					Expected Proficiency (%)																	
CLR-3 :	Model different speech recognition systems					Expected Attainment (%)																	
CLR-4 :	Illustrate of dialogue system design																						
CLR-5 :	Analyze the Stochastic Approaches to dialogue																						
CLR-6 :	Utilize the concepts in signal processing for the understanding of engineering and technology																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Express the basic techniques in speech signal processing broadly used in the area of speech recognition				2	75	60	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	M
CLO-2 :	Outline the use of hidden Markov models can be used as generative models for speech and how they can be trained				2	75	60	H	M	-	-	-	-	-	-	-	-	-	-	M	-	H	
CLO-3 :	Describe commercial as well as research-oriented applications within speech recognition				2	75	60	H	-	-	H	-	-	-	-	-	-	-	-	M	L	M	
CLO-4 :	Summarize the essentials of dialogue system design and evaluation				2	75	60	H	H	M	-	-	-	-	-	-	-	-	-	M	M	M	
CLO-5 :	Implement simple dialogue systems and Stochastic Approaches				2	75	60	H	-	H	-	-	-	-	-	-	-	-	-	M	M	H	
CLO-6 :	Apply the speech recognition techniques in real time applications.				2	75	60	H	-	-	-	-	-	-	-	-	-	-	-	H	L	M	

Duration (hour)		Distance Measurements For Comparing Speech Patterns	Statistical Models For Speech Recognition	Architecture of Continuous Speech Recognition System	Understanding of Spoken Dialogue Systems	Natural Language Generation and Stochastic Process
		9	9	9	9	9
S-1	SLO-1	Feature, Feature Extraction and Pattern Comparison Techniques	Introduction to Perceptual Motivated Representations	Introduction to speech recognition	Simple models of dialogue structure:	Natural language generation for dialogue systems
	SLO-2	Feature, Feature Extraction and Pattern Comparison Techniques	Perceptual Motivated Representations	Introduction to speech recognition	Simple models of dialogue structure:	Natural language generation for dialogue systems
S-2	SLO-1	Speech Distortion measures-Mathematical	Formant Frequencies – Role of Pitch – Pitch Detection of Speech and Music	Large vocabulary continuous speech recognition	Trees and finite state approaches	Text-to-speech synthesis
	SLO-2	Speech Distortion measures-Mathematical	Formant Frequencies – Role of Pitch – Pitch Detection of Speech and Music	Large vocabulary continuous speech recognition	Trees and finite state approaches	Text-to-speech synthesis
S-3	SLO-1	Perceptual-Log spectral distance	Channel Vocoders and Predictive Coding Scalar Waveform Coders	Architecture of large vocabulary continuous speech recognition system	Dialogue acts, key phrase reactive approaches	Use of speech synthesizers in dialogue systems
	SLO-2	Perceptual-Log spectral distance	Channel Vocoders and Predictive Coding Scalar Waveform Coders	Architecture of large vocabulary continuous speech recognition system	Dialogue acts, key phrase reactive approaches	Use of speech synthesizers in dialogue systems
S-4	SLO-1	Cepstral Distances, Weighted Cepstral distances and Filtering	Scalar Frequency Domain Coders	Architecture of large vocabulary continuous speech recognition system	Information retrieval-based approaches	Dialogue system evaluation
	SLO-2	Likelihood Distortions	Code excited linear Prediction	Architecture of large vocabulary continuous speech recognition system	Information retrieval-based approaches	Dialogue system evaluation
S-5	SLO-1	Spectral distortion using a Warped Frequency scale	Low – Bit rate Speech coders Speech Recognition	Acoustics model	Voice XML	Stochastic approaches to dialogue
	SLO-2					

S-6	SLO-1	LPC, PLC and MFCC Coefficients	Hidden Markov Models (HMM) – Practical Issues in Using HMMs – HMM Limitations	Language model	Speech recognition	Dialogue policy design and training
	SLO-2	LPC, PLC and MFCC Coefficients	Hidden Markov Models (HMM) – Practical Issues in Using HMMs – HMM Limitations	Language model	Speech recognition	Dialogue policy design and training
S-7	SLO-1	Time Alignment and Normalization	Acoustic Modeling – Phonetic Modeling, Language Modeling	N-gram model	Use of speech recognizers in dialogue systems	MDP reinforcement learning
	SLO-2	Time Alignment and Normalization	Acoustic Modeling – Phonetic Modeling, Language Modeling	N-gram model	Use of speech recognizers in dialogue systems	MDP reinforcement learning
S-8	SLO-1	Dynamic Time warping	Speaker Recognition Algorithm	Context dependent sub word units	Natural language understanding	POMDP reinforcement learning
	SLO-2	Dynamic Time warping	Speaker Recognition Algorithm	Context dependent sub word units	Natural language understanding	POMDP reinforcement learning
S-9	SLO-1	Multiple Time-Alignment Paths	Signal Enhancement for Mismatched Conditions	Applications and present status	Natural language understanding	Simulated users
	SLO-2	Multiple Time-Alignment Paths	Signal Enhancement for Mismatched Conditions	Applications and present status	Natural language understanding	Simulated users

Learning Resources	<ol style="list-style-type: none"> <li>Huang, A. Acero, H-W. Hon, "Spoken Language Processing: A guide to theory, algorithm and system development", Prentice Hall 2001</li> <li>Rabiner and Juang, "Fundamentals of Speech Recognition", Prentice Hall, 1993</li> <li>F. Jelinek, "Statistical Methods for Speech recognition", MIT Press, 1997</li> </ol>	<ol style="list-style-type: none"> <li>Jurafsky, Daniel, and James H. Martin, "Speech and Language Processing: An Introduction to Natural Language Processing, Speech Recognition, and Computational Linguistics", 2nd edition. Prentice-Hall, 2009.</li> <li>Jokinen and McTear, "Spoken Dialogue Systems, Morgan &amp; Claypool, Synthesis Lectures on Human Language Technologies", Morgan &amp; Claypool Publishers, 2009</li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	1. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	1. Dr. S. Dhanalakshmi, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	2. Mrs. K. HariSudha, SRM IST



Course Code	18ECE360T	Course Name	REHABILITATION ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Learn concepts and terminologies in Rehabilitation Engineering				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand different types of wheel chair design and mobility aids				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Study the components of orthotic and prosthetic devices and their fabrication																					
CLR-4 :	Become aware of Engineering concepts in sensory substitution and augmentation																					
CLR-5 :	Understand the legal concepts in Rehabilitation Engineering																					
CLR-6 :	Study the contemporary topics in Rehabilitation Engineering																					
Course Learning Outcomes (CLO):								At the end of this course, learners will be able to:														
CLO-1 :	Understand the need for rehabilitation Engineering and proficiently use terminologies related to it.				1,2	80	70						M						L	L		
CLO-2 :	Know the various wheel chair design and mobility aid design aspects				1,2	75	65	M		L			L							L	L	
CLO-3 :	Learn about orthotic and prosthetic devices, their design and types.				2	70	65	L		L				L						L		
CLO-4 :	List the various possibilities to augment or substitute visual and auditory capabilities				2,3	70	65	M	M	L			L								L	
CLO-5 :	Describe the legal concepts in Rehabilitation Engineering				3	80	65						M	M								L
CLO-6 :	Gain exposure to the latest topics in Rehabilitation Engineering				3	80	65	M	L	L	M		L							L	M	L

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduce to Rehabilitation Engineering and Assistive technologies	Interventions in seating system	Amputation: Definition, need, situations where it can be avoided	Basic structure of eye, How it functions, problems that can be faced	Application of robots in rehabilitation
	SLO-2	Learn Concepts of Rehabilitation Engineering	Wheel Chairs-Introduction	Classification of amputation	Categories of visual impairment, identification of level of intervention needed	Types of robots used
S-2	SLO-1	Learn Terminologies Rehabilitation Engineering	Types of Wheelchairs	Prosthetics: Definition, Need for prosthesis	Artificial Eye-Complete replacement	Challenges in robot design for differently abled people
	SLO-2	Considerations for Rehabilitation Engineering	Describe on Manual wheelchairs	Use of prosthesis, Where prosthesis can't be used	Retinal implant	Differences in material used
S-3	SLO-1	Various approaches for Rehabilitation engineering	Component Design	Basic types of prosthesis, Prosthesis Prescription	Sensory augmentation for blind	Functional electrical stimulation definition,
	SLO-2	PAD process	Electrical Power wheel chairs	Prosthesis for shoulder, neck, torso	Cortical prosthesis	Circuit for stimulations
S-4	SLO-1	PHAATE model	Power assisted wheelchair-Design	Prosthesis for elbow, arm	Assist devices for visual rehabilitation	Significance of myoelecticl signal
	SLO-2	Universal design- Introduction	Design types	Fabrication and issues involved	Auditory devices	Acquisition of myoelecticl signal, challenges
S-5	SLO-1	Seven Principles of Universal design	Wheelchair transportation	Parts of Lower extremity	Devices for navigation, Design of navigation device	Activities of daily living
	SLO-2	Benefits of Universal design	Lift Mechanism	Significance of each part, Different movements involved	Tactual sensory substitution, Applications and examples of tactual substitution in real life	Low tech and hi tech aids in daily living

S-6	SLO-1	Universal design Matrix	Wheelchair safety	Prosthesis for knee, hip	Main part of ear, Measurement of hearing	Neural engineering
	SLO-2	Design based on human ability	Wheelchair standards and tests	Material used for fabrication, examples of available prosthesis	Problems that can arise, Range of hearing	Implementation in rehabilitation
S-7	SLO-1	Standards for assistive technology-National and International	Intelligent Mobility aids	Orthosis: Definition, Difference between orthosis and prosthesis	Surgical hearing aids	Behavioural disorders and its types
	SLO-2	Role of Rehabilitation Engineering in standards development	Smart wheeled walkers	Orthosis for shoulder, neck	Cochlear and eardrum interventions	Rehabilitation methods involves
S-8	SLO-1	Rehabilitation Engineering and its research opportunities	All terrain wheelchair	Orthosis for foot, Material used: the problems faced with the material	Non surgical hearing aids	Sports rehabilitation
	SLO-2	Future of Engineering in Rehabilitation	Current directions in wheelchair research	Components of lower limb prosthesis	Design of a simple external hearing aid	Measurement technology for sports mechanics
S-9	SLO-1	Seating and common pathologies	Parts of Upper extremity	External circuitry design and support system	Sign language	Legal aspect in rehabilitation
	SLO-2	Seating assessment	Significance of each part, Different movements involved	Identifying the orthosis and prosthesis which can be used Practice session: student to identify the area of amputation and what to use in that location	Devices for sign language translation	Provision for rehabilitation

Learning Resources	<ol style="list-style-type: none"> <li>1. Rory A Cooper, Hisaichi Ohnabe, Douglas A Hodson, "An Introduction to Rehabilitation Engineering", CRC Press, First edition, 2006</li> <li>2. Rory A Cooper, "Rehabilitation Engineering Applied to Mobility and Manipulation", CRC Press, First edition, 2010</li> <li>3. Horia-Nicolai.L. Teodorescu, Lakshmi.C. Jain, "Intelligent Systems and Technologies in Rehabilitation Engineering", CRC Press, First Edition, 2010.</li> </ol>	<ol style="list-style-type: none"> <li>4. Marion A Hersh, Michale A Johnson, "Assistive Technology fo Visually impaired and blind people", Springer Publications, First edition 2008.</li> <li>5. Suzanne Robitaille, "The illustrated guide to Assistive technology and devices-Tools and gadgets for living independently", Demos Health Newyork, First edition, 2010.</li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers			
Experts from Industry		Experts from Higher Technical Institutions	
1. Sathyanarayanan J, Mindray Medical India Pvt Ltd, sathyanarayananjayagopal@mindray.com		1. Dr. S. Poonguzhali, Anna University, poongs@annauniv.edu	
2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com		2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	
		Internal Experts	
		1. Dr. Varshini karthik, SRMIST	
		2. Mrs. A. Bhargavi haripriya, SRMIST	

Course Code	18ECE361T	Course Name	BIOMEDICAL NANOTECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
		1	2	3	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-1 :	Learn the different synthesis method and its application	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-2 :	Apply the various characterization techniques in nano materials				M	-	-	L	-	-	-	-	-	-	-	-	-	-	L	-	L	
CLR-3 :	Comprehend the principles behind nanomedicine				L	-	-	L	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLR-4 :	Gain a broad understanding of concepts and applications of nanomedicine				M	-	-	M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLR-5 :	Apply concepts of nanomedicine to a focused clinical area of their choice				M	-	-	M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLR-6 :	Acquire knowledge to apply these nanosystems for the diagnosis and therapy.				M	-	-	M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Analyze the suitable method in biomedical application	3	80	75																		
CLO-2 :	Identify the various characterization techniques in nano materials	3	80	70																		
CLO-3 :	Describe the properties and techniques in nano biomaterials	3	75	70																		
CLO-4 :	Analyze the concept of nano therapeutics and application in biomedical	3	80	75																		
CLO-5 :	Identify the principle behind modern bio nano imaging techniques	3	80	70																		
CLO-6 :	Apply the nano materials in 3D printing techniques	3	80	70																		

Duration (hour)		Synthesis of nano material	Nano materials characterization techniques	Nano biomaterials	Nano therapeutic	Nano biomedical imaging and 3D Bio printing techniques
		9	9	9	9	9
S-1	SLO-1	Introduction About Nano technology	Introduction to Scanning electron microscope(SEM)	Introduction to nano biomaterials	Drug to delivery to central nervous system	Introduction to biomedical imaging
	SLO-2	Bulk synthesis:	Application of scanning electron microscope	Surface and bulk properties of biomaterials	Drug delivery across blood brain barrier	The emergence of nanoparticle as imaging platform in medicine
S-2	SLO-1	Top down and bottom approaches	Energy dispersive spectroscopy (EDS)	Nano biomaterials, Nano bio ceramics	Nano wire monitoring the brain activity	Magnetic resonance imaging basics
	SLO-2	Physical vapour deposition methods	Basics principle of atomic microscopy	Hydroxyapatite ant its properties	Introduction to Nano robot medical device	MRI working ,paramagnetic contrast agents
S-3	SLO-1	Electron beam evaporation techniques	Construction, working and application of atomic microscopy	Hydroxyapatite ant its applications	Application of Nano robot medical device	Magnetic Nano sensor
	SLO-2	Pulsed laser deposition	Introduction to transmission electron microscopy	Alumina and its properties ,application	Introduction to nano drug carrier	Radio labeled nano particles.
S-4	SLO-1	Sputtering techniques	Application of transmission electron microscopy	Zirconia and Titania and its properties	Nano carrier for ocular drug delivery	Sound waves nano particle
	SLO-2	Evaporation techniques	Scanning probe microscope	Zirconia and Titania ant its applications	Cell therapy for myocardial infection	Application in ultra sound imaging
S-5	SLO-1	Cathodic arc deposition	Nano indentation techniques	Nano diamond carbon nano materials	Types of cell therapy for myocardial infection	Biological imaging
	SLO-2	Spin coating unit, spray pyrolysis	Cantilever array sensor	Nano diamond carbon materials and its applications.	Nano neurosurgery,	Quantum dot in optical imaging

S-6	SLO-1	Chemical vapor deposition(CVD)	Basics principle of scanning tunneling microscopy	Introduction to surface modification	Nanolipoblockers	3D printing
	SLO-2	Types of chemical vapour deposition	Constriction and application of scanning tunneling microscope(STM)	Types of surface modification method	Antirestenosis drugs	Introduction and principle
S-7	SLO-1	Plasma method: Plasma enhanced CVD	Introduction about X-ray diffraction	Textured and porous materials	Introduction to nano particle drug formulations	3D printing technology :ink let based
	SLO-2	Hot filament CVD	Measurement and application of XRD	Cell biomaterials interactions	Nano particle drug formulations for spray inhalations	Pressure assisted, laser assisted
S-8	SLO-1	Chemical synthesis: Sol gel processing	X-ray photon spectroscopy(XPS)	Immune response	Introduction to nano bone implants	Solenoid valve based, acoustic jet based
	SLO-2	Hydrothermal,co precipitation,	Application XPS	Bone Scaffold preparations	Nano bone implants and scaffolds	3D bio printing in ceramics ,polymers
S-9	SLO-1	Wet chemical method	Electrochemical work station	Scaffold properties and its applications	Introduction to nano technology in cardio vascular system	3D bio printing in organs
	SLO-2	Hydrolysis ,Electrophoretic deposition	Application of electrochemical work station	In vitro and in vivo tissue biocompatibility	Regeneration of cardiovascular system	Challenge and future development of 3D bio printing

Learning Resources	1. Khandpur R.S, Hand-book of Biomedical Instrumentation, 2 <sup>nd</sup> ed., Tata McGraw Hill, 2003 2. Michael Giersig, Gennady B. Khomutov, "Nanomaterials for Application in Medicine and Biology", Springer, 2008 3. Jeff W.M., Bulte and Michel M.J. Modo "Nanoparticles in Biomedical Imaging Emerging Technologies and Applications", Springer, 2010 4. Guozhong Cao, "Nanostructures and Nanomaterials, synthesis, properties and applications", Imperial College Press, 2004 5. C. N. Rao, A. Muller, A. K. Cheetham "The Chemistry of Nanomaterials: Synthesis, Properties and Applications", Wiley, 2004
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Dr. D. Ashok Kumar, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	



Course Code	18ECE362T	Course Name	PHYSIOLOGICAL MODELING AND SIMULATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Build an engineering model based on physiological subsystems				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Implement static analysis for physiological systems				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand time domain and stability analysis of physiological systems																					
CLR-4 :	Implement frequency response analysis for physiological systems																					
CLR-5 :	Identify and estimate unknown parameters in system modeling																					
CLR-6 :	Represent the working of physiological systems using different modeling techniques																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	M	-	-	-	-	-	-	-	-	-	-	M	-	-	
CLO-1 :	Develop a more in-depth level of understanding engineering analysis for modeling physiological systems				1,2	80	70	-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-2 :	Perform static analysis of a system				1,2	80	70	-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-3 :	Perform transient and stability analysis of a system.				1,2	80	70	-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-4 :	Able to do frequency analysis of the system				1,2	80	70	-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-5 :	Understand and implement system identification techniques				1,2	80	70	-	L	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-6 :	Implement the various mathematical modeling techniques to physiological systems				1,2	80	70	M	-	-	-	-	-	-	-	-	-	-	-	M	-	-

