

ACADEMIC CURRICULA

Professional Elective Courses

MECHANICAL ENGINEERING

Regulations - 2018

Volume – 4 (7)

(Detailed Syllabus for Third & Fourth Year Courses)



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Kancheepuram, Tamil Nadu, India

Course Code	18MEE301T	Course Name	FUNDAMENTALS OF VIBRATION AND NOISE	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC201T Machines and Mechanisms	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Be familiar with the vibrations of two degree of freedom systems				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with the vibrations of multi degree of freedom systems																							
CLR-3 :	Be familiar with the vibrations of continuous systems																							
CLR-4 :	Be familiar with the Numerical Integration methods in Vibration analysis																							
CLR-5 :	Be familiar with the vibration measurement devices																							
CLR-6	Be familiar with the vibrations of multi degree of freedom systems & Continuous systems, numerical integration methods in vibration analysis and vibration measuring devices																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of Thinking (Bloom)	1 & 2	75	70	Problem Analysis	H	M	M	Design & Development	H	L	L	M	Ethics	L	L	L	L	L	L
CLO-1 :	Able to learn the concepts of vibration analysis of two degree of freedom systems and vibration absorbers																							
CLO-2 :	Able to Understand and apply the various numerical methods for vibration analysis of three degree of freedom systems																							
CLO-3 :	Able to learn the concepts of vibration analysis of continuous systems																							
CLO-4 :	Able to apply the knowledge of numerical integration methods in vibration analysis																							
CLO-5 :	Able to Understand the vibration measurement devices and condition monitoring techniques																							
CLO-6:	Able to understand the vibrations of two, multi degree of freedom systems and continuous systems and apply the knowledge of numerical integration methods in vibration analysis and vibration measuring devices in field measurement.				Level of Thinking (Bloom)	1 & 2	75	70	Analysis, Design, Research	H	M	M	Modern Tool Usage	H	L	L	M	Society & Culture	H	L	L	L	L	L

		Vibrations of Two degree of freedom systems / Module 1	Vibrations of Three Degree of freedom systems / Module 2	Vibrations of Continuous systems Numerical Integration Methods in Vibration Analysis / Module 3	Numerical Integration Methods in Vibration Analysis / Module 4	Vibration Measuring Instruments / Module 5
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to vibration terminologies and multidegree of freedom systems	Equation of Motion for free undamped three degrees of freedom systems using Newton's Method, Orthogonality Condition	Transverse Vibrations of String or a cable	Introduction to Finite Difference method	Vibration Measuring Devices – Transducer, Vibrometer
S-2	SLO-1	Equation of Motion for free undamped two degrees of freedom systems using Newton's method	Multidegree of freedom systems – Matrix method, Eigen Value Method – Eigen values and Eigen vector	Longitudinal vibrations of a Bar or a Rod	Central difference method for single degree of freedom systems	Vibration Measuring Devices – Accelerometer and Seismometer.
S-3	SLO-1	Equation of Motion for free undamped two degrees of freedom systems using Lagrangian energy method	Tutorials on Multidegree of freedom systems – Newton's Method, Matrix method, Eigen Value Method	Tutorials on Transverse Vibrations of Strings and Longitudinal vibrations of Rods	Central difference method for multi degree of freedom systems	Tutorials on vibrometer, Accelerometer and Seismometer.
S-4	SLO-1	Tutorials on free undamped two degrees of freedom systems using Newton's method and Lagrangian method	Influence Coefficients Method – Stiffness and Flexibility matrix – spring mass system	Torsional vibrations of rods	Tutorials on central difference method	Frequency Measuring devices – Single Reed, Multi reed and stroboscope.

S-5	SLO-1	Determine the natural frequencies and mode shapes for coordinate coupling	Dunkerly's Method for closed coupled system , Rayleigh's Method for spring mass system	Lateral Vibrations of a Beam	Runge-Kutta Method for single degree of freedom systems	Vibration exciters
S-6	SLO-1	Concept of Linear undamped vibration absorber	Tutorials on Influence Coefficients Method, Dunkerly's Method and Rayleigh's Method	Tutorials on Torsional vibration of rods and lateral vibration of a Beams	Runge-Kutta Method for multi degree of freedom systems	Tutorials on vibration exciters.
S-7	SLO-1	Tutorials on coordinate coupling and Linear undamped vibration absorber	Concept of Holzer's Method for Far Coupled systems and Close Coupled Sytems	Rayleigh's method for continuous system	Tutorials on Runge-Kutta Method	Experimental Modal Analysis, Condition Monitoring techniques
S-8	SLO-1	Torsional Vibration of Two rotor systems.	Torsional Vibration of Three rotor systems-Equivalent Length Determination	Rayleigh's Ritz method for continuous system	Finite Difference Methods for Longitudinal vibration of bars	Balancing Machines – Single plane and two plane balancing
S-9	SLO-1	Torsional Vibration of Geared Systems with Two rotor System	Tutorials on Hozler's method and Three rotor systems.	Tutorials on Rayleigh's method and Rayleigh's Ritz method	Finite Difference Methods for transverse vibration of beams	Tutorials on Modal analysis

Learning Resources	<ol style="list-style-type: none"> 1. Rao.S.S, "Mechanical Vibrations", 5th Edition, Pearson Education Inc. Delhi 2009. 2. Ambekar.A.G, "Mechanical Vibrations and Noise engineering", PHI New Delhi, 2015. 3. Thomson.W.T, "Theory of Vibration and its Applications", 5th Edition, Prentice Hall, New Delhi, 2001. 4. Meirovitch, L., "Elements of Vibration Analysis", Mc Graw – Hill Book Co., New York, 1986. 	<ol style="list-style-type: none"> 5. Rao.J.S and Gupta.K, "Introductory course on theory and practice of mechanical vibrations", 2nd Edition, New Age International, New Delhi, 2014. 6. Ramamurthi.V, "Mechanical Vibration Practice with Basic Theory", 1st edition, Narosa Publishing House, Chennai, 2000.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40%	-	30%	-	30%	-	30%	-	30%	-
Level 2	Apply Analyze	40%	-	40%	-	40%	-	40%	-	40%	-
Level 3	Evaluate Create	20%	-	30%	-	30%	-	30%	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc,

INDUSTRIAL EXPERT	ACADEMIC EXPERT	INTERNAL EXPERT
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	Dr. Rajendra Machavaram, IIT Kharagpur	V.N.B Prasad Sodisetty, SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Raghavendra bejgam engineering project lead, pentair, noida.	Dr. P. Nandakumar, SRMIST

Course Code	18MEE302T	Course Name	INDUSTRIAL TRIBOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	PSG Design Data book		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand and analyze the surfaces and friction	1	1
CLR-2 :	Understand and analyze the wear mechanisms	2	2
CLR-3 :	Understand and analyze the film theory	3	3
CLR-4 :	Understand and analyze the lubricants and lubrication phenomenon		4
CLR-5 :	Understand and analyze the surface engineering processes and select suitable materials for bearing		5
CLR-6 :	Understand and solve various engineering problems		6

Course Learning Outcomes (CLO):	At the end of the course, student will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand friction and engineering surfaces	1,2	100	85	H	H			H		H					H	H		
CLO-2 :	Apply the knowledge and analyze the failure occurred due to various types of wear	3&4	100	85	H	H	H	H	H		H					H	H		
CLO-3 :	Apply the knowledge of lubrication to provide solutions	3&4	100	85	H	H	H	H	H							H	H		
CLO-4 :	Analyze various surface conditions and provide new ideas of surface protection techniques	3&4	100	85	H	H	H	H	H							H	H		
CLO-5 :	Formulate new materials	5	100	85	H	H										H	H	H	H
CLO-6 :	Investigate the failure of a system	5	100	85	H	H			H	H						H	H	H	H

		Surfaces and friction	Wear	Film lubrication theory	Lubricants and lubrication	Surface engineering and materials for bearings
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to the concept of tribology, Tribological problems	Introduction, background of Wear and Types of Wear with applications.	Introduction to Viscosity and its importance in lubrication.	Types of lubricants and their properties	Introduction to surface engineering
S-2	SLO-1	Nature of engineering surfaces, Surface topography	Abrasive wear	Influence of various particles on viscosity of a lubricant.	Stribeck Curve and its importance	Surface treatments
S-3	SLO-1	Surface profilometer, measurement of surface topography; importance of roughness parameters	Adhesive wear	Fluid film in simple shear, Viscous flow between very close parallel plates.	Boundary and Mixed Lubrication regime	Coatings and cladded plates
S-4	SLO-1	Contact between surfaces, Sources of sliding Friction, Friction characteristics of metals and non-metals	Wear due to corrosion	Shear variation within the film, Lubricant supply, lubricant low rate.	Hydrodynamic lubrication	In situ formed tribo films
S-5	SLO-1	Friction due to ploughing, Friction due to adhesion	Fatigue and fretting wear	Cold jacking, Couette flow,	Elasto hydrodynamic lubrication(EHL); Problems on EHL	Surface Texturing
S-6	SLO-1	Sources of rolling friction, Stick slip motion	Wear in metals	Cavitations, film rupture and oil whirl	Importance of film thickness, Lambda ratio	Tribo corrosion
S-7	SLO-1	Friction of ceramic materials	Wear in polymers	Petroff's equation	Bio degradable lubricants	Surface analysis techniques
S-8	SLO-1	Friction of polymers	Wear of ceramics	Reynolds equation	Nano lubricants	Materials for bearings
S-9	SLO-1	Measurement of friction	Measurement of wear, Ferrography and oil analysis	Sommerfield Number	Hertzian contact and problems on Hertzian contacts	Condition monitoring

Learning Resources	1. Hutchings.I.M and Shipway P, "Tribology, Friction and Wear of Engineering Material, Elsevier Butterworth –Heinemann , UK, 2017.	5. Stolarski.T.A, "Tribology in Machine Design", Industrial Press Inc., 1990.
	2. Bharat Bhushan, "Introduction to tribology", Wiley Publication, 2013.	6. Cameron.A, "Basic Lubrication Theory", Longman, U.K., 1981.
	3. Williams.J.A, "Engineering Tribology", Oxford University Press, 2005.	7. Neale.M.J., "Tribology Handbook", Newnes Butter worth, Heinemann, U.K., 1975.
	4. GwidonStachowiak, Andrew W Batchelor., "Engineering tribology", Elsevier Butterworth –Heinemann, USA, 2005.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	Dr.P. Ramkumar, IITM, ramkumar@iitm.ac.in	Mr. ShubrajitBhaumik, SRM IST ,
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.Chiradeep Ghosh , chiradeep.ghosh@tatasteel.com, Tata Steel	Dr. TVVNL Rao, SRMIST

Course Code	18MEE303T	Course Name	MECHANISM DESIGN, ANALYSIS AND SYNTHESIS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC201T Machines and Mechanisms	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Perform the kinematic analysis of various mechanisms and linkages	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Synthesis a linkage or mechanism for the given requirements	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Determine the acceleration at any point on the coupler																		
CLR-4 :	Perform static and dynamic force analysis of linkages																		
CLR-5 :	Perform kinematic analysis and synthesis of spatial mechanisms and Robot linkages																		
CLR-6 :	Design a mechanism according to the need and analyze it.																		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Determine the position, velocity and acceleration of simple and complex linkages.	1,2 & 3	75	65	H	H	M	M	H	-	-	-	-	-	-	L			
CLO-2 :	Synthesize a linkage based on the given working conditions	1,2 & 3	75	65	H	H	H	H	H	-	-	-	-	-	-	L			
CLO-3 :	Find the conjugate points, radius of curvature and acceleration at any point on the coupler link.	1,2 & 3	75	65	H	H	M	H	H	-	-	-	-	-	-	L			
CLO-4 :	Find forces/moments in various links with or without considering inertia of links	1,2 & 3	75	65	H	H	H	M	H	-	-	-	-	-	-	L			
CLO-5 :	Determine the position, velocity and acceleration of spatial linkages and robot linkages	1,2 & 3	75	65	H	H	H	H	H	-	-	-	-	-	-	L			
CLO-6 :	Do the kinematic and dynamic analysis of mechanisms in addition to its synthesis.	1,2 & 3	75	65	H	H	H	H	H	-	-	-	-	-	-	L			

		Kinematic Analysis of Mechanisms	Kinematic Synthesis of Linkages	Path Curvature Theory	Force Analysis of Mechanisms	Kinematics of Spatial Mechanisms And Robotics
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Review of fundamentals of kinematics, mobility analysis and classifications of mechanisms	Introduction to synthesis, type, number and dimensional synthesis	Fixed and moving centrodes	Static force analysis of linkages	Mobility and description of spatial mechanisms
S-2	SLO-1	Kinematic Inversions, Grashoff's law	Two position synthesis of four bar and slider crank mechanisms by extreme position and inversion methods	Determination of radius of curvature of coupler points by Hartmann's Construction	Static force analysis of linkages by graphical method, principle of super position	Position, velocity and acceleration analysis of spatial mechanisms by vector algebra method
S-3	SLO-1	Mechanical advantage and Transmission angle	Three position synthesis of four bar by inversion method	Determination of radius of curvature of coupler points by the Euler- Savary equation		
S-4	SLO-1	Position analysis of four bar, Slider Crank by complex and vector algebra methods	Three position synthesis of slider crank mechanisms by inversion method	Inflection Points, The Inflection Circle	Dynamics force analysis- D'Alembert's principle	Problems on kinematic analysis of spatial mechanisms
S-5	SLO-1	Velocity, acceleration and jerk analysis of four bar by complex and vector algebra methods	Four position synthesis by point position reduction method and Overlay method.	The collineation axis and Bobiller's theorem	Combined static and dynamics analysis of four bar linkage, Graphical and analytical methods	Kinematic synthesis of spatial mechanisms
S-6	SLO-1	Velocity, acceleration and jerk analysis of Slider Crank by complex and vector	Coupler curve synthesis	Determination of radius of curvature of coupler points by Bobiller's Construction	Problems on combined static and dynamic analysis	Introduction to Robot kinematics, Topological arrangements of robotic

		<i>algebra methods</i>				<i>arms, Eulerian angles, DH parameters</i>
S-7	SLO-1	Velocity analysis of complex and six bar linkages by relative velocity method (Graphical method)	Analytical Methods of synthesis by Blotch's Synthesis	Problems on Bobiller's Construction	Shaking force and shaking couple	Kinematic analysis of robot manipulators using transformation matrices
S-8	SLO-1	Acceleration analysis of complex and six bar linkages by relative velocity method (Graphical method)	Analytical Methods of synthesis by Freudenstein's Method	Problems on Bobiller's Construction	Introduction to force and moment balancing of linkages	Inverse kinematics of robot manipulators
S-9	SLO-1	Problems on velocity and acceleration of mechanisms by Graphical method	Cognate linkages by the Roberts – Chebyshev theorem	The cubic Stationary curvature - Ball's Point	Problems on Balancing of linkages	Robot actuator force analysis

Learning Resources	<ol style="list-style-type: none"> 1. Uicker J. J., Gordon R. Pennock & Joseph E. Shigley John J. Uicker "Theory of Machines and Mechanisms", Oxford Higher education, 2014. 2. Rao, J. S., and Dukkippatti, R.V., "Mechanisms and Machine Theory", 2nd Edition, New Age international (P) Ltd., 1995 3. Sandor, G. N. and Erdman A. G., Mechanism Design, Analysis and Synthesis Vol: I and Vol: II, Prentice Hall, 1990. 4. Norton, R. L., Design of Machinery, McGraw Hill, 1999. 	<ol style="list-style-type: none"> 5. Hamilton H Mabie and Charles F. Reinholtz, Mechanisms and Dynamics of Machinery, John Wiley & Sons, 1987. 6. Amitabha Ghose and Ashok Kumar Malik, Theory of Mechanisms and Machines, EWLP, Delhi, 1999. 7. R.S.Hartenberg and J. Denavit, "Kinematic Synthesis of Linkages", Mc. GrawHill Book Company, 1964
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	1. Dr. Shankar Krishnapillai, skris@iitm.ac.in, IIT Madras	1. Dr P. Nandakumar, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.R.Prabhu sekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	2. Mr. K.R. Arunprasath, SRMIST

Course Code	18MEE304T	Course Name	DESIGN FOR MANUFACTURING AND ASSEMBLY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To study how a design can be made suitable for various manufacturing and assembly process requirements	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Application of this study to various Casting and welding.		
CLR-3 :	Application of this study to various forging, and machining processes		
CLR-4 :	To study about the various assembly methods and processes		
CLR-5 :	Know the effect of manufacturing process and assembly operations.		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:	Level of Thinking	Expected	Expected	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Students will demonstrate the ability to identify needs of the customer and convert them in to technical specifications of a product.		1& 2	90	85	H	--	H	--	--	--	--	--	--	--	--	--	--	--	--
CLO-2 :	Know the manufacturing issues that must be considered in the Casting and welding		1	85	80	H	H	H	H	--	--	--	--	--	--	--	--	--	--	--
CLO-3 :	Know the manufacturing issues that must be considered in the forging and machining processes.		1	85	80	H	H	H	H	--	--	--	--	--	--	--	--	--	--	--
CLO-4 :	Students will understand the principals used while designing for manufacture, assembly.		1&2	85	80	H	H	H	H	--	--	--	--	--	--	--	--	--	--	--
CLO-5 :	Students will understand principles of assembly to minimize the assembly time.		1&2	85	80	H	H	H	--	--	--	--	--	--	--	--	--	--	--	--

Duration (hour)	Learning Unit / Module 1	Learning Unit / Module 2	Learning Unit / Module 3	Learning Unit / Module 4	Learning Unit / Module 5
	9	9	9	9	9
S-1	SLO-1 Significance of design- Systematic working plan-The engineering problem to be solved-The basic design	Influence of loading, Materials, Production methods on form design	Forging Considerations-Hammer forging-Drop forging	DFA-Introduction-Distinction between assembly methods and processes	Approaches to design for assembly-Introduction
S-2	SLO-1 Factors influencing choice of materials-The factors influencing manufacturing	Casting considerations-Grey iron castings	Requirements and rules for forging.	Factors Determining assembly methods and processes-Success and failure-Causes of failure	Approaches based on design principles and rules-Example DFA method using Design Principles
S-3	SLO-1 Process Capability-Mean, Median, Variance, Mode, Standard Deviation, Normal Distribution- Process capability metrics-	Steel castings -Aluminum Casting- Requirements and rules for casting	Redesign of components for forging.	Product Design factors independent of methods and processes-Introduction- Number of operations in the product	DFA Systems employing Quantitative evaluation procedures-IPA Stuttgart Method
S-4	SLO-1 Process Capability and Defect Rate, Assumptions, Conditions and Precautions in process capability	Form design of pressure die castings	Choice between casting, forging and welding.	Assembly Precedence-Standardization. Case studies in assembly precedence.	DFA Methods employing a Knowledge-based approach-Knowledge Representation
S-5	SLO-1 Process Capability-Simple problems	Redesign of components for casting- Pattern-Mould-Parting Line	Machining Considerations-Drills-Milling-Keyways-Dwells and Dwelling Procedure- Countersunk Head screws	Design factors dependent on Assembly methods-Introduction-Single Station Assembly	Computer Aided DFA methods-Part model-Feature Processing
S-6	SLO-1 Tolerances-symbols and Definition	Welding considerations-Welding	Requirements and rules for Machining	Line Assembly-Hybrid Systems-Manual	Assembly measures-Qualitative and

			Processes	considerations-Reduction of machined areas	Assembly Lines-Flexible Assembly Lines	Quantitative measures
S-7	SLO-1	Tolerances relevant to manufacturing, Assembly- Material condition	Requirements and rules for welding	Redesign of components for Machining.	Design factors dependent on Assembly processes-Factors Influencing Production rate to Facility Ratio-Parts Presentation-Manual Assembly	Boothroyd and Dewhurst DFA method-Objectives of the method
S-8	SLO-1	Tolerance stack- effects on assembly-Examples	Redesign of components for welding	Simplification by separation-Simplification by Amalgamation	Dedicated Assembly-Transportation-Separation-Oriented-Flexible Assembly	Redesign of a simple product-Small consumer product-Fastener solution-Redesign using symmetry
S-9	SLO-1	Methods of eliminating tolerance stack-Examples	Case studies in Form Design-simple problems in form design	Case studies- forging and Machining	Gripping-Transferring-Part Insertion-Failures-Error Recovery	Case Studies-Designing of a disposal valve-Design of a lever-arch file mechanism

Learning Resources	<ol style="list-style-type: none"> 1. Harry Peck., Design for Manufacture, Pittman Publications,1983. 2. Alan Redford and chal, Design for Assembly-Principles and Procedures, McGraw Hill International Europe, London, 1994. 3. Robert Matousek,Engineering Design-A Systematic Approach,Blackie&sons Ltd.,1963. 4. James G.Bralla,Hand Book of Product design for Manufacturing,McGraw Hill Co.,1986. 5. Swift,K.G.,Knowledge Based Design for Manufacture,Kogan Page Ltd.,1987.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
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Level 2	Apply Analyze	40%	-	40%	-	40%	-	40%	-	40%	-
Level 3	Evaluate Create	20%	-	30%	-	30%	-	30%	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

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Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Davidson Jebaseelan, davidson.jd@vit.ac.in VIT Chennai.	Mr. P.Susai Manickam, SRM IST, Chennai
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. Vignesh Shanmugam.s Hyundai Motors Limited, Chennai E mail – 273357@hmlil.net	Dr. P. Nandakumar, SRM IST, Chennai

Course Code	18MEE305T	Course Name	FINITE ELEMENT METHOD	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC106T Mechanics of Solids, 18MAB202T Numerical methods	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Find the approximate solution of boundary value problems				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Know the variational and Weighted residual approaches to solve differential equations				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Develop basic finite element concepts and solution procedure																					
CLR-4 :	Formulate the element stiffness and mass matrices for various one and two dimensional elements																					
CLR-5 :	Formulate the element heat conductance and convection matrices one dimensional element																					
CLR-6 :	To formulate and solve problems in solid mechanics, Eigen Value and heat transfer using finite element method.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Solve the differential equations using weighted residual and variational approaches.				1,2&3	75	65	H	H	L	H	M	-	-	L	L	-	-	M			
CLO-2 :	Solve the structural analysis problems, such as bar, truss and beam using 1D element.				1,2 &3	70	65	H	H	L	H	M	-	-	L	L	-	-	M			
CLO-3 :	Analysis of two-dimensional structural problems on plane triangular and quadrilateral elements.				1,2 &3	70	65	H	H	L	H	M	-	-	L	L	-	-	M			
CLO-4 :	Be able to solve Eigen Value problems in solid mechanics using finite element method.				1,2 &3	65	65	H	H	L	H	M	-	-	L	L	-	-	M			
CLO-5 :	Be able to solve one dimensional heat transfer problems using finite element method				1,2 &3	70	65	H	H	H	H	H	-	-	L	L	-	-	M			
CLO-6 :	Analyze structural and heat transfer problems using Finite Element				1,2 &3	65	60	H	H	M	M	M	-	-	L	L	-	-	M			

Duration (hour)		Introduction to FEA	1D Linear Static Analysis	2D Linear Static Analysis	Dynamic Analysis of Structures	1D Heat Transfer Problems
		9	9	9	9	9
S-1	SLO-1	Basics of FEA, Historical background, applications of FEA in engineering, modelling of discrete and continuum models	Finite element procedure for a continuum problem, discretization, types of elements	Introduction to two dimension elasticity, plane stress and strain conditions	Dynamic analysis, Formulation- Hamilton's Principle, lumped and consistent mass models	Review of fundamentals of heat Transfer
S-2	SLO-1	Variational problems, Euler's equation	Selection of interpolation function, shape function, derivation of element stiffness matrix for a one dimensional bar element	Constant strain triangular element, Area coordinate system, shape function, strain displacement matrix	Derivation of lumped and consistent mass matrices for axial bar element, formulation of eigen value problem	Governing equations and boundary conditions for Heat transfer
S-3	SLO-1	Rayleigh-Ritz method, minimum potential energy, Example problem, solving differential equation	assembly of elements, imposing boundary conditions, calculation of element stress, example problems		Determination of natural frequencies and normal mode shapes of axial vibration	Derivation of conductance matrix for steady state 1D heat conduction
S-4	SLO-1	Weighted residual approaches, collocation method, subdomain method, Galerkin method and least square method	Tutorial Problems on axial loading of bars	Derivation of element stiffness matrix for a CST element	Problems on natural frequencies and normal mode shapes of axial vibration	Tutorial on Steady state 1D heat conduction
S-5	SLO-1	Example problem, solving differential equations using weighted residual approaches	Local and global coordinate systems	Tutorial on two dimensional plate problems with CST elements	Derivation of lumped and consistent mass matrices for beam element	
S-6	SLO-1	Galerkin's Finite Element method for solving differential equations, example problems,	Analysis of truss, coordinate transformations, Derivation of the stiffness matrix	LST and four noded quadrilateral elements, isoparametric	Determination of natural frequencies and normal mode shapes of beam	Derivation of element matrix for steady state 1D heat conduction including

		comparison of results with different methods		formulation		convection
S-7	SLO-1	Spring element, formulation of stiffness matrix, assembly procedure for global stiffness matrix, applying boundary conditions	Assembly of stiffness matrix for a truss, Tutorial Problems on Trusses	Gaussian quadrature Integration- Derivation of one point and two point formula	Determination of natural frequencies and normal mode shapes of beam	Tutorial on Steady state 1D heat conduction with convection
S-8	SLO-1	Solution of linear algebraic equations, Gauss elimination method, Cholesky decomposition, example problems	Beam element, Hermite shape functions, derivation of element stiffness matrix of a beam element.	Problems using Gaussian quadrature with one and two points	Problemson eigen value problems on beams	Solution of simple Heat Transfer 1-D and 2-D steady state problems using a FEA software
S-9	SLO-1	Tutorial problems on springs with series and parallel combinations	Calculation of load vector for point, uniform distributed and varying loads on beams	Lagrange interpolation functions for serendipity family elements	Derivation of lumped and consistent mass matrices for a CST element	Introduction to transient heat transfer problems

Learning Resources	1. Hutton, D.V., "Fundamentals of Finite Element Analysis", McGraw Hill, International Edition, 2004. 2. Chandrupatla, T.R., Belegundu, A.D., "Introduction to Finite Elements in Engineering", Prentice Hall of India, 1997. 3. P.Seshu, "Text book of Finite Element Analysis", PHI learning Private Ltd., 2012.	4. S.S,Rao, "The Finite Element method in Engineering", Elsevier Science &Technology Books, 2004 5. Cook R.D., Malkus, D.S., Plesha, M.E., Witt, R.J., "Concepts and Applications of Finite Element Analysis", 4th Edition, John Wiley & Sons, 2001. 6. J.N Reddy, An introduction to the Finite Element Method, 2005, Mcgraw Hill
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	1. Dr. Atanu Banerjee, atanub@iitg.ac.in, IIT Guwahati	1. Dr P. Nandakumar, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.R.Prabhusekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	2. Mr.P. SusaiManikam, SRMIST

Course Code	18MEE306T	Course Name	ADVANCED STRENGTH OF MATERIALS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC106T Mechanics of Solids	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:				Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Be able to Compute the combined effect of deformation/loading arising out of different causes as applied to structural members made of linear, homogeneous, isotropic material so as to be able to predict (as part of a different course) failure of components/sub-systems of a product					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be able to Compute the effect of deformation/loading in straight and curved beams (a class of primary structural member) subjected to bending (a type of primary loading)					Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Be able to Study the effect of bending (a type of primary loading) deformation/load as applied to flat thin plates (a class of primary structural member)																						
CLR-4 :	Be able to Study the use of energy methods in structural analysis as an alternative means of solving a structural mechanics problem																						
CLR-5 :	Be equipped with analytical skills the learning process of which has a bearing in professional practice in understanding difference(s) between exact and approximate solution procedures																						
CLR-6 :	Be able to analyze effects of typical loadings on primary structural members using approximate or exact methods as applicable																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:				1, 2	90	75	H	H													
CLO-1 :	Perform 2D & 3d stress and strain transformation and arrive at maximum values for normal and shear stresses and find the planes on which these stresses act					1, 2	90	75	H	H													
CLO-2 :	Determine i) bending stress in straight beams (due to unsymmetrical bending), ii) transverse shear stresses in straight beams and locate shear center for specified cross-sections, and iii) circumferential (bending) stresses in curved beams					1, 2	90	75	H	H													
CLO-3 :	i) Derive expressions for displacement/strains, stresses, and moments, ii) derive (using these expressions) the governing equation for bending of flat rectangular and axi-symmetric circular plates. Use the expressions for computing these parameters in specified cases					1,2	90	75	H	H													
CLO-4 :	Compute strain energy due to various loadings and using it to determine deflection					1,2	90	75	H	H													
CLO-5 :	Understand the primary difference between theory of elasticity and mechanics of materials approaches and solve plane stress, torsional, and rotating disk problems					1,2	90	75	H	H													
CLO-6 :	Determine displacements, strains, and stresses related to primary structural members					1,2	90	75															

		Stress & Strain Theory	Bending of Straight & Curved Beams	Bending of flat thin plates	Energy Methods	Theory of Elasticity & Its Applications
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction – course overview, Equilibrium, compatibility, and constitutive relations in macroscopic form, Definition of stress at a point in 3D, representation on an element and sign convention	BendingStresses in beams (initially straight) due to symmetrical loading – review and definition of un-symmetrical bending	Introduction to flat plates – definition of a plate, rectangular and axi-symmetric circular plates, thin vs thick plates, comparison with beams (1D) as a structural member (2D), typical real-world	Work, Strain energy definition for linear, perfectly elastic materials; strain energy due to - uniaxial stress, additional normal stresses in other perpendicular directions, shear stress	Introduction to and comparison with mechanics of materials approach, definition of Plane stress and plane strain linear elastic problems

				applications. Linear vs non-linear bending – definition. Derivation of governing equation for bending of a flat, thin, rectangular plate – outline of procedure		
S-2	SLO-1	concept of a tensor (in relation to a scalar and a vector), 2D stress transformation in Cartesian coordinate system using direction cosines	Bending stresses in beams due to unsymmetrical bending (plane of loading not coinciding with plane of symmetry, even if it exists) – explanation of theory in decoupling the problem into sub-problems using the concept of principal axes and moments of inertia	definition of strains, stresses, and moments and use of these parameters in derivation of governing equation for plate bending (based on Kirchhoff theory) – use of strain-displacement, and stress-strain relations	strain energy due to - general state (3D) of stress, plane stress	Plane stress and plane strain linear elastic problems - Airy's stress function in rectangular coordinates – derivation of the biharmonic equation
S-3	SLO-1	3D stress transformation in Cartesian coordinate system using direction cosines	Application of theory in computing bending stresses and determination and location of neutral axis	Use of equilibrium equations and completion of derivation of governing equation; specification of different boundary conditions generally used – simply supported, clamped, free	Total strain energy in bars with simple loading conditions – axial loading, torsional loading of a solid circular bar, and transverse loading	simple problems related to bending of beams using Airy's stress function in rectangular coordinates
S-4	SLO-1	principal stresses in 3D (after a quick review in 2D)	Deflection due to unsymmetrical bending; Intro to shear center, determination of shear center for a symmetrical channel section	Solution due to sinusoidal bending load on a simply supported plate– step-by-step explanation	Castigliano's 1 st theorem, example problems	Additional problems related to bending of beams using Airy's stress function
S-5	SLO-1	Numerical problems (in 2D and 3D based on the above lectures)	determination of shear center for T, unequal I sections	Numerical problems on thin, flat rectangular plates	brief overview of material non-linearity and plasticity; The complementary energy theorem, and Castigliano's 2 nd theorem,	overview of torsion of rectangular cross section structural members, Prandtl stress function for torsion, derivation of Poisson's equation (using Prandtl stress function)
S-6	SLO-1	octahedral normal and shear stresses, definition of strain based on small-displacement theory and strain tensor in Cartesian coordinate system	intro to bending of curved beams	Derivation of governing equation for bending of a flat, thin, axis-symmetric circular plate – outline of procedure - definition of strains, stresses, and moments	example problems using Castigliano's 1 st & 2 nd theorems (for linear materials)	Membrane analogy, brief discussion of torsion of rectangular cross section
S-7	SLO-1	strain transformation and principal strains in 3D for linear, homogeneous, isotropic material	Derivation of circumferential stress expression	use of strain-displacement, stress-strain, and equilibrium relations in derivation of governing equation (for bending)	Rayleigh's method, example problem of beam bending deflection	torsional stress in hollow closed thin-walled (single cell) tubes – overview and expressions for shear stress and angle of twist
S-8	SLO-1	Numerical problems on 3D strain computation, transformation, and determination of principal strains	Numerical problems on determination of circumferential stresses (rectangular and square sections)	derivation of equations for displacement, support reactions, and maximum stresses for a uniformly loaded, simply supported circular plate	Rayleigh-Ritz method applied to beams in bending	Stresses due to rotation - Radial and tangential stresses in a disc of uniform thickness – derivation of expression for the stresses due to rotation at a constant angular speed; maximum stresses
S-9	SLO-1	equilibrium and compatibility relations in differential form, boundary conditions and St. Venant's principle	Additional numerical problems on determination of circumferential stresses (rectangular and square sections); a brief intro (only) to radial stresses in curved beams	Numerical problems on bending of flat, thin, axis-symmetric circular plates	problems based on Rayleigh-Ritz method	Problems related to computation of Radial and tangential stresses in a rotating disc of uniform thickness based on the previous lecture

Learning Resources	1. Arthur Boresi and Richard H. Schmidt, "Advanced Mechanics of Materials," John Wiley & Sons, 6ed, 2009 2. Ansel C. Ugural and Saul K. Fenster, "Advanced Mechanics of Materials and Applied Elasticity," Prentice Hall, 2004	6. G. T. Mase, R. E. Smelser, and G. E. Mase, "Continuum Mechanics for Engineers," 3rd edition, CRC Press, 2004
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Hall; 5 th ed., 2011 3. Richard G Budynas, "Advanced Strength and Applied Stress Analysis," McGraw Hill International Editions, 1999 4. L. S. Srinath, "Advanced Mechanics of Solids," McGraw Hill Education, 3 rd edition, 2017 5. S. P. Timoshenko and J N Goodier, "Theory of Elasticity," McGraw Hill 2017	7. Y. C. Fung, "Foundations of Solid Mechanics," Prentice Hall International, 1965 8. Stephan H Crandal, Norman C Dahl, Thomas J Lardner, "An Introduction to the Mechanics of Solids," McGraw Hill, 2nd edition, 1978 9. Robert Cook and Warren Young, "Advanced Mechanics of Materials," Pearson, 2nd edition, 1998
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Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers

Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	1. Dr. Joel George, IIT Madras, joel@ae.iitm.ac.in	Dr. S. H. Venkatasubramanian, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.Ranjith Mohan, IIT Madras, ranjith.m@iitm.ac.in	

Course Code	18MEE307T	Course Name	AUTOMOTIVE ENGINEERING	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR): <i>The purpose of learning this course is to:</i>		Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Be familiar with the understanding of automotive architecture and performance	1 Level of Thinking (Bloom)	2 Expected Proficiency (%)	3 Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with the transmission system				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Know the working of wheels, tyres, and braking system				H	L	L	L	M	L	L	L	L	L	L	L	L	H	L
CLR-4 :	Be familiar with the suspension and steering system				H	L	L	L	M	L	L	L	L	L	L	L	L	H	L
CLR-5 :	Be familiar with the electrical system and advances in automotive engineering.				H	L	L	L	M	L	L	L	L	L	L	L	L	H	L
CLR-6 :	Understand the structure, transmission system, suspension system, steering system, electrical system and working of wheels, tyres in automotive Engineering				H	L	L	L	M	L	L	L	L	L	L	L	L	H	L
Course Learning Outcomes (CLO): <i>At the end of this course, learners will be able to:</i>		1&2	90	85															
CLO-1 :	Broaden the understanding of automotive architecture and performance	1,2&3	90	85															
CLO-2 :	Introduce the transmission system	1	90	85															
CLO-3 :	Familiarize about the wheels,tyres,and braking system	1,2&3	90	85															
CLO-4 :	Understand the suspension and steering system	1,2&3	90	85															
CLO-5 :	Familiarize in electrical system in automotive engineering.	1,2&3	90	85															
CLO-6 :	Familiarize all the systems involved in automotive Engineering	1,2&3	90	85															

		Automobile Architecture and Performance	Transmission Systems	Wheel, Tyres, and Braking system	Suspension and steering System	Electrical System and Advances in Automotive Engineering
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Automotive components	Clutch types, coil spring and diaphragm type clutch.	Types of wheels, construction, wired wheels	Types front and rear suspension	Battery, general electrical circuits
S-2	SLO-1	Subsystem and their position of chassis	Single and multi-plate clutch	Types, construction, radial, bias tires and belted bias tires	Conventional and independent type suspension	Dash board instrumentation
S-3	SLO-1	Frame and body	Centrifugal clutch	Slip angle, tread patterns	Leaf springs, coil springs, dampers	Chip formation and its passenger comfort, safety and security
S-4	SLO-1	Front, rear and four wheel drives	Gear box types, constant mesh, sliding mesh	Tyre retreading cold and hot, tubeless tyres	Torsion bars, stabilizers bars, arms ,air suspension system	Heating, ventilation and air-conditioning(HVAC), seat belts, air bags
S-5	SLO-1	Operation and performance	Synchromesh gear box	Forces on vehicles, tyre grip	Types of steering system, Ackermann principle	Automotive electronics, Electronic Control Unit(ECU)
S-6	SLO-1	Traction force	Layout of gear box, Gear selector and shifting mechanism	Load transfer, braking distribution between axles, stopping distance	Davis steering gear, steering gear boxes, steering linkages	Variable Valve Timing(VVT), Active suspension system (ASS)
S-7	SLO-1	Traction resistance	Overdrive, automatic transmission	Types of brakes, mechanical, hydraulic brakes	Introduction to sheet metal working and applications	Electronic Brake Distribution(EBD)
	SLO-2		Rolling air, gradient resistance		Power steering , wheel geometry	
S-8	SLO-1	Power required for automobile,	Propeller shaft, universal joint, slip joint	Air brakes, Disc and Drum brakes	Caster, camber toe in,toe out	Electronic Stability program (ESP),

S-9	SLO-1	Power required for automobile,	Differential and real axle arrangement, hydraulic coupling	Engine brakes, antilock braking system	Wheel Alignment and balancing	Traction control System(TCS) Global positioning system(GPS), Electric Hybrid Vehicle
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Learning Resources	1. Kirpal Singh, "Automobile Engineering", standard publishers; Vol-I & II, 2017 2. Ramalingam, K. K," Automobile Engineering", SciTech publications; 2014 3. Rajput R K, " A Text book of Automobile Engineering", Laxmi Publications., 2015	4. Crouse, W.H and Anglia, D.L "Automotive Mechanics", Tata McGraw Hill, 2005 5. Narang, G.B , " Automobile Engineering", khanna publishers, 2001 6. Kamaraju Ramakrishna, "Automobile Engineering", PHI Learning Pvt Ltd, 2012.
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Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40%	-	30%	-	30%	-	30%	-	30%	-
Level 2	Apply Analyze	40%	-	40%	-	40%	-	40%	-	40%	-
Level 3	Evaluate Create	20%	-	30%	-	30%	-	30%	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	DR. K.L.HARIKRISHNA SSN COLLEGE OF ENGINEERING	Mr. C. Subramanian, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in		Dr.P.Nandakumar, SRMIST

Course Code	18MEE308T	Course Name	FOUNDATION SKILLS IN INTEGRATED PRODUCT DEVELOPMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the fundamentals of Product Development	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand requirement Engineering and System Design	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand Conceptual design	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand detail design	Expected Attainment (%)	Design & Development
CLR-5 :	Understand Obsolescence management and IPR		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Do global trend and PESTEL analysis	1 2&3	90	85	H		H			H	H		H						
CLO-2 :	Perform requirement Engineering	1 2&3	90	85	H		H			H	H		H						
CLO-3 :	Develop concepts for products as solution to engineering problem	1 2&3	90	85	H		H			H	H		H						
CLO-4 :	Perform verification and validation	1 2&3	90	85	H		H			H	H		H						
CLO-5 :	Perform maintenance requirement	1 2&3	90	85	H		H			H	H		H						

Duration (hour)		09	09	09	09	09s
S-1	SLO-1	Global Trends Analysis and Product decision: Types of various trends affecting product decision -Social Trends(Demographic, Behavioral, Psychographic ,	Requirement Engineering: Types of Requirements (Functional, Performance, Physical ,Regulatory, Economical, Behavioral);	Conceptualization: Industrial Design and User Interface Design	System Integration, Testing, Certification and Documentation: Manufacturing/Purchase and Assembly of Systems	Sustenance: Maintenance
S-2	SLO-1	Economical Trends(Market, Economy, GDP, Income Levels,Spending Pattern, target cost, TCO), Technical Trends(Technology,Applications, Tools, Methods)	Types of Requirements (, Technical, Stakeholder, Environmental, Industry specific, Internal-Company Specific)	Introduction to Concept generation Techniques	Integration of Mechanical, Embedded and S/W systems;	Sustenance: Repair; Enhancements.
S-3	SLO-1	Environmental Trends(Environmental Regulations and Compliance), Political/Policy Trends,(Regulations, Political Scenario, IP Trends and Company Policies);PESTLE Analysis	Requirement Engineering (Gathering (VOC)	Concept Screening & Evaluation - Concept Design	Introduction to Product verification processes and stages - Industry specific (DFMEA)	Product EoL: Obsolescence Management
S-4	SLO-1	Introduction to Product Development Methodologies and Management: Overview of Products and Services (Consumer product, Industrial product, Specialty products etc)	Analysis (QFD)	S/W Architecture, Hardware Schematics and simulation	Introduction to Product verification processes and stages - Industry specific (FEA, CFD)	Configuration Management; EoL Disposal.
S-5	SLO-1	Types of Product Development (NPD/ Re-Engineering (Enhancements, Cost Improvements)/ Reverse Engineering	Design Specification	Detailed Design: Component Design and Verification	Introduction to Product validation processes and stages Industry specific (Sub-system Testing/ Integration Testing	The Industry: Engineering Services Industry - overview; PLM,Product development in Industry versus Academia
S-6	SLO-1	Design Porting & Homologation);	Traceability Matrix and Analysis	High Level Design/Low Level	Introduction to Product validation processes	The IPD Essentials:

				Design of S/W Programs, S/W testing;	and stages Industry specific (Functional Testing/ Performance Testing / Compliance Testing	Introduction to vertical specific product development processes
S-7	SLO-1	Overview of Product Development methodologies (Over the Wall/ Waterfall/ V-Model/ Stage-Gate Process/ Spiral/Systems Engineering/ Agile)	Requirement Management	Hardware Schematic, Component design, Layout and Hardware Testing.	Product Testing standards and Certification - Industry specific;	Product development Trade-offs
S-8	SLO-1	Product Life Cycle (S-Curve, Reverse Bathtub Curve)	Introduction to System Modeling, System Optimization	Prototyping: Types of Prototypes (Mockups, Engineering Assessment Prototype, Alpha, Beta, Gamma)	Product Documentation (Compliance Documentation, Catalogue, Brochures, user manual)	Intellectual Property Rights and Confidentiality
S-9	SLO-1	Product Development Planning and Management (Budgeting, Risk, Resources and Design Collaboration) Product Development Planning and Management (Scheduling, Change Management, Product Cost Management)	System Specification; Sub-System Design; Interface Design.	Introduction to Rapid Prototyping and Rapid Manufacturing	Product Documentation (maintenance Manual, Spares Parts List, Warranty, Disposal Guide, IETMS, Web Tools)	Security and configuration management.

Learning Resources	1. Foundation Skills in Integrated Product Development (FSIPD), 1st Edition, 2013, Published by NASSCOM. 2. Ulrich, Karl T. and Eppinger, Steven D (2004) Product Design and Development, 5th Edition, McGraw-Hill, 2012.	3. Kevin N. Otto, "product design – techniques in reverse engineering and new product development", PEARSON, New Delhi, 2011
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.R.Prabhusekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	1. Mr. N. arun, SRM IST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr. Shanmugam. P, Shanmugam.p@sfl.co.in, Sundaram fasteners, Chennai	2. Dr. P. Nandakumar, SRMIST

Course Code	18MEE309T	Course Name	MODELING SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :		Acquire knowledge to model systems seen in reality			Level of Thinking (Bloom)	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :		Understand the use of mathematics in modeling																				
CLR-3 :		Understand the basic principles of modeling systems																				
CLR-4 :		Understand and develop simple models																				
CLR-5 :		Understand and recognize that modeling as an interdisciplinary requirement																				
CLR-6 :		Understand and correlate real time problems with mathematical forms																				
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :		Understand and correlate engineering systems seen in real time environment with the modeling systems			1&2	90	85	H	H	-	-	-	-	H	-	-	-	-	-	-	-	-
CLO-2 :		Understand and realize the use of mathematics in modeling engineering systems			1&2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :		Understand and able to convert real time problems into mathematical form			1&2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :		Understand and model various components of engineering systems			1,2,&3	90	85	H	H	H	H	H	-	-	-	-	-	-	-	-	-	-
CLO-5 :		Modeling engineering systems such as mechanical systems and thermal systems			1,2&3	90	85	H	H	H	H	H	-	-	-	-	-	-	-	-	-	-
CLO-6 :		Understand and recognize that modeling is an interdisciplinary requirement			1,2	90	85	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction: Model – Definition, Nature and necessity	Use of Modeling Mathematics: Principles of modeling – common aspects of all mechanical systems	Generate Simple Models: Introductions to system identification	Understanding the Mathematics in Response: Characteristic equation	Project: Identify a system
S-2	SLO-1	History of modeling	Given a simple system – create a model	Model mechanical systems - Rectilinear	Solution of characteristic equation	Objectives of modeling and simulation of a system
S-3	SLO-1	Different type of modeling	Assessment of reality of the model – degree of accuracy	Model mechanical systems - Torsional	Introduction to Eigen values – natural frequencies - eigen vectors – mode shapes	Identify components
S-4	SLO-1	Impact of computers on modeling	Quadratic oscillator system and need for this model	Model a thermal system	Use of Laplace transforms for stability analysis	Model components – test each component
S-5	SLO-1	Different areas of application – Design, Thermodynamics, Mechanics, Controls etc.	Spring mass damper system and need for such a system	Response analysis – the reverse engineered explanation	Different type of representation of systems	Assemble the model
S-6	SLO-1	Modeling in software	Linearity of springs – modeling	Study of response for different inputs – modeling inputs	How to analyze for controllability	Identify suitable inputs – model them
S-7	SLO-1	Introduction to Discrete and continuous systems	Modeling damping – different type	Time driven models	How to analyze for observability, stabilizability	Analyze the response to that input
S-8	SLO-1	Components of systems	Modeling systems – assemble - quadratic	Event driven models	Conditions for the same	Submit a report
S-9	SLO-1	Areas of applications	Relate mathematics to real system –	Numerical experimentation	Relevance of these tests to modeling	Presentation and viva voce

		ODEs, Transforms – solutions		
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Learning Resources	1. G. J. Olsder, J. W. van der Woude, J. G. Maks, D. Jeltsema, "Mathematical Systems Theory", VSSD, Leeghwaterstraat, Delft, Netherlands; 4th Edition, 2011 2. Polderman J. W., Willems J. C., "Introduction to mathematical theory of systems and control", Springer, 1997	3. Frank L Severence, "Systems modeling and simulation – An introduction", student edition, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.R.Prabhu sekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	Dr. G. Rajasekaran, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in		Dr. P. Nandakumar, SRMIST

Course Code	18MEE310T	Course Name	HUMAN BODY MECHANICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)															
CLR-1 :	Upon learning the students shall understand the fundamentals of biomechanics, joints, tissue overall anatomical structure and their importance.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Upon learning the students shall understandthe mechanism of the different parts of the human body.																						
CLR-3 :	Upon learning the students shall understandthe musculoskeletal system with tissue loads and responses and neuromuscular control.																						
CLR-4 :	Upon learning the students shall understand kinematics, is the accurate description of motion and is essential to understanding the biomechanics of human motion. Kinematics can range from anatomical descriptions of joint rotations to precise mathematical measurements of musculoskeletal motions.																						
CLR-5 :	Upon learning the students shall understand, the Newton's Laws of Motion in the human body and how these laws can be applied to human motion in the biomechanical principles of Force–Motion, Force–Time, and Coordination ContinuumPrinciples																						
CLR-6 :	Enableunderstanding of the concepts of human body mechanics that illustrate the application of biomechanics principles. These principles are the application for the biomechanical concepts used to improve movement or reduce injury risk																						
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																					
CLO-1 :	Upon learning the students shall understand the fundamentals of biomechanics, joints, tissue overall anatomical structure and their importance.				1,2,3	90	85	H	H				H		H								
CLO-2 :	Upon learning the students shall understand the mechanism of the different parts of the human body.				1,2	95	90	H	H			H	H	H	H								
CLO-3 :	Upon learning the students shall understand themusculoskeletal system with tissue loads and responses and neuromuscular control.				1,2,3	90	85	H	H			H	H	H	H	H			H				
CLO-4 :	Upon learning the students shall understand kinematics, is the accurate description of motion and is essential to understanding the biomechanics of human motion. Kinematics can range from anatomical descriptions of joint rotations to precise mathematicalmeasurements of musculoskeletal motions.				1,2,3	90	85	H	H	H	H	H	H	H		H			H				
CLO-5 :	Upon learning the students shall understand, the Newton's Laws of Motion in the human body and how these laws can be applied to human motion in the biomechanical principles of Force–Motion, Force–Time, and Coordination Continuum Principles				1,2,3	85	80	H	H		H	H	H	H	H				H				

		Introduction to Biomechanics of Human Movement and Anatomy of Human Body.	Equilibrium and Human Movement	Mechanics of the Musculoskeletal System	Kinematics of Human Movement	Angular Kinetics of Human Movement.
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction to biomechanics, Importance of Biomechanics, Improving Performance Preventing and Treating Injury	Equilibrium and Torque	General introduction of tissue and its classifications.	Kinematic convention, Proximal, Flexion, Anterior	Introduction to angular kinematics in arms for the biceps femoris muscle
S-2	SLO-1	Quantitative versus qualitative problems	Resultant Joint Torques	Response of Tissues to Forces, Stress, Strain, Stiffness and Mechanical Strength, Viscoelasticity	absolute spatial reference system for human gait	Sample problems on applying forces in optimal direction for maximum torque output
S-3	SLO-1	Structure, movements and loads on the shoulder	Levers, Anatomical levers	Biomechanics of the Passive Muscle–Tendon Unit (MTU)	Total description of a body segmentation in space	Moment of inertia of a skeleton about a specific axis
S-4	SLO-1	Structure, movements and loads on the elbow and wrist	Equations of static and dynamic equilibrium	Biomechanics of Bone	Direct measurement techniques	Newton's laws to calculate the net forces and torques acting on body segments.

