ACADEMIC CURRICULA

UNDERGRADUATE/ INTEGRATED POST GRADUATE DEGREE PROGRAMMES

(With exit option of Diploma)

(Choice Based Flexible Credit System)

Regulations 2021

Volume - 7
(Syllabi for Automobile Engineering Programme Courses)
(Revised on Jul 2024)



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Chengalpattu District 603203, Tamil Nadu, India

ACADEMIC CURRICULA

Professional Core Courses

Regulations 2021



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Chengalpattu District 603203, Tamil Nadu, India

Course		Course	APPLIED THERMAL ENGINEERING	Course	_	PROFESSIONAL CORE	L	Т	Р	С	
Code	21AUC2011	Name	APPLIED THERWAL ENGINEERING	Category	C	PROFESSIONAL CORE	3	0	0	3	

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offerin	ng Department	Automobile Engineering	Data Book / Codes / Standards		Nil

THE RESERVE

Course L	earning Rationale (CLR): The purpose of learning this course is to:	111	4			Progi	ram Ou	itcome	s (PO)					rogra	
CLR-1:	identify the fundamental concepts of thermodynamic systems and energy transfer	1	2	3	4	5	6	7	8	9	10	11	12		pecifi itcom	
CLR-2:	utilize thermodynamic laws and their applications	dge		of	US.	1	. "-			Work		9				
CLR-3:	utilize the concept of pure substance and rankine cycle	Knowlec	w	Jent	stigation	Usage	Ъ	. 1		am W		Finance	д			
CLR-4:	enlighten the knowledge in Otto, Diesel, Dual cycle		nalysis	velopment	estig		r and	y k	h.	Теа	ation	∞ర	arning			
CLR-5:	construct knowledge on air compressors, refrigeration systems and air conditioning systems	ering	⋖	ล	t inv	Tool	engineer sty	Environment 8 Sustainability		<u>ھ</u>	<u>ان</u>	Mgt.	gLe			
		9	roblem	ign/de	duct	dern		iron taina	SS	ndividual	nwu	Project	Long	7	2-0Sc	-3
Course O	Outcomes (CO): At the end of this course, learners will be able to:	Engi	Pro	Des	ည် မိ	Mod	The	Env Sus	Ethics	Indi	Sol	Proj	Life	PSO-1	PS(PSO-3
CO-1:	apply the concept of thermod <mark>ynamic properties to quantify energy transfer</mark>	3	2		٠.,	-	-7	-		-	-	-	-	3	2	-
CO-2:	apply thermodynamic laws to analyze various thermodynamic systems, Exergy analysis	3	2	125	7 -4	-	4	-	-	-	-	-	-	3	2	-
CO-3:	apply the concept of entropy and availability to thermodynamic systems and to do	1 / x	2	1	1	-	-	-		-	-	-	-	-	2	1
CO-4:	evaluate the properties of pure substances and analyze vapour power cycles	11 34	2	1	-	-	-	-	1	-	-	-	-	2	_	1
CO-5:	calculate performance of air conditioning system using Psychrometric chart and applications automotive climate control	in _	+ 4	1		-	Ċ	2	-	-	-	-	-	-	-	1

Unit-1 – Concept of Energy, Systems, Processes, Work and Laws of Thermodynamics

9 Hour

Thermodynamic system, control volume, properties, state, process and cycle, thermodynamic equilibrium, Quasi-static process, pure substance, state postulate, concept of temperature, zeroth law of thermodynamics, work and heat interactions, path function and point function, PdV work for various quasi-static processes, tutorials on work and heat transfer. First law of thermodynamics for a closed system, Forms of energy, concept of total energy E, Tutorials on first law of thermodynamics for a closed system, constant volume, constant pressure, process in which PV=C, Tutorials on poly tropic, adiabatic process, Combination of different process, Internal energy and Enthalpy, specific heats, derivation of general energy equation for a control volume, application of SFEE to various steady flow devices, Tutorial on first law applied to various steady flow devices

Unit-2 – Limitations of First Law and Second Law of Thermodynamics

9 Hour

Limitations of first law of thermodynamics, cyclic heat engine, energy reservoirs, pump, thermal efficiency and COP, Kelvin – Planck and Clausius statement of second law of thermodynamics, reversible and irreversible process, causes of irreversibility, Carnot cycle, working of a Carnot engine, thermal efficiency of a Carnot engine engine engine engine efficiency of a Carnot engine engine efficiency of a Carnot engine engine engine engine engin

Unit-3 - Pure Substances 9 Hour

Phase change phenomenon of a pure substance, Property diagrams for phase change process, T-V, P-V, P-T diagram, P-v-T surface, Critical point and Triple point, T-s and h-s diagram, Dryness fraction, Use of Steam tables, Mollier chart, Identification of states & determination of properties, Tutorials oncalculation of steam properties, Rankine cycle, Operation of Rankine cycle, Analysis of Rankine cycle, Problems solving on Rankine cycle, Reheat – regeneration in Rankine cycle – Organic Rankine cycle

Unit-4 - Properties of Ideal Gases 9 Hour

Equation of state, Vander Waal's equation of state, specific heats and entropy of gas mixtures, Maxwell's relations, T-ds relations, Equations for dH and dU, Clausius — Clapeyron Equation, Joule — Thomson experiment, Joule — Thomson coefficient, Tutorials on Thermodynamic relations, Introduction, air standard cycles—Otto cycle, Diesel cycle, Dual cycle—significance, Pv and Ts diagram, work done, mean effective pressure, brake thermal efficiency

Unit-5 – Air Compressor 9 Hour

Construction and Working of Single acting and double acting air compressors, basics of Intercooler, construction, working of multi – stage air compressor, compressor – Isentropic, adiabatic and polytropic, work done without clearance volume – FAD definition – fundamentals of refrigeration cycle – simple vapor compression refrigeration system, simple vapor absorption refrigeration system – construction and working, desirable properties of an ideal refrigerants. Properties of atmospheric air, psychrometric chart, dry bulb temperature and wet bulb temperature, psychrometric processes- sensible heating and cooling, humidification, dehumidification, cooling and dehumidification heating and humidification, Bypass factor for heating and cooling coils, application of air conditioning systems in automobiles, study of Automotive air conditioning systems, automotive climate control – climate governing factors

Learning Resources
Resources

- 1. Mahesh M. Rathore, Thermal Engineering, Tata McGraw HillEducation, 2012
- Yunus. Acengel., Michael A Boles, Thermodynamics An Engineering Approach, 8th ed. Tata McGraw Hill- Education, 2015
- 3. Nag. P.K, Engineering Thermodynamics, 5th edition, Tata McGraw Hill Education, 2013
- 4. R. Rudramoorthy, Thermal Engineering, 4th ed., Tata McGraw-Hill, 2007
- 5. C.P. Kothandaraman, Fundamentals of Heat and Mass Transfer, 4th ed., New Age International Publishers, 2012

Learning Assessm	ent		17/2011	- Charles		2			
	Bloom's Level of Thinking	Formative CLA-1 Average of u	A 100 A 100		4-2	Final Ex	mative amination eightage)		
		Theory (50%)	Practice	Theory (10	%) Practice	Theory	Practice		
Level 1	Remember	15%			15%	• -	15%		
Level 2	Understand	25%	The sale of	to the second second	20%	-	25%		
Level 3	Apply	30%		F 18: 34	25%	-	30%		
Level 4	Analyze	30%	The same of	/ / / / /	25%		30%		
Level 5	Evaluate		- 1077	-	10%	-	-		
Level 6	Create	- L	- 1.7	-	5%	-	-		
	Total	100 %	7) 11') %	100 %				

Course Designers		/ /
Experts from Industry	Experts from Higher Technical Institutions	Internal Exp <mark>erts</mark>
1. Dr. Gunabalan, Manager, R&D Turbo Energy, Chennai,	1. Dr. Chandramohan, NIT Warangal,	1. Mr. <mark>S. Logesh</mark> waran, SRMIST
2. Mr. Shantha Kumar, Lead Engineer, Royal Enfield,	2. Dr. Ganesh, Anna University, Chennai	2. D <mark>r. C. Prabh</mark> u, SRMIST

Course	04 4 1 1 0 0 0 0 1	Course	ALITOMOTIVE ENGINES	Course	0	DDOLLGGIONAL CODE	L	Т	Р	С
Code	21AUC202J	Name	AUTOMOTIVE ENGINES	Category	C	PROFESSIONAL CORE	2	0	2	3

Pre-requisite Courses	N	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offer	ing Department	Automobile Engineering	Data Book / Codes / Standards		Nil

Course L	Learning Rationale (CLR): The purpose of learning this course is to:	41 1	A			Progr	am Oı	utcome	s (PO)					rogran	
CLR-1:	know about Various components of the engi <mark>ne, material</mark> s and its functions	1	2	3	4	5	6	7	8	9	10	11	12		pecific Itcome	
CLR-2:	impart knowledge about the combustion process in SI Engine	de)	of	SL	1				ork		g				
CLR-3:	impart knowledge about the combustion process in CI Engine	wed w		velopment	vestigations x problems	age	Ъ			μ		nance	ρ			
CLR-4:	provide an insight about the lubrication, cooling system used in IC engines	Knowle	Analysis	ndol	estig	l Us	er and	∞ ∞ >	b.	Team	ţį	& Fin	arning			
CLR-5:	provide an insight about the turbo, supercharging and scavenging system in IC Engines	erina	, An	deve	(i = 6)	\vdash	enginee stv	ment		<u>8</u>	ınication	Mgt.	g Le			
			₽.	ign/e	duct	lem	eng etv	taing	S	ndividual	nwwc	oject l	Long	7	7-5	<u>ج</u>
Course C	Outcomes (CO): At the end of this course, learners will be able to:	Engine	Probl	Des	g G	Moo	The	Envi	Ethi	lpdi	Con	Proj	Life	PSO.	PSO-2	PSO-3
CO-1:	identify the components of the engine, materials and its functions	3	- 3	100	-	7	7	-	-	-	-	-	-	3	3	-
CO-2:	evaluate the performance of SI Engines	3	3	75	-	-		-	-	-	-	-	-	3	3	-
CO-3:	evaluate the performance of <mark>CI Engin</mark> es	3	3	1 -	1.4	-	_	-		-	-	-	-	3	3	-
CO-4:	understand the lubrication a <mark>nd cooli</mark> ng system in IC Engines	3	3	421	-	-	-	2	-	-	-	-	-	3	3	-
CO-5:	understand the turbo, super <mark>charging</mark> and scavenging system in IC Engines	3	3	-	-	-		2		-	-	-	-	3	3	-

Unit-1 – Intake and Exhaust Systems Components

12 Hour

Constructional details of engine components —Functions and materials- Valve timing diagram for SI and CI engine- Port timing diagram for SI and CI engine- Firing order and its significance —Tutorial 1: Comparison of Valve Timing Diagrams for SI and CI engine —Intake system components — Discharge coefficient, Pressure drop Air filter, intake manifold, Connecting Pipe Exhaust system components Exhaust manifold and exhaust pipe Spark arresters Exhaust mufflers, Types and operation-Exhaust after treatment systems.

Practice:

1. Dismantling study and assembling of IC engines - Measurement of Bore, Stroke, Ovality and Taper, 2. Valve Timing Diagram for Four Stroke Engine and port Timing Diagram for Two Stroke Engine

Unit-2 - Combustion in SI Engine

12 Hour

Stages of combustion-Nature of charge –Flame propagation –Flame velocity and area of flame front- Rate of pressure rise – Cycle to cycle variation- Abnormal combustion – Theories of detonation-Comparison of SI and CI engine combustion process- Introduction to Combustion chambers - Effect of engine operating variables on combustion –combustion chambers types-factors controlling combustion chamber designModelling SI engine combustion. -Overview

Practice:

1. Study of fuel supply system, 2. Performance test on Petrol engine

Unit-3 - Combustion in CI Engine

12 Hour

Stages of combustion-Nature of charge – Mixture formation in CI engines – Importance of air motion Swirl, squish and turbulence Swirl ratio. Fuel air mixing – Factors affecting delay period- Knocking in CI engines – methods of controlling diesel knock- CI engine combustion chamber: Types – Design objectives – Factors influencing Combustion chamber design- Modelling CI engine combustion. -Overview-Advanced combustion concepts: Homogeneous charged compression ignition- Premixed charged compression ignition-Reactivity charged compression ignition.

Practice:

1 .Performance test on diesel engine, 2. Test for optimum coolant flow rate in IC engines

Unit-4 – Lubrication and Cooling Systems

12 Hour

Need for cooling system- Types of cooling system —Air cooled system-Liquid cooled system—Thermosyphon system- Forced circulation system- pressure cooling system—Properties of coolant- additives for coolants Need for lubrication system- Lubrication methods: Mist lubrication system- your sump lubrication—Properties of lubrication of oil.

Practice:

Determination of viscosity of the lubricating oil. 2. Determination of flash and fire point of the fuel.

Unit-5 - Turbo Charging, Supercharging and Scavenging

12 Hour

Objectives of Super charging-Methods to boost the engine power —Turbo charging methods-Thermodynamics of Turbocharging —Turbo lag-Windage losses Engine exhaust manifold arrangements-Classification of scavenging systems Mixture control through Reed valve Induction — Charging Processes in two-stroke cycle engine — Terminologies Shankey diagram — perfect displacement, perfect mixing.

Practice:

1. Energy Balance test on an Automotive Diesel Engine. 2 Morse test on petrol engines

Learning Resources

- 1. Ganesan V, "Internal combustion engines", 4th edition, TataMcGraw Hill Education, 2012.
- 2. Rajput R. K, "A textbook of Internal Combustion Engines", 2nd edition, Laxmi Publications (P) Ltd, 2007.
- 3. Internal Combustion Engine Fundamentals, 2nd Edition. John B. Heywood. ISBN: 9781260116106. Publication Date & Copyright: 2018.McGraw-Hill Education
- 4. Ramalingam K. K, "Internal Combustion Engines", Second Edition, Scitech Publications, 2009
- 5. Edward F, Obert, "Internal Combustion Engines and Air Pollution", IntextEducation Publishers, 1980

		7	Continuous Learning	Assessment (CLA)		Cum	motivo	
	Bloo <mark>m's</mark> Level of <mark>Thinkin</mark> g	Level of Thinking (45%) CLA-1 Average of unit test CLA-2- Practice (45%) (15%)				Summative Final Examination (40% weightage)		
		Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	15%	N 707 2		15%	15%	-	
Level 2	Understand	25%	1 - Land	P 200	25%	25%	-	
Level 3	Apply	30%		25 No. 3 Land	30%	30%	-	
Level 4	Analyze	30%		A 100	30%	30%	-	
Level 5	Evaluate	- , , , , , , , , , , , , , , , , , , ,	m - 11/2/1	-	-4		-	
Level 6	Create	rela le	- 1.9	-		-	-	
	Total	10	0 %	100	%	10	0 %	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Exp <mark>erts</mark>
1. Mr.Jayaraman.R,BLG Logistics,jayaraman.r@blgparekh.com	Dr.M.Parthasarathy, Vel Tech,nparthasarathy@veltech.edu.in	1. Dr. T <mark>.Prakash,</mark> SRMIST
2. Mr. Shanmuga Sundaram, RNTBCI,	2. Dr.P.Nanthakumar, Amrita school of Engineering,	2. Dr <mark>. C.Prabh</mark> u, SRMIST
sankaran@rntbci.com	p_nanthakumar@cb.amrita.edu	

Course 21AU	Course	MANUFACTURING TECHNOLOGY FOR AUTOMOTIVE	Course	_	DDOEESSIONAL CODE	L	Т	Р	С
Code	Name	ENGINEERS	Category	C	PROFESSIONAL CORE	2	0	2	3

Pre-requisite Courses	Ni	Co- requisite Courses	NI	ressive urses	Nil
Course Offering	ng Department	Automobile Engineering	Data Book / Codes / Standards		Nil
			CITE NO.		

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	411	\mathcal{A}^{-}			Progr	am Ou	ıtcome	s (PO)				_	rogran	
CLR-1:	acquire knowledge of variou	s conventiona <mark>l manufactur</mark> ing processes	1	2	3	4	5	6	7	8	9	10	11	12	_	pecifi itcom	
CLR-2:	utilize the work and tool hold	ding device <mark>s</mark>	dge		of	SL					Work		8				
CLR-3:	identify the various surface	finishing <mark>process a</mark> nd coating techniques	a)	S	velopment	ations	Usage	ъ	. 1				Finance	ning			
CLR-4:	identify the fundamental cor	ncepts <mark>of CNC</mark> machining	Knowle	Analysis	lopi	estig		er and	× t ×	h	Team	tion	∞ర	arni			
CLR-5:	compare various advanced	man <mark>ufacturin</mark> g techniques for suitable applications	ering	E	n/deve	luct inv	n Tool	engineer a	ironment tainability		ual &	unica	t Mgt.	Long Le			
Course C	Outcomes (CO):	At the end of this course, learners will be able to:	Engine	Proble	Design Solutio	12 8	Modern	The er	≥ 🔀	Ethics	Individual	Communication	Project	Life Lo	PS0-1	PS0-2	PSO-3
CO-1:	apply different welding and o	c <mark>asting te</mark> chniques for suitable applications	3	1-1	13		-	7	-	-	-	-	-	-	3	-	-
CO-2:	compare the advanced met	al forming process and current role in industries	3	1	125	-11	-		-	-	-	-	-	-	3	1	-
CO-3:	produce prismatic componen	ts and Gears	ALC: 8	2	.	1	-	-	-	-	-	-	-	-	-	2	-
CO-4:	apply the knowledge of CN	C machining in various Automotive component manufacturing	2	- 1		7	3	-	2	-	-	-	-	-	2	-	-
CO-5:	select viable manufacturing	process of complex parts alternative to conventional manufacturing		44	1	3	-	_	2	-	-	-	-	-	-	-	1

Unit-1 - Conventional Manufacturing - Overview

12 Hour

Introduction to Welding- classifications – Types – Working principles of ARC, MIG, TIG, SPOT, Laser welding – Welding defects – Welding Applicationin Automobile. Introduction to casting – Pattern materials & types – Shell, investment & pressure die casting – casting defects – casting application in Automobile. Introduction to Forging – types & defects – Rolling process – types & defects – Extrusion process & defects – tube drawing - sheet metal operations – Bending – stretch forming – Deep drawing – Ironing – Hydroforming

Unit-2 - Machining and Gear Manufacturing Process

12 Hour

Introduction to Machining – theory of metal cutting – Mechanics of chip formation & types of chips – cutting tool materials – Tool life calculation – Tool wear – Tool signature for single point cutting tool – Lathe machine - Types of lathe – cutting fluids & Machinability – Material removal rate – Operating parameter – cutting speed, feed & depth of cut. Introduction to Milling machine – types – milling cutters & Indexing process – overview of surface machining, drilling operation – Gear forming process – Extrusion & stamping – Gear Hobbing process – types – Gear shaping & types - Powder metallurgy technique – sintering – properties of metal powders – particle size and blending – compaction – applications in automobile

Unit-3 - Surface Finishing Treatments

12 Hour

Introduction to Finishing operations – Grinding machine - surface & cylindrical – external, internal & Centre less – Automotive Application of Lapping – Honing – Buffing – Deburring – shot blasting – shot peening. Superfinishing process – cylindrical & centerless micro honing – Application – Electrochemical polishing – protective & decorative coating techniques – Applications.

Unit-4 - CNC Machine Tools

12 Hour

Evolution of CNC Technology – principles – features – advantages – CNC & DNC concept. Classification of CNC Machines – Turning centre, machining centre, EDM, Types of control systems – CNC controllers – characteristics – interpolators – computer-aided inspection. CNC Machine building – structural details – configuration & design – guide ways – Friction, Anti friction – spindle drives – DC shunt motor - Feed drives – stepper motor, servo principle, DC & AC servo motors – open loop & closed loop control – Axis measuring system – Gratings – encoders – Laser interferometer.

Unit-5 - Additive Manufacturing Techniques

12 Hour

Introduction to Additive Manufacturing – Importance of rapid prototyping – classification – Advantages – Stereo Lithography – Multi jet modelling – Powder based techniques – selective Laser sintering – 3D Printing – its working & applications – Fused deposition modelling – Laser powder bed fusion process.

Learning Resources

- 1. Seropkalpakjian, Manufacturing Engineering and Technology,7th ed., Pearson Education, 2013.
- 2. P.N. Rao, Manufacturing technology Machining and MachineTools, Vol. 2, 3rd ed., Tata Mc Graw Hill, 2017
- 3. P.N. Rao, Manufacturing technology Foundry forming and welding, Vol. 1, 4th ed. Tata Mc Graw Hill, 2013.
- 4. Mikel P Groover, Fundamentals of Modern Manufacturing, 4th ed., JohnWiley and Sons, 2009.
- 5. Sharma P C, A Text Book of Production technology manufacturingProcesses, S Chand & Company, New Delhi.

Learning Assessm	ent						
	Bloom's Level of Thin <mark>kin</mark> g	CLA-1 Avera	Continuous Learning native ge of unit test 5%)	g Assessment (CLA) Life-Long CLA (15)	1-2	Final Ex	mative amination eightage)
		Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	20%	2004/09/2015	3423.0	20%	20%	-
Level 2	Understand	30%	Carlot Marian	17 " " The	30%	30%	=
Level 3	Apply	50%	A 10 10 10 10 10 10 10 10 10 10 10 10 10	- 16 (50%	50%	-
Level 4	Analyze	A	100 may 1 1 186	Sec. 1 (2)		-	-
Level 5	Evaluate —	F 1777	AN 1979 A. P. C. C.	The state of the s	- C	-	-
Level 6	Create	2 2 7 7 9 7	FE 18 35	1. 机电离器系统。		-	-
	T <mark>otal — — — — — — — — — — — — — — — — — — —</mark>	10	0%	100	%	10	0 %

Course Designers		(
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Ajeet Babu ARAI,ajeetbabu.fid@araiindia.com	1. Dr. B. Mohan Anna University bmohan@annauniv.edu	1. Mr.S. Palan <mark>isa</mark> my, SRMIST
2. Mr.Dalpat Singh M & M,	2. Dr.R.Elansezhian, Pondicherry Engineering	2. Dr. J. Cha <mark>ndradass</mark> , SRMIST
singh.dalpat@mahindra.com	College,elansezhianr@gmail.com	7 2 V 2 2

Course	21AUC301T	Course	CAD ANALYSIS FOR AUTOMOTIVE ENGINEERS	Course	_	PROFESSIONAL CORE	L	Т	Р	С
Code	214003011	Name	CAD ANALTSIS FOR AUTOMOTIVE ENGINEERS	Category	C	FROFESSIONAL CORE	3	0	0	3

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	Progressive Courses	Nil	
Course Offerin	g Department	Automobile Engineering	Data Book / Codes / Standards		Nil	

Course I	Learning Rationale (CLR): The purpose of learning this course is to:	11	4	- T		Progr	am Oı	ıtcome	es (PC))					ograr	
CLR-1:	describe the various design concepts and modelling techniques	1	2	3	4	5	6	7	8	9	10	11	12		oecifi tcom	
CLR-2:	introduce the latest developments in CAD Packages	ge		of	ટા					Work		8				
CLR-3:	understand the basic knowledge of automotive components respective to design	Knowledge	S	velopment of	investigations ex problems	Usage	ъ		L			& Finance	р			
CLR-4:	provides the knowledge on forces of connecting rod	중	Analysis	udoli	estig	ı Us	r and	۲ ک ک		Team	Įį.		eaming			
CLR-5:	familiarize the design procedure of engine components	Engineering		deve	t inv	Tool	inginee tv	ironment tainability		<u>ळ</u>	ommunication	Project Mgt.				
		inee	Problem	sign/dev	onduct in	Modern T	erget	Environi Sustain <mark>a</mark>	S	Individual	nwu	ect	ife Long	SO-1	0-2	53
Course (Outcomes (CO): At the end of this course, learners will be able to:	Eng	Prol	Des	Cor	ОМ	The	Env Sus	Ethics	Indi	Con	Proj	Life)Sd	PS(PSO.
CO-1:	create the design models by various technique	3	16	3	2	-	-7	-		-	-	-	1	3	2	-
CO-2:	develop the model using various features	3	2	3	- 1	-	4		- 1	-	-	-	-	3		-
CO-3:	explain the procedure involve <mark>d in des</mark> ign	3	146	2	1	3	-	7 -		-	-	-	-	3	-	-
CO-4:	familiarize with various design standards	3	3	2		3	-		- 4		-	-	-	3	-	-
CO-5:	design various automotive components to suit industrial needs	3	20		2	3		-		_	-	-	-	3	1	-

Unit-1 - Introduction to CAD

Introduction to CAD, Product life cycle management, Design models – Pahl and Beitz model, Shigley model and Ohsuga model, Geometric modelling, Constructive solid geometry, Boundary representation, Introduction to Coordinate system, Model coordinate system, Transformations in 2D and 3D, Concatenated and Inverse transformation, Visibility techniques – Minimax test, Containment test, Hidden line removal – priority algorithm

Unit-2 - Modelling and Software Packages

9 Hour

Introduction to Software Packages, Salient features and technical comparison, Modules and tools, Open-source tools (FreeCAD, LibreCAD), Need for dataexchange standards and types, Structure of STEP file system: Advantages and Disadvantages, Structure of IGES file system: Advantages and Disadvantages, outline of feature technology, Classification of features, Design by features, Applying features to various automotive components, Advantages and limitations of feature-based modelling. Introduction to GD & T, Need of GD&T, Geometrical tolerance, Dimensional tolerance.

Unit-3 - Design of Cylinder and Piston

9 Hour

Introduction to Cylinder And Piston, Principal Parts of an IC Engine, Cylinder and Cylinder Liner, Design of Bore, Length, Thickness of cylinder head, study size of the cylinder head, Material for piston, Design of critical parameters of piston: Piston Rings, Piston Skirt, Piston pin. Modelling of cylinder and piston using CADsoftware.

Unit-4 - Design of Connecting Rod

9 Hour

Introduction to Connecting Rod, Material selection for connecting rod, Forces Acting on the connecting rod, Dimensions of cross Section of the connecting rod, Dimensions of the crank pin at the big end, Dimensions of the piston pin at the small end, Size of bolts for securing the big end cap, Thickness of the big end cap. Modelling of Connecting Rod using CAD software.