Duration (hour)		Linear Model 9	Static Analysis 9	Time Domain Analysis 9	Frequency Domain Analysis 9	System Identification 9
S-1	SLO-1	Introduction to modeling methodology, need for models, approaches to modeling	Static analysis: Open loop versus closed loop	Introduction to time domain analysis	Frequency response: Open loop frequency response	Identification of physiological control system
	SLO-2	Model identification, model validation and Simulation	Loop gain calculation: Room temperature control	Linearized respiratory mechanics transient response	Closed loop frequency response	Basic problems in Physiological system analysis
S-2	SLO-1	System analysis, fundamental concepts	Steady state characteristics	Linearized respiratory mechanics first order model – impulse response for open loop	Relation between transient and frequency response	Nonparametric and parametric identification methods
	SLO-2	Physiological control system an example	Determination of steady state operating point for simple model of muscle stretch reflex	Linearized respiratory mechanics first order model – impulse response for closed loop	Frequency domain specifications	Numerical Deconvolution, Least square estimation
S-3	SLO-1	Engineering control system versus physiological control system	Human body Glucose – Insulin regulatory system	Transient response descriptors : Impulse response	Graphical representation of frequency response: Bode plot	Estimation using correlation functions
	SLO-2	Science of modeling	Steady state analysis of glucose –insulin model	Transient response descriptors : Step response	Bode plot :Linearized lung mechanics	Estimation in frequency domain, optimization techniques
S-4	SLO-1	Generalized system properties	Human body chemical regulation of ventilatory system	Concept of sliding theory	Graphical representation of frequency response: Nicholas chart	Problems in parameter estimation
	SLO-2	Models with combinations of system elements	Mechanism of respiration	Neuromuscular reflex action	Nicholas chart : Linearized lung mechanics	Input design
S-5	SLO-1	Linear model of respiratory mechanics	Gas exchanger mathematical modeling	Mathematical model of neuromuscular	Graphical representation of frequency	Identification of closed loop systems –

				reflex motion	response : Nyquist plot	"opening the loop"
	SLO-2	Linear model of respiratory mechanics: Derivation of transfer function	Respiratory controller mathematical modeling	Calculation of transfer function	Nyquist plot: Linearized lung mechanics	Starling heart- lung preparation
S-6	SLO-1	Linear model of muscle mechanics	Closed loop analysis : lung and controller	Stability and transient response	Introduction : Circulatory system	Kao's cross – circulation experiment
	SLO-2	Linear model of muscle mechanics: Derivation of transfer function	Calculation of transfer function	Root locus and Routh-Hurwitz stability criterion	Mathematical model of circulatory system	Artificial brain perfusion for partitioning central and chemo reflexes
S-7	SLO-1	Distributed versus lumped parameter model	Heart and systemic circulation	Stability analysis: root locus method	Frequency response of circulatory system	Voltage clamp
	SLO-2	Distributed versus lumped parameter model: Derivation of transfer function	Mathematical modeling of cardiac output	Introduction to Nyquist plot	Graphical representation for frequency response of circulatory system	Opening the Pupillary reflex loop, Read rebreathing technique
S-8	SLO-1	Linear system and superposition principle	Calculation of transfer function for simplified model of cardiac output regulation	Nyquist criterion for stability	Frequency response of glucose – insulin model	Identification under closed loop condition
	SLO-2	Laplace transform and transfer function	Cardiac characteristics curve analysis	Relative stability theory	Mathematical model and simulation of glucose – insulin model	Minimal model of blood glucose regulation
S-9	SLO-1	Impulse function analysis	Venous return curve	Physiology: Pupillary reflex control	Frequency response approach to pupil control	Optimization : Introduction
	SLO-2	Basics of Linear convolution	Closed loop analysis of heart and systemic circulation	Mathematical modeling and stability analysis of pupillary reflex control	Frequency response characteristics curve for pupillary control	Optimization in systems with negative feedback

Learning Resources	<p>1. Michael C.K. Khoo, "Physiological Control Systems - Analysis, Simulation and Estimation", Prentice Hall of India Private Ltd., 2<sup>nd</sup> edition, New Delhi, 2001.</p> <p>2. V.Z. Marmarelis, "Advanced Methods of Physiological System Modeling", Vol.3, Springer Science and Business Media, 2013.</p>	<p>3. Claudio Cobelli Ewart Carson., "Introduction to Modeling in Physiology and Medicine", Academic press series, 1<sup>st</sup> edition, 2008.</p> <p>4. Johnny T. Ottesen, Mette S. Olufsen, Jesper K. Larsen, "Applied Mathematical Models in Human Physiology", Vol.9, SIAM, 2004.</p> <p>5. Dorf, "Modern Control Systems", Pearson Education India, 1<sup>st</sup> edition, 2008</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers															
Experts from Industry				Experts from Higher Technical Institutions					Internal Experts						
1. Sathyanarayanan J, Mindray Medical India Pvt Ltd, sathyanarayananjayagopal@mindray.com				1. Dr. S. Poonguzhali, Anna University, poongs@annauniv.edu					1. Dr. T.Jayanthi, SRMIST						
2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com				2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu					2. Mrs.G.Anitha, SRMIST						
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com				3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in											
Course Code	15EC363J	Course Name	MEDICAL IMAGE PROCESSING					Course Category	E	Professional Elective		L	T	P	C

								2	0	2	3
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Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		Learning			Program Learning Outcomes (PLO)																	
		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
CLR-1 :	Understand the fundamental image operations and image transforms	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-2 :	Apply various image enhancement techniques in enhancing the medial images				M																	
CLR-3 :	Analyze the various types of image segmentation algorithms				M																	
CLR-4 :	Gain knowledge in Image compression and image registration methods						M		M											M		L
CLR-5 :	Understand the image reconstruction techniques used in reconstruction of medical images								M													
CLR-6 :	The learner gains knowledge in Image retrieval and digital image watermarking				M																M	
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Describe the 2D Sampling theory and different types of image transforms	1, 2	80	70																		
CLO-2 :	Implement the image enhancement techniques for improving the quality of medical images	2	80	70																		
CLO-3 :	Apply the different image segmentation algorithms for various medical applications	2	80	70																		
CLO-4 :	Differentiate and analyze the various image compression and registration algorithms	3	80	70																		
CLO-5 :	Analyze the various image reconstruction methods used for medical images	3	80	70																		
CLO-6 :	Illustrate the concepts of wavelet transform and digital image water marking	3	80	70																		

Duration (hour)		Fundamental Image Operations and Transforms	Image Enhancement methods	Image Segmentation Algorithms	Image compression and image registration methods	Image Reconstruction Methods
		12	12	12	12	12
S-1	SLO-1	Elements of Visual Perception- structure of human eye and image formation	Basic gray level transformation- image negative, intensity slicing techniques	Morphological operations-Erosion	Image compression-Introduction	Image reconstruction from projections- Radon transform- derivation
	SLO-2	Brightness range adaptation and discrimination	Contrast stretching, dynamic range compression and bit plane slicing	Dilation	Types of redundancies	Properties
S-2	SLO-1	Image sampling-2D sampling Theory	Histogram equalization	Image opening	Huffman coding technique	Inverse radon transform- convolution back projection
	SLO-2	Reconstruction from its samples	Histogram specification	Image closing	Procedure	Filter back projection
S 3-4	SLO-1	Lab1: Basic operations on images	Lab4: Gray transformation and histogram equalization	Lab 7: Morphological operations	Lab 10: Image compression	Lab 13: Image reconstruction from projection data
	SLO-2					
S-5	SLO-1	Quantization- optimal mean square quantizer	Image smoothening in spatial domain – Low pass filter	Edge detection- Marr hildreth edge detector	Image registration- Introduction	Digital implementation of filter back projection- Block diagram
	SLO-2	Uniform quantizer	Median filter	Algorithm	Dimensionality transformation	Algorithm
S-6	SLO-1	Neighborhood pixel relationships-adjacencies	Image sharpening in spatial domain –High pass filter, high boost filter	Canny edge detection- smoothing	Rigid registration algorithm	Wavelet transform-Introduction
	SLO-2	Distance measures	Derivative filters	Non maxima suppression and thresholding	Rigid registration algorithm	Algorithm
S 7-8	SLO-1	Lab2: Image transforms in spatial domain	Lab 5: Image smoothening using suitable filters	Lab 8: Edge detection techniques	Lab 11: Image registration	Lab 14: Wavelet transform
	SLO-2					
S-9	SLO-1	Image transform –DFT, DCT	Image smoothening in frequency domain	Thresholding –basics	Registration of MRI and PET images	Digital image watermarking-Introduction

	SLO-2	Properties	Image sharpening in frequency domain	Global thresholding algorithm	Clinical applications	Applications
S-10	SLO-1	Haar Transform	Color image processing-Introduction	Region based segmentation-region growing algorithm	Registration of MRI and CT images	Image retrieval-Introduction
	SLO-2	Properties	Color models	Region splitting and merging algorithm	Clinical applications	Content based image retrieval
S	SLO-1	Lab3: Image transforms in frequency domain	Lab 6: Image sharpening using suitable filters	Lab9: Image segmentation using Thresholding	Lab 12: Fusion of MRI and CT images	Lab 15: Digital image watermarking
11-12	SLO-2					

Learning Resources	1. Rafael C., Gonzalez and Richard E. Woods, "Digital Image Processing", Pearson Education Asia, Third Edition, 2007 2. Anil.k.Jain, "Fundamentals of Digital image processing", Prentice Hall of India, 2 <sup>nd</sup> edition 1997.	3. Joseph V.Hajnal, Derek L.G.Hill, David J Hawkes, "Medical image registration", Biomedical Engineering series, CRC press,2001.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Sathyanarayanan J, Mindray Medical India Pvt Ltd, sathyanarayananjayagopal@mindray.com	1. Dr. S. Poonguzhali, Anna University, poongs@annauniv.edu	1., Dr. U. Snehalatha, SRMIST
2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anil@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Dr. D. Ashok kumar, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	



Course Code	18ECE364T	Course Name	BODY AREA NETWORK AND MOBILE HEALTHCARE	Course Category	E	Professional Elective				L	T	P	C
										3	0	0	3

Pre-requisite Courses	18ECC205J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering				
	Data Book / Codes/Standards				

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Comprehend technical information and challenges in WBAN.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Describe the hardware requirements of BAN				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Review the wearable sensors and standards for BAN																					
CLR-4 :	Describe the mobile devices that is available for health care																					
CLR-5 :	Summarize the possible and latest applications of mobile healthcare																					
CLR-6 :	Learn about context-aware health care applications																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)															
CLO-1 :	List out the BAN challenges																					
CLO-2 :	Identify the hardware necessary for BAN																					
CLO-3 :	List and describe the various wearable sensors																					
CLO-4 :	Appreciate the mobile devices available for healthcare																					
CLO-5 :	List the latest applications and research opportunities with mobile healthcare.																					
CLO-6 :	Think about context-aware health care solutions				1	80	75															
					1,2	80	75	L											L			
					1,2	80	75	L														
					2	80	75														L	
					3	80	75															M

Duration (hour)		9	9	9	9	9
S-1	SLO-1	BAN-Definition	Processor in BAN	RF Communication	Sensors for wearable system	Mobile health technologies
	SLO-2	Terminologies used with BAN	Low Power MCUs	RF Communication in and around the body	Wearable system design for specific applications	Mobile nutrition tracking
S-2	SLO-1	Technical Challenges	Mobile Computing MCU	Antennal Design	Wearable system for ECG monitoring,	Accessing existing virtual electronic patient record
	SLO-2	Sensor design concepts	Integrated processor	Antenna testing	Wearable system for EEG monitoring,	Mobile personal health records,
S-3	SLO-1	Types of sensors	Radio transceiver along with the processor	Propagation issues	Wearable system for Gait analysis	Monitoring hospital patients,
	SLO-2	Biocompatibility issues	Integrated processor with Memory	Base Station considerations	Evaluation of general performance	Sensing vital signs
S-4	SLO-1	Energy Requirements	Antenna for BAN	Network topology	Evaluation of night time performance	Transmission using wireless networks
	SLO-2	Energy supply	Antenna Requirements	Stand – Alone BAN	Evaluation parameters	Continuous monitoring
S-5	SLO-1	Nodes, number of node	Antenna Considerations	Wireless personal Area Network	Latest health monitoring methods	Patient Monitoring and wearable devices
	SLO-2	Optimal node placement in BAN	Types of antenna	Wireless personal Area Network Technologies	Smart phone based health care monitoring system	Patient Monitoring in Diverse Environments
S-6	SLO-1	System security	Wire antenna	IEEE 802.15.1	Phone based fall risk prediction	A framework for Capturing Patient Consent in Pervasive Healthcare Applications
	SLO-2	System Reliability	Ceramic antenna	IEEE P802.15.13	Emergency alerts	M-health application
S-7	SLO-1	BAN Standards	External antenna	IEEE 702.15.14	RFID based personal mobile medical assistance	Context aware sensing

	SLO-2	BAN with other standards	Sensor Interface	Zigbee	Other similar technologies	Technology Enablers for context-Aware healthcare Applications
S-8	SLO-1	BAN Architecture	Considerations on the interface	BAN and WBAN technologies	Infusing image processing capabilities	Case study I
	SLO-2	BAN and other technologies	Power sources- Batteries	Limitations in use	Secure medical sensor network with HIP	Case study I
S-9	SLO-1	BAN and Healthcare	Fuel cells for sensor nodes.	Coexistence issues with BAN	Diagnostic applications	Case study II
	SLO-2	Medical Applications of BAN	Other novel power sources	Other practical considerations	Therapeutic applications	Case study II

Learning Resources	<ol style="list-style-type: none"> <li>1. Annalisa Bonfiglio, Danilo De Rossi, "Wearable Monitoring Systems", Springer, 2011.</li> <li>2. Philip Olla, Josep Tan, "Mobile Health solutions for Biomedical applications", Medical Information science reference, Hershey New York, IGI Global 2009.</li> <li>3. Zhang, Yuan-Ting, Wearable Medical Sensors and systems, Sringers, 2013.</li> <li>4. Guang-Zhogn Yang(ED), "Body Sensor Networks", Springers, 2013</li> <li>5. Mehmet R. Yuce Jamil Y.Khan, "Wireless Body Area Networks Technology, Implementation and applications", Pan Stanford Pte. Ltd., Singapore, 2012</li> </ol>	<ol style="list-style-type: none"> <li>6. Konstantina, James C. Lin, Dimitrios, Maria Teresa, "Wireless mobile Communication and healthcare", Secon International ICST conference, Mobihealth 2011, Springers 2011.</li> <li>7. Ullah, Sana, Et at, "A review of wireless body area networks for medical applications", arXiv: 1001.083, 2010</li> <li>8. Patel, Shyamal, Et al, "A review of wearable sensors and systems with application in rehabilitation", Neuroeng Rehabil 9.12, 2012, 1-17.</li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
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2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	Dr. U. Snehalatha, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE365T	Course Name	BIO-INSPIRED HUMAN MACHINE INTERFACE	Course Category	E	Professional Electives				L	T	P	C
										3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/ Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Study the HMI design, principles and standards			
CLR-2 :	Attain knowledge in optic and acoustic based HMI design			
CLR-3 :	Acquire knowledge in Bioelectric interfaces			
CLR-4 :	Study the brain signal based HMI design			
CLR-5 :	Have an insight knowledge in advanced HMI design			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Explain the basics, rules and generic design flow of HMI systems			
CLO-2 :	Explain and analyze the optic and Acoustic based HMI systems			
CLO-3 :	Analyze and discuss the bioelectric based HMI design			
CLO-4 :	Explain and analyze brain signal based HMI design			
CLO-5 :	Analyze and discuss the advances and challenges in HMI design			
CLO-6 :	Design a biomimetic system for neural prosthesis			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to HMI	Vision based HMI design-Introduction-	Bioelectric Interfaces-Introduction	Brain Computer Interfaces-Introduction	Affective Computing based HMI-Introduction
	SLO-2	Need for HMI systems	Face Recognition-Signal Acquisition	Myoelectric interfaces-Introduction	Brain regions and responsibilities	Affective Computing based HMI-Data Acquisition
S-2	SLO-1	Types of HMI	Face Recognition-Data Analysis	Muscle regions and responsibilities	Active methods for measuring brain activity	Affective Computing based HMI-Data Classification
	SLO-2	Types of HMI	Vision based HMI design-Data Classification	Methods for measuring muscle activity	Active methods for measuring brain activity(Contd.)	Application of Affective Computing based HMI
S-3	SLO-1	HMI-guidelines	Gait Recognition-Signal Acquisition	Myoelectric Signal –Data Analysis	Invasive BCI	Wearable Computing-Introduction
	SLO-2	HMI-principles	Gait Recognition-Data Analysis & Classification	Myoelectric Signal –Data Analysis(Contd.)	Non-invasive BCI	Wearable Computing
S-4	SLO-1	HMI-standards	Gesture Recognition-Data Analysis & Classification	Myoelectric Signal –Data Classification	EEG based BCI	Tactile based HMI
	SLO-2	HMI-Ethical Issues	People tracking	Application of Myoelectric HMI	P300 based BCI	Tactile based HMI
S-5	SLO-1	Interaction design-basics	LED based HMI system	ECG based HMI design	VEP based BCI	Motion based HMI
	SLO-2	Interaction design-Design rules	LASER based HMI system	ECG based HMI design(Contd.)	NIRS based BCI	Motion based HMI
S-6	SLO-1	HMI Systems-Data Collection	Speech Communication	EOG based HMI design-Introduction	Application in Prosthetic Control	Biomimetic design of neural prosthesis
	SLO-2	HMI Systems-Data Analysis	Speech Communication (Contd.)	EOG based HMI design-Signal Acquisition	Application in Prosthetic Control	Biomimetic design of neural prosthesis
S-7	SLO-1	HMI Systems-Design	Fundamentals of Speech Recognition	EOG based HMI design-Signal Analysis	Neurorehabilitation	Intracranial human machine interfaces for Communication and control