S-5	SLO-1	Structure, movements and loads on the hip	Center of gravity and locating the center of gravity	Biomechanics of Ligaments	Goniometers Eletro goniometer	static equilibrium and a reaction board to calculate whole body center of gravity
S-6	SLO-1	Structure, movements and loads on the knee	Locating the human body Center of Gravity, Stability and balance.	Three Mechanical Characteristics of Muscle, Force–Velocity Relationship, Force–Length Relationship, Force–Time Relationship	Image measurement techniques	whole body center of gravity of a high jumper using the segmental method and a three-segment model of the body. Most
S-7	SLO-1	Structure, movements and loads on the spine	Properties of Bone, Maxwell & Voight Models of bone	Stretch-Shortening Cycle (SSC)	Cinematography	PRINCIPLE OF BALANCE
S-8	SLO-1	Structure, movements and loads on the foot	Biomechanics of human skeletal muscle.	Force–Time Principle	Optoelectic techniques	two-dimensional area within all supporting Biomechanical system.
S-9	SLO-1	Common injuries in shoulder, elbow wrist, hip knee, spine and foot.	Biomechanics of human Skeletal Articulations	Neuromuscular Control, The Functional Unit of Control: Motor Units, Regulation of Muscle Force, Proprioception of Muscle Action and Movement.	Problems on calculating velocities and accelerations	The position of the line of gravity relative to the limits of the base of support

Learning Resources	1. Susan .J. Hall, "Basic biomechanics", Tata Mcgraw Hill, Sixth edition, 2011. 2. Y. C. Fung, "Biomechanics", Springer Verlag, 2nd Edition, 1997. 3. D. J. Schneck and J. D. Bronzino, "Biomechanics- Principles and Applications", CRC Press, Second Edition, 2000 4. Kreighbaum, E. and Barthels, K., "Biomechanics: A Qualitative Approach for Studying Human Movement", Pearson, 1996.	5. Boston: Allyn and Bacon Alexander. R. Mc. Neill, "Biomechanics", Chapman and Hall, 1975 6. Fundamentals of Biomechanics by Duane Knudson (Springer) 7. Biomechanics and Motor Control of Human Movement By David A. Winter
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

Industrial Expert	Academic expert	Internal Expert
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Amit Roy Roy Chowdhury, IISER Shibpur, amit@aero.iests.ac.in	Dr. Sandipan Roy, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in		Dr. P. Nandakumar, SRMIST

Course Code	18MEE401T	Course Name	DESIGN OF TRANSMISSION SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC308T	Co-requisite Courses	Nil	Progressive Courses	//Course code
Course Offering Department	Department of Mechanical Engineering			Data Book / Codes/Standards	Approved Design Data Book

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Selection of flexible drives			
CLR-2 :	Design the Parallel gears			
CLR-3 :	Design the Non-Parallel gears			
CLR-4 :	Design the gear box			
CLR-5 :	Selection of bearings			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Select the flat belt, V-belt, chain and wire ropes			
CLO-2 :	Design the spur gear and helical gear			
CLO-3 :	Design the bevel gear and worm gear			
CLO-4 :	Design the multi speed gear box for machine tool applications			
CLO-5 :	Select the journal bearing, ball bearings, roller bearings and deep grove bearings			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
1,2,3	90	85
1,2,3	90	85
1,2,3	90	85
1,2,3	90	85
1,2,3	90	85

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	H	H	M	M	L	H	L	M	L	M	M	L	H	L
H	H	H	M	M	L	H	L	M	L	M	M	L	H	L
H	H	H	M	M	L	H	L	M	L	M	M	L	H	L
H	H	H	M	M	L	H	L	M	L	M	M	L	H	L

Duration (hour)		Flexible Drives	Parallel Gears	Non-Parallel Gears	Gear Boxes	Bearings
		9	9	9	9	9
S-1	SLO-1	Belt drives: types, selection of belt drives	Review of gear fundamentals, Forces and stresses in gear tooth	Straight bevel gear: Terminology	Geometric progression, standard step ratio, structural and ray diagrams Number of teeth calculation	Introduction of Hydrodynamic journal bearings
	SLO-2	Belt materials and applications	Equivalent number of teeth, gear tooth failures, Selection of gear materials	Forces and stresses on gear tooth		Sommerfeld Number, Raimondi and Boyd graphs
S-2	SLO-1	Selection of flat belt drives using fundamental equations	Design procedure on spur gear based on strength consideration	Design procedure on bevel gear based on strength consideration	Design procedure on sliding mesh gear box	Bearing materials, properties required for bearing materials, System of lubrication
	SLO-2	problems on flat belt drives using fundamental equations	Problems on spur gear based on strength consideration	Problems on bevel gear based on strength consideration	problems on sliding mesh gear box	
S-3	SLO-1	Selection procedure for flat belt drives using manufacturer's data	Problems on spur gear based on strength consideration	Problems on bevel gear based on strength consideration	problems on sliding mesh gear box	Selection procedure for journal bearing
	SLO-2	Problems on flat belt drives using manufacturer's data				
S-4	SLO-1	Selection procedure for V-belt drives using fundamental equations	Design procedure on spur gear based on wear consideration	Design procedure on bevel gear based on wear consideration	Design procedure on constant mesh gear box	Problems in journal bearings
	SLO-2	Problems on V-belt drives using fundamental equations	Problems on spur gear based on wear consideration	Problems on bevel gear based on wear consideration	Problems on constant mesh gearbox	
S-5	SLO-1	Selection procedure for V-belt drives	Problems on spur gear based on wear	Problems on bevel gear based on wear	Design of Multi speed gear box for	Introduction to Roller contact bearings

		using manufacturer's data	consideration	consideration	machine tool applications	
	SLO-2	Problems on V-belt drives using manufacturer's data				
S-6	SLO-1	Wire ropes: types, construction and Selection of wire ropes	Design procedure on helical gear based on strength consideration	Worm gear: Thermal capacity, efficiency, forces and stresses	Design of Multi speed gear box for machine tool applications	Types of bearing, Load rating, bearing materials and bearing failure
	SLO-2	Stresses in wire ropes	Problems on helical gear based on strength consideration	Design procedure on worm gear based on strength consideration		
S-7	SLO-1	Selection procedure for wire ropes	Problems on helical gear based on strength consideration	problems on worm gear based on strength consideration	Variable speed gear box	Selection of bearing
	SLO-2	Problems on wire ropes				
S-8	SLO-1	Power transmission chains: types and applications	Design procedure on helical gear based on wear consideration	Design procedure on worm gear based on wear consideration	Fluid couplings	Problems in ball bearing
	SLO-2		Problems on helical gear based on wear consideration	Problems on worm gear based on wear consideration		
S-9	SLO-1	Selection procedure on power transmission chains and sprockets	Problems on helical gear based on wear consideration	Problems on worm gear based on wear consideration	Torque convertor for automotive applications	Problems in roller bearing
	SLO-2	Problems on power transmission chains and sprockets				

Learning Resources	<ol style="list-style-type: none"> 1. Robert. C. Juvinall, Kurt. M. Marshek, "Fundamentals of Machine Component Design", John Wiley & sons, 6th Edition, 2017. 2. Joseph Edward Shigley and Charles R. Mischke, "Mechanical Engineering Design", McGraw – Hill International Editions, New York, 10th Edition, 2014. 3. Spotts, M.F., Shoup, T.E., Hornberger, L.E., "Design of Machine Elements", Prentice Hall of India Eighth Edition, 2004. 4. Paul H Black and O. E. Adams, P., "Machine Design", 3rd edition, Mc Graw Hill Book Company, Inc., New York, USA, 2007. 	<ol style="list-style-type: none"> 5. Bernard Hamrock, Steven Schmid, Bo Jacobson, "Fundamentals of Machine Elements", 2nd Edition, Tata McGraw-Hill Book Co., 2006. 6. Dr. Sadhu Singh, "Design of Machine Elements (Machine Design)", Khanna Publishers; Fifth edition (1987). 7. Khurmi R.S., Gupta J.M., "A text book of machine design", S.Chand & Company Ltd, 25th revised edition, 2005. 8. P.S.G Tech., "Design Data Book", Kalaikathir Achchagam, 2012
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Mr. Vignesh Shanmugam.s, Hyundai Motors India Limited, Irungattukottai – 602117.E mail – 273357@hmlil.net	Mr. D. Raja, SRM IST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr. Davidson Jebaseelan, davidson.jd@vit.ac.in, VIT, Chennai	Dr. P. Nandakumar, SRMIST

Course Code	18MEE402T	Course Name	OPTIMIZATION IN ENGINEERING DESIGN	Course Category	E	Professional elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Approved design data book		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Be familiar with principles of optimization and its need	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Be familiar with various conventional optimization techniques																							
CLR-3 :	Be familiar with Solving multivariable problems techniques																							
CLR-4 :	Be familiar with Solving problems using unconventional optimization techniques																							
CLR-5 :	Be familiar with Application of optimization to design of machine elements.																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	understand optimization principles and its need	1& 2	90	85																				
CLO-2 :	understand and apply the concept of conventional optimization techniques	1&2	90	85																				
CLO-3 :	understand and apply the concept of constrained in single variable as well as multivariable	1&2	90	85																				
CLO-4 :	understand and apply the concept unconventional optimization techniques	1&2,3	90	85																				
CLO-5 :	apply the methods of optimization in real life situation	1&2,3	90	85																				

		Introduction to optimization	Unconstrained optimization techniques	Constrained optimization techniques	Modern Methods of Optimization	Applications
Duration(hour)		9	9	9	9	9
S-1	SLO-1	Introduction to optimization: adequate and optimum design	Techniques of unconstrained optimization	Direct search methods: Random jumping method, Random walk method	Genetic Algorithm Introduction	Design optimization of springs
S-2	SLO-1	Principles of optimization, design vector, design constraints	Golden section method.	Tutorials on Random Jumping Method	Basic elements of natural genetics—reproduction, crossover, and mutation	Design vector for springs
S-3	SLO-1	Statement of an optimization problem	Fibonacci method	Tutorials on Random Walk Method	The computational procedure involved in optimizing the fitness function in genetic algorithm	Objective function for springs
S-4	SLO-1	Formulation of objective function	Random search	Direct search methods: conjugate gradient method, quasi-Newton methods	Tutorials on Genetic Algorithm	Design optimization of shafts and torsionally loaded members.
S-5	SLO-1	Design constraints	Random search	Tutorial on conjugate gradient method	Simulated Annealing: Introduction	Design vectors for torsionally loaded members
S-6	SLO-1	Classical optimization techniques: single variable	Pattern search	Indirect methods –Penalty function method	Simulated Annealing - Steps involved	Objective function for torsionally loaded members
S-7	SLO-1	Classical optimization techniques: single variable	Gradient search	Indirect methods –Penalty function method problems	Ant colony optimization: Basic Concept	Design optimization of simple truss members
S-8	SLO-1	Classical optimization techniques: multivariable	Quadratic interpolation method	Interior penalty function method	Ant colony optimization: Ant Searching Behavior	Design vectors for simple truss members
S-9	SLO-1	Classical optimization techniques multivariable	Cubic interpolation method	Exterior penalty function method	Graphical representation of the Ant colony optimization process	Objective function for simple truss members

Learning Resources	1. Rao Singaresu.S, "Engineering Optimization – Theory & Practice", New Age International (P) Limited, New Delhi, 2009.	5. William Orthwein, "Machine Component Design", Vol. I and II, Jaico Publishing house, New Edition, 2006.
	2. Kalyanamoy Deb, "Optimization for Engineering design algorithms and Examples", Prentice Hall of India Pvt. Ltd., 2006.	6. Rao.C.S, "Optimization Techniques", Dhanpat Rai & Sons, New Delhi
	3. Johnson Ray C, "Optimum design of mechanical elements", Wiley, John & Sons, Digitized 2007	7. Fox.R.L, "Optimization methods for Engineering Design", Addison Wesley Pub, Digitized 2007.
	4. Goldberg .D.E, "Genetic algorithms in search, optimization and machine", Barnen, AddisonWesley, New York, 1989.	8. Garret N. Vanderplaats, "Numerical optimization techniques for engineering", McGraw-Hill Ryerson, Limited, 1984.

Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	DR. SUBHAS GANGULY, sganguly.met@nitrr.ac.in NIT Raipur	Vamsi krishna dommeti SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	HARESH DURAI KARUPPIAH, Haresh.durai@mtbci.com, RENAULT NISSAN	Dr. P. Nandakumar, SRMIST

Course Code	18MEE403T	Course Name	TOOL ENGINEERING DESIGN	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Be familiar with tool materials and their properties			
CLR-2 :	Be familiar with the design of single point cutting tools and twist drills			
CLR-3 :	Be familiar with the design of various types of dies			
CLR-4 :	Be familiar with the blank development for different components			
CLR-5 :	Be familiar with the design of jigs and fixtures for simple components			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	Identify suitable tool materials for the specific manufacturing applications			
CLO-2 :	Design single point cutting tools and twist drill for different machining requirements			
CLO-3 :	Design various types of dies for manufacturing components			
CLO-4 :	Develop the blank for cylindrical and non-cylindrical shells			
CLO-5 :	Design and develop the jigs and fixtures for simple mechanical components			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	L	M	M	-	-	-	-	M	-	-	-	H	L	H
H	M	M	M	-	-	-	-	M	-	-	-	H	L	H
H	H	H	M	-	-	-	-	M	-	-	-	H	L	H
H	H	H	L	-	-	-	-	M	-	-	-	H	L	H
H	H	H	H	-	-	-	-	M	-	-	-	H	L	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Different types of tool materials: cemented carbides, coated carbides, cermets,	Press working terminology	Principles of jigs and fixtures	Design principles of fixtures	Case study in jigs
S-2	SLO-1	ceramics and polycrystalline and new tool materials	Different types of Presses and press accessories	Locating principles and different locating elements	Design of fixtures for milling operation	Case study in jigs
S-3	SLO-1	Composition and properties of tool materials	Computation of capacities and tonnage requirements of presses	Clamping principles, clamping devices and types in jigs	Design of fixtures for boring operation	Case study in jigs
S-4	SLO-1	Cutting tool selection and treatments	Various types of Strip layout	Analysis of clamping force	Design of fixtures for broaching & grinding operation	Case study in fixture
S-5	SLO-1	Design of single point turning tools and multipoint tools	Different types of dies, Progressive dies, Combination dies and compound dies	Function of drill bush, types drill bushes	Design of fixture for assembly	Case study in fixture
S-6	SLO-1	Problems on the design of single point cutting tool alone	Design and development of various types of cutting, forming, bending and drawing dies	Different types of jigs , Plate jig, latch jig, channel jig,	Design of fixture for inspection	Case study in fixture
S-7	SLO-1	Selection of tool holders and inserts for turning	Design and development of various types of cutting, forming, bending and drawing dies	Different types of jigs Post jig, angle plate jig, turn over jig, and pot jigs	Design of fixture for welding	Case study in press tools
S-8	SLO-1	Function of Chip breaker, types of chip breaker	Blank development for cylindrical and non-cylindrical shells, blank size calculation	Design and development of jigs for given components	Design and development of fixtures for given components	Case study in press tools
S-9	SLO-1	Design of twist drill and reamers	Forging dies basics and materials for forging dies	Design and development of jigs for given components	Design and development of fixtures for given components	Case study in press tools

Learning Resources	1. Sadasivan.T.A, and Sarathy.D, "Cutting tools for Productive machining", 1st edition, Widia (India) Ltd, Bangalore, 1999.	5. Prakash H. Joshi, "Press tool design and construction", 1st edition, Wheeler Publishing, New Delhi, 2000.
	2. Donaldson.C, Lecain.G.H and Goold.V.C, "Tool Design", Tata McGraw Hill publishing company limited, New Delhi, 2002	6. Kempster.M.H.A, "An Introduction to Jig and tool design", 3rd edition, ELBS, 1987
	3. Edward G. Hoffman, "Jigs and Fixture design", 2nd edition, Galgotia publication Pvt. Ltd., New Delhi, 1987	7. Prakash H. Joshi, "Cutting tools", 1st edition, Wheeler Publishing, New Delhi, 1997.
	4. Hiram E. Grant, "Jigs and Fixtures - Nonstandard clamping device", Tata McGraw Hill, New Delhi, 1971.	8. Prakash H. Joshi, "Tooling Data", 1st edition, Wheeler Publishing, New Delhi, 2000.

Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers

Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. S.Bhargav, GM,Rane Brake, Trichy	1. Dr. V.Srinivasan, Annamalai University, srinivraghavan@yahoo.com	1. Mr.V.G.Umasekar, SRMIST
2. Dr. Muthumanikkam, Jt. Director, CVRDE, DRDO, Avadi, Chennai.	2. Dr. Assaithambi, Govn. Col. of. Eng, sengipatti, Thanjavur, basaitambi@gcetj.edu.in	Dr. U. M. Iqbal, SRMIST

Learning Resources	1. Donald Hearn and Pauline Baker M. "Computer Graphics", Prentice Hall, Inc., 2009	3. Harington, Stevan, "Computer Graphics: A Programming Approach", McGraw Hill, 1983
	2. Ibrahim Zeid "CAD/Cam Theory and Practice", McGraw Hill, International Edition, 2010.	4. Plastock, Roy A., & Kally, "Theory and Problems of Computer Graphics", McGraw Hill, 1986

Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in		Dr. Davidson Jebaseelan, davidson.jd@vit.ac.in, VIT Chennai
2. A. Don Bosco, Valeo, Chennai		S.DineshBabu, Renault Nissan Technology, Chennai
		Internal Experts
		Mr.S.ArunPrasath, SRMIST
		Mr.R.Yogeswaran, SRMIST

Course Code	18MEE405T	Course Name	FATIGUE, FRACTURE MECHANICS AND CREEP	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with fatigue crack propagation and micromechanisms of fatigue	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the concepts of environmentally assisted cracking in metals	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Know about fracture mechanics and stress intensity factors	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Know about deformation at crack tip, crack tip opening displacement, crack initiation and growth	Expected Attainment (%)	Design & Development
CLR-5 :	Be familiar with characteristics, mechanisms, effects and considerations of creep		Analysis, Design, Research
			Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Recognize and analyze fatigue crack propagation, crack closure, fatigue threshold, variable amplitude loading and retardation and micromechanisms of fatigue	1&2 90 85	H H - - - - - - - - - - - - -
CLO-2 :	Appreciate the knowledge on environmentally assisted cracking, stress corrosion, hydrogen embrittlement and corrosion fatigue in metals	1&2 90 85	H - - - - - H - - - - - - -
CLO-3 :	Understand fracture mechanics and acquire knowledge on energy release rate, stress intensity factors of simple and complex cases	1&2 90 85	H H - - - - - - - - - - - -
CLO-4 :	Acquire knowledge on elastic deformation at the crack tip, J-integral, crack tip opening displacement and mixed mode crack initiation and growth	1&2 90 85	H H - - - - - - - - - - - -
CLO-5 :	Understand characteristics of creep and acquire knowledge on mechanisms, tests, interactions, temperature effects, materials and design considerations of creep	1&2 90 85	H H - - - - - - - - - - - -

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Fatigue crack propagation, similitude in Fatigue	Introduction to environmentally assisted cracking in metals, Corrosion principles: electrochemical reactions	Introduction to fracture mechanics: Kinds of failure, brittle and ductile fracture, modes of fracture failure	Anelastic deformation at crack tip: approximate shape and size of plastic zone
S-2	SLO-1	Empirical fatigue crack growth equations	Corrosion current and polarization, electrode potential and passivity, cathodic protection	Energy release rate: Griffith's dilemma, surface energy, Griffith's analysis, mathematical formulation, compliance approach, strain energy approach	Anelastic deformation at crack tip: effective crack length, effect of plate thickness
S-3	SLO-1	Crack closure, closer look at crack-welding mechanisms, loading variables on closure	Environmentally assisted cracking (EAC) overview: Cracking mechanisms	Energy release rate: anelastic deformation at crack tip, thin plate vs thick plate	Definition of J-Integral, path independence, stress-strain relation
S-4	SLO-1	The fatigue threshold: a two-criterion model, threshold behavior in inert environments	Crack growth rate vs applied stress intensity, threshold for EAC, small crack effects	Energy release rate: crack resistance, stable and unstable crack growth, critical energy release rate	Further discussion on J-integral from a designer's point of view, critical J-integral, safety or failure
S-5	SLO-1	Variable amplitude loading and retardation: reverse plasticity at crack tip, the effect of overloads and underloads	Static, cyclic and fluctuating loads, cracking morphology, life prediction	Introduction to Stress intensity factors, Investigations closer to crack tip, LEFM	J-Integral: engineers approach, simplified relation, applications

S-6	SLO-1	Models for retardation and variable amplitude fatigue	Stress corrosion cracking, film rupture model	Stress intensity factor: Stress and displacement fields in isotropic elastic materials, field equations	Introduction to CTOD, relationship between CTOD, K_I and G_I , Equivalence between CTOD and J	Creep and Stress Rupture: Deformation and fracture at Elevated Temperature
S-7	SLO-1	Growth of short cracks: microstructural and mechanical	Crack growth rate in stage II, corrosion product wedging	Stress intensity factor: Westergaard's approach, Mode I (opening mode), Mode II (sliding mode), Mode III (tearing mode)	Introduction to mixed mode crack initiation and growth	Theories of low and high temperature creep
S-8	SLO-1	Micromechanisms of fatigue: Fatigue in region II, micromechanisms near the threshold	Hydrogen embrittlement, cracking mechanisms, Variables that effect cracking behavior: load, hydrogen, temperature	SIF of more complex cases: Other applications of Westergaard approach, applications of principle of superposition	Mixed mode crack propagation: maximum tangential stress criteria, Strain energy density criterion	Prediction of longtime properties, effect of metallurgical variables, Creep resistant materials, hightemperature alloys
S-9	SLO-1	Damage tolerance methodology	Corrosion fatigue, time dependent and cycle dependent behavior, Mechanisms of corrosion fatigue, effect of corrosion product wedging on fatigue	Edge cracks, embedded cracks, critical stress intensity factor	Mixed mode examples, crack growth	Design considerations to avoid creep

Learning Resources	1. T. L. Anderson, "Fracture Mechanics Fundamentals and Applications", CRC Press Taylor & Francis; 4 th edition, 2017 2. Prashant Kumar, "Elements of Fracture Mechanics" Tata McGraw-Hill; 2009	3. C. T. Sun, Z. -H. Zin, "Fracture Mechanics", Elsevier; 2012 4. G. E. Dieter, "Mechanical Metallurgy", McGraw-Hill; 2017
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30%	-	30%	-	40%	-	40%	-	30%	-
	Understand										
Level 2	Apply	50%	-	50%	-	40%	-	40%	-	50%	-
	Analyze										
Level 3	Evaluate	20%	-	20%	-	20%	-	20%	-	20%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Sudheesh Kumar, sudheeshkumar3@gmail.com, GCE, Kannur	Dr T V V L N Rao, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	Dr.R.Prabhusekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	Dr P Nandakumar, SRMIST

Course Code	18MEE406T	Course Name	LINEAR ELASTICITY	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	Advanced calculus and complex Analysis, mechanics of solids	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Department of Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	To studyConcept of Stress- Strains and Deformation	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	To ApplyBoundary Conditions for different kind of problems	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	To solve the problem using different solution method	Expected Proficiency (%)	Problem Analysis
CLR-4 :	To solve the plane elasticity problems using different solution method	Expected Attainment (%)	Design & Development
CLR-5 :	To solvetorsion and elastic cylinders problems		Analysis; Design, Research
CLR-6 :	To studyConcept of Stress- Strains and Deformation		Modern Tool Usage
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		Society & Culture
CLO-1 :	understand the basics of Tensors, Index Notation, Coordinate Transformations, Deformation and Strain, Strain Transformation, Principal Strains, StrainCompatibility,	1,2	Environment & Sustainability
CLO-2 :	apply boundary conditions and can get the general result	1,2	Ethics
CLO-3 :	solve the problem using different solution method	1,2,3	Individual & Team Work
CLO-4 :	solve the plane elasticity problems using different solution method	1,2,3	Communication
CLO-5 :	Solve torsion and elastic cylinders problems	1,2,3	Project Mgt. & Finance
CLO-6 :	Able to understand the basics of Tensors, Index Notation, Coordinate Transformations, Deformation and Strain, Strain Transformation, Principal Strains, StrainCompatibility,	1,2	Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

	Foundations	General Results	System Response	Plane Elasticity Problems	Torsion And Flexure Of Elastic Cylinders
Duration (hour)	9	9	9	9	9
S-1	SLO-1	Mathematical Preliminaries-Scalar, Vector, Matrix, and Tensor Definitions	Review of Field Equations	Anti-plane Strain	Plane Stress and Plane Strain
S-2	SLO-1	Index notation	Field equations and boundary conditions, Navier equations	Field Equations and Boundary Conditions	Introduction to Airy Stress Function
S-3	SLO-1	Concept of Stress- Strains and Deformation	Stress Formulation-Beltrami-Michell compatibility equations	Complex Variable Solutions to Anti-plane Strain Problems	Stress function, stress function for plane stress and plane strain cases
S-4	SLO-1	Coordinate Transformations -Strain Transformation	Displacement Formulation Principle of Superposition	Solution using Taylor Series	Introduction to Cartesian Coordinate Using Polynomials
S-5	SLO-1	Principal Strains, Strain Compatibility	2D approximations (plane stress and plane strain) and solution strategies	Solution using Laurent Series	Cartesian Coordinate Solutions Using Polynomials
S-6	SLO-1	TractionVector	Uniqueness Theorems-Reciprocal Theorem	Solution using Cauchy Integral Formula	Introduction to Cartesian Coordinate Using Fourier Methods
S-7	SLO-1	Stress Transformation	Principle of Virtual Work	Solution using Cauchy Integral Formula	Cartesian Coordinate Solutions Using Fourier Methods
S-8	SLO-1	Equilibrium Equations&Generalized	Principle of Minimum Potential and	Solution using Conformal Mapping	Introduction to Solutions in Polar Coordinates

		<i>Hooke's law.</i>	<i>Complementary Energy</i>			
S-9	SLO-1	<i>Review of Continuum Mechanics Concepts</i>	<i>Saint-Venant's Principle</i>	<i>Solution using Conformal Mapping</i>	<i>Axisymmetric problems, thick-walled cylinders, rotating disks of uniform thickness, stress concentration, effect of circular holes on stress distribution in plates.</i>	<i>Flexure Problems without Twist</i>

Learning Resources	1. Martin H. Sadd, <i>Elasticity: Theory, "Applications and Numeric's"</i> , Elsevier India, 2005 2. Timoshenko.S.P, Goodier.J.N, "Theory of Elasticity", Tata McGraw-Hill Education, 2010. 3. England.A.H, "Complex Variable Methods in Elasticity", Dover Publications, 2003. 4. Malvern.L.E, "Introduction to the Mechanics of a Continuous Medium", Prentice Hall, 1977.	5. Love.A.E.H, "The Mathematical Theory of Elasticity", Dover, 2011. 6. Landau.L.D and Lifshitz.E.M, "Theory of Elasticity, Butterworth-Heinemann", 1986. 7. Atkin.R.J and Fox.N, "An Introduction to the Theory of Elasticity", Dover,2005. 8. Barber.J.R, "Elasticity", Springer, 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	30%	-	30%	-	40%	-	40%	-	30%	-
	Understand										
Level 2	Apply	50%	-	50%	-	40%	-	40%	-	50%	-
	Analyze										
Level 3	Evaluate	20%	-	20%	-	20%	-	20%	-	20%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. R. Damodaram, SSN College of Engineering, Chennai, damodaramr@ssn.edu.in	Mr. K. Jegadheesan, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.R.Prabhusekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	Dr. M. Iqbal, SRMIST

Course Code	18MEE407T	Course Name	DESIGN OF PRESSURE VESSEL AND PIPING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC206T	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	ASME Pressure Vessel and Boiler Code; Section VIII Div. 1&2; 2003.American Standard Code for Pressure Piping; B 31.1.		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1:	Familiarize with basics of Pressure vessel design	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	Familiarize with different types of stresses and their effects in Pressure vessel.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	Equip with Pressure vessel design.				H	H	H	M										L	
CLR-4:	Expose to failure mechanisms in Pressure vessel.				H	H	H											L	
CLR-5:	Expose to the concept of piping layout and the stresses acting on it.				H	H	H											L	
CLR-6:	Analyse and design of pressure vessel and piping.				H	H	H											L	
					H	H	H											L	
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1:	understand the basics of pressure vessel design	1&2	90	85															
CLO-2:	determine various stresses, and their effects in pressure vessel.	12&3	90	85															
CLO-3:	design pressure vessel.	12&3	90	85															
CLO-4:	know the various types of failures in pressure vessel.	12&3	90	85															
CLO-5:	know the concepts of piping layout and the stresses acting on it	12&3	90	85															
CLO-6:	Know the design concepts of pressure vessel and piping	1 2&3	90	85															

		Overview of Pressure Vessel and stresses	Stresses in Pressure Vessels	Design of Pressure Vessels	Failure Analysis of vessels	Fundamentals of piping design
Duration (hour)		09	09	09	09	09
S-1	SLO-1	Introduction, construction and design procedure.	Stresses in cylinder, Dilation of pressure vessels, Intersecting spheres.	Stress concentration at a variable thickness transition section in a cylindrical vessel, circular hole, Elliptical Openings	Buckling phenomenon, vessels under external pressure.	Introduction to piping, definition, codes, standards and specifications.,
S-2	SLO-1	. Design approach, design by rule, design by analysis.	Membrane stresses in vessel under internal pressure, cylindrical vessel, spherical, conical vessel.	Stress concentration factor for superposition, Dynamic and thermal transient condition.	Elastic buckling of circular ring, deflection curve, buckling.	Piping components, pipe, pipe fittings, flanges, valves, bolt and gaskets.
S-3	SLO-1	Introduction, Stress intensity, Stresses in a circular ring.	Thermal stresses in long hollow cylinder, logarithmic, thermal gradient.	Design of tall cylindrical self-supporting process columns for short vertical vessels.	Buckling of long cylinder or tubes, inelastic collapse, initial non-circularity.	Flow diagram, piping layout
S-4	SLO-1	Stress significance, stress pattern.	Linear thermal gradient, Steady state Thermal stresses.	Design of supports for short vertical vessel.	Collapse of thick walled cylinder, fully plastic wall,	underground, above ground pipelines
S-5	SLO-1	Residual stress, shape of a member	Thermal stresses due to thermal gradients.	Theory of reinforced openings.	Collapse of the wall of a cylinder.	Piping stress analysis, Forces and moments
S-6	SLO-1	Methods for determining stresses, strain gauge, Photo elastic, Moiré.	Ultra-high-pressure vessel -design principle, wedge, segment principle.	Nozzle reinforced placement shape, single nozzles, Multiple nozzles, Nonradical nozzles.	Effect of supports on elastic buckling, buckling, collapse coefficient.	Piping specifications, static and dynamic loads
S-7	SLO-1	Thermal stresses, thermal strains and	Cascade principle, yoke Beam and ties,	Pressure vessel design, welded joints,	Buckling under combined external	nomenclature of pipe supports, guided

		their significance.	Anvil principle, Bridge man massive conical anvils.	strength of weldments.	pressure and axial loading	cantilever method
S-8	SLO-1	Terminology of vessel, vessel Ligament.	Discontinuity stresses in pressure vessels, Cylindrical vessels with various heads, Infinite long beam, semidefinite beam.	Bolted joints and gaskets, thread and nut design, bolt head, shank design.	interaction method, interaction equations in design.	Design of piping system, pressure components design
S-9	SLO-1	Ligament efficiency, Longitudinal, circumferential ligaments in a cylindrical and spherical shape.	Stresses in a bimetallic joint, deformation and stresses in flanges.	Introduction to ASME pressure vessel codes.	Safety factors in design, Imperfection sensitivity	minimum wall thickness of pipe, pipe span calculations, Ansi piping codes.

Learning Resources	<ol style="list-style-type: none"> 1. John F. Harvey, "Theory and Design of Pressure vessels", CBS publishers and Distributors, 1987. 2. Henry H Bedner, " Pressure Vessels, Design Hand Book ", CBS publishers and Distributors ,1987. 3. Somnath Chattopadhyay, " Pressure vessels: Design and practice ", CRC Press ,2004. 4. Smith P., "Fundamentals of piping design", Elsevier Gulf Publishing Company 2007. 5. William. J. Bees"Approximate Methods in the design and analysis of pressure vessels and piping ", Pre ASME-pressure vessels and piping conference ,1997. 6. ASME Pressure Vessel and Boiler code, section viii Div. 1&2,2003 American standard code for pressure piping, B31.1 7. Brownell. L E & Young E.D," Process equipment design ", Wiley Eastern Ltd, India.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr V.MARIAPPAN, vmari@nitt.edu, NIT Trichy	Dr. P.Nandakumar, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in		Mr.R.Harris Samuel, SRMIST

Course Code	18MEE408T	Course Name	KINEMATICS AND DYNAMICS OF ROBOTS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire the fundamental concepts of Robot Transformation	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Impart the Knowledge about the concepts of Direct kinematics of Robot	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Impart the Knowledge about the concepts of Inverse kinematics of Robot	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire fundamental knowledge about the planning trajectories on workspace of robot	Expected Attainment (%)	Design & Development
CLR-5 :	Enable students with the basic knowledge of Robot Dynamics		Analysis, Design, Research
CLR-6 :	Understand the kinematics and dynamics models of robots		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understanding rigid body transformations, homogeneous transformation matrices of Robot.	1 & 2 85 75	H H M M M L L L M M M M M M M
CLO-2 :	Derive the direct kinematics equation for robot manipulators.	2 80 70	H H M M M L L L M M M M M M M
CLO-3 :	Derive the inverse kinematics equation for robot manipulators.	1 & 2 80 70	H H H M M L L L M M M M M M M
CLO-4 :	Generate workspace and trajectory planning in Cartesian and joint spaces.	1 & 2 75 70	H H H M M L L L M M M M M M M
CLO-5 :	Understand the equations of motion (dynamics model) of manipulators using Lagrange-Euler and Newton-Euler methods.	1 & 2 75 70	H H H M M L L L M M M M M M M
CLO-6 :	Analyze the kinematic and dynamic model of robot	2 75 70	H H M M M L L L M M M M M M M

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Introduction about machines and mechanisms – Robot anatomy	Link coordinates for D-H representation	Inverse Kinematics of transformation	Introduction & analysis of work space	Introduction to manipulator dynamics
	SLO-2				
S-2	SLO-1 Arm and wrist configuration of Robot	Arm matrix and Arm equation – DH representation of Kinematics model	General properties of solution	Workspace analysis for 4 axis SCARA robot	Lagrange's equation - kinetic and potential energy
	SLO-2				
S-3	SLO-1 Position and orientation of objects, descriptions: Positions, Orientations and Frames	Direct Kinematics of 2 DOF Planar Manipulator arm	Inverse Kinematics for 2 DOF planar robot	Work space fixtures	Link inertia tensor
	SLO-2				Link jacobian manipulator inertia tensor
S-4	SLO-1 Coordinate transformation / Mapping in fixed angle rotation		Inverse kinematics – 3 DOF articulated robot – Guide lines, solution techniques	Trajectory planning - Terminology	
	SLO-2	Direct Kinematics of 3 axis articulated robot – Link		Trajectory planning – pick and place motion	Gravity and generalized forces
S-5	SLO-1 Mappings: Changing descriptions from Frame to Frame		Inverse kinematics – 3 DOF articulated robot – Derivation of equations	Continuous path motion – Joint space technique and Cartesian space technique	Lagrange – Euler Dynamic model formulation
	SLO-2				
S-6	SLO-1 Operators: Translations, Rotations and Transformations, Transformation Arithmetic	Direct Kinematics of 3 DOF wrist	Inverse kinematics of RPY wrist	Trajectory planning – Interpolated motion	Kinetic and Potential Energy Formulation for Two axis planar robot
	SLO-2				

S-7	SLO-1	Transformation of Vectors for Rotation, translation and composite		Inverse kinematics of – 4 axis SCARA robot – General solution	Trajectory planning – straight line motion	L-E Dynamics model for Two axis planar robot
	SLO-2					
S-8	SLO-1	Inverting Transformation	Direct Kinematics Analysis of 4 axis SCARA Robot	Tool Configuration	Trajectory planning for 3 DOF Manipulator	Newton – Euler formulation
	SLO-2					
S-9	SLO-1	Rotation Matrix – fixed and Euler angle representation		Tool configuration of a 4 axis SCARA robot	Trajectory planning for 4 DOF SCARA Manipulator	N-E Dynamics model for Two axis planar robot
	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Robert J. Schilling, <i>Fundamentals of Robotics Analysis and Control</i>, Prentice Hall of India Pvt. Ltd., 2003 2. Richard D. Klaffer, Thomas. A, Chmielewski, Michael Negin, <i>Robotics Engineering an Integrated Approach</i>, Prentice Hall of India Pvt. Ltd., 1993 3. P.A. Janaki Raman, <i>Robotics and Image Processing An Introduction</i>, Tata Mc Graw Hill Publishing company Ltd., 1995 4. John J. Craig, <i>Introduction to Robotics Mechanics and Control</i>, Fourth Edition, Pearson Education International, 2018. 5. Mittal RK, Nagrath IJ, <i>Robotics and Controls</i>, Tata McGraw Hill Publications, 2003
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40%	-	30%	-	30%	-	30%	15%	30%	-
Level 2	Apply Analyze	40%	-	40%	-	40%	-	40%	20%	40%	-
Level 3	Evaluate Create	20%	-	30%	-	30%	-	30%	15%	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Yogesh Singh, Yogesh@mech.nits.ac.in, NIT Silchar	Mr. KR. Arun prasad, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.R.Prabhu sekar, rprabhusekar@mnnit.ac.in, MNNIT Allahabad	Dr. P. Nandakumar, SRMIST

Course Code	18MEE409T	Course Name	COMPUTER APPLICATIONS IN DESIGN	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	understand the overall design process and the types of three-dimensional modeling schemes.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	write programs in MATLAB for Mechanical Engineering Design problems	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	understand in applying CAD model for design	Expected Proficiency (%)	Problem Analysis
CLR-4 :	know how the model data is stored, retrieved and to organize for CIM applications	Expected Attainment (%)	Design & Development
CLR-5 :	know uses of parametric modeling. Uses of Rapid prototyping and Artificial Intelligence		Analysis; Design, Research
CLR-6 :	understand the overall design process and the types of three-dimensional modeling schemes.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:			
CLO-1 :	understand the overall design process and can able to apply on any projects.	1&2	90	85
CLO-2 :	write interactive programs in MATLAB for design problems.	1	90	85
CLO-3 :	understand in applying CAD model in design	1	90	85
CLO-4 :	organize data for CIM applications and various aspects of data storage and manipulation	1&2	90	85
CLO-5 :	understand the uses of parametric modelling and artificial intelligence.	1&2	90	85

		Introduction to CAD	Writing design programs in MATLAB for Machine Elements	Applying the CAD model in design	Entity Manipulation and Data Storage:	Expanding the capability of CAD
Duration (hour)		9	9	9	9	9
S-1	SLO-1	The design process	Introduction to Machine Drawing	Applications to draughting	Manipulation of the model	Parametric modeling
S-2	SLO-1	Different types of design process	Introduction to Machine Drawing	The use of 3D modeling for 2D representation	Model storage	Variation modeling
S-3	SLO-1	Role of CAD in Design	Introduction to MATLAB software	Approaches to 3D modelling	Data structures	Feature based modeling
S-4	SLO-1	Types and applications of design models	Introduction for Writing interactive programs to solve design problems in MATLAB	Direct assessment for the geometric model	Database consideration	Feature recognition
S-5	SLO-1	Computer representation of drawings	Design problems using MATLAB for Shafts	Generation of new models from the geometric model	Object oriented representations	Design by features
S-6	SLO-1	Three-dimensional modeling schemes	Design problems using MATLAB for Gears	The scope of customization and design automation	CIM	
S-7	SLO-1	Wire frame model	Design problems using MATLAB for Pulleys	Typical facilities for system customization	Organizing data for CIM application	Rapid prototyping
S-8	SLO-1	Surface representation model	Design problems using MATLAB for flywheel	The graphics Kernel System	ERP (Enterprise Resource planning)	
S-9	SLO-1	Solid modeling	Design problems using MATLAB for connecting rods	Standard for exchanging images	Design information system	Artificial intelligence in design

Learning	1. Charles. S. Knox, "Organising data for CIM Applications", Marcel Dekker Inc. New York 1987.	5. Chandupatla and Belagundu, "Introduction to Finite Element Methods in Engineering", Prentice
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Resources	2. Ibrahim Zeid, "CAD/ CAM - Theory and Practice" - McGraw Hill, International Edition, 1998. 3. Chris McMahon and Jimmi Browne, "CAD CAM Principles, practice and Manufacturing Management", Pearson Education Asia, 2002. 4. Kr. Gopalakrishna, "Machine Drawing", Subhas Stores, 2007	Hall of India Private Limited, New Delhi, 1997. 6. http://www.machinedesign.com 7. MATLAB: Easy Way of Learning, S. Swapna Kumar and S. V. B. Lenina, 2016
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Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	-	15%	-	15%	-	15%	-	15%	-
	Understand										
Level 2	Apply	20%	-	20%	-	20%	-	20%	-	20%	-
	Analyze										
Level 3	Evaluate	10%	-	15%	-	15%	-	15%	-	15%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers

Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Davidson Jebaseelan, davidson.jd@vit.ac.in VIT Chennai.	Mr. S. Balamurugan, SRM IST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. Vignesh Shanmugam.S, 273357@hmlil.net Hyundai Motors Limited, Chennai	Dr. P. Nandakumar, SRMIST

Course Code	18MEE321T	Course Name	ELEMENTS OF MECHATRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire the fundamental knowledge of mechatronics systems	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the sensors and transducers.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the actuation systems, signal processing and controllers.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire knowledge about the PLC.	Expected Attainment (%)	Design & Development
CLR-5 :	Know mechatronics system design and its applications.		Analysis, Design, Research
CLR-6 :	Knowledge about the concept and components of mechatronics systems.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Differentiate the basic key elements of mechatronics systems	1 90 85	M - M - - - - - - - - - - L L L
CLO-2 :	Have cognizance on performance of sensors and transducers.	1 90 85	H M M L L - - - - - - - H H L
CLO-3 :	Differentiate and utilize actuation systems, signal processing and controllers.	1 90 85	H M M M - - - - - - - H M L
CLO-4 :	program the PLC.	2 90 85	H H M M - - - - - - - H H L
CLO-5 :	Design of mechatronics system and its applications.	3 90 85	H M H H - - - - - - - H M L
CLO-6 :	Differentiate, analysis and design mechatronics systems.	3 90 85	H M M M L - - - - - - - H M L

	Introduction to Mechatronics	Sensors and Transducers	Electrical Drives and Controllers	Programmable Logic Controllers	Mechatronics System Design and Application
Duration (hour)	9	10	10	8	8
S-1	SLO-1	Introduction to Mechatronics systems	Introduction to sensors and transducers, classification and Static and dynamic characteristics.	Introduction, Electromagnetic Principles, Solenoids and Relays	Basic structure, Programming units and Memory of Programmable logic controller
S-2	SLO-1	Mechatronics system components and Measurement Systems, Control Systems.	Principle and working of Resistive, capacitive, inductive transducer.	Electrical drives of stepper motors, servo motors.	Input and Output Modules, Mnemonics for programming
S-3	SLO-1	Open and Closed Loops Systems temperature control	Resonant transducer and Optical measurement systems for absolute and incremental encoders	Operational amplifier	Latching and Internal relays
S-4	SLO-1	Water level controller and Shaft speed control	Photo electric sensor and vision system	A/D converters	Timers, Counters and Shift Registers
S-5	SLO-1	Sequential Controllers : Washing machine control	Fibre optic transducers	D/A converters	Master relay and Jump Controls
S-6	SLO-1		Solid state sensors and transducers for magnetic measurements	Signal processing, Multiplexer and Introduction to Data acquisition system	
S-7	SLO-1				

S-8	SLO-1	Sequential Controllers : Digital camera	Temperature measurements	Proportional, Integral, Derivative and PID controller	Programming the PLC using Ladder diagram for Simple applications.	
S-9	SLO-1	MEMS and the automobile airbag	Chemical measurements, piezoelectric sensor and accelerometers	Introduction to Micro controller : M68HC11 and ATMEGA328		
S-10	SLO-1		Ultrasonic sensors and transducers for flow and distance			

Learning Resources	TEXT BOOKS			REFERENCES		
	1. Bolton.W, "Mechatronics", Pearson, 6th Edition, 2015. 2. Bradley.D.A, Dawson.D.BurdN.C.and Loader A.J, "Mechatronics", CRC Press, 1993, First Indian Print 2010. 3. Jacob Fraden, "Handbook of Modern Sensors Physics, Designs, and Applications", 5th Edition, Springer International Publishing, 2016.			1. James Harter, "Electromechanics, Principles and Concepts and Devices", Prentice Hall, New Delhi, 1995. 2. David W. Pessen, "Industrial Automation Circuit Design and Components", Wiley India, 2011. 3. Bolton.W, "Programmable Logic Controllers", Elsevier, 2015. 4. Brian Morris, "Automatic Manufacturing Systems Actuators, Controls and Sensors", McGraw Hill, New York, 1994 5. Godfrey C. Onwubolu, "Mechatronics Principles and applications", Butterworth-Heinemann, New Delhi, 2006.		