Unit-5 - Design of Crankshaft

9 Hour

Introduction to Crankshaft, Introduction about crank shaft and its function in an I.C Engine, Materials selection for crankshaft, Bearing pressures and stresses in crankshaft, Design Procedure for Crankshaft, Design of Centre Crankshaft When the crank is at dead centre, Design of Centre Crankshaft When the crank is at angle of maximum twisting moment, Design of Overhung Crankshaft When the crank is at an angle of maximum twisting Moment, Modelling of crankshaft using CAD software

	Learning Resources	2.	Ibrahim Zeid, "CAD / CAM - Theory and Practice"., Tata Mcgraw-Hill, New Delhi, 2009 Radhakrishnan. P "CAD / CAM / CIM" New age international, 2018 Mikell P. Groover, "CAD / CAM"., Prentice Hall of India PrivateLimited, New Delhi, 2003	5.	Khurmi, "A text book of Machine Design", S Chand publication, 2016. Bhandari V, "Design of Machine Elements", Tata McGraw-Hill Education, 2010. Shigley J, "Mechanical Engineering Design", Tenth Edition, Mc Graw Hill, 2014.	
--	-----------------------	----	--	----	--	--

Learning Assessm	nent						
<u> </u>	Bloom's Level of Thinking	CLA-1 Averag	ative ge of unit test	CI	g Learning LA-2	Final Exa	native amination eightage)
	g	Theory (50	%) Practice	Theory (1	0%) Practice	Theory	Practice
Level 1	Remember	20%	_	20%		20%	-
Level 2	Understand	30%		30%	2 - 1	30%	-
Level 3	Apply	50%	A CONTRACTOR	50%	- A- V	50%	-
Level 4	Analyze	7.	25.5	-	400	-	-
Level 5	Evaluate	, V -/	A 18 18 18 18 18 18 18 18 18 18 18 18 18			-	-
Level 6	Create				1	-	-
	Tota <mark>l</mark>	100) %	10	00 %	10	0 %

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.B.Prabhakaran, Continental	1. Dr.P.D.Jeyakumar, Crescent Institute of Science and Technology,	1. Dr.J. Chand <mark>radass,</mark> SRMIST
prabhakaran.balaraman@continent <mark>al-corpo</mark> ration.com	pdjeyakumar@gmail.com	
2. Mr.S.Vengatesan, RNTBCI, vengatesan.subramanian@rntbci.com	Dr.R.PrabhuSekar, Motilal Nehru National Institute of	2. Mr.G.Nares <mark>h, SRMI</mark> ST
	Technology, rprabhusekar@mnnit.ac.in	

Course			Course					Course											1	Т	Р	С
Code	21AUC3	801L	Name	DESIGN OF AUTO	MOTIVE SYST	EMS LABORA	IUKY	ategory	, (C			PRO	FESSI	ONAL	CORE			C	0	2	1
Pre-requis			Nil	Co- requisit	е	Nil	******		ressivurses							Nil						
	offering De	partme	ent	Automobile Engineerii	ng	Data Book / Co	odes / Standards		u		• •				Nil							
0			(OL D):	Th	4.			-						4	- /DC					Dı	ogra	m
Course Lea			· '	The purpose of learning	tnis course is t	(0:	TH 44 7	1 12 4 14			4	_ Ť		tcome		i ı	40	44	40	S	pecifi	ic
			•	er aided design	\rightarrow			17	2	3	4 دن	5	6	7	8	9	10	11 o	12	Ou	tcom	es
CLR-2:				ketching tools					.	ent	ation	ge	-			_		nanc	Ð			
CLR-3:	Demonstra	ate tne	various 3D n	nodelling tools				Engineering Knowledge	Problem Analysis	Design/development of solutions	Conduct investigations of complex problems	Modern Tool Usage	The engineer and society	Environment & Sustainability	cs	ndividual & Team Nork	Communication	Project Mgt. & Finance	Life Long Learning)-1)-2)-3
Course Out	tcomes (C	0):		<mark>At the e</mark> nd of this course	, learners will b	be able to:	30 m 100 m	Eng Sno	Pro	Des of s	Sol	Moc	The soci	Env <mark>Sus</mark>	Ethics	Indivi Work	Con	Proj	Life	PS0-1	PS0-2	PSO-3
CO-1:	Understan	d the n	eed of comp	<mark>uter aid</mark> ed design		1 1 1 1 1 1 E	Sec. 19.	2	<u> </u>	2	2	. 7		-	•	-	-	-	-	2	-	2
CO-2:	Create 2D	drawin	gs using sk <mark>e</mark>	<mark>tching t</mark> ools			116.55	3	3	3	2	3	16	-		-	-	-	-	3	3	3
CO-3:	Develop 3	D mode	els using di <mark>ffe</mark>	<mark>erent f</mark> eatures of solid mode	elling	W. 377	TO AN ARMA	3	3	3	-3	3		-	-	-	-	-	-	3	3	3
Practice -					4 7/20 8		<u> </u>	320	47	<u> </u>					-						20	Hour
-	Introducti	on to C	Computer Aid	ed Design and 2D Sketch	toolo	A STATE OF THE STATE OF		<u> </u>	H	- Table			_		-						30	поиг
Practice: 1				<mark>ng rod</mark> , crank shaft and, c											-							
			arbox assem		alli Silait		Mw.a.					$+\epsilon$		-								
				oly r <mark>sal joint</mark> and Propeller sha	.#		1111					-	4	+								
			erential Asse		iil		1774				7	A		1								
			erenual Asse ering Gear b		_						_	7-										
Practice: 7				0.4	\leftarrow			-				-	-/	٠,								
-			nt axle asser	mhly	//11	ARN	· 1 FA1	7	+	4.1	+	7										
Practice: 9				пыу			6.11.17	-+	£,	11.	+	7		7								
			eel assembly	,							_											
i raciice. 10	woueiiiig	OI VVIII	eei asseiiiDi)	<u>'</u>																		
Learning Resources	1. 2. 3.	Introdu	ucing solidwo	"CAD / CAM / CIM" N <mark>ew a</mark> orks "Dassault systems", fastering Solidworks", 201		l, 2018	4. Nitin.S. 6 5. Huei-Hu											2020",	SDCF	Publica	tions,	2020

			Co	ntinuous Learning	g Assessment (C	LA)			
	Bloom's Level of Thinking	exper	CLA-1 Average of first cycle experiments (30%)		ge of second periments 0%)	Practical E	Examination 0%)	Final Examination (0% weightage) Theory Prac	
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember		20%		20%		20%	-	-
Level 2	Understand		30%	. I I '. I '	30%	- "	30%	-	-
Level 3	Apply		30%	-	30%	4 -	30%	-	-
Level 4	Analyze	7-	30%		30%	V	30%	-	-
Level 5	Evaluate	- 4	- L	-	-	4-1		-	-
Level 6	Create			- W	-			-	-
	Total	10	0 %	100	9 %	10	0 %		-

Course Designers	A SAME SWILL THE SAME STATE OF THE SAME SWILL THE SWILL THE SAME SWILL THE S	
Experts from Industry	Experts from Higher Technical Institutions	Internal <mark>Experts</mark>
1. Mr.P. Nirmalkumar, Hubbell India, nirmal06kumar@gmail.com	Dr.P.D.Jeyakumar, Crescent Institute of Science and Technology, pdjeyakumar@gmail.com	1. Mr. P. Baskara Sethupathi, SRMIST,
Mr.SuhasKangde,Mahindra &Mahindra, kangde.suhas@mahindra.com	Dr.R.PrabhuSekar, Motilal Nehru National Institute of Technology, Prayagraj, rprabhusekar@mnnit.ac.in	2. Dr. J. Chandradass, SRMIST

Course	21AUC302J	Course	VEHICULAR STRUCTURES AND DRIVELINE SYSTEMS	Course	_	PROFESSIONAL CORE	L	Т	Р	С
Code	21A0C3023	Name	VEHICULAR STRUCTURES AND DRIVELINE STSTEWS	Category	C	FROFESSIONAL CORE	2	0	2	3

Pre-requisite Courses	Nil	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offering	g Department	Automobile Engineering	Data Book / Codes / Standards		Nil

Course L	earning Rationale (CLR):	The purpose of learning this course is to:		1	4			Progr	am Oı	ıtcome	s (PO)					ogran	
CLR-1:	R-1: familiarize the structure of Vehicle frames, Front and Rear axles			11	2	3	4	5	6	7	8	9	10	11	12		pecific tcome	
CLR-2:	CLR-2: acquire knowledge about various types of automotive driveline systems					of	SI	1	7.			Work		8				
CLR-3:	explore the various compor	nents and functions of steering and suspension systems		wledge	w	Jent	ation	sage	Ъ	· \				ä	БC			
CLR-4:				Knowle	Analysis	evelopment of	vestigations problems	\neg	er and	∞ >	h.	Team	ation	& Fin	arning			
CLR-5:	LR-5: impart the knowledge of braking system, Wheels and tyres		1	ering		deve	e ‡i	100	enginee stv	ment		<u>8</u>	.≌	Mgt.	g Le			
			4	e	Problem	/ugi	duct		enç et v	tain	S	/idu	mwm	roject	Long	7	7.5	ر
Course C	Outcomes (CO):	At the end of this course, learners will be able to:	1	Eng	Prot	Des	S Conc	Mod	The	Env	Ethic	Individual	Coll	Proj	Life	PSO.	PS0-2	PSO.
CO-1:	demonstrate the basic struc	ct <mark>ure of an</mark> automobile and various types of axles	13.1	3	-	7-	2		7	-	-	-	-	-	-	-	-	-
CO-2:	identify the various types of	automotive driveline systems	1	3	-	2	-	-	-	-		-	-	-	-	-	-	-
CO-3:	classify the different types o <mark>f steerin</mark> g and suspension systems			3	No. of		13	-		2		-	-	-	-	-	-	-
CO-4:	4: classify the different types of transmission systems			3	1.5	_ 2	-		-	-		-	-	-	-	-	-	-
CO-5:	identify the various types of braking systems, wheels and tyres			3	75	1	1		_	-		-	-	-	-	-	-	-

Unit-1 - Frames, Front and Rear Axles

12 Hour

Different types of chassis layout- FF, FR,RR and 4WD - Types of vehicle body and Classifications - Frames- construction, Materials, Loads Acting on frames – Types of vehicle frames-Ladder frame, Tubular frame - Integral frame, X-frame, Roll-cage frames - Common vehicle platform- Need, merits and demerits Case study - Volkswagen PQ platform, Nissan B platform, Front axle – Live axles, Dead axles, Drop axles, Push and tag axles – Rear axles - Semi, full andthree quarter floating – Types of rear axle housing - Split Banjo and Salisbury type – Multi link rear axles practice 1: Study and measurement of various types of vehicle frame, body and driver seat. 2: Study of different types of front and rear axles and final drives. Calculation of final drive ratio.

Unit-2 - Transmission System

12 Hour

Types of clutches, construction and working of single plate - Multi plate and centrifugal clutch - Torque capacity of clutch - Numerical Analysis - Simple problems Fluid coupling - Construction and principle of operation - Torque converters - Construction and principle of operation - Hydro kinetic drives - Multistage torque converters - Polyphase torque converters. Types of gear boxes - Working of sliding And constant mesh gear boxes - Construction and working of synchromesh gear box and principle of synchronizers - Planetary gear box - construction and working - Numerical in Gear box - Automatic transmission - Chevrolet turbo glide Construction and working - Chevrolet Power glide - Construction and working - Hydraulic clutch actuation for Automatic transmission. Practice 3: Dismantling, study and assembling of a given clutch and calculate the gear ratio

Unit-3 - Drive Line and Final Drives

12 Hour

Effect of driving thrust and torque reactions - Hotchkiss and torque tube drive - Front wheel drive - Propeller shaft -Construction, Critical Speed - Universal joint, Slip joint, Constant velocity joint and Tripod joint. Different types of final drive - Worm and worm wheel, Straight bevel gear, Spiral bevel gear and hypoid gear final drives - Double reduction final drive - Twin speed final drive - Differential- Principle and constructional details - Differential lock - Limited slip differential. Practice 5: Dismantling, study and assembling of propeller shaft, Universal joint, Slip joint, Constant velocity joint and Tripod joint 6: Dismantling, study and assembling of Final drive assembly and calculation of final gear ratio.

Unit-4 - Steering and Suspension Systems

12 Hour

Front wheel geometry - Caster, Camber, Toe in and toe out, SAI - Steering systems - True rolling motion of wheels and Numerical Analysis — Simple problems - Ackermann and Davis steering Mechanism - Constructional details of steering linkages for rigid and independent front axles. Steering gear box - Re-circulating ball type, Rack and pinion type, Worm and Nut type - Power assisted steering - Hydraulic and EPS — Four wheel steering Need for suspension system. Types of suspension - Non independent and independent suspension - McPherson and Wishbone suspension - Types of suspension springs - Leaf spring, Coil spring, Torsion bar, and Rubber springs — Shock absorbers — Pneumatic suspension - Rear axle suspension system - Independent, Trailing Arm - De-dion suspension and torsion beam - Anti-roll bar, Pan hard rod and Radius rod. Practice 7: Dismantling, study and assembling of different automobile steering systems Practice 8: Dismantling, study and of automobile suspension system.

Unit-5 - Brakes, Wheels and Tyres

12 Ho

Theory of braking - Stopping distance - Braking efficiency, Numerical analysis - Drum brakes - Single cam, Double cam - Leading and Trailing shoe types - Disc brakes - Fixed, floating and radial mounted calipers - Ventilated discs, cross drilled discs, slotted discs - Mechanical and hydraulic brake actuation - Pneumatic braking system - Vacuum assisted hydraulic brakes - Air assisted hydraulic brakes - Need for ABS, ESP, EBD and Regenerative braking systems. Types of Wheels - Dimensions and Constructional details of wheels - Types - Construction - Cross ply, Radial ply - Tube and tubeless tyres - Tyre designation - Tread patterns Practice 9: Dismantling, assembling and bleeding of a hydraulic braking system. Practice 10: Study of different types of wheels and tyres

Learning Resources

- 1. Kirpal Singh, "Automobile Engineering Vol I", StandardPublishers Distributors, 1999.
- 3. Heldt P.M. "Torque converters". Chilton Book Co., 1992.
- Crouse W.H, Anglin D.L, "Automotive Transmission and PowerTrain construction", McGraw Hill. 1976
- 4. Newton Steeds &Garrot, "Motor Vehicles", SAE International andButterworth Heinemann, 2001.

Learning Assessm	nent			t lyst sa							
			Continuous Learning Assessment (CLA)								
	Bloo <mark>m's</mark> Level of <mark>Thinkin</mark> g	Formativ CLA-1 Average o (45%)			practice %)	Summative Final Examination (40% weightage)					
		Theory	Practice	Theory	Practice	Theory	Practice				
Level 1	Remember	20%			20%	20%	-				
Level 2	Understand	30%	1 July 1982		30%	30%	=				
Level 3	Apply	50%		1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	50%	50%	-				
Level 4	Analyze		The state of the s	VIII.		9 -	-				
Level 5	Evaluate		- 1,00%	-	4		-				
Level 6	Create	PG 1	- 1.7	-			-				
	Total	100 %	11.00	100) %	10	0 %				

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Ex <mark>perts</mark>
1. Mr. R. Siva GM GMMCO – Caterpiller	Dr. PD Jayakumar Prof & Head, Dept of Auto, Cresent	1. Dr. <mark>K.Kamalak</mark> kannan SRMIST
rsiva@gmmcoindia.com	pdjeyakumar@cresent.education	
2. Dr. Vijayabalan, Professor & Head Department of Mechanical	2. Mr.S. Kiran, SRMIST kirans@srmist.edu.in	- 100
Engineering HITS vijayabalan@hindustanuniv.ac.in		

Course	21AUC303J Co	ourse	AUTOMOTIVE ELECTRICAL AND ELECTRONIC SYSTEMS	Course	_	PROFESSIONAL CORE	L	Т	Ρ	С	1
Code	Z IAUCSUSS N	Name	AUTOMOTIVE ELECTRICAL AND ELECTRONIC SYSTEMS	Category	C	PROFESSIONAL CORE	2	0	2	3]

Pre-requisite Courses	Nil	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offering	g Department	Automobile Engineering	Data Book / Codes / Standards		Nil

Course Learning Rationale (CLR): The purpose of learning this course is to:				Program Outcomes (PO)												rogram	
CLR-1:	acquire knowledge about the application of electrical and electronics in automotive systems		11	2	3	4	5	6	7	8	9	10	11	12	_	pecific tcomes	
CLR-2:	understanding the working of charging and lighting accessories in automobile		lge		of	SI		1			ork		8				
CLR-3:	acquire the fundamental electronics applied vehicle motion control system		Knowledge	S	nent	vestigations c problems	sage	ъ	٠١.		≥		Finance	ning			
CLR-4:	familiarize the usage of Sensors a <mark>nd actuat</mark> ors in Automobile	. T		Analysis	udoli	estig		r and	ح ۲ ک		Team	fion	& F	arni			
CLR-5:	know about various electrical equipment diagnostics and testing methods		ering	n An	gn/development of ions	∟⊨ ഒ	Tool	engineer etv	nment		a &	ınica	Mgt.	ng Le			
0		<u> </u>	Engine	Problem	Design/d	onpue	odern		wiron Istain	Ethics	ndividual	ommunication	roject Mgt.	으	PS0-1		PSO-3
Course C	Outcomes (CO): At the end of this course, learners will be able to:	100	Ш	٦	2 8	ಕಟ	ž	The	<mark>ற </mark> ல	Ш	<u>=</u>	ပိ	P.	Life	PS	82 8	7
CO-1:	identify the need, requiremen <mark>t and fu</mark> nction of basic vehicle batteries and its types	17	3	. 3	1	1	1	7	-	1	1	1	-	1	3	3	1
CO-2:	describe the charging, lightin <mark>g and au</mark> xiliary electrical system for electrical vehicles	100	3	3	1	1	2		-		1	1	-	1	3	3	1
CO-3:	acquire and analyze the various fuel ignition and fuel injection system procedure		3	3	1	1	2		-	ē	1	1	-	1	3	3	1
CO-4:	apply knowledge of vehicle dynamics to improve performance		3	3	- 1	_1	2	-	-	-	1	1	-	1	3	3	1
CO-5:	analyze the protection system applied to electrical vehicles	7.5	3	3	1	1	2	_	-	7	1	1	-	1	3	3	1

Unit-1 - System Architecture

Automotive Electrical and Electronics architecture – Components, connections, and power distribution, Vehicle Batteries- Fundamentals and types, Lead acid battery – Principle, Construction, Rating, Charging and Discharging mechanism, Peukert Criteria. Testing and Fault Diagnosis of Batteries, Starting System – Requirements and Functionalities, Starter motor Construction and Working principle, Starter Drive Mechanism – Introduction and types, Advancements in Battery Technologies. Practice 1: Battery Testing – Hydrometer, Load test, Individual Cell voltage test 2: Starter Motor – Continuity test, Insulation Test, Load test

Unit-2 - Electrical Accessories

Charging system - Introduction, Alternator – Construction and Working principle, Charging Circuits, Rectification, Voltage Regulator – Principle, construction, working and types, Lighting Circuits – Fundamentals and types, Lighting System regulations, Case Studies in Modern lighting system, Auxiliary Electrical system - Wiper system, Signaling and Warning system, Introduction to D.C charging system. Practice 3: Battery Testing – Hydrometer, Load test, Individual Cell voltage test4: Starter Motor – Continuity test, Insulation Test, Load test

Unit-3 – Electronic Fuel Injection and Ignition System

12 Hour

Introduction – Engine management system, SI Engine Fuel Injector, Single point Fuel Injections, Multi Point Fuel Injections, Merits of MPFI, Testing of Fuel Injectors, programmed ignition system, Distributor less Ignition System, Waste spark analysis, Digital Engine Control Modes, EGR Control variable valve timing, Ignition Controlling – Introduction Closed loop ignition timing, Spark Advance Correction Scheme, Practice 5: Study of Lab view Programming6: ADC interfacing for IR Sensor.

Unit-4 - ECU for Vehicle Control 12 Hour

Introduction – Vehicle motion control, Cruise Control System, Adaptive Cruise Control System – Construction, - Working, Throttle Actuator Stepper Motor Based Control, Antilock Braking Mechanism – Working, Tire Slip Controller, Merits of ABS, Electronic Suspension System, Construction, Working Variable Damping, Variable Spring rate, Merits of Electronic suspension system, Electric Power Assisted Steering Mechanism- Construction Working, Four Wheel Steering, Steer-by-Wire, Lab: Review class. Practice 7: PWM Signal generation 8: H-Bridge Motor speed and position Control.

Unit-5 - Brakes, Wheels and Tyres 12 Hour

Introduction – Telematics, GPS Navigation, GPS Structure, Dead Reckoning – Construction, Dead Reckoning – Working, Inertial Navigation System – Construction, Working, In vehicle infotainment systems, ADAS – Introduction, features, Electronic Control System Diagnostics, OBDII – Objective, Comparison of OBD I and OBD II, Diagnostics Fault Codes, Introduction to Model-based Sensor Failure Detection, Model-based Sensor Failure Detection working, Case Study on MAF Sensor calibration, Case Study on MAF Sensor calibration. Practice 9: UART communication for parking sensor 10: Fault Diagnosis using OBD handheld Devices.

Learning Resources
Resources

- 1. Tom Denton "Automobile Electrical and Electronic Systems" 3rdedition, Elsiever Butterworth-Heinemann 2004.
- 2. William.B.Ribbens, "Understanding Automotive Electronics" 7thedition Butterworth-Heinemann publications, 2012.
- 3. Ed Doering "NI MYRIO Project Essential Guide" 2013, National Technology and Science Press
- 4. Allan W.M.Bonnick "Automotive Computer Controlled System2001, Butterworth- Heinemann
- 5. Robert Bosch Gmbh "Bosch Automotive Electric and Electronics" 5th edition Springer- 2007.

-			Continuous Learning	Assessment (CLA)		Sumi	native
	Bloom's Level of Th <mark>inking</mark>	CLA-1 Avera	eative ge of unit test %)	CLA-2 - (15	practice %)	Final Exa	amination eightage)
		Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	15%	Carlot Marketine		15%	15%	-
Level 2	Understand	25%	and the second second	- 1	20%	25%	-
Level 3	Apply	30%	18 1 1 1 July 19 1	80 1 30 77	30%	30%	-
Level 4	Analyze	30%	ALC: 10 PM 10 PM		30%	30%	-
Level 5	Evaluate	22.777517		"一根是刘邦安利。		-	-
Level 6	Create		30 Table 10	100	3	-	-
	Total Total	100)%	100	%	10	0 %

Course Designers	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Associate Director, Skill- lync	1. Mr. Sam Jebakumar, SRMIST, jebakumj@srmist.edu.in	1. Dr.C.Carunai <mark>selvane,</mark> SRMIST
		2. Dr.T.Pravee <mark>nkumar,</mark> SRMIST

Course	21AUC304J	Course	FINITE ELEMENT ANALYSIS	Course	(DDOEESSIONAL CODE	L	Т	Р	С
Code	21A003043	Name	FINITE ELEWENT AWALTOIS	Category	C	PROFESSIONAL CORE	3	0	2	4

Pre-requisite Courses	N	Co- requisite Courses	Nil	gressive ourses	Nil
Course Offeri	ing Department	Automobile Engine <mark>ering</mark>	Data Book / Codes / Standards		Nil

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	4	7	4			Progr	<mark>am</mark> Ou	itcome	s (PO)					ograi	
CLR-1:	predict how a product react	s to real-worl <mark>d forces, vibr</mark> ation, heat, fluid flow, and other physical effects		1	2	3	4	5	6	7	8	9	10	11	12	_ '	pecifi tcom	
CLR-2:	model any physical system i	n to a finite <mark>element m</mark> odel and solve for its field variables		dge		of	SL					ork		9				
CLR-3:				Knowlec	S	/development	stigations oblems	Usage	ъ			N N		Finan	Б			
CLR-4:					Analysis	log	estig		er and	t &		Team	tion	∞ర	arning			
CLR-5:	-5: understand the basics of multi-body systems		4	ring		deve	ex ii.	Tool	9	ment ability		<u>&</u>	ommunication	Project Mgt.	g Le			
				inee	roblem	ign/	omp	dern	engi ety	iron	SS	ndividual	nwu	ect	Long	7)-2) . 3
Course C	ourse Outcomes (CO): At the end of this course, learners will be able to:			Eng	Pro	Des	g G	Moc	The	Env Sus	Ethics	İpu	Sol	Proj	Life	PSO.	PSO	PSO-3
CO-1:	apply finite element technique	u <mark>e to Eng</mark> ineering problems	-	3 -	3	2	-	-	7	-	, 40	-	-	-	-	3	-	-
CO-2:	O-2: improve their ability in solving differential equations for real world problems		1	3	3	25	2	-		-	1	-	-	-	-	3	-	
CO-3:	0-3: equip themselves familiar with multi-domain phenomenon like thermo-structural problems		H.,	3	3	-	-4	-	_	-		-	-	-	-	3	-	-
CO-4:	0-4: familiarize themselves with the applications of finite element method & FEA packages			3	3	- E	-2	-		-		-	-	-	-	3	-	-
CO-5:	solve kinematic and dynamic problems of multibody systems		- 12	3	3	7.64	_	-		-	_	_	_	-	_	3	-	_

Unit-1 - Introduction to FEA 15 Hour

Comparison Of FEA With Exact Solutions - Methods of engineering analysis - Numerical methods - Types of finite elements - Displacement or shape function Material behavior - Stiffness matrix - Steps involved in FEA – preprocessing and solution - Post processing - 2D and 3D stress element - Strain-displacement relationships - Discretization methods - Discretization process - Rayleigh ritz method - Galerkin method - Advantages and disadvantages of FEA - Applications of FEA

Practice:

1. Introduction to ANSYS 2. Cantilever Beam With Point Load at Free End

1. Introduction to Aivo to 2. Cantilover Beam with to one Load at 1 fee Line

Unit-2 - One Dimensional Problems

15 Hour

Elements and node numbering - Global and local co-ordinates - Natural co-ordinates - Polynomial functions - Displacement function for 1D bar element - General stiffness matrix derivation - Stiffness matrix for 1D bar element - Assembly of stiffness matrix - Force vector - Spring element - Stiffness matrix for spring element - Boundary conditions - Imposing boundary conditions to bar element - Beam element - Stiffness matrix derivation of beam element - Truss element - Stiffness matrix for truss element

Practice:

3. Distributed Loading of a 1D Cantilever Beam 4. Application of Distributed Loads

Unit-3 - Two Dimensional Problems

Plane stress formulation - CST element - Shape function derivation for CST element - Strain displacement matrix for CST element - Stress strain matrix for CST element - Stiffness matrix derivation for CST element - Temperature effects - LST element - QST element - Axi –symmetric formulation – Iso-parametric formulation – Iso, sub. Super parametric element formulation - Four noded quadrilateral element - 1D heat conduction problems - Derivation of stiffness matrix

Practice:

5. Buckling Failure 6. Stress Analysis of Axi-Symmetry Structure.

Unit-4 - Multi-Domain Problems

Vibration analysis introduction - Modal analysis of a structure - fluid flow problems - Heat transfer problems - Thermo structural analysis - Introduction to biomedical and MEMS applications - Practice.

7 Analysis of 2D Truss 8. Thermal Analysis...

Unit-5 - Applications of FEA 15 Hour

Roll cage analysis - Rotor thermal analysis - Hub analysis - Knuckle analysis - Brake pedal analysis Bump analysis Practice:

9.Modal Analysis of A Roll cage 10.Crash Analysis of the Roll cage.

	1.	David V. Hutton, "Fundamentals of Finite Element Analysis", Tata McGraw Hill Publishing	
Learning		Company Ltd., New Delhi, 2005	
Resources	2.	Ahmed A Shabana., "Computational Dynamics", Wiley &Sons. thirdedition 2017	

- 3. Bhavikatti S.S., "Finite Element Analysis", New Age International Publishers, New Delhi, 2008.
- 4. ErdoganMadenci, Ibrahim Guven, "the finite element method and applications in engineering using ansys", Springer (India) Private Limited, NewDelhi, 2011.

earning Assessn	nent		1987 F 18 18 18 18 18 18 18 18 18 18 18 18 18	2573			
			Continuous Learnin	g Assessment (CLA)		Summ	native Final
Bloom's Level of Thinking		Forma CLA-1 Avera test (45%	ge of unit	Pra	ngCLA-2 - ctice 5%)	Examina weightag	
		Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	15%	D	7.1	15%	15%	-
Level 2	Understand	25%	FE 1775 TAN	中国为国际和	20%	25%	-
Level 3	Apply	30%	4 7 1 P L P L	4.5	25%	30%	-
Level 4	Analyze	30%	Dr. Sant March		25%	30%	-
Level 5	Evaluate			1.5 No. 344	10%		-
Level 6	Create				5%	-	-
	Total	100 9	6	10	0 %	100	0 %

Course Designers	1111	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. K Suresh HAL Sureshhal82@gmail.com	Dr. R. Jagadeeshwaran, BIT, profresearch@bitsathy.ac.in	1. Dr. J. Ch <mark>andradas</mark> s,, SRMIST
2. Mr. V. Raja Raman, Altair rajarav@asiapac.altair.com	2. Dr. Vijayabalan, Professor & Head Department of Mechanical	2. Mr. P. <mark>Baskara S</mark> ethupathi, SRMIST
	Engineering HITS vijayabalan@hindustanuniv.ac.in	

Course	21AUC401J	Course	VEHICLE DVNAMICS	Course	^	DDOEESSIONAL CODE	L	Т	Р	С
Code	21/4004013	Name	VEHICLE DYNAMICS	Category	U	PROFESSIONAL CORE	2	0	2	3

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offeri	ng Department	Automobile Engineering	Data Book / Codes / Standards		Nil

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	111	4			Prog	<mark>am</mark> Ou	ıtcome	es (PO)				P	rogra	m
CLR-1:	learn the basic of overall com Tyres, K & C and Wheel align	ponents related to Vehicle Dynamics – Steering, Suspension, Brakes and		2	3	4	5	6	7	8	9	10	11	12		pecifi itcom	
CLR-2:	enable students to understan	d the role <mark>of tyre ch</mark> aracteristics and its mechanics for vehicle dynamics.			1	1			ility								
CLR-3:	involved in it such as braking, traction, road holding, vehicle control and stability			Engineering Knowledge	ent of	tions of	e e	society	Sustainability		Work		Finance				
CLR-4:				<u> </u>		tiga	Sac	and			eam	_	Ë	earning			
CLR-5:	demonstrate how to address challenges.	futuristic vehicle's dynamics requirements (ADAS), Homologation and	y pair	Problem Analysis	Design/development	t investigations	Modern Tool Usage	The engineer	Environment &		∞	Communication	Project Mgt. &				
		 See See See See See See See See See See	2	<u> </u>			err	ë	io Lo	S	νig] [ect	Long	7)-2	5.
Course O	utcomes (CO):	At the end of this course, learners will be able to:		ַבַ בַּ	Des	Conduct	No.	The		Ethics	Individual	Sol	Proj	Life	PSO	PSO-2	PSO-3
CO-1:	Understand different types of application.	Steering, Suspension, Brakes, tires and their significance with respect to	1 .3	3	3	- 3	3	2	2	1	2	1	2	1	3	3	2
CO-2:	Predict the necessary forces	and moments during tyre/road interaction and basic tyre nomenclature.		3	- 3	3	3	2	2	1	2	1	2	1	3	3	2
CO-3:	Compute maximum traction, control strategies.	optimum braking force distribution and stability of the vehicles and their		3	3	3	3	2	2	1	2	1	2	1	3	3	2
CO-4:	Demonstrate the application of fundamental governing equations for longitudinal, lateral and vertical dynamics and able to use state space approach.		Š	3	3	3	3	2	2	1	2	1	2	1	3	3	2
CO-5:	Simulate the dynamic perform	na <mark>nce of vehicles</mark>	,	3	3	3	3	2	2	1	2	1	2	1	3	3	2

Unit-1 - Fundamentals of Vehicle Dynamics and Tire Mechanics

12 Hour

Introduction to Automotive Chassis – Basic of Steering system, types of steering, selection based on suspension & FAL, Ackermann Geometry, Wheel Alignment – Toe IN/Out, Caster, Camber and its impact in Tire performance. King Pin Inclination (KPI),King Pin Offset (KPO), Scrub radius, Suspension types – HCV, selection of suspension system based on road conditions/axle loads/ride comfort, Brakes – Disc & Drum brakes, Wheel rim types (Steel & Al Alloy), Wheel Rim Profile (B, J, JJ etc). Practical: Wheel alignment.