	SLO-2	HMI Systems-Prototyping	Fundamentals of Speech Recognition(Contd.)	EOG based HMI design-Signal Analysis(Contd.)	Neurorehabilitation	Intracranial human machine interfaces for Communication and control
S-8	SLO-1	Evaluation of HMI Systems	Automatic Speech Recognition	EOG based HMI design-Signal Classification	Neuromarketing	Multimodal approaches for advanced HMI design
	SLO-2	Evaluation of HMI Systems	Automatic Speech Recognition(Contd.)	EOG based HMI design-Signal Classification(Contd.)	Neuromarketing	Multimodal approaches for advanced HMI design
S-9	SLO-1	Bio-inspired HMI Systems	Multimodal Interaction & Approaches	Applications of EOG based HMI	Brain controlled wheel chairs	Multimodal approaches for advanced HMI design
	SLO-2	Bio-inspired HMI Systems	Multimodal Interaction & Approaches (Contd.)	Applications of EOG based HMI (Contd.)	Brain controlled wheel chairs	Multimodal approaches for advanced HMI design

Learning Resources	1. Yvonne Rogers, Helen Sharp, Jenny Preece, "Interaction Design: Beyond Human Computer Interaction", 3rd Edition, Willey Publisher, 2012. 2. P C Yuen, Y Y Tang, P S P Wang, "Multimodal Interface For Human-Machine Communication", World Scientific, 2002. 3. Aboul-Ella Hassanien and Ahmad Taher Azar, "Brain-Computer Interfaces: Current Trends and Applications", Springer International Publishing AG, 2016.	4. Rajesh P. N. Rao, "Brain-Computer Interfacing : An Introduction", Cambridge University Press, 2013 5. Masaki Kurosu, Human-Computer Interaction. User Interface Design, Development and Multimodality, Springer International Publishing AG, 2017
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
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3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in
		Internal Experts
		1. Dr. Hariharan, SRMIST
		2. Dr. U. Snehalatha, SRMIST



Course Code	18ECE366T	Course Name	IMPLANTABLE BIOELECTRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18EES101J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Comprehend technical information about miniaturized Implantable Biomedical devices				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Introduce to neural interfaces and cyborgs				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Know about implantable user interface and CMOS imaging systems																					
CLR-4 :	Learn about implantable electronics biocompatibility criteria and telemetry																					
CLR-5 :	Know the key design trends in implantable systems																					
CLR-6 :	Know the future of Biomedical Implantable systems																					
Course Learning Outcomes (CLO):																						
CLO-1 :	Describe the design of Implantable Biomedical Devices				1,2	80	75	M														
CLO-2 :	Tell about neural interfaces and cyborgs				1	80	75	L														
CLO-3 :	Describe about implantable user interface and CMOS imaging systems				1,2	80	75	M														
CLO-4 :	Tell about implantable electronics biocompatibility criteria and telemetry				1	80	75						L	L								
CLO-5 :	Consolidate on design trends in implantable systems				2,3	80	75	L													L	
CLO-6 :	Summarize the future of Biomedical Implantable systems				2,3	80	75														L	

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Bioelectronics-Introduction	Neural interfaces and cyborgs- introduction	Implantable user interfaces	Biotelemetry	Design trends in Biomedical Implantable systems
	SLO-2	Energy Harvesting as a Pathway to miniaturization,	Fusing Robotics with the Human Body	Design Considerations	Inductive Link for Forward Data	Design of Implant Systems-
S-2	SLO-1	Implantable Devices	Anatomy of Peripheral Nerves	Evaluating Basic Implanted User Interfaces	Wireless Power Link	Review-History
	SLO-2	Implementation of Implantable Devices	Interfacing with the periphery for recording and stimulation	Qualitative Evaluation,	Implantable device with external units	Basic Considerations and Characteristics of RF MEMS Implantable Systems-
S-3	SLO-1	RF Power Harvesting	Listening to the Brain	Medical Considerations	Implantable Telemetry Link	Legal Considerations of the Radio Frequency (RF)
	SLO-2	Matching network, rectifier,	Interfacing with the Central Nervous System	Limitations	Wideband telemetry links	Field Strength
S-4	SLO-1	Regulator and band gap reference	Electrical Modulation of the Human Nervous System	CMOS Imaging Devices	Multichannel neural recording systems	Power Levels
	SLO-2	Implant functional block	Pain Modulation	Fundamentals of CMOS Imaging	Wireless endoscope	Biocompatibility
S-5	SLO-1	Wireless Communication Link,	Electrical Modulation of Inflammation	Photo sensors,	Microelectrode Arrays	Protection of the Biomedical Implant
	SLO-2	Forward and reserve data link	Cyborgs	Log sensors	Interface Electronics	Systems-Characteristics of Biological and Medical Signals
S-6	SLO-1	Payload	The Neuro-Tech Version	SPAD sensors	Electrode equivalent circuit	Design considerations of Implantable Systems, Micro power Electronic Design
	SLO-2	Applications	Biological Brains in a Robot Body	Artificial Retina	Stimulation Front Ends	Approaches

S-7	SLO-1	Locomotive Implant	Deep Brain Stimulation	Principle of Artificial Retina	Recording Front-Ends	Samples
	SLO-2	Implantable Cardiac Probe,	General Purpose Brain Implants	Artificial Retina Based on CMOS Imaging Device	Instrumentation amplifier	Power Supply design.
S-8	SLO-1	Communication power delivery	Brain-Computer Interfaces	Brain-Implantable CMOS Imaging Device	Improving the Biocompatibility of Implantable Bioelectronics Devices.	System integration
	SLO-2	System Overview of a Generic Bioelectronics Implant	Noninvasive Brain-Computer Interfaces	Measurement Methods for Brain Activities	Implantable Bioelectronics Devices Materials	Micro-Packages,
S-9	SLO-1	Circuit Design for Low-Power Signal Processing.	Sub dermal Magnetic Implants	Fiber Endoscope and Head-Mountable Device	Surface Composition	Present Challenges,
	SLO-2	Architecture-Level Optimization for Low-Power Data Processing	RF ID Implants.	Summary and future directions	Response to Implantation	Nano-Enabled Implantable Device for In Vivo Glucose Monitoring

Learning Resources	1. Evgeny Katz, "Implantable Bioelectronics Devices materials and Applications", Wiley-VCH, 2014. 2. Vinod Kumar Khanna, "Implantable Medical Electronics Prosthetics, Drug Delivery and Health Monitoring", Springer, 2016	3. Swarup Bhunia, Steve Majerus, Mohamad Sawan, Implantable Biomedical Microsystems: Design Principles and Applications", Elsevier, 2015.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		-	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Sathyanarayanan J, Mindray Medical India Pvt Ltd, sathyanarayananjayagopal@mindray.com	1. Dr. S. Poonguzhali, Anna University, poongs@annauniv.edu	Dr. Varshini Karthik, SRMIST
2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	Mr. Karthik Raj, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE367T	Course Name	REGULATORY AFFAIRS IN MEDICAL INSTRUMENTS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECC201J, 18ECE260J	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Understand the fundamental troubleshooting procedures and testing of basic electronic components			
CLR-2 :	Get an idea about the fault diagnosis in analog circuits and digital ICs.			
CLR-3 :	Acquire an idea about the basic troubleshooting procedures for biomedical equipment			
CLR-4 :	Get an idea about the medical device classification globally and regulatory standards			
CLR-5 :	Get an idea about the Indian perspective medical device regulatory system			
CLR-6 :	Get an overall idea about the importance of troubleshooting and medical device classification in India			

Learning		
1	2	3
Thinking (Bloom)	Proficiency (%)	Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Analysis	Development	Design,	Tool Usage	Culture	Int & ty		Team Work	Communication	Life & Finance	Learning			

Course Learning Outcomes (CLO):	<i>At the end of this course, learners will be able to:</i>	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Apply the common troubleshooting procedures in Electronic Equipment and Outline the testing procedures of active and passive components	1, 2	80	70	M	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Analyze the faults in analog circuits and digital ICs	1, 2	80	70	M	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-3 :	Identify the problems in common biomedical equipment in hospitals when it is not working and provide a suitable solution	2	80	70	-	M	-	-	-	-	-	-	-	-	-	-	M	-	-
CLO-4 :	Outline the importance of medical device classification based on the application and ISO standards	1	80	70	-	-	H	-	-	-	-	-	-	-	-	M	-	M	-
CLO-5 :	Describe the Indian medical device regulatory system	1	80	70	-	-	-	-	-	-	-	-	-	-	-	M	-	-	-
CLO-6 :	Outline the job opportunities in regulatory affairs in India	1,2	80	70	-	-	-	-	-	-	-	-	-	-	-	L	-	-	-

Duration (hour)		Basic Troubleshooting Techniques & Testing Procedures	Fault Diagnosis in Analog, Digital Integrated Circuits and Home care device	Biomedical Machine Troubleshooting in Hospitals	Medical Device Classification and Standards	Medical Device Regulatory System in India
		9	9	9	9	9
S-1	SLO-1	Equipment failure and its types	Characteristics of ideal op-amps	Troubleshooting- ECG Machine	Global Harmonization Task Force (GHTF) definition for medical device	Importance of regulatory system
	SLO-2	Causes of Equipment failure	Typical op-amp based medical circuits	And its preventive maintenance	Medical Device Life Cycle: Identify, Characterize	Market Overview
S-2	SLO-1	Functional block diagram of a troubleshooting system	Typical op-amp based medical circuits	Troubleshooting- EEG Machine	Medical Device Life Cycle: Optimize, Verify/Validate	Overview of Regulatory Environment
	SLO-2	Functional block diagram of a troubleshooting system	Fault diagnosis in op-amp circuits	And its preventive maintenance	Global Perspective on medical device regulations: USA, European Union	Overview of Regulatory Environment
S-3	SLO-1	Troubleshooting process	Example: Inverting amplifier troubleshooting process	Troubleshooting- defibrillator, suction machine	Global Perspective on medical device regulations: Canada, Australia, Japan	Functions Undertaken by DCGI and Central Government
	SLO-2	Fault finding aids	Typical Faults in digital circuits	And its preventive maintenance	Medical device classification: USA	Functions Undertaken by the FDA and State Governments
S-4	SLO-1	Troubleshooting techniques: Preliminary Observations	Different testing methods in digital circuits: Functional Testing, DC Test	Troubleshooting- electrosurgical unit	Medical device classification: European Union, GHTF	Indian Pharmacopoeia Commission
	SLO-2	Troubleshooting techniques: Functional block diagram approach	AC Test	And its preventive maintenance	Premarket Notification 510(k), Premarket Approval	Details of Key Regulator

S-5	SLO-1	Troubleshooting techniques: Split half method	Digital IC Troubleshooter:, Logic clip, Logic probe	Troubleshooting- anesthesia machine	Standards and its need	Organization Chart — CDSCO
	SLO-2	Application of Split half method in circuit troubleshooting	Digital IC Troubleshooters: Logic pulser, Logic current tracer	And its preventive maintenance	ISO 9000 core standards: Basic overview	Role of Distributors or Local Subsidiaries
S-6	SLO-1	Troubleshooting techniques: Systematic Troubleshooting	Digital IC Troubleshooters: Logic comparator	Troubleshooting- autoclaves & sterilizers	ISO 13485: Basic overview	Product Registration
	SLO-2	Correction action	Circuit board Troubleshooting	And its preventive maintenance	ISO 14971: Basic overview	Manufacturing site and product registration: process flow chart
S-7	SLO-1	Testing of passive components: Resistors, Capacitors	Troubleshooting- oxygen concentrators	Troubleshooting- endoscope	ISO 10933: Basic overview	Quality System Regulation
	SLO-2	Testing of passive components: Inductors, Diodes, LDR	And its preventive maintenance	And its preventive maintenance	ISO 14155: Basic overview	Technical Material Requirement & Labelling Requirement of Medical Device
S-8	SLO-1	Testing of active components: BJT	Troubleshooting- sphygmomanometers, Analog Blood pressure apparatus	Troubleshooting- incubators	ISO 11607: Basic overview	Manufacturing-Related Regulation
	SLO-2	Testing of active components: JFET	And its preventive maintenance	And its preventive maintenance	ISO 11137: Basic overview	Clinical Trial-Related Regulation
S-9	SLO-1	Testing of active components: MOSFET	Troubleshooting- nebulizer	Troubleshooting- X-ray Machine	IEC 60601: Basic overview	Commercial Aspect
	SLO-2	Testing of variable resistors and its different types	And its preventive maintenance	And its preventive maintenance	IEC 62353: Basic overview	Related Agencies/Departments and Ministries

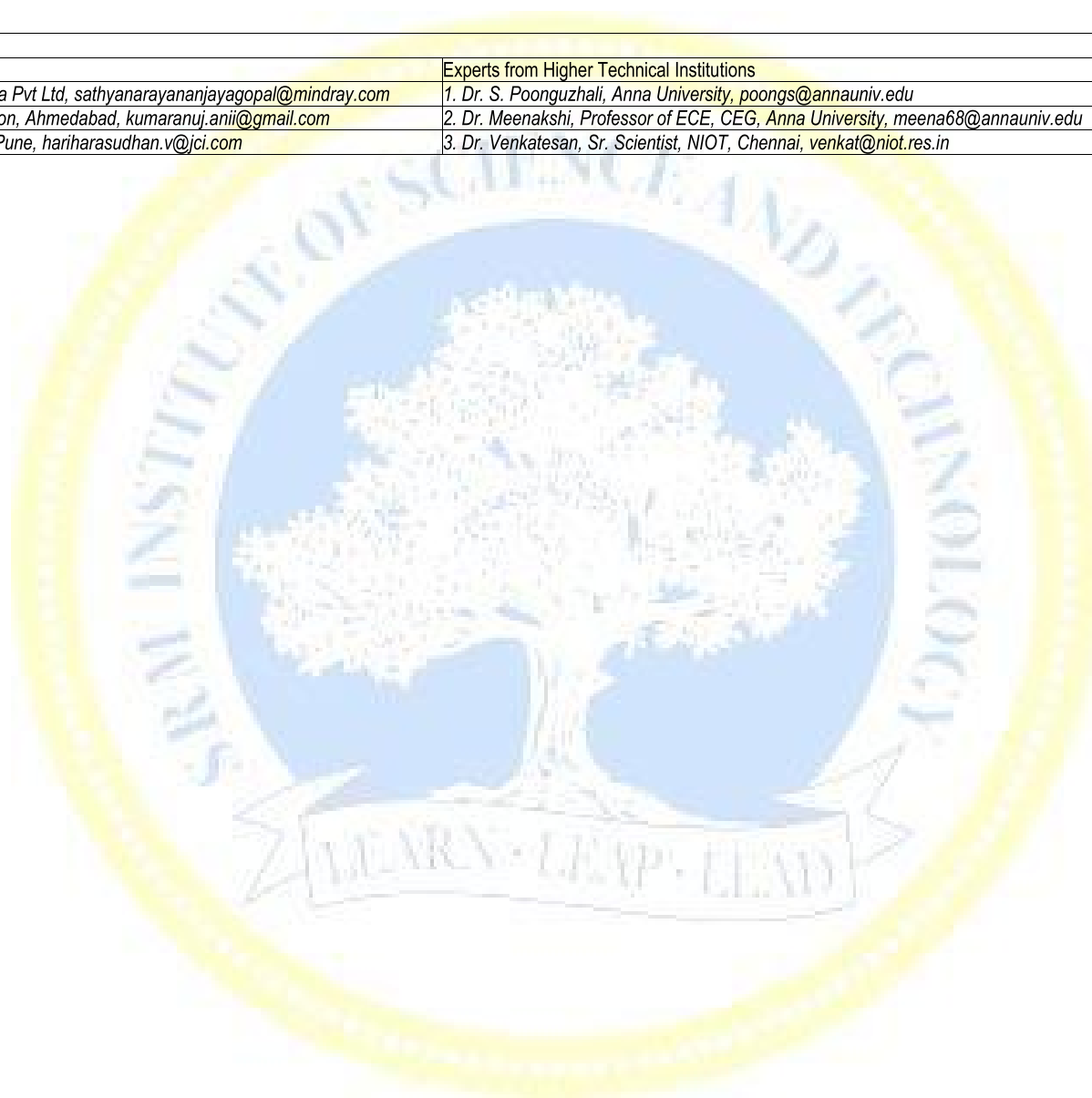
Learning Resources	<ol style="list-style-type: none"> <li>1. Joseph D Bronzino &amp; Donald R Peterson, "Medical Devices and Human Engineering", CRC Press, 4<sup>th</sup> Edition, 2015</li> <li>2. Myer Kutz, "Biomedical Engineering and Design Handbook- Volume 2: Applications", McGraw-Hill, 2<sup>nd</sup> Edition, 2009</li> <li>3. Richard Fries, "Reliable Design of Medical Devices", CRC Press, 2<sup>nd</sup> Edition, 2006</li> <li>4. Basem S EL-Haik &amp; Khalid S Mekki, "Medical Device Design for Six Sigma: A Road Map for Safety and Effectiveness", John Wiley &amp; Sons, 1<sup>st</sup> Edition, 2008</li> <li>5. John J Tobin &amp; Gary Walsh, "Medical Product Regulatory Affairs- Pharmaceutical, Diagnostics, Medical Devices", Wiley-Blackwell, 1<sup>st</sup> Edition, 2008</li> <li>6. Norbert Leitgeb, "Safety of Electromedical Devices Law – Risks – Opportunities", SpringerWienNewYork, 1<sup>st</sup> Edition, 2010</li> </ol>	<ol style="list-style-type: none"> <li>7. "Medical Device Regulations Global overview and guiding principles", World Health Organization Geneva, 2003</li> <li>8. Jack Wong and Raymond K Y Tong, "Handbook of Medical device regulatory affairs in Asia", Pan Stanford Publishing Pte. Ltd., 2<sup>nd</sup> Edition, 2018</li> <li>9. Khandpur R S, "Troubleshooting Electronic Equipment- Includes Repair &amp; Maintenance", Tata McGraw-Hill, 2<sup>nd</sup> Edition, 2009</li> <li>10. Nicholas Cram &amp; Selby Holder, "Basic Electronic Troubleshooting for Biomedical Technicians", TSTC Publishing, 2<sup>nd</sup> edition, 2010</li> <li>11. Dan Toma &amp; Neal Widmer, "Electronic Troubleshooting", McGraw Hill, 3<sup>rd</sup> edition, 2004</li> <li>12. Ministry of Health &amp; Family Welfare, "Medical Equipment Maintenance Manual- A first line maintenance guide for end users", New Delhi, 2010</li> </ol>