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr. B. Sriram, WABCO INDIA LTD, sriram.b@wabco-auto.com	DR J.Prasanna, CEG, Anna University, pras_me@yahoo.com	1. Mr.N. Karthikeyan, SRMIST
Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.R.Sivaramakrishnan, MIT, Anna University, srk@mitindia.edu, srk@annauniv.edu	2. Mr.V.Manojkumar, SRMIST

Course Code	18MEE322T	Course Name	FLUID POWER CONTROL	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses		Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards			NIL

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	Be familiar with the construction and working of hydraulic power generating and utilizing elements			
CLR-2 :	Know the working of various control valves and familiar with accessories in hydraulic systems			
CLR-3 :	Be familiar with the construction and working of pneumatic systems and fluidic control			
CLR-4 :	Be familiar with designing of fluid power circuits for given applications			
CLR-5 :	Know the maintenance procedures and trouble shooting			
CLR-6 :	understand the fluid power systems and to develop circuits for industrial applications			

Learning		
1	2	3
Thinking (Bloom)	Proficiency (%)	Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Analysis	Development	Design,	Tool Usage	Culture	Environment & Sustainability	Ethics	Team Work	Communication	Management & Finance	Learning			

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Recognize the use of power generating elements, and acquire knowledge the principles and characteristics of hydraulic components	1&2	90	85	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Acquire knowledge on working of various control valves and familiar with accessories in hydraulic systems	1	90	85	H	-	-	-	-	-	-	-	-	-	-	-	M	L	L
CLO-3 :	Acquire knowledge on the principles and working of pneumatic components.	1	90	85	H	-	-	-	-	-	-	-	-	-	-	-	M	L	L
CLO-4 :	Design the circuit for given applications	1,2&3	90	85	H	H	H	-	M	-	-	-	-	-	-	-	H	H	H
CLO-5 :	Acquire knowledge on maintenance and analyze the trouble shooting of fluid power systems	1&2	90	85	H	-	-	-	-	M	-	-	-	-	-	M	H	H	H
CLO-6 :	Understand fluid power systems and apply knowledge to develop fluid power circuits for industrial applications	1,2&3	90	85	H	H	H	-	-	-	M	-	-	-	-	-	M	M	M

Duration (hour)		Hydraulic Power Generating And Utilizing Systems	Hydraulic Valves And Accessories	Pneumatic Systems	Design Of Fluid Power Systems	Applications, Maintenance And Trouble Shooting
		10	9	9	9	8
S-1	SLO-1	Introduction to fluid power system, Hydraulic fluids functions, types, properties, selection and application.	Construction and working of manually, pilot and solenoid operated 2/2, 3/2, 4/2,4/3, directional control valves	Introduction, comparison with hydraulic systems and electrical systems	Fluid power actuators: Speed and force calculations in fluid power systems	Industrial hydraulic circuits for riveting machine.
S-2	SLO-1	POWER GENERATING ELEMENTS: Construction, operation, characteristics of External Gear pump, internal Gear pump	Construction and working of pressure relief, compound pressure relief, pressure sequence valves	Construction, operation, characteristics and symbols of reciprocating and rotary compressors	Pump performance calculations, Sizing of reservoirs. Calculation of pressure and pressure drop across components in fluid power circuits	Hydraulic circuits for grinding and shaping machine.
S-3	SLO-1	Construction, operation, characteristics of Lobe, Gerotor and Screw pumps	Construction and working of pressure reducing, counter balance valves	Construction, operation, characteristics and symbols of 3/2, 5/2, 5/3 manual operated, pilot operated and solenoid operated DCVs	Finding the capacity of accumulators required for hydraulic systems.	Working of hydraulic press and pump unloading circuits
S-4	SLO-1	Construction, operation, characteristics of Un balanced and balanced vane pump	Working principle of check valve, throttle valve, one way FCV.	Need for air treatment, Filter, Regulator, Lubricator, Muffler and Dryers	Selection of different components such as reservoir, various valves, actuators, filters, pumps for a practical application.	Hydraulic / pneumatic circuits for material handling Systems
S-5	SLO-1	Construction, operation, characteristics of pressure compensated vane pump	Working principle of pressure compensated FCV, and their applications.	Introduction to fluidic devices, working of Bi-stable, monostable devices	Design of hydraulic/pneumatic circuits for simple reciprocation, regenerative, speed control of actuators	Preventive and breakdown, maintenance procedures in fluid power systems

S-6	SLO-1	Construction, operation, characteristics of bent axis piston pump, swash plate piston pump and Radial Piston Pump	Importance of proportional valves, Servo valves and its applications	Fluidic application circuits – continuous reciprocation and sequencing	Design of hydraulic/pneumatic circuits for sequencing, synchronization	Trouble shooting of fluid power systems : problems, causes and remedies- hydraulics
S-7	SLO-1	Construction and working of single acting, double acting hydraulic linear actuators	Need for intensifier in hydraulic systems, applications	Pneumatic Sensors types and applications	Cascading circuit for trapped signals : two cylinders	Trouble shooting of fluid power systems : problems, causes and remedies- pneumatics
S-8	SLO-1	Special cylinders: Tandem, Rodless, Telescopic	Different switches, filters, seals, fittings and other accessories used in hydraulic systems	Introduction to Electro Pneumatics – switches, relays, solenoids	Cascading circuit for trapped signals : three cylinders	Safety aspects involved fluid power systems
S-9	SLO-1	Cushioning arrangement for cylinders to reduce the impact on the cylinders, Various cylinder mountings	Functions, types and applications of accumulators in hydraulics	Constructing electrical ladder diagrams for various fluid power applications.	Fail-safe circuit, counter balance circuit, actuator locking	
S-10	SLO-1	Construction and working of Gear, Vane, Piston motors to obtain rotary motion				

Learning Resources	<ol style="list-style-type: none"> 1. Anthony Esposito, "Fluid Power with applications", Pearson Education Inc, 2015. 2. Majumdar.S.R, "Oil Hydraulic Systems: Principles and Maintenance", Tata McGraw Hill Publishing company Ltd, New Delhi, 2006. 3. Majumdar.S.R, "Pneumatic systems – principles and maintenance", Tata McGraw Hill Publishing company Ltd, New Delhi, 2006 4. Ilango Sivaraman, "Introduction to Hydraulics and Pneumatics", PHI Learning Pvt. Ltd, New Delhi, 2017. 	<ol style="list-style-type: none"> 5. Joji Parambath "Industrial Hydraulic Systems: Theory and Practice", Universal Publishers, USA, 2016. 6. Eurling Ian C. Thmer, "Engineering Applications of Pneumatics and Hydraulics", Routledge, Taylor & Francis group, London and Newyork, 2011. 7. Andrew Parr, "Hydraulics and Pneumatics: A technician's and engineer's guide", Elsevier Ltd, 2011. 8. Anton H Hehn, "Fluid Power Trouble Shooting", Marcel Dekker Inc., NewYork, 1995
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Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers

Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	Dr. M. R. Stalin John, SRMIST
Mr. S. Sendilkumar- Festo India Pvt Ltd	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Mr. R. Murugesan, SRMIST

Course Code	18MEE323T	Course Name	PROCESS PLANNING AND COST ESTIMATION	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	18MEC103T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Acquire knowledge about Process planning	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand Different Cost and its components	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Learn about cost estimation of products manufactured in foundry and forging shops	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire knowledge about various cost involved in welding and sheet metal shops	Expected Attainment (%)	Design & Development
CLR-5 :	Calculate Machining time for different process		Analysis, Design, Research
CLR-6 :	Impart clear knowledge about process planning, costing, and estimation of machining time		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Design and plan for various process and various manufacturing methodologies	1,2	90	85	H	L	H	M	H	-	-	-	-	-	-	M	H	L	H
CLO-2 :	Estimate various cost involved in a product	1,2	90	85	H	M	-	M	-	-	-	-	-	-	-	M	H	L	M
CLO-3 :	Estimate cost in different manufacturing shops	1,2	90	85	H	H	-	H	-	-	-	-	-	-	-	M	M	L	H
CLO-4 :	Estimate cost in different fabrication shops	1,2	90	85	H	H	-	H	-	-	-	-	-	-	-	M	M	L	H
CLO-5 :	Estimate machining time of various metal removal operations	1,2	90	85	H	H	-	H	-	-	-	-	-	-	-	M	M	L	H
CLO-6 :	Familiarize in process planning, costing and estimation of machining time	1,2	90	85	H	H	M	M	M	-	-	-	-	-	-	M	M	L	H

	Process Planning	Costing and Estimation	Estimation of costs in different shops	Estimation of costs in fabrication shops	Estimation of machining times and costs
Duration (hour)	8	9	9	9	10
S-1	SLO-1	Production system and Types of production	Objectives of costing and estimation	Estimation in foundry shop	Welding, Types of weld joints, Gas welding
S-2	SLO-1	Standardization and Simplification	costing and estimation: Functions and procedure	Pattern cost, Casting cost	Machine shop operations, Estimation of Machining time
S-3	SLO-1	Production design and selection	Introduction to costs, Computing material cost	Cost estimation in Foundry shop: Tutorials-1	Estimation of machining time for turning, knurling and facing operations : Tutorials
S-4	SLO-1	Process planning, Selection and analysis	Direct labor cost, Analysis of overhead costs	Cost estimation in Foundry shop: Tutorials-2	Estimation of machining time for reaming, threading and tapping operations : Tutorials
S-5	SLO-1	Manual/Experience based planning, Variant type CAPP	Expenses: Factory expenses	Forging: Types, Operations	Cost estimation in Welding shop: Tutorials-1
S-6	SLO-1	Generative type CAPP	Administrative expenses, Selling and distributing expenses	Estimation of Losses and time in forging	Cost estimation in Welding shop: Tutorials-2
S-7	SLO-1	Economics of process planning, case studies	Cost ladder ,Cost of product	Estimation in sheet metal shop	Estimation of machining time for boring : Tutorials
S-8	SLO-1	Processes analysis, Break even analysis	Depreciation, Analysis of depreciation	Estimation of Forging cost	Estimation of machining time for shaping Tutorials
S-9	SLO-1	Problems in depreciation method	Cost estimation in Forging shop: Tutorials - 1	Shearing and forming	Estimation of machining time for planning Tutorials
S-10	SLO-1		Cost estimation in Forging shop: Tutorials - 2	Cost estimation in Sheet metal shop: Tutorials - 1	Estimation of machining time for grinding operations : Tutorials
				Cost estimation in Sheet metal shop: Tutorials - 2	Case studies: Estimation of cost for a product

Learning Resources	<p>1. Banga.T.R and Sharma.S.C, "Mechanical Estimating and Costing", Khanna publishers, New Delhi, 17th Edition, 2015.</p> <p>2. Adithan.M.S and Pabla, "Estimating and Costing", Konark Publishers Pvt., Ltd, 2013.</p> <p>3. Nanua Singh, "System Approach to Computer Integrated Design and Manufacturing", John Wiley & Sons, New York, 2011.</p> <p>4. Joseph G. Monks, "Operations Management, Theory and Problems", McGraw Hill Book Company, New Delhi, 2008.</p>	<p>5. Narang.G.B.S and Kumar.V, "Production and Planning", Khanna Publishers, New Delhi, 2014.</p> <p>6. Chitale.A.K and Gupta.R.C, "Product Design and manufacturing", Prentice Hall of India, New Delhi, 2014.</p> <p>7. Peter Scalon, Process planning, Design/Manufacture Interface, Elsevier Sci. & Tech. 2002.</p>
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Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers

Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	Mr. I. Aatthisugan, SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Mr.M.Dhanasekaran, SRMIST

Course Code	18MEE324T	Course Name	FOUNDRY ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the basics of foundry, castings, limitations, patterns, materials, allowances	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Learn design, types of mold, materials, equipment's, sand mold, core, runner, raiser air vents, gatings, methods of solidification.		
CLR-3 :	Be familiar with the casting process, permanent mold, gravity, pressure die casting, centrifugal casting, precision, shell molding.		
CLR-4 :	Melting, pouring, qualities issues, types of furnaces, remelting, molten metal treatment, pouring temperature, casting inspection, rectification, cause and remedies for casting defects, destructive testing, NDT, dye penetrant, magnetic particle, X-ray, elimination of dissolved gasses, use of statistical quality control in foundry.		
CLR-5 :	Understand the Need and area for automation material handling, of raw, molten metal, storage and dispatch, overhead crane, trolley, pollution control, computers in castings and foundry.		
CLR-6 :	Understand about castings, patterns, molds, quality control, modernization in foundry		

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level	Expected	Expected	Engin	Probl	Design	Anal	Model	Societ	Envir	Ethics	Individ	Comm	Proje	Life L	PSO	PSO	PSO
CLO-1 :	Understand the process in foundry, patterns, allowances	1&2	90	85	H	L	M	M	H	L			L	M		M	H	H	M
CLO-2 :	Learn the mold types, core making, methods of solidification	1&2	90	85	H	H	M	M	H					M		M	H	H	M
CLO-3 :	Study the various casting process	1	90	85	H	L	L	M	H					M		M	H	H	M
CLO-4 :	Gain knowledge about furnaces, and quality control in castings.	1&2	90	85	H	L	L	M	H							M	H	H	M
CLO-5 :	Understand the automation in foundry, for handling raw, molten metal finished products,	1&2	90	85	H	L	M	M	H	M	M					M	H	H	M
CLO-6 :	Learn the foundry techniques in broader sense and able to implement.	1&2	90	85	H	L	M	M	H	M						M	H	H	M

	Foundry, patterns, materials, allowances.	Mold types, core making, runner and raisers,	– Different casting types, second operations, rework	Melting of metal and testing of casting and quality control	Modernization economic way of producing castings
Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to foundry technology, ,	Types of mold	Types of casting process	Types of furnace
S-2	SLO-1	Over view of Casting, patterns	Mold equipment's	Permanent molds, gravity casting	Selection of furnace
S-3	SLO-1	Patterns materials,	Mold and core preparation	Co2 process	Melting and remelting
S-4	SLO-1	allowances	Gatings	Image sharpening, Butterworth filters	Inspection of castings
S-5	SLO-1	Castings limitations	Runner and raiser	Generation of spatial masks from frequency domain specification,	Defects analysis and remedies, molten metal purification.
S-6	SLO-1	Types of patterns	Air vents and its importance	Basic steps in frequency domain filtering	Destructive testing, nondestructive testings. Magnetic particle testings, ultrasonic cell
S-7	SLO-1	Advantages of castings	Solidification, types of solidification	Nonlinear filters, function, Max filter, Min filter	Quality control of castings, techniques.
S-8	SLO-1	Limitations of castings	Defects related to solidifications	Homomorphic filtering, False color, Pseudo color and its approaches and	Application of statistical quality control methods
S-9	SLO-1	Assignment on casting, patterns and allowances	Assignment on molds, runner, riser, solidification	Assignments on image filtering in MATLAB/Open CV/Python	Assignment in furnace, casting defects Quality control
					Assignment on automation, Materials handling, Materials handling equipments,

Course Code	18MEE325T	Course Name	THEORY OF METAL FORMING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Impart knowledge about various metal forming process	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the stress criterion for plastic deformation	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Attain the ability to identify the process parameters responsible for metal forming	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Provide good exposure towards recent trends in metal forming process	Expected Attainment (%)	Design & Development
CLR-5 :	Understand the defects and overcome with remedies		Analysis, Design, Research
CLR-6 :	Be familiar with the basic science of metal forming, plastic deformation of bulk and sheet metals, in addition to acquire knowledge about the modern processes such as high velocity & super plastic forming.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Apply & analyze the theories involved in plastic behavior of metals	1&2 90 85	H M L L
CLO-2 :	Estimate the metal working process under various conditions	1,2&3 90 85	H M L L
CLO-3 :	Appreciate the types of plastic forming and equipment's used.	1&2 90 85	H M L L
CLO-4 :	Utilize the various processes of sheet metal forming.	1&2 90 85	H M L L
CLO-5 :	Appreciate the importance of modern metal forming processes.	1&2 90 85	H M L L
CLO-6 :	Apply the theories of plasticity and inspecting methods in various metal forming processes and produce engineering components	1,2&3 90 85	H M L L

Duration (hour)	9	9	9	9	9
S-1 SLO-1	Theory of plasticity: State of stress	Mechanics of metal working -Flow stress determination	Classification of rolling process, Types of rolling mills, Hot and cold rolling	Introduction to Sheet metal forming processes	Comparison with conventional forming methods
S-2 SLO-1	Components of Stress- Stress tensor	Effect of temperature in metal working	Forces and geometric relationship in rolling	Rod and wire drawing equipment	High Energy Rate Forming, fine blanking
S-3 SLO-1	Engineering stress strain relationship	Strain rate effects	Rolling of bars and shapes, Rolling defects, causes and remedies	Shearing, blanking, bending, stretch forming,	P/M forging-Isothermal forging
S-4 SLO-1	Flow curve and flow rules	Hot, cold and warm working	Classification of Forging process, Forging Equipment, Open and closed die forging	Explosive and press brake forming	Electrohydraulic forming
S-5 SLO-1	True stress and true strain	Metallurgical structure, Anisotropy	Forging defects, residual stresses	Deep drawing & tube drawing	Magnetic pulse forming
S-6 SLO-1	Yield criteria	Effects of hardening ,friction and lubrication	Classification of extrusion process, Variables affecting extrusion	Principles and process parameters	Rubber pad forming
S-7 SLO-1	Slip line field theory	Hydrostatic pressure	Hydrostatic extrusion, Production of seamless pipe and tubing	Sheet metal formability	Superplastic forming
S-8 SLO-1	Plastic work, Plastic anisotropy	Workability, Spring back	Deformation, lubrication and defects in extrusion	Formability limit diagram	Types of Severe plastic forming: ECAP
S-9 SLO-1	Plastic deformation of crystals	Residual stresses, Deformation processing system	Basics of Severe plastic deformation and its approaches	Defects in formed parts	Accumulative Roll Bonding

Learning Resources	1. George E Dieter, "Mechanical Metallurgy", Tata McGraw-Hill Education Pvt. Ltd, 2014. 2. Iuzalec, Andrzej, "Theory of Metal Forming Plasticity", Springer Berlin Heidelberg, 2010 3. A.Rosochowski, "Severe Plastic Deformation Technology", Whittles Publishing, 2017. 4. Z. R. Wang, Weilong Hu, S. J. Yuan, Xiaosong Wang, "Engineering Plasticity: Theory and Applications in Metal Forming", Wiley, 2018, ISBN: 978-1-119-23730-3 5. Serope Kalpakjian and Stevan R Schmid, "Manufacturing Process for Engineering Materials", Pearson Education, 2007	6. Surendar Kumar, "Technology of Metal Forming Processes", PHI Learning Pvt Ltd, 2008 7. William F Hasford, Robert M Caddell "Metal Forming: Mechanics and Metallurgy", Cambridge University Press, 2011 8. ASM "Metals Handbook, Volume 14, Forming and Forging", ASM Metals Park, Ohio, USA, 1998
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
R.GNANAKARAN AGM-Human Resources, Super Auto Forge Pvt.Ltd Kolapakkam.Mobile:98849 06001, Email: gnanakaran@superautoforge.net Tel:044 40753611	Dr. Uday Chakkingal, IITM	Mr.S.Sasikumar , SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.V..S. Sethilkumar,CEG,Anna University	Dr.U. Mohammed Iqbal , SRMIST

Course Code	18MEE326T	Course Name	WELDING TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Be familiar with the welding power sources and welding fundamentals
CLR-2 :	Be familiar with the fusion welding processes
CLR-3 :	Be familiar with the solid-state welding processes
CLR-4 :	attain the knowledge about welding metallurgy
CLR-5 :	attain the knowledge about brazing and soldering technology
CLR-6 :	Understand the concept of weldability, weld quality, welding defects and welding inspection

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Understand the fundamentals of welding processes and to recognize the importance of arc physics , weld protection
CLO-2 :	Understand the fusion welding processes and to recognize the various types of fusion techniques and be able to apply those techniques for any work
CLO-3 :	Understand the solid-state welding processes and to recognize the various types of solid-state techniques and be able to apply those techniques for any work
CLO-4 :	Obtained the knowledge about welding metallurgy and be able to apply the principle of metallurgy to recognize weld joint microstructure
CLO-5 :	Understand the concept of brazing and soldering techniques and able to apply the concept to critical welding aspects
CLO-6 :	Understand the concept of weldability, weld quality, and welding defects, acquire the knowledge of welding inspection and testing and be able to apply the concept to identify any weld defects

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
1 & 2	90	85	H	M	L	M	-	-	M	M	-	-	-	-	H	L	M
1, 2 & 3	90	85	H	M	M	H	M	-	H	M	-	-	-	-	H	M	H
1, 2 & 3	90	85	H	M	M	H	M	-	H	M	-	-	-	-	H	H	H
1, 2 & 3	90	85	H	H	-	H	-	-	H	M	-	-	-	-	H	M	M
1 & 2	90	85	H	L	L	L	-	-	M	M	-	-	-	-	H	L	M
1, 2 & 3	90	85	H	H	M	H	L	-	M	M	-	-	-	-	H	M	H

		Welding Fundamentals & Basic Fusion Welding Processes	Advanced Fusion Welding Processes	Solid-State Welding Processes	Welding Metallurgy	Weld Quality & Inspection
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Manufacturing and Joining, Welding, Need for welding, Applications, Advantages and Disadvantages	Fundamentals of gas metal arc welding, process variables, effect of filler metals on weld	Fundamental aspects of solid state processes, common process variables, bonding mechanism	Basic solidification concepts, solidification modes and constitutional supercooling, dendrite and cell spacing	Design of weldments, Concept of weldability
S-2	SLO-1	Fundamental Mechanisms of welding, Classifications of welding process	Fundamentals of gas tungsten arc welding, process variables, flux	Fundamentals of forge welding, characteristics, application	Epitaxial and nonepitaxial growth, effect of welding parameters, weld metal nucleation mechanisms	Weldability of ferrous and nonferrous alloys, Weldability test method
S-3	SLO-1	Heat Input and Power density of different welding processes, Cooling rate effect	Pulsed TIG Welding process, process variables	Fundamentals of roll bonding, characteristics, application	Dissimilar welds: issues and solutions	Fundamental concepts of residual stress and distortion,
S-4	SLO-1	Weld protection, Shielding gas, Flux, Types of flux coatings	Cold metal transfer welding process , Process Variables	Fundamentals of ultrasonic welding, characteristics, application	Weld Thermal Cycle	Welding defects, classification and characteristics

S-5	SLO-1	Principle of Fusion welding process, Gas welding process, Types of flames in gas welding process	Fundamentals of flux cored arc welding, process variables, electrode classification	Fundamentals of friction welding, characteristics, application	Heat affected zone thermal cycle	Solidification crack, Hydrogen induced crack
S-6	SLO-1	Shielded Metal arc welding process, welding variables, electrode classification, Physics of welding arc, polarity	Fundamentals of submerged arc welding, process variables, flux	Fundamentals of friction stir welding, process variables, application	Post weld heat treatment of weldments: Need and selection of PWHT parameters	Destructive testing of welded joints, tensile and hardness
S-7	SLO-1	Volt - Ampere Characteristics: Constant current, constant voltage and alternating current	Fundamentals of plasma arc welding, process variables, Hybrid Plasma TIG process.	Friction stir welding tools, effect of tool geometry	Formation of heat affected zone, recrystallization and grain growth	Destructive testing of welded joints, toughness, fatigue and creep
S-8	SLO-1	Arc characteristics: Arc plasma, effect of temperature, Arc distribution, Arc blow	Fundamentals of resistance welding, process variables, types	Fundamentals of explosive welding, characteristics, application	Fundamental concepts of brazing, characteristics, applications	Concept of non-destructive testing, classification
S-9	SLO-1	Fundamentals of weld bead geometry, Types of welded joints, Welding positions and welding processes	Fundamentals of laser beam welding, process variables, Hybrid laser welding process	Fundamentals of diffusion bonding process, process variables, applications	Fundamental concepts of soldering, characteristics, applications	Concept of Radiography, dye penetration and Ultrasonic test

Learning Resources	<ol style="list-style-type: none"> 1. John C. Lippold, <i>Welding Metallurgy and Weldability</i>, John Wiley & Sons, Inc., publication, 2015. 2. A.C. Davies, <i>The science and practice of welding</i>, Vol. 1 and 2, Tenth Edition, Cambridge University Press, 2010. 3. <i>Welding Handbook – 9th Edition</i>, Volume 1 to volume 5, American Welding Society, 2007. 4. Sindo Kou, <i>Welding Metallurgy</i>, 2nd edition, John Wiley & Sons, Inc., publication, 2003. 	<ol style="list-style-type: none"> 5. Robert W. Messler, Jr., <i>Principles of Welding-Processes, Physics, Chemistry, and Metallurgy</i>, John Wiley & Sons, Inc., publication, 1999. 6. R S Parmar, <i>Welding Engineering and Technology</i>, Khanna Publisher, 2008 7. O. P. Khanna, <i>Welding Technology</i>, Dhanpat Rai Publications; 2013 edition (2011) 8. Richard L. Little, <i>Welding and Welding Technology</i>, McGraw Hill Education (1 July 2017)
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Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. B. Arivazhagan Scientific Officer- E, Materials Technology Division, Metallurgy and Materials Group, IGCAR, Kalpakkam 603 102	Dr. P. Sathiyar, Professor, Department of Production Engineering, NIT Trichy	Dr. Madhavan S, SRMIST
Dr. Manidipto Mukherjee, Sr. Scientist Advanced Manufacturing Centre, Design and Manufacturing Research Group, CSIR-Central Mechanical Engineering Research Institute, Mahatma Gandhi Rd., City Centre, Durgapur 713209, West Bengal, India	Dr.S.Aravindan, Professor, Department of Mechanical Engineering, IIT Delhi	Dr. Shashi Kumar, SRMIST

Course Code	18MEE327T	Course Name	MECHANICAL HANDLING SYSTEMS AND EQUIPMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering			Data Book / Codes/Standards	PSG Tech "Design Data Book" Kalaikathir Achchagam Coimbatore

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Be familiar with Fundamentals of material handling and intraplant transporting facilities	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with Common material handling systems	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Be familiar with automated feeding mechanism and design				H	M	L	L	L							M	H	H	M
CLR-4 :	Be familiar with Unit Built Machines (UBM), Automated systems in transfer lines				H	M	M	M	H							M	H	L	M
CLR-5 :	Be familiar with Transfer mechanisms, conveyors, part feeding devices				H	L	M	M	H							M	H	L	M
CLR-6 :	Be familiar with material handling equipments, and their automated systems				H	L	M	M	H							M	H	L	H
CLO-1 :	Understand about Fundamentals of material handling and intraplant transporting facilities	1	90	85	H	M	L	L	L							M	H	H	M
CLO-2 :	Acquire knowledge on Common material handling systems	1&2	90	85	H	M	M	M	H							M	H	L	M
CLO-3 :	Acquire knowledge on automated feeding mechanism and design	1&2	90	85	H	L	M	M	H							M	H	L	M
CLO-4 :	Understand the Automated systems in transfer lines	1&2	90	85	H	L	M	M	H							M	H	H	M
CLO-5 :	Understand Transfer mechanisms, conveyors, part feeding devices	1	90	85	H	L	M	M	H							M	H	L	H
CLO-6 :	Understand material handling equipments, and their automated systems	1&2&3	90	85	H	L	M	M	H							M	H	H	H

Duration (hour)		Introduction	Common Material Handling Equipment	Automation of Material Handling	Classification of Automated System	Automated Material Handling Equipment
		9	9	9	9	9
S-1	SLO-1	Introduction to work handling concepts - types of intraplant transporting facility	Concepts of Unit Loads, Material handling and Storage	Automated feeding arrangements for discrete parts	Concepts of Unit Built Machines (UBM)	Automated handling and storage systems in manufacturing environment
S-2	SLO-1	Principles of material handling-manual and mechanical handling	Equipments operation and selection	Design based in work piece requirements, orienting methods	Gain lean and green endorsement, collaboration to achieve lean and green goals	Rail Guided Vehicles (rgvs), Automated Guided Vehicles (agvs)
S-3	SLO-1	Principle groups of material handling	Containers, Pallets, Conveyor systems, Industrial trucks, Wagon tippers	One by one feeding, agonizing, stapling etc	Classification and elements, Power Units, self-contained and separate feed type, Change over UBM	Applications of rgvs and agvs, Automated Storage and Retrieval Systems (AS / RS)
S-4	SLO-1	Choice of material handling equipment, hoisting equipment	Transporters, stackers, reclaimers	Feeding continuous material liquids, granules etc	Transfer lines – classification and their components	AS / RS in the Automated factory
S-5	SLO-1	Surface and overhead equipment-General characteristics of overhead equipments and their application	Silos & hoppers and their accessories, Ropeways, Ship loaders, Cable cranes	Automated assembly system, elements,	Automated systems for handling and transfer of prismatic, axis symmetric parts and asymmetric parts in transfer lines	Considerations for planning an AS /RS system, Applications of AS / RS
S-6	SLO-1	Introduction to control of hoisting equipments	Container handling systems, Electric lifts	Automated assembly system ,configuration design, details and control	Case studies on transfer lines – interlocked	Principles of work holding devices – Modular fixturing
S-7	SLO-1	Storage – open and closed storage systems	Hoists, EOT cranes, Elevators	Special feeding mechanisms	Case studies on palletized and flexible inter linkage transfer lines	Flexible fixturing systems
S-8	SLO-1	Bulk loading, Unloading, Shipping	Material handling equipments in Steel	Automated inspection and their design	Control systems for flexible inter linkage	Fixturing for FMS

			mills, Power plants, Mines, Automobile and Transport Industries		transfer lines	
S-9	SLO-1	Receiving systems and operations-First in first out(FIFO),last in first out(LIFO)	Large scale Constructions etc. Case Study for All Above Mentioned Handling systems.	Case study for automated material handling.	SWARF handling and disposal systems	Robots and their applications in handling and storage

Learning Resources	1. Groover. M. P., "Automation, Production Systems and CIM", Prentice hall India, 2007. 2. Morris A. Cohen, Uday M. Apte., "Manufacturing Automation", Irwin, Chicago, 3. James A. Tompkins., "Facilities planning", John wiley& Sons Inc, 1984.	4. James. M. Apple, "Principles of layout and material handling", Ronald press, 1977 5. N.Rudenko" Materials Handling equipment" Envee publisher, New Delhi
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	1. Mr. C. Balasuthagar, SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Dr. M. Iqbal, SRMIST

Course Code	18MEE328T	Course Name	NON-TRADITIONAL MACHINING TECHNIQUES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Be familiar with the concept of Non-traditional machining techniques and their need and advantages over traditional machining techniques		1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Be familiar with the classification of Non-traditional machining techniques		Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Be familiar with the Mechanical energy based Non-traditional machining techniques																			
CLR-4 :	Be familiar with the Electro-chemical energy based Non-traditional machining techniques																			
CLR-5 :	Be familiar with the Thermal energy based Non-traditional machining techniques																			
CLR-6 :	Be familiar with the latest developments in various Non-traditional machining techniques																			
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																		
CLO-1 :	Differentiate between Traditional and Non-traditional machining techniques.		1, 2	90	85	H	-	-	-	-	-	M	-	-	-	-	-	-	-	M
CLO-2 :	Acquire knowledge on basic components and working principles of different Non-traditional machining techniques.		1	90	85	H	-	-	-	-	-	-	-	-	-	-	-	H	-	-
CLO-3 :	Understand the major process parameters like operating voltage, current, time on, time off etc.		1	90	85	H	-	-	-	M	-	-	-	-	-	-	-	H	-	-
CLO-4 :	Evaluate the effect of various process parameters on machining characteristics like surface roughness, surface integrity, etc.		1, 2, 3	90	85	H	-	-	-	L	-	-	-	-	-	-	-	H	-	-
CLO-5 :	Learn the processes of machining hard to cut and high strength materials and alloys.		1, 2	90	85	H	-	-	-	L	-	M	-	-	-	-	-	H	-	-
CLO-6 :	Understand the recent developments and applications in Non-traditional machining techniques.		1, 3	90	85	H	-	-	-	-	-	-	-	-	-	-	-	H	-	M

		Basics of Non-Traditional Machining and Mechanical Energy Techniques-I	Mechanical Energy Techniques-II	Chemical and Electro Chemical Techniques	Thermo Electrical Energy Techniques	Thermal Energy Techniques
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction of non-traditional machining	Operating principles and equipment of water jet machining	Fundamentals, operating principle, advantages, limitations, applications of chemical machining process.	Operating principles and equipment of electrical discharge machining	Operating principle and equipment of electron beam machining
	SLO-2	Difference between traditional and non-traditional machining	Process parameters, applications, advantages and limitations of water jet machining	Classification and selection of Etchant and maskant	Subsystems of electrical discharge machining	Generation and control of electron beam
S-2	SLO-1	Need for non-traditional machining	Operating principles and equipment of abrasive water jet machining	Operating principles, equipment and subsystems of electrochemical machining	Power circuits and electrode feed mechanism in electrical discharge machining	Parameters influencing metal removal in electron beam machining
	SLO-2	Machining characteristics and classification of non-traditional machining	Mechanism of metal removal in abrasive water jet machining	Material removal rate and tool design in electrochemical machining	Process parameters, selection of tool electrode in electrical discharge machining	applications, advantages and limitations of electron beam machining
S-3	SLO-1	Consideration in process and material selection.	Parameters influencing metal removal rate	Tool Material, Tool Feed System, Design For Electrolyte Flow	Dielectric fluids and flushing methods in electrical discharge machining	Operating principle and equipment of plasma arc machining

	SLO-2	Applications of non-traditional machining	Applications, advantages and limitations of abrasive water jet machining	Process parameters in electrochemical machining	Characteristics of spark eroded surface	Gas mixture, Types of Torches of plasma arc machining
S-4	SLO-1	Operating principle, elements and equipment of Ultrasonic machining	Operating principle and equipment of abrasive flow machining	Problems for estimation of material removal rate in electrochemical machining	Recast layer formation	Parameters influencing metal removal in plasma arc welding
	SLO-2	Tool feed Mechanism	Mechanism of metal removal in abrasive flow machining	Advantages, limitations, applications and recent development of electrochemical machining	Surface finish and machining accuracy in electrical discharge machining	Applications, advantages and limitations of plasma arc machining
S-5	SLO-1	Cook's model for material removal	Process parameters in abrasive flow machining	Operating principle and equipment of electro chemical grinding	Tool Electrode design, Tool wear characteristics of spark eroded surfaces	Operating principle and equipment of laser beam machining
	SLO-2	Problems in estimation of Material removal rate (MRR) for Ultrasonic machining	Classification of abrasive flow machining, Applications, advantages and limitations of abrasive flow machining	Metal removal rate and process parameters in electro chemical grinding	Problems in estimation of material removal rate in electrical discharge machining	Process Characteristics and Thermal Features of laser beam machining
S-6	SLO-1	Process parameters of Ultrasonic machining	Operating Principle of magnetic abrasive machining	Problems for estimation of metal removal rate in electro chemical grinding	Operating principle of wire cut electrical discharge machining	Types of lasers used in laser beam machining
	SLO-2	Applications, Advantages and limitations of Ultrasonic machining	Elements and equipment of magnetic abrasive machining	Process Characteristics of electro chemical grinding	Equipment of wire cut electrical discharge machining	Parameters influencing metal removal, applications, advantages and limitations of laser beam machining
S-7	SLO-1	Operating Principle of Abrasive jet machining	Mechanism of metal removal in magnetic abrasive machining	Benefits, limitations and applications of electro chemical grinding	Process parameters of wire cut electrical discharge machining	Operating principle and equipment of Ion beam machining
	SLO-2	Elements and equipment of Abrasive jet machining	Process parameters of magnetic abrasive machining	Recent developments in electro chemical grinding process	Advantages, limitations and applications of wire cut electrical discharge machining	Process Characteristics of Ion beam machining
S-8	SLO-1	Mechanism of metal removal in Abrasive jet machining	Applications, advantages and limitations of magnetic abrasive machining	Electrochemical Drilling	Operating principles and equipment in electrical discharge grinding	Material removal rate, Accuracy and surface effects in Ion beam machining
	SLO-2	Process parameters of Abrasive jet machining	Process capabilities of magnetic abrasive machining	Electro Stream (Capillary) and Electrochemical jet drilling.	Process parameters, surface finish and machining accuracy in electrical discharge grinding	Parameters influencing metal removal rate
S-9	SLO-1	Process capabilities of Abrasive jet machining	Operating Principle of Ice jet machining	Fundamentals of electro chemical honing	Machine tool selection	Applications, advantages and limitations of Ion beam machining
	SLO-2	Applications, Advantages and limitations of Abrasive jet machining	Process description of Ice jet machining	Fundamentals of deburring process	Application and recent developments in electrical discharge grinding	Recent developments and trends in Thermal energy based non-traditional machining techniques

Learning Resources	<ol style="list-style-type: none"> 1. P. C. Pandey and H.S. Shan, "Modern Machining Processes", McGraw Hill, 2017. 2. Vijay K. Jain, "Advanced Machining Processes". Allied Publishers, 2007. 3. P K Mishra, "Nonconventional Machining", Narosa Publishing House, 2007. 4. G. F. Benedict, "Non-Traditional Manufacturing Processes", CRC Press, New York, 1987. 5. Sahu R.K. and Somashekhar S.H, "Corona Discharge Micromachining for the Synthesis of Nanoparticles: Characterization and Applications", CRC Press, Taylor & Francis, New York, 2019. 	<ol style="list-style-type: none"> 6. Amithaba Bhattacharya, 'New Technology', Tata McGraw Hill, 2006. 7. Hassan El-Hofy, 'Advanced Machining Processes', McGraw Hill, 2005. 8. Wellar P C, 'Non-Traditional Machining Processes', SME Michigan, 1984. 9. Carl Sommer, 'Non Traditional Machining Handbook', Advanced Pub, 2000.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.K.Balasubramanian, AGM, Lucas TVS Ltd., Puducherry	1. Dr.V.Satheesh Kumar, Assistant Professor, Production Engg., NIT Trichy	1. Mr.V.Veeranaath, SRMIST
2. Mr.Durga PrasadPadhy, Manager, Vendata Resources Ltd., Jharsuguda, Orissa		2. Dr.Ranjeet Kumar Sahu, SRMIST

Course Code	18MEE329T	Course Name	MODERN MANUFACTURING TECHNIQUES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with the modern casting methods	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Know the modern methods of manufacturing from powders	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Be familiar with the micro-electronic manufacturing	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Acquire knowledge about polymers and composites manufacturing	Expected Attainment (%)	Design & Development
CLR-5 :	Learn the methods of rapid prototyping and additive manufacturing		Analysis, Design, Research
CLR-6 :	Be acquainted with manufacturing approaches of modern intricate products		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Acquire knowledge of modern and non-conventional casting methods for manufacturing complex intricate shapes of metals	1 & 2 90 85	H
CLO-2 :	Understand the manufacturing methods using powders of metals and ceramics	1 & 2 90 85	H
CLO-3 :	Get acquaintance with manufacturing methods of semiconductors and microelectronic devices	1, 2, 3 90 85	H
CLO-4 :	Obtain knowledge of polymers and composites manufacturing methods	1 & 2 90 85	H
CLO-5 :	Understand the purpose and methods of rapid prototyping and additive manufacturing	1 & 2 90 85	H
CLO-6 :	Identify suitable methods for various product manufacturing	1, 2, 3 90 85	H

	Modern Casting Methods	Modern Forming Methods	Manufacturing Of Semiconductors And Electronic Devices	Manufacturing Of Composite Materials	Rapid Prototyping And Additive Manufacturing
Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to conventional and modern casting methods	High speed metal forming- Explosive, Electromagnetic and electrohydraulic	Semiconductors and silicon-Introduction, Structure of silicon, Properties	Selection of composite matrices and reinforcements
S-2	SLO-1	Expendable pattern casting - Pattern making process, Advantages, Applications	Semisolid metal forming Types (Thixocasting, Rheocasting, Thixomolding) Advantages, Applications	Crystal growing and wafer preparation	Overview of polymer matrix composites, Types of reinforcements, Preforms, Prepregs
S-3	SLO-1	Plaster mold casting – Conventional and Antioch Process, Advantages, Applications	Peen forming of sheet metals - Process, Advantages, Applications	Film deposition -Evaporation, Sputtering, CVD	Open mould processes - Hand lay-up, Spray-up, Vacuum Bagging, Automated tape -laying machines
S-4	SLO-1	Ceramic mold casting - Process, Advantages, Applications	Super plastic forming - Material requirements, Advantages, Disadvantages	Oxidation - Dry oxidation, Wet oxidation	Closed mould processes - Compression moulding, Transfer moulding, Injection moulding
S-5	SLO-1	Vacuum casting - Process, Advantages, Applications	Design consideration for Powder Metallurgy forming	Lithography - Photolithography process	Filament winding, Pultrusion, Pulforming, Cutting of FRP

S-6	SLO-1	Squeeze casting - Process, Advantages, Applications	Production of metal powders Atomization, Reduction, Electrolytic Deposition, Carbonyls, Comminution, Mechanical Alloying	Etching - Wet chemical etching, Dry plasma etching, Cryogenic dry etching	Fabrication of metal matrix composites- Liquid state and Solid state	Selective laser sintering
S-7	SLO-1	Rapid solidification for amorphous alloys, Melt Spinning Process	Sintering, Finishing of sintered parts, Secondary and finishing operations	Diffusion, Drive-in Diffusion and Ion implantation	Deposition technique for MMC, Insitu composites	Fused deposition modeling
S-8	SLO-1	Casting techniques for single crystal components	Ceramic forming -casting, powder	Metallization - Requirement, Methods and testing	Conventional manufacturing of ceramic composites, Prepeg formation-slurry impregnation	Solid ground curing, 3D ink jet printing
S-9	SLO-1	Conventional casting of Turbine blades, Directional solidified blades, Single crystal blades	Forming and shaping glass-Flat Sheet, Rods and Tubes, Discrete Products, Glass Fiber	Bonding and packaging, MEMS, NEMS	Porous preform infiltration- Melt, Sol-gel, Polymer, Reactive liquid, Chemical vapour, Directed oxidation	Additive manufacturing-Applications

Learning Resources	<ol style="list-style-type: none"> 1. Serope Kalpakjian, "Manufacturing Engineering and Technology", Fourth Edition, Addison-Wesley Publishing Co., Boston, 2014. 2. Mikell P. Groover, "Principles of Modern Manufacturing SI Version", Wiley India, 2018. 3. Parasuraman Swaminathan, "Semiconductor Materials, Devices and Fabrication", Wiley India, 2017. 4. Madou.M.J, "Fundamentals of micro fabrication: The Science of Miniaturization, Second Edition", CRC Press, USA, 2002. 	<ol style="list-style-type: none"> 5. C. S. Lim, K. F. Leong, C. K. Chua, "Rapid Prototyping: Principles and Applications" (3rd Edition), World Scientific Publishing Company, 2009. 6. P. D. Hilton, P.F. Jacobs, "Rapid Tooling: Technologies and Industrial Applications", 1st Ed., Marcel Dekker, Inc., 2010. 7. Steinar Westhrin Killi, "Additive Manufacturing: Design, Methods, and Processes", Pan Stanford Pub., 2017. 8. T. DebRoy et al., Review Article – "Additive manufacturing of metallic components – Process, structure and properties", Progress in Materials Science, Volume 92 (2018), 112-224.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Saurabh Kundu Head Product Research Tata Steel Jamshedpur Email: saurabhkundu@tatasteel.com	Dr. Debdulal Das, Associate Professor Dept of Metallurgy and Materials Engineering Indian Institute of Engineering Science and Technology, Shibpur Howrah, Email: debdulal_das@metal.iests.ac.in	1. Dr.Shubhabrata Datta
Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Dr. M. Iqbal, SRMIST

S-8	SLO-1	Simple problems in selection of plant location.	Introduction to FMS, components of FMS.	Benefits and limitations for FMS system	Lean manufacturing with example	FMS development towards factories of the future
S-9	SLO-1	Design the different layouts like automobile plant and supermarket and hospitals and airport...etc	FMS need and types FMS systems.	Simple example of FMS planning for Automobile plant.	Agile manufacturing and example case study	Example case study for FMS

Learning Resources	1. William W. Luggen, "Flexible manufacturing Cells and systems", Prentice hall of New Jersey 1991. 2. Mikell P. Groover, "Automation Production systems and Computer Integrated manufacturing", prentice hall of India, New Delhi, 2007.	3. Jha N.K, "Hand book of Flexible Manufacturing systems", Academic Press, 1991. 4. David J. Parrish, "Flexible Manufacturing", Butterworth-Heinemann, Newton, MA, USA, 1990.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Mariappan Kanagaraj (Manager - Part Quality Engineering (STA) at Renault Nissan Technology & Business Centre India Pvt Ltd, Chennai Area, India	1. Dr. B. K .Ragunath, Associate Professor, Dept. of Manufacturing Engineering, Annamalai University	1. Mr. Abburi Lakshman Kumar, AP Mech, SRMIST, Kattankulathur
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	2. Dr.G. Elatharasan, Asst.Professor, Dept. of Mechanical Engg., Anna University, Pattukottai.	Dr. M. Iqbal, SRMIST

Course Code	18MEE421T	Course Name	SUSTAINABLE GREEN MANUFACTURING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with objectives, concepts and role of Green Manufacturing	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the tools of Green Manufacturing	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Be familiar with the attribute's decision-making methods	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with creating Lean and Green organization	Expected Attainment (%)	Design & Development
CLR-5 :	Be familiar with the Design resources saving into product and processes		Analysis, Design, Research
CLR-6 :	Be familiar with the concepts, tools, attributes, design resources of green manufacturing		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand Green Manufacturing and Sustainable engineering concepts	90 85	M M M L H H M L
CLO-2 :	Develop Multi attributes decision making methods	90 85	M M M L H H M L
CLO-3 :	Develop Green manufacturing management	90 85	M M M L H H M L
CLO-4 :	Develop Applications in green manufacturing	90 85	M M M L H H M L
CLO-5 :	Develop design resources saving into product and process		M M M L H H M L
CLO-6 :	Understand about the green manufacturing concepts, management, applications and design development.		M M M L H H M L

Duration (hour)	8	9	9	9	10
S-1	SLO-1	Definition of manufacturing, Impact of manufacturing in environmental ecology	Principles of green manufacturing and its efficiency	Introduction to Multi attributes decision making methods	Question wasteful practices
S-2	SLO-1	Role of manufacturing sector in national growth	Green manufacturing and sustainability	definition, structure for Multi attributes decision making methods	Gain lean and green endorsement, collaboration to achieve lean and green goals
S-3	SLO-1	Technological change and evolving risk	System model architecture and module	variants and analysis of different methods like Simple Additive Method (SAM)	Track progress for environment and profits
S-4	SLO-1	concepts of "green" manufacturing need of green manufacturing	Design and planning, control or tools for green manufacturing (Qualitative Analysis)	Weighted Product Method (WPM)	Creation of sustainable growth
S-5	SLO-1	Green manufacturing strategies	Consumption Analysis, Life Cycle Analysis, Efficiency, Sustainability tools).	Analytic Hierarchy Process (AHP)	Enabling techniques for assuring green manufacturing
S-6	SLO-1	Green manufacturing – motivation, barriers, regulation, policy	Standards for green manufacturing (ISO 14000 and OHSAS 18000)	Technique for Order of Preference by Similarity to Ideal Solution (TOPSIS), Grey Relation Analysis (GRA)	Drivers of green manufacturing, impact, advantages and disadvantages of drivers
S-7	SLO-1	Casting defects and remedies.	Waste stream mapping and application	Elimination and Choice Expressing Reality (ELECTRE)	Green architecture and buildings, Sustainable manufacturing resources management
S-8	SLO-1	Advantages and limitations of green	Identify and apply the concepts of product	VIKOR method	Carbon footprint analysis and

		manufacturing	and process design with environmental forethought		management of manufacturing processes	lean manufacturing at industries
S-9	SLO-1	Significance of green manufacturing	Design for environment and for sustainability – Discuss the Product Life Cycle of manufactured goods.	Problems based on different MADMs. 1 C 3 3,4	Green Process Economics, Resource Recovery and Reuse	Various case studies of implementation of Optimizing process or product at industries

Learning Resources	<ol style="list-style-type: none"> 1. Ronald G. Askin & Jeffrey B. Goldberg, "Design and Analysis of Lean Production Systems", John Wiley & Sons, 2003. 2. Rao.P.N, "Manufacturing Technology, Vol I and II", Tata McGraw Hill Publishing Co., 3rd edition, Sixth Reprint 2010 3. Charles Wankel "21st century management: a reference handbook" SAGE Publications, Inc., 2008. 4. Christian N. Madu "Handbook of environmentally conscious manufacturing" London : Kluwer Academic Publishers, 2001. 5. T.E. Graedel & B.R. Allenby "Industrial Ecology" Pearson Education, Inc. 2003. 6. Joseph Sarkis "Greener manufacturing and operations: from design to delivery and back" Greenleaf Pub., 2001. 7. Ranky, P.G.: "An Introduction to Alternative Energy Sources: An interactive multimedia 3D eBook publication by CIMware USA, Inc. and CIMware Ltd., UK, ISBN 1-872631- 97-5, 2008. 8. Ranky, P.G.: "Digital Product Design: Design For Quality, Manufacturing, Assembly & Disassembly Principles, and an Inkjet Printer Disassembly Use Case", DVD video publication by CIMware USA, Inc. and CIMware Ltd., UK, 2008, UPC 632568002983
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. U. Natarajan, ACGCET-Karaikudi, u.natarajan@accetedu.in	E.Muthu, AP(OG), SRMIST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	2. Dr. D. Dinakaran, HITS Padur, dinakaran.d@hindustanuniv.ac.in	Dr.P. Nandakumar, SRMIST

Course Code	18MEE422T	Course Name	ADDITIVE MANUFACTURING TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with the evolution of Additive manufacturing (Why it is disruptive in nature based on evolution) and the materials and design involved	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the various process steps involved in Additive manufacturing (Generic process flow for AM systems)		
CLR-3 :	Learn the various types of machines and systems involved in Additive manufacturing		
CLR-4 :	Know the working of powder based Additive manufacturing processes and their applications and limitations		
CLR-5 :	Know the working of solid and liquid based Additive manufacturing processes and their applications and limitations (Understanding the feedstock material in various AM process)		
CLR-6 :	Be familiar with components of Additive manufacturing and its applications in industries (Understanding the requirement of process certification for various industrial applications) – Fabrication and repair applications		