Tyre & Vehicle axes systems - Mechanical Properties of Rubber- Tyre types and construction - Tyre forces and moments - Slip, Grip and Rolling Resistance, Contact Patch and Contact Pressure Distribution - Cornering properties of tyres (Practical – Tyre cut section study) TPMS - Tire Brush Model Tyre Models – Magic Formula, Lateral Force Generation, Ply Steer and Conicity, Classification of Tyre Models and Combined Slip, Tire noise, NVH – Random Processes.

Practice 1: Introduction to modelling of dynamic systems using Simulink / Simscape / Modelica tools.

Practice 2: Simulation and analysis of single, two degree of freedom systems using Simulink / Simscape / Modelica. Case

study to be offered by Volvo – Estimation of rolling resistance for a given tire fitted in a truck.

Co Teaching Area / Content by Volvo - Complete Vehicle Model (CVM) approach for truck design followed in Volvo Group.

Unit-2 - Longitudinal Dynamics and Vertical Dynamics

12 Hour

Vehicle forces - Longitudinal forces and resistances - Rolling resistance, Aerodynamic drag force, Traction force, Deceleration and speed control, brake drag, Road gradient forces. Performance characteristics - Maximum tractive effort - Power plant and Transmission characteristics - Braking performance- Brake force distribution, brake efficiency, braking distance, Anti lock brake system and Traction control system.

Homologation for braking system IS 11852-2013.

Vehicle ride characteristics Sprung & Unsprung mass, Stiffness, damping ratio, Human response to vibration - Vehicle ride models -Quarter car model - pitch and bounce-bounce and roll model -Suspension performance for ride-vibration isolation - suspension travel - Road holding - Active and Semi-active suspensions, Suspension bushes - Introduction to random vibration - ISO road roughness and road profiles - RMS acceleration of sprung mass of vehicle for random road excitation.

Practice 3: Magic Formula Tire model – Simulation of longitudinal and lateral forces.

Practice 4: Simulation and analysis of Quarter Car model using Simulink / Simscape / Modelica.

Case study to be offered by Volvo – Fundamental Equation of Motion for longitudinal dynamics of a truck

Co Teaching Area / Content by Volvo - Longitudinal dynamics and Vertical Dynamics understanding in Complete Vehicle Model.

Unit-3 - Lateral Dynamics and Vehicle Stability

12 Hour

General frame work for governing equations for ground vehicles - Bicycle Model - Low speed turning - High speed cornering-State space approach - Steady state handling characteristics of two axle vehicle- neutral steer-understeer-oversteer - Steady state gains from Bicycle Model during pure cornering - Vehicle handling tests (Constant radius cornering and fishhook) - Vehicle transient responses and understeer gradient effects due to lateral load transfer - roll steer - camber thrust - lateral force compliance and steering system compliance. On/Off center feel Homologation for steering system IS12222, IS11948.

Yaw plane stability and steering conditions - characteristic polynomial and stability factor – Handling response of a vehicle - Lateral transient response - Mimuro plot. Effect of suspension on cornering - Roll center and Roll axis - Roll moment distribution, ARB - Tyre relative angles - Caster theory - Role of suspension and nonlinearity of tyres on vehicle roll and its effect on Understeer co-efficient - roll over stability analysis - Control strategies required for vehicle.

Practice 5: Shock absorber testing - Characterizing the shock absorber and formulating simple models for shock absorber using curve fitting.

Practice 6: Control Strategy in ride modeling – Analysis of controllers like PID, Skyhook, LQR in ride comfort of vehicles using Simulink / Simscape / Modelica. Case study to be offered by Volyo – Quarter Car model formulation for a truck with cabin suspension and seat suspension.

Co Teaching Area / Content by Volvo - Stability analysis of Trucks in Complete Vehicle Model.

Unit-4 - Vehicle Dynamics for Electric, Hybrid and Autonomous Vehicles

12 Hour

introduction to EVs, HEVs, and AVs and their dynamics requirements - Dynamics behavior of the vehicle based on the battery pack location - Dynamics aspects based on the motor location and power distribution - NVH challenges for the EV and HEV- Experimental techniques - Frequency response functions - Modal analysis - Transfer path analysis - Single reference - Multi reference analysis.

Practice 7: Active Suspension system study using Quanser active suspension test rig. Practice 8:

Control strategy for a basic ABS implementation using Simulink.

Case study to be offered by Volvo – Bicvcle model formulation for a truck system.

Co Teaching Area / Content by Volvo - Differences in Complete Vehicle Model for Electric / Hybrid trucks when compared with Conventional trucks.

Unit-5 - Modelling, Simulation and Advancements in Vehicle Dynamics Systems

12 Hour

ADAS, Role of ADAS, ADAS Levels, ADAS features - Adaptive Cruise Control, Adaptive Headlights, Antilock Brake Systems, Automatic Parking Assistance, Autonomous Emergency Braking, Blind Spot Monitor, Electronic Stability Control, Forward Collision Warning, Lane-departure Warnings, Lane-Centering Steering, Lane-keeping assistance. ISO 26262 – Overview.

Practice 9: Plotting longitudinal, lateral and vertical forces involved in vehicle motion using Carmaker software. Practice 10:

Single Track model simulation and analysis using Simulink / Simscape.

Practice 11: Basic kinematic Simulation with Motion Solve

Case study to be offered by Volvo - Basic ABS system design for trucks

Co Teaching Area / Content by Volvo - Simulation of trucks in Complete Vehicle Model

Learning Resources

- 1. J. Y. Wong, Theory of Ground Vehicles, 3rd Edition, Wiley-Interscience, 2008.
- 2. Thomas D Gillespie, Fundamentals of Vehicle Dynamics, 2nd Revised Edition, SAE International, Warrendale, 2021.
- 3. Reza N Jazar "Vehicle Dynamics: Theory and Application", 3rd Edition, Springer International Publishing AG, Switzerland, 2017.
- 4. Katsuhiko Ogata, "Modern Control Engineering",5th Edition, Prentice Hall Pearson, 2015
- C. Sujatha, "Vibration and Acoustics: Measurements and Signal Analysis", McGraw Hill Education (India) Private limited, 20178.
- 6. Ellis.J.R "Vehicle Dynamics" Business Books Ltd., London 1991...
- Giles.J.G.Steering "Suspension and Tyres", Illiffe Books Ltd., London- 1998. Chalmers Vehicle Dynamics, Chalmers publication Library.

			Continuous Learning	g Assessment (CLA)		Summative				
	Bloom's Level of Thinking	Formative CLA-1 Average of unit test (45%)			practice	Final Examination (40% weightage)				
		Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	15%	ATTEN.	7 3 mg	15%	15%	-			
Level 2	Understand	25%	CALIFIE	U.17:- 1	20%	25%	-			
Level 3	Apply	30%	3		30%	30%	-			
Level 4	Analyze	30%	-	- 7/	30%	30%	-			
Level 5	Evaluate		-		7	-	-			
Level 6	Create					-	-			
	Total	100) %	100) %	100	0 %			

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Inte <mark>rnal Expe</mark> rts
1. Mr. Shantanu Chakraborty, Deputy General Manager, Volvo Group Trucks	1. Dr. V. Ganesh, Associate Professor, Dept. of Automobile	1. Dr. AJD Nanthakumar, SRMIST
Technology, Banagalore.	Engineering, Sri Venkateswara College of Engineering, Per	nnalur.



Course	2111111111111	Course	VEHICLE MAINTENANCE	Course	_	PROFESSIONAL CORF	L	Τ	Р	С	
Code	21AUC402J	Name	VEHICLE MAINTENANCE	Category	C	PROFESSIONAL CORE	2	0	2	3	

Pre-requisite Courses	Nil	Co- requisite Courses	Nil Progressive Courses	Nil
Course Offerin	g Department	Automobile Engineering	Data Book / Codes / Standards	Nil
			at Division	

Course L	Learning Rationale (CLR): The purpose of learning this course is to:	Ų,	Program Outcomes (PO)												rogram		
CLR-1:	LR-1: understand the fundamental workshop and maintenance concepts			2	3	4	5	6	7	8	9	10	11	12		pecific itcomes	
CLR-2: familiarize with the engine sub-systems nomenclature and maintenance					Jo	SI		1			ork		g				
CLR-3:	understand the principles and construction of vehicle chassis and body		Knowledge	S	Jent	stigations roblems	age	ъ	١.\		Μ		inance	ng			
CLR-4:	familiarize with the operational characteristic of vehicle electrical system	24.		nalysis	udoli	estig	l Us	r and	∞ ×		Team	fion	⊗ T	arni			
CLR-5:	CLR-5: understand the concepts of various vehicle auxiliary system		ering	₹	development of s	t inve	T00	engineer etv	nment		<u>8</u>	ommunication	Mgt.	g Le			
		1	a a	roblem	ign/	and duc	lern		tain	S	ndividual	חשר	Project	Long	7	7 7	
Course C	Outcomes (CO): At the end of this course, learners will be able to:	Sec. 5	Engine	Prof	Des	of O	Moc	The	Sus	Ethics	İndi	Con	Proj	Life	PSO.	PSO-2 PSO-3	
CO-1:	interpret the workshop maintenance and practice	-13		13	2	-		7	-	4	-	-	-	-	-		
CO-2:	diagnose the various engine sub systems for engine maintenance	9.51	-10		22.5	2	-	=	-	1	-	-	-	-	-		
CO-3:	analyze the performance ch <mark>aracteris</mark> tics of vehicle chassis and body		1 85	Viscol.		3	-		-	ė	-	-	-	-	-		
CO-4:	compare the operational characteristic of vehicle electrical system		1	1	- E	-	-	-	-		-	-	-	-	-		
CO-5:	analyze the maintenance schedule of various vehicle auxiliary system	100	1	95	-	-	3		-		-	-	-	-	-		

Unit-1 - Maintenance of Workshop Records and Schedule

12 Hour

importance of maintenance, scheduled and unscheduled maintenance, requirements of maintenance, preparation of check lists, vehicle down time, vehicle inspection, inspection schedule, maintenance of records, reports log books, trip sheets and other forms, safety precautions in maintenance, fleet maintenance requirement, work shop layout, tools and equipment, spare parts and lubricants stocking, manpower, training, workshop management, warranty, replacement policy.

Practice: 1. Layout for Garage and Preparation of Job Card Assignment (Two Wheeler/LCV/HCV), 2. Chart Preparation for Daily, Weekly, Monthly and Scheduled Maintenance

3. Performance Evaluation of A Two-Wheeler Using Eddy Current Chassis Dynamometer

Unit-2 - Powertrain Maintenance

Dismantling of engine components and cleaning, cleaning methods, visual and dimensional inspections, minor and major reconditioning of various components, reconditioning methods, engine assembly, special tools used for maintenance and overhauling, engine tune up, layout of transmission system, servicing and maintenance of automobile clutch, servicing and maintenance of gear box, servicing and maintenance of propeller shaft, servicing and maintenance of differential system, troubleshooting checklist for engine, troubleshooting checklist for clutch, troubleshooting checklist gear box.

Practice: 4. Engine Tuning Process (Decarbonizing, Valve Lapping, Reboring, Valve Clearance and Shim Adjustment of Shafts), 5. Transmission System – Servicing and Maintenance (Clutch Gearbox Propeller Shaft Universal Joint and Slip Joint)

Unit-3 - Vehicle Chassis and Body Maintenance

12 HOUI

Maintenance and servicing of front axle, maintenance and servicing of rear axle, maintenance and servicing of steering systems, maintenance and servicing of steering systems, maintenance of steering systems, wheel alignment, computerized alignment, wheel balancing, troubleshooting checklist for front axle, troubleshooting checklist for rear axle, troubleshooting checklist for suspension systems, troubleshooting checklist for steering systems, body panel tools for repairing, body panel tools for tinkering and painting.

Practice: 6. Steering System Servicing and Maintenance, 7. Tire Removal, Fitment, Computerized Wheel Alignment and Wheel Balancing 8. Determination of Side Slip, Suspension Efficiency, And Brake Efficiency Using Dynamometer.

Unit-4 - Electrical System Maintenance

12 Hour

Testing methods for checking electrical components, checking of battery, checking of starter motor, checking of charging system, checking of, dc generator, checking of alternator, checking of ignition systems, checking of lighting systems, fault diagnosis of modern electronic controls, maintenance of modern electronic controls, checking of dash board instruments, servicing of dash board instruments, trouble shooting on engine management system, on board diagnosis using multi-scanner.

Practice:

- 9. Measurement of HC, CO, CO2, and O2 Using Exhaust Gas Analyzer and Smoke Density Measurement
- 10. Studying the Pattern of Secondary Ignition System Using Oscilloscope Type Engine Analyzer FSA 450 (Bosch)

Unit-5 - Maintenance of Auxiliary Systems

12 Hour

Servicing of fuel system of different types of vehicles, maintenance of fuel system of different types of vehicle, calibration and tuning of engine for optimum fuel supply, maintenance of cooling system, water pump, radiator, thermostat, anticorrosion and antifreeze additives, maintenance of lubrication system, different grades of oil, lubricant oil additive, lubricating oil changing, greasing of part, minor and major repairs of body parts, maintenance of door locking mechanism, maintenance of window glass actuating system.

Practice:

11. Vehicle Assessment and Benchmarking of Tires by Tire Print Study, 12. Servicing of Coolant and Lubrication System.

Learning	1. MartyrA.J,PlintM.A, gine Testing Theory and Practice",3rdedition,But	erworth- Heinemann, 2. Wolf-He	Heinrich Hucho, "Aerodynamics of road vehicles", 4th edition,2000	
Resources	2007.Butterworth Heinemann, 2007.	3. Gousha	ha H. M, "Engine Performance Diagn <mark>osis & Tu</mark> ne up Shop Manual".	

Learning Assessme	ent		A PORT OF THE PARTY OF THE PART	The same of the sa			
Bloom's Level of <mark>Thinkin</mark> g		CLA-1 Avera	Continuous Learning native ge of unit test 5%)	CL	Learning A-2 5%)	Final Exa	native amination aightage)
	6	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	15%	The second second second	the state of the s	15%	15%	-
Level 2	Understand	25%		1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	20%	25%	-
Level 3	Apply	30%		A	25%	30%	=
Level 4	Analyze	30%	- NY	}	25%	30%	-
Level 5	Evaluate	AG 1	- 1	-	10%	-	-
Level 6	Create		- 1	-	5%	-	-
	Total	100	0 %	100	0 %	10	0 %

Course Designers	Control of the second	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr. P. Poongukamaran, MD TICEL md@ticelbiopark.com	Dr. Ganesh V, Professor SVCE vinaganesh@svce.ac.in	1. Jerome Stanley M, SRMIST
	2. Dr. Vijayabalan, Professor & Head Department ofMechanical	2. Dr. <mark>K.Kamalakk</mark> annan, SRMIST
	Engineering HITS vijayabalan@hindustanuniv.ac.in	

Course	21MEC202T Course	MECHANICS OF SOLIDS	Course	PROFESSIONAL CORF	L	Т	Р	С	
Code	Name	MECHANICS OF SOLIDS	Category	PROFESSIONAL CORE	3	1	0	4	

Pre-requisite Courses	Ni	Co- requisite Courses	Nil Progressi Courses	Nil
Course Offeri	ng Department	Mechanical Engineering	Data Book / Codes / Standards	Nil

Course L	earning Rationale (CLR): The purpose of learning this course is to:	de	Program Outcomes (PO)											Program Specific		
CLR-1:	LR-1: utilize concepts of stress and strain to determine the axial deformations				4	5	6	7	8	9	10	11	12		tcome	
CLR-2:	CLR-2: construct the shear force and bending moment diagram, and determine the stresses in beams				SI	1				or Y		e				
CLR-3:	determine the slope and deflection in beams for various loading conditions	wled		Jent	ation	age	ъ			n Wol		& Finance	бL			
CLR-4:	utilize concepts to design shafts based on strength and rigidity	Α̈́	Analysis	elopment	restigations problems	Us	r and	× ×	k.	Team	tion	& Fi	eaming			
CLR-5:	CLR-5: utilize concepts to design column and cylinders to predict the failure conditions			deve	ĕ ⊇.	Tool	engineer stv	ment ability		<u>छ</u>	ommunication	Project Mgt.				
		inee	roblem	ign/ ition	onduct	Modern		iron	SS	ndividual	nmu	ect	Long	-1)-2	
Course O	utcomes (CO): At the end of this course, learners will be able to:	Eng	Pro	Des	Cor	Moc	The	Env Sus	Ethics	Indi	Cor	Proj	Life	-OSd	DSO	PSO-3
CO-1:	apply the concepts of theory of linear elasticity	3	2	-		-	7	-	1	-	-	-	-		-	-
CO-2:	analyze the force, bending moment and stresses in beams	3	3	125	-5	-		-	1	-	-	-	-		-	-
CO-3:	analyze the slope and defle <mark>ction in b</mark> eams	3	3	Ē-		-	-	-	-	-	-	-	-	-	-	-
CO-4:	apply the concept of torsion in shafts	3	2	12.	-	-		-	-	-	-	-	-	-	-	-
CO-5:	analyze the stresses in columns and pressure vessels	3	3		-	-	_	-		-	-	-	-	-	-	-

Unit-1 - Concepts of Stress and Strain	12 Hour
Free body diagram, Types of stresses, strain, Poisson's ratio, stress-strain diagram, Elastic Constants, Deformation in axially loaded members,	
Stress Tensor, Equations of Equilibrium, Different states of stress, Transformation of plane stress, Principal stresses and maximum shear stress -	- Mohr's circle f <mark>or plane s</mark> tress
Unit-2 - Theory of Beams	12 Hour
Types of beams, support reactions, Shear Force Diagram, Bending Moment Diagram, Bending Stress & Shear stress in beams,	
Unit-3 - Deflection of Beams	12 Hour
Deflection of beams by double integration method-Macaulay's method-Moment area method-Castigliano's theorems, Maxwell's reciprocal theorem	em
Unit-4 - Torsion of Shafts	12 Hour
Stresses in a Shaft, Deformations in a Circular Shaft, Stresses and Angle of Twist in the Elastic Range, Comparison of hollow and solid shafts	
Unit-5 - Columns and Pressure Vessels	12 Hour
Crippling load - Euler's theory and Rankine's theory, thin and thick pressure vessels, Lame's theory-case study on pressure vessels	.* /

	1.	Ferdinand P. Beer, E. Russell Johnston, John T. DeWolf, David F. Mazurek, Sanjeev	3.	Egor P. Popov, Engineering Mechanics of Solid, 2nd ed., Prentice Hall of India Pvt. Ltd., 2009
Learning		Sanghi, "Mechanics of Materials: 8th Edition" McGraw Hill, 2020	4.	James M. Gere, Mechanics of Materials, 8th ed., Brooks/Cole, USA, 2013
Resources	2.	William A. Nash, Merle C. Potter, "Strength of Materials: 6th Edition, Schaum's Outlines	5.	Shigley. J. E., Applied Mechanics of Materials, International Student edition, McGraw Hill, 2000
		Series, McGraw Hill Education, 2014		144

			Continuous Learning Assessment (CLA)							
	Bloom's Level of Thinking	CLA-1 Avera	native age of unit test 0%)	CI	g Le <mark>arning</mark> LA-2 0%)	Summative Final Examination (40% weightage)				
		Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	15%		15%	2 - 1	15%	-			
Level 2	Understand	25%	ACC.	25%	- A- 10	25%	-			
Level 3	Apply	30%	77 - 17 10 10	30%	400	30%	-			
Level 4	Analyze	30%	Sec. 2777	30%		30%	-			
Level 5	Evaluate			- Att 1	1 2 2		-			
Level 6	Create		R. J. H. W. 27 J. A. C.	1000			-			
	Tot <mark>al</mark>	10	0 %	- 10	00 %	10	0 %			

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. N. Babu, CVRDE, DRDO, Avadi, babu.n. cvrde@gov.in	1. Dr. Shankar Krishnapillai, IIT Madras skris@iitm.ac.in	1. Dr. E Vijayaraga <mark>van, SR</mark> MIST
2. Mr. Parameswaran, Nokia, Chennai parameswaran, s@nokia.co	om 2. Dr. Raiu Abraham, NIOT, Chennai, abraham@niot.res.in	2. Dr. A Vinoth, SRMIST

Course Code	21MEC202L	Course Name	MATERIAL TESTING LABORATORY	Course Category	С	PROFESSIONAL CORE		T 0	P 2	1 1	

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	rogressive Courses	Nil
Course Offeri	ng Department	Mechanical Engineering	Data Book / Codes / Standards		Nil

Course L	earning Rationale (CLR):	The purpose of learning this course is to:		4			Progra	am Ou	ıtcome	es (PO)				Р	rogram
CLR-1:	understand the specimen p and non-ferrous alloy specii	reparation proce <mark>dures and</mark> correlate structure-property relationship of ferrous mens	1	2	3	4	5	6	7	8	9	10	11	12		pecific utcomes
CLR-2:	acquire knowledge to perfor	rm grain size analysis and determine coating thickness and hardenability				1			ty							
CLR-3:	avaluate the varieties in hardness and microstructure of heat treated steel engaineers and also to				of	ns of	À.	society	Sustainability		Work		8			
CLR-4:	have a bottor understanding on the machanical behaviour of materials under compression, double shear				pment	investigations problems	ool Usage	and so	& Susta		Team W	<u>_</u>	Finance	Learning		
CLR-5:	understand the behaviour of wear analysis	of materials subjected to fatigue, impact loads and to know the procedure of	Engineering Knowledge	Problem Analysis	Design/development solutions	luct investigat		The engineer	Environment 8	S	Individual & Te	Communication	Project Mgt. &	Life Long Lear	-	5 5
Course C	Outcomes (CO):	At the end of this course, learners will be able to:	Engir	Prob	Design	Conduct	Modern	The (Envir	Ethics	Indiv	Com	Proje	Life	PS0-1	PSO-2
CO-1:	prepare different metal spec	c <mark>imens a</mark> nd identify specimens by examining their microstructures	1 8	No.		3	-		-	=	1	-	-	-	-	-
CO-2:	determine hardenability, coa	a <mark>ting thic</mark> kness and analyze microstructure	5-40	15.	1	3	2	-	-	7	1	-	-	-	-	-
CO-3:		n <mark>ardness</mark> and microstructures of heat-treated specimens and study their tensile o <mark>n of simp</mark> ly supported beams	-			3	- 1	-	-		1	-	-	-	-	-
CO-4:	Analyze the mechanical bel and torsion loads	ha <mark>viour of</mark> materials subjected to compression, double shear, three- point bend	-	-	-	3	1	4	-		1	-	-	-	-	-
CO-5:	evaluate fatigue, impact and wear characteristics of materials		-	-	-	3	_		-	- 1	1	-	-	-	-	-

110	
Unit-1 - Specimen Identification	6 Hour
Study of metallurgical microscope, specimen preparation - mounting, polishing, etching. Identification of ferrous and non-ferrous alloys.	
Unit-2 - Coating Thickness and Phase Fraction	6 Hour
Determination of coating, case hardening thickness, hardenability. Evaluation of grain size and phase fraction.	
Unit-3 - Heat Treatment, Microstructure and Tensile Properties	6 Hour
Heat-treated steel specimens - investigation of microstructure and hardness. Tensile behaviour of steel specimens, deflection of simply supported beams.	
Unit-4 - Compression, Shear, Flexural and Torsion Properties	6 Hour
Compression, double shear, three-point bend and torsion tests of materials	
Unit-5 - Fatigue, Impact and Wear Properties	6 Hour
Fatigue test, impact test, wear analysis - pin-on-disc apparatus	

Learning
Resources

- 1. Sidney H Avnar, Introduction to physical metallurgy, 2nd ed., McGraw Hill Education, 2017
- 2. Donald R. Askeland, Wendelin J. Wright, Science and Engineering of Materials, 7th ed., Cengage Learning, 2015
- Ferdinand Beer, E. Russell Johnston, Jr., John DeWolf, David Mazurek, Mechanics of Materials, 7th ed., McGraw - Hill, 2017
- 4. Kazimi S. M. A, Solid Mechanics, 2nd ed., Tata McGraw Hill, 2017
- 5. Laboratory Manuals Metallurgy & Strength of materials laboratories

Learning Assessm	nent										
			Co	ntinuous Learning	g Assessment (C	LA)					
	Bloom's Level of Thinking	CLA-1 Average of first cycle experiments (30%)		cycle exp	ge of second periments 0%)		Examination 0%)	Final Examination (0% weightage)			
	4	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember		15%		15%	A	<mark>15%</mark>	-	-		
Level 2	Understand		25%	N.F.	20%	-	25 <mark>%</mark>	-	-		
Level 3	Apply		30%	Grand Control	25%		30%	-	-		
Level 4	Analyze		30%	1. July 1787	25%	-	30%	-	-		
Level 5	Evaluate		military.	1.78.92.7	10%	-	-	-	-		
Level 6	Create		2,200	873	5%	-		-	-		
	Tot <mark>al</mark>	10	0 %	100	0 %	10	0 %		-		

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Inte <mark>rnal Exp</mark> erts
1. Shankar Subburathinam, Engineering Manager – Caterpillar India Ltd	1. Dr. A. Suresh Babu, Associate Professor, CEG - Anna University	1. Mr. D. Selwyn Jebadurai, AP, SRMIST
2. Dr. N Saravanan, Principal Engineer, Smart Implements & Machinery and	2. Dr. N. Arunachalam, Associate Professor, IITM	2. Mr. S. Arokya Agustin,AP, SRMIST
Sustainability, Mahindra Research Valley.		



Course	21MEC203T	Course	ENCINEEDING MATERIALS AND METALLURGY	Course	_	DDOEESSIONAL CODE	L	Т	Р	С
Code	ZTIVIEGZUST	Name	ENGINEERING MATERIALS AND METALLURGY	Category	U	PROFESSIONAL CORE	3	0	0	3

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offerin	ng Department	Mechanical Engineering	Data Book / Codes / Standards		Nil

The Part of the Control of the Contr

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	Program Outcomes (PO)										Р	rogra	m		
CLR-1:	acquire knowledge about ph process	ase diagrams, salient features of iron-carbon system and heat treatme	nt 1	2	3	4	5	6	7	8	9	10	11	12	_	Specif utcom	
CLR-2:	ELR-2: apply mechanism of plastic deformation, principle of strengthening methods				ent	1 .	0										
CLR-3:				.83	mer	-Ju	sage	and			E	_		arning			
CLR-4:						S			± ≥		Team	Communication	∞.	earn			
CLR-5:	acquire knowledge about pro	pert <mark>ies and a</mark> pplications of advanced engineering materials	ering	dge A	. <u> </u>	solutions anduct	20	engineer	Environment 8		<u>8</u>	nic.	Mgt.	Ľ			
	1	The State of the S	ue.	el Ne	lgn/	duc	Modern		taio (S	ndividual Vork		Project Finance	Long	Ξ	7.5	53
Course O	outcomes (CO):	At the end of this course, learners will be able to:	Eng	S S	Design	Con	M	The	Env	Ethics	Individ	Sol	Pagin	Life	PSO	PS0-2	PSO.
CO-1:		am, describe the micro-constituents in iron-carbon system effect of h ing on the properties of materials	eat 3		1		-	1	-	÷	-	-	-	-	-	-	-
CO-2:	explain different strengthenin	g mechanisms, concepts related to plastic deformation	. 3	d	1		-	_	-	-	-	-	-	-	-	-	-
CO-3:	discuss the failure of enginee	ring materials, material testing and characterization techniques	1	1/2	3	1	-		-	7	-	-	-	-	-	-	-
CO-4:	classify metals and non-meta	Is for various engineering applications		19.	- 3		-	-	-	-5	-	-	-	-	-	-	-
CO-5:	apply advanced materials for methods related to materials	specific applications based on their properties and describe computation	nal _		3	-	2	0	-	į	-	-	-	-	-	-	-

Unit-1 - Phase Diagram and Heat Treatment

9 Hour

Crystal structure, Imperfection in solids, Solid solutions – Types, factors governing solubility rules. Phase diagram – cooling curve, phase rule, types and interpretation. Iron- carbide (Fe-Fe3C) phase diagram, Microstructural aspects and invariant reactions in Fe-Fe3C diagram. Effect of alloying elements on Fe-Fe3C diagram. TTT and CCT diagrams. Various heat treatment and surface hardening process

Unit-2 - Elastic and Plastic Behaviour of Materials

9 Hour

Stress Strain relation in elastic and plastic region, Mechanism of plastic deformation – slip and twinning, Slip systems, critically resolved shear stress, Shear strength of perfect and real crystals. Dislocation – climb, interaction, multiplication and pile ups. Strengthening mechanisms – Solid solution, Grain boundary, Dispersion, Precipitation, Fiber, Martensite strengthening, Strain aging and Strain hardening.