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	40 %	-	40 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	20 %	-	20 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,



Course Designers		
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Course Code	18ECE368T	Course Name	Biomedical Laser Instruments	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Learn the optical characteristics of tissue	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know the functioning of a laser system	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Familiarise the applications of laser in ophthalmology, Dermatology and cardiology				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Familiarise the applications of laser in Urology, Gynecology and dentistry				M	-	-	-	-	-	-	-	-	-	-	-	M	-	-
CLR-5 :	Learn the non- thermal applications of laser in medicine				-	M	-	-	-	-	-	-	-	-	-	-	M		
CLR-6 :	Acquire knowledge on laser safety and management				-	-	-	-	-	-	-	M	-	-	-	-	L		
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>																			
CLO-1 :	Describe the optical properties of tissues	3	80	75															
CLO-2 :	Have a deep understanding on technical aspects of a LASER system	3	80	70															
CLO-3 :	Describe the applications of laser in ophthalmology, Dermatology and cardiology	3	75	70															
CLO-4 :	Describe the applications of laser in Urology, Gynecology and dentistry	3	80	75															
CLO-5 :	Explain the non- thermal applications of laser in medicine	3	80	70															
CLO-6 :	Implement the aspects of laser safety	3	80	70															

Duration (hour)		Optical properties of the tissues	Laser System	Laser Applications-I	Laser Applications-II	Non Thermal Applications of LASER and Laser safety management
		9	9	9	9	9
S-1	SLO-1	Fundamental Properties of light - Refraction, Reflection, Laws (Snell's law and Fresnel law)	Characteristics of Laser	Disorders in Eye	Lasers in urology- Lithotripsy	Optical coherence tomography-System description
	SLO-2					
S-2	SLO-1	Scattering, Absorption characteristics	Construction and working principle of laser system	Diagnostic Applications of laser in ophthalmology	Therapeutic applications of Lasers in urology	Applications of Optical coherence tomography
S-3	SLO-2	Light transport inside the tissue	Pumping Schemes	Therapeutic Applications of laser in ophthalmology	Laproscopy- System description	Elastography
S-4	SLO-1	Tissue properties	Classification of Laser	Dermatological disorders	Applications of laser in Gynecology	Laser Induced Fluorescence (LIF)- Imaging,
S-5	SLO-2	Laser Characteristics as applied to medicine and biology,	Solid state Laser - Construction and working principle	Applications of Lasers in dermatology	Applications of laser in Gynecology	FLIM Raman Spectroscopy and Imaging
S-6	SLO-1	Laser tissue Interactions – Photo chemical, Photo thermal and Photo mechanical interactions	Atomic laser- Construction and working principle	Diagnostic Applications of Lasers in cardiology	Applications of laser in laryngeal surgery	FLIM – Holographic and speckle application of lasers in biology and medicine
S-7	SLO-2	Fluorescence and Speckles	Molecular Laser- Construction and working principle	Therapeutic Applications of Lasers in cardiology	Applications of laser in Otology	Types of laser hazards
S-8	SLO-1	Alterations of bio tissue properties during hyper thermal and ablation reactions	Dye Laser - Construction and working principle	Lasers in Surgery	Applications of laser in neurology	Laser safety
	SLO-2					

S-9	SLO-1 SLO-2	Photodynamic therapy - Principle and mechanism	Semiconductor Laser- Construction and working principle	Tissue welding and Soldering	Applications of Lasers in dentistry	Laser risk management,
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Learning Resources	1. Leon Goldman, M.D., & R.James Rockwell, Jr., <i>Lasers in Medicine</i> , Gordon and Breach Science Publishers Inc., 1975. 2. Abraham Katzir, <i>Lasers and Optical Fibers in Medicine</i> , Academic Press Edition, 1998.	3. Tuan Vo Dirh, <i>Biomedical Photonics – Handbook</i> , CRC Press, Boca Raton, 2003. 4. Glasser, O., <i>Medical Physics -- Vol 1, 2, 3</i> Adam Hilgar Brustol Inc, 1987. 5. G.David Baxter, <i>Therapeutic Lasers – Theory and practice</i> , Churchill Livingstone Publications
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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		Internal Experts
		1. Dr. D. Kathirvelu, SRMIST
		2. Dr. D. Ashok kumar, SRMIST

Course Code	18ECE369T	Course Name	HOME MEDICARE TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understanding the Home health Nursing practice	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Explaining the homecare care working with different clients	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Demonstrating the various medical devices used at home				L	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLR-4 :	Highlighting the advancement in medical technologies				L	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLR-5 :	Visualizing the use of wireless technology in health care				M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLR-6 :	Classifying the various mode of healthcare technology at home				M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		3	80	75	L	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLO-1 :	Applying Home health Nursing practice	3	80	70	L	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLO-2 :	Illustrate the homecare care working with different clients	3	80	70	M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLO-3 :	Analyze the various medical devices used at home	3	75	70	M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLO-4 :	Identify the advancement in medical health technologies	3	80	75	M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLO-5 :	Analyze the use of wireless technology in health care	3	80	70	M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLO-6 :	Describe the various type of healthcare technology at home	3	80	70	L	-	-	-	-	-	-	-	-	-	-	-	L	-	L

Duration (hour)		Introduction to Home health Nursing	Working With Clients	Medical Devices At Home	Advancement In Medical Technologies	Wireless Technology
		9	9	9	9	9
S-1	SLO-1	Home health care – purpose	Basic human needs	Medical devices at home	Advances and trends in health care technologies	Wireless communication basics
	SLO-2	Historical perspective	Communication and interpersonal skills	Medical devices at home	Advances and trends in health care technologies	Wireless communication basics
S-2	SLO-1	Understanding Home healthcare:Applying Theory to clinical practice	Caregiver observation	User centered design and Implementation	Driver impacting the growth of medical Technologies	Types of wireless network
	SLO-2	Role preparation and implementation	Caregiver observation	User centered design and Implementation	Driver impacting the growth of medical Technologies	Types of wireless network
S-3	SLO-1	Developing the plan of care and documentation	Recording and reporting, confidentiality	Co-design with old users	Impact of Moore's law of medical imaging	Body area network
	SLO-2	Legal and ethical issues in home care	Recording and reporting, confidentiality	Co-design with old users	Impact of Moore's law of medical imaging	Body area network
S-4	SLO-1	Case management and leadership strategies	Working with elderly – aging and body systems.	Device types – user issues.	E-health and personal healthcare	Emergency rescue
	SLO-2	Organisation of home care system	Working with elderly – aging and body systems.	Device types – user issues.	E-health and personal healthcare	Emergency rescue
S-5	SLO-1	Home care organisation	Working with children	Ethical and legal issues. Infant monitors	Defining the future of health Technology	Remote recovery
	SLO-2	Home care nursing practice	Working with children	Ethical and legal issues. Infant monitors	Defining the future of health Technology	Remote recovery
S-6	SLO-1	Home care nursing practice	Need for home care	Medical alert services	Inventing the future -tools for self-health	General health assessments Technology



	SLO-2	Role of home care nurse and orientation strategies	Need for home care.	Medical alert services	Inventing the future -tools for self-health	in medical information processing General health assessments Technology in medical information processing
S-7	SLO-1	Environmental influences on home care	Mobility transfers and ambulation	Activity monitors	Future of Nano fabrication molecular scale devices	Future trends in healthcare technology
	SLO-2	Environmental influences on home care	Mobility transfers and ambulation	Activity monitors	Future of Nano fabrication molecular scale devices	Future trends in healthcare technology
S-8	SLO-1	Infection control in home	Range of motion exercises	The ventilator dependent patient	Future of telemedicine	Paradoxes of progress: Implications for home health care
	SLO-2	Infection control in home	Range of motion exercises	Device for patient with congestive heart failure	Future of telemedicine	Paradoxes of progress: Implications for home health care
S-9	SLO-1	Patient education in home	Skin care and comfort measures	Device for Patient with chronic Obstructive pulmonary disease	Future of medical computing	Cost of home healthcare
	SLO-2	Patient education in home	Skin care and comfort measures	Device for patient with Diabetic	Future of medical computing	Direction for emerging technology

Learning Resources	1. Robyn Rice, "Home care nursing practice: Concepts and Application", 4th edition, Elsevier, 2006. 2. Lodewijk Bos, "Handbook of Digital Homecare: Successes and Failures", Springer, 2011.	3. Yadin David, Wolf W. von Maltzahn, Michael R. Neuman, Joseph. D. Bronzino, "Clinical Engineering", CRC Press, 2010. 4. Kenneth J. Turner, "Advances in Home Care Technologies: Results of the match Project", Springer, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Sathyanarayanan J, Mindray Medical India Pvt Ltd, sathyanarayananjayagopal@mindray.com	1. Dr. S. Poonguzhali, Anna University, poongs@annauniv.edu	1. Dr. D. Ashok Kumar, SRMIST
2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Mrs. Lakshmi Prabha.P, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE460T	Course Name	ACOUSTICS AND OPTICAL IMAGING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	To study in-depth the various optical properties of tissues and light interactions with tissues	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	To study about various optical sources and instrumentation for various measurements	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	To study about photonic detection and imaging techniques				M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLR-4 :	To understand the special techniques like optical holography				L	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLR-5 :	To make them understand the working principles of optical imaging systems				L	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLR-6 :	To Utilize the imaging techniques for various applications				M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
					M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>																			
CLO-1 :	Analyze in-depth about the various optical properties of tissues and light interactions with tissues	3	80	75															
CLO-2 :	Illustrate the hardware and techniques involved in acoustic imaging	3	80	70															
CLO-3 :	Describe the optical properties of tissues	3	75	70															
CLO-4 :	Analyze the physics behind optical holography	3	80	75															
CLO-5 :	Identify the principle behind modern imaging techniques	3	80	70															
CLO-6 :	Apply the imaging modality for interpretation	3	80	70															

Duration (hour)		PHYSICS OF ACOUSTICS	ACOUSTIC IMAGING	OPTICAL PROPERTIES OF TISSUES	OPTICAL HOLOGRAPHY	PHOTONIC DETECTION AND IMAGING TECHNIQUES
		9	9	9	9	9
S-1	SLO-1	The sine wave , sound in media-particle motion	Fundamentals of photo acoustic tomography	Fundamental Optical Properties	Fundamentals – Object wave	Life time based imaging
	SLO-2	Propagation of sound	Photo acoustic effect	Refraction, scattering, absorption	Photography	Techniques for Lifetime-Based Imaging
S-2	SLO-1	Speed of sound - wavelength and frequency	Image reconstruction methods	Light Transport in Tissue	Holography	Specifics of FLIM Data Analysis
	SLO-2	Complex waves- harmonics	Instrumentation	Numerical Approach: Monte Carlo Simulations	Interference during recording	Selected FLIM Applications
S-3	SLO-1	Phase, partials ,octaves, spectrum	Transducer array	Kubelka–Munk Model	Diffraction during reconstruction	Confocal microscopy
	SLO-2	Electrical, mechanical and acoustic analogs	Transducer array-based photoacoustic tomography	Tissue Properties	Imaging techniques –In line hologram	Image Formation in Scanning Microscopes
S-4	SLO-1	Wave phenomenon	Array-based PAT System	Refractive Indices	Off axis hologram, fourier hologram	Applications of Depth Discrimination
	SLO-2	Wavefronts, Interference,	2-D Imaging	Scattering Properties	Fraunhofer hologram, reflection hologram	Fluorescence Microscopy
S-5	SLO-1	Reflection, scattering	3-D Imaging	Absorption Properties	Optical properties of holographic imaging	Optical Architectures
	SLO-2	Diffraction, refraction	4-D Imaging	Light Interactions with a Strongly Scattering Tissue	Hologram of an object	Abberation Correction
S-6	SLO-1	Doppler effect , convection	Photoacoustic microscopy	Continuous Wave Light , Polarized Light, Short Light Pulses, Diffuse Photon-Density Waves	Image equation, angular magnification	Near-Field Optical Microscopy

	SLO-2	Sound levels and decibel: ratios versus differences	Computed microscopy	Optothermal Interactions	Longitudinal magnification, image aberrations	Biological Applications of Near-Field Optical Microscopy
S-7	SLO-1	Logarithms , decibels, reference levels	Optical-resolution	Temperature Rise and Tissue Damage ,	Properties of light source -spectral bandwidth	Special Near-Field Techniques for Biological Applications
	SLO-2	Logarithmic and exponential forms compared	Acoustic-resolution	Optothermal and Optoacoustic Effects	Image plane holograms	Principles of Operation of Optical Coherence Tomography
S-8	SLO-1	Acoustic power	C-scan photoacoustic Microscopy	Fluorescence	Image luminance- without pupil	Applications of Optical Coherence Tomography
	SLO-2	Measuring sound pressure level	Photoacoustic computed microscopy	Formation of Speckles	With pupil, image plane holograms	Thermal imaging for biological and medical diagnosis
S-9	SLO-1	Sine wave measurement	Photoacoustic microscopy based on acoustic lens with variable focal length	Detectors: solid state detectors	Speckles- diffuser	Infrared Radiation and Thermal Imaging
	SLO-2	Examples	Confocal photoacoustic microscopy using a single multifunctional Lens	Time resolved and phase resolved detectors	Resolution, incoherent illumination	Applications of Infrared Thermal Imaging

Learning Resources	<ol style="list-style-type: none"> <li>1. F. Alton Everest, Ken Pohlmann , "Master Handbook of Acoustics" McGraw-Hill, sixth edition, 2014</li> <li>2. Huabei Jiang, "Photoacoustic Tomography" CRC press, Taylor &amp; Francis Group,first edition, 2015.</li> <li>3. Jose Luis del Cura, Pedro Seguí, Carlos Nicolau, "Learning Ultrasound Imaging"springer,first edition 2012.</li> <li>4. Peter R. Hoskins, Kevin Martin, Abigail Thrush, "Diagnostic Ultrasound: Physics and Equipment", Cambridge university press,second edition, 2010</li> <li>5. Gerhard K. Ackermann, Jürgen Eichler, "Holography: A Practical Approach", WILEY-VCH Verlag GmbH &amp; Co, first edition, 2008.</li> <li>6. Tuan Vo Dirh, "Biomedical photonics – Handbook", CRC Press, second edition, 2003</li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Dr.D.Kathirvelu, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE461T	Course Name	MACHINE VISION IN MEDICAL TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Utilize the types and concepts of machine vision	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Utilize the techniques involved in motion analysis	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Utilize the properties and techniques in 3D reconstruction				M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLR-4 :	Utilize the algorithm behind different methods of photogrammetry				L	M	L	-	-	-	-	-	-	-	-	-	L	-	L
CLR-5 :	Applying the machine vision techniques to medical applications				L	M	L	L	-	-	-	-	-	-	-	M	L	-	L
CLR-6 :	Utilize the numerical techniques for various medical applications				M	-	M	L	M	-	-	-	-	-	-	-	L	-	L
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		3	80	75	M	-	-	-	-	-	-	-	-	-	-	-	L	-	L
CLO-1 :	Familiarize with the machine vision and its problems	3	80	70	L	M	L	-	-	-	-	-	-	-	-	-	L	-	L
CLO-2 :	Explain the applications of differential vision and motion analysis	3	80	70	L	M	L	L	-	-	-	-	-	-	-	M	L	-	L
CLO-3 :	Describe and understand the concept of three dimensional reconstruction	3	75	70	M	-	-	L	-	-	-	-	-	-	-	M	L	-	L
CLO-4 :	Use stereo vision techniques and optical flow methods to study imaging techniques	3	80	75	M	-	M	L	M	-	-	-	-	-	-	-	L	-	L
CLO-5 :	Use contemporary numerical and simulation tools to implement methods and algorithms	3	80	70	M	-	-	-	M	-	-	-	-	-	-	-	L	-	L
CLO-6 :	Apply the machine vision in medical technology	3	80	70	M	-	-	-	M	-	-	-	-	-	-	-	L	-	L