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			Level of	Expected	Expected	Engineering	Problem	Design	Analysis	Modern	Society	Environment	Ethics	Individual	Communication	Project	Life Long	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand the basic concepts of Additive manufacturing (Why they are classed as disruptive technology(ies)				1&2	90	85	H														
CLO-2 :	The knowledge acquired on the process chain of Additive manufacturing and the various steps involved (Opportunities of implementation in India, global relevance of AM in supply chain – The concepts of Remanufacturing)				1&2	90	85	H		M		H						M	H	H		
CLO-3 :	Recognize the various machines and systems involved in Additive manufacturing and understand their role (in industrial application – fabrication or repair of component)				1	90	85	H	M	M	H	H						M	H	H		
CLO-4 :	Understand the major solid and liquid based Additive manufacturing processes such as stereolithography and fused deposition modeling and recognize their application and potential				1&2	90	85	H	M	M	H	H						M	H	H		
CLO-5 :	Understand the major powder based Additive manufacturing processes such as 3D printing (Directed Energy deposition, powder bed fusion)and electron beam melting, Binder jetting and recognize their application and potential in fabrication and repair for various industrial application				1&2	90	85	H	M	M	H	H						M	H	H		
CLO-6 :	Recognize the importance of Additive manufacturing and its various processes and systems – Industry specific (such as Aerospace, power generation, heavy machinery, Automotive)				1&2	90	85	H														

	Introduction To Additive Manufacturing	Process Chain Of Additive Manufacturing	Machines And Systems Of Additive Manufacturing	Solid And Liquid Based Additive Manufacturing	Powder Based Additive Manufacturing
Duration (hour)	9	9	9	9	9
S-1	SLO-1	Evolution of Additive manufacturing, Need, Comparison with CNC machining (Concepts of Hybrid manufacturing & applications)	Conceptualisation, Synergistic interaction of processes (AM + CNC/Adaptive)	Introduction to various machines and systems of Additive manufacturing (based on feedstock material, based on energy used, application)	Classification (scale of printing)
S-2	SLO-1	Basic principles of additive manufacturing (Complex interaction of process, design and materials)	CAD model preparation, CAM operations (Tool path generation)	Construction of CNC machines, Process chamber (Subtractive process conversion to AM process)	Guidelines for process selection
S-3	SLO-1	Classification of Additive manufacturing	Part orientation and support generation	Energy Delivery: Lasers and electron beam, Fused deposition modeling - Processes and	Powder fusion mechanisms: solid-state sintering, Chemically induced sintering
					Selective laser sintering: process,

		processes		plasma arc, kinetic energy (cold spray in AM)	principle	principles
S-4	SLO-1	Materials for Additive manufacturing (selection of feedstock materials)	Conversion to Stereolithographic file format	Material delivery: Powder feeding and wire feeding systems (difference in powder and wire feedstock – advantages and limitations for both), handling of feedstock material	Advantages, applications	Advantages, applications
S-5	SLO-1	Designing for Additive manufacturing (Design optimization)	Transfer to Additive manufacturing machine and file manipulation	Rapid tooling equipment: direct and indirect methods	Laminated object manufacturing	3D printing: process, principles
S-6	SLO-1	Role of Additive manufacturing in product development (Complex geometry requirements, strength to weight requirements)	Machine setup and build, Health & Safety practice (best practice), Feedstock material handling	Post processing equipment: support material removal, preparation for use as a pattern	Stereolithography apparatus: processes and principle	Advantages, applications
S-7	SLO-1	Advantages, Disadvantages, Applications and Opportunities of Additive manufacturing (Opportunities in Indian industries, global prospective)	Removal and clean up, Health & Safety practice (best practice),	Temperature, humidity, oxygen level controllers (process monitoring, affect on mechanical and microstructural properties with these variables)	Advantages, applications	Laser engineered net shaping (LENS process, unique advantages on hybrid scale), process control advantages, limitations,
S-8	SLO-1	Emerging trends and business models (Concepts of Remanufacturing)	Post processing (insitu or external transformative post processing such as heat treatments), machining	Scanning: Raster scan, patterned vector scanning	Challenges in solid and liquid AM processes	Electron beam melting
S-9	SLO-1	Related technologies: Reverse engineering, Computer aided engineering, AM process simulation concepts, predictive modelling	Property enhancement by thermal and non-thermal methods (In relation to type of material)	Post processing: surface texture, accuracy and aesthetic improvement	Case study (with relevance to technology certification)	Case study (with relevance to technology certification)

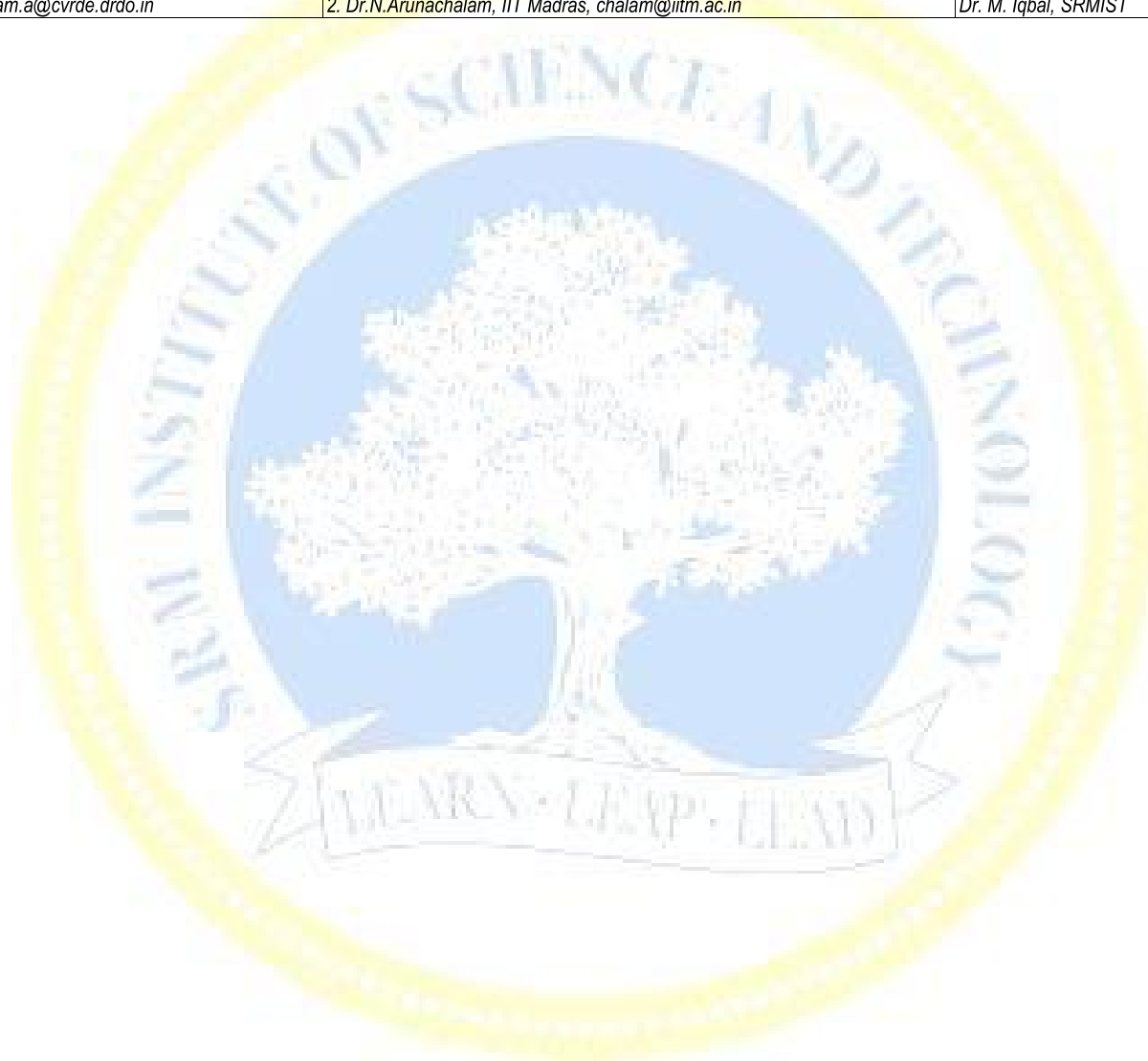
Learning Resources	<ol style="list-style-type: none"> 1. Ian Gibson, David W Rosen, Brent Stucker., "Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing", Springer, 2015. 2. Chua C.K., Leong K.F., and Lim C.S., "Rapid prototyping: Principles and applications", Third Edition, World Scientific Publishers, 2010. 3. Gebhardt A., "Rapid prototyping", Hanser Gardener Publications, 2003. 4. Liou L.W. and Liou F.W., "Rapid Prototyping and Engineering applications: A tool box for prototype development", CRC Press, 2007. 5. Kamrani A.K. and Nasr E.A., "Rapid Prototyping: Theory and practice", Springer, 2006. 	<ol style="list-style-type: none"> 6. Hilton P.D. and Jacobs P.F., "Rapid Tooling: Technologies and Industrial Applications", CRC press, 2000. 7. Pham D.T, Dimov S.S, "Rapid Manufacturing: The Technologies and Applications of Rapid Prototyping and Rapid Tooling", Springer 2001. 8. Gu D, "Laser Additive Manufacturing of High-Performance Materials", Springer, 2014. 9. Rafiq Noorani, "Rapid prototyping: Principles and Applications in Manufacturing" John Wiley & Sons, 2006.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers

Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Mr.Purushothaman, Tesscorn Nano Science Inc.	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	Dr. P. Mohan Babu, SRMIST
Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Dr. M. Iqbal, SRMIST



Course Code	18MEE423T	Course Name	PRECISION ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Understand the concept of accuracy and precision in various parametric testing
CLR-2 :	Realize the striving need for precision and applications
CLR-3 :	Know the causes for dimensional and geometrical characteristics errors prior and during machining
CLR-4 :	Impart knowledge about basics of precision and ultra precision machining methods
CLR-5 :	Be familiar with different precision measuring systems at micro/nano level
CLR-6 :	Be familiar with the various lithography techniques

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
1&3	80	85
1&2	70	85
1, 2&3	75	85
1,2&3	85	85
1&2	80	85
1&2	80	85

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Acquire knowledge about the basics of accuracy and alignment tests
CLO-2 :	Identify the dimensional and geometrical errors prior and during machining
CLO-3 :	Deepen the knowledge of static stiffness and thermal effects
CLO-4 :	Understand the principles of precision machining and importance of digitization in micro-machining
CLO-5 :	Understand the principles of nano measuring systems
CLO-6 :	Understand the principles of various lithographic techniques and currently emerging microscopic techniques

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H				M		M					H	M		H
H	L			M								M		M
H	L		M	M								H	M	
H	H	L	M	M		M		L			H	H		H
M			M	H		L		M			M			M
M	H	L	M	M		M		L			H	H		H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	General concept of accuracy, repeatability and precision; Spindle rotation accuracy	Static stiffness	Introduction to precision Engineering and need for having high precision	Introduction to nanotechnology and need for measurement in nanotechnology
S-2	SLO-1	Test methods for displacement accuracy	Nature of deformation in a machine tool	Precision machining and finishing operations	Measuring Systems for Nano-manufacturing
S-3	SLO-1	Dimensional wear of cutting tools	Overall stiffness of a lathe	Ultra-precision Processes	In - process measurement of position of processing point
S-4	SLO-1	Accuracy of NC systems, Clamping errors, Setting errors	Compliance of work piece	Tool Materials for Precision Machining: Carbides, Ceramic, Diamond, Cubic Boron Nitride	Post process and online measurement of dimensional features
S-5	SLO-1	Location of rectangular prism, cylinder	Errors due to the variation of the cutting force and total compliance	Ultra-Precision Machine Elements	Mechanical measuring systems
S-6	SLO-1	Basic type of tests, Measuring instruments used for testing machine tools	Case study: Errors caused by cutting force deformation in turning and milling	Machining of micro-sized components	Optical measuring systems
S-7	SLO-1	Alignment, Straightness, Flatness tests	Study of thermal effects on machine tool accuracy	Positioning mechanisms and drives – precision gears, servo control systems, electromagnetic and piezo actuators	Electron beam measuring systems
S-8	SLO-1	Parallelism, Squareness tests	Methods of decreasing thermal effects	Micro- electro-Mechanical Systems: Characteristics and Principles, Materials, and Fabrication processes	X-ray imaging systems
					Nano Lithography
					Photolithography
					Electron beam lithography
					Ion Beam lithography
					Optical lithography
					LIGA process
					Nanocoatings
					Micro-metrology

S-9	SLO-1	Circularity, Cylindricity tests	Influence of vibration and noise on accuracy	Emergence of digital precision machining	Pattern recognition and inspection systems	Microscopy techniques for materials characterization: Electron microprobe analysis and atom probe tomography
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Learning Resources	<ol style="list-style-type: none"> 1. Murthy.R.L, "Precision Engineering in Manufacturing", New Age International, New Delhi, 2005. 2. V.C.Venkatesh, Precision Engineering, Tata Mc.Graw Hill, New Delhi 2007 3. Kalpakjian S., Manufacturing Engineering and Technology. 3rd Ed. Addison-Wesley Publishing Co., New York, 2001. 4. Norio Taniguchi, "Nanotechnology", Oxford university press, Cambridge, 1996. 5. Lee Tong Hong, "Precision Motion control, Design and Implementation", Springer Verlag, U.K., 2001. 6. Liangchi Zhang, "Precision Machining of Advanced Materials", Trans Tech Publications Ltd., Switzerland, 2001. 7. Hiromu Nakazawa, "Principles of precision engineering", Oxford University Press, 1994. 8. Sahu R.K. and Somashekhar S.H, "Corona Discharge Micromachining for the Synthesis of Nanoparticles: Characterization and Applications", CRC Press, Taylor & Francis, New York, 2019.
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* Combination of surprise, quiz and assignment tests.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Durga Prasad Padhy, Manager, Vedanta Resources Limited (Vedanta Aluminium Limited), Jharsuguda, Odisha – 768201, durga.prasadpadhy@vedanta.co.in	Dr. V. Sateesh Kumar, NIT Trichy, sateeshv@nitt.edu	Dr. Ranjeet Kumar Sahu, SRMIST ranjeetkumar.c@ktr.srmuniv.ac.in
Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	Dr. M. Iqbal, SRMIST

		roughness.				
S-8	SLO-1	Surface engineering by material addition (principle and its application with examples).	Plasma and ion beam assisted surface modification	Micro Arc Oxidation,	Electron Energy Loss Spectroscopy	Surface engineering of polymers
S-9	SLO-1	Surface modification of steel, non-ferrous and ferrous components: (principle and scope of application).	Surface modification by Ion implantation and Ion beam mixing	Electro Spark Coating	Photoelectron Spectroscopy	Surface engineering of composites

Learning Resources	<ol style="list-style-type: none"> 1. K.G. Budinski, <i>Surface Engineering for Wear Resistances</i>, Prentice Hall, Englewood Cliffs, 1988. 2. M. Ohring, <i>The Materials Science of Thin Films</i>, Academic Press Inc, 2005 3. D. Satas, Arthur A. Tracton, "Coatings technology handbook", Marcel Dekker, 2000 4. K. Oura, V. G. Lifshits, A. A. Saranin, A. V. Zotov and M. Katayama, "Surface Science – An Introduction" Springer, 2009. 5. B G Miller, "Surface coatings for protection against wear", Wood head Publishing, 1st Edition, 2006 6. Riviere.J.C and Myhra.S, "Handbook of Surface and Interface analysis", CRC Press, 2009. 7. Hari Singh Nalwa, "Nanostructured Materials and Nanotechnology", Academic Press, 2002.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. O P Khatri, CSIR-Indian Institute of Petroleum, Dehradun – 248005 (India)-400701 opkhatri@iip.res.in	1. Dr. P Ramkumar, IIT Madras, ramkumar@iitm.ac.in	Dr. Jitendra Kumar Katiyar, SRMIST jitendrakumar.v@ktr.srmuniv.ac.in
2. Dr. Prasanta Kumar Padhi, Deputy General Manager, SAIL Raurkela, Odisha – 769011 prasantakumar.padhi@sailrsp.co.in	2. Dr. T V K Gupta, VNIT Nagpur, tvkgupta@mec.vnit.ac.in	Dr. T V V L N Rao, SRMIST narasimharao.t@ktr.srmuniv.ac.in

Course Code	18MEE425T	Course Name	SUPPLY CHAIN MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the role of logistics	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the phases of supply chain	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the evolution of supply chain models	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the supply chain activities	Expected Attainment (%)	Design & Development
CLR-5 :	Understand the SCM organization and information system		Analysis, Design, Research
CLR-6 :	Understand the role, phases, evolution, activities and SCM information system		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Familiar in Logistics and its role of operations.	1 2&3 90 85	H L
CLO-2 :	Familiar in Supply chain and its different phases.	1 2&3 90 85	H L
CLO-3 :	Familiar in evolution of supply chain models and solution for engineering problem	1 2&3 90 85	H L
CLO-4 :	Familiar with the activities of supply chain	1 2&3 90 85	H L
CLO-5 :	Familiar in Understanding different SCM organization and different ERP systems	1 2&3 90 85	H L
CLO-6 :	Familiar in logistics operations, SCM phases, SCM models, SCM activities, SCM organization and different ERP systems	1 2&3 90 85	H L

	Introduction to Logistics	Phases of Supply Chain	Evolution of Supply Chain Models	Supply Chain Activities	Scm Organisation and Information System
Duration (hour)	09	09	09	09	09
S-1	SLO-1	Introduction of Logistics and its concepts	The new paradigm shift	Strategy of supply chain	Introduction of Structuring the supply chain
S-2	SLO-1	Logistics definitions	The modular company	structure of supply chain	Supply chain challenge – five tasks for management
S-3	SLO-1	Different Logistics approaches	Introduction to strategic core, network structures, management networks and vertical integration	Supply Chain as activity systems	The management task
S-4	SLO-1	Factors influencing logistics	The network relations in supply chain	New products of supply chain	Types of Logistics organization
S-5	SLO-1	Basic tasks of supply chain	Supplier relationship, partnerships and alliances, cooperation and integration, Governance, boundary management, global networks	Foundation for supply chain change	The logistics in information systems
S-6	SLO-1	Defection of supply chain	Supply processes in supply chain	Functional roles in supply chain change	Topology of Supply chain application
S-7	SLO-1	Approaches of supply chain	Process flow, product design, product issues, product structure, logistics issue	Frame work Design for supply chain	Product Data Management
S-8	SLO-1	Influencing supply chain	Procurement processes in supply chain	Institutionalizing supply chain changes	Warehouse management system MRP- 1,
S-9	SLO-1	A new corporate model.	Distribution management in supply chain	Collaborative product commerce	Warehouse management system MRP- 2
			linking supply chain with customer		ERP case study
					ERP software's

Learning Resources	<p>1. Shari, P. B. and Lassen, T. S., <i>Managing the global supply chain</i>, Viva books, New Delhi, 2000.</p> <p>2. Ayers, J. B., <i>Hand book of supply chain management</i>, The St. Lencie press, 2000. 1.</p> <p>3. Nicolas, J. N., <i>Competitive manufacturing management – continuous improvement, Lean production, customer focused quality</i>, McGrawHill, New York, 1998.</p> <p>4. Steudel, H. J. and Desruelle, P., <i>Manufacturing in the nineteen – How to become a mean, lean and world class competitor</i>, Van No strand Reinhold, New York, 1992.</p>
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr.M. K. Marichelvam, Mepco Schlenk Engineering College, Sivakasi.	1. Mr.M. Sachidhanandham Asst. Professor, ME SRM Institute of Science and Technology, Kattankulathur,
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2.Mr.A.Prabukarthi A, PSG College of Technology Coimbatore-641004	Dr. M. Iqbal, SRMIST

Course Code	18MEE426T	Course Name	COMPOSITE MATERIALS AND MECHANICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Understand the overview, constituents, classifications, and advanced applications of composites
CLR-2 :	Understand the mechanics and performance of composite materials
CLR-3 :	Understand the manufacturing techniques and inspection of various composite materials
CLR-4 :	Learn to test and understand the failure, and analysis methods of laminated composites and their constituents and analyze the characteristics of laminated composites
CLR-5 :	Learn design aspects and acquiring knowledge on material selection for advanced engineering composite materials.
CLR-6 :	Understand the applications, performance, inspection of composites

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Familiar with the Overview, constituents, classifications, and advanced applications of composites and composites mechanics
CLO-2 :	Familiar the mechanics and performance of composite materials
CLO-3 :	Familiar with the manufacturing techniques and inspection of various composite materials
CLO-4 :	Familiar with the testing and understand the failure, and analysis methods of laminated composites and their constituents and analyze the characteristics of laminated composites
CLO-5 :	Familiar with the Design and select the material for advanced engineering composite materials.
CLO-6 :	Familiar with overview, performance, applications and inspection of composites

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
			H	H			M										
			H		M	L											
				M	H		M										
			H		H	M	M										
			H		H	M	L										

Duration (hour)		Overview of Composites	Mechanics and Performance	Manufacturing	Testing and Analysis	Design and Material selection
9		9	9	9	9	9
S-1	SLO-1 & 2	Introduction to composites - Definitions Classification of composite materials	Introduction to solid mechanics - lamina and laminates	Overview of composite manufacturing processes	Fiber test, Neat resin matrix test Tensile, compressive test In-plane shear, Interlaminar shear tests Flexural, Interlaminar fracture, Fiber/Matrix interface tests	Failure predictions in a Unidirectional Lamina
S-2	SLO-1 & 2	Polymer matrix Ceramic matrix,	Mechanics terminology Interlaminar stresses	Overview of glass fibre production	Analysis of an orthographic lamina	Failure predictions for Unnotched Laminates
S-3	SLO-1 & 2	Metal matrix; Special composites - Functionally graded materials	Unidirectional and angle lamina and laminates	Carbon fiber production	Analysis of an orthographic laminates	Laminated Design Consideration
S-4	SLO-1 & 2	Characteristics of composite materials Mechanical behavior of composite materials	Engineering constants of an angle lamina and laminates	Spray-up, Hand lay-up	Hooke's law, stiffness and compliance matrices	Bonded joints; Bolted joints; Bonded-Bolted joints
S-5	SLO-1 & 2	Structural Materials Constituent materials for composite materials	Static Mechanical Properties Hooke's law for different types of materials	Filament winding Fiber placement	Strengths of orthographic lamina	Design requirements and design failure criteria
S-6	SLO-1 & 2	Matrix materials – types and properties Reinforced materials– types and properties	Effective modulus in stress-strain	Closed-mould processes, Bag Moulding	Stress analysis of laminated composite beams	Design load definitions Design analysis philosophy for composite structures

S-7	SLO-1 & 2	Fibers for advanced composites Current and potential advantages of fiber-reinforced composite materials	Symmetry in stress-strain	Compression moulding, Pultrusion, and Other manufacturing processes	Stress analysis of laminated composite Plates	Laminate optimization Design examples
S-8	SLO-1 & 2	Applications of composite materials - Military aircraft, Civil aircraft	Fatigue and Impact properties and Environmental effects	Quality Inspection method	Stress analysis of laminated composite Shells	Materials selection criteria Different material section factors
S-9	SLO-1 & 2	- Automotive applications, Commercial applications,	Fracture Behavior and Damage Tolerance	Composite defects, detection and possible solution	Free vibration	- Fiber selection factor - Matrix selection factor - Importance of constituents

Learning Resources	<ol style="list-style-type: none"> 1. P.K. Mallick, FIBRE REINFORCED COMPOSITES: MATERIALS, MANUFACTURING AND DESIGN, Marcel Dekker, 1993. 2. J.C. Halpin, PRIMER ON COMPOSITE MATERIALS, ANALYSIS, Techomic Publishing Co., 1984. 3. B.D. Agarwal, and L.J. Broutman, ANALYSIS AND PERFORMANCE OF FIBRE COMPOSITES, John Wiley and Sons, New York, 1990. 4. P.K. Malick and S. Newman, (eds), COMPOSITE MATERIALS TECHNOLOGY: PROCESSES AND PROPERTIES, Hansen Publisher, Munich, 1990. 5. R.P.L. Nijssen, COMPOSITE MATERIALS AN INTRODUCTION, A VKCN publication, 1st Edition, 2015. 6. Robert M. Jones, MECHANICS OF COMPOSITE MATERIALS, 2nd Edition, Taylor & Francis, 1999. 7. Ronald F. Gibson, PRINCIPLE OF COMPOSITES MATERIAL MECHANICS, McGraw Hill, 1994. 	<ol style="list-style-type: none"> 8. Autar K. Kaw, MECHANICS OF COMPOSITE MATERIALS, 2nd Edition, Taylor & Francis, 2006. 9. Valery V. Vasiliev and Evgeny V. Morozov, ADVANCED MECHANICS OF COMPOSITE MATERIALS AND STRUCTURAL ELEMENTS, 3rd Edition, Elsevier, 2013. 10. Madhujit Mukhopadhyay, Mechanics of Composite Materials and Structures, University Press, 2018. 11. Reddy J. N., Mechanics of Laminated Composites Plates and Shells, CRC Press, 2016. 12. Bhagwan D. Agarwal, Analysis and Performance of Fiber, Wiley India, 2015. 13. Balasubramaniam, Composite Materials, John Wiley & Sons, Indian Ed., 2013. 14. K.K. Chawla, Composite Materials, Springer, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	2 Dr. Sumit PRAMANIK Research Associate Professor, ME, SRM Institute of Science and Technology, Kattankulathur, H/P: +91-8777740422 Email: sumitpramanik.s@ktr.srmuniv.ac.in



Course Code	18MEE427T	Course Name	GLOBAL OPTIMIZATION ALGORITHMS	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																					
CLR-1 :	Be familiar with evolutionary algorithm				Level of Thinking (Bloom)	1	Expected Proficiency (%)	2	Expected Attainment (%)	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15				
CLR-2 :	Be familiar with particle genetic algorithm																												
CLR-3 :	Be familiar with modern optimization techniques																												
CLR-4 :	Be familiar with search algorithms																												
CLR-5 :	Be able to apply the knowledge of optimization in mechanical engineering applications																												
CLR-6 :	Be familiar with evolutionary algorithm, genetic algorithm, modern optimization techniques, search algorithms and optimization applications																												
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:									Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3				
CLO-1 :	Recall the concepts of optimality criteria for various types of optimization problems.				1	90	85	H						M					H	H	M		H	H	M				
CLO-2 :	Understand the problems				2	90	85	H	H			H	M	M					M	H	H			H	H	M			
CLO-3 :	Apply the methods of optimization to solve real life problems				3	90	85	H	H	H		H	H	M				M	M	M			H	H	M				
CLO-4 :	Analyze the methodology followed and test the results				4	90	85	H	H	H			H			M					M			H	H	M			
CLO-5 :	Investigate the results to obtain the optimized solution				5	90	85	H	H				H	M										H	H	M			
CLO-6 :	Investigate with evolutionary algorithm, genetic algorithm, modern optimization techniques, search algorithms and optimization applications				1-5	90	85	H	H	H		H	H	M				M	M	M	M			H	H	M			

Duration (hour)		Global optimization technique	Modern optimization techniques Part I	Modern optimization techniques Part II	Search Methods	Applications of optimization techniques
		9	9	9	9	9
S-1	SLO-1	Introduction to Optimization Algorithms	Introduction to Particle Swarm Optimization (PSO)	Introduction to Simulated Annealing algorithm (SAA)	Linear search and binary search	Desirable and undesirable effects, functional requirements such as geometry and materials.
S-2	SLO-1	The Structure of Optimization - Formulae and Search Space/Operator Design	Theoretical derivatives in particle swarm optimization, Variants of PSO	Asymptotic convergence and typical behavior of SAA, Multi objective SA	Jump search, interpolation search	Stochastic optimization
S-3	SLO-1	Evolutionary algorithms, ranking selection, VEGA, Convergence prevention	Performance Enhancing techniques in PSO, Applications of PSO	External optimization, Tabu Search, Memetic and Hybrid algorithms	Exponential search, Fibonacci search	Integrating simulation in optimization models
S-4	SLO-1	Optimization problems in engineering, Inverse problems; Scheduling and Routing	Introduction to Ant colony optimization (ACO), Framework of ACO	Downhill simplex, Applications of SAA	Golden selection, Random, pattern and gradient search methods	Multi-Disciplinary Optimization in enhancing the features of an automobile.
S-5	SLO-1	Data Mining, Intelligent System designing, Introduction to Genetic Algorithm, Operators of GA's, Differences and similarities between genetic algorithms and traditional techniques	Hill Climbing, Multi-Objective Hill Climbing	Introduction to Differential Evolution (DE)	State Space Search, Uninformed Search	Optimization for modular design.

S-6	SLO-1	Introduction to utilization of computer programs in GA, Schema Algorithm, Advanced operators and techniques in genetic search	Problems in Hill Climbing, Hill Climbing with Random Restarts	Structure of Differential algorithm (DA)	Breadth-First Search, Depth-First Search	Optimization of design parameters to design a mechanical component.
S-7	SLO-1	Genetic algorithm and machine learning, Introduction to multi objective optimization, Types of multi objective problems and principles	GRASP, Raindrop Method, Random Optimization	Computing environments in DE	Depth-limited Search, Iterative Deepening Depth	Optimization of process parameters in machining operations.
S-8	SLO-1	Pareto optimality, Non-Elitist multi objective algorithms, Elitist multi objective algorithms	Monte Carlo methods	Applications of DA	Informed Search - Greedy Search- A* search - Adaptive Walks, Tree search,	Optimization in minimizing cost and enhancing strength mechanical elements
S-9	SLO-1	Constrained multi objective algorithm, Usage of multi objective optimization in various optimization techniques	Multi disciplinary optimization methods and their applications in engineering.	Optimization with parameter uncertainties – Robust Optimisation, formulation, algorithms, applications	Interpolation methods: quadratic and cubic, direct root method.	Optimization problems on scheduling.

Learning Resources	<ol style="list-style-type: none"> 1. Kalyanmoy Deb, "Optimization for Engineering design-Algorithms and Examples", Prentice Hall, India, 2012. 2. Kalyanmoy Deb, "Multi objective optimization using Evolutionary algorithms", John Wiley, 2001. 3. Joshua Knowles, David Corne, Kalyanmoy Deb "Multiobjective Problem Solving from Nature: From Concepts to Applications", Springer- 2008. 4. Thomas Weise, "Global Optimization Algorithms – Theory and Application", Thomas Weise, 2009. 5. S.S Rao, "Optimization – Theory and Applications", Wiley Eastern, New Delhi, 2009 6. Parsopoulos K and Vrahatis M.N, " Particle Swarm Optimization and Intelligence:Advances and Applications", IGI Global, 2010.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Dr. Chiradeep Ghosh, Principal Scientist, TATA Steel. Chiradeep.ghosh@tatasteel.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu , hariharan2311@gmail.com	Shubrajit Bhaumik, SRMIST
Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	2. Dr.N.Arunachalam, IIT Madras, chalam@iitmadras.ac.in	Dr. Shubhabrata Datta, SRMIST

Course Code	18MEE428T	Course Name	SIMULATION OF MECHANICAL SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with the function of physical system	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the models use in need for simulation	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	understand about different methods of simulation	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with translational simulation	Expected Attainment (%)	Design & Development
CLR-5 :	Be familiar with rotational mechanical systems		Analysis, Design, Research
CLR-6 :	Be familiar with simulation of hydraulic and manufacturing system		Modern Tool Usage
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		Society & Culture
CLO-1 :	Recognize and analyze the use of different methods of simulation	1&2 90 85	Environment & Sustainability
CLO-2 :	Acquire knowledge on basic components and working of various mechanical systems	1 90 85	Ethics
CLO-3 :	Recognize the application of Random variables and their properties, estimation of means, variance and correlation	1 90 85	Individual & Team Work
CLO-4 :	Understand the Static and dynamic modeling	1&2 90 85	Communication
CLO-5 :	Recognize the Numerical computation techniques based upon the application	1&2 90 85	Project Mgt. & Finance
CLO-6 :	Simulation of rotational systems and translational system as well as the hydraulic system	1 90 85	Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Duration (hour)	Introduction	Types and principles of modeling	Methods of simulation	simulation of translational and Rotational systems	Simulation of hydraulic systems and manufacturing system
S-1	SLO-1	Need for modeling and simulation in mechanical systems	Static modeling with examples	Monte Carlo simulation	Building of simulation models in mechanical systems
S-2	SLO-1	Basics of modeling of physical systems	dynamic modeling with examples	Experimental nature of simulation	Simulation of translational systems
S-3	SLO-1	methods of modeling	Stochastic models with examples	Numerical computation techniques	Case studies – Translatory motion for Serial Manipulator
S-4	SLO-1	Review of basic probability and statistics	Principles of modeling	Analog system models	Simulation of rotational systems
S-5	SLO-1	Random variables and their properties, estimation of means, variance and correlation	Study and evaluation of model	hybrid system models	real time examples
S-6	SLO-1	Concept of system and environment, continues and discrete systems	Continues system models	Continues system models	Transform Function Analysis. Developing a Linear Model
S-7	SLO-1	Linear systems	Introduction to simulation, basic simulation, advantages of simulation	Role of computers in simulation	Case studies – Rotary Joint Link for SCARA ROBOT
S-8	SLO-1	nonlinear systems	Role of simulation in model evaluation	introduction to simulation software	Techniques for variance reduction
S-9	SLO-1				

		with examples	packages		
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Learning Resources	<ol style="list-style-type: none"> 1. Dym C.L., "Principles of Mathematical Modeling", Elsevier, 2nd Edition 2004. 2. Geoffrey Gordon, "System Simulation" Phi Learning, 2nd Edition 2002 3. M. Close and Dean K. Frederick, "Modeling and Analysis of Dynamic Systems", Houghton Mifflin, 3rd Edition, 2002 4. Guy L, Richard M. Feldman, "Manufacturing Systems Modeling and Analysis", Springer, 2011. 	<ol style="list-style-type: none"> 5. Performance Modeling of Automated Manufacturing Systems (Prentice Hall Information and System Sciences Series) 1st Edition Edition, 1992 6. J. Schwarzenbach and K.F. Gill, "System Modeling and Control".Halsted Press, New York, 1992 7. Robert E. Shannon, "System Simulation: The Art and Science", Prentice Hall, 1975 8. Automation, Production Systems, and Computer-Integrated Manufacturing 4 Edition (English, Paperback, Mikell P. Groover), 2016
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,
SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. S.Bhargav, GM,Rane Brake, Trichy	1. Dr. V.Srinivasan, Annamalai University, srinivaghavan@yahoo.com	1. Dr. M. Prakash, SRMIST
2. Dr. Muthumanikkam, Jt. Director, CVRDE, DRDO, Avadi, Chennai.	2. Dr.Ashok Kumar, Govn. Col.of. Eng, Bargur, Krishnagiri, Tamil Nadu Akrt02au@gmail.com	2. Dr.A.Arul Jeya Kumar, SRMIST

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering		Data Book / Codes/Standards	Nil	

Duration (hour)	9	9	9	9	9
S-1	IoT-An Architectural Overview	Big Data Platforms for the Internet of Things	Introduction to the Cloud Computing	Myths Of Information Security Mana	Introduction To Digital Manufacturing
S-2	Building an architecture	Network protocol	History of cloud computing	The big picture	Features and development of digital manufacturing
S-3	Main design principles and needed capabilities	Data dissemination –current state of art	Cloud service options	Learning from experience	Theory system of digital manufacturing science
S-4	An IoT architecture outline, standards considerations	Improving Data and Service Interoperability with Structure	Cloud Deployment models	Weaknesses in Information Security	Operation Mode
S-5	M2M and IoT Technology Fundamentals	Compliance, Conformance	Business concerns in the cloud,Cloud Orchestration	The extent of crime in cyberspace	Architecture of Digital Manufacturing System
S-6	Devices and gateways, Local and wide area networking	Context Awareness	Exploring virtualization, Load balancing	The cyberspace crimoid syndrome	Additive Manufacturing - overview, Techniques.
S-7	Data management, Business processes in IoT	interoperability problem in the IoT context	Hypervisors, Machine imaging,	Policies and technologies	
S-8	Everything as a Service (XaaS)	Big Data Management Systems for the Exploitation of Pervasive Environment	Cloud marketplace overview	A new framework for information security.	Rapid manufacturing-Future development-Virtual prototyping
S-9	M2M and IoT Analytics, Knowledge Management.	Big Data challenges and requirements coming from different Smart City applications.	Comparison of Cloud providers.		

Learning Resources	1. Vijay Madiseti and Arshdeep Bahga, "Internet of Things (A Hands-on-Approach)", 1st Edition, VPT, 2014. 2. Bernd Scholz-Reiter, Florian Michahelles, "Architecting the Internet of Things", ISBN 978-3-642-19156-5 e-ISBN 978-3-642-19157-2, Springer 3. Stackowiak, R., Licht, A., Mantha, V., Nagode, L., "Big Data and The Internet of Things Enterprise Information Architecture for A New Age", Apress, 2015	4. Cloud Computing: Principles and Paradigms by Rajkumar Buyya, James Broberg and Andrzej M. Goscinski, Wiley, 2011. 5. Zude Zhou, Shane (Shengquan) Xie and Dejun Chen, Fundamentals of Digital Manufacturing Science, Springer-Verlag London Limited, 2012 6. Chua.C.K, "Rapid Prototyping", John Wiley, New York, 1997.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,
SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	Dr.U.Mohammed Iqbal
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in		
3. Mr.P.Karthikeyan, Head Operations Improvement, Nokia Solutions, Oragadam Kartikeyan.p@nokia.com	2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	J.Santhakumar

Course Code	18MEE430T	Course Name	TQM AND RELIABILITY ENGINEERING	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the importance of TQM and its concepts, tools and techniques and apply in the real-world environment	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Analyze the role of human involvement to improve the quality of product and service	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand, apply and evaluate the tools and techniques used for product and service quality	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the basic concepts of reliability, apply and evaluate reliability for different systems	Expected Attainment (%)	Design & Development
CLR-5 :	Understand and apply the concept of maintainability of a system to evaluate time for different cases		Analysis, Design, Research
CLR-6 :	Understand the importance of quality and reliability in every process in the current scenario		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Recognize the importance of quality in every activity of an organization and in personal life	1,2 80 75	M M M - M - - M H M - - - - M
CLO-2 :	Apply the different tools and techniques to solve day to day issues and will seek an opportunity to practice	1,2,3 80 75	M H - - H - - - H M - - - - M
CLO-3 :	Think from the customer perspective and will plan for customer retention through total quality management	1,2,3 80 75	M H M - H M - - M H M - - - - M
CLO-4 :	Develop and test a system for its reliability	1,2 80 75	M M M - M - - - - - - - - M
CLO-5 :	Estimate MTTF, MTTR, MMT and MDT and plan for a maintenance strategy	1,2,3 80 75	M H M - H - - - - - - - - M
CLO-6 :	Recognize the importance of quality in every activity of an organization and in personal life	1,2 80 75	M M M - M - - M H M - - - - M

Duration (hour)	Evolution, theories and implementation	Principles and 7 QC tools	Management Tools	Reliability	Maintainability
9	9	9	9	9	9
S-1	SLO-1 Evolution of Total Quality Management	Customer Satisfaction – Types of customers, customer supplier chain	Affinity diagram – Relations diagram	Probabilistic nature of failures	Introduction Availability and Maintainability
S-2	SLO-1 Definition of quality, Dimensions of Quality	Customer perception of quality customer feed back	Tree diagram – Matrix diagram – Matrix data analysis diagram	Mean failure rate – Mean time between failures	Types of maintenance strategy
S-3	SLO-1 Deming's theory	Customer complaints – Customer retention – Service quality	Process decision program chart, Arrow diagram	Hazard rate – Hazard models	Mean time– to repair (MTTR)
S-4	SLO-1 Juran and Crosby theories	Employee involvement and motivation – Maslow's hierarchy of needs	5S Principles	Weibull model	Factors contributing to Mean Down Time (MDT)
S-5	SLO-1 Taguchi and Ishikawa theories	Herzberg theory – Empowerment and team work	Quality Function Deployment (QFD)	System reliability improvement	Fault diagnosis, and routine testing for unrevealed faults
S-6	SLO-1 Quality costs, Product quality Vs Service quality	Seven QC tools – Check sheets	Failure mode and effects analysis (FMEA)	Redundancy	Factors contributing to Mean Maintenance Time – (MMT) on condition maintenance
S-7	SLO-1 Goal setting	Histograms, control charts	Root cause analysis, poka-yoke	Series – Parallel and Mixed configurations	Total Productive Maintenance (TPM)
S-8	SLO-1 Strategic Quality planning	Pareto diagram, Cause and effect diagram	Introduction to Six Sigma	Problems in Series – Parallel and Mixed configurations	Periodic condition monitoring, Continuous condition monitoring
S-9	SLO-1 TQM implementation	Stratification, Scatter diagrams	DMAIC	Problems in Series – Parallel and Mixed configurations	Economics of maintenance

Learning Resources	1. M. P. Poonia, S.C. Sharma, "Total Quality Management", Khanna Publishing, 2019.	5. Roderick A Munro, Govindarajan Ramu and Daniel J Zrymiak, "The Certified Six Sigma Green Belt Handbook", Second Edition, American Society for Quality, USA, 2015.
	2. R Kiran, "Total Quality Management: Key Concepts and Case Studies", Elsevier Inc., 2017.	6. L S Srinath, "Reliability Engineering", Fourth Edition, Affiliated East West Press, 2008.
	3. Dale H Besterfield, "Total Quality Management", Fourth Edition, Pearson Education Asia, 2015.	7. E Balagurusamy, "Reliability Engineering", Tata McGraw Hill Education, 2010.
	4. John Oakland, Peter Morris "TQM – A pictorial guide for managers", Routledge, 2011.	

Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry		Experts from Higher Technical Institutions
Mr. R. Nanda Kumar, Vice Chairman, National Institution for Quality and Reliability (NIQR)		1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com
Mr. N. Palani, Head – Quality Assurance Rane TRW Steering Systems Limited		2. Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in
		Internal Experts
		Mr. E. Vijayaragavan, SRM IST

Course Code	18MEE431T	Course Name	DESIGN OF JIGS, FIXTURE AND PRESS TOOLS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	DESIGN DATA BOOK		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Explore the various locating and clamping method	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the functions and design principles of Jigs	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the functions and design principles of Fixtures	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the functions and design principles of press work	Expected Attainment (%)	Design & Development
CLR-5 :	Understand the functions and design principles of bending, forming and drawing		Analysis, Design, Research
CLR-6 :	Be Familiar with design of jigs, Fixtures and Press Tools		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Able to design the locator and the clamp for the mechanical component	1&2 80 85	H M H - - - - - - - - - - M - -
CLO-2 :	Acquire knowledge on different type of jigs and its application	1 80 85	H M H - - - - - - - - - - H - -
CLO-3 :	Acquire knowledge on different type of fixture and its application	1 80 85	H M H - - - - - - - - - - H - -
CLO-4 :	Understand the major design principle of press work and element of cutting die	1&2 80 85	H L M - - - - - - - - - - - - -
CLO-5 :	Understand the functions and design principles of bending, forming and drawing	1&2 80 85	H - M - - - - - - - - - - - - -
CLO-6 :	Understand the functions and design principles of locator and clamping of jigs and fixtures, use of press tools in bending, forming and drawing operations	1&2 80 85	H H M - - - - - - - - - - - - -

		Locating and Clamping Principles	Design of Jigs	Design of Fixtures	Press Working Terminologies and Element of Cutting Dies	Bending, Forming and Drawing Dies
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Objective of tool design, Function, features and advantages of jigs and fixture.	Types of jigs – Template and Plate Jigs	Introduction to fixture, type of fixtures	Press working terminology, types of presses	Types of Bending dies, press capacity
S-2	SLO-1	Locating Principle, Locating methods and devices,	Channel, Pot, Turnover, Box and Post Jig	Design Principles of milling fixture	Press accessories and press working operation.	Spring back, knockout, direct and indirect, pressure pads, ejectors
S-3	SLO-1	Pin and Button locator, Rest pads and plates, Diamond pin locator	Indexing Jigs	Lathe fixture	Shearing action, clearances, press work materials.	Variables affecting metal flow in drawing operation
S-4	SLO-1	Clamping Principles, types of clamps, mechanical actuation clamps	Drill Bushes and Jig Buttons	Design Principles of boring fixture, and Broaching Fixture	Center of pressure, design of various elements of dies	Draw die insert, draw beads, ironing
S-5	SLO-1	Pneumatic actuation clamping	method of construction of drill jigs	Design Principles of Grinding Fixture	Accessories of blanking dies – punch, punch holder, die set, stripper, pilots	Design and development of bending and forming
S-6	SLO-1	Hydraulic actuation clamping	General consideration in the design of Drill jigs	Assembly, Inspection and welding fixtures		Drawing reverse re-drawing and combination die
S-7	SLO-1	Vacuum and magnetic clamping	Drill jigs and modern manufacturing	Modular fixturing system,	Selection of standard parts	Blank development for axisymmetric, rectangular and elliptic parts, single and double action dies
S-8	SLO-1	Standard parts in jigs and fixtures	Design and development of jigs and for	Design and development of fixtures and for	Design and preparation of four standard	Bulging, swaging, Embossing, coining,

S-9	SLO-1	Limits, fits, Tolerances and types of tolerances	given component 1	given component 1	views of simple blanking and piercing die Shaving, notching, compound and progressive dies	curling Hole flanging, shaving, and sizing, assembly, fine blanking dies
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Learning Resources	1. Donaldson, Lecain and Goold "Tool Design ", 3rd edition Tata McGraw hill ,2007 2. Joshi, P.H. "Jigs and Fixtures" second edition, Tata McGraw hill publishing co., ltd., New delhi,2004 3. K.Venkataraman, "Design of Jigs Fixtures and Press tool", Tata McGraw hill New delhi,2005 4. Kempster, "jigs and fixtures design" Hoddes and Stoughton – third edition 1974	5. Joshi, P.H "Press tool – Design and Construction", S.Chand &company, 2010. 6. Hoffman "Jigs and Fixtures Design" – Thomson Delmar learning, Singapore, 2004. 7. ASTME fundamentals of tool design prentice hall of India. 8. P.S.G tech..., "design data book", kalaikathir Achchagam, 2012.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	1. Dr. P. Hariharan, Anna University, hari@annauniv.edu, hariharan2311@gmail.com	1. Kolli Balasivarama Reddy Asst. Professor, ME SRM Institute of Science and Technology, Kattankulathur,
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	2.Dr.N.Arunachalam, IIT Madras, chalam@iitm.ac.in	

Course Code	18MEE341T	Course Name	REFRIGERATION AND AIR CONDITIONING SYSTEMS	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	18MEC107T	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Refrigerant and Psychrometric Properties Tables & Charts/M.L.Mathur & F.S.Mehta		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with vapour compression system	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the refrigeration cycles and methods for improving Performance	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the working of components of refrigeration systems.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with design of air conditioning systems	Expected Attainment (%)	Design & Development
CLR-5 :	Be familiar with air conditioning systems for various applications.		Analysis; Design, Research
CLR-6 :	Be familiar with refrigeration and air conditioning system s		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Recognize and analyze the vapour compression systems	1&2 90 80	H H M
CLO-2 :	Acquire knowledge on refrigeration cycles and methods for improving Performance	1,2,3 90 80	H M M
CLO-3 :	Understand the working of refrigeration systems.	1,2 90 80	H H M
CLO-4 :	Analyze and design of air conditioning systems.	1,2,3 90 80	H H H M
CLO-5 :	Appreciate the need and applications of air conditioning systems.	1&2 90 80	H H M
CLO-6 :	Understand and analyze the refrigeration and air conditioning system s	1&2 90 80	H M M

		Vapour Compression Refrigeration Systems	Absorption Refrigeration Systems	Refrigeration Equipment's & Contro	Design of Air Conditioning Systems	Applications of Refrigeration And Air Conditioning Systems
Duration (hour)		9	9	9	9	9
S-1	SLO1	Review of thermodynamic principles of refrigeration	Ideal vapour absorption refrigeration system	Construction features of reciprocating compressors, Rotary and screw compressors	Different heat sources-sensible heat load, Latent heat load	Preservation of different products
S-2	SLO1	Simple vapour compression refrigeration system	Absorbent refrigerant combination - Properties of refrigerant absorbent pair	Type of Condenser, heat transfer in condensers	Heating and Cooling Load - Occupants load, equipment load, fresh air load, infiltration air load	Construction and working of Ice factory
S-3	SLO1	Problem on COP of VCR system	Vapour absorption refrigeration system based on Water-lithium bromide.	Types of cooling towers- Construction features of Natural, Mechanical draft.	Design of air conditioning system-cooling load and air quantities	The heating and cooling requirements for different dairy products and processes in Dairy plant
S-4	SLO1	Methods to improve the COP of VCR system	Problems based on Water - lithium bromide systems	Type of Evaporators-working of dry expansion and flooded evaporator.	Bypass factor(BPF) of heating and cooling coil, Effective sensible heat factor(ESHF)	Application of non-conventional refrigeration method in vortex and pulse tube refrigeration. system
S-5	SLO1	Multiple evaporator and compressor system	Vapour absorption refrigeration system based on Aqua Ammonia	Working of automatic (or) constant pressure expansion valve and thermostatic expansion valve	Room sensible heat factor(RSHF).Grand sensible heat factor	Application of non-conventional refrigeration method in Solar Refrigeration system
S-6	SLO1	Cascade system	Problems based on Aqua -Ammonia Systems	Properties of refrigerants	Factors affecting Human comfort	Application of air conditioning in hotels and restaurants
S-7	SLO1	COP comparison with sub cooling	Single effect absorption refrigeration	Selection of refrigerants-alternate refrigerants	Problems on –RSHF, and GSHF	Application of air conditioning in theatres

		and super heating	system			
S-8	SLO1	Problems based on sub cooling	Comparison of vapour compression refrigeration system versus vapour absorption refrigeration system	thermostatic control-operating and safety controls	Problems on design of air conditioning system	Application of air conditioning in auditorium and hospitals
S-9	SLO1	Problems based on super heating	Advantage and disadvantage of vapour absorption system	Refrigerant charging procedure, methods for measuring a Refrigerant Charge	Cooling coils and dehumidifier, air washers	Cryogenics-low temperature applications