Unit-3 - Failure, Testing and Characterization of Materials

9 Hour

Types of fracture in metals, Griffith's theory of brittle fracture, Stress intensity factor, Fracture toughness, Theory of Ductile to brittle transition. Creep — Creep curve, mechanism of creep deformation. Fatigue - S-N curve, low and high cycle fatigue, stages of fatigue. Sources of failure, Procedure of failure analysis. Hardness: Rockwell, Brinell, Vickers hardness, Nano-Indentation Technique. Introduction to characterization of materials - XRD, SEM and TEM.

Unit-4 - Properties of Advanced Materials

9 Hour

Properties of plain carbon steel, Tool steel, Stainless steel, Cast iron. Need of micro alloying, HSLA steel - Dual phase steel, TRIP steel. Aluminum alloys - classifications, properties, applications, Titanium alloys. Polymers - Types, Properties and applications of PE, PP, PVC. Ceramics - Types, Properties and applications of Al2O3, ZrO2, SIC. Composites - classification, Reinforcement and matrix material, Rule of Mixture. Properties and applications of MMC, CMC and PMC. Functionally graded materials.

Unit-5 - Futuristic Materials and Computational Materials Design

9 Hour

Smart materials – Types, Shape memory alloys. Nanomaterials: Carbon nanotubes, Graphene – properties and applications. Metallic foams, Metallic glasses, Super alloys, High entropy alloys, biomaterials, Multi-scale materials modelling. Integrated Computational Materials Engineering with application to Industry 4.0. Materials Informatics, Machine learning for design of materials, Property Optimization

	1. Flake.C Campbell, Elements of Metallurgy and Engineering Alloys, ASM International, 2008
Learning	Dieter.G.E, Mechanical Metallurgy, McGraw Hill, Singapore, 2017
	3. Budinski.K.G, Budinski.M.K, Engineering Materials Properties and selection, Edition 9,
	Pearson Publication, 2010
	4. ASM Hand book, Failure analysis and prevention, Vol: 11, 2021
Resources	5. Reza Abbaschian, Lara Abbaschian& Robert E. Reed-Hill, Principles of Physical
	Metallurgy, Cengage Learning, 2013
	6. Chaudhery Mustansar Hussain,, "Smart Materials and New Technologies", Springer, 2022

7. Shubhabrata Datta and J. Paulo Davim, Machine Learning in Industry, Springer, 2021.

8.	James F. Shackelford et.al.	CRC Materials	Science and	l Engineering Handbo	ok, Taylor &
	Francis, 2015.				
_					

- 9. William D. Callister, David G. Rethwisch, Materials Science and Engineering: An Introduction, 10th ed., Wiley publication, 2018
- 10. Donald R. Askeland, Wendelin J. Wright, Essentials of Materials Science & Engineering, 4th ed., Cengage, 2018
- 11. Raghavan V. Physical Metallurgy: Principles and Practice, PHI Learning, 2015.
- 12. Shubhabrata Datta and J. Paulo Davim, Materials Design Using Computational Intelligence Techniques, CRC Press, Boca Raton, FL, USA, 2016

earning Assessm	nent		Continuous Learnin	g Assessment (CLA)	- 1	0		
	Bloom's Level of Thin <mark>king</mark>	CLA-1 Avera	native ge of unit test %)	Life-Long CL	g Learning A-2 0%)	Summative Final Examination (40% weightage)		
		Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember	20%		20%		20%	-	
Level 2	Understand	30%	Carlotte Carlotte	30%		30%	-	
Level 3	Apply	30%	A STATE OF THE STA	30%	. 7	30%	-	
Level 4	Analyze	20%	William Commence to the	20%		20%	-	
Level 5	Evaluate	3	MARK 1997 P. S. C.	7 1 3 3 3 3 3 3 3 3	- (0)	-	-	
Level 6	Create	22.7 77 57	FE 1851 155	"一根"这类"特殊"。		-	-	
	Total	100) %	100	0 %	10	0 %	

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Ex <mark>perts</mark>
1. Dr.V.S.Saravanan , Indo Shell Cast Private Limited,	1. Dr. Raju Abraham, Scientist-F, National Institute of Ocean Technology,	1. Dr. S <mark>hub</mark> h <mark>abra</mark> ta Datta, SRMIST
saravananvs@indoshellcast.com	Velachery-Tambaram Road, Pallikaranai, Chennai 601302, abraham@niot.res.in	
2. Mr. R.Sadagobaramanujam, TVS Sundram	2Dr. N Arunachalam, IIT Madras, chalam@iitm.ac.in	2. Mr. <mark>M.Dhana</mark> sekaran, SRMIST
Fasteners Ltd, sadagobar@gmail.com		A-8

Course Code	21MEC204L	Course Name	FLUID MECHANI	CS LABORATORY	Course Categor		С			PROF	FESSI	LANC	CORE			L 0	T 0	P 2	C 1
Pre-requi Course		Nil	Co- requisite Courses	Nil		gressi ourses							Nil						
Course (Offering Departm	ent M	lechanical Engine <mark>ering</mark>	Data Book / Codes / Standar	'ds							Nil							
Course Le	arning Rationale	(CLR): The r	ourpose of learning this cou	urse is to:	1	,			Progr	am Ou	ıtcome	s (PO)				Pı	rogra	
CLR-1:		measuring devices		4.5	1	2	3	4	5	6	7	8	9	10	11	12		pecifi	
CLR-2:	apply the princip	les of Bernoulli's eq	uation		ge		j o	ဟ			h.		춪		Φ				<u></u>
CLR-3:		ous energy losses in		-0-10-	Engineering Knowledge	(0)	Design/development of solutions	Conduct investigations of complex problems	ge	-			n Work		Finance	б			l
CLR-4:	assess the worki	ing of pumps/ Turb <mark>ir</mark>	nes	A. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1.	Z Š	alysis	lopu	stig	Use	ran	∞ _		Tear	. <u>u</u>	⊗ E	arnir			l
CLR-5:	measure forces a	around streamline b	ody/bluff body in wind/ water	tunnel	ring	Problem Analysis	deve	inve ex p	Modern Tool Usage	The engineer and society	Environment 8 Sustainability		Individual & Team	Communication	∕lgt.	Long Learning			l
				and the second second	nee	lem	gn/c tions	duct	ern	eng ety	ronr	တ္သ	idus	Jumur Jumur	Project Mgt.	Long	-1	7	က္
Course Ou	tcomes (CO):	At the	<mark>e e</mark> nd of this course, learne	rs will be able to:	Engi	Prof	Desi	Sol	Mod	The en	Envi	Ethics	Indi	Con	Proj	Life	PS0-1	PSO-2	PSO-3
CO-1:	demonstrate the	coefficient o <mark>f dis</mark> cha	<mark>ar</mark> ge in flow measurement de	rices	3	133	-	-		7	-		3	-	-	-	-	-	-
CO-2:	identify Bernoulli	i's equation f <mark>or meas</mark>	suring different heads	TARREST LANGE	3	-	24.5	-	-	4	-	-	3	-	-	-	-	-	-
CO-3:	determine and a	nalyze the v <mark>arious e</mark>	nergy losses in pipes		3	War.		3	-		-		3	-	-	-	1	-	-
CO-4:	interpret the diffe	erent types <mark>of pumps</mark>	s/turbines based on its perfor	mance	3	112	3.5		-	-	-		3	-	-	-	-	-	-
CO-5:	perform forces m	neasuremen <mark>t ar</mark> ou <mark>nc</mark>	streamline body/bluff body i	n wind/ water tunnel	3	7-1	100	-	-	_	-	2	3	-	-	-	-	-	-
	li.		47	STORY TO STORY	# 18 ·	34				w				ı		I			
	ow Measuring De			الأسارا المستحدث والمتعار					<u>L</u>	3								6	Hou
	the coefficient of a rnoulli's Principl		<mark>me</mark> ter/ Venturimeter, Flow me	easurement using Pitot tube					-2										Hou
			the pipe/ Bernoulli's theorem	, forced vortex and find the depth of th	ne forced	vortex	curve	7		7									TOU
	ergy Losses in P			- 1300		ronton	00.70		7		7.5							6	Hou
			<mark>nor los</mark> ses due to pipe fittings	and bends			-		-	1		ř							
	mps and Turbine		setion Durant let numer 10	Divini Destance to the Dellar	ال مواطنين		ا ء ما طیب	Fuence										6	Hou
	ce test on Submer Ind and Water Tu		cating Pump/ Jet pump/ Gea	r Pump, Performance test on Pelton to	urbine/ Ka	apıan t	urbine/	⊢ranc	s turb	ine									Hou
Silic-0 - VV	na ana mater ru	1111013																	iou

Learning
Resources

1. Robert W. Fox, Alan T. McDonald, Philip J. Pritchard, Introduction to Fluid Mechanics, 8thed., Wiley,2013
2. Frank M. White, Fluid Mechanics,7th ed., McGraw-Hill,2018

Velocity and pressure measurement using pitot tube, hot wire Anemometry and pressure sensor, model mounting technique, Force calculations

- 3. P.N.Modi, S.M.Seth, Hydraulics & Fluid Mechanics Including Hydraulics Machines, 20thed., Standard Book House, 2018
- 4. KL Kumar., Engineering Fluid Mechanics, 10th ed., S Chand&Co., 2015 Laboratory Manual

			Co	ontinuous Learning	Assessment (C	LA)				
	Bloom's Level of Thinking	exper	ge of first cycle iments 0%)	CLA-2 Avera cycle exp (30	eriments		Examination 0%)	Final Examination (0% weightage)		
		Theory	Practice Practice	Theory	Practice	Theory	Practice	Theory	Practice	
Level 1	Remember		30%		30%		30%	-	-	
Level 2	Understand	7	30%		30%	-	30%	-	-	
Level 3	Apply		40%		40%	A	40%	-	-	
Level 4	Analyze	/ /-		_	_	7 V 3		-	-	
Level 5	Evaluate	- 4	V .	-	-	7.1	- O. Y	-	-	
Level 6	Create		- 4	- 15 - 1- 10	-	-		-	-	
	Total	10	0%	100	0%	10	00%	L	-	

Course Designers	SAN 2610 00	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Er. N. Palani, Scientist D/SAMEER – Chennai.	1. Dr. Dhiman Chatterjee, IIT Madras, Chennai, dhiman@iitm.ac.in	1. Dr. P <mark>ankaj Ku</mark> mar, SRMIST
2. Er.D. Harihara Selvan, Technical Leader, GE Power, Noida - 20130	1 2. Dr. Raju Abraham, NIOT, Chennai, abraham@niot.res.in	2. Dr. S <mark>antosh K</mark> umar Singh, SRMIST



Course	21MEC205T	Course	FLUID MECHANICS AND MACHINERY	Course	_	DDOEESSIONAL CODE	L	Т	Р	С
Code	Z TIVIEGZUST	Name	FLUID MECHANICS AND MACHINERY	Category	U	PROFESSIONAL CORE	3	0	0	3

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	rogressive Courses	Nil
Course Offeri	ng Department	Mechanical Engineering	Data Book / Codes / Standards		Nil

THE PROPERTY OF THE PARTY OF TH

Course L	earning Rationale (CLR):	The purpose of learning this course is to:		4			Progr	am O	utcome	s (PO)					rograr	
CLR-1:	utilize the properties of fluid	and pressure measurement techniques using manometer	1	2	3	4	5	6	7	8	9	10	11	12	_	pecifi itcom	
CLR-2:	utilize the basic equations of	f fluid mech <mark>anics to sol</mark> ve fluid flow problems	dop	5	of	SI		70			Work		8				
CLR-3:	utilize the applications of din	nensiona <mark>l and mod</mark> el analysis			velopment	vestigations c problems	sage	ъ	b \				nance	Вu			
CLR-4:	utilize the concept of bounda	ary lay <mark>er, lift and</mark> drag forces	- A		udoli	estig	l Us	r and	∞ >		Team	ation	& Fi	arning			
CLR-5:	identify the working principle	and <mark>design o</mark> f hydraulic turbines and pumps	ering	Ī	deve	, ⊢ છે	\vdash	engineer etv	nment		<u>a</u>	munica	Mgt.	ig Le			
			ē.	흗	/ugi	omp	dern	eng •	tai o	S	ndividual		roject	Long	7)-2	5.
Course C	Outcomes (CO):	At the end of this course, learners will be able to:	2	Prof	Des	500	Moo	The	Env	E	lndi	Con	Proj	Life	PSO-1	PSO.	PSO.
CO-1:	determine the properties of t	fluid	1 3	3	-	-	- 1	7	-	-	-	-	-	-	-	-	-
CO-2:	solve the fluid flow problems		3	3	2.55	4	-	生	-		-	-	-	-	-	-	-
CO-3:	apply the mathematical tech	niques for practical fluid flow problem	3	3	<u> </u>	-	-	-	-	-	-	-	-	-	-	-	-
CO-4:	analyze the boundary layer	theory and flow over submerged bodies	3	3	122	-	-	-	-		-	-	-	-	-	-	-
CO-5:	identify the energy exchange	e process in fluid machinery	3	3	2.54	-	-	_	- 1	-	-	-	-	-	-	-	-

Unit-1 - Fluid Properties and Fluid Statics

9 Hour

Types of fluids, Properties of fluid, Dynamic and Kinematic viscosity - Newton's law of viscosity- Surface tension and capillarity- -Bulk modulus of elasticity and compressibility, Fluid statics: Pascal's law, Hydrostatic law, Buoyancy and Meta centre, Pressure, Manometers - Piezometer- Applications and limitation - U-Tube, Single column, Differential U-tube, Inverted differential U-tube manometers.

Unit-2 - Fluid Kinematics and Dynamics

9 Hour

Types of fluid flow, Lagrangian and Eulerian approach, Velocity and acceleration of fluid particles- Continuity equation- Euler equation of motion-Bernoulli's equation- Applications - Venturimeter- Orificemeter -Pitot tube-Nozzle flow meter- Types of flow lines, Stream line-Streak line and Path line-Impulse Momentum equation.

Unit-3 - Dimensional Analysis and Flow Through Pipes

9 Hour

Dimensions, Dimensional homogeneity-Buckingham's pi theorem-Model analysis-advantages and applications-similitude, Dimensionless numbers-Model laws-Reynold's, Froude, Weber, Mach, and Euler model laws, Concept of fully developed pipe flows - Darcy equation – Major and minor losses-Pipes connected in series and parallel-Equivalent pipe.

Unit-4 –Boundary Layer and Flow Around Submerged Bodies

9 Hour

Flow over flat plate - Laminar and turbulent boundary layers - Von Karman momentum integral equation - Boundary layer thickness – Displacement, momentum and energy thickness - Forces exerted by a flowing fluid on a stationary bluff and streamlined bodies -Separation of flow over bodies - Development of lift and drag forces.

Unit-5 - Hydraulic Machines

9 Hour

Pumps and turbines - Classification - Centrifugal and reciprocating pumps - Working principle - Design parameters - Velocity triangle - Performance curves - Pelton turbine, Francis turbine and Kaplan turbine, - Working principle - Design parameters - Velocity triangle - Performance curves - Cavitation in pumps and turbines.

Learning	
Resources	
ivesonices	

- Ltd., 6th ed., 2015
- 2. Bansal.R.K, A text book of Fluid Mechanics and Hydraulics Machines, Laxmi publications 6. Cengel, Y.A. and Cimbala, J.M. (2018) FluidMechanics. Fundamentals and Applications. 4th (P) Ltd., 9th ed., 2015
- 3. Modi P.N, Seth S.M, Hydraulics and Fluid Mechanics, Standard Book House, 15th ed., 2002 7. White F.M, Fluid Mechanics, Tata McGraw-Hill, 7th ed., 2011
- 4. Streeter, V.L., Wylie, E.B., Fluid Mechanics, McGraw Hill, 5th ed., 1984
- 1. Rajput.R.K, A text book of Fluid Mechanics and Hydraulic Machines, S.Chand& Company 5. Robert W. Fox & Alan T. McDonald & Philip J. Pritchard, Introduction to Fluid Mechanics, John Wiley & Sons Inc. 8TH ed 2011
 - Edition. McGraw-Hill, New York.

_earning Assessm			Continuous Learnin	g Assessment (CLA)		0			
	Bloom's Level of Thinking	CLA-1 Aver	mative age of unit test 50%)	Life-Long CL	Learning A-2 0%)	Summative Final Examination (40% weightage)			
		Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	20%	0.514.54	20%		20%	-		
Level 2	Understand	20%	200	20%		20%	-		
Level 3	Apply	30%		30%	V 2 2	30%	-		
Level 4	Analyze	30%	ALTERNATION OF	30%		30%	-		
Level 5	Evaluate	4 7 / -	Charles To the Control	- The			-		
Level 6	Create			- 10 de la	. 1	-	-		
	To <mark>tal</mark>	10	00 %	10	0 %	100	0 %		

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Interna <mark>l Exper</mark> ts
1. Er. N. Palani, Scientist D/SAMEER – Chennai.	1. Dr.S.Mohammed Ibrahim, IITKanpur	1. D <mark>r.R. Sent</mark> hil Kumar, SRMIST
2. Er.D. Harihara Selvan, Technical Leader, GE Power,	Noida - 201301 2. Dr.S. Jayavel, IITDM, Kancheepuram	2. D <mark>r.V. Raj</mark> asekar, SRMIST

Course	21MEC206T	Course	KINEMATICS AND DYNAMICS OF MACHINES	Course	_	DDOEESSIONAL CODE	L	Т	Р	С
Code	Z TIVIEGZUUT	Name	KINEWATICS AND DINAMICS OF WACHINES	Category	U	PROFESSIONAL CORE	3	0	0	3

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offer	ing Department	Mechanical Engine <mark>ering</mark>	Data Book / Codes / Standards		Nil

Course L	Course Learning Rationale (CLR): The purpose of learning this course is to:					Program Outcomes (PO)										n
CLR-1:	R-1: apply the kinematic analysis concepts to familiarize the working principle of machine tools		2	3	4	5	6	7	8	9	10	11	12		pecifi tcom	
CLR-2: familiarize the IC engine's valve and port mechanism and design the gear-box for power transmission systems				o	ns of		society	N		Work		es				
CLR-3:	apply the concepts of static and dynamics forces in IC engines and flywheels	wledge	S	nent	latio 1S	age		1		_		Finance	Б			
CLR-4:	R-4: familiarize the balancing of forces and moments in rotor bearings, ships and aeroplanes		ineering Knowledg olem Analysis ign/development of tions duct investigations	vestigat	Tool Usage	r and	y t y		Team	tion	∞ర	arning				
CLR-5:	familiarize the fundamentals of vibrations in Single degree of freedom systems	ering		deve	r iv		engineer	Environment Sustainability		<u>8</u>	Communication	Project Mgt.	g Le			
		nginee	Problem	ign/	duct	Modern	enĝ	ron	SS	ndividual	III.	ect	Long	-1	7-5	က္
Course C	outcomes (CO): At the end of this course, learners will be able to:	Eng	Pro	Des	Condu	Mod	The	Envi	Ethics	Indi	Con	Proj	Life	PSO.	PSO-2	PSO
CO-1:	apply the concepts of theory <mark>of mech</mark> anisms to perform kinematic analysis	3	3	983	1.5	l - ,	4	-		-	-	-	-	-	-	-
CO-2:	analyze the kinematics of cam and follower, and gear trains	3	3	4 -	17.5	-	-	-	Ξ	-	-	-	-	-	-	-
CO-3:	perform the static and dyna <mark>mic forc</mark> e analysis of mechanisms	3	3	1.7	-	-	=	-		-	-	-	-	-	-	-
CO-4:	analyze the effect of unbalancing forces and gyroscopic effects in machines	3	3		-	-	_	-		-	-	-	-	-	-	-
CO-5:	formulate the governing equations and solve for single DOF systems	3	- 3		-	- (_ =	-	-	-	-	-	-	-	-	-

Unit-1 - Kinematics of Mechanisms 9 Hour

Introduction to mechanism: Link, pair, kinematic chain, mechanism and machine - Degrees of Freedom - Mobility - Four Bar Chain, Grashof's law, Kutzback's and Grubler's criterion for planar mechanisms - Kinematic Inversions of kinematic chain, Kinematic Analysis: Velocity and acceleration analysis of Four bar and single slider crank mechanism by graphical method - Instantaneous center (IC) method, Kennedy's theorem, Velocity analysis of Four bar and single slider crank mechanism by Instantaneous center method

Unit-2 - Kinematic Analysis of Machine Elements

9 Hour

Cams and Followers: Cam terminology, types of cams and followers, Types of follower motion - Kinematics of follower for parabolic, simple harmonic, uniform acceleration and cycloidal motions - construction of circular cam profile for radial and offset followers with different follower motions Gears: Gear terminology, types of gears - law of gearing - path of contact, arc of contact, sliding velocity - interference and undercutting of gears – Gear trains: types and applications - velocity ratio calculations in simple, compound and epicyclic gear train

Unit-3 - Force Analysis

9 Hour

Applied and Constrained Forces – Free body diagrams – Static Equilibrium conditions – Two, Three and four force members – Static Force analysis in simple machine members – Dynamic Force Analysis – Inertia Forces and Inertia Torque – D'Alembert's principle – superposition principle – dynamic force Analysis in reciprocating engines - Turning moment diagrams - flywheels- Case study on four bar mechanism

Unit-4 - Balancing and Gyroscope

9 Hour

Balancing of rotating masses: Static and dynamic balancing of seve<mark>ral masses rotating in same and different planes by analytical and graphical methods - Balancing of reciprocating masses by graphical method. Gyroscopic Gyroscopic forces, couple, precessional angular motion, Gyroscopic effects on automobiles, trains, aeroplane and ship</mark>

Unit-5 - Fundamentals of Vibrations

9 Hour

Basics of vibrations - Terminology and types of vibrations - Governing equations for free undamped and damped vibrations of single degree of freedom system - logarithmic decrement. Forced vibration: Types of - of forced vibration single degree of freedom system under harmonic excitation.

Learning Resources	1. 2. 3.	Rattan S.S., "Theory of Machines", McGraw Hill Education, 4th edition, 2015 Thomas Bevan, Theory of Machines, 3rd Edition – P Education Limited – 2005 – 3rd Edition	 Robert L. Norton, Kinematics and Dynamics of Machinery, 2nd Edition, McGraw Hill, 2013. Rao SS, 'Mechanical Vibrations, 5th Edition, Prentice Hall 				

			0						
	Bloom's Level of Thinking	Formative Life CLA-1 Average of unit test (50%)			g <mark>Learning</mark> LA-2 0%)	Summative Final Examination (40% weightage)			
		Theory	Practice	Theory	Practice Practice	Theory	Practice		
Level 1	Remember	15%	-	15%		15%	-		
Level 2	Understand	25%	- A - A	20%	7) - 1	25%	-		
Level 3	Apply	30%	ACCUMENT	25%	- A- 10	30%	-		
Level 4	Analyze	30%	44.5	25%	A 1-3	30%	-		
Level 5	Evaluate	/~ · /	- N. A. S. J. S. W.	10%		• -	-		
Level 6	Create			5%			-		
	Tota <mark>l</mark>	100)%	10	00 %	10	0 %		

Course Designers	PERSONAL PROPERTY OF THE PROPE	
Experts from Industry	Experts from Higher Technical Institutions	Interna <mark>l Experts</mark>
1. Dr. N. Babu, CVRDE, DRDO, Avadi, babu.n.cvrde@gov.in	1. Dr. Shankar Krishnapillai, IIT Madras, skris@iitm.ac.in	1. K <mark>R. Arun P</mark> rasad, SRM IST
2. Mr. Parameswaran, Nokia, Chennai, parameswaran.s@nokia.com	2. Dr. Raju Abraham, NIOT, Chennai, abraham@niot.res.in	

ACADEMIC CURRICULA

UNDERGRADUATE/ INTEGRATED POST GRADUATE DEGREE PROGRAMMES

(With exit option of Diploma)

(Choice Based Flexible Credit System)

Regulations 2021

Volume - 7C
(Syllabi for Automotive Engineering Programme Courses)



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Chengalpattu District 603203, Tamil Nadu, India

ACADEMIC CURRICULA

Professional Elective Courses

Regulations 2021



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Chengalpattu District 603203, Tamil Nadu, India

Course	21ALIF202T Course	SENSORS, ACTUATORS AND SIGNAL CONDITIONERS	Course	Е	PROFESSIONAL ELECTIVE	L	Т	Р	С	
Code	Name	SENSORS, ACTUATORS AND SIGNAL CONDITIONERS	Category	E	PROFESSIONAL ELECTIVE	3	0	0	3	

Pre-requisite Courses	Ni	Co- requisite Courses	Nil Progressiv	NII
Course Offeri	ing Department	Automobile Engineering	Data Book / Codes / Standards	Nil

Course L	earning Rationale (CLR): The purpose of learning this course is to:	Program Outcomes (PO)												Progra		
CLR-1:	define the sensors, their operations and select appropriate sensors for automotive applications	1 2 3 4 5 6 7 8 9 10 11 12		12	Specific Outcomes											
CLR-2:	define and classify the actuators and select to integrate them into an overall system	dge		of	SI		, "s			Work		8				
CLR-3:	identify signal conditioning operation <mark>s and devi</mark> ces	nowlec	w	Jent	vestigations problems	Usage	ъ			Μ		Finan	б			
CLR-4:	evaluate and analyze the sensor s <mark>ignals</mark>	조	alysis	udoli	estig	ı Us	r and	y k		Team	ţį	∞ర	arning			
CLR-5:	compare the input signals and select appropriate data conversion methods	ering	٩	gn/development of ions	I.⊑ ∷	dern Tool	engineer ety	nment nability		ual &	ommunication	: Mgt.	Long Le			
Course C	outcomes (CO): At the end of this course, learners will be able to:	Engine	Problem	Design solution	Conduct of comple	Moderi	The en	Enviroi S <mark>ustair</mark>	Ethics	Individual	Comm	Project	Life Lo	PSO-1		PSO-3
CO-1:	acquire the knowledge of construction and operation of sensors and its applications in automobiles	3	- 3	1		1		-		-	-	-	1	3	-	-
CO-2:	understand the basics of actu <mark>ators an</mark> d its operations	3	3	2	7-19	2	4	-	-1	-	-	-	1	2	1	-
CO-3:	know the fundamentals of signal conditioning devices and its operation	3	3	2	43	2	-	-	-	-	-	-	1	3	-	-
CO-4:	applications of operational amplifier and its applications	3 -	3	2		2	-	-	-	-	-	-	1	3	-	-
CO-5:	learn and implement the basics of data conversion devices	3	- 3	2	7 -	2		-		_	_	-	1	3	-	-

Unit-1 - Automotive Sensors 9 Hour

introduction to sensors, variables to be measured for automotive engine control applications, airflow rate sensor – construction and operations, pressure measurement – strain gauge and map sensor, engine crank position sensor - -magnetic reluctance, hall effect sensor, optical crank position, throttle angle sensor – construction and operation, construction and operation, temperature sensor construction and operations and types, sensors for engine feedback control - ego sensor, ego characteristics, wide band lambda sensor, magnetostrictive principle and knock sensor, oil pressure sensors, accelerometer construction and operations, gyro sensors construction and operations, inertial measurement unit, sensors for climate control, switches and knobs313

Unit-2 - Automotive Actuators 9 Hour

basics of actuators and its principles of operations, variables to be controlled for automotive engine control applications, pulse width modulated signal, h-bridge device for speed and direction control, electric motor actuator - dc motor, brushless dc motor, stepper motor mechanism, servomechanism, engine control actuators -fuel injector, ignition coil operation, egr actuator operation, electric actuators — overview, relays, reed switches — construction and operation, actuators applications, electric power assisted steering, rain sensing wipers, motorized seat position control, power window application

Unit-3 - Introduction to Operational Amplifier

Introduction – Signal conditioning operations, Basics of operational amplifier, Ideal operational amplifier – Introduction, characteristics, Operational amplifier- open and closed loop, Operational amplifier. Inverting, Non- Inverting amplifier, Voltage follower; Differential amplifier - Difference mode gain, Common mode gain, Common Mode Rejection Ratio; Operation amplifier internal circuit, DC characteristics of operational amplifier, IC 741 internal circuit Introduction, IC 741 Operations, Filters – Introduction, High pass and low pass Filter, Band pass Filter

Unit-4 - Operational Amplifier Applications

9 Hour

9 Hour

Applications of operational amplifiers, Basics of Instrumentation amplifiers, Operational amplifier using diodes- Half wave Rectifier, Full wave rectifiers, Precision diodes; Sample and Hold circuits, Voltage to Current converters, Current to Voltage converters, Applications of operational amplifiers as Adder, Subtractor, Multiplier, divider, Differentiator and Integrator, Instrumentation amplifier application, Voltage comparator, Peak detector

Unit-5 - Waveform Generators, A/D And D/A Convertors

9 Hour

Comparator introduction, Comparator Applications, Regenerative Comparator Introduction, Square Wave Generator - Astable Multivibrator, Monostable Multivibrator and Bistable Multivibrator Introduction to Analog to Digital Converters - Direct TypeADC, Flash Type, Successive approximation type, Numerical Examples for ADC; Basics of Digital to Analog Conversion Techniques - R-2R Ladder DAC, Weighted Resistor type DAC, Numerical Examples.