Duration (hour)		Machine Learning For Machine Vision	Visualizing Of Objects In Motion	3D Reconstruction –Basics And Methods	Photogrammetry And Stereo Methods	Applying Computational Vision
		9	9	9	9	9
S-1	SLO-1	Learning and inference in vision	Two-frame structure	2D and 3D feature-based alignment	Photometric calibration	Automated Visual Inspection
	SLO-2	Human Vision	Two-frame structure from motion	Correlating 2D and 3D	Noise level estimation	Automated Visual Inspection with CT image
S-2	SLO-1	Geometric primitives	Perspective and projective factorization	Shape from texture	High dynamic range imaging	Computer Vision in Interventional Cardiology
	SLO-2	2D and 3D transformations	Constrained structure and motion	Shape from shading and photometric stereo	Optical blur (spatial response) estimation	Computer Vision using CT image
S-3	SLO-1	Photometric image formation	Dense motion estimation- Definition	Shape from focus	Super-resolution	Fusion of three dimensional quantitative coronary angiography and intracoronary imaging for coronary interventions
	SLO-2	Global optimization	Dense motion estimation	Active range finding	Blur removal	Merging Two image
S-4	SLO-1	Low level vision : Definition , example	Parametric motion	Surface representations	Image matting and compositing	Feature centric lesion detection and retrieval in thoracic images
	SLO-2	Classical filtering operations	Parametric motion- application in analysis	Interpolation, simplification	Optimization-based matting	Algorithm for retrieval
S-5	SLO-1	Edge detection: sobel	Motion models-Definitions	Point-based representation-Definition	Texture analysis and synthesis	Colorization of image after retrieval
	SLO-2	Geometric intrinsic calibration	Motion models-application	Point-based representations -Examples	Hole filling and inpainting	False coloring
S-6	SLO-1	Middle level: Definition , example	The Geometry of multiple views	Volumetric representations	Epipolar geometry	Medical image registration
	SLO-2	Segmentation by clustering	Affine structure from motion	Implicit surfaces and level sets	Rectification	For thermal image & digital image
S-7	SLO-1	Hough Transform	Elements of Affine Geometry	Model-based reconstruction	Sparse correspondence	Z-keying and background replacement



	SLO-2	Case study: Human Iris location	Affine structure and motion from two images	Heads and faces	3D curves and profiles	In registered image
S-8	SLO-1	High level: Definition , example	Affine structure and motion from multiple images	Application: Facial animation	Dense correspondence	Volumetric and 3D surface reconstruction
	SLO-2	Model based vision	Application to Gait analysis	Whole body modeling and tracking	Sub-pixel estimation and uncertainty	Shape from silhouettes
S-9	SLO-1	Regression model- definition	Image Stitching - Concept	Rendering- Layered depth images	Multi-view stereo	Video denoising
	SLO-2	Graphical model	Image Stitching – Application	Light fields and Lumigraphs – 3D	Shape from silhouettes	Video denoising for live endoscopic images

Learning Resources	<ol style="list-style-type: none"> <li>1. Richard Szeliski , "Computer Vision: Algorithms and Applications", Springer, 2010</li> <li>2. E R Davies , "Computer &amp; Machine Vision : Theory , Algorithms, Practicalities" 4th Edition , Elsevier, 2012</li> <li>3. Computer vision – A modern Approach, David A Forsyth &amp; Jean ponce, Prentice Hall, 2002.</li> <li>4. Milan Sonka , Vaclav Hlavac, Roger Boyle, "Image processing, analysis and machine vision" (3. ed.), 2008</li> <li>5. Chi Hau Chen , "Computer Vision in Medical Imaging"- Series in Computer Vision – Vol 2, World Scientific Publishing Co Ltd, 2014</li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Anuj Kumar, Bombardier Transportation, Ahmedabad, kumaranuj.anii@gmail.com	2. Dr. Meenakshi, Professor of ECE, CEG, Anna University, meena68@annauniv.edu	2. Dr. U. Snehalatha, SRMIST
3. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	3. Dr. Venkatesan, Sr. Scientist, NIOT, Chennai, venkat@niot.res.in	

Course Code	18ECE280T	Course Name	INDUSTRIAL INSTRUMENTATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire familiarity about various industrial instrumentation types, their parameters and different types of measurement techniques.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain knowledge about pressure measurement techniques.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Learn about the different techniques of measurement of flow.																					
CLR-4 :	Get exposed to the various techniques of measurement of level.																					
CLR-5 :	Gain knowledge about the temperature measurement techniques.																					
CLR-6 :	Familiarize the measuring devices used in industrial applications.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Understand the need for measurement in industries and the basic measurement techniques.				3	80	75	H	H	-	H	H	-	-	H	L	-	H	H	M	H	L
CLO-2 :	Elucidate the construction & working of various industrial devices used to measure pressure.				3	80	70	H	H	H	H	H	-	-	H	L	-	H	H	H	H	L
CLO-3 :	Summarize the different methods for flow measurement.				3	75	70	H	H	H	H	H	-	-	H	L	-	H	H	H	H	L
CLO-4 :	Illustrate the different methods for the measurement of level.				3	80	75	H	H	H	H	H	-	-	H	L	-	H	H	H	H	H
CLO-5 :	Analyze different techniques to measure temperature.				3	80	70	H	H	H	H	H	-	-	H	L	-	H	H	H	H	H
CLO-6 :	Analyze, formulate and select suitable sensor for the given industrial applications.				3	80	70	H	H	-	H	H	-	-	H	L	-	H	H	M	H	H

Duration (hour)		Force, Acceleration and Speed Measurement	Pressure Measurement	Level Measurement	Flow Measurement	Temperature Measurement
		9	9	9	9	9
S-1	SLO-1	Introduction to industrial symbols and standards	Units of pressure and vacuum	Need for level Measurement	General concepts - Laminar flow, Reynolds's number	Definitions and standards
	SLO-2	Classification of industry	Need for pressure measurement	Visual level indicators	Effect of temperature and pressure on flow rate measurement	Primary and secondary fixed points
S-2	SLO-1	Definitions of Process variable	Manometer Dynamics	Purge method	Calibration of flow meters.	Calibration of thermometer
	SLO-2	Unit conversions	Types- U tube, Inclined Tube and Well type Manometers	Buoyancy method	Head type flow measurement -Principle	Different types of filled in system thermometer
S-3	SLO-1	Types of measurement required	Elastic Pressure Sensor Instruments – Bourdon Tube Pressure Gauge, Capsule Gauge	Resistance, Capacitance and inductive probes	Orifice , Venturi tube	Sources of errors in filled in systems and their compensation
	SLO-2	Detectors, probe analyzers, actuators	Diaphragm gauges, bellows and force balance type sensors	Ultrasonic type	Pitot Tubes, Flow nozzle	Bimetallic thermometers
S-4	SLO-1	Measurement of force	Electronic Pressure / DP transmitters- capacitive type	Laser type	Variable Area Flow meters-Principle	Review of RTD and Thermistors
	SLO-2	Different types of load cells – Magneto-elastic load cell, Strain gauge load cell	Piezo - resistive and resonating wire type	Optical fiber, Thermal type	Rotameters	Signal conditioning of industrial RTDs and their characteristics
S-5	SLO-1	Acceleration Measurement	Vacuum pressure Measurements- Mcleod	Radar, Radiation type	Electrical Type Flow meters-Principle	Three lead and four lead RTDs.

	SLO-2	Strain gauges, Piezoelectric	Gauge Pirani gauge	Solid level measurement	Electromagnetic type, Ultrasonic type	Thermocouples – Laws of thermocouple
S-6	SLO-1	Translational and rotational displacement using potentiometers	Thermocouple gauge	Boiler drum level measurement :- Differential pressure method	Positive displacement type	Fabrication of industrial thermocouples
	SLO-2	Differential transformers	Knudsen gauge	Hydrastep method	Nutating disc, Reciprocating piston	Commercial circuits for cold junction compensation
S-7	SLO-1	Mechanical type vibration instruments – Seismic instrument as an accelerometer	Ionization gauge- cold cathode and hot cathode types	Miscellaneous Measurement,	Mass flow meters - Coriolis type	Pyrometers: Total radiation pyrometers
	SLO-2	Vibrometer	Thermal conductivity gauge	Humidity – Dry and wet bulb psychrometers	Thermal, Impeller type	Selective radiation pyrometers
S-8	SLO-1	Speed measurement – Revolution counter	Testing and calibration of pressure gauges	Resistive and capacitive type hygrometers	Weirs, Flumes	Optical pyrometer
	SLO-2	D.C and A.C tachogenerators	Dead weight tester	Moisture measurement in solids- Conductivity sensor-Microwave and IR sensors.	Open channel flow measurement	Two colour radiation pyrometers
S-9	SLO-1	Stroboscope.	Discussion of device types and models used in practical industrial applications	Discussion of device types and models used in practical industrial applications	Discussion of device types and models used in practical industrial applications	Discussion of device types and models used in practical industrial applications
	SLO-2	Discussion of device types and models used in practical industrial applications	Installation Requirements	Installation Requirements	Installation Requirements	Installation Requirements

Learning Resources	1. Liptak B.G., "Instrument Engineers Handbook (Measurement)", Chilton book Co., McGraw Hill, publishing Ltd., 19th revised edition-2011. 2. A.K. Sawhney, "A course in Electrical and Electronic Measurements and instrumentation Dhanpatrai co., 19th revised edition-2011. Reprint 2014 3. Patranabis D, "Principles of industrial Instrumentation", Tata McGraw Hill, 3rd Edition, New Delhi, Reprint 2010	4. Tony R. Kuphaldt, "Lessons In Industrial Instrumentation ", Version 2.02, 2014 5. Singh S. K., "Industrial Instrumentation & Control", Tata McGraw Hill, 2 <sup>nd</sup> Edition, Reprint 2007 6. NPTEL video lectures on "Industrial Instrumentation" by Prof. Alok Barua, IIT Kharagpur
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Dr. A. Vimala Juliet, SRMIST

Course Code	18ECE281J	Course Name	PROCESS DYNAMICS AND CONTROL	Course Category	E	Professional Elective	L	T	P	C
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S-9	SLO-1	Laws and assumptions governing gas process	Tuning – Process reaction curve method	Valve Positioner and its importance	Adaptive controllers	Multi-loop multivariable control , Introduction
	SLO-2	Mathematical models of pressure processes	Z-N open loop tuning techniques	Control valve sizing	Model predictive control	Interaction between control loops
S-10	SLO-1	Laws and assumptions governing thermal process	Continuous cycling method	Cavitation and flashing	Smith predictor control scheme	The Relative Gain Array (RGA)
	SLO-2	Mathematical models of thermal processes	Damped oscillation method	Selection criteria	Internal model control (IMC) ,P& I diagram	Decoupling of control loops
S 11-12	SLO-1	Lab3: Determine the characteristics of non interacting system	Lab 6: Design on-off control, P,PI and PID controller for the level Process	Lab 9: Determine the characteristics of Pneumatically Actuated Control Valve (with and without Positioner)	Lab12: Compare the responses of simple and cascade control system using MATLAB	Case study : Design of computerized multi loop controller
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> <li>1. Seborg ,D.E., Mellichamp, D.P., Edgar, T.F., and Doyle,F.J., III, "Process Dynamics and Control", John Wiley and Sons, 4th Edition 2016</li> <li>2. Stephanopoulos. G" Chemical Process Control - An Introduction to Theory and Practice", Prentice Hall of India, 2nd Edition, 2015</li> <li>3. Gopal, M., "Digital Control and State Variable Methods", Tata McGraw Hill, 2003</li> <li>4. D.R. Coughanour, 'Process Systems analysis and Control', McGraw-Hill, 3rd Edition, 2013</li> <li>5. Bela.G.Liptak., "Process Control and Optimization", Instrument Engineers' Handbook., volume 2, CRC press and ISA, 2005</li> <li>6. Curtis D. Johnson Process Control Instrumentation Technology, 8th Edition, Pearson, 2006</li> <li>7. NPTEL video lectures on "Chemical Process Control" by Prof. SujitJogwar, IITM.</li> <li>8. P.W. Murrill., "Fundamentals of Process Control Theory", 3rd Edition-ISA Books</li> </ol>
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Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Mrs. N. Deepa, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Mrs. Indirani, SRMIST

Course Code	18ECE282T	Course Name	MODERN CONTROL SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ECS201T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Know and design various conventional compensators.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know and develop mathematical modeling using state space technique.				Thinking (Bloom)	Proficiency (%)	Attainment (%)	Engineering Knowledge	Analysis	Development	Design	Tool Usage	Culture	Int & ty	Team Work	Communication	E. & Finance	Learning				
CLR-3 :	Know and analyze the system using state space analysis techniques.																					
CLR-4 :	Know the importance of structural properties and to analyze the stability of the system.																					
CLR-5 :	Study the state space control methodologies for various systems.																					
CLR-6 :	Know and design modern control techniques which are linear.																					

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Design cascade compensators in time domain and design PID controllers in time domain.	3	80	75	H	H	H	-	L	-	-	H	-	-	-	H	H	-	H
CLO-2 :	Understand and develop state space model for different systems	3	80	70	H	L	H	-	H	-	-	H	-	-	-	-	M	-	H
CLO-3 :	Analyze the controllability and observability of a system and to design controllers and observers.	3	75	70	H	H	-	H	H	-	-	H	-	-	-	-	M	-	H
CLO-4 :	Implement procedure to find the structural properties of any linear system	3	80	75	H	H	-	H	H	-	-	H	-	-	-	-	M	-	H
CLO-5 :	Understand the procedure of applying the control methodology on various linear systems	3	80	70	H	H	H	H	H	-	-	H	-	-	-	H	M	-	H
CLO-6 :	Design and apply linear based modeling and modern control methods for different linear systems.	3	80	70	H	H	H	-	L	-	-	-	-	-	-	H	H	-	H

Duration (hour)	Linear Control Design	State Space Analysis	Controllability And Observability	Controller Design For Linear System	Applications
	9	9	9	9	9
S-1	SLO-1	Design specifications	Concept of State variables	Concept of Stability	State space Modeling of Inverted Pendulum
	SLO-2	Compensator configuration (series and feedback)-	Concept of State space model	Computation of Stability of State space model	
S-2	SLO-1	Design cascade compensators - lag by using time domain	Relationship between transfer function and State space model	Concept of Controllability	State space Modeling of Ball and Beam system
	SLO-2	Design feedback compensators - lag by using time domain	State space representation of linear continuous time systems using physical variables	Computation of Controllability of State space model	
S-3	SLO-1	Design cascade compensators - lead by using time domain	State space representation of linear continuous time systems using phase variables	Concept of Observability	State space Modeling of Translational Mechanical Systems
	SLO-2	Design feedback compensators - lead by using time domain	State space representation of linear continuous time systems using canonical variables	Computation of Observability of State space model	
S-4	SLO-1	Compensator design exercises	Conversion of transfer function to various state space representations	Computation of structural properties using Controllability & Observability	State space Modeling of Rotational Mechanical Systems
	SLO-2	Compensator design exercises			
S-5	SLO-1	Design cascade compensators – lead-lag by using time domain	Diagonalization	Computation of structural properties using eigen decomposition	Modeling exercises for Translational and Rotational Mechanical Systems
	SLO-2	Design feedback compensators – lead-	State space representation of discrete		

		lag by using time domain	time systems			
S-6	SLO-1	Design specifications – PID Controllers	Solution of state equations – from differential equations	Concept of Pole Placement by state feedback	Optimal Control – Linear Quadratic Regulation (LQR)	State space Modeling of Electrical Systems
	SLO-2	Effect of PID on linear systems		Concept of State Observers	Infinite Horizon Regulator	
S-7	SLO-1	Design of PD controller using time domain	Solution of state equations – from Transfer Functions	Control System Design Via Pole Placement by state feedback	Receding Horizon Regulator	Modeling exercises for Electrical Systems
	SLO-2	PD Controller design exercises			Receding Horizon Regulator - Design Parameters	
S-8	SLO-1	Design of PI controller using time domain	Concepts of state transition matrix.	Effect of state feedback	Controller Design with Reference Input	State space Modeling of Field controlled DC Motor
	SLO-2	PI Controller design exercises	Computation of state transition matrix		Tracking/ Servo Control using State Feedback	
S-9	SLO-1	Design of PID controller using time domain	Computation of state transition matrix	State feedback Controller design exercises	State controller with reference input design exercise	State space Modeling of Armature controlled DC Motor
	SLO-2	PID Controller design exercises				

Learning Resources	<ol style="list-style-type: none"> <li>1. Katsuhiko Ogata, "Modern Control Engineering"-fifth edition, Prentice Hall of India Private Ltd, New Delhi, 2009.</li> <li>2. Kirk D.E, "Optimal control theory-an introduction", Dover Publications, 2004.</li> <li>3. Richard .C, Dorf and Robert.H.Bishop, "Modern Control System Engineering", Pearson Education (US), United States, 2010.</li> <li>4. Gopal. M, "Modern Control System theory", New age international (P) ltd, 2012.</li> <li>5. Nagarath, I.J. and Gopal, M., "Control Systems Engineering", New Age International Publishers, 2010.</li> <li>6. NPTEL Video Lecture Notes on "Advanced Linear Continuous Control Systems "by Prof. Yogesh Vijay Hote, IIT Roorkee. <a href="https://nptel.ac.in/courses/108107115/">https://nptel.ac.in/courses/108107115/</a></li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Mr. Hariharasudhan - Johnson Controls, Pune, <a href="mailto:hariharasudhan.v@jci.com">hariharasudhan.v@jci.com</a>	2. Dr. D. Nedumaran, Madras University, <a href="mailto:dnmaran@gmail.com">dnmaran@gmail.com</a>	2. Mr. P. Jekan, SRMIST

Course Code	18ECE283J	Course Name	PROGRAMMABLE LOGIC CONTROLLER	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Study the hardware components of Programmable Logic Controller				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Understand the need of programming languages for PLC				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3	
CLR-3 :	Explore the ladder logic program for control application							H	L	-	-	-	-	-	-	-	L	-	-	H	H	H	H
CLR-4 :	Identify applications of timers and counters in process automation							H	H	H	H	H	-	-	H	H	M	-	H	H	H	H	H
CLR-5 :	Locate the malfunctions and troubleshooting various types of errors in Programmable Logic Controller							H	H	H	H	H	-	-	H	H	M	-	H	H	H	H	H
CLR-6 :	Provide the knowledge of Commissioning, Maintenance and their importance in industry.							H	H	-	H	H	-	-	-	H	H	-	H	M	H	H	H
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:						3	80	75	H	L	-	-	-	-	-	-	L	-	-	H	H
CLO-1 :	Select right I/O modules in PLC for process control				3	80	70	H	H	H	H	H	-	-	H	H	M	-	H	H	H	H	
CLO-2 :	Develop ladder logic program for control application				3	75	70	H	H	H	H	H	-	-	H	H	M	-	H	H	H	H	
CLO-3 :	Use timers and counters in process automation				3	80	75	H	H	H	H	H	-	-	H	H	M	-	H	H	H	H	
CLO-4 :	Interpret data compare instruction in PLC program				3	80	70	H	H	-	H	H	-	-	H	H	M	-	H	M	H	H	
CLO-5 :	Troubleshoot the input and output malfunctions in PLC				3	80	70	H	H	-	H	H	-	-	H	H	M	-	H	M	H	H	
CLO-6 :	Select a right PLC for the given application				3	80	70	H	H	-	-	-	-	-	H	H	-	M	M	H	H	H	