Learning Resources	<ol style="list-style-type: none"> 1. Arora, S. C. and Domkundwar, S., A course in Refrigeration and Air conditioning, Dhanpat Rai (P) Ltd., New Delhi, 2012 2. Ananthanarayanan.P.N, "Basic Refrigeration and Air Conditioning", Tata McGraw Hill, 3rd Edition, New Delhi, 2006 3. Manohar Prasad, Refrigeration and A 4. Air conditioning, New Age International (P) Ltd, New Delhi, 2010 5. Roy J. Dossat, Principles of Refrigeration, Pearson Education Asia, 4th edition, 2001 	<ol style="list-style-type: none"> 6. Arora, C. P., Refrigeration and Air Conditioning, Tata McGraw Hill, New Delhi, 2006 7. Andrew D. Althouse, Modern Refrigeration and Air Conditioning, Goodheart-Willcox Company, Incorporated, 2016 8. G F Hundy Refrigeration, Air conditioning and heat pumps, McGraw-Hill Book company(UK) Ltd, fifth edition 2016 9. S.N.Sapali, Refrigeration and Air conditioning, published by asoke K.Ghosh, PHI Learning Private Limited, Second edition 2014 10. MI Mathur Fs Mehta, Refrigerant & Psychrometric Properties Tables & Charts, Published by Jain Brothers, 2010
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	Dr P.Balachander Assistant Professor Thermal Sciences Block Refrigeration & Air Conditioning Department of Mechanical Engineering, College of Engineering, Guindy campus, Anna University, Chennai-600025 Email: p_balachander@annauniv.edu	Mr.J.Thavamani Assistant Professor, Department of Mechanical Engineering SRM IST Email: thavamani.j@ktr.srmuniv.ac.in
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. K. LAKSHMIKANTH M.E (Refrigeration and Air conditioning system) MANAGER Frick India Limited Seshadri Puram, Bangalore - 560020 Email: bng@frickmail.com	Mr. D. kathirkaman Assistant Professor Department of Mechanical Engineering SRM IST Email: kathirkaman.d@ktr.srmuniv.ac.in

Course Code	18MEE342T	Course Name	INTERNAL COMBUSTION ENGINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC101T, 18MEC102T	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	familiarizewith the I.C.enginebasics, analyze the ideal cycles and performance characteristics	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Study about carburetors, fuel injection systems, ignition, lubrication and cooling systems.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the combustion in S.I. engines, combustion chambers and knocking phenomena	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the combustion in C.I. engine, diesel combustion chambers and abnormal combustion;	Expected Attainment (%)	Design & Development
CLR-5 :	Study about the emissions from the I.C. engines, alternative fuels and new combustion concepts		Analysis, Design, Research
CLR-6 :	Understand the design principles of I.C. engines		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Performance calculations of I.C. engines, Interpret the ideal and fuel-air cycles; performance maps	1,2&3 90 80	H H H H L L M
CLO-2 :	Evaluate the functioning of various auxiliary systems	1&2 90 80	H H H M M L M
CLO-3 :	Analyze SI engine combustion, knocking and the design principles of combustion chamber.	1&2 90 80	H H M H M L M
CLO-4 :	Analyze CI engine combustion, design principles of combustion chamber and abnormal combustion	1&2 90 80	H H M H M L M
CLO-5 :	Recognize the need for reducing the emission from I.C. engines, and alternate fuels	1&2 90 80	H M M H H M H
CLO-6 :	Evaluate the performance, combustion and emissions of I.C. engines from thermodynamic principles	1,2&3 90 80	H H M M M M H

		Performance of I.C. Engines	Engine Auxiliary systems	Combustion in S.I. Engines	Combustion in C.I. Engines	Emissions and Alternative fuels
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Engine operating cycle, terminology and components, four stroke and two stroke engines and their comparison	Carburation, mixture requirements at different loads and speeds, simple carburetor	Combustion in spark ignition engines, Stages of combustion in SI engine, flame front propagation	Combustion in Compression Ignition engines, Stages of combustion in CI engines,	Air pollution due to IC engines, Emissions standards, hydrocarbon and CO emissions,
S-2	SLO-1	Operation of SI and CI engines, their p-v diagrams and comparison, classifications and applications IC engines,	Problems on simple carburetor	Analysis of cylinder pressure data	Analysis of cylinder pressure data and heat-release analysis	Oxides of nitrogen and soot, aldehydes, sulphur, lead and phosphorus emissions
S-3	SLO-1	Volumetric efficiency, and its variation with respect to engine speed, supercharging and turbocharging of engines	Functional requirements and classification of an injection systems, injection pump	Factors influencing the flame speed,	Factors affecting the delay period	Exhaust gas recirculation and catalytic converter
S-4	SLO-1	First law applied to engine, thermal, mechanical efficiencies, pumping work, mean effective pressure	Nozzle types, EFI systems: MPFI, PFI, GDI	Rate of pressure riseAbnormal combustion, knocking in SI engines,	Basics of fuel sprays: Fuel flow rate through injector nozzle, Overall spray structure	Basics of selective catalyst reduction, diesel particulate filter
S-5	SLO-1	Engine parameter measurements.	Functional requirements of ignition systems, Battery ignition system	Effect of engine variables on engine knock	Atomization and spray penetration	Flame ionization detector, non-dispersive infrared detector
S-6	SLO-1	Problems on engine performance.	magneto ignition system, Ignition timing and engine parameters	Combustion chambers for SI engines	Phenomenon of knock in CI engines, comparison of knock in CI and SI engine	Chemiluminescence analyzer, smoke types, Bosch smoke meter
S-7	SLO-1	Concept of heat balance and problems	Functional requirements of lubrication system, properties of lubricants, mist	Smooth engine operation, High power output and thermal efficiency	Combustion chambers for CI engine: Direct injection engines	Fuels for IC engines: Liquid fuels: Alcohol, methanol, ethanol, vegetable oil

			<i>lubrication system</i>			
S-8	SLO-1	<i>Review of ideal cycles and fuel-air cycles significance</i>	<i>Wet and dry sump lubrication system</i>	<i>Concept of hybrid electric drive trains</i>	<i>Gasoline Direct Injection (GDI) Engines: Direct injection Vs port injection, classification of GDI engines</i>	<i>Bio diesel advantages and disadvantages; Gaseous fuels: CNG, LPG, Hydrogen</i>
S-9	SLO-1	<i>Engine performance characteristics</i>	<i>Liquid and air cooling systems, properties of the coolant and antifreeze solutions</i>	<i>Architectures of hybrid electric drive trains</i>	<i>Spray, wall and air guided combustion systems for GDI engines</i>	<i>Advanced concepts: Stratified charge and HCCI engines</i>

Learning Resources	<ol style="list-style-type: none"> 1. Ganesan. V, "Internal Combustion Engines", Tata McGraw-Hill, New Delhi, 2015 2. Heywood, J.B., "Internal Combustion Engine Fundamentals", McGraw-Hill International, New York, 2017 3. Ramalingam, K.K., "Internal Combustion Engines-Theory and Practice", SciTech Publications India Pvt Ltd, Chennai 2016. 4. Thipse, S.S., "Internal Combustion Engines", Jaico Publication House, 2010. 5. Sharma, M.L., and Mathur R.P., "A Course in Internal Combustion Engines" Dhanpant Rai & Sons, New Delhi, 2014. 6. Fuquan Zhao, David L. Harrington and Ming-Chia D. Lai, "Automotive Gasoline Direct-Injection Systems", SAE International Publisher, 2002 7. Mehrdad Ehsani, Yimin Gao, Stefano Longo and Kambiz Ebrahimi "Modern Electric, Hybrid Electric and Fuel Cell Vehicles", CRC Press, 2018
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Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
K. SaratChander Prasad, Sr. Lead Engineer, Mahindra & Mahindra Pvt Ltd	Dr. Shamit Bakshi, Professor, Indian Institute of Technology Madras	Dr. D. Siva Krishna Reddy, Assistant Professor, SRM IST
Ramesh K.J., Kistler, Product Manager, Instruments India Pvt Ltd	Dr. Maha Lakshmi, Professor, Anna University	Dr. G. Balaji, Associate Professor, SRM IST

Course Code	18MEE343T	Course Name	ELEMENTS OF SPACE TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Develop a basic knowledge on earth's atmosphere.	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Learn the different orbit bodies. & Understand the aspects of satellite injection.	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Know the interplanetary and missile trajectories and materials for Spacecraft.				H			H											
					H	H		H											
					H			H											
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Develop a basic knowledge on earth's atmosphere.	1&2	100	95															
CLO-2 :	Learn the different orbit bodies. & Understand the aspects of satellite injection.	1	100	95															
CLO-3 :	Know the interplanetary and missile trajectories and materials for Spacecraft.	1	100	95															

Duration (hour)		9	9	9	9	9
S-1	SLO-1	The solar system	The Many body problem – Lagrange, Jacobi identity	General aspects of satellite injections The	Two-dimensional interplanetary trajectories	Introduction to Hypersonic Aerodynamics, thin shock layers, Entropy layer, Viscous interaction, High temperature flow, Low density flow.
S-2	SLO-1	Reference frames and coordinate systems	The circular restricted three body problem	Launch Phase, The Orbit Injection Phase	Fast interplanetary trajectories	High temperature gas dynamics- Importance of high temperature flows.
S-3	SLO-1	Motion in Acceleration Reference Frames	Libration points	Satellite orbit transfer - Various cases	Three dimensional interplanetary trajectories Launch of interplanetary spacecraft	Atmospheric entry of blunt nosed body.
S-4	SLO-1	The celestial sphere	Relative Motion in the N-body problem	Orbit deviations due to injection errors	Trajectory Characteristics	Spacecraft acoustics and shock loads
S-5	SLO-1	The ecliptic, Motion of vernal equinox	The two body problem	Special and general perturbations - Cowell's Method ,	Trajectory about the target plant.6	Thermal environment and Thermal Balance
S-6	SLO-1	Precession and Equatorial Coordinates	Satellite orbits ,Relations between position and time	Encke's method	The boost phase, The ballistic phase	Thermal analysis and Thermal design
S-7	SLO-1	Sidereal time, Solar time, Standard time	Orbital elements.	Cowell's Method ,	Trajectory geometry - Optimal flights	Thermal active & passive control and thermal control coatings.
S-8	SLO-1	The earth's atmosphere.	Parameters used to describe the orientation in space	Method of variations of orbital elements	Time of flight, Reentry phase	Requirements and material selection
S-9	SLO-1	Troposphere, Stratosphere, Mesosphere, Thermosphere & Exosphere	Examples of orbits	General perturbations approach.	The position of the impact point , Influence coefficients	Spacecraft materials and composite materials.

Learning Resources	1. Sutton. G.P, "Rocket Propulsion Elements", 7th Edition, John Wiley & Sons, NewYork, 2011	4. Parker.E.R, "Materials for Missiles and Spacecraft", McGraw Hill Book Co., NewYork, 2000.
	2. Cornelisse.J.W, "Rocket Propulsion and Space Dynamics", W.H. Freeman & Co., New York, 2005	
	3. Rudolph X. Meyer., "Elements of Space Technology", Academic press, London, 2003.	
	5. Ramamurthi. K, "Rocket Propulsion", MacmillanPublishers India Ltd. 2010.	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,
SLO – Session Learning Outcome

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in, rkpearls@yahoo.com	Dr.Raju Abraham, Scientist –F, National Institute of Ocean Technology Chennai – 600 100	Mr. P.Udayakumar Assistant Professor (O.G) Department of Mechanical Engineering SRM IST
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr. R.Velraj, Professor, Institute for Energy Studies, Anna University, Chennai, India - 600025	Dr. M. Cheralathan, SRMIST

Course Code	18MEE344T	Course Name	ENERGY ENGINEERING AND MANAGEMENT	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Understand Environmental aspects of energy utilization.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand Energy conservation concepts.				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Understand concepts of energy savings in various thermal systems.																					
CLR-4 :	Energy management techniques																					
CLR-5 :	Energy economics concepts																					
CLR-6 :	Know about the importance of energy management systems and its utilization.																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1 :	Recognize the importance of energy usage as per the requirements				1&2	90	80	H	L	L	L	L	M	H	M			L				
CLO-2 :	Acquire knowledge on the energy conservations and acts				1&2	90	80	H	L	L	L	L	M	H	M	M		L				
CLO-3 :	Knowledge of the working of various heat exchangers and various energy storage systems.				1&2	90	80	H	L	L	L	L	L	H	L			L				
CLO-4 :	Recognize the cost involved for energy systems				1,2&3	90	80	H	L	L	L	L	L	M	M	H	M	H				
CLO-5 :	Implementation of energy management systems in industries				1,2&3	90	80	H	L	L	L	L	L	M	M	H	M	H				
CLO-6 :	Get the knowledge about the various energy sources and its management systems				1,2&3	90	80	H	L	L	L	L	L	H	M	H	H	L				

		Energy And Environment	Energy Conservation	Energy Savings In Thermal Systems	Energy Management	Energy Economics
Duration (hour)		09	09	09	09	09
S-1	SLO-1	Introduction to Energy and Environment	Introduction to energy conservation	Fuels and its consumption	Energy management principles.	Introduction to engineering economics
S-2	SLO-1	Represent World energy consumption	Energy conservation schemes	Energy savings in Boiler.	Energy resource management.	Costing techniques in energy engineering
S-3	SLO-1	Effect of Greenhouse gases	Industrial energy conservation methods	Firing methodology in boilers	Energy management levels.	Cost factors
	SLO-2	Global warming				Break even analysis
S-4	SLO-1	Renewable energy sources	Energy surveying for industries.	Waste heat recovery systems	Energy management information systems.	Cost optimization for energy engineering techniques
	SLO-2		Energy auditing for industries.			Optimal target investment schedule
S-5	SLO-1	Environment aspects utilization	Energy index and cost	Energy saving system in HVAC	Energy instrumentation.	Financial appraisal and profitability
S-6	SLO-1	Energy prices	Energy conservation in engineering and process industry	Energy savings in Refrigeration systems	Energy measurement in energy management	Investment decisions
S-7	SLO-1	World energy reserves	Simple case study of energy auditing in process industries	Energy Storage systems	Energy management Techniques.	Method of investment appraisal
	SLO-2					Discounted cash flow
S-8	SLO-1	World energy polices	Energy conservation in Buildings	Energy saving methodologies by using	Computerized energy management	Summary investment appraisal

	SLO-2			Insulated pipe work systems		techniques
S-9	SLO-1	The energy future and the role of renewable energy	Concept of Green building	Heat exchangers	Importance of energy management	Optimization with one variable
						Optimization with multiple variable.

Learning Resources	<ol style="list-style-type: none"> 1. Murphy.W.R and McKay G, "Energy Management", Butterworths, London, 2007. 2. Reay.D.A, "Industrial Energy Conservation", Pergamon Press, 2003. 3. Steve Doty, Wayne C. Turner, "Energy Management Handbook", Fairmont Press, 7th edition, 2009. 4. Barney L. Capehart, Wayne C. Turner, William J. Kennedy, "Guide to Energy Management", The Faimont Press, 6th edition, 2008. 5. Callaghan.P.W.O, "Design and Management for Energy Conservation", Pergamon Press, Oxford, 2003. 6. Hamies, "Energy Auditing and Conservation; Methods", Measurements, Management and Case study", Hemisphere, 2003. 7. Trivedi.P.R and Jolka.K.R, "Energy Management", Common Wealth Publication, 2002.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.M.VENKATA RAMANAN Professor Institute for Energy Studies venkat@annauniv.edu	S.PANNEERSELVAM Department of Mechanical Engineering SRM IST Email: panneerselvam.s@ktr.srmuniv.ac.in
2. Dr. A. Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in	Dr.S.KUMAR MRT TNEB CHENNAI.	Dr. M. Cheralathan, SRMIST

Course Code	18MEE345T	Course Name	TURBOMACHINES	Course Category	E	Professional elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC102T	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the basic flow concepts in turbo machines	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the performance of centrifugal flow machines.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the performance of axial flow machines	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Familiarize the performance of axial flow turbines	Expected Attainment (%)	Design & Development
CLR-5 :	Know the Working and performance of hydraulic turbines.		Analysis, Design, Research
CLR-6 :	Understand the performance and design of turbomachines.		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Acquire the knowledge on basic flow concepts in turbomachines.	1& 2 90 85	H M - - - - - - - - - - - - - - -
CLO-2 :	Appreciate the working and performance of centrifugal flow machines.	1& 2 90 85	H H - - M - - - - - - - - - - - - - - -
CLO-3 :	Analyze the working and performance of axial flow machines.	1& 2 90 85	H H - - M - - - - - - - - - - - - - - -
CLO-4 :	Recognize the working and performance of axial flow turbines	1& 2 90 85	H H - - M - - - - - - - - - - - - - - -
CLO-5 :	Analyze the working and performance of hydraulic turbines.	1& 2 90 85	H H - - M - - - - - - - - - - - - - - -
CLO-6 :	Acquire the knowledge on performance and design of turbomachines.	1& 2 90 85	- -

Duration (hour)	Basic flow concepts in turbomachines	Centrifugal flow machines	Axial flow machines	Axial flow turbines	Hydraulic turbines
	9	9	9	9	9
S-1	SLO-1	Definition, classification and stages of turbo machines	Fans - different impeller sizes, shapes, blade angles, speed and construction	Aero-Thermodynamics of flow through an Axial flow Compressor stage. Blade profile, lift and drag coefficients	Introduction: Turbine stage: Turbine blade 2-D (cascade) analysis Work done.
S-2	SLO-1	Estimation of specific work for incompressible and compressible flow machines	Blade shape, blade number, design calculations	Compressors - brief introduction to two-dimensional cascade and its application to design	Degree of reaction; Losses and Efficiency.
S-3	SLO-1	Internal and external losses, various efficiencies	Performance in series and parallel	Flow deflection and stagnation pressure loss across blade rows	Flow passage: Subsonic, transonic and supersonic turbines, Multi-staging of Turbine.
S-4	SLO-1	Representation of specific work on T-s and h-s diagrams	Compressor - slip, inducers, designs without inducer but with inlet guide vanes (IGV)	Flow passage: Subsonic, transonic and supersonic turbines, Multi-staging of Turbine.	Performance calculations considering losses in the nozzle and buckets
S-5	SLO-1	Velocity triangles - centrifugal and axial flow machine impellers	problems with inducer and IGV's - blade angles, temperature rise and static pressure rise across the impeller	Exit flow conditions: Turbine cooling	Francis turbine - reaction, impeller shapes for different shape Numbers/heads
S-6	SLO-1	Euler's energy equation across the impeller as applicable to all machines,	Vaned and vaneless diffuser and volute casing. Surging; Chocking; Rotating stall	Turbine blade design	Calculations on impeller dimensions, blade angles and performance using velocity triangles, draft tubes
S-7	SLO-1	Slip and its estimation	Design of impeller blades for free vortex and forced vortex	Turbine profiles, Testing of turbine - test rigs - standard instrumentation- operational	Kaplan / Propeller Turbine - reaction, impeller (adjustable and fixed) blades and guide blades

S-8	SLO-1	Degree of reaction	Pump - system head, priming of pumps, net positive suction head, minimum starting speed and cavitations. Testing of pumps - test rigs – standard instrumentation- operational characteristics	Design and performance calculations. Stall and surge phenomenon. Noise problem in Axial Compressors and Fans.	characteristics	
S-9	SLO-1	Blade angles and their effects, calculations considering slip.			Airfoil data and Profile construction.	Calculation of performance using velocity triangles / blade angles at different radii for free vortex flow, its suitability for low heads

Learning Resources	1. .Gopalakrishnan.G, PrithviRaj.D, "Treatise on Turbomachines", 1st Edition, Chennai, SciTech Publications, 2006. 2. .Seppo A. Korpela., "Principle of Turbomachinery", John Wiley and Sons Ltd, 2012. 3. .Yahya.S.M, "Turbines, Fans and Compressors", 3rd Edition, Tata McGraw Hill Publications, 2010.	4. .Dixon.S.L, "Fluid mechanics and Thermodynamics of Turbomachinery", 5th edition, Elsevier Butterworth Heinemann, 2005. 5. .Venkanna. B.K, "Fundamentals of Turbomachinery", 4th Edition, New Delhi, PHI Learning Pvt. Ltd, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.Ravindran S, Professor, Hindustan University Padur, Chennai E-mail: dravimepco@gmail.com	Mr. N. Vijay Krishna Assistant Professor (O.G) Department of Mechanical Engineering SRM IST Email: vijaykrishna.n@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Vanjeswaran MN, Engineer. Tata Steels Ltd, Jamshedpur Email: mechvanje@gmail.com	Mr. P. Sudhakar Assistant Professor (S.G) Department of Mechanical Engineering SRM IST Email: sudhakar.p@ktr.srmuniv.ac.in

Course Code	18MEE346T	Course Name	THERMAL POWER SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning		Program Learning Outcomes (PLO)																
CLR-1 :	Know the functions of various auxiliary combustion equipment's.				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
CLR-2 :	Understand the various Thermal power systems.				ing (Bloom)	iciency (%)	nment (%)	nowledge	ysis	elopment	gn,	sage	ure	t		eam Work	n	Finance	ining				
CLR-3 :	Analyze the performance of boiler and condenser. Familiarize with operation of cooling towers.																						
CLR-4 :	Familiarize with operation of Nuclear, Diesel and Gas turbine power plants.																						
CLR-5 :	Know the power plant economics.																						

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Familiarize with the combustion equipment of Thermal power plants.	12	90	80	H														
CLO-2 :	Familiarize with the Boilers, accessories and mountings in thermal power system.	12	90	80	H	H		M											
CLO-3 :	Familiarize with the working principle of cooling tower and condensers	12	90	80	H	H													
CLO-4 :	Familiarize with the working principle of Nuclear power plant and Diesel power plant.	12	90	80	H						M								
CLO-5 :	Familiarize with economics in power plant	12	90	80	H										L				

		Fuel Combustion	Thermal Power	Performance Of Thermal Power System	Nuclear, Diesel And Gas Turbine Power Plants	Power Plant Economics
Duration (hour)		09	09	09	09	09
S-1	SLO-1	equipmentIntroduction to power plant-Layout of Thermal power plant	Systems classification of steam generators.	Selectionof Boilers	Fuels for Nuclear power plants	Power load factor
	SLO-2	Combustion equipment's and its types.			Moderator for Nuclear power plants	Utilization factor
S-2	SLO-1	Solid fuel firing method	Working principle of high pressure boilers	Boiler capacity rating	Control rods for Nuclear power plants	Power plant cost economics
	SLO-2				Coolants for Nuclear power plant.	
S-3	SLO-1	Classification and working of stokers	Working principle of high pressure boilers	Boiler testing and performance	Types of Nuclear reactor	Tariff rates for electricity
	SLO-2			Boiler Energy Balance		
S-4	SLO-1	Fuel and ash handling system	Working principle of supercritical boilers	Condenser design factors	Boiling water reactor	Demand changes for electricity
	SLO-2				Pressurized water reactor.	Load distribution
S-5	SLO-1	Working principle of draft system its type	Working of fluidized bed boilers.	Air removal rate and performance of condenser	Radiation hazards	Effect of Variable load on plant design
	SLO-2				Radioactive waste disposal.	Energy conservation in power plant
S-6	SLO-1	Heat recovery equipments: Economiser, preheaters and reheaters	Boiler mountings	Cooling towers range and	Classification of Diesel power plant	Energy audit in power plant
	SLO-2					
S-7	SLO-1	Types of superheaters	Boiler accessories	Cooling towers approach	Components of Diesel power plant	Maintenance aspects of power plant

	SLO-2	Types of desuperheaters.	Feed water Treatment		Selection of Engine type.	
S-8	SLO-1	Emission control methods-Flue gas cleaning	Working of Condensers	Cooling towers load and performance	Closed cycle Gas Turbine plant	Maintenance aspects of power plant
	SLO-2		Types of Condensers. Factors affecting condenser. Theory and Design of Condenser		Open cycle gas turbine plant.	
S-9	SLO-1	Particulate and gaseous emission control methods.	Working of cooling towers.	Selections of condenser and cooling towers.	Combined power cycles.	Natural and global energy scenario.
	SLO-2		Types of cooling towers.Factors affecting cooling Tower			

Learning Resources	<ol style="list-style-type: none"> 1. El Wakil MM "Power plant Technology" McGraw Hill Inc 2010. 2. Nag P K " Power plant Engineering" Tata McGraw-Hill, New Delhi, 4th Edition, 2014 3. Ramalingam K K "Power plant engineering", Scitech publications Pvt Ltd, 2015 	<ol style="list-style-type: none"> 4. Arora S C and Domkundwar S "Power plant Engineering",DhanapatRai& sons, New Delhi, 2015 5. Rai G D " Non-Conventional Energy sources, "Khanna publishers, 5thEdition, New Delhi, 2014
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragirir_kalimuthu@vssc.gov.in	Dr. K Karuppasamy Assistant Professor Department of Mechanical Engineering Anna University Regional Campus Tirunelveli - 627 007	Mr. S.Malarmannan Assistant Professor, Department of Mechanical Engineering SRM IST Email: malarmannan.s@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	D.Ramesh Kumar, Shin Thermo Dynamic Engineering Private Limited Chennai-600 002 Phone:9445534340 Email: ramesh@shinthermo.co.in	Dr. M. Cheralathan Professor, Department of Mechanical Engineering SRM IST Email: cheralathan.m@ktr.srmuniv.ac.in

Course Code	18MEE347T	Course Name	SOLAR ENERGY SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18ME101T-Thermodynamics	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:		
CLR-1 :	be familiar with basics of solar radiation			
CLR-2 :	understand the working of solar collectors			
CLR-3 :	be familiar with the solar thermal energy systems and their applications			
CLR-4 :	understand the solar thermal energy storage and solar cooling systems			
CLR-5 :	be familiar with the solar photovoltaic energy conversion systems			
CLR-6 :	be familiar with the solar energy conversion systems			

Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:		
CLO-1 :	understand the fundamentals of solar radiation			
CLO-2 :	understand the basic principles of solar collector systems			
CLO-3 :	analyze and design solar thermal energy systems			
CLO-4 :	acquire knowledge on solar thermal energy storage and solar cooling systems			
CLO-5 :	acquire knowledge and analyze solar photovoltaic energy conversion systems			
CLO-6 :	acquire knowledge on solar energy conversion systems			

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H			M			M							H	
H		H											H	
H	M	H			L	H							H	
H	H		M			H							H	
H			M		M	H							H	
H			H		L	M							H	

		Solar Radiation	Solar Thermal Collectors	Design of Solar Thermal Systems	Solar Thermal Energy Storage and Solar Cooling	Solar Photovoltaic Energy Conversion
Duration (hour)		9	9	9	9	9
S-1	SLO-1	The sun and the earth, electromagnetic spectrum	Cassification of solar collectors and solar flat plate collectors	Design of solar flat plate collector systems	Need for solar thermal energy storage	Photovoltaic effect , advantages and disadvantages of solarphotovoltaic technology and classification,
S-2	SLO-1	Laws of thermal radiation	Solar evacuated tube collectors		Sensibleand latent heat storage, its advantages and disadvantages	Semiconductors, p-n junction, photo generation of charge carriers
S-3	SLO-1	Solar radiation:beam and diffuse radiations, terrestrial radiation	Advantages and disadvantages of concentrators over flat plate collectors	Problems on solar flat plate collector systems	Stratified thermal energy storage	I-V characteristics of solar cell
S-4	SLO-1	Sun and earth geometry	Solar concentrators and receiver geometries, concentrationratio	Design of solar active systems using f-chart method	PCM based solar thermal energy storage	Losses in solar cells and solar module
S-5	SLO-1	Solar angles	Compound parabolic concentrators, fresnel lens collectors	Design of solar cooker	Selection of latent heat storage materials	Maximum power point tracking in solar photovoltaic system
S-6	SLO-1	Sunrise, sunset and day length	Solar parabolic concentrators: trough systems	Solar air heater and solar dryer	Solar cooling systems and its advantages	Photovoltaic modules in series and parallel
S-7	SLO-1	Solar radiation on tilted surfaces	Solar parabolic concentrators: dish systems	Solar desalination: types, and operation	Vapour compression refrigeration systems and its solar operation	Concentrated photovoltaic cells
S-8	SLO-1	Measurement of solar radiation:	Solar central receiver system	Solar pond: types, principles and	Vapour absorption cooling systems	Temperature dependencies and multi junction

S-9	SLO-1	pyranometer Measurement of solar radiation: pyrheliometer, sunshine recorder	Solar collector orientation and sun tracking systems	applications Solar thermal power plants and solar furnace	Solar thermoelectric cooling systems	solar cells Grid connected and standalone photovoltaic system
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Learning Resources	<ol style="list-style-type: none"> 1. Duffie.J.A, & Beckman.W.A, "Solar Engineering of Thermal Processes", 3rd Edition, John Wiley & Sons, Inc., 2006 2. Sukhatme.K, Suhas P. Sukhatme, "Solar energy: Principles of thermal collection and storage", Tata McGraw Hill publishing Co. Ltd, 8th Edition, 2011. 3. Green MA. Solar cells: operating principles, technology, and system applications. Englewood Cliffs, NJ, Prentice-Hall, Inc., 2009. 4. Garg. H.P, Prakash.J, "Solar energy fundamentals and applications", Tata McGraw Hill publishing Co. Ltd, 2006. 	<ol style="list-style-type: none"> 6. Yogi Goswami.D, Frank Kreith, Jan F.Kreider, "Principle of solar engineering", Taylor and Francis, 2nd Edition, 2000. 7. Chetan Singh Solanki, "Solar Photovoltaic technology and systems: A manual for Technicians, Trainers and Engineers", PHI Learning private limited, 2013. 8. G. N. Tiwari and M. K. Ghosal, "Renewable Energy Applications", Narosa Publications, 2004.
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Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. G Kumaresan Associate Professor/Institute for Energy Studies/College of Engineering Guindy Anna University E-Mail : gkumaresan@annauniv.edu	Dr. S. Manikandan Research Assistant Professor, Department of Mechanical Engineering SRM IST Email: maniandan.su@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. SAI SANTHOSH SOMASUNDARAM Senior Designer – Solar Easi Engineering Chennai, Tamil Nadu, India E-Mail : saisanthoshsomasundaram@gmail.com	Mr. Joji Johnson Assistant Professor, Department of Mechanical Engineering SRM IST Email: joji.j@ktr.srmuniv.ac.in

Course Code	18MEE348T	Course Name	GAS TURBINE TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Approved Gas Tables are permitted		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Familiarize the functions of components of gas turbine.	1	1
CLR-2 :	Analyze the power cycles for optimum thermal performance.	2	2
CLR-3 :	Understand axial flow compressor characteristics.	3	3
CLR-4 :	Understand combustion systems and axial flow turbine operation	4	4
CLR-5 :	Familiar with the performance predictions.	5	5
CLR-6 :	Familiar with gas turbine technologies and their performances	6	6

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Appreciate the functions of components of gas turbine.	1& 2	90	80	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Appreciate the analysis knowledge of the power cycles for optimum thermal performance.	1,2,3	90	80	H	H	H	-	-	-	-	-	-	-	-	-	-	-	-
CLO-3 :	Appreciate the understanding of the axial flow compressor characteristics.	1,2, 3	90	80	H	H	H	-	-	-	-	-	-	-	-	-	-	-	-
CLO-4 :	Appreciate the understanding of the combustion systems and axial flow turbine operation	1,2,3	90	80	H	H	H	-	-	-	-	-	-	-	-	-	-	-	-
CLO-5 :	Appreciate the familiarity with the performance predictions of gas turbines.	1,2,3	90	80	H	H	H	L	L	-	-	-	-	-	-	-	-	-	-
CLO-6 :	Appreciate the familiarity with gas turbine technologies and their performances	1,2,3	90	80	H	H	H	L	L	-	-	-	-	-	-	-	-	-	-

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Definition, classification of gas turbines	Ideal cycle operation and thermal performance	Centrifugal compressor, Principle of operation, work done. Pressure rise and the diffuser	Operation requirements	Prediction performance of gas turbines component characteristics
S-2	SLO-1	Open cycle single shaft and twin shaft multi speed arrangement, Closed cycle, aircraft propulsion	Methods of determining component losses	Compressibility effects, Non dimensional quantities	type of combustion – Factors affecting combustion process, Combustion chamber performance	Off design operation and its relative performance
S-3	SLO-1	Gas turbine components and their description	Design point performance calculations, Comparative performance of actual and practical cycles.	Computerized design procedure. Axial flow compressor basic operation	Different types of combustion chambers and their relative merits and demerits	Equilibrium running of gas generator
S-4	SLO-1	Representation of specific work on T-s and h-s diagrams	Analysis of polytropic efficiency (Infinitesimal stage efficiency) of a gas turbine and Velocity triangles		Turbine construction – Performance, Impeller blade fixing	Off design operation of free turbine – Methods of displacing of the equilibrium running line
S-5	SLO-1	Comparison of steam and gas turbines	Closed cycle gas turbine and Combined cycle and Cogeneration schemes, Integrated gasification combined cycle.	Elementary theory, Factors effecting stage pressure ratio, Blockage in compressor annulus	Cooling of turbine blades – Blade vibration	Incorporation of variable pressure losses
S-6	SLO-1	Applications of gas turbine in various fields.Industrial applications of gas turbines.			Protective coating – Gas turbine turbo chargers - Power expanders	Matching procedure for two spool engines – Principle of control systems.
S-7	SLO-1	Gas Turbine in Co- Generation - Heat recovery and steam generation scheme.	Reheat, intercooling and Regenerator cycles for improved thermal performance.	Degree of reaction, Blade fixing details, Sealing materials, Material selection for compressor blades. Stage performance		

S-8	SLO-1	Gas turbine fuels and their properties	Optimum pressure ratio for maximum thermal efficiency, work ratio, air rate, effect of operating variables on thermal efficiency, work ratio, and air rate	Design and off design performance characteristics.	Vortex theory – Estimation of stage performance.	Factors influence the gas turbine performance and the improvement methods.
S-9	SLO-1	Environmental issues related to the operation and maintenance, Future of gas turbine engines and the new possibilities				

Learning Resources	<ol style="list-style-type: none"> 1. Ganesan.V, "Gas Turbines", Tata McGraw Hill, 3rd Edition, 2010. 2. Mattingly.J.D, "Elements of Propulsion: Gas turbines and Rockets", McGraw Hill, 2012 3. Yahya S.M, "Turbines, Fans and Compressors", 3rd Edition, Tata McGraw Hill Publications, 2010. 4. Irwin E. Treager, 'Gas Turbine Engine Technology', Mc Graw Hill Education, 3rd edition, 2013. 5. Saravanamuttoo. H.I.H, Rogers.G.F.C, Henry Cohen, "Gas Turbine Theory", Pearson Prentice Hall, 6th Edition, 2009. 6. Gopalakrishnan.G, Prithvi Raj D, "Treatise on Turbomachines", 1st Edition, Chennai, SciTech Publications, 2006. 7. Horlock.J.H, "Advanced Gas Turbine Cycles", Elsevier Science Ltd, 2003. 8. Venkanna.B.K, "Fundamentals of Turbomachinery", 4th Edition, New Delhi, PHI Learning Pvt. Ltd, 2011. 9. Yahya.S.M, "Gas Tables for compressible flow calculations", New Age International (P) Ltd, NewDelhi, 6th Edition, 2011
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.K. Karunamurthy, Associate Professor, School of Mechanical and Building Sciences, VIT, Chennai. Email: karunamurthy.k@vit.ac.in	Dr. R. Senthil Associate Professor Department of Mechanical Engineering SRM IST. Kattankulathur Campus. Email: senthil.r@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr.M.Periyasamy Chief Manager, NLC Limited, Neyveli.Tamil Nadu Email: mpsamy34912@gmail.com	Dr. M. Cheralathan Professor, Department of Mechanical Engineering SRM IST Email: cheralathan.m@ktr.srmuniv.ac.in

Course Code	18MEE349T	Course Name	SOLAR ENERGY UTILIZATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with basics of solar radiation data and its measurement	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with construction and operation of solar thermal energy systems	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the operation of solar thermal power plants	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with basics and design of solar photovoltaic systems	Expected Attainment (%)	Design & Development
CLR-5 :	Be exposed to the concept solar architecture in buildings and green buildings		Analysis, Design, Research
CLR-6 :	Be familiar with solar energy concepts and various applications of solar energy like thermal systems, photovoltaic systems and building architecture		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand solar radiation, solar angles and recognize and analyze the working of solar radiation measuring instruments	1&2 85 75	H M
CLO-2 :	Understand the components and working of low temperature solar thermal systems	1 85 75	M
CLO-3 :	Acquire knowledge on basic components and working of concentrated solar thermal systems for power generation	1 85 75	M
CLO-4 :	Comprehend the solar cell working and manufacturing and can design a solar system for buildings	1&2 85 75	M M
CLO-5 :	Recognize the various solar architecture in buildings and gain a basic knowledge in green buildings	1 85 75	M
CLO-6 :	Understand solar radiation and its seasonal variations along with understanding of the practical application of solar energy powered systems in the three main domains of thermal, photovoltaic and building architecture	1 85 75	M

	Solar Radiation and its measurement	Low Temperature Systems	High Temperature systems	Photovoltaics	Solar Systems for Buildings
Duration (hour)	18	18	18	18	18
S-1	SLO-1 The Sun and the Earth, Electromagnetic spectrum	Solar flat plate collectors	Solar concentrators and receiver geometries, Concentration ratio	Photovoltaic effect, Classification, Advantages and disadvantages of Solar photovoltaic technology	Need for passive architecture, Thermal comfort
S-2	SLO-1 Laws of radiation	Basic design of solar flat plate collectors, example problems	Advantages and disadvantages of concentrated collectors over non-concentrated collectors	Semiconductors, p-n junction, Photo generation of charge carriers	Sun's motion, Orientation and design of buildings
S-3	SLO-2 Solar radiation: beam and diffuse radiations, Terrestrial radiation	Solar evacuated tube collectors	Rankine power cycle	Photovoltaic cell manufacture: Czochralski, Zone refining and ribbon growth	Thermal capacity, Sensible and latent heat storage in buildings, Insulation
S-4	SLO-1 Depletion of Solar radiation in atmosphere	Domestic hot water systems: Integral collector storage, Thermosiphon system, Drain back system, Drain down system, Anti-freeze system	Compound parabolic concentrators, Fresnel lens collectors	I-V characteristics of solar cell	Solar Passive architecture : Heating of Buildings
S-5	SLO-1 Solar angles, example problems	Solar Cooker : Box type and Dish type	Solar parabolic concentrators: trough system	Losses in solar cell	Solar Passive architecture : Cooling of Buildings
S-6	SLO-1 Sunrise, sunset and day length, example problems	Solar Cooking application problems	Solar parabolic concentrators: dish system	Solar Module manufacturing	Air conditioning : Solar vapour compression refrigeration system

S-7	SLO-1	Solar radiation on tilted surfaces	Solar air heater, Solar dryer and its types	Central receiver plant / Power tower	Photovoltaic system for power generation : Standalone system and grid connected system	Air conditioning : Solar vapour absorption refrigeration system
S-8	SLO-1	Measurement of solar radiation: Pyranometer	Solar desalination, solar still design, example problems	Solar furnaces: types, principle and application	Photovoltaic system design for a building: DC system and AC system, example problems	Green buildings, Zero energy buildings, Rating systems
S-9	SLO-1	Measurement of solar radiation: Pyrheliometer, Sunshine Recorder	Solar Pond: types, principle and application	Orientation and sun tracking systems		

Learning Resources	<ol style="list-style-type: none"> 1. Duffie.J.A, &Beckman.W.A, "Solar Engineering of Thermal Processes", 4th Edition, John Wiley & Sons, Inc., 2013. 2. Sukhatme.K, Suhas P. Sukhatme, "Solar energy: Principles of thermal collection and storage", Tata McGraw Hill publishing Co. Ltd, 8th Edition, 2011. 3. Chetan Singh Solanki, "Solar Photovoltaic: Fundamentals, Technologies and Applications", PHI Learning private limited, 2015. 4. Jan F. Kreider, "The solar heating design process: active and passive systems, McGraw-Hill, 2007. 5. G.D. Rai, "Solar Energy Utilisation", Khanna Publishers, 5th Edition, 2014. 	<ol style="list-style-type: none"> 6. Yogi Goswami.D, Frank Kreith, Jan F.Kreider, "Principle of solar engineering", Taylor and Francis, 2nd Edition, 2000. Andy Walker, "Solar Energy", John Wiley & Sons, 2013. 7. Garg. H.P, Prakash.J, "Solar energy fundamentals and applications", Tata McGraw Hill publishing Co. Ltd, 2006. 8. Tiwari.G.N, "Solar energy: Fundamentals, Design, Modeling and Applications", Alpha Science International, Limited, 2013. 9. David A Bainbridge, Ken Haggard, "Passive solar architecture: Heating, Cooling, Ventilation and more use of natural flows", Chelsea Green Publishing, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragirir_kalimuthu@vssc.gov.in	Dr. G Kumaresan Associate Professor Institute for Energy Studies College of Engineering Guindy Anna University E-Mail : gkumaresan@annauniv.edu	Mr. Joji Johnson Assistant Professor, Department of Mechanical Engineering SRM IST Email: joji.j@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. SAI SANTHOSH SOMASUNDARAM Senior Designer – Solar Easi Engineering Chennai, Tamil Nadu, India E-Mail : saisanthoshsomasundaram@gmail.com	Dr. S. Manikandan Research Assistant Professor, Department of Mechanical Engineering SRM IST Email: manikandan.su@ktr.srmuniv.ac.in

Course Code	18MEE350T	Course Name	GAS DYNAMICS AND SPACE PROPULSION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC201T, 18MEC202T	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Gas Tables		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Familiarize the compressible fluid flow concepts	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the isentropic flow through variable area ducts and normal shocks.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Familiarize with the oblique shock and expansion waves	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the flow through constant area duct with friction and heat transfer	Expected Attainment (%)	Design & Development
CLR-5 :	Understand the aircraft and rocket propulsion		Analysis, Design, Research
CLR-6 :	Familiarize with the gas dynamics and space propulsion		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Analyse and evaluate the compressible flow problems	123 90 80	H H M
CLO-2 :	Analyse and solve the engineering flow problems through the nozzles and diffusers with and without Normal shock.	123 90 80	H H M
CLO-3 :	Analyse and solve problems related to oblique shock and expansion waves.	123 90 80	H H M
CLO-4 :	Analyse and solve problems related to flow through constant area ducts with friction and heat transfer..	123 90 80	H H M
CLO-5 :	Analyse and evaluate the performance of Aircraft and Rocket Engines.	123 90 80	H H M
CLO-6 :	Understand the gas dynamics and space propulsion.	123 90 80	H H M

Duration (hour)	Fundamentals of Compressible Flow	Isentropic Flow Through Variable Area Ducts	Oblique Shock And Expansion	Flow Through Constant Area Ducts	Aircraft and Rocket Propulsion
	9	9	9	9	9
S-1	SLO-1 SLO-2	Energy equation for compressible fluid flow	T-s and h-s diagrams for nozzles and diffusers	Introduction and oblique shock relations	Flow in constant area ducts with friction (Fanno flow), Fanno curves
S-2	SLO-1 SLO-2	Stagnation state and Mach number	Area ratio as a function of Mach number, Impulse function	Relation between wave angle and deflection angle	Fanno flow equations,
S-3	SLO-1 SLO-2	Various regimes of flow	Mass flow rate through nozzles and diffusers	Supersonic flow over a wedge and weak oblique Shock	Variation of flow properties (no derivation)
S-4	SLO-1 SLO-2	Reference velocities , Critical states	Problems on variable area duct	Problems on the oblique shock wave	Variation of Mach number with duct length
S-5	SLO-1 SLO-2	Problems on energy equations	Flow with normal shock – Development, governing equations	Supersonic compression and expansion, Prandtl-Meyer expansion	Flow in constant area duct with heat transfer - Rayleigh line & curves
S-6	SLO-1 SLO-2	Equivalent of Bernoulli's equation for compressible flow	Derivation of Prandtl – Meyer equation	Problems on Prandtl-Meyer expansion and compression	Rayleigh flow equations
S-7	SLO-1 SLO-2	Effect of Mach number on compressibility	Variation of flow parameters -static pressure & temperature, density, stagnation pressure and entropy across the shock (no derivations)	Detached shock waves, reflection and intersection of shocks and expansion waves	Variation of flow properties (no derivation)
S-8	SLO-1 SLO-2	Velocity of sound and wave propagation-subsonic, sonic and supersonic waves	Impossibility of shock in subsonic flows, strength of a shock wave	Problems on intersection of shocks and expansion waves	Maximum heat transfer concept

S-9	SLO-1 SLO-2	Problems on energy equations	Problems on Normal shock	Underexpanded and overexpanded nozzles	Tables and charts for Fanno flow and Rayleigh flow.	Types and applications of rocket engines
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Learning Resources	1. Yahya.S.M, "Fundamentals of Compressible Flow with Aircraft and Rocket Propulsion", New Age International (P) Ltd, New Delhi, 3rd edition, 2012. 2. Radhakrishnan.E, "Gas Dynamics", PHI Learning Pvt. Ltd, 4th edition, 2012. 3. Mattingly.J.D, "Elements of Propulsion: Gas turbines and Rockets", McGraw Hill, 2012. 4. Balachandran.P, "Fundamentals of compressible fluid dynamics", PHI Learning, 2012	5. Robert.D.Zucker, "Oscar Biblarz, Fundamentals of Gas Dynamics", John Wiley and Sons, 2nd edition, 2011. 6. Ascher H.Shapiro, "The dynamics and thermodynamics of compressible flow", R.R.Kreiger Publishers, Volume 2, 1983. Databook 7. Yahya.S.M, "Gas Tables for compressible flow calculations", New Age International (P) Ltd, New Delhi, 6th edition, 2011.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. R.Velraj, Professor, Institute for Energy Studies, Anna University, Chennai, India - 600025	Dr. P.Chandrasekaran, Associate Professor, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.Raju Abraham, Scientist –F, National Institute of Ocean Technology Chennai – 600 100	Mr.G.Manigandaraja, Assistant Professor, SRMIST

Course Code	18MEE441T	Course Name	COMPUTATIONAL FLUID DYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC101T, 18MEC105T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Be familiar with the basic governing equations of fluid mechanics and behavior of PDE.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the different discretization techniques	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Know the CFD solution techniques in compressible flow	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with incompressible fluid flow problems solution techniques	Expected Attainment (%)	Design & Development
CLR-5 :	Be familiar with the basics of turbulence modeling.		Analysis, Design, Research
CLR-6 :	Be familiar to solve fluid flow problems		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		
CLO-1 :	Understand and apply basic governing equations to different problems.	1& 2 90 85	H H H H L M
CLO-2 :	Choose and apply different discretization techniques in solving problems.	1 90 85	H H H H L H
CLO-3 :	Choosing different solution techniques to solve numerical problems.	123 90 85	H H H H L H
CLO-4 :	Solving different incompressible flow problems with appropriate pressure correction and solution techniques.	123 90 85	H H H H L H
CLO-5 :	Apply turbulence modeling in solving high Reynolds number flows	1&2 90 85	H H H H L H
CLO-6 :	Choose and apply different discretization and solution techniques to solve fluid flow problems	123 90 85	H H H H L H

		Governing Equations	Discretisation Techniques	Soluton Techniques And Numerical Methods For Compressible Flow	Finite Volume Method And Techniques For Incompressible Flow	Turbulence Modeling
Duration (hour)		9	9	9	9	9
S-1	SLO 1	Introduction, various application of computational fluid dynamics	Discretization techniques and principles	Solution techniques for linear system of equations- Gauss elimination method.	Introduction to finite volume method(FVM)	Concept of boundary layer
S-2	SLO 1	Conservation and Non conservation form of governing equations. Models of fluid flow	Finite difference method – Forward, Backward difference methods	Numerical solution – Gauss Siedel and Tri-diagonal matrix algorithm	Discretization of one dimensional steady state heat conduction convection equation using FVM	Laminar sub layer logarithmic layer Velocity defect law
S-3	SLO 1	Continuity equation derivation in all forms	Finite difference method – central difference methods	Numerical solution – Jacobie and relaxation techniques	Discretization of incompressible Naviers Stokes Equations using finite differences	Concept of turbulence, Reynolds averaging
S-4	SLO 1	Momentum equation derivation	One dimensional steady state heat conduction problem -Explicit method	Solution techniques for ordinary differential equations, Linear multistep method	Concept of staggered grid.	Time average equations for turbulent flow
S-5	SLO 1	Energy equation derivation	One dimensional steady state heat conduction problem -Implicit method	Predictor and corrector scheme – McCormack technique	Pressure correction method	Boissuniq approximation method, Types of turbulence models –
S-6	SLO 1	Different types of boundary conditions – Dirichlet, Neumann, Cauchy and Robbins boundary conditions with examples	Discretization of one dimensional wave equation	Solution of supersonic flow through converging-diverging nozzle with predictor and corrector method: Governing equations	SIMPLE algorithm and boundary conditions	Prandtl mixing length model, One-equation models
S-7	SLO 1	Classification of Partial differential equations –elliptic, parabolic, hvperbolic	Stability analysis of different equations, consistencv and convergence	Numerical method	Solution of Couette flow using SIMPLE algorithm	Two-equation models