Learning
Resources

- William. B. Ribbens, "Understanding Automotive Electronics" 8th Edition Butterworth-Heinemann publications, 2017.
- 2. Ronald. K. Jurgan "Automotive Electronics Handbook", 2ndEdition, McGraw-Hill, Inc 2005
- 3. Robert F. Coughlin, Frederick F. Driscoll, "Operational Amplifiers and Linear Integrated Circuits", 6th Edition, PHI, 2000.
- 4. D.Roy Choudhry, Shail Jain, "Linear Integrated Circuits", New AgeInternational Pvt. Ltd., 4th edition. 2018.
- 5. Sergio Franco, "Design with Operational Amplifiers and Analog Integrated Circuits", 3rd Edition, Tata Mc Graw-Hill, 2017.

_earning Assessm	nent			(0)	<u> </u>				
	Bloom's Level of Thi <mark>nkin</mark> g	CLA-1 Avera	Continuous Learning native ge of unit test %)	g Assessment (CLA) Life-Long L CLA (10%	-2	Summative Final Examination (40% weightage)			
		Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	15%	Carlotte Marian	15%		15%	-		
Level 2	Understand	25%	A STATE OF THE STA	25%		25%	-		
Level 3	Apply	30%	128 1 1 1 2 miles 197	30%	- 4	30%	-		
Level 4	Analyze	30%	All and the second	30%	- (2)	30%	-		
Level 5	Evaluate	25.2 (0.1)	No. 1751 745	中的社会国际发展。	4	-	-		
Level 6	Create		N 727 L 2 L	4.50		-	-		
	Total —	100)%	100	%	100) %		

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Associate Director,	1. Mr. Sam Jebakumar, SRMIST, jebakumj@srmist.edu.in	1. Dr.C.Carunai <mark>selvane,</mark> SRMIST
Skill- Lync		
2. Mr.G.Giri, Managing Director, Atalon, giri@atalon.co.in	2. Dr. SathishKumar. P, Assistant Professor, sathish.p@nitpy.ac.in, NIT,	2. Dr.T.Prave <mark>enkumar,</mark> SRMIST
	Karaikal	/ 67

Course	21AUE211J	Course	ANALOG AND DIGITAL CIRCUITS FOR AUTOMOTIVE	Course	П	PROFESSIONAL ELECTIVE	L	T	Р	С
Code	ZIAUEZIIJ	Name	APPLICATIONS	Category		PROFESSIONAL ELECTIVE	2	0	2	3

Pre-requisit Courses	N	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Off	ering Department	Automobile Engineering	Data Book / Codes / Standards		Nil

Course Lo	e Learning Rationale (CLR): The purpose of learning this course is to:			Program Outcomes (PO)											rogram
CLR-1:	2-1: acquire knowledge about the BJT, MOS based amplifiers			3	4	5	6	7	8	9	10	11	12	_	pecific itcomes
CLR-2:	know the working of oscillator, wave Shaper and Multi vibrator circuits	dge		of	ટા	-				Work		e e		1	
CLR-3:	impart the techniques of minimizing digital logic circuits	owlec	S	nent	stigations	age	ъ	. 1	L	Μ		inan	bu		'
CLR-4:	familiarize the combinational circuits for different digital applications	줃	alysis	lopi	estig	l Usag	er and	× t ∞	h.	Team	ţi	8 F	arni		'
CLR-5:	familiarize the digital sequential circuits and memory devices			Long Le											
Course O	outcomes (CO): At the end of this course, learners will be able to:	Engine	Proble	Design solutio	Conduct i	Modern	The en society	Enviro S <mark>ustai</mark>	Ethics	Individual	Comm	Project	Life Lo	PS0-1	PSO-2 PSO-3
CO-1:	understand the use of analog circuits that are essential for Automotive Application	3	- 2	1	·	2	-7	-		1	1	1	1	3	
CO-2:	understand the Oscillators, Wave Shaping and Multi Vibrator Circuits	3	3	1	- 19	2	4	-		1	1	-	1	3	
CO-3:	apply the Boolean expressi <mark>on minim</mark> ization techniques and implement using logic gates		3	1	1.0	2	-	<i>-</i>	-	1	1	-	1	-	2 -
CO-4:	design and implement the Combinational Circuits		3	. 1	-	2	-	d -		1	1	-	1	3	
CO-5:	design and implement Sequential Circuits and understand the Memory Devices		2	1	<u> </u>	2		-	-:	1	1	-	1	3	

Unit-1 - Introduction to Analog Circuits

12 Hour

Introduction to Analog circuits, BJT Small signal Model, CMOS Circuit Model, CMOS Circuit Mode, Biasing Circuits, MOS amplifiers, Frequency response of amplifiers, Operational amplifiers. Differential amplifiers, Application of amplifiers in Automobile.

Practice 1: Operation of BJT and CMOS as amplifier 2: Characteristic of Op Amp

Unit-2 – Oscillator Wave Shaping and Multivibrator Circuits

12 Hour

Oscillator: Introduction, Analysis of LC oscillator, Wave shaping: RC and RL Filters, Differentiator, Integrator, Clippers, Clamper, Comparator, UJT-Saw tooth Waveform Generator, Multivibrators: astable, Monostable and Bistable, Schmitt trigger circuits.

Practice 3: Study and Design of Filters 4: Study and Design of multivibrators

Unit-3 - Logic Gates and Arithmetic Application

12 Hour

Logic circuit implementation: AND, OR, NOT, NAND, NOR, EXOR, EX-NOR, TTL Logic, CMOS Logic, Arithmetic application: Boolean Postulates, Demorgan's Theorem, , Min term, Max term, POS, SOP form, K-MAP – Overview,

Practice 5: Study of Logic Gates through Basic Digital IC's 6: Minimization of Boolean Expression using K map

Unit-4 - Combinational Circuits

12 Hour

Introduction to Combinational Circuit, Arithmetic and logic functions: Adder and Subtractor operation and circuit example, Serial adder/Subtractor, BCD addition, Data transmission: Multiplexer, Demultiplexer, Decoder, Encoder, Parity Checker, Parity Generator, Code Convertor.

Practice 7: Combination Logic Adder, Subtract or, Differentiator Circuits 8: Circuit realization of UX, DEMUX 9: Circuit realization of Code Converter.

Unit-5 - Sequential Circuits and Memory Devices

12 Hour

Latches and Flip-flops: SR, JK, D, T characteristic table and Equation, Counters: Asynchronous Counters, Synchronous Counters, ProgrammableCounters. Registers: Shift Registers, Universal Shift Register, and Sequence Generator, Memory Devices: RAM, ROM, PROM, EPROM, Programmable Logic Devices: PLA VS PLD, Introduction to FPGA.

Practice 10: Circuit realization of Flip-flops

l	Learning
l	Resources

- David A.Bell "Electronic Devices and Circuits", Oxford HigherEducation Press, 5th Edition, 2010
- 2. M. Morris Mano, "Digital Design", 5th Edition, Prentice Hall of India Pvt. Ltd., 2014 / 4. Pearson Education (Singapore) Pvt. Ltd., New Delhi.
- 3. Donald P.Leach and Albert Paul Malvino, "Digital Principles and Applications", 6th Edition, TMH, 2006.
 - Sedra and Smith, "Micro Electronic Circuits"; 7th Edition, Oxford University Press, 2011. Millman and Halkias. C., Integrated Electronics, TMH, 2017.

Learning Assessme	ent									
	Bloom's Level of Thin <mark>king</mark>	CLA-1 Avera	Continuous Learning mative age of unit test 5%)	CL	Learning A-2 5%)	Summative Final Examination (40% weightage)				
		Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	15%	CONTRACTOR OF S	1444	25%	15%	-			
Level 2	Understand	25%	Carlot of the same	The second second	30%	25%	-			
Level 3	Apply	30%	A 12 1 1 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		30%	30%	-			
Level 4	Analyze	30%	100 May 17 - 150 M	Sec. 1 30. 7	- 4	30%	-			
Level 5	Evaluate	3777	Mary State State	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	- 2	-	-			
Level 6	Create	E. (7)	100	""中国国际发展。	1	-	-			
	T <mark>otal </mark>	10	00 %	100	0 %	10	0 %			

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Associate Director, Skill-Lync	1. Dr.S.Jeevananthan, Professor, Electrical and Electronics Engineering,	, 1. Dr.C.Carunais <mark>elv</mark> an <mark>e, SRMIST</mark>
	PTU, drsj_eee@pec.edu.in	
	2. Mr. Sam Jebakumar, SRM IST, jebakumj@srmist.edu	2. Dr.T.Pravee <mark>nkumar,</mark> SRMIST



Course	21ALIF371T Course	VEHICLE DVNAMICS AND DESIGN	Course _	PROFESSIONAL ELECTIVE	Г	Т	Р	С	
Code	Name	VEHICLE DYNAMICS AND DESIGN	Category	PROFESSIONAL ELECTIVE	3	0	0	3	

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offeri	ng Department	Automobile Engineering	Data Book / Codes / Standards		Nil

THE PARTY OF THE P

Course L	earning Rationale (CLR): The purpose of learning this course is to:	111	4			Prog	am Ou	ıtcome	s (PO)					rogram
CLR-1:	broaden the importance of vehicle performance characteristics	1	2	3	4	5	6	7	8	9	10	11	12		pecific itcomes
CLR-2:	enable the students to understand various automotive vehicle stability, ride and handling	dge		of	SI					Work		8			
CLR-3:			S	Jent	estigations roblems	Usage	ъ	٠, ١				Finan	ning		
CLR-4:	4: enable the students to understand various Convenience System		alysis	velopment of	estig		r and	∞ ∞ >	h.	Team	ioi	≪ ⊞	ä		
CLR-5:	enable the students to understan <mark>d variou</mark> s methods in Automotive Styling	ering	A	n/deve	.≧ ×	looT r	engineer ety	nment nability	1	ual &	mmunication	: Mgt.	Long Le		
Course C	Outcomes (CO): At the end of this course, learners will be able to:	Engine	Problem	Design	Conduct of comple	Modern	The en society	Enviro S <mark>ustai</mark>	Ethics	Individual	Comm	Project	Life Lo	PS0-1	PSO-2 PSO-3
CO-1:	acquire and analyze the various factors that affect the vehicle performance	3		17.	·	2	7	-	-	-	-	-	-	-	
CO-2:	characterize various conditions as Vehicle Stability, Ride & Handling	3	2	40.50	- 19	-	4	-	-	-	-	-	-	-	
CO-3:	demonstrate Dynamic Characteristics of Vehicles	N 3	di rek	_3	1	2	_) -		-	-	-	-	-	
CO-4:	discuss about Convenience System with their challenges and its applications			3	-	2	-	- 1		-	-	-	-	-	
CO-5:	apply knowledge of vehicle styling		20	2	3	-		-		-	-	-	-	-	

Unit-1 - Vehicle Performance Estimation and Prediction

9 Hour

Aerodynamic Drag, Methods of Estimation Of Resistance To Motion, Power Requirement For Propulsion, Power Plant Characteristics & Transmission Related Requirements. Vehicle Controls and Arrangement Of Power Train. Vehicle Acceleration, Maximum Speed, And Grade Ability. Drive Systems Comparisons, Hill Climbing Characteristics. Ride Characteristics On Different Road Surfaces, Effect Of Pressure, Temperature And Humidity On Power Output

Unit-2 - Vehicle Stability and Handling

Hour

Introduction to Electric Vehicles, Wiring Diagram/ Power Flow in EVs & HEVs z, Wiring Diagram/ Power Flow in EVs & HEVs, Types of EVs: HEV, FCEV, HEVs Configuration: Series Case Study, HEVs Configuration: Parallel - Case Study, HEVs Configuration: Series Parallel - Case Study, Motor, Battery Pack, DC-DC Convertor, Inverter, On-Board Charger, Communication System, smart hybrid technology - NEXA, Micro Hybrids - Case Study Electric Vehicle Charging - Fundamentals, Single and Multi-motor drives, In wheel drives

Unit-3 - Vertical Dynamics

9 Hour

List the methods for assessing human tolerance to vibration, Describe the criteria for ride comfort, Categorize the vertical dynamics modeling of vehicles, Evaluate the equation of motion for the vertical dynamic models, Design passive suspension system in quarter car model, Analyze passive suspension systems in quarter car model, Analyze semi active and active suspension systems in quarter car model, Design passive suspension system in half car mode, Design passive suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in half car model, Analyze semi active and active suspension systems in quarter car model, Analyze semi active and active suspension systems in quarter car model, Analyze semi active and active suspension systems in quarter car model, Analyze semi active and active suspension systems in quarter car model, Analyze

Unit-4 - Convenience System

9 Hour

Antiskid Braking System, Traction Control System, Adaptive Cruise Control, Driving Assistance System- Electronic All-Around Visibility, Parking Aid With Ultrasonic Sensors, Environment Information System, Driver Alertness Detection System, design Of Seat Belt, Automatic Seat Belt Tightening System, Collapsible, Tilt-Able Steering System Design, The Design, Construction Of Air Bags

Unit-5 - Automotive Styling 9 Hour

Fundamentals of drawing perspective, aesthetics, ergonomics, anthropometry, vehicle proportions, styling process, sketching, clay modeling, rendering, digital visualization, designing of Interiors: R/H-Point, seating positioning, dash board equipment's arrangement, positioning of operational controls, visibility and vehicle packaging.

Learning Resources

- Reza N. Jazar, "Vehicle Dynamics: Theory and Application", 3rd Edition, Springer International Publishing AG, Switzerland, 2017.
- 2. Thomas D. Gillespie, "Fundamentals of Vehicle Dynamics (R114) Publisher: Society of Automotive Engineers Inc., 1992.
- 3. William F. Milliken and Douglas L. Milliken, "Race Car Vehicle Dynamics", SAE, 1995.
- 4. Rajesh Rajamani- "Vehicle Dynamics and Control"- 1st edition- Springer- 2005.
- 5. W.H. Hucho, 'Aerodynamics of Road Vehicles', SAE Publications, 6th edition 2012
- 6. R.McCallen, Browand, Ross, "The Aerodynamics of Heavy Vehicles", Springer, 2014
- 7. Pope "Wind Tunnel Testing"- John Wiley & Sons 2nd Edition, New York 1974.
- 8. Julian Happian-Smith, "An introduction to modern vehicle design", Butterworth Heinmenn, 2001
- 9. Fenton John, "Handbook of automotive body and system design", Wiley-Blackwell, 1998
- 10. R.N. Bahl, "Automobile Design", Wiley.

earning Assessm	ient		Continuous Learning	g Assessment (CLA)		Sumn	native
	Bloom's Level of Thi <mark>nking</mark>	CLA-1 Avera	ative ge of unit test %)	Life-Long CLA (10	1-2	Final Exa (40% we	amination
		Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	15%	all a series	15%		15%	-
Level 2	Understand	25%	A 100 TO	20%	. 1 . 7	25%	-
Level 3	Apply	30%	123 / 1 to app 10 /	25%		30%	-
Level 4	Analyze	30%	Mar. 1960 1971	25%	- C	30%	-
Level 5	Evaluate	23 77 31 1		10%	1 - 3	-	-
Level 6	Create		30 BAC 6 B	5%	3 -	-	-
	Total	100)%	100	%	100) %

Course Designers	7.7.4	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr.Mohammed Rafiq, ARAI	1. Dr. P. Sathish Kumar NIT - Karaikkal	1. Mr. M.Jerom <mark>e Stanley</mark> SRMIST
	17.00	2. Mr. Yokeshwaran S SRMIST

Course	21AUF411T	Course	DOWED ELECTRONICS EOD ELECTRIC VEHICLE ADDLICATION	Course	_	PROFESSIONAL ELECTIVE	L	Т	Р	С	1
Code	ZIAUE4III	Name	POWER ELECTRONICS FOR ELECTRIC VEHICLE APPLICATION	Category		PROFESSIONAL ELECTIVE	3	0	0	3	

Pre-requisite Courses	Ni	Co- requisite Courses	 Nil	Progressive Courses		Nil
Course Offeri	ng Department	Automobile Engineering	Data Book / Codes / Standards		4_ 1	Nil

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	11	4			Progr	<mark>am O</mark> u	itcome	s (PO)					rogram	
CLR-1:	define and understand the	power semicond <mark>uctor compon</mark> ents and its characteristics	1	2	3	4	5	6	7	8	9	10	11	12	_ '	pecific itcomes	
CLR-2:	distinguish and demonstr	rate the different DC-DC and AC-AC converters topology	dge		o	SI		, "s			Work		8				
CLR-3:	LR-2: distinguish and demonstrate the different DC-DC and AC-AC converters topology LR-3: interpret and relate the operation, characteristics and performance parameters of rectifiers LR-4: compare and contrast the operation, switching techniques for various types of DC-AC inverters		wlec	W	velopment of	stigations	Usage	ъ			Μ		Finan	БC			
CLR-4:	compare and contrast the	e operation, switching techniques for various types of DC-AC inverters	Α̈́	alysi	ndol	estig		r and	y k	h.	Team	fion	∞ర	arning			
CLR-5:	design and develop the m	otor driv <mark>es for aut</mark> omotive motor control applications	ring	An	deve	t inv	Tool	engineer ety	ment ability	. 1	<u>8</u>	mmunication	Mgt.	g Le			
	•		nee	plem	fign/	duct ir	ern	enc ety	ron	SS	ndividual	חת	ist ist	Long	7	7-5	က္
Course C	Outcomes (CO):	At the end of this course, learners will be able to:	Eng	Prot	Des	Con	Mod	The	Envi S <mark>us</mark> f	Et	Indi	Con	Proje	Life	PSO.	PSO-2	PSO.
CO-1:	list and recognize the val	riou <mark>s power</mark> semiconductor devices suitable for motor drive applications	3	- 1		-	-		-		-	-	-	-	3	-	2
CO-2:	identify and solve the DC	C-D <mark>C and A</mark> C-AC converters suitable for the desired requirements	3	2	2	1	-	4	-		-	-	-	-	3	-	2
CO-3:	experiment and sketch th	e v <mark>arious A</mark> C-DC Rectifier configurations and their input and output Waveforms	3	2	2	1	-	-	-	-	-	-	-	-	3	-	2
CO-4:	relate and use the DC - AC Inverters with various sources and control techniques		3	2	2	1	-	-	-		-	-	-	-	3	-	2
CO-5:			3	2	2	1	_		-		-	-	-	-	3	-	2

Unit-1 - Automotive Semiconductor Devices

9 Hour

Introduction to power semiconductor devices, Diodes: Construction, characteristics and applications – Rectification, Diodes – Freewheeling, Diodes – Clamping Devices, Transistors: BJT, Power MOSFETs, and - Low-Voltage Load Drivers, IGBTs: Construction, characteristics and applications. Operation parametrization: Turn ON and Turn OFF techniques, Series and Parallel operation Power Integrated Circuits, Power Integrated Circuits Examples, Smart Power Devices, Emerging Device Technologies - Super- Junction, Emerging Device Technologies - Sic Devices, Protection circuit, Power Losses and Thermal analysis in semiconductors, Interpretation of data sheets.

Unit-2 - Chopper

9 Hour

Chopper circuit – Construction, Operation and Types, DC chopper: Buck, Boost, and Buck-Boost Converter: Construction, Principle of Operation and Characteristics – Duty cycle, Control strategies: Variable and constant frequency- Bi-directional operation, overview, Buck, Boost, and Buck-Boost Converter Circuit overview, Buck Converter - Components, Buck Converter - circuit, Buck Converter - Analysis, Buck-Boost Converter - Components, Buck-Boost Converter - Circuit, Buck-Boost Converter - Analysis, Buck-Boost Converter - Components, Buck-Boost Converter - Circuit, Buck-Boost Converter - Analysis, Push-Pull Converter: Half Bridge and Full Bridge operation, AC choppers: Construction, Working and types.

Unit-3 - Converters

у пои

Rectifiers: Characteristics and Circuit Configuration, Full Bridge Diode AC-DC Rectifier, Three-Phase Full-Bridge Diode Rectifier - Circuit Configuration, Three-Phase Full-Bridge Diode Rectifier — Waveforms, Design of Dynamic Breaking Unit, Calculation of DC-Link Power, Three-Phase Full-Bridge. Thermistor AC-DC Rectifier-Circuit Configuration, Three-Phase Full-Bridge Thermistor AC-DC Rectifier-Analysis, Three-Phase Full-Bridge Thermistor AC-DC Rectifier-Analysis, Three-Phase Full-Bridge Thermistor AC-DC Rectifier-Waveforms, Topology and Operation Modes, 2 pulse and 6 pulse: Construction, Principle of Operation and Characteristics - Fire Angle Control Scheme, Ripple Inverters: Types of Inverters overview, Voltage Source Inverters: 120 and 180 degree mode of operation, Current Source inverters, Current Source inverters applications, Control Techniques — PWM generation and types, Harmonics, Current control techniques - Hysteresis Current Control Filter circuits, Multilevel inverters

Unit-4 - Automotive Motor Drives 9 Hour

Drive module architecture, DC motor drives: DC motor- Construction, Working Principle and types, Speed control techniques, converter fed operation, Introduction to brushless motor drive. DC motor drives-Types, Torque Production in Brushed DC-Motor Drives, Series operation connected DC motor drives, Induction Motor Drives: Induction motor- Construction, Working Principle and types, Speed control techniques, inverter fed operation, Introduction to permanent magnet motor drive, Induction Motor Drives., Induction motor Variable Speed Drive operating modes, Torque and speed control of Induction - Motor Drives, Fundamentals of Scalar and vector control for induction motors, Types of vector control for induction motors, Induction motors, Induction motor drives for Electric Vehicles, Configurations Drive module for Electric vehicles.

Unit-5 - Power Electronics Interface for Electric Vehicles

9 Hour

Schematic diagram of the battery electric vehicles, Power distribution, Power Management Control Strategy, Back-to-Back power converters, Calculation of DC-Link Power, Design of heat sink, G2V and V2G operation in EV, Power Quality Improvement, Automotive standards

Learning Resources
Resources

- 1. Ali_Emadi" Handbook of automotive power electronics and motor drives",3rd Edition, 2014
- Ned Mohan, T.M.Undeland, W.P.Robbins," Power Electronics: Converters, applications and design", John wiley and Sons, 3rd Edition, 2006.
- 3. Rashid M.H., "Power Electronics Circuits, Devices and Applications", Prentice Hall India, 4th Edition, New Delhi, 2013

Learning Assessme	ent			
	Bloom's Level of Thinking	Formative CLA-1 Average of unit test	g Assessment (CLA) Life-Long Learning CLA-2	Summative Final Examination (40% weightage)
		(50%) Theory Practice	(10%) Theory Practice	Theory Practice
Level 1	Remember	15%	15% -	15% -
Level 2	Understand	25%	- 25%	25% -
Level 3	Apply	30%	30% -	30% -
Level 4	Analyze	30%	30%	30% -
Level 5	Evaluate		SERVE STATE OF THE SERVE STATE O	-
Level 6	Create	- Your Harris - 170		-
	Tot <mark>al</mark>	100 %	100 %	100 %

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Associate Director, Skill-	1. Mr. Arockiya Vijay, SRMIST, arockiaj1@srmist.edu.in	1. Dr.C.Carunaiselvane, SRM <mark>IST</mark>
		2. Dr.T.Praveenkumar, SRMIST

Course	UE414J Cours	MODELLING AND CONTROL OF ELECTRIC AND HYBRID	Course	_	PROFESSIONAL ELECTIVE	L	T	Ρ	С
Code	Name	VEHICLES	Category	С	PROFESSIONAL ELECTIVE	2	0	2	3

Pre-requisite Courses	N	Co- requisite Courses	NI	rogressive Courses	Nil
Course Offerin	ng Department	Automobile Engineering	Data Book / Codes / Standards		Nil
			- 17 N Lens		

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	11	4			Progr	<mark>am O</mark> ı	ıtcome	s (PO)					rogram	
CLR-1:	state and classify the elec	tric and hybrid po <mark>wer train tec</mark> hnologies	1	2	3	4	5	6	7	8	9	10	11	12		pecific	
CLR-2:	investigate and interpret t	he performanc <mark>e characte</mark> ristics of EV / HEV power train components	agb		of	SI		. ".			Work		8				
CLR-3:	LR-3: classify and test the various EV / HEV energy storage technologies		Knowled	S	elopment	stigations oblems	age	ъ			am W		Financ	Б			
CLR-4:	develop and relate the various Energy management control techniques for EV and HEV vehicles		Αñ	alysis	lobi	estig	Usa	r and	∞ >	h.	Теаг	ion	ĕ ≪	arni			
CLR-5:			ring	A	deve	t inve	Tool	engineer aty	nment nability	. 1	<u>∞</u>	nmunication	Mgt.	g Le			
			inee	plem	g/ tion	duct ii	ern	enc et<	ig ig	SS	ndividual	ПШ	roject	Long	7	7.	က္
Course C	Outcomes (CO):	At the end of this course, learners will be able to:	Engi	Prot	Desi	o So	Mod	The	Envi Sust	EF	lg je	Com	Proj	Life	PSO.	PSO-2	PSO
CO-1:	compare and operate the	different electric and hybrid vehicle power train configuration	3	- 2	2	- ,	1	7	-		-	-	-	-	3	-	-
CO-2:	CO-2: demonstrate and design the EV / HEV power train model and its components		3	3	3	1-14	2	4	-		-	-	-	-	3	-	-
CO-3:	:0-3: identify and examine the storage batteries, fuel cells and ultra-capacitors used in vehicles		3	2	2	- 3	1	-	-		-	-	-	-	3	-	-
CO-4:	D-4: construct and solve the EV / HEV power and energy management systems		3	3	3		1	-	-		-	-	-	-	3	-	-
CO-5:			3	- 3	3	-	2		-		-	-	-	-	3	-	-

Unit-1 - Introduction to Electric Vehicles

12 Hour

Introduction to Electric Vehicles, Energy storage for EV, EV Configuration, Hybrid Electric Vehicles- Degree of Hybridization, Battery Electric Vehicles (BEV's) vs. Fuel Cell Electric vehicle (FCEV)technologies, Case Study on Tesla and Toyota Mirai

Practice:

1 Introduction Lab 2 Introduction to Virtual Instrumentation and Rapid control prototyping hardwar 3 Power/Energy Management System

Unit-2 - Electric and Hybrid Power Train Technologies

12 Hour

Selection of Motors: Criteria, Electric Motor Performance characteristics—Power-Torque characteristics, DC Motors Vs. AC Motors, Steady state Performance analysis, Advantage of BLDC motors, Battery Performance Characteristics-Battery Terminologies (OCP, SOC, DOD, Energy Density, Power density, Inverters and Motor drives, Regenerative Braking Characteristics

Practice:

4 Data acquisition using data loggers and virtual instrumentation hardware, 5 Interfacing Analog input, Signal conditioning using control hardware: 6 Control of actuators with Rapid control prototyping hardware

Unit-3 - Modelling and Characteristics of EV/HEV Power Train Components

12 Hour

Architecture of EV system, Electro chemical reactions, Battery technologies – Basic principle and Modelling of Lead acid battery and Lithium based Ultra- capacitors –Basic principle and Modelling, Fuel cells: Basic principle and Modelling

Practice:

7 Testing and validation of Electric Vehicle Battery, 8 Testing and Validation of Electric Motor for power assisted Steering system, 9 Speed control for Electric Vehicle motors