Duration (hour)		PLC Hardware Components	PLC Programming and Wiring	Timers and Counters	Data manipulation and Math instructions	Troubleshooting
		12	12	12	12	12
S-1	SLO-1	Evolution of Programmable logic controllers	PLC programming languages-Ladder Logic	Timer Instructions	Data manipulation	Electrical Noise
	SLO-2	Architecture of a PLC	Function Block Diagram, Instruction List	On-Delay timer instruction	Data transfer operations	Leaky Inputs and Outputs
S-2	SLO-1	Principles of Operation	Instruction Addressing	Off-delay timer instruction	Data compare instructions	Grounding
	SLO-2	PLCs versus Computers	Branch Instructions	Retentive Timer	Data manipulation programs	Voltage Variations and Surges
S-3-4	SLO-1	Lab1: PLC Wiring	Lab 4: Traffic light control system	Lab 7: HMI Programming	Lab10: Lift control	Lab13: Electro pneumatic direction control
	SLO-2					
S-5	SLO-1	PLC size and application	Electromagnetic Control Relays	Cascading Timers	Numerical Data I/O Interfaces	Program Editing and Commissioning
	SLO-2	Discrete I/O modules	Contactors	Up-Counter	Closed-Loop Control	Preventive Maintenance
S-6	SLO-1	Sinking and sourcing	Manually Operated Switches	One-Shot Instruction	Math Instructions	Troubleshooting
	SLO-2	Analog I/O modules	Mechanically Operated Switches	Down-Counter	Addition Instruction	Processor Module
S-7-8	SLO-1	Lab 2 :Water level control system	Lab 5: Sequential operation of motor	Lab 8: DC motor speed control system	Lab11: Car parking system	Lab14: Stamping machine control
	SLO-2					
S-9	SLO-1	Special I/O modules	Proximity Sensor, Magnetic Reed Switch	Cascading Counters	Subtraction Instruction	Input Malfunctions
	SLO-2	I/O Specifications	Light Sensors, Velocity and Position Sensors	Combining Counter and Timer Functions	Multiplication Instruction	Output Malfunctions
S-10	SLO-1	Human Machine Interfaces (HMIs)	Output Control Devices, Seal-In Circuits, Electrical Interlocking Circuits	High-Speed Counters	Division Instruction	Comparative study of Industrial PLCs.
	SLO-2	Alarms, Graphics Library	Converting Relay Schematics into PLC	Problems	Other Word-Level Math Instructions	



			Ladder Programs			
S 11-12	SLO-1 SLO-2	Lab3: Material handling system	Lab 6: Bottle filling system	Lab 9: Temperature control system	Lab12: Flow control system	Lab15: Servo controller programming

Learning Resources	1. Frank D. Petruzella, "Programmable Logic Controller", Tata McGraw Hill 5 <sup>th</sup> Edition, 2017. 2. Bolton. W, "Programmable Logic Controllers", 6 <sup>th</sup> Edition, Elsevier Newnes, 2016. 3. John W. Webb, Ronald A. Reis, "Programmable Logic Controllers", Principles and Applications, Prentice Hall, 5 <sup>th</sup> Edition, 2011	4. Gary Dunning, "Programmable Logic Controllers", Cengage Learning, 3 <sup>rd</sup> Edition, 2009. 5. John R. Hackworth, "Programmable logic controllers Programming Methods and Applications", Pearson, 1 <sup>st</sup> Edition, 2006 6. NPTEL Video Lecture Notes on "Industrial Automation and Control" by Prof. S. Mukhapadhyay, IIT Kharagpur
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Mr. J. Sam Jebakumar, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaman@gmail.com	2. Dr. G. Joselin Retna Kumar, SRMIST

Course Code	18ECE284J	Course Name	GRAPHICAL SYSTEM DESIGN IN VIRTUAL INSTRUMENTATION	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Study the concepts of Virtual instrumentation and to learn the programming concepts in VI.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO – 3
CLR-2 :	Study about the various measurement systems and their data acquisition methods in real time.																						
CLR-3 :	Study about the various Instrument Interfacing concepts.																						
CLR-4 :	Explore various control techniques using VI software																						
CLR-5 :	Explore various remote accessing techniques																						
CLR-6 :	Get exposed with various analysis tools for Process control applications.																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Expected Proficiency (%)	Expected Attainment (%)																	
CLO-1 :	Identify the purpose and need of virtual instrumentation in process control Industries				1,2	80	70	H	-	-	-	-	-	-	-	-	H	-	-	-	H	-	-
CLO-2 :	Measure the parameters using various data acquisition methods.				2,3	85	75	H	H	-	-	-	-	-	-	H	H	-	H	H	H	-	-
CLO-3 :	Implement the available interfacing instruments				2,3	75	70	H	H	H	H	H	-	-	-	-	H	-	H	H	H	H	-
CLO-4 :	Implement various control techniques using VI software				2,3	85	80	H	H	H	H	H	-	-	-	H	H	-	H	H	H	H	-
CLO-5 :	Apply remote accessing Techniques				2,3	85	75	H	H	H	H	H	-	-	-	-	H	H	H	H	H	-	H
CLO-6 :	Develop a system for an engineering application.				2,3	80	70	H	H	H	H	H	-	-	-	H	H	H	H	H	H	H	-

Duration (hour)		Programming Concepts in LabVIEW	Measuring Concepts in Virtual Instrumentation	Controlling Concepts in Virtual Instrumentation	Final Control Elements and its implementation	Signal Processing and Applications
		12	12	12	12	12
S-1	SLO-1	Historical perspective, Need of VI, Advantages of VI, Virtual Instruments versus Traditional Instruments	Components of Measuring System, Origin of signals	Introduction to Non continuous controllers in LabVIEW	Final Control Operation	PC based digital storage oscilloscope
	SLO-2	Review of software in Virtual Instrumentation, Software environment Architecture of VI, Introduction to the block diagram and Front panel Palettes	Transducer, Sensors, Differences between chemical sensors, physical sensors, Biosensors. Selection criteria	Introduction to continuous controllers in LabVIEW	Fundamentals of Mechatronic Actuators	Sensor Technology
S-2	SLO-1	Creating and saving a VI, Front Panel Tool Bar, Block diagram Tool Bar, Palettes	General Conditioning Functions, A/D Control; D/A Control in VI platform	Design of ON/OFF controller	Position-Controlled Actuators	Oscillators, counters
	SLO-2	Creating sub VI, Creating an ICON, Building a connector pane, Displaying VI'S Placing and Saving Sub VI'S on block diagram Example of full adder circuit using half adder circuit	Introduction to MyRIO, Applications of MyRIO	P,PI,PID controllers for a mathematically described processes using VI software.	Open-loop and closed-loop actuator position control in a hands-on application	Signal and image processing Techniques
S-3,4	SLO-1	Lab 1: Verification of Arithmetic Operations & Verification of Half Adder	Lab 4 :Design a VI to measure angle with my RIO using Y-axis onboard accelerometer	Lab 7: To apply on-off controller using QNET HVAC in virtual instrumentation platform	Lab 10: To apply Position Controlled actuators	Lab 13: To Design of DSO
	SLO-2					
S-5	SLO-1	Loops-For Loop,	Introduction to PC Buses	Modeling of level process	Manipulator Importance, Operation of Manipulators	Spectrum Analyzer
	SLO-2	While Loop	Local Buses-ISA, PCI,	Basic control of level process in LabVIEW	Types of Manipulators Selection	Waveform Generator

S-6	SLO-1	Arrays	RS232, RS422	Modeling of Reactor Processes	Criteria, Controlling techniques on Manipulators	Data visualization from multiple locations
	SLO-2	Clusters, plotting data	RS485	Basic control of Reactor process in LabVIEW	Controlling techniques on Manipulators	Distributed monitoring and control
S-7,8	SLO-1	Lab 2:Program to find Addition of First n natural numbers using for loop	Lab 5:To implement Speed Control of DC Motor (QNET)	Lab 8:Continuous Control of any process using LabVIEW	Lab 11:To apply PID to Control Manipulators	Lab 14:Real time spectrum analysis using LabVIEW
	SLO-2	Charts, Graphs, Formula nodes,	Interface Buses-USB,PXI	Case studies on development of HMI in VI	Remote access using LabVIEW	Vision and Motion Control
S-9	SLO-1	Case and Sequence Structures	VXI,	Case studies on development of HMI in VI	Different types of Protocols	Examples on Integrating Measurement with vision and motion
	SLO-2	Acquiring Data Using Hardware	SCXI	Case studies on development of SCADA in VI	Case study on TCP/IP Protocol application	NI Motion control
S-10	SLO-1	DAQ Devices	PCMCIA	Case studies on development of SCADA in VI	Case studies on web publishing tool	Speed control system
	SLO-2	Lab 3:Design a Voltmeter by using AO to generate a signal and AI to acquire the signal using DAQ	Lab 6: Simple Modeling of QNET Rotary Inverted Pendulum	Lab 9:Controlling of Rotary Inverted Pendulum	Lab 12:Online process control using LabVIEW using TCP/IP and web publishing	Lab 15 :Minor Project

Learning Resources	<ol style="list-style-type: none"> <li>1. Nadovich, C., "Synthetic Instruments Concepts and Applications", Elsevier, 2005.</li> <li>2. Bitter, R., Mohiuddin, T. and Nawrocki, M., "Labview Advanced Programming Techniques", CRC Press, 2nd Edition, 2007.</li> <li>3. Gupta, S. and Gupta, J. P., "PC Interfacing for Data Acquisition and Process Control", 2nd Edition, Instrument Society of America, 1994</li> <li>4. Liptak, "Instrument Engineers Handbook Process Measurement and Analysis", Elsevier, 2005</li> </ol>	<ol style="list-style-type: none"> <li>5. Jamal, R. and Picklik, H., "Labview – Applications and Solutions", National Instruments Release.</li> <li>6. Johnson, G., "Labview Graphical programming", McGraw-Hill, Newyork, 1997.</li> <li>7. Wells, L.K. and Travis, J., "Labview for Everyone", Prentice Hall, NewJersey, 1997.</li> <li>8. Buchanan, W., "Computer Busses", CRC Press, 2000.</li> </ol>
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Learning Assessment											
	Bloom'sLevel of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	

Course Code	18ECE380T	Course Name	INSTRUMENTATION AND CONTROL IN PROCESS	Course Category	E	Professional Elective	L	T	P	C
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			INDUSTRIES				3	0	0	3
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Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Learn various methods involved in the petroleum industries.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Import the knowledge of control and measurement used in iron and steel industries.																							
CLR-3 :	Study the various instruments and the role of instrumentation in paper industries.																							
CLR-4 :	Learn the measurement and control in thermal industries.																							
CLR-5 :	Study the industry standards and safety consciousness in process industries.																							
CLR-6 :	Import the knowledge of chemical process hazards in industries.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Expected Proficiency (%)	Expected Attainment (%)	Expected Attainment (%)	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLO-1 :	Understand the basics of petrochemical industries.																							
CLO-2 :	Apply knowledge in working of various instruments that are used in iron and steel industries.																							
CLO-3 :	Acquire the knowledge of analyzers and measurement of density, level in paper industries.																							
CLO-4 :	Understand the operation of boiler in thermal industries.																							
CLO-5 :	Understand the process safety in chemical industries.																							
CLO-6 :	Apply the knowledge of process hazards in industries.																							

Duration (hour)		Instrumentation in Petroleum Industry	Measurement and control in Iron and Steel Industry	Instrumentation and control in Paper Industry	Boiler operation and control in Thermal Industry	Industrial Safety Management
		9	9	9	9	9
S-1	SLO-1	<i>Introduction to petroleum</i>	<i>Introduction: Steel Production</i>	<i>Conventional and non-conventional raw materials for paper manufacture</i>	<i>Introduction to power generation</i>	<i>Introduction to process safety</i>
	SLO-2	<i>Petroleum exploration Methods</i>	<i>Basic oxygen furnace</i>	<i>Different pulping processes</i>	<i>Importance of instrumentation &amp; control in power generation</i>	<i>Importance of Safety consciousness in Indian Chemical Industries</i>
S-2	SLO-1	<i>Magnetic Survey</i>	<i>Blast furnace</i>	<i>Continuous and batch digesters</i>	<i>Classification of instruments in power plant</i>	<i>Industry Standards and Regulations.</i>
	SLO-2	<i>Drilling process</i>	<i>Rolling process</i>	<i>Chemical recovery process</i>	<i>Building blocks</i>	<i>Set of Standards. HSE – PES,AIChE – CCPS,</i>
S-3	SLO-1	<i>Rotary Drilling</i>	<i>Hot rolling process</i>	<i>Conversion process</i>	<i>Combined Heat and Power System</i>	<i>Process hazard analysis</i>
	SLO-2	<i>Petroleum production</i>	<i>Cold rolling process</i>	<i>Identification of various process parameters</i>	<i>Control Loops in Boiler</i>	<i>Chemical process hazards</i>
S-4	SLO-1	<i>Petroleum refining and unit operations in refinery</i>	<i>Temperature measurement</i>	<i>PH measurement</i>	<i>Combustion Control,</i>	<i>Material hazards</i>
	SLO-2	<i>Constituents of crude oil</i>	<i>Pressure measurement</i>	<i>Density measurement</i>	<i>Air/fuel ratio control</i>	<i>Energy hazards</i>
S-5	SLO-1	<i>Atmospheric distillation of crude oil</i>	<i>Shape and thickness measurement</i>	<i>Level measurement</i>	<i>Steam flow measurement</i>	<i>Chemical interaction hazards</i>
	SLO-2	<i>Vacuum distillation process</i>	<i>Analyzers in iron and steel industry</i>	<i>Special applications for control</i>	<i>Smoke, density measurement</i>	<i>Layers of protection</i>
S-6	SLO-1	<i>Thermal conversion process</i>	<i>Oxygen analyzer</i>	<i>Digester blow tank control</i>	<i>Turbine speed and vibration measurement</i>	<i>Types of safeguard</i>
	SLO-2	<i>Control of distillation column</i>	<i>Blast furnace and stove combustion</i>	<i>Dryer temperature control.</i>	<i>Use of feed forward and cascade control</i>	<i>Safety performance measurement tools</i>



			control system		in process industries	
S-7	SLO-1	Temperature control.	Casting mold Level Control	Fuel gas oxygen analyzer	Instrumentation and control in reactors	Techniques used to reduce explosion hazards
	SLO-2	Pressure control	Computer Applications	Dissolved oxygen analyzer	Sodium analyzer	Hazard identification techniques
S-8	SLO-1	Level measurement of petroleum	Data logging applied to Steel Making	Computer applications:Direct Digital Control	Flue gas analyzer	Fault tree analysis
	SLO-2	Temperature measurement of petroleum	Steel rolling mill Control	Distributed control system in power plant	Fuel composition analyzer	Operation and maintenance
S-9	SLO-1	Case Study: An. Application for Petroleum Refineries.	Case Study on iron and steel manufacturing process.	Case Study: Water Treatment for Paper and Pulp Industry	Case Study: Chandrapura Thermal Power Station	Case Study: Safety in Explosive
	SLO-2	Case Study: Control of an Industrial Distillation Column	Case Study: Analysis of the Production Processes in a Steel Factory	Case Study: Boiler Materials for the Pulp and Paper Industry	Case Study:Boiler tube failures	Case Study: Chemical splash at process plant.