S-8	SLO 1	Mathematical behavior of Partial differential equations - Elliptic, Parabolic equation	Problems on stability analysis	Boundary conditions, case set-up and results	Problems in Couette flow using SIMPLE algorithm	Energy cascade mechanism in turbulent flows
S-9	SLO 1	Mathematical behavior of Partial differential equations - Hyperbolic equations –well posed problems	Discussion on CFL condition	Problems in supersonic flow through converging-diverging nozzle	Alternating direction implicit method and application to unsteady two dimensional heat conduction	Comparison of merits and demerits of different turbulent models

Learning Resources	1. Anderson J.D., "Computational Fluid dynamics", McGraw Hill Int., New York, 2010. 2. Versteeg H.K., and Malalasekera W., An introduction to computational fluid dynamics, "The finite volume method", Longman, 2007. 3. Suhas.V. Patankar, "Numerical Heat Transfer and Fluid Flow", Hemisphere Publishing Corporation, 2009.	4. Muralidhar.K, and Sundararajan.T, "Computational Fluid Flow and Heat Transfer", Narosa Publishing House, New Delhi, Second Edition, 2008. 5. Ghoshdasdidar.P.S, "Computer simulation of fluid flow and heat transfer", Tata McGraw Hill Publishing Company Ltd., 1998.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr.R.Sivakumar ,Professor and Dean SMBS, VIT, Chennai	P.Sudhakar, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr.P.Sivaganga kumar,Support Manager,Siemens Industry software Computational Dynamics India(P) ltd Bengaluru	Dr.D.Siva Krishna reddy SRMIST

Course Code	18MEE442T	Course Name	ADVANCED ENGINEERING THERMODYNAMICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Engineering Thermodynamics (18MEC101T)	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Steam tables, Mollier and generalized compressibility chart		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Familiarize with entropy, exergy and thermodynamics properties.	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the relationship between thermodynamic properties	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	To attain the knowledge about chemical thermodynamics	Expected Proficiency (%)	Problem Analysis
CLR-4 :	To attain the knowledge about statistical thermodynamics	Expected Attainment (%)	Design & Development
CLR-5 :	To attain the knowledge of irreversibility in Thermodynamics		Analysis, Design, Research
CLR-6 :	To attain the knowledge of thermodynamics for various engineering systems		Modern Tool Usage
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		Society & Culture
CLO-1 :	Understand the application of exergy and entropy in various engineering devices.	1, 2, 3	Environment & Sustainability
CLO-2 :	Understand the concept of Real gas behaviour and multicomponent systems.	1, 2, 3	Ethics
CLO-3 :	Understand the concept Chemical thermodynamics and equilibrium.	1, 2, 3	Individual & Team Work
CLO-4 :	Understand the concept Statistical thermodynamics.	1, 2, 3	Communication
CLO-5 :	Understand the concept of irreversible thermodynamics.	1, 2, 3	Project Mgt. & Finance
CLO-6 :	Understand the concept of thermodynamics to various engineering systems.	1, 2, 3	Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

	Entropy, Exergy Analysis And Property Relations	Real Gas Behaviour And Multicomponent Systems	Chemical Thermodynamics And Equilibrium	Statistical Thermodynamics	Irreversible Thermodynamics
Duration (hour)	9	9	9	9	9
S-1	SLO-1	Entropy principle and its applications, Entropy transfer mechanisms phase diagram, phase changes, various properties diagram, 1st order phase transition and 2nd order phase transition	Law of corresponding states, Generalized compressibility chart, Reduced coordinate Phase transition, types of equilibrium and stability, multi-component and multi-phase systems, equations of state.	Degree of reaction, reaction equilibrium, law of mass action, heat reaction Chemical equilibrium, Thermodynamic equation for phase	Statistical thermodynamics: Introduction, energy states and energy levels
S-2	SLO-1	Exergy transfer by heat, work and mass	Stability of thermodynamic systems, Le Chatelier's Principle, Other equation of state: Vander Waals equation of state, Beattie-Bridgeman equation of state	Temperature dependence of the heat of reaction and equilibrium constant, thermal ionization of a monatomic gas	Micro and Macro state, Maxwell-Boltzmann statistics
S-3	SLO-1	Exergy destruction, exergy balance in closed and open systems	Benedict-Webb-Rubin equation of state, Virial equation of state	Gibbs function change, Fugacity and Activity, heat capacity of reacting gases in equilibrium	Sterling's approximation, Maxwell-Boltzmann distribution function
S-4	SLO-1	Exergy analysis of industrial systems: power system and refrigeration systems	Use of generalized charts for enthalpy and entropy departure	Enthalpy of formation, 1 st law for reactive system	Bose-Einstein statistics, Fermi-Dirac statistics
S-5	SLO-1	Maxwell relations, Generalized relations for changes in entropy, internal energy and enthalpy.	Fugacity coefficient, Lee-Kesler generalized three parameter tables	Adiabatic flame temperature, Enthalpy and energy of combustion	Distribution of particles over energy levels, partition function
S-6	SLO-1	General thermodynamic consideration an	Fundamental property relations for systems of	Entropy change for reactive system	Microscopic interpretation of heat and
					Thermoelectricity: Application

		equations of state, Evolution of thermodynamics properties from equation of state	variable composition.		work	of irreversible thermodynamics to a thermocouple
S-7	SLO-1	Type of equilibrium, local equilibrium condition	Partial molar properties, Real gas mixture.	Absolute entropy, third law of thermodynamics	Statistical interpretation of entropy	Uncoupled effects in thermoelectricity
S-8	SLO-1	condition of equilibrium for a heterogeneous system, Gibbs phase rule	Ideal solution of real gases and liquid, activity, equilibrium in multi-phase systems	2 nd law analysis for reactive system	Application of statistics to gases-mono-atomic ideal gas	The coupled equations of thermoelectricity
S-9	SLO-1	Condition of stability and Third law of thermodynamics	Gibbs phase rule for non-reactive components.	chemical exergy, 2 nd law efficiency of a reactive system	Principle of equipartition of energy, thermodynamics properties, specific heat of solids	Other effects in Thermocouples

Learning Resources	<ol style="list-style-type: none"> 1. Yunus, A. C., and Boles, A., "Thermodynamics-An engineering approach, 8th edition", Tata McGraw Hill-Education New Delhi, 2015. 2. Nag, P. K., "Engineering Thermodynamics", 5th edition, Tata McGraw Hill education New Delhi, 2013. 3. Bejan, A., "Advance Engineering Thermodynamics, 3rd edition, John Wiley and sons, 2006. 	<ol style="list-style-type: none"> 4. Smith, J. M. etal, "Introduction to chemical engineering thermodynamics" Tata McGraw Hill, 2005 5. Puri, I. K., and Annamalai, K., "Advance Engineering Thermodynamics", CRC Press, 2001.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Expert from Industry	Experts from Higher Technical Institute	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	1. Dr. Laltu Chandra Indian Institute of Technology (BHU)	1. Dr. Piyush Sharma, Asst. Prof.
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr. Amit Gupta (ABSTC) Aditya Birla Science and Technology Company	Dr. Pankaj Kumar Research Asst. Prof.

Course Code	18MEE443T	Course Name	ADVANCED FLUID MECHANICS	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Courses	Fluid Mechanics (18MEC102T)	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards			

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Familiarize with fundamental fluid flow pattern	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Be familiar with the concept of potential flow	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	To attain the knowledge about the exact solution of Navier-Stokes Equations	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Be familiar with laminar boundary layers, turbulent flows, turbulence modeling and equations, Basic discretization method	Expected Attainment (%)	Design & Development
CLR-5 :	To attain the knowledge of the various types of flow stability theory		Analysis, Design, Research
CLR-6 :	Be familiar with the applications of N-S equation in internal and external flows		Modern Tool Usage
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		Society & Culture
CLO-1 :	Analyze the different flow patterns, difference in rotational and irrotational flow, Stream and velocity potential function.	1, 2, 3	Environment & Sustainability
CLO-2 :	Acquire knowledge on Source and Sink; Vortex flow, Doublet, Superposition of basic plane potential flows	1, 2, 3	Ethics
CLO-3 :	Understand the basic calculations for force and momentum calculations using N-S equations, understand the Couette flows, Poiseuille flows	1, 2, 3	Individual & Team Work
CLO-4 :	Understand the Integral form of boundary layer equations, Turbulent boundary layer equation, major turbulence modeling, finite element method, finite volume method	1, 2, 3	Communication
CLO-5 :	Understand the concept of the Linear Stability theory	1, 2, 3	Project Mgt. & Finance
CLO-6 :	Able to apply and solve N-S equation for different flow conditions.	1, 2, 3	Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

	Analyze the different flow patterns, difference in rotational and irrotational flow, Stream and velocity potential function	Acquire knowledge on Source and Sink; Vortex flow, Doublet, Superposition of basic plane potential flows	Understand the basic calculations for force and momentum calculations using N-S equations, understand the Couette flows, Poiseuille flows	Understand the Integral form of boundary layer equations, Turbulent boundary layer equation, major turbulence modeling, Discretization	Understand the concept of the Linear Stability theory
Duration (hour)	9	9	9	9	9
S-1	SLO-1 Continuity Equation, Streamlines, and Stream Function	Uniform flow, source flow, sink flow	Solutions to the Steady-State Navier-Stokes Equations	Boundary layer on a flat plate	Concept of small-disturbance stability,
S-2	SLO-1 Vorticity and Circulation	Free vortex flow	Problems based on Steady-State Navier-Stokes Equations	Similarity solutions, Integral form of boundary layer equations Approximate Methods	Linear Stability Theory of Fluid Flows
S-3	SLO-1 Problem based on vorticity and circulation	Super imposed flow, source and sink pair	Poiseuille Flow in a Rectangular Conduit	General equations of turbulent flow, Turbulent boundary layer equation	Orr-Sommerfeld equation,
S-4	SLO-1 Irrotational Flows and the Velocity Potential	Doublet	Couette Flow Between Concentric Circular Cylinders	Flat plate turbulent boundary layer	Boundary layer stability
S-5	SLO-1 Problems based on irrotational Flows and the Velocity Potential	Flow past a Rankine oval body	Creeping flows	Turbulent Models-zero, one and two	Thermal Instability
S-6	SLO-1 Lagrangian and Eulerian description	doublet in a uniform flow	Fully developed flows in non- circular cross-sections	Prandtl mixing hypothesis,	Transition to turbulence
S-7	SLO-1 Reynolds transport theorem	Flow past a cylinder with circulation	Unsteady Flows: Impulsive Motion of a Plate—Stokes's First Problem	Basic discretization – Finite difference method	Inviscid stability theory

S-8	SLO-1	Derivation of continuity and momentum equations using Reynolds transport theorem	Magnus effect; Kutta-Joukowski lift theorem	Oscillation of a Plate—Stokes's Second Problem	Finite volume method	Problems based on Navier-Stoke's equation for steady incompressible flows
S-9	SLO-1	Problem based on Reynolds transport theorem	Concept of lift and drag.	Flow in Convergent and Divergent Channels	Finite element method	Favorable and adverse pressure gradients, flow separation

Learning Resources	1. Graebel. W.P, "Advanced Fluid Mechanics", 1st Edition, Academic Press, Elsevier Inc., 2007 2. Muralidhar and G. Biswas, "Advanced Engineering Fluid Mechanics", 3rd Edition, Narosa Publishers, 2015 3. Stevan A Jones, "Advanced Methods for Practical Applications in Fluid Mechanics", InTech Publishers, 2012	4. Kundu P., Cohen I and Dowling D, "Fluid Mechanics" 6 th edition, 2015 5. Schlichting H., K. Gersten, Boundary Layer Theory, 8/e, Springer 2000
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Expert from Industry	Experts from Higher Technical Institute	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. Dhiman Chatterjee, Professor, Dept. of Mechanical Engineering, IIT Madras	1. Dr. Pankaj Kumar
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	1. Dr Parag Deshpande, senior scientist, NAL	Dr. M. Cheralathan, SRMIST

Course Code	18MEE444T	Course Name	DESIGN OF PUMPS AND TURBINES	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC102T	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																														
					1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15																
CLR-1 :	Acquire the knowledge on basic flow concepts in turbines and pumps				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3																
CLR-2 :	Understand the design principles of simple radial flow pumps							H															H	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-3 :	Know the design principles of various turbines							H															H	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-4 :	Understand the phenomenon of cavitation in hydraulic machines							H															H	H	M	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-5 :	Know the hydro machine applicability from the cavitation point of view.							H															H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLR-6 :	Familiarize with the performance and design of turbines and pumps							H															H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																																				
CLO-1 :	Appreciate the basic flow concepts in turbines and pumps.				1&2	90	85																															
CLO-2 :	Know the design principles of simple radial flow pumps				1	90	85																															
CLO-3 :	Appreciate the design principles of various turbines				123	90	85																															
CLO-4 :	Familiarize with the effects of cavitation in hydraulic machines				123	90	85																															
CLO-5 :	Become familiar with hydro machine applicability from the cavitation point of view.				1&2	90	85																															
CLO-6 :	To solve practical fluid flow problems in turbines and pumps				123	90	85																															

Duration (hour)		Basic principles of fluid machinery	Theory of Pumps	Design of pumps	Theory and design of turbines	Cavitation
		9	9	9	9	9
S-1	SLO 1	Definition, classification and stages of turbines and pumps	Introduction to mixed flow centrifugal pumps	Design procedure for pumps	Theory of turbines , specific speed, Euler's turbine equation	Introduction to cavitation
S-2	SLO 1	Basic equations of energy transfer between the fluid and the rotor	Calculation of thrust In mixed flow centrifugal pumps	Thermal design of pumps -	Introduction to Pelton wheel (impulse turbine) - single jet and multiple jet units	Cavitation in pumps
S-3	SLO 1	Performance characteristics of various turbines and pumps	Impellers, Pump casings – volute casing and vortex casing	Selection of materials for withstanding high temperature and corrosive fluids	Velocity diagrams at the inlet and exit of the buckets	Cavitation in turbines
S-4	SLO 1	Dimensional analysis	Velocity diagrams for mixed flow centrifugal pumps	Hydraulic design of pumps	Performance calculations considering the losses in the nozzle and the buckets	Thomas cavitation factor
S-5	SLO 1	Dimensionless parameters in turbines and pumps	Calculation of work input to mixed flow centrifugal pumps	Selection of the impeller for pumps	Introduction to reaction turbine (mixed flow and axial flow) and Degree of reaction	Net positive suction head (NPSH)
S-6	SLO 1	Specific speed in turbines and pumps	Head, Losses and efficiency of mixed flow centrifugal pumps	Calculation of casing dimension	Francis turbine – Velocity diagrams and Design procedure	Effects of cavitation on the performance of turbines and pumps
S-7	SLO 1	Velocity triangles of a stage	Specific speed, Power requirement and operating characteristics	Introduction to computer programs for iterative and interactive design	Introduction to Kaplan / Propeller Turbine – axial flow reaction type	Cavitation – damage to equipments
S-8	SLO 1	Calculation of work output of turbine	Minimum starting speed of centrifugal pump	System head, Net positive suction head,	Velocity diagrams and design procedure for Kaplan turbine	Design considerations to avoid cavitation
S-9	SLO 1	Computation of efficiency	Multi stage pump	Priming of pumps	Governing of turbines	Cavitation and energy harvesting
Learning	1.	Dixon.S.L, "Fluid Mechanics and Thermodynamics of Turbomachinery", 6th Edition, Butterworth			4.	Seppo A. Korpela., "Principle of Turbomachinery", John Wiley and Sons Ltd, 2012

Resources	2. Heinemann, U.K., 2010	5. Yahya.S.M, "Turbines, Fans and Compressors", 3rd Edition, Tata McGraw Hill Publications, 2010
	3. Viktor Gelpke, "Hydraulic turbines their design and installation", Research press, 2010	6. Venkanna. B.K, "Fundamentals of Turbomachinery", 4th Edition, New Delhi, PHI Learning Pvt. Ltd, 2011.

Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr K KARUNAMURTHY Associate Professor School of Mechanical and Building Sciences VIT Chennai	Mr. S.Bharath Subramaniam, Assistant Professor, SRMIST
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr. Udhayakumar Balaji Senior Piping Engineer Petrofac Engineering services India ltd	Dr. M. Cheralathan, SRMIST

Course Code	18MEE445T	Course Name	THERMAL ENERGY STORAGE SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC101T-Thermodynamics	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Familiarize with the techniques used for storing various forms of energy	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Understand the sensible thermal energy storage systems and materials	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand the latent and thermochemical energy storage systems.	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Understand the properties of storage materials and heat transfer fluids	Expected Attainment (%)	Design & Development
CLR-5 :	Know the various techniques used for storing thermal energy in heating/cooling applications and energy savings		Analysis, Design, Research
CLR-6 :	Be familiar with the Thermal energy storage systems and its applications.		Modern Tool Usage
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:		Society & Culture
CLO-1 :	Familiarize with the techniques used for storing various forms of energy	1 90 80	Environment & Sustainability
CLO-2 :	Understand the sensible thermal energy storage, material and methodology	12&3 90 80	Ethics
CLO-3 :	Understand the latent and thermochemical energy storage systems.	12&3 90 80	Individual & Team Work
CLO-4 :	Understand the properties of storage materials and heat transfer fluids	1&2 90 80	Communication
CLO-5 :	Know the various techniques used for storing thermal energy in heating/cooling applications and energy savings	1&2 90 80	Project Mgt. & Finance
CLO-6 :	Be familiar with various techniques used for storing thermal energy in heating/cooling applications and energy savings	12&3 90 80	Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Duration (hour)	Energy Storage	Sensible Thermal Energy Storage Systems	Latent Thermal And Thermochemical Energy Storage Systems	Thermal Energy Storage Materials	Thermal Storage Applications And Energy Savings
9	9	9	9	9	9
S-1	SLO-1	Basics of Energy storage and its types	Sensible Thermal Energy Storage (STES) system and its types	Latent Thermal Energy Storage (LTES) system and its types	Thermal energy storage materials - Classification, thermophysical properties
S-2	SLO-1	Energy storage by mechanical medium	Selection of sensible thermal energy storage materials and methodologies	Types and properties of latent heat storage materials and cooling/Heating load calculations	Various methods to improve the thermophysical properties of PCM
S-3	SLO-1	Energy storage by chemical medium	Properties of sensible heat storage materials	Encapsulation techniques of LTES (PCM) materials	selection criteria for thermal energy storage materials
S-4	SLO-1	Low and Medium temperature thermal storage systems	Sensible cooling and heating load calculations	Performance assessment of LTES system in building	Phase Change Materials – classifications and properties
S-5	SLO-1	High temperature thermal storage systems	STES Technologies, storage tanks using water and rock bed thermal storage	Passive and active LTES systems	PCM selection for heating and cooling applications
S-6	SLO-1	Necessity of TES, types of TES technologies and Comparison of thermal energy storage technologies	Solar pond thermal storage and building structure thermal storage	Thermochemical energy storage principles and materials	Heat transfer fluids and properties

S-7	SLO-1	Seasonal thermal energy storage Principle	Passive solar heating storage	Thermochemical energy storage systems - open adsorption energy storage system and closed adsorption energy storage system	Selection of heat transfer fluid for heating and cooling applications	TES and Energy Savings - utilization of waste or surplus energy, reduction of demand charges and deferring equipment purchases
S-8	SLO-1	Seasonal (Source) TES technologies - aquifer thermal storage, borehole thermal storage and cavern thermal storage	Active solar heating storage	Closed absorption energy storage system solid/gas, thermochemical energy storage system and thermochemical accumulator energy storage system	Measuring instruments for thermophysical properties	Additional energy savings considerations for TES
S-9	SLO-1	Earth-to-air thermal storage, energy piles thermal storage, sea water thermal storage, rock thermal storage and roof pond thermal storage	High temperature Sensible Thermal Energy Storage system	Floor heating system using thermochemical energy storage and thermochemical energy storage for building heating applications	Necessity of improving thermophysical properties	Case studies for TES energy savings

Learning Resources	<ol style="list-style-type: none"> 1. R. Parameshwaran and S. Kalaiselvam, "Thermal Energy Storage Technologies for Sustainability: Systems Design, Assessment and Applications", Academic Press Inc, 23 September 2014. 2. Ibrahim Dincer and Marc A. Rosen, "Thermal Energy Storage Systems and Applications", 2nd Edition, John Wiley and Sons Ltd., 2011. 3. Luisa F. Cabeza, "Advances in Thermal Energy Storage Systems: Methods and Applications", October 31, 2014 4. Charles E. Dorgan, James S. Elleson, "Design Guide for Cool Thermal Storage", ASHRAE, Atlanta, 1993. 5. R. Velraj "Sensible heat Storage for solar heating and cooling systems" in the book titled "Advances in Solar Heating and Cooling - Pages 399 - 428, Elsevier Publication, 2016 6. ASHRAE, "Handbook of Fundamentals", American Society of Heating Refrigeration and Air Conditioning Engineers, New York, 1993. 7. Alternate fuels for IC Engines: Liquid fuels, Gaseous fuels - properties, advantages and disadvantages, Emissions from engines – Emission standards – Euro, BS
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	Experts from Higher Technical Institutions	Internal Experts
Experts from Industry		
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	VELRAJ R Professor Institute for Energy Studies, Anna University Chennai 600 025 Email: velraj@annauniv.edu	Mr. A.Sathishkumar Assistant Professor, Department of Mechanical Engineering SRM IST Email: sathishkumar.a@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Raju Abraham, Sc-F National Institute of Ocean Technology Chennai 600 100 Ph 044-6678 3339 Email: abraham@niot.res.i	Dr. M. Cheralathan Professor, Department of Mechanical Engineering SRM IST Email: cheralathan.m@ktr.srmuniv.ac.in

Course Code	18MEE446T	Course Name	Design of Heat exchangers	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	Heat and mass Transfer	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Gain knowledge on the basics of Heat Exchanger	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15		
CLR-2 :	Familiarize with Design Aspects of heat exchangers																							
CLR-3 :	Acquire the basic skills acquired to design the double pipe and shell and tube heat exchangers																							
CLR-4 :	Acquire the basic skills acquired to design the compact and plate heat exchangers																							
CLR-5 :	familiarize with the condensers and evaporators																							
CLR-6 :	familiarize with the design of heat exchangers																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	understand the fundamentals of heat exchanger	1	2	3	90	85																		
CLO-2 :	Understand the various design aspects of heat exchangers	1	2	3	90	85																		
CLO-3 :	Evaluate the design of double pipe and shell and tube heat exchangers	1	2	3	90	85																		
CLO-4 :	Evaluate the design of compact and plate type heat exchangers	1	2	3	90	85																		
CLO-5 :	Familiarize with design of various types of condensers and evaporators	1	2	3	90	85																		
CLO-4 :	To understand with the design of heat exchangers	1	2	3	90	85																		

		Fundamentals Of Heat Exchanger	Design Aspects Of Heat Exchangers	Double Pipe Heat Exchangers And Shell & Tube Heat Exchangers	Compact And Plate Heat Exchanger	Condensers And Evaporators
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction, classification of heat exchangers, Recuperator and Regenerator	Introduction, effect of turbulence,	Introduction, Thermal design and analysis of inner tube and outer tube	Classification of compact heat exchangers, Merits and Demerits of Compact heat exchangers	Types of Condensers,
S-2	SLO-1	Geometry of Construction, Tubular, Plate heat exchangers	Effect of friction factor, pressure drop in tube side,	hydraulic design and analysis of inner tube and outer tube	Design of compact heat exchangers	Design of surface condensers- Down-flow
S-3	SLO-1	Effect of Extended Surface Heat Exchangers Heat transfer Mechanisms,	Effect of Pressure drop in tube bundles.	Design of Double Pipe Heat Exchangers- parallel flow & counter flow-problems	Factors affecting of compact heat exchangers	Types of Condensers, Design of surface condensers- Central-flow
S-4	SLO-1	Flow arrangements, Application, Selection of Heat Exchangers.	Heat Transfer and pumping power relationship	Design of Double Pipe Heat Exchangers- cross flow heat exchanger-	Design of plate heat exchangers	Design of evaporative condensers- Inverted flow & Regenerative
S-5	SLO-1	Overall Heat transfer coefficient, LMTD method for Heat Exchanger analysis for parallel flow heat exchanger	Pressure Drop in Bends and fittings	Basic components of shell & tube heat exchangers	Factors affecting Design of plate heat exchangers	Design of evaporative condensers
S-6	SLO-1	Overall Heat transfer coefficient, LMTD method for Heat Exchanger analysis for COUNTER flow heat exchanger	Effect of fins arrangement ant its geometry on heat transfer	Design of shell & tube heat exchangers	Operational characteristics of plate heat exchanger	Types of Evaporators,
S-7	SLO-1	Overall Heat transfer coefficient, LMTD method for Heat Exchanger analysis for CROSS heat exchanger	Fouling of Heat exchangers, effect on heat transfer	Factors affecting in shell & tube heat exchangers	flow arrangements in plate heat exchangers	calculation of Evaporator surface and multiple evaporator

S-8	SLO-1	ϵ NTU method for Heat Exchanger analysis	Problems in pressure drop and fouling in Heat exchangers	Shell side heat transfer. Pressure drop	Heat transfer and pressure drop calculations	calculation of Evaporator multiple effect
S-9	SLO-1	Heat Exchanger design considerations - Material requirement Design codes and its requirement	Factors affecting performance of HE/PHE/Condensers/Evaporator	Problems on design of shell and tube heat exchangers and its applications	Applications of compact and plate heat exchanger	Factors affecting in condensers and evaporators of heat changers

Learning Resources	1. SadikKakac and Hongtan Liu, "Heat Exchangers Selection, Rating and Thermal Design", CRC Press,2002 2. Kern D.Q, "Process Heat Transfer", Tata McGraw Hill , 1997, Reprint 2008 3. Ramesh K. Shah, "Fundamentals of Heat Exchanger Design", John Wiley & Sons,2003 4. Arthur. P Frass, "Heat Exchanger Design", John Wiley & Sons, 1988.	5. Taborek.T, Hewitt.G.F and Afgan.N, "Heat Exchangers, Theory and Practice", McGraw-Hill Book Co.2018 6. Kuppan T, "Heat Exchanger design handbook", Marcel Dekker INC, 2000. 7. Standards of Tubular Exchanger Manufacturers Association(TEMA), 9th Edition,2007 – www.tema.org 8. Wolverine Heat Transfer Data book – III by Wolverine Tube Inc.,
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Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers	Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in		Dr. K Karuppasamy Assistant Professor Department of Mechanical Engineering Anna University Regional Campus Tirunelveli - 627 007	Mr. G.Manikandaraja Assistant Professor, Department of Mechanical Engineering SRM IST Email: manikandaraja.g@ktr.srmuniv.ac.in
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cwrde.drdo.in		K.Pasupathi Deputy manager – mechanical- AQUATHERM Engineering Consultants(India) Pvt. Ltd.,	Mr. S. Malarmannan Assistant Professor, Department of Mechanical Engineering SRM IST Email: malarmannan.s@ktr.srmuniv.ac.in

Course Code	18MEE447T	Course Name	COMBUSTION ENGINEERING	Course Category	E	Professional elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	18MEC101T Thermodynamics	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Acquire the fundamental knowledge of combustion
CLR-2 :	Gain knowledge on thermodynamics of combustion
CLR-3 :	Understand the kinetics of combustion
CLR-4 :	Understand the types of flames
CLR-5 :	Familiarize with combustion aspects in SI and CI engines
CLR-6 :	Acquire knowledge on combustion reactions and its stages in internal combustion engines

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
1&2	90	80
1	90	80
1	90	80
1&2	90	80
1&2	90	80
1	90	80

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Acquire the knowledge of combustion equations for different air fuel ratios
CLO-2 :	Analyze combustions based on first law and second law of thermodynamics in reacting systems
CLO-3 :	Evaluate the kinetic of combustion and reaction order and its theory
CLO-4 :	Acquire the knowledge of flames characteristics and its types
CLO-5 :	Understand the stages of combustion in SI and CI engines and acquire knowledge with normal and abnormal combustion.
CLO-6 :	Understand the emission norms and its control method

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	M												H	
H	H												H	
H	H		M										H	
H	H		M										H	
H													H	
H						H							H	

Duration (hour)		Combustion Of Fuels	Thermodynamics Of Combustion	Kinetics Of Combustion	Flames	Engine Combustion
		9	9	9	9	9
S-1	SLO-1	Combustion engineering and its importance	Thermo-chemistry first law analysis of reacting systems	Rates of reaction	Different types of flames Laminar and turbulent	Combustion in SI and CI engines
S-2	SLO-1	Combustion behavior with different air composition	To understand the reacting system and calculations on first law of thermodynamics	Determination of rates of reaction	Premixed and diffusion flames	Stages of combustion in SI and CI engines,
S-3	SLO-1	Combustion equations for Theoretical air	Acquire knowledge on Adiabatic combustion Temperature	Reaction order and molecularity complex reactions	Laminar Jet Flame Height – Turbulent flame Lift-Off Height and Blowout Limit.	Advanced techniques of combustion in IC engines-learn burn engine –HCCI engine
S-4	SLO-1	Combustion equations for excess air	Adiabatic combustion Temperature calculations	Determination of reaction order and molecularity complex reactions	Fuel burning velocity, Determination of Burning velocity, Factors affecting burning velocity	Normal combustion and abnormal combustion
S-5	SLO-1	Proper Air fuel ratio for combustion	Second law analysis of reacting systems	Chain reactions - Arrhenius rate equation, collection theory	Droplet Evaporation and Combustion	Emission norms in Heavy duty and light duty vehicles and its standards BS and Euro norms
S-6	SLO-1	Equivalence Ratio	Criterion for chemical Equilibrium	Calculation on Chain reactions - Arrhenius rate equation, collection theory	Flame Quenching, flammability	Emissions from premixed combustion
S-7	SLO-1	Exhaust gas composition	Determination of equilibrium constant for gaseous mixtures	Activated complex theory	Flame by ignition	Emission from non-premixed combustion
S-8	SLO-1	Air fuel ratio from exhaust gas composition	Evaluation of equilibrium composition	Explosive and general oxidative	Flame stabilization in open burners	Reasons of HC, sulphur , PM, NO _x and CO emissions in engines
S-9	SLO-1	Heating value of fuels	Chemical availability	Characteristics of fuels on Explosive and general oxidative	Methods to stabilize the flame in open burner	Control of HC, sulphur , PM, NO _x and CO emissions in engines

Learning Resources	1. Stephen.R.Turns, "An Introduction to Combustion concepts and applications", 2nd Edition, McGraw Hill Book Company, Boston, Edition 3,2011.	5. Thipse.S.S, "Alternate Fuels", Jaico Publication House., 2010.
	2. Ganesan.V, "Internal Combustion Engines", Tata McGraw-Hill, New Delhi,2009.	6. Mathur.M.L, and Sharma.R.P, "A course in Internal Combustion Engines",Dhanpat Rai & Sons, New Delhi, 2010.
	3. Ramalingam.K.K, "Internal Combustion Engines - Theory and practice",SciTech Publications India Pvt. Ltd., Chennai, 2010.	7. Heywood.J.B, "Internal Combustion Engine Fundamentals", McGraw Hill International, New York, 2008.
	4. Thipse.S.S, "Internal Combustion Engines", Jaico Publication House, 2010.	8. Domkundwar.V.M, "A course inInternal Combustion Engines", Dhanpat Rai & Sons, 2010.

Learning Assessment

	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. K.KarunamurthyAssociate Professor, Department of Mechanical Engineering VIT –Chennai campus	Mr. M.Sivashankar Assistant Professor, Department of Mechanical Engineering SRM IST –KTR campus
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Mr.P.Balaji Manager Product Development HVAC Division Ashok LeylandChennai	Dr. M. Cheralathan, SRMIST

Course Code	18MEE448T	Course Name	SUSTAINABLE ENERGY SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	NIL	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)														
CLR-1 :	be familiar with the energy scenario	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	be familiar with environmental impact of energy generation				Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3			
CLR-3 :	understand the various energy conservation options and measures				H						M											
CLR-4:	be familiar with the energy policies				H						H											
CLR-5:	be familiar with the sustainable development and life-cycle analysis				H						H											
CLR-6:	be familiar with energy conservation, policies and sustainability of energy systems.				H						M											
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:			1&2	90	80	H						M								
CLO-1 :	acquire knowledge on the energy scenario.	1,2&3	90	80	H									H								
CLO-2 :	acquire knowledge on environmental impact of energy generation	1,2&3	90	80	H									H								
CLO-3 :	acquire knowledge on basic the energy conservation measures	1	90	80	H									H					L			
CLO-4:	understand the basic energy policies	1	90	80	H									H					L			
CLO-5:	acquire knowledge on basic the sustainable development and life-cycle analysis	1,2&3	90	80	H									H					L			
CLO-6:	acquire knowledge on energy conservation, policies and sustainability of energy systems.	1,2&3	90	80	H									M								

Duration (hour)		Energy scenario	Environmental impact of energy generation and utilization	Energy conservation	Sustainable development and Energy policies	Life-cycle assessment and Ecology
9		9	9	9	9	9
S-1	SLO-1	Basics of sustainability and sustainable energy sources	Global warming and acid precipitation,	Energy conservation measures	Sustainable energy strategies	General description of LCA
S-2	SLO-1	Introduction to conventional energy resources	Analysis of modeling of earth's climate,	Improvement Factors of Energy Conservation	Key expectations from implementation of green energy strategies and policies	LCA methodology
S-3	SLO-1	Introduction to non-conventional energy resources	Radiation balance of earth planet	Energy conservation case studies	Interdependence of the factors affecting sustainable development	Energetic life-cycle analysis
S-4	SLO-1	World energy scenario – Conventional energy sources.	Greenhouse gases and radiative forcing Concept	Energy management-understanding energy costs, Bench marking, Energy performance	Modeling instruments and case studies	
S-5	SLO-1	World energy scenario – Non-Conventional energy sources.	Global warming potentials	Energy management policies	Sustainable assessment of solar energy	LCA of solar PV and thermal systems
S-6	SLO-1	Indian energy scenario – Conventional energy sources.	Anthropogenic effect on climate and its control	Energy conservation in thermal systems	Sustainable assessment of fossil fuel	LCA of hydrogen-fuel cell vehicles
S-7	SLO-1	Indian energy scenario – Non-Conventional energy sources.	Impact of energy efficiency	Energy conservation in electrical systems	fossil fuel combustion	LCA of gasoline vehicles
S-8	SLO-1	Energy forecasting	other environmental impact aspects and cogeneration	Introduction to energy audit	Assessment of green energy strategies	Case study, comparative LCA of hydrogen-fuel cells vs gasoline

S-9	SLO-1	Energy security	Problems in cogeneration	Case study in energy audit	Green energy-based sustainability ratio	vehicles Case study, comparative LCA of conventional and alternative vehicles
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Learning Resources	1. Dincer, C. Zamfirescu, "Sustainable Energy Systems and Applications", Springer, 2012. 2. Frank Kreith, Susan Krumdieck, "Principles of Sustainable Energy Systems", 2nd Edition, Taylor & Francis, 2014. 3. Muthu, Subramanian Senthilkannan, "Social Life Cycle Assessment An Insight", Springer, 2015.	4. Demirel, Yaşar, "Energy Production, Conversion, Storage, Conservation, and Coupling", Springer, 2016. 5. https://beeindia.gov.in/sites/default/files/1Ch1.pdf 6. http://www.mospi.nic.in/sites/default/files/publication_reports/Energy_Statistics_2017r.pdf
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.R.Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	Dr. R.Velraj, Professor, Institute for Energy Studies, Anna University, Chennai, India - 600025	S. Arul Kumar, SRMIST.
2. Dr.A.Velayutham, DRDO, Avadi, velayudham.a@cvrde.drdo.in	Dr.Raju Abraham, Scientist –F, National Institute of Ocean Technology Chennai – 600 100	Dr.S. Manikandan, SRMIST.

Course Code	18MEE449T	Course Name	FUEL CELL TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Nil	Co-requisite Courses	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	Nil		

Course Learning Rationale (CLR):		The purpose of learning this course is to learn:			Learning			Program Learning Outcomes (PLO)														
CLR-1:	The basics of fuel cell technology				1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2:	The concepts of fuel cell electrochemistry				Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3:	The major types of fuel cells and their modes of operation																					
CLR-4:	The methods of production, storage and utilization of hydrogen as a fuel																					
CLR-5:	The application of fuel cells in power cogeneration																					
CLR-6:	The Safety issues and cost expectation																					
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																				
CLO-1:	Understand the basics of fuel cell and fuel cell thermodynamics				1&2	90	80	H														
CLO-2:	Understand the fuel cell electrochemistry&Implications and use of fuel cell polarization curve.				1&2	90	80	H						H								
CLO-3:	The major types of fuel cells and their modes of operation such as Polymer electrolyte membrane fuel cell,Direct methanol fuel cells,Alkaline fuel cell,Molten Carbonate fuel cell&Solid oxide fuel cell				1&2	90	80	H						H								
CLO-4:	The methods of production, storage and utilization of hydrogen as afuel				1&2	90	80	H														
CLO-5:	The methods of production, storage and utilization of hydrogen as afuel				1&2	90	80	H														
CLO-6:	Understand the Fuel Processor &Safety issues and cost expectation				1	90	80	H						H								

		Introduction to Fuel Cells And Fuel Cell Thermodynamics	Fuel Cell Electrochemistry	Types Of Fuel Cells	Hydrogen Production, Storage And Utilization	Application Of Fuel Cells In Power Cogeneration
Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction and overview of fuel cell technology: A simple fuel cell, fuel cell advantages and disadvantages	Fuel cell reaction kinetics	Classification of fuel cells	Hydrogen: Its merit as a fuel, Production methods: from fossil fuels, electrolysis, thermal decomposition	Fuel cell power plant, Balance of fuel cell power plant.
S-2	SLO-1	Basic fuel cell operation, Layout of a Real Fuel Cell: The Hydrogen–Oxygen Fuel Cell with Liquid Electrolyte.	Introduction to electrode Kinetics.	Polymer electrolyte membrane fuel cell (PEMFC)	Production method from photochemical.	Fuel cell power plantstructure.
S-3	SLO-1	Difference between fuel cell and batteries, fuel choice.	Electro Chemical Energy Conversion – Factors affects Electro Chemical Energy Conversion.	Direct methanol fuel cells (DMFC)	Production method from photocatalytic, hybrid.	Cogeneration
S-4	SLO-1	Overview of types of fuel cells (with emphasis on PEMFC and DMFC technology)	Conversion of chemical energy to electricity in a fuel cell	Alkaline fuel cell (PAFC)	Hydrogen storage methods: Onboard hydrogen storage.	Benefits and Drawbacks of fuel cell power plant.
S-5	SLO-1	Fuel cell thermodynamics: Thermodynamics review, Application of first and second law to fuel cells	Reaction rate	Molten Carbonate fuel cell (MCFC)	Chemical storage & physical storage.	Fuel cell electric vehicles.
S-6	SLO-1	Heat Potential of a fuel: Enthalpy of reaction,	Butler -Volmer equation.	Solid oxide fuel cell (SOFC)	In metal and alloy hydrides.	Motor cycles and bicycles, airplanes

S-7	SLO-1	Work potential of a fuel: Gibbs free energy Predicting reversible voltage of a fuel cell under nonstandard-state conditions.	Fuel cell charge	Comparison of fuel cell,	Carbon nanotubes.	Fueling stations.
S-8	SLO-1	Basic Parameters of Fuel Cells. Fuel cell efficiency.	Mass transport.	Performance behavior	Glass capillary arrays - pipeline storage and hydrogenutilization.	Fuel processor and fuel cell stack.
S-9	SLO-1	Basic Parameters of Fuel Cells. Fuel cell efficiency., Comparison with Carnot efficiency.	Implications and use of fuel cell polarization curve.	Proton Exchange Membrane Fuel Cells.	Glass capillary arrays - pipeline storage and hydrogenutilization.	Safety issues and cost expectation.

Learning Resources	1. O'Hayre, R. P., S. Cha, W. Colella, F. B. Prinz, "Fuel Cell Fundamentals", Wiley, NY 2006. 2. Viswanathan. B, AuliceScibioh, M, "Fuel Cells – Principles and Applications", Universities Press (India) Pvt., Ltd., 2009. 3. Bagotsky .V.S, "Fuel Cells",Wiley, 2009.	4. DetlefStolten, "Hydrogen and Fuel Cells: Fundamentals, Technologies and Applications", 2010 5. Larminie .J, Dicks A. "Fuel Cell Systems", 2nd Edition, Wiley, 2003. 6. Barclay .F.J. "Fuel Cells, Engines and Hydrogen", Wiley, 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
Babu C Chief Consultant Conserve Consultant private Limited Hyderabad	Dr. Joseph Daniel, Associate Professor, School of Mechanical and Building Sciences, VIT Chennai	Mr. S. Rajendra Kumar, SRMIST
C. Anand Raj, Head Green Initiative, Infosys Chennai	Dr. Rayapati Subbarao, Associate Professor, NITTR Kolkata	Mr. V. Thirunavukkarasu, SRMIST

Course Code	18MEE450T	Course Name	MODELING OF THERMAL SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Courses	Thermodynamics Fluid Mechanics Heat Transfer	Co-requisite Courses	NIL	Progressive Courses	NIL
Course Offering Department	Mechanical Engineering	Data Book / Codes/Standards	NIL		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Understand the fundamentals of the thermal system design
CLR-2 :	Develop Mathematical models for the thermal systems
CLR-3 :	Apply numerical analysis to solve the mathematical models
CLR-4 :	Familiarize with different optimization methods
CLR-5 :	Apply optimization methods in problem solving of thermal systems
CLR-6 :	Evaluate the economic factors involved in design and application of thermal systems

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Understand system design and steps involved in the formulation of the design process
CLO-2 :	Development of mathematical models from the physical system
CLO-3 :	Solve the mathematical models using numerical analysis
CLO-4 :	Explore optimization methods to provide feasible solutions in the design of thermal systems
CLO-5 :	Evaluate the economic factors in the design and application of thermal systems
CLO-6 :	familiarize with design and analysis of the thermal systems

Learning	1	2	3
Level of Thinking (Bloom)	1	2	3
Expected Proficiency (%)	85	75	75
Expected Attainment (%)	12	85	75

Program Learning Outcomes (PLO)	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	H	M	M	M											
Problem Analysis	H	H	M	H											
Design & Development	H	H	M	H											
Analysis, Design, Research	H	H	M	H											
Modern Tool Usage	H	H	M	H											
Society & Culture	H	H	M	H											
Environment & Sustainability	H	H	M	H											
Ethics	H	H	M	H											
Individual & Team Work	H	H	M	H											
Communication	H	H	M	H											
Project Mgt. & Finance	H	H	M	H											
Life Long Learning	H	H	M	H											
PSO - 1	H	H	M	H											
PSO - 2	H	H	M	H											
PSO - 3	H	H	M	H											

Title of the module	Introduction to Thermal System Design	Mathematical Modeling of Thermal systems	Numerical Analysis of Thermal Systems	Optimization Methods	Economics and Financial Aspects of thermal system
Duration (hour)	9	9	9	9	9
S-1	SLO-1	Engineering design; Design Versus Analysis, Synthesis for Design	Importance of Modeling in Design, Basic Features of Modeling	Numerical Model for a System	Optimization; basic concepts, optimization methods
S-2	SLO-1	Need for optimization; Thermal system design	Types of Models; Analog Models, Mathematical Models, Physical Models, Numerical Models, Interaction Between Models	Modeling of Individual Components	Optimization of Thermal Systems, Practical Aspects in Optimal Design
S-3	SLO-1	Basic Characteristics of thermal design; Analysis Types	Development of Mathematical Modeling, General Procedure, Final Model and Validation	System Simulation, Importance of Simulation Methods for Numerical analysis	The Lagrange Multiplier Method, Basic Approach, and Physical Interpretation,
S-4	SLO-1	Formulation of the Design Problem, Variables, Constraints and Limitations	Physical Modeling, Dimensional Analysis, Modeling and Similitude	Simulation: Steady & Lumped Systems	Significance of the Multipliers, Optimization of Unconstrained Problems
S-5	SLO-1	Design Types; Conceptual Design, Innovative Conceptual Design ; Modifications in the Design of Existing Systems	Development of a Numerical Model Solution Procedures	Dynamic Simulation of Lumped Systems	Search Methods, Basic Considerations, Importance of Search Methods,
S-6	SLO-1	Steps involved in the Design Process	Curve Fitting; Exact Fit, Best Fit	Distributed systems, simulation of large systems	Golden Search method and typical exercise problem
S-7	SLO-1	Problems on Thermal Resistance and	Problems on exact fit	Numerical Simulation Versus	Fibonacci Search method

		Capacitance		Real System,		Profitability Index method (PI) ; Simple problems
S-8	SLO-1	Problems on Building Heating with variable temperatures	Problems on best fit	Design of Systems for Different Application	Problems on Fibonacci Search method	Internal rate of return method (IRR) & Benefit cost method (BCR); Simple Problems
S-9	SLO-1	Problems on unsteady state heat transfer	Problems on nonlinear least squares	Problem on numerical modeling of fluid flow systems	Steepest Ascent/Descent Method	Comparison between NPV and IRR methods

Learning Resources	1. Y Jaluria, "Design and optimization of thermal systems", Tata McGraw Hill, 3rd Edition, New Delhi, 2007 2. W F Stoecker, "Design of thermal systems", Tata McGraw Hill, 3rd Edition, New Delhi, 1989. 3. C Balaji, "Essentials of Thermal System Design and Optimization," Ane Books, New Delhi 2014	4. J S Arora, "Introduction to optimum design", Elsevier Publication, 3rd Edition, 2012 5. Bender.E.A, "Introduction to Mathematical Modeling", Dover Publication, 2000
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember Understand	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
Level 2	Apply Analyze	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
Level 3	Evaluate Create	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Expert
R. Mohan Prabhu Senior Engineer, Compression GEA Group, Pune, India	Dr. VenkataRamanan Professor, Institute of Energy Studies Anna University, Guindy Campus, Chennai – 600025	Dr. S. Shashi Kumar, SRMIST
Joseph ShekharSanthappan Faculty Mechanical Section, Engg. Dept. Shinas College of Technology, Al-Agur, Shinas, Sultanate of Oman.	Dr. R. Chandrasekhar Research Scientist Dept. of Electrical and Computer Engineering, Colorado State University Fort Collins, Colorado Area, USA	Dr. M. Cheralathan, SRMIST

Course Code	18MEE331J	Course Name	SENSORS AND ACTUATORS FOR AUTOMATION	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards		Nil	

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Expose the basics of various sensors used in automation
CLR-2 :	Impart the fundamental concept of electro-mechanical and fluid power systems
CLR-3 :	Provide exposure on practical knowledge of sensors and its measurements
CLR-4 :	Impart knowledge in mechanical, magnetic and electromechanical sensors
CLR-5 :	Provide the knowledge on the working principle of hydraulic, pneumatic, mechanical and electrical actuators
CLR-6 :	Impart the fundamental concept of drives and control system

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Understand the different types of sensors used in automation
CLO-2 :	Identify suitable sensor for the developments of automation processes
CLO-3 :	Develop the automation system by integration of electromechanical sensors and fluid power systems
CLO-4 :	Identify the type of actuators and its associated drivers for different application
CLO-5 :	Demonstrate effective use of actuators, its elements for the generation, control and conversion of energy for the typical automation system
CLO-6 :	Build real time automation system within realistic constraints such as industrial, economic, environmental, ethical, social, health and safety

Learning		
1	2	3
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)
1	85	80
2	90	85
3	90	80
2	85	80
2	90	80
3	95	85

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	-	M	-	H	-	-	-	-	-	-	-	L	-	L
H	M	L	L	H	-	-	-	-	-	-	-	M	-	M
H	H	H	M	H	-	-	-	-	-	-	M	H	-	H
H	M	-	-	H	-	-	-	-	-	M	M	-	M	
H	-	-	-	H	-	-	-	-	-	M	L	-	L	
H	M	M	M	H	M	M	L	L	-	-	M	H	-	H