Unit-4 - Energy Storage 12 Hour

Energy management controllers, Battery Management system (BMS) for EV and HEV, Rule based Control Strategies for HEV and PHEV –Deterministic Rule- based, Fuzzy rule-based control strategies, Optimization based Control Strategies –Global Energy Management Optimization, Real-time Energy Management Optimization

Practice:

10 Direction control of Electric Vehicle moto, 11 Electronic differential Design for Electric Vehicles, 12 Revision

Unit-5 - Energy Management Systems for EV and HEV

12 Hour

Fundamentals of Vehicle Dynamics Control (VDC) Systems —Driver Model, Fundamentals of Vehicle Dynamics Control (VDC) Systems —Environment Model, Working principle of VDC Systems, VDC System Overview, VDC implementation on Electric and Hybrid Vehicles-structure of the control system, Control system Design and simulation study,

Practice:

13 Revision Lab. 14 Lab Model Examination, 15 Evaluation & Discussion

Learning
Resources

- Amir Khajepour, M. Saber Fallah, Avesta Goodarzi-"Electric and Hybrid Vehicles Technologies, Modeling and Control - A Mechatronic Approach" Wiley Publication, 1st edition, 2014
- Iqbal Husain, "Electric and Hybrid vehicles Design Fundamentals", CRC Press, 2nd edition, 2013
- James Larminie, John Lowry, "Electric vehicle technology Explained", WileyPublication, 2nd edition, 2012
- 4. Ali Emadi, MehrdadEhsani, Joh<mark>n M. Muller</mark>, "Vehicular Electric PowerSystems" Marcel Dekker, Inc., 2004

Learning Assessm	nent			B 1741 1843-81	10.0	or Combustion			
				Continuous L	.earnin	g Assessment (CLA)		Com	
	Bloom's Level of Thinking	<u> </u>	CLA-1 Averag	ative ge of unit test %)		Life-Long CL (15	4-2	Final Ex	mative camination reightage)
			Theory	Practice	The Section	Theory	Practice	Theory	Practice
Level 1	Remember		15%	4 7 3 7	2	1 1 1 1 1 1 1 1 1 1 1 1	15%	15%	-
Level 2	Understand		25%	The same while	1	100	25%	25%	-
Level 3	Apply		30%			1 3 F 18 - 3 L	30%	30%	-
Level 4	Analyze		30%		NI.	A COLUMN TO SERVICE AND ADDRESS OF THE PARTY	30%	30%	-
Level 5	Evaluate		-	All -	101	-	-4		-
Level 6	Create		-	-	1. 7	-		-	-
	Total		100) %	THE STATE	100) %	10	00 %

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Associate Director, Skill-Lync	Mr. Arockiya Vijay, SRMIST, arockiaj1@srmist.edu.in	1. Dr.A <mark>runkumar</mark> Jayakumar, SRMIST
	/ADELLE, ELAP-LEAD	2. D <mark>r.T.Pravee</mark> nkumar, SRMIST

Course	211111177	Course	MACHINE LEARNING APPROACH FOR AUTOMOTVE	Course	Е	PROFESSIONAL ELECTIVE	L	Т	Р	С
Code	21AUE4171	Name	APPLICATION	Category		PROFESSIONAL ELECTIVE	3	0	0	3

Pre-requisite Courses	N	Co- requisite Courses	Nil Progress Course	Nil	
Course Offeri	ing Department	Automobile Engineering	Data Book / Codes / Standards	 Nil	

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	111	4			Progr	r <mark>am O</mark> ı	ıtcome	s (PO)					rogram
CLR-1:	understand the basic con	cept of condition <mark>monitoring a</mark> nd Machine learning algorithm	1	2	3	4	5	6	7	8	9	10	11	12	_	pecific itcomes
CLR-2:	understand the different t	ypes of senso <mark>r signals a</mark> nd data acquisition system	dge		of	SI	4				Work		9			
CLR-3:	LR-3: interpret and relate the different signal processing techniques		Knowlec	S	Jent	stigations roblems	Usage	Ъ	, 1				inan	б		
CLR-4:				Analysis	udoli	estig		r and	ج ج ک	h.	Team	Įį.	∞ π	arning		
CLR-5:	LR-5: understand the implementation of condition monitoring techniques for automotive application		ering	- An	n/development of	t inve lex pi	T00	engineer a	ment ability	1	<u>8</u>	ommunication	Mgt.	g Le		
			e	roblem	ign/	nduct ir	er.	enç ety	ron	SOIL	ndividual	חשר	roject	Long	7)-2)-3
Course C	Outcomes (CO):	At the end of this course, learners will be able to:	Eng	Prot	Des	g G	Mod	The	Envi	E E	Indi	Sol	Proj	Life	PSO-1	PSO-2 PSO-3
CO-1:	list and recognize the var	ious <mark>machin</mark> e techniques and condition monitoring techniques	3	- 5	1	-	3	7	-		-	-	-	-	-	
CO-2:	CO-2: identify and Estimate Parameters of signals using different sensors		3	2	40.50	- 1	-	1	-	-	-	-	-	-	-	
CO-3:	0-3: identify and use various signal processing techniques		- X	l res	3	13	2	_	<i>-</i>	-	-	-	-	-	-	
CO-4:	7-4: relate and use the various classification and regression models		1 3-1	1.40	3	-	2	-	ul -		-	-	-	-	-	
CO-5:	0-5: investigation of condition monitoring for automotive application		- 15	20	2	3	_		-		-	-	-	-	-	

Unit-1 - Introduction to Condition Monitoring

9 Hour

Introduction to Machine Learning, Introduction to Condition Monitoring, Types of Machine Learning Techniques, Supervised, Unsupervised And Reinforcement Learning, Machinery Failures, Basic Maintenance Strategies, Factors Influencing Maintenance, Strategies, Factors Influencing Maintenance, Strategies, Factors Influencing Maintenance Activity, Condition Monitoring, Machine Condition Monitoring, Condition Based Maintenance Activity, Transducer Selection and Location, Transducer Selection and Location, PC Interfacing and Virtual Instrumentation, PC Interfacing Activity, Interfacing and Virtual Instrumentation, PC Interfacing Activity, Interfacing Activity

Unit-2 - Sensing and Instrumentation

9 Hour

Types of Sensors in Condition Monitoring and its Application, Types of Sensors in Condition Monitoring and its Application, Different Types of Vibration Sensors, Working Principle of Piezoelectric Type Transducer, Different Types of Sound Sensors, Working Principle of Free Field Array Microphone, Basic Principle of Acoustic Emission (AE), Signals, Working Principle of AE Sensors, Types of Temperature Sensors and its Working Principle, Types of Ultrasonic Sensors and its Working Principle, Different Types of Infra-Red Sensors, Working Principles of IR Sensor and its Key Application, Oil Analysis, Thermography, Motor Current Analysis, Motor Current Analysis, Data Acquisition System (DAQ), Signal Conditioning

Unit-3 - Signal Processing

9 Hour

Basic Signal and Systems Concepts, Basic Signal and Systems Concepts, Time Domain Analysis, Time Domain Analysis, Frequency Domain Analysis, Frequency Domain Analysis, Frequency Analysis, Wavelets Analysis, Wavelet Packets, Vibration Signatures of Faults in Rotating Machines, Vibration Signatures of Faults in Rotating Machines, Vibration Signatures of Faults in Reciprocating Machines, Vibration Signatures of Faults in

Unit-4 - Pattern Recognition

9 Hour

Feature Extraction Methods, Feature Selection Methods, Feature Reduction using PCA - Discriminant Functions, Feature Reduction using PCA - Decision Boundaries, Feature Reduction using Decision Tree, Classification using Maximum Likelihood, and Nearest Neighbor, Bayesian Theory, Neural Networks, Neural Networks, Fuzzy Logic, Fuzzy Logic, Support Vector Machines (SVM), Proximal Support Vector Machines (PSVM), Regression- Linear, Regression- Linear, Regression- Polynomial, Regression- Polynomial

Unit-5 - Automotive Applications 9 Hour

Application and Case Studies of Bearings, Application and Case Studies of Bearings, Case Study of Gearbox, Case Study of Gearbox, Case Study of Engines, Case St Structural Health Monitoring, Machine Tool Condition Monitoring, Machine Tool Condition Monitoring, Machine Learning Vs Deep Learning, Machine Learning Vs Artificial Intelligence, Machine Learning Vs Artificial Intelligence, Machine Learning Applications Across Industries, Machine Learning Applications Across Industries, Tutorial

Learning	
Resources	

- 1. Balageas D., Fritzen C P. and Guernes A. 'Structural Health Monitoring' Published by ISTE 5. Norton M. and Karczub D. 'Fundamentals of Noise and Vibration Analysis for Engineers' Ltd., USA - 2006
- 2. Clarence de Silva 'Vibration and Shock Handbook'- CRC Taylor & Francis 2005
- 3. Collacot Mechanical Fault Diagnosis and Condition Monitoring'- Chapman Hall 1987
- 4. Davies 'Handbook of Condition Monitoring Techniques and Methodology' Springer 1998 7. Strang G. and Nguyen T. 'Wavelets and Filter Banks' Wellesley-Cambridge Press 1996
- Cambridge University Press 2003 2nd Edition
- 6. Duda R.O., Peter Hart E., and Stork D. E. -Pattern Classification' -Wiley India -2007 2nd

	/ 6		Continuous Learning	g Assessment (CLA)		Summative				
	Bloom's Level of Thi <mark>nking</mark>	CLA-1 Avera	native ge of unit test 0%)	Life-Long CL	Learning A-2 0%)	Final Ex	mative amination eightage)			
		Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	15%	Carlotte Marian	15%		15%	-			
Level 2	Understand	25%	A 18 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	20%	. 1 - 7	25%	-			
Level 3	Apply	30%	100 may 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	25%		30%	-			
Level 4	Analyze	30%	William State Control	25%	- C	30%	-			
Level 5	Evaluate	23 7 77 31		10%	4	0 -	-			
Level 6	Create	- W		5%	3 -	-	-			
	Total	10	0%	100	0 %	10	0 %			

Course Designers	Y. A. S.	
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Technical Specialist, Skill-lync	1. Dr.S.Jeevanandan, Professor, Department of EEE,	1. Dr. T. Pravee <mark>nkumar,</mark> SRMIST
jegan.a@skill-lync.com	Pondicherry Technological University.	
2. Mr.Govardhana Giri, Director, Atalon Product Center Pvt,	2. Dr. Dhoorei K. Khatad. Accesists Drofessor, Dont. of E.C. UTD.	2. Dr.C.Caru <mark>naiselvan</mark> e, SRMIST
Ltd. giri@atalon.co	2. Dr.Dheeraj K Khatod, Associate Professor, Dept. of EE, IITR	

Course	21AUF372T	Course	DESIGN APPROACHES IN ELECTRIC VEHICLETECHNOLOGY	Course	П	PROFESSIONAL ELECTIVE	L	T	Р	С	1
Code	ZIAUESIZI	Name	DESIGN APPROACHES IN ELECTRIC VEHICLETECHNOLOGY	Category	С	PROFESSIONAL ELECTIVE	3	0	0	3	

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offeri	ng Department	Automobile Engineering	Data Book / Codes / Standards		Nil

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	JJJ	4			Progr	<mark>am</mark> Օւ	itcome	s (PO)					rogram	
CLR-1:	know about the working p	principle of electri <mark>c vehicles</mark>	1	2	3	4	5	6	7	8	9	10	11	12		pecific Itcomes	,
CLR-2:	identify the construction a	and working pri <mark>nciple of various motors used in electric vehicles</mark>	egp		of	SI		. ".			Work		ЭG				
CLR-3:	CLR-3: analyze the different control strategies used in electric motors for electric vehicles				Jent	estigations roblems	Usage	ъ	. 1		Μ		Finance	ЭC			
CLR-4:					n/development of	estig		r and	∞ >	h.	Team	ioi	& Fi	arning			
CLR-5:	5: interpret the various types and working principle of batteries & fuel cells				deve	t inve	Tool	engineer ety	ment ability		<u>∞</u>	mmunication	Mgt.	g Le			
	•		neering	oblem	g'/bi	nduct in complex	ern	enc ety	ron	S	/idu	חונו	roject	Long	7	2-0	3
Course C	Outcomes (CO):	At the end of this course, learners will be able to:	Еng	Prok	Des	of or	Mod	The	Envi	Ethi	Individual	Con	Proj	Life	PSO-1	PSO-2	5
CO-1:	describe about working p	rinci <mark>ple of el</mark> ectric vehicles	3		1.5	-	2	/	-		-	-	-	-	-		-
CO-2:					10 35	- 1	-	4	-		-	-	-	-	-		-
CO-3:	0-3: compare and analyze the different control strategies used in electric motors for electric vehicles			l rea	3	13	2		-	-	-	-	1	-	-		-
CO-4:	0-4: describe the different types and working principle of hybrid vehicles				3		2	-	-		-	-	-	-	-		-
CO-5:			-	4	2	3	_		-	-	-	-	-	-	-		-

Unit-1 - Introduction to Electric Vehicles

9 Hour

Electric Vehicle Need Types Cost and Emi<mark>ssions C</mark>ost and Emissions – End of life-Electric Vehicle Technology End of life-Electric Vehicle Technologylayouts- cables- components Controls. Batteries – overview and its types. Battery plug-in and life Ultra-capacitor- Charging – Methods and Standards. Alternate charging sources Wireless & Solar Introduction of electric vehicles Safety

Unit-2 - Electric Vehicle Motors

9 Hour

Motors (DC- Induction- BLDC) Types- Principle- Construction- Control, Electric Drive Trains (EDT), Series HEDT (Electrical Coupling), Power Rating Design, Peak Power Source (PPS), Parallel HEDT (Mechanical Coupling), Torque Coupling and Speed Coupling. Switched Reluctance Motors (SRM) Drives, Basic structure- Drive Convertor- Design. Testing of Motors/Generators, Selection of Motors under variable parameters

Unit-3 - Electronics and Sensor-Less Control in EV

9 Hour

Basic Electronics devices, Diodes- Thyristors, BJTs- MOSFETs- IGBTs- Convertors- Inverters, Safety – Risks and Guidance, Precautions- High Voltage safety Hazard management. Sensors - Autonomous EV cars, Self-Drive Cars, Hacking; Sensor less, Control methods- Phase Flux Linkage-Based Method- Phase Inductance, Mutually Induced Voltage-Matching of Battery and Engine, Motor and Wheels, Synchronizing

Unit-4 - Hybrid Vehicles

9 Hour

Hybrid Electric vehicles, Classification, Layout, operation modes, Architecture, Propulsion systems and components, Regenerative Braking, Regenerative Braking Economy, Economy, Vibration and Noise reduction, Vibration and Noise reduction, Hybrid Electric Vehicles System, Hybrid Electric Vehicles System, Analysis and its Types- Controls.

Unit-5 - Batteries and Fuel Cells for EVs & HEVs

9 Houi

Introduction Basics Terminologies used for Energy Storage, Oxidation & Reduction reaction, Cell construction, types, advantages & disadvantages, and working, principles of different battery chemistries used for EVs: Lead Acid Battery, Nickel batteries, Sodium batteries, Lithium batteries, Advancement in Li-ion batteries, Battery Management System, Battery Sizing for EVs & HEVs. Fuel Cells, Lifetime cost of Fuel cell Vehicle

Learning
Resources
Resources

- Ehsani, M., Gao, Y., Longo, S., & Ebrahimi, K. M. (2018). Modern electric, hybrid electric, and fuel cell vehicles. CRC press.
- 2. Larminie, J., & Lowry, J. (2012). Electric vehicle technology explained. John Wiley & Sons.
- 3. Husain, I. (2021). Electric and hybrid vehicles: design fundamentals. CRC press.
- 1. Ehsani, M., Gao, Y., Longo, S., & Ebrahimi, K. M. (2018). Modern electric, hybrid electric, and 4. Liu, W. (2017). Hybrid electric vehicle system modeling and control. John Wiley & Sons.
 - 5. Hayes, J. G., & Goodarzi, G. A. (2018). Electric powertrain: energy systems, power electronics and drives for hybrid, electric and fuel cell vehicles.

	Bloom's Level of Thinking	CLA-1 Avera	Continuous Learning native ge of unit test 0%)	C	g Learning LA-2 (0%)	Summative Final Examination (40% weightage)			
		Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	15%		15%		15%	-		
Level 2	Understand	25%	ALC: U.S.	20%	V	25%	-		
Level 3	Apply	30%	20 E 10 C G	25%	(P) 1	30%	-		
Level 4	Analyze	30%	No. 25 24 777	25%		30%	-		
Level 5	Evaluate			10%		4 -	-		
Level 6	Create		A 24 BANG A	5%		-	-		
	Tot <mark>al</mark>	100	0%	- 10	00 %	10	0 %		

Course Designers	
Experts from Industry	Experts from Higher Technical Institutions Internal Experts
1. Dr. Ajeet Babu, Manager, ARAI	1. Mr. Shirish Mane 1. Dr. Y.K. Bhateshvar, ARAI
2. Mr. Rakesh Mulik, DGM, ARAI	2. Dr. Deepak Watvisave 2. Dr. S.A. Patil, ARAI

Course	21A11E373T	Course	ENGINE DESIGN AND DEVELOPMENT	Course	Е	PROFESSIONAL ELECTIVE	L	Т	Р	С
Code	21AUE3/31	Name	ENGINE DESIGN AND DEVELOPMENT	Category		PROFESSIONAL ELECTIVE	3	0	0	3

Pre-requisite Courses	N	Co- requisite Courses	Nil Progress Course	Nil	
Course Offeri	ing Department	Automobile Engineering	Data Book / Codes / Standards	 Nil	

Course L	earning Rationale (CLR)	: The purpose of learning this course is to:	Program Outcomes (PO)											ogra			
CLR-1:	define the nomenclatur	e and parts of auto <mark>motive engin</mark> es	1	2	3	4	5	6	7	8	9	10	11	12		pecifi tcom	
CLR-2:	know various aspects of	of automotive eng <mark>ine design</mark>	0		11	Jo	-	ety			~						
CLR-3:	identify the requiremen	t, process an <mark>d developm</mark> ent of automotive engines	edge		nt of	ions	a o	society			Work		Finance				ı
CLR-4:	evaluate the requiremengines	줃	Analysis	velopment	estigation oblems		and	t &	h.	Team	tion	∞ŏ	earning			ı	
CLR-5:	evaluate the requireme	ering	An	(D)	t in y	_00_	engineer	vironment stainability		ह इ	Sommunication	Mgt.				1	
			nginee	Problem ,	ign/d tions		ern	ence	ron tain	S	ndividual	l E	Project	Long	-1	-2	
Course C	ourse Outcomes (CO): At the end of this course, learners will be able to:				Des	Som	Mod	The	Envii Sust	Ethics	lpdi	Con	Proj	Life	PSO-1	PS0-2	PS0-3
CO-1:	acquire knowledge abo	out the <mark>importa</mark> nce of automotive engines	3	10	16/20	- T	2	1	-	-	-	-	-	-	-	ı	-
CO-2:	understand various as	pects <mark>of autom</mark> otive engine design	3	2	196	-	-		-		-	-	-	-	-	-	-
CO-3:	understand requiremer	t, process and development of automotive engines	1.4.3	176	3	-	2	_	-		-	-	-	-	-		-
CO-4:	demonstrate the requirement of lubrication, cooling system and crankcase arrangement for automoti				3	7-	2	Ę	-	- 0	-	-	-	-	-	-	-
CO-5:	demonstrate the requir	demonstrate the requirement of fuel system and crank train arrangement for automotive engines				3	_	-	-		-	_	-	-	-	,	-

Unit-1 - Engine Design and Operating Parameters

9 Hour

Need Requirements Engine Classifications Engine Classifications Engine Efficiency and Fuel Consumption Engine Efficiency and Fuel Consumption Brake Torque and Power Mean Effective Pressure, Air/Fuel and Fuel/Air Ratios, Performance Curves, Engine Specific Weight and Specific Volume Engine Downsizing Engine Packaging Engine Reliability and Durability

Unit-2 - Engine Configuration and Balance

9 Hour

Engine Configuration based on Requirements Estimating Engine Displacement Estimating Engine Displacement Determining Number of Cylinders Bore-to-Stroke Ratio Mean Piston Speed, Engine Noise Vibration and Harshness (NVH) Engine Forces and Couples Engine Balancing.

Unit-3 - Engine Components Design

9 Hour

Engine Cylinder Block Engine Cylinder Block Features Deck Height Cylinder Bore Spacing Integral Cylinder Liner Wet Cylinder Liner Dry Cylinder Liner Cylinder Liner Positive Crankcase Loads and Sizing, Cylinder Head Layout Design, Intake Port Ventilation, Bearing Swirl and Tumble, Intake Port and Manifold Length Exhaust Port and Manifold Length, Piston Construction, Piston Design

Unit-4 - Lubrication, Cooling and Crankcase System

у пои

Pump type, sump, size and location Lubrication circuit, Oil drain back and scavenging Crankcase ventilation, breathing Pump drive and location Cooling System Cooling System Pump capacity and temperature control Circuit design and analysis Flywheel sizing Accessory Systems Additional drives (power steering, hydraulic pump, air pumps) Alternator, starter and compressor (air, HVAC)

Unit-5 - Fuel System, Crank train, Valve Train and Camshafts

9 Hour

Fuel system Injectors and spark plugs Combustion chamber design Combu<mark>stion chamber design Gear train type and location Cranksh</mark>aft sizing and proportions Bearings, Connecting rod size and type, journals, crank webs, torsional vibration & damper Camshaft and valve train Type of valve train, number Type of valve train, number Valve arrangement and location of camshafts Cam drive

Learning Resources	 Hoag Kevin L., Vehicular Engine Design, Springer-Verlag, USA, 2006. Engineering Know-How in Engine Design (Part 1 to 24), SAE, USA. 	 Applications and Developments in New Engine Design and Components, SAE, USA Goetze A. G., Piston Rings Manual, Technischer Verlag Herbert Cram "Bosch' Automotive Handbook", 8thEdition
-----------------------	--	---

			Continuous Learnin	g Assessment (CLA)		Summative			
	Bloom's Level of Thinking	CLA-1 Average	Formative CLA-1 Average of unit test (50%)		Learning 4-2 %)	Final Examination (40% weightage)			
	4	Theory	Practice	Theory	Practice Practice	Theory	Practice		
Level 1	Remember	15%	-	15%		15%	-		
Level 2	Understand	25%		20%	2 - 1	25%	-		
Level 3	Apply	30%	ACCURATE OF	25%	1/2- 1	30%	-		
Level 4	Analyze	30%	200	25%	A	30%	-		
Level 5	Evaluate	/- V	- A St. 250 178	10%		-	-		
Level 6	Create			5%			-		
	Tota <mark>l</mark>	100)%	100) %	100	0 %		

Course Designers	TO A THE STATE OF	3 7
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr S S.Ramdasi,	1. Dr. M. R. Nandgaonkar	1. Mr H J Gayen, ARAI
2. Mr N V Marathe	2. Dr. Sanjay Kumbhar	2. Mr Aatmesh Jain <mark>, ARAI</mark>
		3 Mr K Sarayanan ARAL

Course	211112777	Course	ENERGY MANAGEMENT AND STORAGE SYSTEMS	Course	_	PROFESSIONAL ELECTIVE	L	Т	Р	С
Code	21AUE3/41	Name	ENERGY MANAGEMENT AND STORAGE SYSTEMS	Category	E	PROFESSIONAL ELECTIVE	3	0	0	3

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offeri	ng Department	Automobile Engineering	Data Book / Codes / Standards		Nil

ニャコンド しょっし

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	17	- 4			Progr	am Oı	ment 8 Tability Lal & Tability Mgt. 8 Mgt. 8						rogram		
CLR-1:	know different types of en	ergy storage sys <mark>tem</mark>	1	2	3	4	5	6	7	8	9	10	11	12		pecific itcomes	
CLR-2:	identify the battery charac	cteristic & para <mark>meters</mark>	ge		of	SI	-	. "			ork		8				
CLR-3:	compare different types o	Knowledge	S	velopment	stigations roblems	Usage	ъ	,		Μ		nan	БC				
CLR-4:	evaluate the concepts of l			ldol	estig		r and	∞ >	h.	Теаг	ion		arni				
CLR-5:	evaluate the battery testin	ng, disp <mark>osal and</mark> recycling	ering	Ana	a)	t inv	700	jinee	men			nica	Mgt.	g Le			
	•		9	<u>a</u>	ign/d	nduct i	Modern T		ron in in	SS	/jg	Ш	Project	<u> </u>	7	2 2	
Course C	LR-1: know different types of energy storage system LR-2: identify the battery characteristic & parameters LR-3: compare different types of batteries LR-4: evaluate the concepts of battery management system and design the battery pack LR-5: evaluate the battery testing, disposal and recycling Durse Outcomes (CO): At the end of this course, learners will be able to: O-1: discuss about the different types of energy storage system O-2: describe about the battery characteristic & parameters O-3: model different types of batteries O-4: apply the concepts of battery management system and design the battery pack		Engi	Program	Des	of of	Mod	The	Envi	Ethics	Indi	Con	Proj	Life	PS0-1	PSO-2	2
CO-1:	discuss about the differen	t ty <mark>pes of en</mark> ergy storage system	3	- 5	-	-	2	-7	-		-	-	-	-	-		-
CO-2:	describe about the battery	/ c <mark>haracteri</mark> stic & parameters	3	2	40 10	7-19	-	4	-	1	-	-	-	-	-		-
CO-3:	model different types of b	att <mark>eries</mark>		RE TO	3	13	2	_	-		-	-	-	-	-		-
CO-4:	apply the concepts of battery management system and design the battery pack				3	-	2	-	-	-	-	-	-	-	-		-
CO-5:	explain about the battery	tes <mark>ting, dis</mark> posal and recycling		4.	2	3	_		-		-	-	-	-	-		-

Unit-1 - Energy Storage System

9 Hour

Batteries: Introduction Lead Acid Battery Nickel based batteries, Sodium based batteries, Lithium based batteries Lithium based batteries – Li-ion & Li-poly, Metal Air Battery, Zine Chloride battery; Ultra capacitors; Flywheel Energy Storage System; Hydraulic Energy Storage System; Comparison of different Energy Storage System.

Unit-2 - Battery Constructions

9 Hour

Cells and Batteries - conversion of chemical energy to electrical energy, Battery Specifications: Variables to characterize battery operating conditions and Specifications to characterize battery nominal and maximum characteristics; Efficiency of batteries; Electrical parameters- Heat generation Battery design-Performance criteria for Electric vehicles batteries, Vehicle propulsion.

Unit-3 - Battery Modelling

9 Hour

General approach to modelling batteries Simulation model of a rechargeable Li-ion battery, Simulation model of a rechargeable NiCd battery, Parameterization of the NiCd battery model. Simulation examples

Unit-4 – Battery Pack and Battery Management System

9 Hour

Selection of battery for EVs & HEVs Traction Battery Pack design Requirement of Battery Monitoring Battery State of Charge Estimation methods battery State of Charge Estimation methods Battery Cell equalization problem, thermal control Protection interface, SOC Estimation, Energy & Power estimation Battery thermal management system, Battery Management System: Definition, Parts: Power module Battery, DC/DC Converter, load, communication channel, Battery Pack Safety, Battery Standards & Tests.

Unit-5 - Battery Testing, Disposal and Recycling

9 Hour

Chemical & Structure material properties for cell safety and battery design Battery Testing, Limitations for transport & storage of cells and batteries Recycling, disposal and second use of batteries. Battery Leakage: gas generation in batteries, Leakage path, leakage rates. Ruptures: Mechanical stressand pressure tolerance of cells Safety vents, Explosions: Causes of battery exp.