Learning Resources	1. Mian.M.A, "Petroleum Engineering Handbook for the Practicing Engineer", Gulf Professional Publishing, 2005. 2. Liptak, Bela G, "Instrumentation in the Processing Industries", Chilton Publishers, 1973. 3. Considine D. M., "Process/Industrial Instruments and control Handbook", McGraw Hill, 6 <sup>th</sup> Edition 2019.	4. Sam .G.Duke low, "The Control of boilers", instrument Society of America, 1991. 5. Paul Gruhn& Harry Cheddie, Safety Instrumented Systems: Design, Analysis and Justification, 2 <sup>nd</sup> Edition, International Society of Automation, 2005.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controls of Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Ms. A.Asuntha, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Dr. A. Vimala Juliet, SRMIST

Course Code	18ECE381T	Course Name	DISTRIBUTED CONTROL SYSTEM AND SCADA	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Give basic knowledge in SCADA in the field of automation				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the Communication modules used in SCADA																							
CLR-3 :	Give basic knowledge in different architectures of DCS																							
CLR-4 :	Explore the local control unit of distributed control system																							
CLR-5 :	Impart adequate information in the interfaces used in DCS																							
CLR-6 :	Learn the applications of DCS in process industries																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Expected Proficiency (%)	Expected Attainment (%)		Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLO-1 :	Understand the elements of SCADA system				3	80	75	H	-	-	-	-	H	-	-	-	-	-	H	M	H	-	-	
CLO-2 :	Develop any application based on SCADA along with GUI using SCADA software.				3	80	70	H	-	-	-	-	H	-	-	-	-	H	H	-	H	-	-	
CLO-3 :	Understand evolution and architecture of DCS and hierarchical control in DCS				3	75	70	H	H	M	H	M	H	-	M	M	-	H	H	H	H	H	H	
CLO-4 :	Demonstrate interfacing of hardware and software of computer based automation system.				3	80	75	H	H	M	H	M	-	-	M	H	-	H	H	M	H	H	H	
CLO-5 :	Select and use the most appropriate automation technologies for a given application				3	80	70	H	-	M	-	H	-	-	H	H	-	H	H	M	H	H	H	
CLO-6 :	Evaluate computer based automation system used in industries ranging from discrete, continuous process to hybrid processes.				3	80	70	H	-	-	-	-	H	-	H	H	-	H	H	H	H	H	H	

Duration (hour)		SCADA Elements	Communication	DCS Architecture	Operator interface	DCS Application
		9	9	9	9	9
S-1	SLO-1	SCADA basics introduction	SCADA Communication introduction	DCS - basics	DCS operator interfaces- introduction	DCS Application in Power plant
	SLO-2	Elements of SCADA	Communication system components	Evolution of Distributed Control System	Operator Interface Requirements	Automation strategy
S-2	SLO-1	Functionality of SCADA	Structure of a SCADA Communications Protocol	DCS Architecture	Low-level Operator Interface	Distributed system structure
	SLO-2	Process example	Field/RTU Communication	Local control unit	Continuous control station	Application functions
S-3	SLO-1	History of SCADA	Analog electronic controllers	I/O module(Analog & Digital)	Manual Loader Station	DCS Application in cement plant
	SLO-2	Development from Telemetry	Communication Topology	Basic elements	Indicator/Logic Station	System architecture
S-4	SLO-1	Key features	RTU/MTU Communication	Architectural parameters	Smart annunciators	DCS Application in iron plant
	SLO-2	Real time systems	System components	Types of architecture	High level Operator interface	System architecture
S-5	SLO-1	Analog signals measurement	Communication Protocols	CPU, Memory	Architectural Models	DCS Application in steel plant
	SLO-2	Control techniques	Operator interface	Local control unit languages	Hardware Elements	System architecture
S-6	SLO-1	Discrete signals measurement	Monitoring alarms	Language requirements	Operator displays	DCS Application in Paper and pulp industry
	SLO-2	Control techniques	Status points	Functional blocks	Engineering interface- Introduction	System architecture
S-7	SLO-1	Remote terminal unit	Control interfacing	Problem-oriented languages	System configuration requirements	DCS Application in petroleum-refining industry
	SLO-2	Analog and Discrete control	Parallel operator interface	High-level languages	Diagnosis of System Problems	
S-8	SLO-1	Monitoring signals	SCADA Development for any one typical application	Process interfacing issues	Low-level engineering interface	DCS Application in oil and gas processing industry.
	SLO-2	Master terminal unit		Security design issues	System configuration	
S-9	SLO-1	Process configuration	Programming for GUI development using SCADA software	Process input/output design issues	High-level engineering interface	DCS Application in water treatment plant
	SLO-2	Applications		Remote I/O and Communication	System configuration	System architecture

			modules		
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Learning Resources	1. Stuart Boyer A, "SCADA : Supervisory control and data Acquisition", Fourth Edition, ISA-The Instrumentation, Systems, and Automation Society, 2010 2. Dobrivojic Poppovik, Vijay P Bhatkar, "Distributed Computer Control Systems in Industrial Automation" CRC Press, 1990	3. Michael Lucas, "Distributed Control Systems", Van Nostrand Reinhold Co., 1986 4. IDC Technologies, "Practical Distributed Control Systems (DCS) for Engineers and Technicians" 2012 5. Krishna Kant, Computer Based Industrial Control, 2 <sup>nd</sup> Edition, Prentice Hall of India, New Delhi, 2010
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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1. D. Karthikeyan, Controls of Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in		1. Dr. J. Prakash, MIT, Chennai, prakait@rediffmail.com
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com
		Internal Experts
		1. Dr. G. JoselinRetna Kumar, SRMIST
		2. Mr. J. SamJeba Kumar, SRMIST

Course Code	18ECE382T	Course Name	BUILDING AUTOMATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Give basic knowledge in intelligent building and building automation systems	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Gain Knowledge on different sensors and measurement systems in BMS system	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Know the basic concepts of HVAC Air handling unit				H	-	-	-	-	H	H	-	-	-	-	H	H	H	H
CLR-4 :	Understand the basic concepts of HVAC terminal unit				H	-	-	-	-	H	H	-	-	-	H	H	-	M	H
CLR-5 :	Explore the BAS Architecture				H	H	M	H	M	M	H	H	-	-	H	H	M	M	H
CLR-6 :	Present an overview of different Communication protocols				H	-	M	-	H	-	M	H	-	-	-	H	-	M	H
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		3	80	75	H	-	-	-	-	H	-	H	-	H	M	H	H	-	H
CLO-1 :	Understand the need of intelligent buildings and automation systems	3	80	70	H	-	-	-	-	H	H	-	-	-	H	H	-	M	H
CLO-2 :	Measure the parameters and design of sensors	3	75	70	H	H	M	H	M	H	M	H	-	-	H	H	M	M	H
CLO-3 :	Design different Air handling units	3	80	75	H	H	M	H	M	-	M	H	H	-	-	H	-	M	H
CLO-4 :	Understand and design terminal units	3	80	70	H	-	M	-	H	-	M	H	-	-	-	H	-	M	H
CLO-5 :	Familiarize with the components of BAS architecture	3	80	70	H	-	-	-	-	H	-	H	-	H	M	H	H	-	H
CLO-6 :	Select the Communication protocol for a particular application	3	80	70	H	-	-	-	-	H	-	H	-	H	M	H	H	-	H

Duration (hour)		Introduction to Building automation systems	Comfort parameters	HVAC Basic Concepts- Air handling unit	Terminal Unit	BAS Architecture
		9	9	9	9	9
S-1	SLO-1	Introduction to intelligent building	Temperature	Concept of Air handling unit	Concept of Variable Air Volume (VAV) system	BAS Hierarchy
	SLO-2	Intelligent architecture	Enthalpy, Entropy	Components in AHU	Different types of VAV	Field level components
S-2	SLO-1	Structure	Heat Transfer - Conduction, Convection, Radiation	Different types of dampers	Design, working	Direct Digital Control (DDC)
	SLO-2	Facility management vs. intelligent buildings	Working Principle, Characteristics of RTD	Working, configuration,	Series fan powered	Supervisory Controller
S-3	SLO-1	Lifecycle of building	Thermistor, Thermocouple	Different types of AHU	Parallel fan powered	Server, Operator Workstation (OWS)
	SLO-2	Evolution of intelligent buildings	Bimetallic strip	Design and working	Pressure dependent	Different Communication protocol
S-4	SLO-1	Introduction to BAS	Humidity, Specific Humidity,	Operation of different modes in AHU	Supply-exhaust VAV	Addressing concepts
	SLO-2	Different systems of BAS	Relative Humidity, Dew point, Saturation point	Humidification	Dual duct VAV	Open Protocols -BACnet, LON
S-5	SLO-1	HVAC	Working principle of relative humidity sensors	Dehumidification	Design, working, use of radiation coil	Profibus, Modbus
	SLO-2	HVAC Applications	Mounting for humidity sensors in BAS	Static pressure control	Chilled beam	M-bus
S-6	SLO-1	Security system	Psychrometric chart	Volume matching	CRAC unit, VRF systems	Proprietary Protocols- N2, CBUS
	SLO-2	Field Devices	Pressure, Static Pressure, Velocity pressure, Absolute Pressure	Cooling, heating,	Unit heater, Fan coil unit and unit ventilator	Wireless field devices
S-7	SLO-1	Fire alarm system	Gauge Pressure, Vacuum Pressure, Differential Pressure, Sealed Pressure	Economizer mode	Chilled water system	Controllers



	SLO-2	Types of Detectors	Working Principle of Different types of Pressure Sensors	Heat recovery techniques	Concept of refrigeration cycle, components used in refrigeration cycle	Routers
S-8	SLO-1	Modules	Working of principle of different air flow sensors	Plate heat exchanger	Different types of chilled water system	Cordinators
	SLO-2	Indicating Devices	Working of principle of different water flow sensors	Heat recovery wheel	Working and design of different types of boilers	Benefits of a Wireless BAS
S-9	SLO-1	Lighting systems	Measurement of CO2 level	AHU for different applications	Working and design of different types of heat exchanger	Wireless Field Bus
	SLO-2		Working principal of BTU meter			Basic Reference Model (BRM)

Learning Resources	1. Smart Buildings by Jim Sinopoli, Butterworth-Heinemann imprint of Elsevier, 2 <sup>nd</sup> Edition., 2010 2. Intelligent Building Systems by Albert Ting-Pat So, WaiLok Chan, Kluwer Academic publisher, 3 <sup>rd</sup> Edition. 2012.	3. Design of Special Hazards and Fire Alarm Systems by Robert Gagnon, Thomson Delmar Learning; 2 <sup>nd</sup> Edition, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1. Dr.G.JoselinRetna Kumar, SRMIST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2. Mr.J.SamJeba Kumar, SRMIST

Course Code	18ECE383J	Course Name	INSTRUMENTATION SYSTEM DESIGN	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Impart knowledge on basic signal conditioning circuits.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Familiarize students on the requirements of industry.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Obtain adequate knowledge on process parameter optimization.				H	H	H	M	-	-	-	-	-	-	-	M	H	-	-
CLR-4 :	Gain expertise to handle basic instruments in Industry.				H	H	-	M	H	-	-	-	H	-	L	-	M	M	H
CLR-5 :	Acquire knowledge of piping diagram in Industry.				H	-	M	M	M	-	H	M	-	-	-	-	-	-	M
CLR-6 :	Bridge the gap between industrial requirements and operational constraints.				H	M	-	M	-	M	M	-	-	-	-	-	-	M	-
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>					H	-	H	-	-	-	M	-	H	M	-	-	H	-	L
CLO-1 :	Apply mathematical knowledge, science, engineering fundamentals to design circuits pertaining to various process measurements	3	80	75	H	H	-	-	-	-	-	-	-	-	-	-	H	M	H
CLO-2 :	Design signal conditioning circuits for various process parameters.	3	80	70	H	-	M	M	M	-	H	M	-	-	-	-	-	-	M
CLO-3 :	Optimize the performance of process output.	3	75	70	H	M	-	M	-	M	M	-	-	-	-	-	-	M	-
CLO-4 :	Select optimal sensor for process measurement.	3	80	75	H	-	H	-	-	-	M	-	H	M	-	-	H	-	L
CLO-5 :	Choose type of indication circuits for industry.	3	80	70	H	H	-	-	-	-	-	-	-	-	-	-	H	M	H
CLO-6 :	Analyze and select the suitable sensing and transduction unit.	3	80	70	H	H	-	-	-	-	-	-	-	-	-	-	H	M	H

Duration (hour)		Review of Signal Conditioning circuits	Design of Level and Pressure Measurement	Design of Flow measurements and Control Valve	Design of Transmitters and final control element	Design of indicators and Logic circuits
		12	12	12	12	12
S-1	SLO-1	Requirements of Signal Conditioning	Electronic PID controller Design.	Study of Orifice, Venturi and Rotameter.	2 Wire and 3 wire transmitter	Alarm circuit design
	SLO-2	Analog, Digital and adaptive filter design	P,I,D modes of operation Solving numerical..	Review of design requirements.	Thermocouple based temperature transmitter	Annunciator circuit design
S-2	SLO-1	V/I and I/V Converter design. Design of amplifiers – Pre amplifier	Composite modes – PI, PD and PID.	Design of Orifice.	Design of transmitter	Interlocks
	SLO-2	Instrumentation Amplifier, Bridge and Isolation Amplifier.	Realization using composite modes.	Design of Rotameter.	Capacitance based flow transmitter	Overview of Programmable logic controllers
S-3-4	SLO-1	Lab1: Design of Active Filters – LPF, HPF and BPF.	Lab 4: Design, Fabrication and Testing of Analog PID Controller.	Lab 7: Development of Software Program for sizing Orifice.	Lab10: Design, Fabrication and Testing of 2-wire Analog Transmitter.	Lab 13: Sequential controller using PLD
	SLO-2	Signal conditioning circuits for temperature measurement. – RTD.	Requirements of Pressure Measurement.	Design constraints.	Level transmitter	Microprocessor based PID controller
S-5	SLO-1	Design of RTD	Bourdon tube, Bellows, Diaphragms	Study of Valve characteristics and valve body	Flapper nozzle amplifier characteristics	Study of recorders
	SLO-2	Signal Conditioning for Thermocouple.	Factors affecting sensitivity.	Design of Actuator and positioner	Pneumatic actuator	Numerical in alarm circuit
S-6	SLO-1	Design of thermocouple	Adjustment of set point, bias and controller settings	Control Valve sizing	Hydraulic actuator	Real time case study
	SLO-2	Lab 2: Design of Instrumentation	Lab 5: Design of V/I and I/V converter.	Lab 8: Development of Software Program	Lab11: Design of multi channel data	Lab 14: Functional constraints and

	SLO-2	Amplifier.		for sizing Rotameter.	acquisition system	specification in industry
S-9	SLO-1	Cold junction compensation and Linearization.	Air purge Level Measurement	Design of Control valve factor and plug area.	Characteristics of pumps	Operating console and control room panel design.
	SLO-2	Design of cold junction compensation circuits.	Design of air purge system	Selection of material for body and trim.	Instruments used in pumping practices	Instrument symbols and signals
S-10	SLO-1	Zero and Span adjustment in Temperature Transmitters.	Capacitive based level Measurement.	Cavitation and flashing in Control valve	Pump operation and maintenance	Mini project on any process application.
	SLO-2	Temperature indicators and selection criteria for temperature sensing instruments.	Design of capacitance based level measurement.	Characteristics of control valve for typical applications	Selection of pumps	Discussion on project
S 11-12	SLO-1	Lab3: Design of regulated power supply.	Lab 6: Design of signal conditioning circuits for level measurements.	Lab 9: Study of control valve characteristics	Lab12: Study of P&I diagrams	Lab 15: Process application

Learning Resources	1. C.D.Johnson, "Process Control Instrumentation Technology", 8th Edition, Prentice Hall, 2015. 2. Bentley, J. P., Principles of Measurement Systems, Pearson Education, 2015. 3. Beta G.Liptak, "Instrument Engineers Handbook – Process Control and Optimization". 4th Edition. CRC Press. 2008.	4. N.A.Anderson, Instrumentation for Process Measurement and Control, Chilton Company, 2003. 5. R.W.Miller, "Flow measurement engineering Handbook", McGraw hill. New York, 1996.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100 %		100 %		100 %		100 %		-	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in	1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com	1.S.Sharanya SRM IST
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com	2. Dr. D. Nedumaran, Madras University, dnmaran@gmail.com	2.Dr.G.Joselin Retna Kumar

Course Code	18ECE384T	Course Name	FACTORY INSTRUMENTATION NETWORKS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Educate on the basic concepts of data networks	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Introduce the basics of inter-networking and serial Communications																							
CLR-3 :	Provide details on HART and Field busses																							
CLR-4 :	Know different techniques on Modbus, PROFIBUS and other Communication protocols																							
CLR-5 :	Present an overview of industrial Ethernet																							
CLR-6 :	Study the working of computer busses and protocols																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Understand the basic concepts of data networks	3	80	75																				
CLO-2 :	Analyze the techniques of inter-networking and serial Communications	3	80	70																				
CLO-3 :	Understand the protocols and layers of HART and field bus	3	75	70																				
CLO-4 :	Analyze the techniques of MODBUS, PROFIBUS and other Communication protocol	3	80	75																				
CLO-5 :	Utilize the concept of industrial Ethernet	3	80	70																				
CLO-6 :	Analyze the working of computer busses and protocols	3	80	70																				

Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	H	-	-	M	H	-	-	-	-	-	H	H	-	H
H	-	-	H	-	H	-	-	-	-	-	H	-	M	H
H	-	M	H	M	H	-	H	-	H	M	H	M	H	H
H	H	M	H	M	-	-	H	H	H	H	H	-	H	H
H	-	M	-	H	-	-	H	-	H	H	H	H	H	H
H	-	M	-	-	H	-	H	-	H	-	H	H	H	H

Duration (hour)		OSI Model 9	Inter-Networking	HART and Field bus 9	PROFIBUS and Modbus 9	Industrial Ethernet 9
S-1	SLO-1	Introduction to Modern instrumentation	Introduction to RS-232	Introduction to HART and smart instrumentation	Introduction to PROFIBUS	Introduction to Industrial Ethernet
	SLO-2	Introduction to control systems	RS-422 and RS-423	HART protocol	PROFIBUS protocol stack	10 Mbps Ethernet
S-2	SLO-1	Open systems interconnection (OSI) model	Electrical characteristics of RS 232	Physical layer- Analog 4–20 mA	Physical layer (layer 1)	Media systems
	SLO-2	Representation of the OSI model	Examples	Digital frequency shift keying (FSK)	Type A cable	10Base5, 10Base2, 10BaseT
S-3	SLO-1	Protocols	Communications between two nodes	Data link layer	Type B cable	Signaling methods
	SLO-2	Basic structure of an information frame defined by a protocol	Transmission and reception of characters	HART protocol implementation of OSI model layer	Data link layer (layer 2)	Medium access control
S-4	SLO-1	Standards	Simple no-handshaking Communications	Application layer- Universal commands	Hybrid medium access control	Frame transmission
	SLO-2	EIA-232 interface standard	Software handshaking	Common practice commands, Device specific commands	Application layer	Frame reception
S-5	SLO-1	EIA-485 interface standard	Hardware handshaking	Troubleshooting	Introduction to Modbus	MAC frame format
	SLO-2	Interoperability, Interchangeability	Two-way Communications with handshaking	HART cable length calculation	Modbus protocol structure	Differences between IEEE 802.3 and Blue Book Ethernet (V2)
S-6	SLO-1	Mod bus	DTE-DCE connections (PC to modem)	Introduction to foundation field bus	Function codes	IEEE 802.2 LLC
	SLO-2	Data Highway Plus protocol structure	Exercises	Physical layer	Read coil or digital output status (function code 01) and Read digital input status (function code 02)	Reducing collisions



