ACADEMIC CURRICULA

POST GRADUATE DEGREE PROGRAMMES

Master of Technology

(Choice Based Flexible Credit System)

Regulations 2021

Volume - 21 Curriculum



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY

(Deemed to be University u/s 3 of UGC Act, 1956)
Kattankulathur, Chengalpattu District 603203,
Tamil Nadu, India



SRM INSTITUTE OF SCIENCE AND TECHNOLOGY Kattankulathur, Chengalpattu District 603203, Tamil Nadu, India

42. M.Tech in Mechatronics Engineering

42. (a) Department Vision Statement

Stmt - 1

To impart structured theory and extensive practical experience in all the sub-fields contributing to Mechatronics Engineering to make our engineers as experts in multi-disciplinary system integration.

42. (b) Department Mission Statement

Stmt - 1	To impart high-quality education in mechatronics with ethical values to meet global excellence. To establish state-of-the-art laboratories and pave the way to create exposure in research through international collaborations for interdisciplinary areas.						
Stmt – 2							
Stmt - 3	To inculcate entrepreneurship and mankind qualities to meet the expectations of industry and the needs of society.						

42. (c) Program Education Objectives (PEO)

PEO - 1	Impart knowledge and skills in a multi-disciplinary approach through use of modern technologies and tools so as to enable development of innovative and sustainable products.					
PEO - 2 Develop a perspective of a system integrator which involves the understanding of handshaking of various sub-systems complex multi-disciplinary system.						
PEO - 3	Work or pursue research career in multicultural, multilingual and multinational environment with competent oral and written communication					
PEO - 4	PEO - 4 Lead and contribute in a team entrusted with professional, social and ethical responsibilities					
PEO - 5	Enable the skills to identify the scope for modernization of industries in the terms of sustainable automated solutions through the structured acquisition of knowledge and skills as part of mechatronics education					

42. (d) Consistency of PEO's with Mission of the Department

42. (4)	Mission Stmt 1	Mission Stmt 2	Mission Stmt 3
PEO - 1	4 3 3 3 3 3 3 3 3 3 3	UN 31 1938	3
PEO - 2	3	2	3
PEO - 3	2	3	3
PEO - 4	2	3	1
PEO - 5	3	2	3

42. (e) PO – Program Outcomes

PO - 1	An ability to independently carry out research /investigation and development work to solve practical problems.				
PO - 2	An ability to write and present a substantial technical report/document.				
PO - 3	PO - 3 Students should be able to demonstrate a degree of mastery over the area as per the specialization of the program. The mastery should be at a level higher than the requirements in the appropriate bachelor program.				

42. (f) Consistency of PEO's with Program Outcomes (PO)

.2. (.)	Program Outcomes (PO)								
	1-	2	3						
PEO - 1									
PEO - 2									
PEO - 3									
PEO - 4									
PEO - 5									

^{3 –} High Correlation, 2 – Medium Correlation, 1 – Low Correlation

42. (g) Programme Structure: M.Tech in Mechatronics Engineering

Professional Core Courses (C)						Professional Elective Courses (E)					
						(Any 7 Courses)					
Course	Course		Hours/			Course	Course		Hours/		
		Week		_			<u> </u>	We	ek		
Code	Title	L		Р	С	Code	Title	_ 1	L T	ΓР	C
	Advanced System Dynamics	3	0	2	4	21MHE521J	Industrial Manipulators- Kinematics,		2 0) 2	
		1	0	6	4	0444455005	Dynamics and Control	_			3
	Drives and Actuators	3	0	2	4	21MHE529T	Industrial Automation		3 (
	Mechatronics System Design	3	0	2	4	21MHE522J	Modern Control Engineering	_ 2	2 () 2	
	,	0	0	6	3	21MHE528J	Digital Manufacturing and Smart		2 0) 2	, 3
	Research Methodology	2	1	2	4	220200	Factories		`	1	
21MHC601T ¹		3	0	0	3	21MHE523T	Mechatronics Applications in Science		3 0	0 0	, .
	Total Credits	<u>; </u>			26		and Engineering				3
						21MHE524J	Computer Vision		2 (
	Project Work, Internship In					21MHE525J	3		2 (_	- 2
Industry / Higher Technical Institutions (P)		s (P)	(P)			21MHE527J	Autonomous Mobile Robotics		2 (
	,	` '			21MHE526T	Vetronics		3 0 0		3	
Course	Course	Hours/ Week		21WH20001 Hatomotive recimelogy		Automotive Technology	_	3 (1	
0 1	T:11			_		21MHE532L ¹	Robot Programming Laboratory		0 0		
Code	Title	L			C	21MHE533T	Mechatronics in Electric Vehicle		3 (3
21MHP501L	Specialization Project	0	0 4	40	20	21MHE600T ¹	Journal Publication		0 0		<u>⊣</u>
0.44.41.55004	(OR)		<u> </u>	00	4.5	21MHE530T	Smart Materials and Systems		3 (
	Specialization Project				15	21MHE531J	X-Reality and Haptics		2 (
21MHP503L	Domain Internship	0	0 1		5	21MHE534T	Automotive Software		3 (0 0	
	Total Credits				20		Total Credi	ts			21
				-		- A 14					
Ass	essment by Open Book Examination	n (²)				100% assessment by the Department (1)					
Course	Course	Hours/			Course	Course		ours			
	555.55	W	eek_			0 1	T''	. V\	/eel	-	
Code	Title	L	T	Р	С	Code	Title	L	1	P	C
						21MHC601T 1		3	0	0	3
21IPC501J ²	Research Methodology	2	1	2	4			0	0	0	3
					٧.		Elements of Mechatronics	1	0	6	4
	200	-			ĸ.	21MHC505L ¹	Real-Time Embedded Systems	0	0	6	3
	and the second s				10.1	21MHF532 ¹	Robot Programming Laboratory	0	0	6	3