	1.	G. Pistoia, J.P. Wiaux, S.P. Wolsky, "Used Battery Collection and Recycling", Elsevier, 200
		(ISBN: 0-444-50562-8)"
	2.	Guangjin Zhao, "Reuse and Recycling of Lithium-Ion Power
Learning	3.	Batteries", John Wiley & Sons. 2017. (ISBN: 978-1-1193-2185-9)

Resources

- 4. T R Crompton, "Battery Reference Book-3rd Edition", Newnes- Reed Educational and 9. James Larminie, John Lowry, "Electric Vehicle Technology Explained", John Wiley & Sons Professional Publishing Ltd., 2000.
- Battery Systems", JohnWiley & Sons Ltd., 2016.
- 6. Chris Mi, Abul Masrur & David Wenzhong Gao, "Hybrid electric
- 7. Vehicle- Principles & Applications with Practical Properties", Wiley, 2011.
- 8. Mehrdad Ehsani, Yimin Gao, Ali Emadi, "Modern Electric Hybrid Electric and Fuel Cell Vehicles", Taylor & Francis Group, 2010.
- Ltd. 2003.
- 5. Ibrahim Dinçer, Halil S. Hamut and Nader Javani, "Thermal Management of Electric Vehicle 10. Arno Kwade, Jan Diekmann, "Recycling of Lithium-Ion Batteries: The LithoRec Way", Springer, 2018. (ISBN: 978-3-319-70571-2)

earning Assessme	ent <u> </u>			- 14//						
	Bloom's Level of Thinking	Forma CLA-1 Averago (50%	tive e of unit test		Learning 4-2 %)	Summative Final Examination (40% weightage)				
		Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	15%		15%	(-4)	15%	-			
Level 2	Understand	25%		20%		25%	-			
Level 3	Apply	30%	Carlot Page Control	25%		30%	-			
Level 4	Analyze	30%	And the second	25%		30%	-			
Level 5	Evaluate		23 / P - 120 P 10 P	10%		-	-			
Level 6	Create	S	\$5 - 18 TO 1	5%		-	-			
	Total	100	%	100) %	10	0 %			

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr Rahul Bollini, Consultant	1. Dr Parag Jose, Assistant Professor, CHRIST (Deemed to be University)	1. Mr Punit Kongi, Ass <mark>istant Fa</mark> culty, ARAI
2. Miss Hemavathi , Scientist, CSRI	2. Mr Gowtham Sanjay, Assistant Professor, CHRIST (Deemed to be University)	2. Dr. Sanjay A. Patil <mark>, Ge</mark> n <mark>eral</mark> Manager, ARAI

Course	21AUF375T Course	ALTERNATE ENERGY FOR MOBILITY APPLICATION	Course	П	PROFESSIONAL ELECTIVE	L	Т	Р	С	
Code	Name	ALTERNATE ENERGY FOR MOBILITY APPLICATION	Category	Е	PROFESSIONAL ELECTIVE	3	0	0	3	

Pre-requisite Courses	Ni	Co- requisite Courses	Nil Progr	Nil
Course Offeri	ing Department	Automobile Engineering	Data Book / Codes / Standards	 Nil

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	111	-4			Prog	<mark>ram</mark> Οι	ıtcome	s (PO)					ograi	
CLR-1:	define the physio-chemical	l characteristic o <mark>f fuels in IC e</mark> ngine	1	2	3	4	5	6	7	8	9	10	11	12		pecifi tcom	
CLR-2:	categories the techniques	in production <mark>, storage a</mark> nd handling techniques of a fuel	ge		of	SL					Work		99				
CLR-3:	identify the features and m	ethods ad <mark>opted for t</mark> he of alternative fuels in SI engines	Knowledge	S	evelopment	investigations ex problems	Usage	ъ	. 1				Finance	gu			
CLR-4:	Identify the features and m		Analysis	udoli	estig		r and	م × ح م	h.	Team	tion	∞ర	arni				
CLR-5:	compare the technical feat	ures o <mark>f EV-HE</mark> V and Fuel Cell for automotive applications	ering		deve		Modern Tool	engineer ety	ironment tainability		∞ర	Sommunication	Mgt.	ng Le			
		and the state of t	Enginee	Problem	lign/	Sonduc of comp	Jern	le en	io in in in in in in in in in in in in in	S	Individual	nmu	Project	Long	7	PS0-2	7-3
Course C	urse Outcomes (CO): At the end of this course, learners will be able to:				Des	909	Mod	The	Envii Sust	Ethics	ig i	Š	Proj	Life	PSO-1	PS(PSO-3
CO-1:	understand the potential characteristics	and feasibility to use fuel in IC Engines through its physio-chemic	cal 3				2	7	-	-	-	-	-	-	-	-	-
CO-2:	understand various produc	ti <mark>on, stora</mark> ge and handling techniques of a fuel	3	2	197		-		-		-	-	-	-	-	-	-
CO-3:	explain the concept-metho engines	d <mark>, modifi</mark> cations and various features related to use of alternative fuels in	SI _	1	3	5	2	=	-	-:	-	-	-	-	-	-	-
CO-4:	explain the concept-method, modifications and various features related to use of alternative fuels engines		CI	-4	- 3	3-	2		-	-0	-	-	-	-	-	-	-
CO-5:	illustrate the technical feat	illustrate the technical features of EV-HEV and Fuel Cell for automotive applications				3	-	-	-	-	-	-	-	-	-	-	-

Unit-1 - Introduction 9 Hour

Status of petroleum reserves, Economics; Need for alternative fuels, Alternative Fuel Requirements; Advantage & Disadvantages of different alternative fuel; Review of fuel properties. Alternative Fuel Adaptability Techniques. Comparison of density, Fuel consumption and emissions, Fuel import/export statistics, Government of India Policies, National Biofuel Policy

Unit-2 - Alcohol Fuel

General properties, Alcohol Production process, Compatibility as a fuel, Properties as engine fuel, Alcohols and gasoline blends, Performance and emission analysis in SI engine, Feasibility study of alcohol in CI

General properties, Alcohol Production process, Compatibility as a fuel, Properties as engine fuel, Alcohols and gasoline blends, Performance and emission analysis in SI engine, Feasibility study of alcohol in CI engines, Performance and emission analysis in CI engines, Modifications required to use in engines. E85, ED95, DME, DEE fuels and their characteristics, Flex fuel vehicle, reformed alcohol.

Unit-3 - Gaseous Fuel: Natural Gas, LPG, Hydrogen and Biogas

9 Hour

Introduction to CNG, LNG and LPG fuel, Availability of CNG, LPG, Properties of natural gas, Modification required to use inengines, Performance and emission, Characteristics of CNG & LPG in SI & CI engines, Biogas, Producer Gas. LNG as a power source to Heavy Duty Vehicles, CNG Gas cylinder, Kit testing methods, Hydrogen: Properties, Production methods, Storage methods – challenges associated, Safety Aspects Use in SI and CI engines; Engine/vehicle level modifications required Performance and emissions; On-board hydrogen generation methods; well to wheel life cycle analysis.

Unit-4 - Biofuels 9 Hour

Generation of Biofuels, Composition and properties, Various vegetable oils for engines, esterification, Biodiesel Production Process, Optimization in production process, Performance & emissions characteristics in engines, Biodiesel standards, Issuesrelated to biofuels in engines, Super-critical alcoholic's, Gas to liquid, process; F-T Process; Synthetic Fuel, Plastic Fuel.

Unit-5 - Electric, Hybrid and Fuel Cell

у нои

Layout of an electric vehicle, Advantage and limitations, System components, Electronic control system, Hybrid Vehicle, Various Architecture of HEVs, Fuel cells - Types, working, Fuel cells: Advantages, and Disadvantages, Performance Parameters, Losses associated in fuel cells, Synthetic fuel – Gas to liquid process, Fisher Tropic process, DME & DEE, Plastic fuel.

	1.	Thipse 3. 3, (2010), Alternative Fuels. Concepts, Techn
		Publishing House.
Learning	2.	Michael F. Hordeski, (2013), Alternative Fuels: The Future of
Resources	3.	Maheswar Dayal - "Energy today & tomorrow"- I & B Horish
	1	Canagan V (2012) Internal Combustion Engines McCrow

- 1. Thipse S. S, (2010), Alternative Fuels: Concepts, Technologies and Developments, Jaico
 - of Hydrogen, the Fairmont Press, Inc.
 - sh India 2012.
 - 4. Ganesan V., (2012), Internal Combustion Engines, McGraw-Hill Education India Pvt. Ltd
- 5. Richard.L.Bechfold Alternative Fuels Guide Book SAEInternational Warrendale -
- Nagpal "Power Plant Engineering" Khanna Publishers, 16thedition, 2015.
 Alcohols as motor fuels progress in technology -SeriesNo.19 -SAE Publication USE -
- 8. SAE paper nos. 840367, 841333, 841334, 841156, Transactions, SAE, USA.

earning Assessme			Continuous Learnin	g Assessment (CLA)		0			
	Bloom's Level of Thinking	CLA-1 Aver	mative age of unit test 50%)	Life-Long CL/ (10	4-2	Summative Final Examination (40% weightage)			
		Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	15%	48 F 10 F 10	15%		15%	-		
Level 2	Understand	25%	200 SW	20%		25%	-		
Level 3	Apply	30%		25%		30%	-		
Level 4	Analyze	30%	12 TH WATER OF S	25%		30%	-		
Level 5	Evaluate		Charles To the Control	10%	78 -	-	-		
Level 6	Create			5%	. 1	-	-		
	Total	10	00 %	100)%	100	0 %		

Course Designers		의 선생님 사용한 그 전에 가장 전기 위에 되어 사랑하다. 네트	
Experts from Industry		Experts from Higher Technical Institutions Internal Experts	
1. Dr S S Thipse, EDL, ARAI		1. Mr Shirish Mane, RIT	
2. Mr Nagendra Chintakula, FEV		2. Dr K R Patil, MMCOE 2. Mr H J Gayen, GM, ARAI	

Course	21AUE376T	Course	INTELLIGENT TRANSPORT SYSTEM	Course	_	PROFESSIONAL ELECTIVE	L	Т	Р	С
Code	ZIAUESTOI	Name	INTELLIGENT TRANSPORT SYSTEM	Category		PROFESSIONAL ELECTIVE	3	0	0	3

Pre-requisite Courses	Nil	Co- requisite Courses	_ • '	Nil	Progressive Courses	Nil
Course Offerin	ng Department	Automobile Engineering		Data Book / Codes / Standards		Nil

Course L	earning Rationale (CLR):	The purpose of learning this course is to:		T 4	7		Pı	rogra	m Ou	tcome	s (PO)					gram	
CLR-1:	familiarize with the concep	ots of digital map <mark>database</mark>	1	- 2	2	3	4	5	6	7	8	9	10	11	12		ecific come	
CLR-2:	know the usage of neural	network for in <mark>telligent ve</mark> hicle system	ac	9	Jo	્ દ		7	. ":			Work		9				
CLR-3:			Alwork	2	s nent	velopinent or nvestigations x problems		Usage	ъ			Μ		Finance	gu			
CLR-4:	1177				evelopme	estig	lob		r and	× ×	1	Team	ig.	∞ర	arning			ļ
CLR-5:	.R-5: compare the challenges for vehicle Autonomy for Indian scenario		Pripa During	2 <	sign/development	∹ای ی	<u>6</u>	Tool	engineer sty	Environme <mark>nt</mark> Sustainability		<u>a</u>	Sommunication	Mgt.	ng Le			
			9	2 3		onduct	omple	Modern		ron	S	Jġ.	<u>ا</u>	ect	Long	7	7-5	ကို
Course O	Course Outcomes (CO): At the end of this course, learners will be able to:		, L		Des lo		of	Moo	The	Envi	Ethics	Individual	Col	Project	Life	PS0-1	PS0-2	PSO-3
CO-1:	0-1: describe the digital map database		3	}		2	- 4	2	7	-		-	-	-	-	-	-	-
CO-2:	2: analyze use of neural network for intelligent vehicle system		. 3	3	2	32.54	-11	-	4	-	-	-	-	-	-	-	-	-
CO-3:	-3: understand use of different Sensor & Its applicability for IVS			X P	100	3		2	_	-	-	-	-	-	-	-	-	-
CO-4:	build smaller / simpler AD	A <mark>S system</mark>	1175			3	-	2	-	-	-	-	-	-	-	-	-	-
CO-5:				-	J	2	3	-	-	-	-	-	-	-	-	-	-	_

Unit-1 - Basics of Intelligence

9 Hour

Definition of intelligence, systems blocks for data collection (data gathering) Need Definition of intelligence, systems blocks for data collection (data gathering) data pruning/cleaning and sanity checks (levels and understanding), data pruning/cleaning and sanity checks (levels and understanding) use or adaptation beyond data, use or adaptation beyond data, data and its properties statistical measures and tests, statistical measures and tests, statistical measures and tests, statistical measures and tests automotive applications.

Unit-2 - Neural Network and its Implementation

9 Hour

Basics of Neural network, multiple hidden layers, Convolution, open source framework (such as Tensor flow and Auto ware), programming framework, programming framework

Unit-3 - Sensors and Communication

9 Hour

LiDAR, RADAR, Camera, specifications and utilization, CAN OBD, communication - V2V, communication V2V, VI, V2X, Internet of Cars, communication V2V, VI, V2X, VI

Unit-4 - ADAS Applications

9 Hour

Simultaneous localization and motion, path planning, ambience awareness, driver drowsiness and intent detection, machinelearning, algorithms for automotive applications, machine learning algorithms for automotive applications.

Unit-5 - What Next in Automotive Intelligence

9 Hour

Prognostics and diagnostics of moving vehicle, vehicle health monitoring and status checks, last mile mobility solutions, trends and future of automotiveintelligence (dialog system, speaker awareness), (Auto cyber security challenges for implementation in Vehicle, Auto cyber security challenges for implementation in Vehicle.

	1.	Lawrence D. Burns, Christopher Shulgan, "Autonomy: The Quest to Build the Driverless	3.	Intelligent Transportation Systems from Good Practices to Standards By Paolo Pagano,
Learning		Car-And How It Will Reshape Our		Published by CRC Press, ISBN 9780367782825
Resources	2.	Reports on Automotive Intelligence by various agencies such as McKinsey, Price water	4.	Perspectives on Intelligent Transportation Systems (ITS) by Professor Joseph M. Sussman from
		house Cooper (PwC), Standard chartered, IBM, NITI Aayog		MIT

earning Assessme	ent		Onethern Transfer	. A(OLA)	*				
	Bloom's Level of Thinking	CLA-1 Avera	native ge of unit test 0%)	CL	g Learning .A-2 0%)	Summative Final Examination (40% weightage)			
		Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	15%	- A - A	15%	2	15%	-		
Level 2	Understand	25%	No.	20%	1/2-	25%	-		
Level 3	Apply	30%	20 E 10 E 10	25%	(P)	30%	-		
Level 4	Analyze	30%	Sec. 277	25%		30%	-		
Level 5	Evaluate			10%	4-2		-		
Level 6	Create	-	2, 178 W275 x 3	5%		-	-		
	Tot <mark>al</mark>	10	0%	- 10	0 %	10	0 %		

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Ajeet Babu, Manager, ARAI	1. Mr. Shirish Mane	1. Dr. Y.K. Bhateshvar, ARAI
2. Mr. Rakesh Mulik, DGM, ARAI	2. Dr. Deepak Watvisave	2. Dr. S.A. Patil, ARAI

Course 21ALIE471T	Course	VEHICLE BODY AND CRASH WORTHINESS	Course	Е	PROFESSIONAL ELECTIVE	L	Т	Р	С
Code ZTAUE4711	Name	VEHICLE BODT AND CRASH WORTHINESS	Category		PROFESSIONAL ELECTIVE	3	0	0	3

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offeri	ng Department	Automobile Engineering	Data Book / Codes / Standards		Nil

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	11	4			Progr	am Ou	itcome	s (PO)					gram	
CLR-1:	know the different vehicle	s layout, bodies and correlate with AIS053 standard requirements	1	2	3	4	5	6	7	8	9	10	11	12		ecific come	
CLR-2:	11 1 J 1 1 1 1 1 1 1 1 J 1 1 J 1 1 J 1 1 J 1 J 1 J 1 J 1 J 1 J 1 J 1 J 1 J 1 J 1 J 1 J 1 J 1 J 1 J 1 J 1 J 1 J		dge		o	SL		, "c			Work		9				
CLR-3:	LR-3: evaluate structural elements, Diagnose vehicle crashworthinessrequirements		owledge	S	elopment of	restigations problems	age	ъ			M W		Finan	рu			
CLR-4:			조	alysis	udo	estig	Usag	r and	y k		Team	ţį	∞ర	arni			
CLR-5:	LR-5: evaluate the Vehicle safety features for the modern vehicle systems		ering	An	deve	2 ~	<u>0</u>	engineer ety	ment ability		<u>a</u>	mmunication	Mgt.	ong Le			
			<u>ue</u>	roblem	lgi lgi	nduct ir complex	<u>e</u>	enç ety	iron tain	S	Jġ.] E	roject	٦	-	7	ကို
Course C	Course Outcomes (CO): At the end of this course, learners will be able to:		Eng	Prot	Des	Con	Mod	The	Envi Sus	E	Individual	Sol	Proj	Life	PS0-1	PS0-2	PSO-3
CO-1:	P-1: recognize & explain different vehicles layout, bodies and correlate with AIS 053 standard requirements		3		-	-	2	-7	-		-	-	-	-	-	-	-
CO-2:	2: construct a vehicle body topology, and summarize vehicle body nomenclature		3	2	10.00	- 1	-	4	-	- 1	-	-	-	-	-	-	-
CO-3:	D-3: analyze structural elements, Diagnose vehicle crashworthiness requirements		- x	172	3	1 3	2	-	- 1		-	-	-	-	-	-	-
CO-4:	demonstrate materials use	ed in Automotive to meet the weight, safety requirement	134	1.77	3		2	-	-		-	-	-	-	-	-	-
CO-5:				4.5	2	3		_	-		-	-	-	-	-	-	

Unit-1 - Introduction 9 Hour

Vehicle Layout, AIS 053 - Vehicle Types & Terminology, Vehicle Categories (L, M, N, C, A, T, O and G), Vehicle Layouts and Types (Car Body Construction), Body Functions, Fundamentals of Vehicle Crash and Calculations - Galileo's Principal of Inertia, Newton's First Law, Newton's Second Law – Momentum and Impulse, Acceleration Due to Gravity, Impact of Crash on A Human Body, Crashworthy

Unit-2 - Passenger Vehicle Body

9 Hour

The Automobile Body, DMU - Digital Mock-Up, Aggregate Packaging Like Power Train, Suspension, Wheels and Human (At Least Driver), Description of the Automobile Body Types, Space Frame, Central Frame, Body-on-frame, Monocoque Body Configuration, Body Nomenclature, Vehicle Layout (Side-view, front-view, plan-view vehicle layout), Different types of Car Body Style, Body work - Body in White

Unit-3 - Monocogue Body Structure and Crashworthiness

9 Hour

Categories of Structural Requirements, Locate and Retain Function with Example, Flow Down of Requirements From Vehicle-Level Functions, Overview of Classical Beam Behavior, Design of Automotive Beam Sections, Design For Durability (Road Load Data, Torsion, Bending Stiffness & Fatigue), and NVH; Design For Crashworthiness (Crashworthiness-Deceleration Curve, Square Wave, Injury Tolerance, Control Of Deceleration), Standardized Safety Test Conditions and Requirements, Introduction To Crash Safety, Crash Tests: Front Barrier, Side Impact, Rear Impact and Roof Crush.

Unit-4 - Vehicle Body Materials, Trim, and Mechanism

9 Hour

Automotive Body Requirements, Automotive Body Structural Elements, Automotive Body Materials, Lightweight and High Strength Steel Alloys, Steels Used in Automotive Bodies (AHSS: DP Steel CP Steel, MART Steel, FB Steel, HF Steel, TRIP Steel, TWIP Steel, Hot Formed, Bake Hardened, IFHS, HSLA, Cmn, Plastic/Composite, Austenitic Grade, and Magnesium and Aluminum, Electric Vehicle Battery Pack Structure and Materials Plastics Used in Automotive, Materials Used in Electric Vehicles (Battery, Battery Pack, Motors). Manufacturing Processes and Joining / Assembly Methods.

Unit-5 - Vehicle Safety

9 Hour

Automotive Safety, Road Safety – Five Pillars, Basic Concept of Vehicle Safety: Principles, Fail-Safe, Alternate Design, Human Error Control, Occupant Injury Prevention: Biokinetics, Technology & Regulations, Recent Advancements (Active and Passive Safety), (Active And Passive Safety), Future Vehicle Safety, NCAP Ratings, Future Vehicle Safety, NCAP Ratings

	2.
Learning	2
Resources	٥.

- International Publication 2019
- Morello, Rossini, Pia and Tonoli; "The Automotive Body Vol I and II"; Springer Publication 2015
- 3. George A. Peters, Barbara J. Peters; "Automotive Vehicle Safety"; CRC Press (Taylor & Francis, London) 2016
- 4. Heinz Heisler, "Advanced Vehicle Technology", second edition, Butterworth Heinemann, New York, 2002.
- 1. Donald E. Malen; "Fundamentals of Automobile Body Structure Design"; SAE 5. Mark Gonter, Ulrich W. Seiffert; Integrated Automotive Safety Handbook R-407; SAE International Julian Happian-Smith, an Introduction to Modern Vehicle Design, Butterworth- Heinemann.
 - 6. K. Newton, W.Steeds and T.K.Garret, "The Motor Vehicle", 13th Edition, Butterworth Heinemann, India Automotive Hand book/ Robert Bosch, SAE, 2003.
 - 7. Powloski. J., Vehicle Body Engineering, Business BooksLtd.
 - 8. Priya Prasad, Jamel E. Belwafa; Crashworthiness and Occupant Protection, American Iron and Steel Institute, Southfield, Michigan Mark Gonter, Ulrich W. Seiffert
 - 9. P. M. Heldt, "Automotive Chassis", Chilton Co., NewYork, 1982.
 - 10. W.Steed, "Mechanics of Road Vehicles", IlliffeBooks Ltd., London.

arning Assessme	Bloom's Level of Thinking	CLA-1 Avera	ative	CL	Learning A-2 19%)	Final Ex	mative amination eightage)
	/ 5 /	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	15%		15%		15%	-
Level 2	Understand	25%	at the same	20%		25%	-
Level 3	Apply	30%	A Section of the second	25%	. 1 - 7	30%	-
Level 4	Analyze	30%	William Comment to	25%		30%	-
Level 5	Evaluate	S	AND 18 18 18 18 18 18 18 18 18 18 18 18 18	10%	- C	-	-
Level 6	Create	27 77 11		5%	4	0 -	-
	T <mark>otal ====================================</mark>	100)%	100	0 %	10	0 %

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Dr. Ajeet Babu, Manager, ARAI	1. Mr. Shirish Mane	1. Mr. Nilesh A S <mark>akle,ARA</mark> I
2. Mr. Rakesh Mulik, DGM, ARAI	2. Dr. Deepak Watvisave	2. Mr. Punit Kon <mark>gi, ARAI</mark>

Course	21ALIF472T Course	NOISE VIRRATION AND HARSHNESS	Course _	PROFESSIONAL ELECTIVE	Г	Т	Р	С	
Code	Name	NOISE VIBRATION AND HARSHNESS	Category	PROFESSIONAL ELECTIVE	3	0	0	3	

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offeri	ng Department	Automobile Engineering	Data Book / Codes / Standards		Nil

Course L	earning Rationale (CLR): The purpose of lea <mark>rning this co</mark> urse is to:	CHENC	11	4			Progr	<mark>am</mark> Οι	itcome	s (PO)					rogram
CLR-1:	understand various sources of noise and vibration in automotiveapplications		1	2	3	4	5	6	7	8	9	10	11	12	_	pecific itcomes
CLR-2:	know working of noise & vibration measuring instruments		ge		o	SI		. ".			Work		8			
CLR-3:	Try 113				nent	ation	Usage	ъ			M M		Finance	ning		
CLR-4:	compare noise control techniques	A. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1.	ering Knowledge	ıalysis	udoli	estig	l Us	r and	× ×		Team	tion	∞ర	ਕ		
CLR-5:	R-5: compare signal analysis techniques			Ā	n/development of ons	nduct investigations complex problems	T ₀₀	engineer ety	nment nability		a 8	Sommunication	Mgt.	ng Le		
				Problem	ign/ rtion	induct in complex	dern		iron tain	S	ndividual	nuu	Project	Long	PS0-1	PSO-2 PSO-3
Course C	Outcomes (CO): At the end of this course, learners will be able	to:	Engi	Pro	Solu	Sor	ĕ	The	Env S <mark>us</mark>	Ethics	<u>la</u>	Š	Pro	Life	PS(PSO PSO
CO-1:	identify the various sources of noise and vibration in automotive applications	N. J. W. 300 M.	3	- 5	1	1	2	-7	-		-	-	-	-	-	- -
CO-2:	2: infer working of noise & vibration measuring instruments			2	45	-19	-	4	-	-1	-	-	-	-	-	- -
CO-3:	: categories significance of acoustic materials and its application			17/2	_3	-34	2	-	-	-	-	-	-	-	-	
CO-4:	enumerate the methods in noise control techniques		7-1	1.40	. 3		2	-	-		-	-	-	-	-	
CO-5:	enumerate the signal analysis techniques		4	4	2	3	_		-		-	-	-	-	-	- -

Unit-1 - NVH in the Automotive Industry

9 Hour

Sources of Noise and Vibration, Design Features, Common Problems, Pass-By Noise Requirements, Target Vehicles and Objective Targets, Vehicle Structure Noise, Engine Noise, Transmission noise, and Exhaust

Unit-2 - Vibration Theory

9 Hour

Transient state response, Steady State Response, one degree of freedom system, Transient and steady state response of one degree of freedom system applied to vehicle systems, Transmissibility, Modes of Vibration

Unit-3 - Basics of Sound

9 Hour

Sound Measurement, Human Sensitivity and Weighting Factors, Human Sensitivity and Weighting Factors, Combining Sound Sources, Acoustical Resonances, Properties of Acoustic Materials

9 Hour

Unit-4 - Test Facilities and Instrumentation

Anechoic Rooms, Silent Room, Modal Analysis, Data Acquisition System, Sound Pressure Level Measurements, Microphone, Accelerometers, Sound Sources Impedance Tube, Transmission Loss Measurement, Sound Absorption Coefficient Measurement, etc. Transducers, Signal Conditioning

Unit-5 - Signal Processing

9 Hour

Sampling, Aliasing and Resolution, Statistical Analysis, Frequency Analysis, Campbell's Plots, Cascade Diagrams, Coherence and Correlation Functions

Learning	
Resources	

- Matthew Harrison, "Vehicle Refinement: Controlling Noise and Vibration in Road Vehicles", Elsevier, 2004
- 2. Noise and Vibration Control, Munjal, M.L. USA World Scientific Publishing Co.Pvt.Ltd., 2013
- 3. Noise and vibration control engineering principles and applications Ver, Istvanl, USA John Wiley & Sons, 2006
- Handbook of noise and vibration control Crocker, Malcolm J., Crocker, Malcolm J., USA John Wiley & sons, 2007
- 5. Vehicle noise and vibration refinement Wang, Xu, Wang, Xu, USA Woodland Publishing Limited,, 2010
- Active control of noise and vibration, Hansen, Colin; Snyder, Scott New York CRC PRESS, 2013 Fundamentals of noise and vibration analysis for engineers, Norto

earning Assessme			Continuous Learning	g Assessment (CLA)		0				
	Bloom's Level of Thinking	CLA-1 Aver	mative age of unit test 50%)	Life-Long	4-2	Summative Final Examination (40% weightage)				
		Theory	Practice	Theory	Practice	Theory	Practice			
Level 1	Remember	15%	18 F 18 F 18	15%		15%	-			
Level 2	Understand	25%	20 July 27 W	20%		25%	-			
Level 3	Apply	30%		25%	G-2	30%	-			
Level 4	Analyze	30%	10 TH WATER OF	25%		30%	-			
Level 5	Evaluate		Charles Mary and	10%		-	-			
Level 6	Create			5%		-	-			
	Total Total	10	00 %	100)%	100	0 %			

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions Internal Experts	
1. Dr S S Ramdasi	1. Dr. M. R. Nandgaonkar 1. Mr Kiran Wani, ARAI	
2. Mr N V Marathe	2. Dr. Sanjay Kumbhar 2. Mr Punit Kongi, ARAI	

Course	21ALIF473T Course	MOTOR DRIVES AND CONTROL SYSTEM	Course _	PROFESSIONAL ELECTIVE	L	T	Р	С	1
Code	Name	MOTOR DRIVES AND CONTROL SYSTEM	Category	PROFESSIONAL ELECTIVE	3	0	0	3	

Pre-requisite Courses	Ni	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offeri	ng Department	Automobile Engineering	Data Book / Codes / Standards		Nil

Course L	earning Rationale (CLR):	The purpose of learning	t <mark>his co</mark> urse is to:	11	4			Progr	<mark>am</mark> Ou	itcome	s (PO)					rogram	
CLR-1:	familiarize the fundament	al concept of Ele <mark>ctromagne</mark> tion	es .	1	2	3	4	5	6	7	8	9	10	11	12		pecific itcomes	,
CLR-2:	familiarize the fundament	al concept of c <mark>ontrol syst</mark> ems	7 O.	Knowledge		Jo	SI	1	. "			Work		8				
CLR-3:						sign/development of utions	estigations roblems	Usage	ъ	. 1		Μ		Finance	Б			
CLR-4:	4: demonstrate the Operation and behavior of AC drives					udola	estig orobl		r and	ج ا ا	h.	Team	tion	∞ŏ	arning			
CLR-5:	F. 11 No.			ering	n Analysis	deve	i ×	<u> </u> 2	engineer ety	nment nability	. 1	<u>ه</u>	ommunication	Mgt.	g Le			
					roblem	fign/	nduct in complex	dern	eng ety	ron	SS	ndividual	חונו	Project	Long	7	2 5	
Course C	Outcomes (CO):	At the end of this course	, learners will be able to:	Engi	Prot	Desi	Con	Mod	The	Envi S <mark>us</mark> f	Ethics	lpdi	Con	Proj	Life	PSO-1	PSO-2	5
CO-1:	enumerate the concepts of	of El <mark>ectroma</mark> gnetics	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	3	- 5		-	2	7	-		-	-	-	-	-		-
CO-2:	enumerate the concepts of control systems		3	2	40	- 1	-	4	-	-	-	-	-	-	-	-	-	
CO-3:	infer the Operation and behavior of DC drives		L - x	17.	3	434	2	_	-	-	-	-	-	-	-	-	-	
CO-4:	infer the Operation and beh <mark>avior of</mark> AC drives			1.34	1.1	3	-	2	-	-		-	-	-	-	-	-	-
CO-5:			- 11		2	3	_		-		-	-	-	-	-	-	-	