S-7	SLO-1	DeviceNet	Introduction to RS-485 (ISO 8482)	Wiring rules	Read holding registers (function code 03) and Reading input registers (function code 04)	Design rules
	SLO-2	Profibus	RS-485 connecting to multiple nodes	Encoding rule, permeable and delimiters	Force single coil (function code 05)	Length of the cable segments
S-8	SLO-1	Introduction to OLE for process control	Line drivers	Data link layer	Preset single register (function code 06)	100 Mbps Ethernet
	SLO-2	Common problems and solutions	Unbalanced digital interface circuit (RS-423) and balanced digital interface circuit (RS-422)	Data link layer: packet format	Troubleshooting	Media access: full-duplex
S-9	SLO-1	General comments on troubleshooting	RS-232/485 converter	Application layer	Common Problems and Discussion	Auto-negotiation
	SLO-2	Specific Methodology	Exercises	User layer	Modbus Plus protocol overview	Fiber optic cable distances 100BaseFX

Learning Resources	<ol style="list-style-type: none"> <li>1. Steve Mackay, Edwin Wrijut, Deon Reynders, John Park, "Practical Industrial Data Networks Design, Installation and Troubleshooting", Newnes Publication, Elsevier 1<sup>st</sup> edition, 2004.</li> <li>2. Lan Verhappen and Augusto Pereira, "Foundation Field bus", 4<sup>th</sup> Edition, Feb 29, 2012</li> <li>3. William Buchanan, "Computer Buses", CRC Press, 2000.</li> </ol>	<ol style="list-style-type: none"> <li>4. Andrew S. Tanenbaum, David J. Wetherall, "Computer Networks", Prentice Hall of India Pvt. Ltd., 5<sup>th</sup> Edition. 2011.</li> <li>5. A. Behrouz Forouzan, "Data Communications &amp; Networking", 3<sup>rd</sup> edition, Tata Mc Graw hill, 2006.</li> </ol>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
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1. D. Karthikeyan, Controlsoft Engineering India Pvt Ltd, karthikeyan.d@controlsoftengg.in		1. Dr. J. Prakash, MIT, Chennai, prakaiit@rediffmail.com
2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. D. Nedumaran, Madras University, dnmaman@gmail.com
		Internal Experts
		1. Dr.S.Umamaheswari, SRMIST
		2. Dr. A. Vimala Juliet, SRMIST

Course Code	18ECE385T	Course Name	IoT IN PROCESS INSTRUMENTATION AND AUTOMATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Impart fundamental knowledge on the concepts of Internet of Things with its Architecture.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Provide an overview of various techniques that are using Internet of Things in Industry applications.																							
CLR-3 :	Understand the working of Internet of Things in Industry with the advanced Industry 4.0 platforms.																							
CLR-4 :	Understand the application of Internet of Things in Automation																							
CLR-5 :	Gain knowledge on the operation of Engineering in IoT Automation with arrowhead framework.																							
CLR-6 :	Explore the working of IoT in various real-time industries																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Expected Proficiency (%)				Problem Analysis															
					Expected Attainment (%)				Design & Development															
CLO-1 :	Understand the basic concepts of IoT, Architecture and Its Applications				3	85	80																	
CLO-2 :	Analyze the techniques to apply IoT for Industry				3	85	75																	
CLO-3 :	Apply the knowledge of different techniques of IoT in industry with an advanced platform of Industry 4.0				3	80	80																	
CLO-4 :	Develop the knowledge of IoT in Automation.				3	85	80																	
CLO-5 :	Apply the knowledge of Engineering in IoT Automation System				3	80	75																	
CLO-6 :	Design the IoT based real-time projects				3	85	85																	

Duration (hour)		IoT – Landscape, System Architectures 9	Industrial Internet of Things(IIoT) 9	IIoT Platforms 9	IoT Automation 9	Engineering of IoT Automation System 9
S-1	SLO-1	Introduction to IoT	Introduction to IIoT	Introduction to IIoT Conceptual diagram	From DCS and SCADA to IoT	Engineering of an Arrowhead domain facility
	SLO-2	Applications and Architectures	IIoT Architecture	Middleware Architecture	Automation System Architectures	Engineering Tool Interoperability
S-2	SLO-1	Wireless Networks, Devices	Communication Methods for IoT Devices	Functions of Middleware Platforms	Automation System Properties	Component based Engineering Method
	SLO-2	Security and Privacy	IoT Reference Model by ITU	IIoT WAN and Protocol	Communication within Automation Systems	Life Cycle Dimensions
S-3	SLO-1	Event-Driven Systems	IoT Business Model by ITU	IIoT Device for M2M	Current Trends in Automation System	Data Model
	SLO-2	IoT System Architectures	Designing Industrial Internet Systems	Securing the Industrial Internet	Automation System Security	Design Guidelines for Component based Engineering
S-4	SLO-1	Protocols Concepts	OSI Table	Security in Manufacturing	Future Automation System Requirements	Safety and Security Engineering of IoT Automation System
	SLO-2	IoT- Oriented Protocols	Web 2.0 Layers	OT Manufacturing Network	Next Generation Automation	Security Analysis
S-5	SLO-1	Data bases & Time Bases	IP Layers vs IIoT Layers	OT vs IT Security Domains	Internet of Things	ETSI and STRIDE method
	SLO-2	IoT Device Design Space	Modern Communication Protocols	Defining Industry 4.0	System of Systems	Safety Analysis
S-6	SLO-1	Cost of Ownership	Wireless Communication Technologies	Characteristics of Industry 4.0	Service Oriented Architecture	FMEA / FMECA Analysis
	SLO-2	Power Consumption	Proximity Network Communication Protocols	Industry 4.0 Design Principles	Local Automation Cloud Concept	Engineering Scenarios
S-7	SLO-1	Cost per Transistor and Chip Size	Access Network Technology	Building Blocks of Industry 4.0	Local Cloud Properties	Efficient Deployment of IoT Sensors
	SLO-2	Duty Cycle and Power Consumption	Ethernet, IP Routing	Industry 4.0 Reference Architecture	Local Cloud Establishment	Network Deployment tool

S-8	SLO-1	Platform Design	TCP/IP	Smart Factories - Introduction	Automation Support	Cost of Wireless Sensor Network
	SLO-2	IoT Network Model	Application Programming Interface	Smart Factory Production line	Latency in Local Clouds	Swift Deployment and Configuration
S-9	SLO-1	Single and Multi – Hub Networks	API – Technical Perspective with Example	Smart Manufacturing	Security in Local Clouds	Deployment Procedure
	SLO-2	Physical Networks	Summary	Real World Smart Factories	System of System Scalability	Replacement of Device

Learning Resources	1. Dimirios Serpanos and Marilyn Wolf, <i>Internet-of-Things (IoT) Systems, Architectures, Algorithms, Methodologies</i> , Springer, 2018.			4. Patel Chintan, <i>Internet of Things Security: Challenges, Advances, and Analytics</i> , Auerbach Publications, 2019.		
	2. Alasdair Gilchrist, <i>Industry 4.0 – The Industrial Internet of Things</i> , Apress, 2016.			5. Jeschke S Brecher, Song C, <i>Industrial Internet of Things – Cyber Manufacturing Systems</i> , Springer, 2017.		
	3. “IoT Automation Arrowhead Framework”, Jerker Delsing, CRC Press, Taylor & Francis Group, 2017.			6. Stamatios Manesis, George Nikolakopoulos, <i>Introduction to Industrial Automation</i> , CRC Press, Taylor & Francis Group, 2018.		

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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2. Mr. Hariharasudhan - Johnson Controls, Pune, hariharasudhan.v@jci.com		2. Dr. D. Nedumaran, Madras University, dnmaman@gmail.com
		Internal Experts
		1. Dr. G. Y. Rajaa Vikhram, SRMIST
		2. Dr. Joselin Retna Kumar, SRMIST

Course Code	18ECE386T	Course Name	MEMS - BASED MICROSYSTEM ANALYSIS AND DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	<i>Study the basics of microfabrication and its techniques</i>	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	<i>Impart the knowledge of mechanical micro sensors</i>	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	<i>Understand the mechanism for various actuators</i>																		
CLR-4 :	<i>Know the behavior of fluid at the micro level, working of microfluidic devices and its fabrication techniques</i>																		
CLR-5 :	<i>Identify the correct interfacing circuits for microsystem</i>																		
CLR-6 :	<i>Know the working and readout mechanism for micro devices or microsystems</i>																		
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>																			
CLO-1 :	<i>Apply the knowledge of micro technology to fabricate micro devices</i>	3	80	80	H	H	-	H	H	-	-	H	H	-	-	H	M	-	H
CLO-2 :	<i>Design a micro sensor based on an application with a suitable working principle.</i>	3	80	80	H	H	H	H	H	-	-	H	H	-	-	H	M	-	H
CLO-3 :	<i>Design, analyse and optimise the micro actuator for different applications.</i>	3	80	80	H	H	H	H	H	-	-	H	H	-	-	H	M	-	H
CLO-4 :	<i>Design a microfluidic device for automobile, medical, electronics and industrial applications</i>	3	80	80	H	H	H	H	H	-	-	H	H	-	-	H	M	-	H
CLO-5 :	<i>Design an interfacing circuit for reading output from microsystems</i>	3	80	80	H	H	H	H	H	-	-	H	H	-	-	H	M	-	H
CLO-6 :	<i>Develop a microsystem for a specific application</i>	3	80	80	H	H	H	H	H	-	-	H	H	-	-	H	M	-	H

Duration (hour)		Micromachining Technology 9	Mechanical Microsensors 9	Microactuators 9	Microfluidics 9	Interface Circuitry and Microsystems 9
S-1	SLO-1	Introduction	Introduction	Introduction	Introduction	Introduction
	SLO-2	Bulk Micromachining	Automotive	Actuators: Transducers with Mechanical Output	Properties of Fluids	Microsensor Systems
S-2	SLO-1	Wet Etching	Computers and Peripherals	Transduction Mechanisms	Volumes and Length Scales	Microsensor System Applications - Automotive Sensors
	SLO-2	High-Aspect-Ratio Micromachining	Consumer Products	Scaling Advantages and Issues	Mixtures, Physical Properties	Biomedical Sensors
S-3	SLO-1	Surface Micromachining	Medical and Biological Applications	Electrical Microactuators	Vapour Pressure, Surface Tension	Sensors for Household Appliances, Building Control
	SLO-2	Basic Process Sequence	Inertial Sensors	Electrostatic Forces	Electrical Properties, Optical Properties, Transport Phenomena	Industrial Control
S-4	SLO-1	Deposition, Sputtering and Etching	Accelerometers	Electrostatic Systems	Physics of Microfluidic Systems	Environmental Sensors
	SLO-2	Epi-Micromachining	Yaw-Rate Sensors	Forces in Electrostatic Systems	Navier-Stokes Equations	Interface Circuit Architecture
S-5	SLO-1	SIMPLE, SCREAM	Pressure Sensors	Scaling Properties	Laminar Flow, Dynamic Pressure	Requirements and Specifications
	SLO-2	Black Silicon, MELO	Fundamentals	Electrostatic Microactuator Configurations	Fabrication Technologies	Analog Front-End
S-6	SLO-1	Porous Silicon	Bulk-Micromachined Pressure Sensors	Gap-Closing Electrostatic Microactuators & Examples	Silicon, Plastics,	Voltage Output - Current or Charge Output
	SLO-2	SIMOX	Surface-Micromachined Pressure Sensors	Constant-Gap Electrostatic Microactuators & Examples	Quartz, Glass	Impedance Variation
S-7	SLO-1	Epi-Po1y	Signal Generation	Hybrid Electrostatic Microactuators	Microarrays	A/D Converter
	SLO-2	Release and Stiction	Force and Torque Sensors	Electrostatic Induction, Issues and Challenges	Concept, Fabrication, Particle-Based	Types of converters



					Microarray Concepts	
S-8	SLO-1	IC Compatibility Issues	Linking the Macro World to the Micro World	Piezoelectric Microactuators	Micropumps	Digital Processing and Output Interface
	SLO-2	Compatible Bulk Micromachining	Fabrication	Piezoelectric Energy Density	Microdisplacement Pumps, Charge-Induced Pumping Mechanisms, Other Pumping Mechanisms	Digital Signal Processing
S-9	SLO-1	Compatible Surface Micromachining	Protection	Piezoelectric Microactuator Configurations & Design Issues	Microanalytical Chips	Wired Output Interfaces
	SLO-2	Compatible Epi-Micromachining	Test and Calibration	Electrostriction, Electrets, and Electro-rheological Fluids	Lab-on-a-Chip Systems, Chip-Based Capillary Electrophoresis	Wireless Output Interfaces

Learning Resources	1. Jan G. Korvink, Oliver Paul, "MEMS: A Practical Guide to Design, Analysis and Applications", William Andrew, Inc. & Springer, 2006 2. Chang Liu, "Foundations of MEMS", Pearson; 2 <sup>nd</sup> edition, 2011 3. Mohamed Gad-el-Hak, "MEMS: Design and Fabrication", CRC Press; 1 <sup>st</sup> edition, 2005.	4. Julian W. Gardner, "Micro sensors, MEMS, and Smart Devices", John Wiley & Sons Inc, 2001 5. John A. Pelesko, "Modeling MEMS and NEMS", CRC Press; 1 <sup>st</sup> edition, 2002 6. Stephen Beeby, "MEMS Mechanical Sensors", ARTECH HOUSE, INC 2004
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyse										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

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		Internal Experts
		1. Mr.C. Likith Kumar, SRMIST
		2. Dr. A. Vimala Juliet, SRMIST

Course Code	18ECE387T	Course Name	MICRO SENSORS AND SMART DEVICES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Electronics and Communication Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To realize the importance of micro sensors and actuators	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	To learn the operating principle of various micro sensors	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	To analyze the applications of various micro fabrication techniques	Expected Proficiency (%)	Problem Analysis
CLR-4 :	To understand the different packaging techniques	Expected Attainment (%)	Design & Development
CLR-5 :	To appreciate the significance of available MEMS based smart devices		Analysis, Design, Research
CLR-6 :	To recognize recent developments and challenges in MEMS		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Appreciate the importance of sensors and actuators based on MEMS technology	3	80	75	H	-	-	-	-	H	-	-	-	-	-	H	H	-	H
CLO-2 :	Understand the fabrication and machining techniques of MEMS devices	3	80	70	H	-	-	-	-	H	-	-	-	-	-	H	-	-	H
CLO-3 :	Familiarize with the concepts of packaging and interfaces in MEMS devices	3	75	70	H	H	M	H	M	H	-	-	-	-	-	H	H	-	H
CLO-4 :	Appreciate the significance of general micro fabrication processes	3	80	75	H	H	M	M	M	-	-	-	H	-	-	H	-	-	H
CLO-5 :	Differentiate between the working principle of various micro sensors	3	80	70	H	-	M	-	H	-	-	-	-	-	-	H	-	-	H
CLO-6 :	Analyze recently developed smart devices employing MEMS technology	3	80	70	H	-	-	-	-	H	-	-	-	-	-	H	H	-	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction to Microelectronics	Micro thermal Sensors-overview	Micro machining techniques	MEMS Packaging	Smart Devices-Overview
	SLO-2 Evolution & History of MEMS	TEG and Thermopiles	Significance and types	Objectives in Packaging	Functionalities
S-2	SLO-1 Overview of Micro system technology	Micro radiation Sensors-overview	Bulk MMC-overview	Flip chip assembly	Features & requirements
	SLO-2 Broad applications of Micro systems	Implementation	Principle and block diagram	Ball grid array	Broad applications
S-3	SLO-1 Miniaturization & Scaling laws	Micro mechanical Sensors-overview	Surface MMC-overview	Wire bonding techniques	Airbag deployment
	SLO-2 Micro devices -examples	Vibration sensor -Accelerometer	Principle and block diagram	Types	Tire pressure monitoring
S-4	SLO-1 Types of Micro Sensors	Micro pressure Sensors-overview	LIGA process-overview	Surface bonding techniques	GPS-Gyro sensor
	SLO-2 Types of Micro actuators	Parameter measurement	Principle and block diagram	Types	Micro Energy harvesters
S-5	SLO-1 Si and other substrates	Micro humidity Sensors-overview	Photolithography	Sealing	Smart home automation
	SLO-2 Special MEMS Materials & properties	Types of Sensing film & measurement	Process Description, implementation	Different types of sealing	MEMS devices in agriculture
S-6	SLO-1 Polymer materials	Micro SAW Sensors-overview	Ion implantation and oxidation	Process design	Blood pressure monitor
	SLO-2 Electro active polymers	Implementation	Process Description, implementation	Block diagram	Heart Parameter monitors
S-7	SLO-1 Shape memory alloys	Micro magnetic Sensors-overview	PVD-CVD	Interferences	RF MEMS technology
	SLO-2 Shape memory polymers	Significance & measurement	Process Description, implementation	Types of interferences	Optical Mirrors
S-8	SLO-1 Piezoelectric materials	Micro bio chemical Sensors-overview	Wet and dry etching	Electronic Interfacing	Micro fluidics
	SLO-2 Ceramic materials	Parameter measurement	Isotropic and Anisotropic	Electro mechanical interfacing	LOC module
S-9	SLO-1 Case study-1	Micro optical Sensors-overview	Case study-1	Case study-1	Case study-1
	SLO-2 Case study -2	Types & Implementation	Case study -2	Case study -2	Case study -2

Learning Resources	1. Marc Madou, "Fundamentals of Microfabrication" CRC Press 2. Tai Ran Tsu, "MEMS and Microsystems: Design Manufacture", Tata McGraw Hill	3. Vardhan Gardener, "Micro sensors and smart devices", John Wiley & Sons
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	30 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

# CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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