Duration (hour)		12	12	12	12	12
S-1	SLO-1	Role of sensors in manufacturing: Importance of estimation in sensing	Resistive sensors: Potentiometer	Fiber optic sensors – Temperature sensors	Pneumatic systems – Types, components	Mechanical systems – Types of motion
	SLO-2	Role of sensors in manufacturing: Innovative sensor technologies	Resistive sensors: Strain gauge	Fiber optic sensors – Liquid level sensing	Pneumatic systems – working principle	kinematics chains
S-2	SLO-1	Physical transduction principles: Mechanical, Thermal	Inductive sensors: Methods of achieving inductance	Fluid flow level sensing	Hydraulic systems – Types, components	Cams, gears, ratchet and pawl
	SLO-2	Physical transduction principles: Electrical, Magnetic	Ferromagnetic plunger type, Transformer type	Micro bend sensing	Hydraulic systems – working principle	belt and chain drives
S-3	SLO-1	Classification of sensors: property based	Capacitive sensors: parallel plate capacitive sensor	Film sensors – Thick film sensors	Directional control of valves	Electrical systems – mechanical switches
	SLO-2	Classification of sensors: applications based	Serrated plate capacitive sensor	Thin film sensors	Valve symbols	solid state switches
S-4	SLO-1	Characterization: Electrical	Force/stress sensors using Quartz Resonators	Nano sensors - Introduction	Pressure control valves	Solenoids
	SLO-2	Characterization: Mechanical	Various beam designs	Nano structure, operation mechanism	Cylinders	DC motors
S-5	SLO-1	Characterization: Thermal, Optical	Ultrasonic sensors: introduction	Smart sensors –Introduction, properties	Rotary Actuators (Hydraulic type) components	Stepper motors – introduction, specifications
	SLO-2	Characterization: Biological and Chemical	Principles, Materials, Applications	Smart sensors – primary sensors, Compensation	Working principle	Stepper motors – types

S-6	SLO-1	Static characteristics of sensors	Magnetic sensors: Types	Functional integration of sensors	Rotary Actuators (Pneumatic type) components	Stepper motor – control
	SLO-2	Dynamic characteristics of sensors	Magnetic sensors: working principles	Smart sensors – information coding/processing	Working principle	Stepper motor - characteristics
S 7-8	SLO-1	Lab 1: Measurement of speed and displacement using linear and rotary sensors	Lab 4: Temperature measurement using RTD and thermocouple	Lab 7: Study on eddy current sensor for thickness measurement	Lab 10: Simulation of single and double acting cylinder circuits using different directional control valves	Lab 13: Speed and torque characterization and sequence control of stepper motor
	SLO-2	Lab 2: Force and Torque measurement using strain gauge	Lab 5: Experimentation on voltage, current, power, and frequency measurement	Lab 8: Study on ultrasonic sensors for material fault diagnosis	Lab 11: Sequencing of pneumatic circuits	Lab 14: Closed loop position and velocity control of a DC servo motor
S 11-12	SLO-1	Lab 3: Pressure measurement system using sensors	Lab 6: Experimentation with tactile sensor for force and touch detection	Lab 9: Simulation of hydraulic circuits in a hydraulic trainer	Lab 12: Simulation of logic and electro-pneumatic circuits	Lab 15: Speed and torque characterization and control of DC motors
	SLO-2					

Learning Resources	1. Patranabis D., "Sensor and Actuators", Prentice Hall of India (Pvt) Ltd., 2013. 2. Bolton W., "Mechatronics", Fourth edition, Pearson publishers, 2010. 3. Andrzej M. Pawlak., "Sensors and Actuators in Mechatronics – Design and Applications", CRC press, Taylor and Francis group, 2007.	4. Clarence W de Silva, "Sensors and Actuators – Engineering system instrumentation", second edition, CRC press, Taylor and Francis group, 2016. 5. Ian R. Sinclair, "Sensors and Transducers", third edition, Newnes, 2001. 6. R.K.Rajput, "A text book of Mechatronics", S.Chand & Company Limited, Second edition, 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. P.Haja Syeddu Masooth, SRM IST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRM IST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE332J	Course Name	MICROPROCESSOR AND MICROCONTROLLERS	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Expose the basics of microprocessors
CLR-2 :	Introduce the need and use of Interrupt structure
CLR-3 :	Impart the applications of microprocessor
CLR-4 :	Enable to understand the architecture of microcontroller
CLR-5 :	Expose the instruction set and register set of microcontroller
CLR-6 :	Impart knowledge about different peripheral interfacing devices

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Understand the basics of microprocessors
CLO-2 :	Use the processors for various applications
CLO-3 :	Develop the assembly language programs
CLO-4 :	Understand the interfacing techniques
CLO-5 :	Understand the internal architecture of microcontroller
CLO-6 :	Use microcontroller with different peripherals

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
1	95	90	H	L	M	L	H	-	-	-	-	-	-	-	M	-	M
3	90	85	H	L	L	M	M	-	-	-	L	-	-	L	M	-	H
1	85	80	H	L	L	L	M	-	-	-	M	-	-	L	M	-	L
3	80	75	H	L	L	M	H	-	-	-	M	-	-	L	M	-	M
2	80	75	H	L	L	M	M	-	-	-	M	-	-	L	M	-	L
3	90	85	H	L	M	M	H	-	-	-	H	-	-	L	H	-	M

Duration (hour)		12	12	12	12	12
S-1	SLO-1	Introduction to 8086 microprocessor- Internal Architecture	Peripherals and Interfacing-Interfacing I/O Ports	Application of Microprocessor- Microprocessor based Aluminium Smelter Control, Process Description	Introduction to 8051 Microcontroller- Microcontroller Block Diagram	Microcontroller Interfacing and Applications- System Design - Traffic Light Control
	SLO-2	Physical Memory Organization	Interfacing I/O Ports		Microcontroller Block Diagram	Switching Circuit
S-2	SLO-1	Addressing Modes	8086 Interrupts	Microprocessor based Aluminium Smelter Control, Process Description	Instruction Set	8051 Hardware Interface - Operation Sequence
	SLO-2		Interrupt Responses			
S-3	SLO-1	Instruction Set	Direct Memory Access (DMA)	Lab 7: Program to perform following conversion : BCD to ASCII BCD to hexadecimal	Register Set	System Design - Washing Machine Control
	SLO-2		I/O Mode			
S-4	SLO-1	Lab1: Basic arithmetic operations	Lab 4: Sorting of array in: Ascending order	Design of Microprocessor based Pattern Scanner System BCD to hexadecimal	Lab 10: A/D and D/A converter interface	Lab 13: Fabrication of 8-bit LED interfaces for 8085 kit through 8155 and 8255
	SLO-2		Lab 4: Sorting of array in: Descending order			
S-5	SLO-1	I/O Addressing Capability	Interfacing Analog to Digital Data Converters	Design of Microprocessor based Pattern Scanner SystemBCD to hexadecimal	Memory	LCD Interfacing
	SLO-2					
S-6	SLO-1	General Bus Operation	Interfacing Digital to Analog Converters	Lab 8: Program to demonstrate decision making and looping operation	I/O Addressing	Keyboard Interfacing
	SLO-2					
S-7	SLO-1	Lab2: Basic Logical operations	Lab 5: Program to demonstrate string		Interrupts	Relays and opt Isolators
	SLO-2					
S-8	SLO-1				Lab 11: Key board and Display	Lab 14: Interfacing and programming

S-9	SLO-2		manipulations	Design of an Electronic Weighing Bridge		of 8255. (E.g. traffic light controller)
	SLO-1					
	SLO-2					
S-10	SLO-1	Assembler Directives	Stepper Motor Interfacing	Design of an Electronic Weighing Bridge	Design of Microcontroller based Length Measurement System for Continuously Rolling Paper	DC motor Interfacing
	SLO-2	Operators				PWM
S-11	SLO-1	Lab 3: Transfer of block to another location in reverse order	Lab 6: Program to demonstrate Factorial of given numbers	Lab 9: Program to demonstrate parameter passing methods	Lab 12: Stepper motor interface	Lab 15: Interfacing DC motor and Servo motor
	SLO-2					
S-12	SLO-1					
	SLO-2					

Learning Resources	1. A K Ray and K M Bhurchandi, "Advanced Microprocessor and Peripherals", McGraw Hill Education private Limited, 2011.	4. Muhammad Ali Mazidi, Janice Gillispie Mazidi, Rolin D.Mckinlay, "The 8051 Microcontroller and Embedded Systems", McGraw Hill Education private Limited, 2008.
	2. Krishna Kant, "Microprocessors and Microcontrollers", Eastern Economy Edition, PHI learning private ltd, 2012.	
	3. Douglas V Hall and SSSP Rao, "Microprocessors and Interfacing", Pearson Education, 2012.	
	5. Ramesh S. Gaonkar, Microprocessor Architecture. Programming and Applications with the 8085, 5th ed., Penram International Publishing (India) Private Limited. 2005	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. Eastus Russel, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE333T	Course Name	INDUSTRIAL ROBOTICS AND AUTOMATION	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Introduce the basics of robotic technology and its applications
CLR-2 :	Impart knowledge on robot motion analysis and control
CLR-3 :	Explore the application of robot in manufacturing and assembly
CLR-4 :	Impart knowledge on automation and control technologies in manufacturing
CLR-5 :	Introduce the concept of automated material transport systems
CLR-6 :	Impart knowledge on fundamentals and applications of automated production lines

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Understand the basics of robot anatomy, control and sensing system
CLO-2 :	Gain knowledge on robot manipulator kinematics, path control and dynamics
CLO-3 :	Understand the application of robot in manufacturing and assembly
CLO-4 :	Gain knowledge on various elements of automations in manufacturing
CLO-5 :	Understand the concept of automated guided vehicle system for shop floor application
CLO-6 :	Gain knowledge on automated storage and retrieval system and automated assembly system

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
1	90	85	M	L	L	L	M	-	L	-	M	L	L	-	H	-	H
2	90	85	H	M	L	M	M	-	M	-	L	M	L	-	H	-	L
2	90	85	M	M	M	L	M	L	M	-	M	H	L	-	H	-	M
2	90	85	L	M	L	M	H	-	L	-	L	L	M	-	H	-	H
2	90	85	M	L	L	M	H	-	L	-	L	L	M	-	H	-	M
2	90	85	M	M	L	M	M	-	L	-	M	H	M	-	H	-	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to Robotics	Introduction to manipulator kinematics – position representation	Robot Applications in Manufacturing:	Automation in production systems
	SLO-2	History of Robots	forward and reverse transformation of the 2 degree of freedom arm	General consideration in Robot Material Handling	Automated manufacturing system
S-2	SLO-1	Robot Anatomy	3 degree of freedom arm in two dimensions	Material Transfer Application – pick and place operations	Computerized manufacturing and support systems
	SLO-2	Components	4 degree of freedom manipulator in three dimensions	Palletizing and related operations	Reasons for automating
S-3	SLO-1	Work Volume	Homogeneous transformations and Robot kinematics, parallel kinematics	Machine Loading and unloading	Automation principles and strategies – The USA principle
	SLO-2	Polar, cylindrical and cartesian	Kinematic equations using Homogeneous transformations	Die casting, plastic moulding	Strategies for Automation and process improvement
S-4	SLO-1	Robot drive systems	Solving the kinematic equations	Forging and related operations	Automation Migration strategy
	SLO-2	Hydraulic drive	Examples	Machining operations, Stamping press operations	Manual, automated and automated integrated production
S-5	SLO-1	Electric drive	A discussion on orientation	Robots used in Spot welding	Basic elements of an Automated System

	SLO-2	Pneumatic drive	Roll, pitch and yaw for a manipulator wrist mechanism	Application and benefits	Power to accomplish the Automated Process	Autonomous intelligent vehicle
S-6	SLO-1	Control systems	Manipulator path control – motion types	Robots used in Continuous Arc welding	Program of instructions	Automated storage Systems
	SLO-2	Dynamic performance	joint space schemes	Problems for Robots in Arc welding, applications, features of the welding robot, sensors, advantage and benefits	Control system	Retrieval Systems
S-7	SLO-1	Precision of Movement, Spatial resolution	Robot dynamics analysis,	Robots used in Spray Coating, and additive manufacturing	Advanced automation functions –	Carousel Storage Systems.
	SLO-2	Accuracy, Repeatability	Static analysis,	Application and benefits	Safety monitoring,	
S-8	SLO-1	End Effectors – grippers	Compensating for gravity,	Other Processing operation using Robots	Maintenance and repair diagnostics,	Automated assembly system –
	SLO-2	tools	Robot arm dynamics	Drilling, Grinding, Riveting	Error detection and recovery	system configuration,
S-9	SLO-1	Robotic sensors	Configuration of a Robot controller	Assembly system configurations - Single work station assembly,	Levels of automation	parts delivery at work stations,
	SLO-2	Types of sensors	General robot controller elements	series assembly system, parallel assembly system	Device, machine, cell or system, plant, enterprise levels.	applications.

Learning Resources	<ol style="list-style-type: none"> 1. "Industrial Robotics Technology, Programming, and Applications" - Mikell P Groover, Mitchell Weiss, Rogen N Nagel, Nicholas G Odrey, AshishDutta, Tata McGraw Hill Special Indian Edition, 2012. 2. "Computer Aided Design and Manufacturing" - K.Lalit Narayan, K.MallikarjunaRao, Prentice Hall of India, 2008. 3. "Automation, Production systems, and Computer intergrated Manufacturing"- Mikell P. Groover, Prentice Hall of India, 2008. 	<ol style="list-style-type: none"> 4. "Industrial Robotics Technology, Programming, and Applications"- Mikell P Groover, Mitchell Weiss, Roger N Nagel 2008 5. "Robotics Technology & Flexible Automation" - S.R.Deb, S.Deb 2012 6. "Introduction to Robotics in CIM system" - James A Reh 2002
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. E. Sankar, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE334T	Course Name	PLC AND ITS APPLICATIONS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards		Nil	

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Impart PLC principle to reduce the human efforts by means of automation				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Identify the main parts of PLC and hardware components																							
CLR-3 :	Analyze and interpret typical PLC timer ladder logic programs																							
CLR-4 :	Acquire knowledge on HMI remote control monitoring in industrial automation																							
CLR-5 :	Learn PLC process – control design and PID configuration																							
CLR-6 :	Design PLC control system I/O and its applications																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Utilize the parts of machine controller diagram including rungs, branches of PLC				2	85	80	M	-	-	-	M	-	-	-	-	-	-	-	-	-	L	-	L
CLO-2 :	Understand the equipment used to program a PLC and mnemonic code				2	90	85	M	-	-	-	-	-	-	-	-	-	-	-	-	M	-	L	
CLO-3 :	Gain knowledge on hardwired and Human Machine Interface communicate with PLC				2	85	80	H	-	M	M	-	-	-	-	-	-	-	-	-	L	-	M	
CLO-4 :	Learn the functions of PLC process – control design and elements				2	85	80	H	-	-	-	-	-	-	-	-	-	-	-	-	L	-	L	
CLO-5 :	Understand basic knowledge of PLCs concepts and its application in industries				3	90	85	H	-	M	M	-	-	-	-	-	-	-	-	-	M	-	H	
CLO-6 :	Develop complete system of PLC to meet industrial tasks				2	85	80	H	M	H	H	M	-	-	-	M	-	M	-	H	-	H		

Duration (hour)		9	9	9	9	9
S-1	SLO-1	Introduction	Control system classifications	Advanced program techniques-Introduction	Introduction: level of lontrol & automation	Case studies of manufacturing and process automation
	SLO-2	History of the PLC	Manual and auto control system	Physical components vs program components	Components of control system	PLC interface to a robot
S-2	SLO-1	Principles of operation	Automated system building block	RS Flip Flop, one shot,	Control elements of industrial automation	Case studies of on - off control
	SLO-2	Benefits of PLC	Requirements for industrial control	D Flip Flop, T Flip Flop	Examples of control requirements	Automatic control in manufacturing
S-3	SLO-1	Various parts of PLC	Motor magnetic starter	Forms of counters	Selection criteria for control elements	Water tank level control
	SLO-2	Hardwired system replacement	Process control choices	Counter application	Standardization	Irrigation - Canal water level control & logic diagram
S-4	SLO-1	Functions of PLC	Components of modularized PLC	Sequencers	Signal conversion	Filling of bottle - Case study
	SLO-2	Need for PLCs and its advantages	PLC configuration	Sequential functional chart	Quantification errors and resolution	
S-5	SLO-1	Inputs & Outputs of PLC	Introduction to human machine interface	NAND logic function	Process control system	Conveyor System Speed Control - Case Study
	SLO-2	Common types of mechanical design for PLCs	Device and PLC / HMI configuration	NOR logic function	Control Strategy and types	
S-6	SLO-1	PLC Architecture and Wiring Diagrams	Fundamentals of human machine interfacing	AND ladder Rung	PLC Selection factors	Coal Handling System- Case Study
	SLO-2	Internal structure Architecture of PLC	HMI-PLC application	OR ladder Rung	PLC Families	
S-7	SLO-1	Basic components and their symbols of	Network standards	Types of timer	Feedback control of continuous systems	Multi-Unit Chemical Process- Case

		Ladder diagram				Study
	SLO-2	Functions & function blocks of Ladder diagram	Network systems role in industry	On/off cyclic timer	PLC systems and safety	
S-8	SLO-1	Switches & Its types	Number systems	Simple and complex branches	PID control configuration	Commissioning of PLC systems
	SLO-2	Relay systems	PLC data	standard format program	PID control systems	Fault Finding Techniques
S-9	SLO-1	PLC size and Applications	PLC in automation technology	Logical Actuators: solenoid, valves cylinders	Design cases: Oven temperature control, supervisory control and data acquisition	Power Plant Monitoring and Control
	SLO-2	PLCs versus other technologies	Examples of commercial systems involving PLC	Logical Actuators: hydraulics and pneumatics	Position measurement	Other Applications of PLC

Learning Resources	<ol style="list-style-type: none"> 1. Khaled Kamel, Eman Kamel, "Programmable Logic Controllers, Industrial C", Mc Graw Hill private Ltd, 2014. 2. Gar Dunning, "Programmable Logic Controllers, Industrial Control", Mc Graw Hill private Ltd, 2009. 3. John R. Hackworth, Frederick D. Hackworth, Jr., "Programmable Logic Controllers : Programming Methods and Applications" Prentice Hall Publishing, 2003 4. W. Bolton, "Programmable Logic Controllers", Newnes Education private Limited, 2009. 5. Frank D, Petruzella, "Programmable Logic Controllers", Mc Graw Hill private Ltd, 2011. 6. Hugh Jack, "Automating Manufacturing Systems with PLCs" Mc Graw Hill private Ltd 2007. 	<ol style="list-style-type: none"> 7. Kelvin T. Erickson, "Programmable Logic Controllers: An Emphasis on Design and Application" Mc Graw Hill private Ltd 2007. 8. R. Bliesener, F. Ebel, C. Loffler, "Programmable Logic Controllers", Festo Didactic, Ltd, 2002. 9. Kevin Collins, "PLC Programming for Industrial Automation", Newnes Education private Limited, 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continious Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. A. Arunnath, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE335T	Course Name	FLEXIBLE MANUFACTURING SYSTEM	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Introduce the concepts that can be flexible to the modern competitive environment.
CLR-2 :	To impart knowledge of Group Technology
CLR-3 :	To impart knowledge about flexible manufacturing systems and its concepts
CLR-4 :	Introduce the concepts of manufacturing cell and its systems
CLR-5 :	Introduce the concepts JIT and KANBAN system
CLR-6 :	To impart knowledge about FMS software structure and description

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Understand the concepts of FMS in the modern competitive environment
CLO-2 :	Understand the concepts about Group Technology and various coding schemes
CLO-3 :	Understand the need of FMS layout, applications with scheduling concepts
CLO-4 :	Understand the concepts of cell, Unattended machining, JIT in detail
CLO-5 :	Understand the FMS software modules, ideas in data exchanges
CLO-6 :	Ability to perform Planning, Scheduling and control of FMS

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
1	90	85	M	-	H	L	M	-	L	-	M	-	M	-	H	-	H
2	90	85	H	-	-	L	M	-	M	-	-	M	M	-	H	-	H
2	90	85	M	-	M	L	M	-	M	-	M	H	L	-	H	-	H
2	90	85	L	-	L	L	L	-	-	-	L	L	M	-	H	-	H
2	90	85	M	-	H	L	H	-	-	-	L	-	H	-	H	-	H
2	90	85	M	-	H	L	M	-	-	-	M	H	H	-	H	-	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Traditional production planning, forecasting, process planning	Introduction to Group Technology	Introduction to FMS	Manufacturing Cell, Product flow from cell to cell
	SLO-2	Estimating, master scheduling, and various steps involved in planning and control	Part families	Basic components of FMS	Classification of Cell
S-2	SLO-1	Problems in production planning and control	Introduction to parts classification and coding	Application Characteristics of FMS	Unattended machining
	SLO-2	Cycle of activities	Coding system architecture	Significance of FMS	Features and requirement
S-3	SLO-1	Computer Integrated production management systems	Opitz system structure, classification system	Types of FMS	Differences between FMS and FMC
	SLO-2	Cycle of activities in CIPMS	MICLASS system	Types of FMS layouts	Introduction to JIT, Goals
S-4	SLO-1	Cost Planning	Code system	Factors influencing FMS layout	Objectives of JIT, Ingredients
	SLO-2	Cost Control	Group Technology machine cells	Objectives, AIMS of FMS	Quality and Quantity Principles of JIT
S-5	SLO-1	Inventory types	Types of GT machine cells	Advantages of FMS	Primary quantity JIT principles
	SLO-2	Inventory Management	Benefits of Group technology	Disadvantages of FMS	Benefits of JIT
S-6	SLO-1	Material Requirements Planning	Product design benefits, tooling and	Area of Application of FMS in an Industry	JIT implementation
					FMS software – Introduction
					General structure and requirements
					Advantages of FMS software
					Activities and functions to be performed by FMS software, within the system
					Types of FMS software modules
					Work-order processing
					Data distribution and collection
					System diagnostics and maintenance
					Tool management
					Traffic management and control
					Quality control management

			setups			
	SLO-2	Basic MRP concepts	Material handling	Various equipment and their functions required for an FMS	KANBAN/CARD system introduction	Fixtures and work piece control
S-7	SLO-1	Inputs to MRP	Production and inventory control	CIM technology	Push Vs pull system	Planning scheduling and simulation
	SLO-2	Master production schedule, bill of materials, Inventory record file	Employee satisfaction	Hierarchy of CIM	Dual card KANBAN	Computer simulation
S-8	SLO-1	Principles of MRP	Process planning procedures	Direct Real Time schedule control	Dual card KANBAN for milling and drilling	General phases of simulation analysis
	SLO-2	MRP output reports	System planning-objective, guideline,	Major functions of FMS host	Single card KANBAN concept	Functions
S-9	SLO-1	Benefits of MRP	System definition and sizing-	FMS concepts	Single card KANBAN- Example	FMS hosts
	SLO-2	MRP-II	Human resources	Process routings in an FMS	Benefits of KANBAN system	Data exchanges

Learning Resources	<ol style="list-style-type: none"> 1. "CAD/CAM Computer Aided Design and Manufacturing" - M.Groover&E.Zimmers, Pearson Prentice Hall, 2012 2. "Flexible Manufacturing System"- H.K.Shivanand, M.M.Benal, V.Koti, New Age International Pvt Limited, 2006 3. "Computer Aided Manufacturing" - P.N RAO, N.K.TIWARI, T.K.KUNDRA, McGraw Hill Education India private Ltd, 2014 	<ol style="list-style-type: none"> 4. "CAD/CAM Theory and Practice"- Ibrahim Zyed, Sivasubramaniam Tata McGraw Hill International 2011 5. "Flexible Manufacturing Cells and Systems" - William .W.LuggenPrentice Hall 1991 6. "Automation production Systems & Computer Integrated Manufacturing" - MikellP Groover 1989 7. "Handbook of Flexible of Manufacturing Systems" - JHA N.K 1991
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. M.Kamatchi Hariharan SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE432T	Course Name	INTERNET OF THINGS IN AUTOMATION	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Acquire knowledge on IoT enabling technologies
CLR-2 :	Impart knowledge on work logic of IoT in manufacturing system
CLR-3 :	Acquire knowledge on prototyping and production
CLR-4 :	To know the role of IoT in laser cutting, 3D printing, CNC milling
CLR-5 :	To know the use of smart objects for smart applications
CLR-6 :	Track and trace real time manufacturing information

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Understand the design principles of connected devices
CLO-2 :	Apply IoT models in manufacturing technologies
CLO-3 :	Understand the importance of standardization in IoT
CLO-4 :	Understand the capabilities and application of IoT
CLO-5 :	Become master of IoT for business model
CLO-6 :	Acquire the real time manufacturing information

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
			H	M	M	L	L	-	-	-	-	-	-	M	H	-	H
			H	M	L	L	-	-	-	-	-	-	-	M	H	-	H
			H	L	L	-	M	-	-	-	-	-	-	M	H	-	H
			H	L	-	-	L	-	-	-	-	-	-	M	M	-	M
			H	L	-	-	-	-	-	-	-	M	M	M	-	M	
			H	L	-	-	-	-	-	-	-	-	-	M	M	-	M

Duration (Hour)	9	9	9	9	9
S-1	SLO – 1	Introduction to IoT	Existing manufacturing paradigms and their limitations	Real time status monitoring and Real time production guiding	IoT application for industry value creation and challenges
	SLO – 2	Definition and characteristic of IoT	Agile manufacturing, Networked manufacturing	Real time production data sharing, Real time production queueing	
S-2	SLO – 1	Physical design of IoT	Reconfigurable manufacturing system	Deployment of multi-sensors, multiple sensor selection, multiple sensor manager	IoT application requirement and capabilities
	SLO – 2	Physical design of IoT	Product service system and industrial product service system,	Multisource manufacturing information capturing and sharing	
S-3	SLO – 1	Logical design of IoT	Manufacturing grid	Information encapsulation	Future factory concepts
	SLO – 2	Logical design of IoT	Cloud manufacturing	Case study – hardware device, software system	
S-4	SLO – 1	IoT enabling technologies	Limitations of agile manufacturing system	IoT standardization	The smart factory initiative
	SLO – 2	IoT enabling technologies	Applications of IoT in manufacturing system	Importance of standardization – beginning of everything	
S-5	SLO – 1	IoT levels and deployment models	Key features and limitations of IoT in manufacturing system	The need of methods and tools and corresponding research	From technologies to technology concept
	SLO – 2	IoT levels and deployment models	Integration framework of real time manufacturing information – sharing and integration	Gaps between IoT standardization, IoT research, IoT development and IoT innovation	
					Configuration of smart shop floor
					The logical flow of the prototype system
					The framework of the prototype system
					The framework of the prototype system
					Deployment of hardware devices
					Workflow of the prototype system
					Task driven manufacturing resource configuration model
					Production scheduling / rescheduling model
					The scheduling and rescheduling method

S-6	SLO – 1	Design principles for connected devices	Real time manufacturing data processing	M2M service layer standardization	Smart objects and smart applications	IoT enabled smart materials handling module
	SLO – 2	Design principles for connected devices		Prototype and production		
S-7	SLO – 1	Calm and ambient technology		Physical prototypes and mass personalization	Four aspects in your business to master IoT	IoT enabled smart station
	SLO – 2	Calm and ambient technology		Sharing and exchange service Open source versus closed source		
S-8	SLO – 1	Internet principles	IoT enabled smart assembly station	Prototyping embedded devices, sensors, actuators	Value creation from big data and serialization from pharmaceutical industry	Operation guidance from the system
	SLO – 2	Internet Communication – overview	Overall architecture of IoT enabled smart assembly station	Embedded computer basics, Arduino, Raspberry Pi, sketch, iterate and explore		
S-9	SLO – 1	Overall architecture of IoT manufacturing system (MS)	IoT enabled smart trolley	Non digital methods, Laser cutting, 3D printing, types of 3D printing	IoT for oil and gas industries	Real time manufacturing information track and trace
	SLO – 2	The work logic of IoT MS, Description of core technologies of IoT MS	IoT enabled materials handling	Moving to manufacture, Moving to manufacture, CNC milling, recycling		Real time production performances monitor module

Learning Resources	1. ArshdeepBahga, Vijay Madiseti, "Internet of Things – A hands on approach", ArshdeepBahga& Vijay Madiseti 2014	4. Dr. Ovidiu Vermesan, Dr. Peter Friess, "Internet of Things – Covering technologies for smart environments and ecosystem", River Publishers 2013.
	2. Yingfeng Zhang, Fei Tao, "Optimization of manufacturing using internet of things", Academic Press Elsevier 2017.	
	3. Adrian McEwen, Hakim Cassimally, "Designing the internet of things", Springer International Publishing 2018.	5. Christoph Jan Bartodziej, "The concept of industry 4.0" – An empirical analysis of technologies and applications in production logistics", Springer Gabler 2017
		6. Francis daCosta, "Rethinking the internet of things – A scalable approach to connecting everything", Apress 2013.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% weightage)	
		CLA-1 (10%)		CLA-2 (15%)		CLA-3 (15%)		CLA-4 (10%) #			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%	-	100%	-	100%	-	100%	-	100%	-

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from industry	Expert from higher technical institution	Internal Expert
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. N. Dinakar, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE433T	Course Name	VIRTUAL INSTRUMENTATION	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards		Nil	

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Impart knowledge on virtual instrumentation and differentiate it from conventional instruments
CLR-2 :	Learn the basic programming concepts
CLR-3 :	Learn different Data Acquisition System
CLR-4 :	Impart knowledge on interfacing of virtual instrumentation
CLR-5 :	Provide knowledge in process analysis by virtual instrumentation tool.
CLR-6 :	Develop real time applications using LabVIEW

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Describe about virtual instrumentation
CLO-2 :	Get adequate knowledge on virtual instrumentation tool sets
CLO-3 :	Describe data acquisition
CLO-4 :	Understand virtual instrumentation programming techniques
CLO-5 :	Gain knowledge on interfacing and networking of virtual instrumentation
CLO-6 :	Use virtual instrumentation tool for process monitoring

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
1	90	85	M	-	M	L	H	-	L	-	-	-	-	L	H	-	H
2	90	85	H	-	-	L	H	-	L	-	-	-	-	L	H	-	H
2	90	85	H	-	M	M	H	-	L	-	M	-	-	L	H	-	H
2	90	85	H	-	M	L	H	-	-	-	L	-	-	L	H	-	H
2	90	85	H	-	M	M	H	-	-	-	L	-	-	-	H	-	H
2	90	85	H	-	M	L	H	-	L	-	M	-	-	-	H	-	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Historical perspective, advantages of virtual instrumentation	Modular Programming in Lab-VIEW	Introduction to PC based data acquisition	Common Instrument Interfaces
	SLO-2	Block diagram of a virtual instrument	Building a connector pane	Sampling fundamentals	Current loop
S-2	SLO-1	Architecture of a virtual instrument	VIs and sub-Vis	Analog Input/output techniques	Serial port Communication
	SLO-2	Conventional instruments versus Traditional instruments	Opening and editing sub-Vis	Digital Input/output techniques	Instrument driver VIs
S-3	SLO-1	Hardware in virtual instrumentation	Placing sub-VIs, Saving sub VIs	Buses	RS 232C/ RS485
	SLO-2	Software in virtual instrumentation	Loops and charts, Terminals inside or outside loops	ADC, DAC	GPIOB
S-4	SLO-1	Layers of virtual instrumentation software	Shift Registers	Counters and timers	Using other interfaces
	SLO-2	Graphical system design model	Arrays, creating arrays	DMA	Bus Interfaces: USB, PCMCIA
S-5	SLO-1	Virtual instrumentation for test	Deleting, inserting and replacing elements	Software and hardware installation	VXI, SCSI
	SLO-2	Virtual instrumentation for industrial I/O and control	Clusters and graphs	Calibration, resolution	PCI, PXI, Fire wire
S-6	SLO-1	Virtual instrumentation for design	Case and sequence structures	Signal conditioning	PXI system controllers
	SLO-2	Graphical programming in data flow	formula nodes, feedback nodes	Computer based measurements system	Ethernet control of PXI.

S-7	SLO-1	Comparison with conventional programming	Control timing	Selecting and configuring data acquisition system	Networking basics for office	Motion control employing stepper motor
	SLO-2	Virtual instrumentation in the engineering processes	Local and global variables	Concept of universal data acquisition card	Networking basis for industrial applications	On-Off controller PID Controller
S-8	SLO-1	Virtual instrumentation personal computers	State machine	Data acquisition interface requirements	VISA and IVI.	PID controller theory
	SLO-2	Graphical programming and textual programming	String and file I/O	Use of timers/counters	VISA Programming terminology	PID tuning software
S-9	SLO-1	Development of Virtual Instrument using Graphical user interface (GUI)	Instrument Drivers	Signal sources, measurement system	VISA and Serial	Advantages and Limitations of PID controller
	SLO-2	Real-time systems	Publishing measurement data in the web, cable news network	Increasing the measurement quality	IVI software technology	Advantages and Limitations of On-Off controller

Learning Resources	<ol style="list-style-type: none"> 1. Robert H.Bishop, "Learning with LabVIEW 2009", Pearson Education 2010. 2. Jovitha Jerome, "Virtual Instrumentation Using LabVIEW", Eastern Economy Edition, PHI learning private Ltd, 2010. 3. Sanjay Gupta and Joseph John, "Virtual Instrumentation Using LabVIEW", McGraw Hill Education private Limited, 2013. 	<ol style="list-style-type: none"> 4. N.Mathivanan, "PC-based Instrumentation: Concepts and Practice", Eastern Economy Edition, PHI Learning private Ltd, 2007. 5. Kevin James, "PC Interfacing and Data Acquisition: Techniques for Measurement, Instrumentation and Control", Newnes, 2000.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram. skumaran@iiitdm.ac.in	1. Dr.R.Rajaraman, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.I.Suresh Kannan, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE434T	Course Name	NEURAL NETWORK AND FUZZY SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards		Nil	

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning			Program Learning Outcomes (PLO)														
CLR-1 :	Acquire knowledge on the fundamental of neural networks	1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Apply the neural network recurrence for automation	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLR-3 :	Utilize the practical applications of neural networks in automation																		
CLR-4 :	Understand the principles of Clustering approaches to automation																		
CLR-5 :	Understand various applications of fuzzy in automation																		
CLR-6 :	Understand the Neural Network approach to Pattern Recognition																		
Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:																		
CLO-1 :	Acquire basic understanding of the various algorithms involved in Neural Networks & Fuzzy Systems	3	90	80	H	H	H	H	-	-	-	-	H	-	-	H	H	-	H
CLO-2 :	Analyze the neuron model and fundamentals on learning algorithms	3	90	80	M	-	-	-	-	-	-	-	-	-	-	H	M	-	M
CLO-3 :	Understand various Fuzzy algorithms.	3	90	80	H	H	L	H	H	-	-	-	M	-	-	H	H	-	M
CLO-4 :	Analyze how to apply the concept of fuzzy & neural in automation	3	90	80	H	M	M	H	H	-	-	-	M	-	-	H	H	-	M
CLO-5 :	Application of Neural and Neuro fuzzy concepts	3	90	80	H	L	L	H	-	-	-	-	M	-	-	H	H	-	M
CLO-6 :	Analyze and compare a variety of automation techniques to real-world problems	3	90	80	H	H	L	H	-	-	-	-	M	-	-	H	H	-	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Introduction to ANN	Counter propagation	Introduction to Fuzzy Sets	Fuzzy Relations on Sets and Fuzzy Sets
	SLO-2	History of neural networks	Self-organization Map	Crispness, Vagueness, Fuzziness, Uncertainty	Application of neural networks and fuzzy logic
S-2	SLO-1	Biological Neurons and its Artificial Models	Cognitron and Neocognitron	Fuzzy Set Theory	Compositions of Fuzzy Relations
	SLO-2	Models of Artificial Neural Networks		Fuzzy Sets-Basic Definitions	Applications of Fuzzy Set Theory
S-3	SLO-1	Learning and Adaptation	Hopfield Net- kohonnen Nets	Basic Set-Theoretic Operations for Fuzzy Sets	Properties of the Min-Max Composition
	SLO-2	Neural Network Learning Rules		Types of Fuzzy Sets	
S-4	SLO-1	Hebbian Learning Rule	Mathematical foundations of Discrete-Time hopfield networks	Further Operations on Fuzzy Sets	Fuzzy Graphs
	SLO-2	Perceptron Learning Rule		Algebraic Operations	
S-5	SLO-1		Mathematical foundations of gradient type hopfield networks	Set-Theoretic Operations	Fuzzy Functions on Fuzzy Sets
	SLO-2	Types of activation Functions		Criteria for Selecting Appropriate Aggregation Operators	Linguistic Evaluation and Ranking of Machine Tools
S-6	SLO-1	Multilayer perceptron	Grossberg nets	Fuzzification and Defuzzification	Integration of Fuzzy Functions
	SLO-2	Batch Learning and On-Line Learning			Application in Flexible Manufacturing Systems
S-7	SLO-1	Supervised Learning Viewed as an Optimization Problem	Transient response of continuous-Time Networks	Fuzzy Measures and Measures of Fuzziness	Performance index – Modification of rule base
	SLO-2				Adaptive Neural Controllers

S-8	SLO-1	Back propagation algorithm and its variants	Relaxation Modeling in Single-Layer Feedback Networks	The Extension Principle and Applications	Genetic algorithms	Signal Processing and Image Processing
	SLO-2				Adaptive fuzzy system	
S-9	SLO -1	Different types of learning, examples	Art-I, Art-II reinforcement learning	Algebraic Operations with Fuzzy Numbers	Neuro fuzzy systems	Case studies
	SLO -2					

Learning Resources	1.	Vallum B. R And Hayagriva V.R C++, Neural networks and Fuzzy logic, BPB Publications.	6.	Fuzzy sets Fuzzy logic, Klir, G.J and Yuan B.B Prentice Hall of India Pvt. Ltd., New Delhi
	2.	Simon Haykins, "Neural Networks - A comprehensive foundation", Macmillan College, Proc. Con. Inc. New York, 2005	7.	Neural Networks and Fuzzy systems, Kosko.. Prentice hall of India Pvt. Ltd., New Delhi 1994
	3.	Zimmermann.H.J, "Fuzzy set theory and its applications", Allied Publication Ltd., Chennai, 2001.New Delhi, 1996	8.	Introduction to Fuzzy control, Dirankov D. Hellendoorn H, Reinfrank M., Narosa Publications House, New Delhi 1996
	4.	Fuzzy logic & Neural Networks/ Chennakesava R. Alavala/ New Age International, 2008	9.	Introduction to Artificial Neural systems, Zurada J. M Jaico Publishing House, New Delhi 1994
	5.	Neural Networks for control, Millon W. T, Sutton R.S and Werbos P.J, MIT Press 1992.		

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE435T	Course Name	ELEMENTS OF MECHATRONICS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Understand the basic key elements of mechatronics systems	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Have cognizance on performance of sensors and transducers.	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understand different actuation systems, signal processing and Controllers	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Program the PLC	Expected Attainment (%)	Design & Development
CLR-5 :	Design mechatronics system and its applications		Analysis, Design, Research
CLR-6 :	Case studies		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	To discuss mechanical systems used in Mechatronics	1	90	85	H	L	H	H	-	-	L	-	-	-	-	-	H	-	H
CLO-2 :	To integrate mechanical, electronics, control and computer engineering in the design of mechatronics systems	2	85	80	H	L	H	M	L	-	L	-	-	H	-	-	M	-	M
CLO-3 :	Use mathematical methods and tools to analyse and develop electrical and mechanical engineering systems	3	85	80	L	M	L	-	L	-	-	-	-	-	-	L	M	-	H
CLO-4 :	Identify, define, formulate and solve complex mechatronics engineering problems	2	85	80	H	M	H	H	H	-	L	-	-	-	M	-	H	-	H
CLO-5 :	Ability to work in design, implementation and integration of mechatronics engineering applications	2	85	80	H	-	H	-	M	-	L	-	-	L	-	-	M	-	M
CLO-6 :	Conduct feasibility study for using mechatronics systems for solving assistive technology applications	2	85	80	M	M	-	H	L	-	-	-	-	L	M	L	M	-	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 SLO-2	Mechatronics Engineering Design	Mathematical models	Microprocessor systems	Introduction of basic structure Stepper motor
S-2	SLO-1 SLO-2	Classification of Sensors Classification of transducers	Building Blocks : Mechanical Building Blocks : Electrical	Basic elements of control systems	Input and output processing Stepper motor - types
S-3	SLO-1 SLO-2	Thermal and electrical sensors Optical sensor	Building Blocks : Fluid Building Blocks : thermal system	Microcontrollers	Programming Servo motor
S-4	SLO-1 SLO-2	Acoustic sensor Pneumatic sensor	System models	Microprocessor architecture and terminology	Mnemonics Servo motor - types
S-5	SLO-1 SLO-2	Magnetic sensor Piezo electric sensor	Dynamic response of systems	Closed loop controllers	Timers Case studies of mechatronics system-pick and place robot
S-6	SLO-1 SLO-2	Transducers: Static characteristics Transducers: Dynamic characteristics	first and second order systems	Proportional, derivative and integral controls Derivative and integral controls	counters and internal relays automatic car park barrier
S-7	SLO-1 SLO-2	Open loop control systems Closed loop control systems	Modeling dynamic systems	PID controller	Data handling Engine management system
S-8	SLO-1 SLO-2	Servo mechanism	System transfer functions	Controllers Tuning of controller	Selection of PLC Digital camera
S-9	SLO-1 SLO-2	Frequency response	Adaptive control of machine tools	Development of simple ladder programs for specific purposes	A PC based computer numerically controlled drilling machine

Learning Resources	1. W.Bolton, "Mechatronics electronic control systems in mechanical and electrical engineering", Pearson Education 2013.	3. Devdas Shetty & Richard A.Kolk, "Mechatronics system design", Indian Edition, Cenage Learning, 2009.
	2. Godfrey C.Onwubolu, "Mechatronics principles and applications", Elsevier, 2011.	4. Nitaigour Premchand Mahalik, "Mechatronics principles, concepts and applications", Tata McGraw-Hill, 2008. 5. R.K.Rajput, "A textbook of Mechatronics", Revised Edition, S.Chand Company,2009.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

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2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr.R.Rajaraman, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE801J	Course Name	ARTIFICIAL INTELLIGENCE AND MACHINE LEARNING	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Learn about Artificial Intelligence and identify the need of AI in Mechanical Engineering
CLR-2 :	Learn about different search algorithms
CLR-3 :	Learn about Logic controllers, Microprocessors
CLR-4 :	Learn about Python Programming
CLR-5 :	Apply the concept of Machine Learning for mechanical applications
CLR-6 :	Apply Mechanical concepts in AI and build an efficient working environment

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Understand the concept of Artificial Intelligence
CLO-2 :	Characterize the concepts of Machine Learning
CLO-3 :	Identify the different concepts in Heuristic methods
CLO-4 :	Understand MATLAB and Python programming
CLO-5 :	Solve problems in Genetic programming
CLO-6 :	Apply the basic knowledge of Mechanical in smart manufacturing

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
1	90	85	H	L	M	M	H	-	M	H	M	-	-	M	-	-	-
1	90	85	H	-	M	M	H	-	M	L	M	-	-	M	-	-	-
1	90	85	H	-	-	M	L	-	-	H	M	L	-	-	M	L	M
2	90	85	H	H	L	M	M	-	L	L	M	L	-	M	M	L	M
2	90	85	H	H	-	M	M	-	-	L	M	L	-	L	M	L	M
2	90	85	H	M	-	M	H	-	L	L	M	L	-	H	M	L	M

Duration (hour)	12	12	12	12	10
S-1	SLO-1	Artificial Intelligence and its foundations	Lab-4: MATLAB- Optimization methods GA, Fuzzy, Neural & PSO	Tutorial 4: Artificial Intelligence in Manufacturing Industry	Fuzzy matching techniques
	SLO-2	History of AI, LISP and PROLOG		Hebb's Rule, McCulloch and Pitts Neurons	Syntax programming for optimization
S-2	SLO-1	Blind search, Breadth first	Formalized symbolic logics	Evolutionary Learning: Genetic Algorithm and Problems in GA	Tutorial 6: Microcontrollers
	SLO-2	Lab-1: Python Programming	Syntax and semantics for Logics Representing knowledge using rules and rules-based deduction systems	Genetic Programming	Lab-12: FLEXSIM Software
S-3	SLO-1	Heuristic search techniques	Reasoning under uncertainty	Lab-7: Image Processing, Object and Motion detection	Reduced environmental impact by ML
	SLO-2	Hill climbing technique	Bayes' probabilistic inferences		Object-Oriented representations
S-4	SLO-1	Best first search technique, A* algorithm,	Heuristic methods	Markov Chain Monte Carlo (MCMC) methods, Bayesian Networks	Lab-13:Hydraulic and Pneumatic simulator
	SLO-2	AO* algorithm	Fuzzy reasoning	Lab:8- Pick and place operation of ABB Robot in Manual Mode	Harnessing useful data using AI and ML
S-5	SLO-1	Lab-2: Machine Learning using python	Lab-5: Introduction to SIMULINK & Modelling of problems related to kinematics and dynamics of robot using MATLAB	Graphical models Markov Random Fields	RETE matching algorithm
	SLO-2	Tutorial:1 Python Programming in Mechanical applications		Hidden Markov Models (HMMs)	Supply chain Communication
					Single Value Decomposition(SVD), t-Distributed Stochastic Neighbor Embedding (t-SNE) methods
					Ensemble Techniques Boosting Bagging
					Cutting waste using AI
					Integration of man machine system
					Improved customer service using AI
					Minimizing Equipment Failures
					Predictive Maintenance
					Multi-dimensional optimization

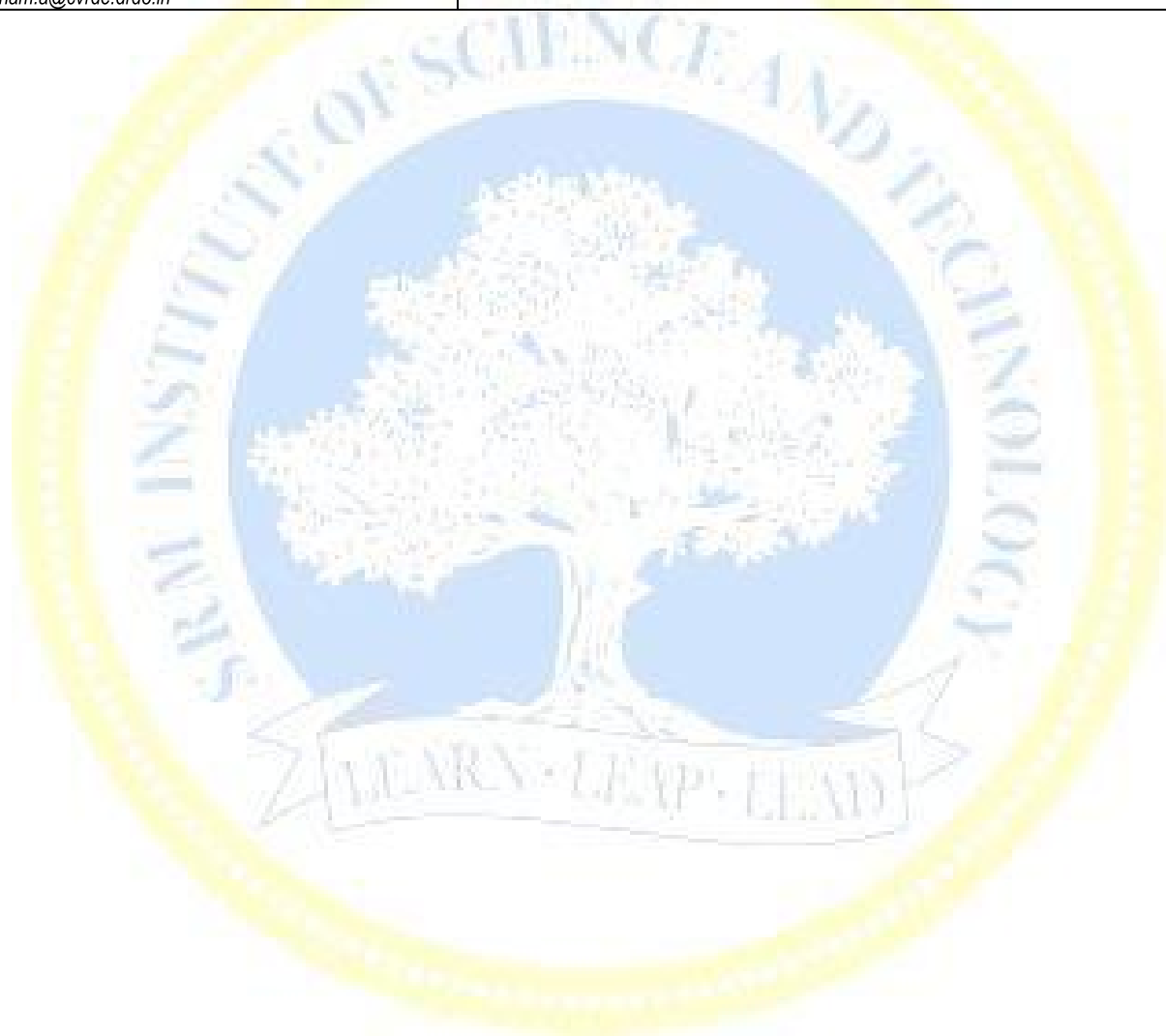
S-6	SLO-1	Game trees- Numerical	Expert system, Relationship between Artificial Intelligence and Mechanical Engineering	Lab-9: Pick and place operation of ABB Robot in Teach Pendent method, PLC Controlled material handling system	Data visualization in machine learning	Artificial Neural network
	SLO-2	Minimax algorithm	Expert system, Relationship between Artificial Intelligence and Mechanical Engineering		Text mining	Greedy algorithm
S-7	SLO-1	Game playing	Diagnosis of rule-based reasoning Case-based reasoning and fault-based tree fault diagnosis	Tracking Methods	Lab-14: Study on Microcontrollers	Greedy algorithm problems
	SLO-2	Alpha beta pruning	Diagnosis of rule-based reasoning Case-based reasoning and fault-based tree fault diagnosis	Python- Basics of coding, Writing and importing code		Robotic perception
S-8	SLO-1	Lab-3: Basics of MATLAB programming	Case study: Manufacturing scheduling	Tutorial 5: PLC controllers	Case study on driverless vehicles	Sensors and effectors
	SLO-2		Case study: Manufacturing scheduling			Types of sensors and acutators
S-9	SLO-1	Definition and importance of Knowledge Representation of knowledge	Tutorial 2: Case study in manufacturing industry Case study: Intelligent Diagnostic system for Rotating machinery	Lab-10: 8051 Micro controller- Temperature and Traffic control	Lab-15: Study on Driverless Vehicles	Dynamics and control
	SLO-2	Organization and Manipulation Logical Agents	Case study: Fault diagnosis to Hot Forging Press			Problems in Dynamics
S-10	SLO-1	Problems in Genetic Algorithm	Lab-6: Sensors and its applications	Python coding	Application of AI and ML in Inventory control	Robotic software architecture
	SLO-2	Programming GA in MATLAB				Writing Robotic software
S-11	SLO-1	Problems in Artificial Neural Network	Tutorial 3: Image Processing, Object and Motion detection	MATLAB and its applications in Fault detection and Optimization	Reducing time of production with AI	Robotic programming language
	SLO-2	Programming ANN in MATLAB	Basics of Machine Learning		Cost reduction of production with AI	Case study on Humanoid robot
S-12	SLO-1	Programming Particle swarm optimization (PSO)	Definition & uses of Machine Learning	Lab-11: 8051 Micro controller- Temperature and Traffic control	Automating quality control using AI and ML	Machine Learning in supply chain
	SLO-2	Problems in PSO	Decision Tree & Practical applications			

Learning Resources	1. Russell, Stuart J., and Peter Norvig. Artificial intelligence: a modern approach. Malaysia; Pearson Education Limited., 2016.	4. Luger, George F., and William A. Stubblefield. Artificial intelligence and the design of expert systems. Benjamin-Cummings Publishing Co., Inc., 2009.
	2. Patterson, Dan W. Introduction to artificial intelligence and expert systems. Prentice-hall of India, 2010.	
	3. Marsland, Stephen. Machine learning: an algorithmic perspective. Chapman and Hall/CRC, 2009.	5. Charniak, Eugene. Introduction to artificial intelligence. Pearson Education India, 2000.
		6. Nilsson, Nils J. Principles of artificial intelligence. Morgan Kaufmann, 2014.