Unit-1 - Introduction 9 Hour

Magnetically coupled circuits, Review of basic concepts, Magnetizing inductance, Modelling linear magnetic circuits, Modelling nonlinear magnetic circuits, Electromechanical energy conversion, Concept of field energy, Examples: Simulation study using Multiphysics tool, Torque expression, Principle of energy flow, Principle of co-energy flow, Examples: Simulation study using Multiphysics tool

Unit-2 - Concepts of Control Systems

9 Hour

Overview of Control system, Control system and examples, Mechanical translational system, Mechanical rotational systems, Transfer function basics, Transfe<mark>r functio</mark>n of rotating machine, Electrical analogous of Mechanical translational systems, Block diagram representation of Drive systems, Signal flow graph representation of the systems, Numerical examples

Unit-3 - DC Motor Drives

9 Hour

Introduction: DC traction motor, Principle of DC motor, Speed control of DC motor, Dynamics of D.C. motor drives, Basic features of an Electric Drive, Criteria for selection of drive components, Introduction: DC Chopper, Principle of operation: DC chopper, Chopper controlled drives, Control Techniques, Duty-ratio control, Current-limit control, Chopper circuit: four quadrant operation, Chopper fed drive: Applications, Examples: Simulation study using mathematical solver tool, duction: AC traction motor, Principle of AC motor, Speed control of AC motor, Variable voltage operation, Variable frequency operation, Constant flux operation, Torque-Slip characteristic

Unit-4 - AC Motor Drives

9 Hour

Introduction: AC traction motor, Principle of AC motor, Speed control of AC motor, Variable voltage operation, Variable frequency operation, Constant flux operation, Torque-Slip characteristic, Implementation of V/f control, Slip compensation scheme, Vector control scheme, Inverter fed Closed loop control schemes, Dynamic and regenerative braking, Speed reversal, Examples: Simulation study using mathematical solver tool

Unit-5 - EV System Layout and Design

9 Hour

Classifications of EV motors Unit 1, Transfer function for EV motors, Closed loop control: Current feedback, Closed loop control: Speed feedback, Armature voltage control, Field oriented control, Design of controllers: Fundamentals and calculations, Current controllers. Speed controllers, Examples: Simulation study using mathematical solver tool. Converter selection and characteristics

Learning		R. Krishnan, "Electric Motor Drives – Modelling, Analysis and Control", PHI. 2015 P.S. Bhimbra, "The Generalized Theory of Electrical Machines", Tata McGraw Hill, 2021.		Gopal K.Dubey, Fundamentals of Electrical Drives, Narosa Publishing House, 1992. I.J.Nagarath and M. Gopal, Control system Engineering, New Age International (P) Ltd, 2021.
Resources	3.	C.V. Jones, "The unified Theory of ElectricalMachines", Butterworth, -London.1967	6.	A. Nagoor Kani, Control System, RBA Publications, 2017.
_			-	The same of the sa

			Continuous Learning	g Assessment (CLA)		C				
	Bloom's Level of Thinking					Summative Final Examination (40% weightage)				
		Theory	Practice	Theory	Practice Practice	Theory	Practice			
Level 1	Remember	15%	-	15%		15%	-			
Level 2	Understand	25%	- 6 - 6	20%	2 - 1	25%	-			
Level 3	Apply	30%	A CONTRACTOR	25%	- A- 1	30%	-			
Level 4	Analyze	30%	27 - 17 - 17	25%	A 1-3	30%	-			
Level 5	Evaluate	~ /	1 N. A. St., 2777	10%			-			
Level 6	Create			5%			-			
	Tota l	100)%	10	0 %	10	00 %			

Course Designers	Part of Market and Market	
Experts from Industry	Experts from Higher Technical Institutions	Internal Exp <mark>erts</mark>
Mr.Jegan Amirthalingam, Technical Specialist , Skill- lyncjegan.a@skill- lync.com	Dr.S.Jeevanandan, Professor, Departmentof EEE, Pondicherry Technological University.	1. Dr. Caru <mark>naiselva</mark> ne C, SRMIST
Mr.Govardhana Giri, Director, Atalon Product Center Pvt, Ltd. giri@atalon.co	2. Dr.Dheeraj K Khatod, Associate Professor, Dept. of EE, IITR	

Course	21AUE474T	Course	AUTOMOTIVE EMBEDDED SYSTEMS AND COMMUNICATION	Course	_	PROFESSIONAL ELECTIVE	L	Τ	Ρ	С	Ì
Code		Name	PROTOCOL	Category		PROFESSIONAL ELECTIVE	3	0	0	3	

Pre-requisite Courses	Nil	Co- requisite Co	urses	Nil	Progressive Courses	Nil	
Course Offering Department	Automol	bile Engineering 🖊		Data Book / Codes / Standards		Nil	

Course L	earning Rationale (CLR):	The purpose of learning this course is to:	612	-				Progr	am Oı	ıtcome	s (PO)				Prog	
CLR-1:	familiarize with the princip	les and application <mark>s of embedded</mark> systems	(1		2	_3	4	5	6	7	8	9	10	11	12	Spe Outco	
CLR-2:	familiarize with the archite	cture and perip <mark>herals interf</mark> acing	9	D	47	of	SL		T-6	N.		Work		8			
CLR-3:	identify the usage of progr	ramming in e <mark>mbedded</mark> system	oppolimon X	N N	S	velopment of	estigations roblems	Usage	ъ	. `\		N W		Finance	ning		
CLR-4:	infer and implement the d	evelopme <mark>nt embedd</mark> ed softwareconfiguration and applications			alysis	lopi	estig		r and	t &		Team	tion	∞ర	ä		
CLR-5:	implementation of the auto	omotive <mark>communi</mark> cation protocols and Sub systems		בו בו	⋖	de ve s	t inve lex pr	70 100	engineer	ronment tainability		<u>रू</u>	ommunication	Mgt.	g Le		
	<u> </u>		21 2 1 2	5	oblem	ign/ tion	nduct	em	er et	iron	S	Individual	I III	roject	Long	7 5	7 5
Course O	utcomes (CO):	At the end of this course, learners will be able to:	, G	2	Prof	Des	Con	<u>8</u>	The	Env Sus	Ethics	Indi	S	Proj	Life	PSO-1	F30-2 PS0-3
CO-1:	perform the basic operation	ns o <mark>f autom</mark> otive embedded systems	J. 1943	3	4	-3		2	استر	-	1	-	-	-	-	-	- -
CO-2:	learn using the peripheral	s us <mark>ed in au</mark> tomotive controllers		3	2	0.50	-	-	7	-	-	-	-	-	-	-	- -
CO-3:	apply Programming techn	iq <mark>ues to au</mark> tomotive embedded systems	Her I.		-	3	- 1	2	-	-		-	-	-	-	-	
CO-4:	perform the basic operation	n <mark>s on real</mark> time operating systems	- H.S	8	194	3	7.2	2	-	-		-	-	-	-	-	
CO-5:	demonstrate the commun	ic <mark>ation pro</mark> tocols in automotive systems	1 2		2	2	3	-	-	-		-	-	-	-	-	

Unit-1 - Introduction to Embedded Systems

9 Hour

Introduction to embedded systems, Characteristics of Embedded systems, Build Process for embedded systems overview, Challenges in Embedded SystemDesign, Design Process: Requirements, Specifications, Design Process: Architecture Design, Designing of Components System Integration (Battery & Subsystems), Embedded System Architecture, Instruction Set Architecture CISC and RISC instruction set architecture, Basic Embedded Processor/Microcontroller Architecture, CISC Examples, Motorola (68HC11) Example, 8051, RISC Example, ARM,Co-processors and Hardware Accelerators, DSP Processors, Processor Performance Enhancement, Harvard Architecture, PIC, Memory System Architecture, Caches, Virtual Memory, Pipelining, Super-scalar Execution, Memory Management Unit and Address Translation, I/O Subsystem, Busy-wait I/O, DMA, Interrupt driven I/O

Unit-2 - Embedded System Architecture

9 Hour

Embedded Systems Architecture Introduction, Memory Organization, Memory Devices and their Characteristics RAM, ROM, UVROM, EEPROM, Flash Memory, DRAM, Memory Organization Tutorial, /O Devices, Timers and Counters, Watchdog Timers, Interrupt Controllers, DMA Controllers, A/D and D/A Converters, I/O Device Interfacing, Keyboard, Displays, Serial Port, Converters, Interfacing Demo Component Interfacing, Memory Management and addressing, Interfacing Protocols: GPIB, FIREWIRE, USB, IRDA, Designing with Processors: System Architecture, Hardware Design, FPGA Based Design, Implementation: Development Environment, Debugging Techniques, Manufacturing and Testing, Design Examples: Data Compressor, Alarm Clock

Unit-3 - Embedded System Programming

9 Hour

Programming Embedded Systems, Program Design, Design Patterns for Embedded Systems, Models of Program: Control and Data flow Graph, Programming Languages: Desired Language Characteristics, Introduction to Object Oriented Programming, Data Typing Overloading and Polymorphism, Control in embedded systems, Multi-tasking and Task Scheduling, Timing Specifications, Run-time Exception handling, Use of High Level Languages, C for Programming embedded systems, Object Oriented Programming for Embedded, High level software for Embedded Systems - Overview, Programming and Run-time Environment, Compiling, Assembling, Linking, Debugging, Programming and execution — Demo, Basic Compilation Techniques, Analysis and Optimization of Execution Time, Analysis and Optimization of Program Size, Program Validation and Testing

Unit-4 - Operating System 9 Hour

Basic Features of an Operating System, Kernel Features: Real-time Kernels, Polled Loops System, Co-routines, Interrupt- driven System, Multi-rate System, Processes and Threads, Context Switching, Cooperative Multi-tasking, Pre-emptive Multi-tasking, Scheduling types: Rate-Monotonic, Earliest-Deadline First Scheduling, Task Assignment, Fault-Tolerant Scheduling, Inter-process Communication: Signals, Shared Memory Communication, Message-Based Communication, Process Stack Management, Dynamic Allocation, Real-time Memory Management, I/O: Synchronous and Asynchronous I/O, Interrupt Handling, Device Drivers, Real-time Transactions and Files, Example Real-time OS, RTOS Classification - Hard Real-time and Soft Real time, RT-Linux, Psos, Evaluating and Optimizing Operating System Performance, Response-time Calculation Interrupt latency, Time-loading Memory Loading, Power Optimization Strategies for Processes

Unit-5 - Processors for Automotive Application

9 Hour

Introduction to Automotive grade processors, Automotive grade processors ex: Renesas, Quorivva, Automotive grade processors: NXP, Infineon, Architectural attributes of Automotive grade processors, On-chip Peripherals for ECU overview, Special On-chip Peripherals for Body and chassis control applications, On-chip Peripherals for Electric/hybrid Power train control, On-chip Peripherals for battery System, On-chip Peripherals case study, Overview of Automotive communication protocols: CAN, LIN, Automotive communication protocols: Flex Ray, MOST, Automotive communication protocols: Ethernet, D2B and DSI, Automotive communication protocols - case study, Real-time operating system Demo— for task scheduling activities, RTOS types - Hard Real-time and Soft Real time, RTOS Case Study with real time hardware, Embedded Systems Case Studies — Motor Control System, Case Study — Battery Monitoring System

Learning Resources

- Miroslaw Staron, "Automotive Software Architectures: An Introduction", Springer, 2017. (ISBN: 978-3-319-58609-0)
 Nicolas Navet and Francoise Simonot-Lion, "Automotive Embedded Systems Handbook". CRC Press.
- Nicolas Navel and Francoise Simonol-Lion, Automotive Embedded Systems Handbook, CRC Press, 2009. (ISBN: 978-0-8493-8026-6)
 Muhammad Ali Mazidi. SarmadNaimi. SepehrNaimi "AVR Microcontroller and Embedded Systems using"
- Assembly and C"Pearson Custom Electronics Technology, 2011
- 4. DataSheets of Kinetis 32-bit MCU based on ARM.InfineonXCxx series and Multicore Aurix Architecture
- Ronald K. Jurgen, "Distributed Automotive Embedded Systems", SAE International, 2007. (ISBN: 978-0-7680-1966-7).
- 6. Gilbert Held "Inter and Intra Vehicle Communications: Auerbach Publications, 2008
- 7. Tom Weather Jr. &Cland c. llunter, "Automotive computers and control system"
 Prentice Hall Inc., New Jersey

arning Assessme	and a second	2.7 7/11	Continuous Learnin	g Assessment (CLA)		Cumn	a a tiva		
	Blo <mark>om's</mark> Level of <mark>Thinkin</mark> g	Form CLA-1 Averaç (50	ge of unit test	CI	g Learning LA-2 0%)	Summative Final Examination (40% weightage)			
		Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	15%	···	15%	-4	15%	-		
Level 2	Understand	25%	- 1.7	20%		25%	-		
Level 3	Apply	30%	- // //	25%	- V - /	30%	-		
Level 4	Analyze	30%	- 1/2//	25%	/_//- //	30%	-		
Level 5	Evaluate	-		10%	/ - /-	-	-		
Level 6	Create			5%		-	-		
	Total	100	%	A D T 7 10	00 %	100) %		

Course Designers		9
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Technical Specialist, Skill-lync jegan.a@skill-lync.com	1. Dr.S.Jeevanandan, Professor, Department of EEE,	1. Dr. T. Praveenkumar, SRMIST
	Pondicherry Technological University.	
2. Mr.Govardhana Giri, Director, Atalon Product Center Pvt, Ltd. giri@atalon.co	2. Dr.Dheeraj K Khatod, Associate Professor, Dept. of EE,	
	IITR	

Course 21ALIE4757	Course	ALITONOMOLIS VEHICLE SYSTEMS	Course	_	PROFESSIONAL ELECTIVE	L	Т	Р	С
Code ZIAUE4751	Name	AUTONOMIOUS VEHICLE STSTEMS	Category		PROFESSIONAL ELECTIVE	3	0	0	3

Pre-requisite Courses	Nil	Co- requisite Courses	Nil Progressive Courses	Nil
Course Offering	g Department	Automobile Engineering	Data Book / Codes / Standards	Nil
			CHENION	

Course L	earning Rationale (CLR): The purpose of learning this course is to:	111	4			Progr	am Oı	itcome	s (PO)					rogram
CLR-1:	familiarize the fundamental concept of Autonomous Driving	1	2	3	4	5	6	7	8	9	10	11	12		pecific Itcomes
CLR-2:	familiarize the fundamental concept of Autonomous VehicleLocalization	lge		of	SI		. ".			Work		8			
CLR-3:	demonstrate the Operation and behavior of Perception and AI in Autonomous Driving	nowledge	(C)	velopment of	estigations roblems	Usage	ъ			Μ		Finance	ning		
CLR-4:	demonstrate the Planning Operation and Control behavior of Autonomous Systems	조	alysis	udoli	estig/ probl		r and	× ×		Team	fion	∞ర	ਕੂ		
CLR-5:	implementation of Client Systems, Cloud for EV Autonomous Systems	ering	٩	gn/deve ions	ĹĘ X	Tool	engineer ety	nment nability		Jal &	mmunication	Mgt.	Long Le		
Course C	Outcomes (CO): At the end of this course, learners will be able to:	Engine	Problem	Design solutio	Conduct of comple	Modern	The en society	Enviro S <mark>ustai</mark>	Ethics	Individual	Comm	Project	Life Lo	PS0-1	PSO-2 PSO-3
CO-1:	enumerate the concepts of A <mark>utonomo</mark> us Driving	3		1.	- 1	2	/	-	-	-	-	-	-	-	
CO-2:	enumerate the concepts of Localization	3	2	40.00	- 19	-	4	-		-	-	-	-	-	
CO-3:	infer the Perception Operation and Al	(A)	وترازان	3	1	2	-	- 1		-	-	-	-	-	
CO-4:	infer the Planning Operation and Control of Autonomous Systems	1		3	-	2	-	-		-	-	-	-	-	
CO-5:	identify and Apply Client Systems and Cloud for Autonomous Systems	-	20	3	3	_		-		-	-	-	-	-	

Unit-1 - Introduction 9 Hour

Autonomous Driving Technologies Overview, Sensing, Perception, Object Recognition and Tracking, Autonomous Driving Client System, RobotOperating System, Hardware Platform, Autonomous Driving Cloud Platform, Simulation Methods, Map Types and Generation Methods, Deep Learning for Autonomous systems, Model Training, Methods,

Unit-2 - Localization Techniques

9 Hour

Localization with GNSS, GNSS Error Analysis, Satellite-based Augmentation, Real-Time GPS, Positioning and Integration, Localization with LiDAR, High-Definition Map Generation, Visual Odometry - Stereo, Visual Inertial Odometry, Dead Reckoning and Wheel Odometry, Wheel Odometry and Errors, Reduction of Wheel Odometry Errors, Sensor Fusion, Examples on Localization

Unit-3 - Sensing Concepts

9 Hour

Introduction: Perception, Datasets and Acquisition Methods, Segmentation and Classification, Stereo Vision Flow, Optical Flow, and Scene Flow, Tracking Methods, Introduction: Deep Learning, Convolutional Neural Networks, Object Detection, Semantic Segmentation, Traffic Prediction, Behavior Prediction as Classification, Vehicle Trajectory Generation, Lane Level Routing, Routing Graphs and Algorithms, Examples: Perception, Prediction and Routing

Unit-4 - Approaches to Sensors Assist

9 Hour

Behavioral Decisions, Scenario-based Divide and Conquer Approach, Motion Planning, Vehicle Model, Road Model, and Coordination System, Path Planning and Speed Planning, Longitudinal and Lateral Planning, Feedback Control, Bicycle Model, PID Control Example, Reinforcement Learning, Reinforcement Learning Actor-Critic Methods, Reinforcement Learning on Behavioral Decision,, Reinforcement Learning on Planning and Control, Implementation of Reinforcement Learning, Examples: Planning and Control

Unit-5 - Functionality of Operating Systems

9 Hour

Operating System for Autonomous Driving, Robot Operating System ROS Overview, System Reliability, Performance, Security, Computing Platform Implementation, Computer Architecture Design Exploration, Distributed Computing Framework, Heterogeneous Computing, Simulation, Connecting Spark and ROS, HD Map generation, Map Generation in the Cloud, Examples: Client Systems, Examples: Cloud Platforms

Learning Resources
Learning
Resources

- Shaoshan Liu, "Electric Motor Drives CreatingAutonomous Vehicle Systems", Morgan & ClaypoolPublishers. 2018
- 2. Hong Cheng, "Autonomous Intelligent Vehicles Theory, Algorithms, and Implementation", Springer London DordrechtHeidelberg New York, 2011.
- 3. Markus Maurer, J. Christian Gerdes, Barbara Lenz, HermannWinner, Autonomous Driving Technical, Legal and Social Aspects", Springer-Verlag GmbH Berlin Heidelberg, 2015.
- Syed Faraz Hasan, Nazmul Siddique and Shyam Chakraborty, "Intelligent Transportation Systems-802.11-based Vehicular Communications" SpringerInternational Publishing AG, 2018.
- Gilbert Held, "Inter- and Intra-Vehicle Communications", Auerbach Publications, 2008.A. Nagoor Kani, Control System, RBA Publications, 2017.
- Luca Delgrossi, Tao Zhang, "Vehicle Safety Communications- Protocols, Security, and Privacy", John Wiley & Sons, Inc., 2012.

earning Assessme			Continuous Learning	g Assessment (CLA)		0			
	Bloom's Level of Thinking	CLA-1 Aver	mative age of unit test 50%)	Life-Long	4-2	Summative Final Examination (40% weightage)			
		Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	15%	18 F 18 F 18	15%		15%	-		
Level 2	Understand	25%	20 July 27 W	20%		25%	-		
Level 3	Apply	30%		25%	G-2	30%	-		
Level 4	Analyze	30%	10 TH WATER OF	25%		30%	-		
Level 5	Evaluate		Charles Mary and	10%		-	-		
Level 6	Create			5%		-	-		
	Total Total	10	00 %	100)%	100	0 %		

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Technical Specialist, Skill-	1. Dr.S.Jeevanandan, Professor, Departmentof EEE, Pondicherry	1. Dr.T.Praveenku <mark>mar, SR</mark> MIST
lyncjegan.a@skill- lync.com	Technological University.	
2. Mr.Govardhana Giri, Director, Atalon Product Center Pvt,	2Dr.Dheeraj K Khatod, Associate Professor, Dept. of EE, IIT-K	2. Mr. Jerome St <mark>anley M ,</mark> SRMIST
Ltd. giri@atalon.co		V 9.2 (A)



Course	21AUF476T	Course	ENERGY STORAGE SYSTEMS FOR ELECTRIC AND HYBRID	Course	_	PROFESSIONAL ELECTIVE	L	Т	Р	С	1
Code	21AUE4761	Name	VEHICLES	Category		PROFESSIONAL ELECTIVE	3	0	0	3	

Pre-requisite Courses	N	Co- requisite Courses	Nil	Progressive Courses	Nil
Course Offe	ing Department	Automobile Engineering	Data Book / Codes / Standards		Nil

Course Learning Rationale (CLR): The purpose of learning this course is to:			Program Outcomes (PO)									Program		i								
CLR-1:	gain information about the energy storage fundamentals such asbattery, solar cell and fuel cell in line to EV and hybrid vehicle technology			2	3	4	5	6	7	8	9	10	11	12	Specific Outcome							
CLR-2:	LR-2: familiarize the fundamental concept of Autonomous Vehicle Localization				of	SL	4		, 1		Work		Se.									
CLR-3:	develop the knowledge of drive train and energy managementsystem design				nent	ation	ems	ъ					Finance	ρ								
CLR-4:	study the basics of fuel cells and hydrogen technologies and their applications		Knowledge	alysi	alysi	alysi	Analysis	alysi	alysi	velopment	investigations ex problems	I Us	r and	م ح ک		Team	tion	≪	aming			
CLR-5:	grasp potential knowledge	e on E <mark>V case st</mark> udies, charginginfrastructure and codes and standards	ering		Problem Analysis Design/developmen solutions Conduct investigatio of complex problem Modern Tool Usage The engineer and society		ironment tainability	ustainability thics dividual & Tea			tg -	g Le	ا ا ت									
			9	lem	gn/	grading	ern		in in in in	SS	ndividual	l III	ect	Long	7	7	က္					
Course Outcomes (CO): At the end of this course, learners will be able to:		Engi	Pro	Des	o do	Mod	The	Sust	Ethics	lpdi	Con	Project	Life	PS0-1	PS0-2	PSO-3						
CO-1:	elaborate their knowledge on fundamentals of energy storage system for EV & hybrid vehicles		3	11	F-1		2	1	-		-	-	-	-	-	-	-					
CO-2:	analyze & interpret different EV architecture			2		-	-	_			-	-	-	-	-	-	-					
CO-3:	demonstrate different power <mark>train tec</mark> hnology & energy management systems for EV & hybrid vehicles			17.	-3	7	2	-	-	-	-	-	-	-	-	-	-					
CO-4:	discuss different fuel cell technology with their challenges and applications			-	3	45	2	-	-	- 1	-	-	-	-	-	-	-					
CO-5:	analyze various EVs in the global market, their codes & standards				- 2	3	_		-	_ 1	-	-	-	-	-	-	-					

Unit-1 - Energy Storage Systems

Fundamentals and Requirements of Energy Storage Systems for Electric Vehicles, Electrochemical Energy Storage Systems – Principle, Construction & Working Battery Characteristics, Energy Density and Ragone Plot, Advanced EV Batteries & Super Capacitors, Material Aspects in Battery technology, Hydrogen and Fuel cell technologies, Compressed Hydrogen Storage-EV, Material Aspects in Hydrogen Storage, Fuel cell: Fundamentals, Fuel Cell: Types, Fuel Cell-Efficiency and characteristics, Material Aspects in Fuel Cell, Solar PV for EV applications

Unit-2 - Wiring Layout and Design

Introduction to Electric Vehicles, Wiring Diagram/ Power Flow in EVs & HEVs z, Wiring Diagram/ Power Flow in EVs & HEVs z, Types of EVs: HEV, FCEV, HEVs Configuration: Series Case Study, HEVs Configuration: Series Parallel - Case Study, Motor, Battery Pack, DC-DC Convertor, Inverter, On-Board Charger, Communication System, SMART HYBRID TECHNOLOGY - NEXA, Micro Hybrids - Case Study Electric Vehicle Charging-Fundamentals, Single and Multi-motor drives, In wheel drives,

Unit-3 - Fundamentals of Energy Management System

9 Hour

9 Hour

Energy Management Systems- Introduction, Battery Management Systems- Terminologies, BMS topologies: Centralized, Distributed, Modular:, Fundamentals of A.I for BMS, AI Algorithms for BMS, Kinetic energy recovery systems Flywheel Energy Storage System (FESS) Technology, Fuel cells energy, thermal & water management system, Integrated Energy Management Systems, Range Extender, Numerical Problems, Case: Nissan Leaf vs Tesla, Case: Nissan Leaf vs Tesla

Unit-4 - Grid Architecture 9 Hour

ESS in micro-grid: Architecture, Introduction to Micro-grid and Smart grid, Technology, Subsystems in Micro-grid and Smart grid, Vehicle-to-Grid (V2G) Technology, Vehicle-to-Grid (V2G) Technology, Vehicle-to-Grid (V2G) Technology, Microgrid-EV Integration, Microgrid-EV Integration, Simulations-Microgrid-EV Integration, Simulations-Microgrid-EV Integration-HOMER Software, Simulations-Microgrid-EV Integration-HOMER Software

Unit-5 - EV Market Scenario 9 Hour

EVs: National and International Overview, Techno-Economic Challenges of EVs, Codes & Standards for Batteries, Codes & Standards for Fuel Cells, Codes & Standards for Hybrid Electric Vehicles, Codes & Standards for hydrogen storage, Homologations for EVs, Case study 1- Charging infrastructure, Case study 2-Hydrogen refueling infrastructure, Case Study 3 – Nissan Leaf, Case Study 4 – Tesla Model S, Case Study 5 – Toyota Mirai, EV regulations: America vs Asia vs Europe, Contemporary Challenges Faced in Electric Vehicle Market

Learni	ng
Resou	rces

- Ehsani, M., Gao, Y., Longo, S. and Ebrahimi, K.M., 2018. Modern electric, hybrid electric, and fuel cell vehicles. CRC press.
- Saudemont, C., Hissel, D., Roboam, X., Sareni, B. and Pouget, J., 2016. Electrical Energy Storage inTransportation Systems. John Wiley & Sons.
- 3. Saudemont, C., Hissel, D., Roboam, X., Sareni, B. and Pouget, J., 2016. Electrical Energy Storage in Transportation Systems.
- 4. John Wiley & Sons. "Bosch' Automotive Handbook", 8thEdition

earning Assessme	nt Bloom's Level of Thinking	CLA-1 Avera	Continuous Learning native ge of unit test 1%)		Learning 4-2 %)	Summative Final Examination (40% weightage)			
	/ 27	Theory	Practice	Theory	Practice	Theory	Practice		
Level 1	Remember	15%	The Agency of	15%	-	15%	-		
Level 2	Understand	25%		20%		25%	-		
Level 3	Apply	30%	\$ 15 h 16 10 10 10 10 10 10 10 10 10 10 10 10 10	25%		30%	-		
Level 4	Analyze	30%	8 (A) 1 (A) 1 (A) 1 (A) 1 (A) 1 (A)	25%	77 3 - 2-4	30%	-		
Level 5	Evaluate ====================================	رقيده - ا		10%			-		
Level 6	Create	No. of the second	7427 473	5%		-	-		
	Total	Total 100 %		100) %	100 %			

Course Designers		
Experts from Industry	Experts from Higher Technical Institutions	Internal Experts
1. Mr.Jegan Amirthalingam, Technical Specialist, Skill-	1. Dr. Tolga Taner, Aksaray University, Turkey	1. Dr.T.Praveenk <mark>umar, SR</mark> MIST
lyncjegan.a@skill- lync.com		■ 7 2
2. Mr.Govardhana Giri, Director, Atalon Product Center Pvt, Ltd.	1.7	
giri@atalon.co		



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)

Kattankulathur, Chengalpattu District 603203, Tamil Nadu, India