Learning Assessment											
	Bloom,s Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kanchipuram, skumaran@iiitdm.ac.in	1. Mr.S.Vignesh, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr. Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		



Course Code	18MEE802T	Course Name	DIGITAL IMAGE PROCESSING AND MACHINE VISION	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Study the image fundamentals transforms necessary for image processing.
CLR-2 :	Study the image enhancement techniques
CLR-3 :	Study basic image processing operations
CLR-4 :	Overview of image restoration techniques.
CLR-5 :	Understand the need for image compression and segmentation
CLR-6 :	Understand the rapid advances in Machine vision.

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Review the fundamental concepts of a digital image processing system
CLO-2 :	Analyze images in the frequency domain using various transforms
CLO-3 :	Evaluate the techniques for image enhancement and image restoration
CLO-4 :	Analysis different causes for image degradation
CLO-5 :	Interpret Image compression standards.
CLO-6 :	Interpret image segmentation and representation techniques.

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
2	85	90	M	-	M	-	-	-	-	-	-	-	-	L	L	-	L
2	85	80	M	L	M	M	-	-	-	-	L	-	L	M	-	M	
2	80	85	M	-	M	M	-	-	-	-	-	-	L	L	-	L	
2	90	85	M	-	M	M	L	-	-	-	-	-	L	M	-	M	
2	80	80	M	L	-	M	-	-	M	-	-	-	L	M	-	L	
3	85	80	M	L	L	M	-	-	-	-	M	-	-	L	L		M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Origins of digital image processing	Light used in Machine Vision	Image Enhancement Techniques:	Image Compression - Measuring image information
	SLO-2	Origins of digital image processing	Basic Rules and Laws of Light Distribution	Spatial and Frequency domain	Spatial and temporal redundancy
S-2	SLO-1	Fundamental steps in digital image processing	Light Filters	Spatial Domain	Image compression models - Huffman coding
	SLO-2	Fundamental steps in digital image processing	Light Filters	Point operation & Mask operation	Image compression models - Huffman coding
S-3	SLO-1	Components of image processing system	Types of Light Filters	Histogram manipulation	Image compression models - Arithmetic coding
	SLO-2	Components of image processing system	Types of Light Filters	Histogram equalization and procedure	Image compression models - Run length coding
S-4	SLO-1	Elements of Visual Perception	Machine Vision versus Closed Circuit Television (CCTV)	Linear gray level transformation	Digital Image watermarking
	SLO-2	Basics of Image Sensing and Acquisition	Machine Vision versus Closed Circuit Television (CCTV)	Linear gray level transformation	Digital Image watermarking
S-5	SLO-1	Image Sampling	Imaging Sensors- CCD	Nonlinear gray level transformation	Image Segmentation- Point, line and edge Detection
	SLO-2	Image Quantization	Imaging Sensors- CCD	Nonlinear gray level transformation	Image Segmentation- Point, line and edge

					Detection	Production-Line-Scan Processing
S-6	SLO-1	Basic Relationships between Pixels	Imaging Sensors- CMOS	Comparison between smoothing and sharpening spatial filters	Edge linking and Boundary Detection	Industrial Case Study- Glue Check under UV Light
	SLO-2	Basic Relationships between Pixels	Imaging Sensors-CMOS	Comparison between smoothing and sharpening spatial filters	Edge linking and Boundary Detection	Industrial Case Study- Glue Check under UV Light
S-7	SLO-1	Digital image file formats – GIF	Digital Cameras- B/W Sensor and Processing	Smoothing frequency domain filters (Ideal, Butterworth, Gaussian)	Thresholding, Basics of Global thresholding	Industrial Case Study Multiple Position and Completeness Check
	SLO-2	Digital image file formats – JPEG	Digital Cameras- B/W Sensor and Processing	Smoothing frequency domain filters (Ideal, Butterworth, Gaussian)	Using edge to improve global thresholding	Industrial Case Study-Multiple Position and Completeness Check
S-8	SLO-1	Digital image file formats – PNG	Color Digital Cameras	Sharpening frequency domain filters (Ideal, Butterworth, Gaussian)	Multiple and variable thresholding	Industrial Case Study- Pin Type Verification
	SLO-2	Digital image file formats – TIFF, BMP	Camera Noise&Photon Noise.	Sharpening frequency domain filters (Ideal, Butterworth, Gaussian)	Multiple and variable thresholding	Industrial Case Study- Pin Type Verification
S-9	SLO-1	Applications of Digital Image Processing	Introduction to video analytics	Homomorphic filtering.	Region Based Segmentation	Industrial Case Study- Robot Guidance
	SLO-2	Applications of Digital Image Processing	Introduction to video analytics	Homomorphic filtering.	Pattern recognitions	Industrial Case Study-Robot Guidance

Learning Resources	1. Rafael C Gonzalez and Richard E Woods, Digital Image Processing, Pearson Education, 3rd Edition, 2009. 2. Jayarman.S, Esakkirajan.S and Veerakumar.T, Digital Image Processing, Tata McGraw Hill, 2010. 3. Alexander Hornberg, Handbook on Machine Vision, Wiley – VCH, 2008. 4. William K Pratt, Digital Image Processing, John Wiley, 2007.	5. Myler, Harley R. Fundamentals of machine vision. SPIE Optical Engineering Press, 1999. 6. MillmanSonka, Vaclav Hlavac, Roger Boyle, and Broos Colic, Image Processing Analysis and Machine Vision, Thompson learning, 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India., kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram, skumaran@iiitdm.ac.in	1. Mr. G. Leela Prasad, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr. Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE803J	Course Name	SENSORS FOR INTELLIGENT MANUFACTURING	Course Category	E	Professional Elective	L 2	T 0	P 2	C 3
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Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR): *The purpose of learning this course is to:*

CLR-1 :	Expose the basics and working principle of sensors and Transducers
CLR-2 :	Impart knowledge on motion sensors
CLR-3 :	Learn the Packaging techniques of sensors
CLR-4 :	Provide knowledge on sensors used in Robotics
CLR-5 :	Provide insights on advanced sensors
CLR-6 :	Impart knowledge on sensor based control

Course Learning Outcomes (CLO): *At the end of this course, learners will be able to:*

CLO-1 :	Describe about sensors and transducers
CLO-2 :	Familiarize to use motion sensors for various applications
CLO-3 :	Develop packaging of various sensors
CLO-4 :	Understand the use of sensors in Robotic application
CLO-5 :	Gain knowledge on advanced sensors
CLO-6 :	Develop a control scheme based on sensor feedback.

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
1	90	85	H	-	L	L	M	-	-	-	M	-	-	-	M	-	M
2	90	85	H	-	L	L	H	-	-	-	M	-	-	-	M	-	M
2	90	85	H	-	M	M	M	-	-	-	M	-	-	M	M	-	H
2	90	85	H	-	M	M	H	-	-	-	M	-	-	M	M	-	M
2	90	85	H	-	L	M	H	-	-	-	M	-	-	M	M	-	M
2	90	85	H	-	L	M	M	-	-	-	H	-	-	L	M	-	M

Duration (hour)	12	12	12	12	12
S-1	SLO-1 Role of sensors in manufacturing automation	Motion Sensors	Classification, characteristics	Semiconductor sensors	Types of controllers
	SLO-2 Active and passive sensors	Resistive strain gauge	Internal sensors – position	Hall elements	Electrical, pneumatic
S-2	SLO-1 Operating principles of different sensors electrical,	LVDT, RVDT	Velocity sensors	Silicon sensors for sensing radiation	Hydraulic prime movers and associated control hardware
	SLO-2 Operating principles of optical sensors	Capacitive, piezo	Acceleration sensors	Mechanical signals	Closed loop control of microcomputer based drives
S-3	SLO-1 Operating principles of acoustic sensors	Seismic pickups,	Force sensors	Magnetic signals	Relay control systems
	SLO-2 Operating principles of pneumatic sensors	Vibrometers and accelerometers	External sensors	Chemical and other signals	PLC systems and programming,
S-4	SLO-1 Lab 1: Study of the characteristics of a Piezo resistive Sensor for Pressure Measurement	Lab 4: Characteristics study of LVDT	Lab 7: Study of the characteristics of a Photo reflective sensor for Speed Measurement	Lab 10: Study of PLC system and Programming	Lab 13: Study of Level sensors
S-5	SLO-2				
S-6	SLO-1 Operating principles of magnetic sensors	Sensors for CNC machine tools.	Proximity, touch Slip sensors.	Catalytic devices	Control including sequence control
	SLO-2 Operating principles of electro-optical sensors	Packaging techniques of mechanical sensors	Robotic vision.	Gas sensors	Sensor based control of various actuators.

S-7	SLO-1	Vision sensors, Active transducers, passive transducers	Electrical interconnection	Process of imaging, architecture of robotic vision systems	Acoustic sensors	Mechatronic devices
	SLO-2	Classification of transducers, Sensors and Transducers for: flow, temperature, pressure and torque,	Packaging processes	Image acquisition, components of vision system	Applications of sensors in Robotics	Uses of mechatronic devices in for Intelligent Manufacturing
S-8	SLO-1	Lab2: Characteristics study of Resistance Temperature Detector (RTD)	Lab 5: Characteristics study of RVDT	Lab:8 Characteristics study of Reflective Beam Sensor	Lab 11: Study of Force and torque sensors	Lab 14: Study of Smart material sensors
S-9	SLO-2					
S-10	SLO-1	Current and torque and speed measurements using digital measurement techniques	Mechanical transduction techniques	Image representation, image processing in robotic vision systems	Tactile sensors	Autonomous mobile robots
	SLO-2				Future Inertial Micro machined Sensors	Applications of autonomous mobile robots
S-11	SLO-1	Lab 3: Experiment on the Calibration of a Thermocouple	Lab 6: Characteristics study of an Electromagnetic Flow meter	Lab:9 Experiment on image acquisition and processing	Lab 12: Study of Acceleration sensors	Lab 15: Study of Micro and Nano sensors
S-12	SLO-2					

Learning Resources	<ol style="list-style-type: none"> 1. Stephen Beeby, Graham Ensell, Michael Kraft, Neil White, MEMS Mechanical Sensors, Artech House, Inc. London, 2004. 2. J. Vetelino and A. Reghu, Introduction to sensors, CRC Press, 2010. 3. J. Fraden, Handbook of Modern Sensors: Physics, Designs and Applications, 4th edition, Springer, 2010. 4. T. G. Beckwith, R. D. Marangoni and J. H. Lienhard V., Mechanical Measurements, Pearson Prentice Hall, 2009. Doebelin, Measurement systems: Applications and Design, 5th edition, McGraw Hill Book, 2004. 	<ol style="list-style-type: none"> 5. Doebelin, Measurement systems: Applications and Design, 5th edition, McGraw Hill Book, 2004. 6. I. R. Sinclair, Sensors and Transducers, Elsevier, 2001. 7. J. S. Wilson, Sensor Technology Handbook, Newnes, 2004. 8. B. K. Ghosh, T. J. Tam and N. Xi, Control in Robotics and Automation: Sensor-Based Integration, Academic Press, 1999. 9. C.W. de Silava, Sensors and Actuators, 2nd edition, CRC Press, 2016.
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Learning Assessment											
	Bloom,s Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100%		100%		100%		100%		100%	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram, skumaran@iiitdm.ac.in	1. Mr.ArulRaja . R A, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cwrde.drdo.in		

Course Code	18MEE804T	Course Name	INDUSTRY 4.0	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Acquire knowledge on principles of industry 4.0 and building blocks of industry 4.0
CLR-2 :	Acquire knowledge on IoT enabled manufacturing systems
CLR-3 :	Understand cloud based cyber physical systems in manufacturing
CLR-4 :	Apply data analytics in manufacturing
CLR-5 :	Understand and apply additive manufacturing technologies
CLR-6 :	Acquire knowledge on technologies and application of industry 4.0

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Explain the evolution of industry 4.0
CLO-2 :	Explain the concept of IoT
CLO-3 :	Understand the application areas of IoT in manufacturing
CLO-4 :	Explain the concept of cloud manufacturing
CLO-5 :	Explain the advances in robotics in the era of industry 4.0
CLO-6 :	Identify advances in virtual factory research and application

Learning	1	2	3
Level of Thinking (Bloom)			
Expected Proficiency (%)			
Expected Attainment (%)			

Program Learning Outcomes (PLO)														
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
H	-	M	-	-	-	-	-	-	-	-	M	H	--	H
H	-	M	L	H	-	-	-	-	-	-	H	H	--	H
H	L	M	L	L	-	-	-	-	-	-	M	M	--	M
H	-	H	L	L	-	-	-	-	-	-	M	M	--	M
H	-	H	L	L	-	-	-	M	L	-	L	M	--	M
H	-	H	M	L	-	-	-	L	-	L	M	M	--	M

Duration (Hour)	9	9	9	9	9
S-1	SLO – 1	Industry 4.0 – Definition	The concept of IoT	Concept of cloud manufacturing	Power consumption in manufacturing
	SLO – 2	Why industry 4.0 and why now?	Existing manufacturing paradigms and their limitations – agile manufacturing	Real time production information	Anomaly detection in air conditioner
S-2	SLO – 1	Phases of industrial developments	Networked manufacturing	Cloud service selection and composition	Anomaly detection in air conditioner
	SLO – 2	Central features of the concept	Reconfigurable manufacturing system	Overall architecture of manufacturing resources configuration method	Smart remote machinery maintenance system
S-3	SLO – 1	Principles of industry 4.0	Product service system / industrial product service system	Cloud machine model	Smart remote machinery maintenance system
	SLO – 2	Main characteristics of industry 4.0	Manufacturing grid Cloud manufacturing	Cloud machine model	Quality perdition in steel manufacturing
S-4	SLO – 1	Building blocks of Industry 4.0	Limitations of agile manufacturing system	Cloud machine model	Quality perdition in steel manufacturing
	SLO – 2	The value chain	Applications of IoT in Manufacturing system	Application of cyber physical system & IoT	Predicting drilling efficiency
S-5	SLO – 1	Creating the value chain	Key features and limitations of IoT in Manufacturing System	Cloud manufacturing framework	Techniques used for predictive analytics
	SLO – 2	Benefits of industry 4.0	Architecture of IoT – MS	Manufacturing capability and manufacturing resource	Techniques used for predictive analytics

S-6	SLO – 1	Challenges of industry 4.0	Integration framework of real time manufacturing information – sharing and integration	Cloud architecture	Forecast accuracy calculation	Application areas of additive manufacturing
	SLO – 2	Smart manufacturing	Real time manufacturing data processing, sharing and exchange service	Approaches to achieve product information sharing	Forecast accuracy calculation	Impact of additive manufacturing techniques on society
S-7	SLO – 1	Industrial internet of things	The work logic of IoT MS, Description of core technologies of IoT MS	Standardization for cloud manufacturing	Real world case study – definition	Impact on manufacturing and supply chain
	SLO – 2	Gateways	IoT enabled smart assembly station	Standardization for cloud manufacturing	Data gathering and cleaning	Digital traceability through production value chain
S-8	SLO – 1	Wireless Communication technologies	Overall architecture of IoT enabled smart assembly station	Overview of cyber security in industry 4.0 era	Automation based lean production	Digital traceability technologies
	SLO – 2	Industry 4.0 – the way forward	IoT enabled smart trolley	Overview of cyber security in industry 4.0 era	Automation based lean production	Architectural framework of the digital traceability system, Application of digital traceability
S-9	SLO – 1	Technology road map for industry 4.0	IoT enabled materials handling	Security threat and vulnerabilities of IoT	Model application	Project management in digital traceability, Examples for IoT in value creation in different industries
	SLO – 2	Technology road map for industry 4.0	Real time information enabled material handling strategy	Cases – cyber security	Model application	smart manufacturing – maturity model, Smart agriculture, Smart city Smart life and smart health

Learning Resources	<ol style="list-style-type: none"> 1. ArshdeepBahga, Vijay Madiseti, Internet of Things – A hands on approach, ArshdeepBahga & Vijay Madiseti, 2014 2. Yingfeng Zhang, Fei Tao, Optimization of manufacturing using internet of things, Academic Press Elsevier, 2017. 3. Lihui Wang, Xi Vincent Wang, Cloud based cyber physical systems in manufacturing, Springer International Publishing, 2018. 	<ol style="list-style-type: none"> 4. Christoph Jan Bartodziej, The concept of industry 4.0 – An empirical analysis of technologies and applications in production logistics, Springer Gabler, 2017 5. Alp Ustundag, EmriChevikcan, Industry 4.0 - Managing the digital transformation, Springer International Publishing, 2018.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from industry	Expert from higher technical institution	Internal Expert
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram, skumaran@iiitdm.ac.in	1. Mr. Dinakar. N, SRMIST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr. Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE805T	Course Name	MANUFACTURING EXECUTION SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards		Nil	

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Identify the fundamental concepts of MES.
CLR-2 :	Utilize the core functions of MES.
CLR-3 :	Apply technical aspects of MES.
CLR-4 :	Identify the requirements of the factory of the future.
CLR-5 :	Evaluation of Cost Effectiveness in MES.
CLR-6 :	Implementation in Production and its significance.

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Apply the fundamental concepts and core function of MES
CLO-2 :	Understand what and why MES in modern production systems
CLO-3 :	Setup, analysis, and giving possible application of MES
CLO-4 :	Know the connection of function within production systems to MES
CLO-5 :	Identify the requirements of the factory of the future
CLO-6 :	Evaluate the Cost Effectiveness in MES

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
3	90	80	H	H	H	H	-	-	-	-	M	M	M	H	H	-	H
3	90	80	H	H	H	M	-	-	-	-	H	L	M	H	H	-	H
3	90	80	H	H	H	H	-	-	-	-	H	H	M	H	H	-	H
3	90	80	H	M	M	M	-	-	-	-	H	M	H	H	H	-	H
3	90	80	H	H	M	H	-	-	-	-	M	H	M	H	H	-	H
3	90	80	H	H	L	M	-	-	-	-	L	H	M	H	H	-	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Historical Development of MES, Standards of MES	Core Function—Production Flow-Oriented Design	Integration within the Overall Process	Software Architecture, Fundamental Variants
	SLO-2	Development of Business Data Processing	Cross-System Cohesiveness, Classification in the Overall System	Order Data Management	Overview of Central Components
S-2	SLO-1	Definitions of Terms - Classification of Terms	General and Complete Data Model, Origins of Master Data	Supply Management within the MES, Demand Planning	Platform Independence, Scalability
	SLO-2	Company Management Level	Data Model for Product Definition, Relevant Concepts	Interaction between the ERP System and the MES, Material Warehousing Costs	Flexible Adjustment versus Suitability for Updates
S-3	SLO-1	Production Management Level	The Operation, Work Plan, Parts List	The Planning Process and Planning Objectives	MES and Service-Oriented Architecture
	SLO-2	Control/Automation Level	Change Management and Product History	Forward Planning/Reverse Planning/Bottleneck Planning	Database, Resource Monitoring
S-4	SLO-1	Shortfalls of Existing Architectures and Solutions	Data Model for Resource Management.	Collision-Free Planning of a Time Container	Scaling the Database System
	SLO-2	Patchwork, No Common Database, Excessive Response Times	Description of Production Environment	The Importance of the Control Station	Data Management and Archiving, Running Maintenance
S-5	SLO-1	High Operating and Management Outlay	Description of Production Environment	Personnel Planning and Release of Orders	Interfaces with Other IT Systems

	SLO-2	Demands of Future Production Management Systems	Description of Production Environment	General Information on Order Processing and Classification	Usage and Visualization, Reporting, Automated Information Distribution	Sensient Technologies: Emulsions
S-6	SLO-1	Target Management, Integration of Applications and Data	Production Personnel	Order Preparation and Setup	Value-Benefit Analysis, General Information on Cost Effectiveness	Basic Quantity Units and Production Units
	SLO-2	Real-Time Data Management	Operating Resources	Order Control, Managing the Production Bin, Material Flow Control	Performance Measurement	Realization and Implementation
S-7	SLO-1	Lean Sigma and MES	Materials and Preliminary Products	Order Processing and Operating Data Recording	General Information on Evaluation	Basic Quantity Units and Production Units
	SLO-2	Commonalities between Existing Approaches and MES	Information and Documents	Process and Quality Assurance	The Benefits of an MES	Tasks of the MES, Challenges,
S-8	SLO-1	Norms and Guidelines, Recommendations	System and Auxiliary Data	Performance Data	Integrated Data Transparency, Reducing Time Usage	Realization and Implementation
	SLO-2	Adjacent Areas, Product Lifecycle Management	Order Fulfillment Data and Orders	Maintenance Management	Reducing Administration Expenses, Improved Customer Service	The MES as a Medium of Product-Development Management
S-9	SLO -1	Implementation Strategies	Production Data, Operating Data, and Machine Data	Preventive Maintenance and Repair	Early Warning System, Real-Time Cost Control	Standardization of Function Modules
	SLO -2	Points of Contact with MES	Derived Performance Data and Figures	Alarm Management	The Costs of an MES	Merging Consultancy Activities and IT Systems

Learning Resources	1. Heiko Meyer, Franz Fuchs, Klaus Thiel, <i>Manufacturing Execution Systems</i> , McGraw-Hill, 2009. 2. Jürgen Kletti, <i>Manufacturing Execution System</i> – Springer, 2010. 3. Bianca Scholten, <i>MES Guide for Executives</i> – International society of Automation, 2009.	4. Michael McClellan, <i>Applying Manufacturing Execution Systems</i> , CRC Press, 2007.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P.Kartikeyan, Head – Operations Improvement, Nokia India, kartikeyan.p@nokia.com	1. Dr.K.Senthilkumaran, Assistant professor, IIITDM, Kancheepuram, skumaran@iiitdm.ac.in	1. Mr.S.Thamilarasu, SRM IST
2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr. Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE806T	Course Name	ADDITIVE MANUFACTURING TECHNOLOGY	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:	Learning	Program Learning Outcomes (PLO)
CLR-1 :	Learn about Sustainable and Green Manufacturing Techniques	1 2 3	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
CLR-2 :	Aspects of Green supply chain and clean energy in manufacturing	Level of Thinking (Bloom)	Engineering Knowledge
CLR-3 :	Understanding the principle of green manufacturing	Expected Proficiency (%)	Problem Analysis
CLR-4 :	Learn about green in Manufacturing Processes	Expected Attainment (%)	Design & Development
CLR-5 :	Introduce the concept of life cycle analysis (LCA)		Analysis, Design, Research
CLR-6 :	Sustainability aspects in modern manufacturing enterprises		Modern Tool Usage
			Society & Culture
			Environment & Sustainability
			Ethics
			Individual & Team Work
			Communication
			Project Mgt. & Finance
			Life Long Learning
			PSO - 1
			PSO - 2
			PSO - 3

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:	Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
CLO-1 :	Understand the need for green and sustainable manufacturing	1	80	70	M	-	M	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Identification of clean energy and green supply chain in manufacturing	2	85	75	H	-	-	-	M	-	-	-	-	-	-	-	H	-	-
CLO-3 :	Apply the concepts green principles and industrial ecology tools	2	75	70	H	M	H	H	-	-	-	-	-	-	-	M	H	-	-
CLO-4 :	Identification the strategies for green manufacturing	2	80	75	H	-	M	-	M	-	-	-	-	-	-	-	H	-	M
CLO-5 :	Analyze the technologies enabling green manufacturing	1	75	70	H	-	-	M	-	-	-	-	-	-	-	M	M	-	H
CLO-6 :	Apply the concepts of sustainability in modern manufacturing enterprises	2	80	70	M	-	-	M	M	-	L	-	-	-	-	M	-	-	H

Duration (hour)		9	9	9	9	9
S-1	SLO-1	History and Need of AM	Preparation of CAD Model:	Stereo lithography (SLA) : Introduction to SLA	Selective Laser Sintering (SLS): Introduction to SLS	Materials for AM: Metals, Biomaterials for AM
	SLO-2	Evolution of AM	Interfacing of CAD and AM , File formats used in AM	Basic concepts and Working Principle of SLA	Basic concepts and Working Principle of SLS	Polymers for AM
S-2	SLO-1	Basic concepts and working principle of AM	Introduction to STL File format	Constructional details for SLA	Constructional details for SLS	Ceramics for AM
	SLO-2	Additive Manufacturing vs Subtractive manufacturing	Problems (Errors) with STL file	Advantages of SLA	Advantages of SLS	Composites for AM
S-3	SLO-1	AM Process chain	Reverse engineering: Need for Reverse engineering, Introduction to Co-ordinate Measuring machine (CMM)..	Limitations of SLA	Limitations of SLS	Applications of AM in Manufacturing and tooling
	SLO-2	AM Process chain	Reverse engineering: CMM measurement process – Data collection, Digitization from surface, Preprocessing, Surface fitting.	Applications of SLA	Applications of SLS	Applications of AM in Space
S-4	SLO-1	Rapid prototyping on product development	Rapid tooling	Fused deposition modelling (FDM) : Introduction to FDM	Laser Engineered Net Shaping (LENS): Introduction to LENS	Applications of AM in Automotive industry
	SLO-2	Rapid prototyping on product development	Rapid tooling	Basic concepts and Working Principle of FDM	Basic concepts and Working Principle of LENS	Applications of AM in Aerospace industry
S-5	SLO-1	Classification of AM processes	Design for AM: Part orientation	Constructional details for FDM	Constructional details for LENS	Applications of AM in Biomedical industry
	SLO-2	Classification of AM processes	Removal of supports	Advantages of FDM	Advantages of LENS	Applications of AM in Biomedical industry

S-6	SLO-1	Other Related technologies: Overview about other technologies related to AM	Hollowing out parts	Limitations of FDM	Limitations of LENS	Applications of AM in Jewellery industry
	SLO-2	Computer Aided Engineering (CAE)	Inclusion of Undercuts and other manufacturing constraints	Applications of FDM	Applications of LENS	Applications of AM in Various other fields.
S-7	SLO-1	Haptic based CAD	Interlocking features, Reduction of part count in assembly	Laminated Object Manufacturing (LOM) : Introduction to LOM	Electron Beam Melting (EBM): Introduction to EBM	Introduction to Direct digital manufacturing (DDM)
	SLO-2	Haptic based CAD	Identification markings / numbers	Basic concepts and Working Principle of LOM	Basic concepts and Working Principle of EBM	Rapid prototyping vs DDM
S-8	SLO-1	AM unique capabilities: Shape complexity, Hierarchical complexity	Engineering design rules for AM: Tolerances – Digital to Object	Constructional details for LOM	Constructional details for EBM	Future directions of AM
	SLO-2	AM unique capabilities: Functional complexity, Material complexity	Design freedom, Relative fit	Advantages of LOM	Advantages of EBM	Future directions of AM
S-9	SLO-1	Benefits of AM.	Flexures, Hinges, Snap fits	Limitations of LOM	Limitations of EBM	Digiproneurship
	SLO-2	Limitations of AM.	Orientation and Clamping	Applications of LOM	Applications of EBM	Digiproneurship

Learning Resources	1. Li Yang, Keng Hsu, Brian Baughman, Donald Godfrey, Francisco Medina, Mamballykalathil Menon, Soeren Wiener, Additive Manufacturing of Metals	4. Andreas Gebhardt, Understanding Additive Manufacturing. Rapid Prototyping - Rapid Tooling - Rapid manufacturing, Hanser publications 2011.
	2. The Technology, Materials, Design and Production", Springer 2017. 3. Ian Gibson, David Rosen, Brent Stucker, Additive Manufacturing Technologies_ 3D Printing, Rapid Prototyping, and Direct Digital Manufacturing", Springer 2015.	5. T. S. Srivatsan and T. S. Sudarshan, "Additive Manufacturing Innovations, Advances, and Applications, Taylor & Francis group 2016. 6. Ali K Kamrani, Emad Abouel Nasr, Rapid prototyping - Theory and Practice", Springer 2005.

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr. Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cwrde.drdo.in		

Course Code	18MEE807T	Course Name	INDUSTRIAL ROBOTICS AND MATERIAL HANDLING SYSTEMS	Course Category	E	Professional Elective	L	T	P	C
							3	0	0	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards		Nil	

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Introduce the basic concepts, parts of robots and types of robots
CLR-2 :	Familiar with the various drive systems for robot, sensors and their applications in robots and programming of robots
CLR-3 :	Select the robots according to its usage
CLR-4 :	Know about the various applications of robots, justification and implementation of robot
CLR-5 :	Know about material handling in a system
CLR-6 :	Acquire knowledge on various material handling equipment used both in automated and non-automated systems

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Understand the fundamentals of robot technology, sensors, drives and systems
CLO-2 :	Recognize the ideas about robot cell design, work cell control
CLO-3 :	Have knowledge about various applications of robots in material handling
CLO-4 :	Understand the concepts of automated material handling and its types
CLO-5 :	Identify the application of automated guided vehicles in material handling
CLO-6 :	Recognize about vehicle guidance and routing in material handling

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
2	90	85	H	-	H	L	M	-	-	-	-	-	H	-	H	-	H
2	90	85	H	-	H	L	M	-	-	-	-	-	H	-	H	-	H
1	90	85	M	-	M	L	M	-	-	-	-	-	L	-	H	-	H
2	90	85	L	-	L	L	M	-	-	-	-	-	M	-	H	-	H
1	90	85	M	-	H	L	M	-	-	-	-	-	M	-	H	-	H
2	90	85	H	-	H	L	M	-	-	-	-	-	M	-	H	-	H

Duration (hour)	9	9	9	9	9
S-1	SLO-1 Automation and Robotics	Robot cell layouts- Robot centered cell	General consideration in Robot Material Handling	Automated material handling	Automated Guided Vehicle Systems - Introduction
	SLO-2 History of Robots	In line Robot cell	Material Transfer Application	Hand trucks, Powered trucks	Introduction to Drones
S-2	SLO-1 Robot Anatomy	Mobile robot cell	Pick and place operations	Cranes monorails and Hoists	Driverless Trains
	SLO-2 Robot configurations	Multiple robots and machine Interface	Palletizing and related operations	Conveyors systems	AGVs Pallet Trucks
S-3	SLO-1 Robot motions, Joint Notation Scheme	MR- MI Example	Machine loading and unloading	Selection of material handling equipment	AGVs Unit load carriers
	SLO-2 Work volume	Other considerations in work cell design	Die casting, plastic molding	Principles of material handling	Driverless train operation
S-4	SLO-1 Polar, Cylindrical, Cartesian	Work cell control	Forging, Machining operations	Roller, stake wheel conveyor	Storage/ Distribution system
	SLO-2 Robot drive systems	Sequence control	Stamping press operations	Belt, chain conveyors	Assembly line operation
S-5	SLO-1 Speed of motion	operation interface	Robots in spot welding	Overhead trolley conveyor	Miscellaneous operation
	SLO-2 Load carrying capacity	Safety monitoring	Robots in arc welding	slat conveyors	Functions of AGV
S-6	SLO-1 4 types of robot control system	Interlocks	Problems for Robots in arc welding	In floor towline conveyor	Vehicle guidance and routing
	SLO-2 Precision of movement	Error detection and recovery	Features of the welding robot	Cart on track conveyor	Operation of on board sensor system
S-7	SLO-1 End effectors- types of grippers	Work cell controller	Sensors in arc welding robot	Other handling equipment, Dial Indexing tables	Frequency select, path switch select method
	SLO-2 Gripper selection and design	Robot controller	Vision based systems, Benefits	Elevators, Pipelines	Traffic control and safety
S-8	SLO-1 Transducers and sensors	Electro mechanical Relays, Programmable controllers	Robots in Spray coating	Containers, Highway Tractor trailers	On board vehicle sensing, zone blocking

	SLO-2	Tactile sensors	A computer as the work cell controller	Immersion and flow coating, Spray coating methods	Railway trains, Cargo aircraft, Ship, barges.	System management, On board control panel
S-9	SLO-1	Proximity and Range sensors	Robot cycle time analysis	Benefits of robot spray coating	Types of AS / RS	Remote call stations, Central computer control
	SLO-2	Uses of sensors in robotics	Elements in RTM	Other Processing operations using robots	Advanced ware housing robots, Applications.	Automotive Intelligent vehicles

Learning Resources	1. Mikell P Groover, Mitchell Weiss, Rogen N Nagel, Nicholas G Odrey, Ashish Dutta, Industrial Robotics Technology, Programming, and Applications, Tata McGraw Hill Special Indian Edition, 2012. 2. K.Lalit Narayan, K.Mallikarjuna Rao, Computer Aided Design and Manufacturing, Prentice Hall of India, 2008. 3. Mikell P Groover, Mitchell Weiss, Roger N Nagel, Industrial Robotics Technology, Programming, and Applications, Tata McGraw Hill Publishers, 2008.	4. S.R.Deb, S.Deb, Robotics Technology & Flexible Automation, Tata McGraw-Hill Education, 2012. 5. James A Rehg, Introduction to Robotics in CIM system, Prentice Hall, 2002. 6. S.K.Saha, Introduction to Robotics, Tata McGraw Hill Publishing Company Limited, 2014.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
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2. Dr. R. Kalimuthu, ISRO, Mahendragiri, r_kalimuthu@vssc.gov.in	2. Dr.B.Mohan, Professor, Anna University, mohan@mitindia.edu	2. Dr. Suresh Kannan I, SRMIST
3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		

Course Code	18MEE808T	Course Name	SUSTAINABLE GREEN MANUFACTURING	Course Category	E	Professional Elective	L 3	T 0	P 0	C 3
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Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards	Nil		

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	Learn about Sustainable and Green Manufacturing Techniques
CLR-2 :	Aspects of Green supply chain and clean energy in manufacturing
CLR-3 :	Understanding the principle of green manufacturing
CLR-4 :	Learn about green in Manufacturing Processes
CLR-5 :	Introduce the concept of life cycle analysis (LCA)
CLR-6 :	Sustainability aspects in modern manufacturing enterprises

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Understand the need for green and sustainable manufacturing
CLO-2 :	Identification of clean energy and green supply chain in manufacturing
CLO-3 :	Apply the concepts green principles and industrial ecology tools
CLO-4 :	Identification the strategies for green manufacturing
CLO-5 :	Analyze the technologies enabling green manufacturing
CLO-6 :	Apply the concepts of sustainability in modern manufacturing enterprises

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
2	90	90	H	H	-	-	-	H	H	-	-	-	-	H	-	-	H
2	85	80	H	-	H	H	-	H	H	-	-	-	-	H	-	-	H
2	85	80	H	-	M	L	-	H	H	-	-	-	-	-	-	-	H
2	85	85	M	L	-	-	-	H	H	-	-	-	-	H	-	-	M
2	90	85	M	L	H	H	M	H	H	-	H	-	-	H	-	-	M
2	85	70	H	H	H	H	M	H	H	-	H	-	-	H	-	-	M

Duration (hour)	9	9	9	9	9
S-1	SLO-1	Concept of Sustainability	Introduction to thermodynamics analysis in manufacturing processes	Principle of Green Manufacturing	Functions and types of cutting fluids
	SLO-2	Introduction to green Manufacturing	Thermodynamic framework of manufacturing processes	Cleaner Production , Dematerialization	Problems related to cutting fluids
S-2	SLO-1	Motivations for sustainable development	Estimation of minimum work for materials transformations	Closed Loop Production systems Economic and Ecological Benefits of Closed-Loop Systems	Dry machining
	SLO-2	Motivations for sustainable Manufacturing	Estimation of minimum work for materials transformations	Design for Disassembly, Industrial Metabolism	Advantages and Limitations
S-3	SLO-1	Productivity and sustainability	Estimation of minimum work for materials transformations	Adoption of low carbon technologies	Near dry machining
	SLO-2	Metrics for green manufacturing	Temperature and Pressure Changes for Open Materials-Processing Systems	Need to reduce the carbon footprint of manufacturing operations	Advantages, Disadvantages
S-4	SLO-1	Societal metrics	Energy use for elastic – plastic deformation	Life Cycle assessment	Minimum Quantity Lubrication systems
	SLO-2	Economic Metrics	Electric energy used in manufacturing processes	Life cycle assessment elements	Economics of Environmentally Friendly Machining
S-5	SLO-1	Environmental metrics	Resource accounting	Life cycle assessment procedure	Development of Environmentally Friendly Lean Manufacturing Techniques

					cutting fluids, cutting tools and machine tools	
	SLO-2	Barriers to Green Manufacturing	Introduction to Clean Energy Technologies	Life Cycle Assessment (LCA) of Machine tools	Enabling Technologies for Green Manufacturing	Agile Manufacturing
S-6	SLO-1	Advantages and Limitations of Green manufacturing	Solar Photovoltaic	Design for Environment	Sustainable solutions	Components of the agile manufacturing system/enterprise
	SLO-2	Environmental Impact of Manufacturing	Wind Energy	Product life extension and the service economy	Adoptronics in Machine tools	Comparison between agile and traditional manufacturing enterprises
S-7	SLO-1	Standards for green manufacturing	Fuel cells	Eco Labelling, Industrial Ecology tools	Reconfigurable Machine tools	Analysis of Manufacturing Firms for Agility
	SLO-2	ISO 14000	Comparison of lean Energy Technologies	Case studies in Industrial Ecology	Process Monitoring System	Remanufacturing
S-8	SLO-1	OHSAS 18000	Application Potentials of clean energy supply in green manufacturing	Case studies in Industrial Ecology	Smart building blocks	Recycling
	SLO-2	Sustainability rating schemes	Cost benefit of environmental emission mitigation through clean energy supply	How is Industrial Ecology Viewed by Industry	Add-ons for machine tool upgrade	Materials for sustainability and recycling
S-9	SLO-1	Strategies for Green Manufacturing	Technological Performance of clean Energy Supply.	Awareness of Industrial Ecology and its components	Applying Sensor Flows in Decision Making (Automated Manufacturing) Manufacturing Complexity	Sustainability Assessments of Competitive Manufacturing Strategies
	SLO-2	Strategies for Green Manufacturing	Energy efficient manufacturing processes	Case studies of product improvement and redesign	Environmental implications of nano manufacturing and Semiconductor manufacturing	Sustainability Assessment for Industrial Estates

Learning Resources	<ol style="list-style-type: none"> 1. Dornfeld, David A., ed. <i>Green manufacturing: fundamentals and applications</i>. Springer Science & Business Media, 2012. 2. Gouge, Michael, and Pan Michaleris, eds. <i>Thermo-mechanical modeling of additive manufacturing</i>. Butterworth-Heinemann, 2017. 3. Davim, J. Paulo, ed. <i>Sustainable Manufacturing</i>. John Wiley & Sons, 2013. 4. Dixit, Uday S., D. K. Sarma, and J. Paulo Davim. <i>Environmentally friendly machining</i>. Springer Science & Business Media, 2012. 5. Stark, Rainer, Günther Seliger, and Jérémy Bonvoisin. <i>Sustainable Manufacturing</i>. Springer, 2017. 	<ol style="list-style-type: none"> 6. Garbie, Ibrahim. <i>Sustainability in manufacturing enterprises: Concepts, analyses and assessments for industry 4.0</i>. Springer, 2016. 7. Madu, Christian N., ed. <i>Handbook of environmentally conscious manufacturing</i>. Springer Science & Business Media, 2012. 8. Fiksel, Joseph. <i>Design for environment: a guide to sustainable product development: eco-efficient product development</i>. McGraw Hill Professional, Boston, 2009.
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Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40%	-	30%	-	30%	-	30%	-	30%	-
	Understand										
Level 2	Apply	40%	-	40%	-	40%	-	40%	-	40%	-
	Analyze										
Level 3	Evaluate	20%	-	30%	-	30%	-	30%	-	30%	-
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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3. Dr. A. Velayutham, DRDO, Avadi, velayutham.a@cvrde.drdo.in		



Course Code	18MEE809J	Course Name	DATABASE MANAGEMENT SYSTEM	Course Category	E	Professional Elective	L	T	P	C
							2	0	2	3

Pre-requisite Course	Nil	Co-requisite Course	Nil	Progressive Courses	Nil
Course Offering Department	Mechanical Engineering	Data Book/Codes/Standards		Nil	

Course Learning Rationale (CLR):	The purpose of learning this course is to:
CLR-1 :	To impart an introduction to the theory and practice of database systems
CLR-2 :	To learn various database models and query language.
CLR-3 :	To understand effective manipulation of memory space for database files.
CLR-4 :	To understand the normalization in building effective database table
CLR-5 :	To protect the data and database from foreign access

Course Learning Outcomes (CLO):	At the end of this course, learners will be able to:
CLO-1 :	Develop the terminology and features in database
CLO-2 :	Analyze the information of storage details
CLO-3 :	Transform an information into relational database
CLO-4 :	Ability to work in data manipulation
CLO-5 :	Analyze the Client/Server and Internet Database Environment
CLO-6 :	Write queries for design and manipulation of database table using MySQL or Oracle

Learning			Program Learning Outcomes (PLO)														
1	2	3	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Level of Thinking (Bloom)	Expected Proficiency (%)	Expected Attainment (%)	Engineering Knowledge	Problem Analysis	Design & Development	Analysis, Design, Research	Modern Tool Usage	Society & Culture	Environment & Sustainability	Ethics	Individual & Team Work	Communication	Project Mgt. & Finance	Life Long Learning	PSO - 1	PSO - 2	PSO - 3
2	90	85	H	M	-	M	-	-	-	-	M	H	-	M	-	-	-
2	90	85	H	L	-	-	-	-	-	-	-	H	-	L	-	-	-
2	90	85	H	M	M	M	-	-	-	-	M	H	-	H	-	-	-
2	90	85	H	L	-	-	-	-	-	-	M	L	-	L	-	-	-
2	90	85	H	M	-	L	-	-	-	-	-	H	-	M	-	-	-
2	90	85	H	H	M	M	M	-	-	-	M	H	-	H	-	-	-

Duration (hour)	12	12	12	12	12
S-1	SLO-1	Introduction to database Systems	Entity types	Relational Model	Structured Query Language (SQL)
	SLO-2	History of DBMS applications	Entity sets	Structural of database	SQL Data definition
S-2	SLO-1	File System versus a DBMS	Attributes and Keys	Structure of relational Databases	Queries on Single Relation
	SLO-2	Database Language	Basic building blocks	Keys, Schema Diagram	Queries on multiple Relations
S-3	SLO-1	Lab 1: Creating database table	Levels of data abstraction	Relational Algebra	Overview of SQL
	SLO-2		Physical Schemas and Conceptual Schemas	Relational Algebra - Set Operation, Renaming,	Basic structure of SQL Queries
S-4	SLO-1	Lab 2: DDL Commands	Overview of Entity-Relationship (E-R) Model	Relational Algebra - Joins	Lab 9: Simple queries
	SLO-2		Relationship set, Entity set	Relational Algebra - Division	
S-5	SLO-1	Database Interface	Database design and Entity-Relationship(ER) Model, Design alternatives	Lab 7: Joining tables	Storage, Data access
	SLO-2	Form based Interface, Graphical based Interface	Constraints, Entity-Relationship (ER)-Diagrams, Roles and Structural Constraints		Buffer Management
S-6	SLO-1	Database Environment	Lab 4: Basic SELECT statements	Relational Algebra - Division	Database – Backup
	SLO-2	Database Component Modules		Extended Relational Algebra Operations	Recovery Algorithm

S-7	SLO-1	Database System utilities	Lab 5: Advanced SELECT statements	Views	Lab 11: Creation, Insertion, Updating, Deletion of Views operation	Lab 14: DBMS for CAD software design
	SLO-2	Database System Architecture		Functional Dependency		
S-8	SLO-1	Lab 3: Data Manipulation Commands	Entity-Relationship(ER) Design Issues	Various process in designing a Database	Aggregate functions - Basic aggregation	Emerging Database technology - Mobile database
	SLO-2		E-R Model and Enhanced entity-relationship (EER) Model	Lab 8: Basic SQL functions	Aggregate functions- Aggregation with Grouping	Emerging Database technology - Multimedia database
S-9	SLO-1	Data Independence	Enhanced entity-relationship (EER) Model		Lab 12: Basics of PL/SQL	Access controls
	SLO-2	Data Mappings	Enhanced entity-relationship(EER)-Specialization	Normalization using functional dependencies		Security for internet applications
S-10	SLO-1	Structure of DBMS	Enhanced entity-relationship(EER)-Generalization	Decomposition	Null values, Joins, Nested queries	Web Technology in Smart Manufacturing
	SLO-2	Security and Authorization,	Enhanced entity-relationship(EER)-Attribute Inheritance	Boyce-Codd Normal Form	Client/Server Database Environment	Web Technology in Smart Manufacturing
S-11	SLO-1	Database Tuning	Constrain on Generalization	DBMS application in Computer Integrated manufacturing	Basics of Ontology Language and its applications.	DBMS for computer integrated manufacturing
	SLO-2	Data Models	Aggregation	3NF, Correctness of the 3NF Algorithm	Design Challenges in SPARQL,	Material Handling System Design
S12	SLO-1	Types of DBMS	Lab 6: Constraints in Tables	Comparison of BCNF and 3NF	SPARQL Query Forms,	Lab 15: Report Generation for Material Handling System Design
	SLO-2	Objective data model and Hierarchical data model		Normalization using multivalued dependencies	SPARQL Graph Patterns	

Learning Resources	1. RamezElmasri, Shanmkant B., Fundamentals of Database System, 5 th Edition, Pearson, 2011.	4. Hansen, Gary W., and James V. Hansen. Database management and design. 1996.
	2. Silberschatz, Abraham, Henry F. Korth, and ShashankSudarshan. Database system concepts. Vol. 4. New York: McGraw-Hill, 1997.	
	3. Ramakrishnan, Raghu, and Johannes Gehrke. Database management systems. McGraw Hill, 2000.	5. Peter rob, Carlos Coronel, Database Systems – Design, Implementation, and Management , 9 th Edition, 2009, Thomson Learning System Software Needed: Oracle 8, MySQL

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% Weightage)								Final Examination (50% Weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	20%	15%	15%	15%	15%	15%	15%	15%	15%
	Understand										
Level 2	Apply	20%	20%	20%	20%	20%	20%	20%	20%	20%	20%
	Analyze										
Level 3	Evaluate	10%	10%	15%	15%	15%	15%	15%	15%	15%	15%
	Create										
	Total	100%		100%		100%		100%		100%	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

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