All elective courses may be studied under MOOC platform
1 100% assessment by the Department
2 Assessment by Open Book Examination
3 Course Delivery through online mode

42. (h) Implementation Plan: M.Tech in Mechatronics Engineering

Semester - I					Semester - II								
			Hours/			ociniostei ii		Hours		s/			
Code	Course Title		Week			Code	Course Title	Week					
0000			T	Р	С	0000	304.00 1.40	L	T	Р	С		
21MHC501J	Advanced System Dynamics	3	0	2	4	21MHC504J	Mechatronics System Design	3	0	2	4		
	Elements of Mechatronics	1	0	6	4	21MHC505L 1	Real-Time Embedded Systems	0	0	6	3		
21MHC503J	Drives and Actuators	3	0	2	4	21MHE522J	Modern Control Engineering	2	0	2			
21IPC501J ²	Research Methodology	2	1	2	4	24141175201	Digital Manufacturing and Smart	2	^	2	3		
21MHE521J	Industrial Manipulators- Kinematics,	2	0	2		21MHE528J	Factories	2	0	2			
ZIMHESZIJ	Dynamics and Control		U	2	3	21MHE523T	Mechatronics Applications in	3	٥	٥			
21MHE529T	Industrial Automation	3	0	0		ZIIVINESZSI	Science and Engineering	J	0	0	3		
	Total Credits	;			18	21MHE524J	Computer Vision	2	0	2			
						21MHE525J	Machine Learning and Deep	2	0	2			
						ZTIVITESZSS	Learning				3		
						21MHE527J	Autonomous Mobile Robotics	2	0	2			
		6		I		Total Credits 17							
	Semester - III			-		Semester - IV							
	Semester - III	н	ours	1				Hours/					
Code	Course Title		Week					Code	Course Title	Week		k	
Code	Course Title	ı	T	P	С				Τ	Р	С		
	Open Elective	3	0	0	3	21MHP501L	Specialization Project	0	0	40	20		
21MHE526T		3	0	0			(OR)						
	Automotive Technology	3	0	0	3	21MHP502L	Specialization Project	0	0	30			
	Robot Programming Laboratory	0	0	6		21MHP503L	Domain Internship	0	0	10	5		
	Mechatronics in Electric Vehicle	3	0	0	3		Total Credits				20		
· · · · · · · · · · · · · · · · · · ·			0		100								
	Smart Materials and Systems	3	# Students must register either 21MHP501L or 21MHP502L and										
	X-Reality and Haptics	2	0	2	3	3 21MHP503L both in fourth semester							
	Automotive Software	3	0	0									
	Case Studies	3	0	0									
ZIMITOUTI													
ZIMINCOUTT	Total Credits	-			15	5 大學性	2014년 전 🔚 🔀						

Course		Proc	ramme Outo	omes
Code	Course Name	1	2	3
2 <mark>1MHC5</mark> 01J	Advanced System Dynamics			7 *
	Elements of Mechatronics		Y	
21 <mark>MHC503</mark> J	Drives and Actuators			
21M <mark>HC504J</mark>	Mechatronics System Design		- N	
21MH <mark>C5</mark> 05L	Real-Time Embedded Systems	1 -7		
21MH <mark>C601</mark> T	Case Studies	- /		
21MHE5 <mark>21J</mark>	Industrial manipulators- Kinematics, Dynamics and control			
	Modern Control Engineering		/ .*	7
21MHE523 <mark>T</mark>	Mechatronics applications in Science and Engineering	1		
	Computer Vision	/		
21MHE525J	Machine learning and Deep Learning			
21MHE526T	Vetronics			
21MHE527J	Autonomous Mobile Robotics	_ * *	, E	
	Digital Manufacturing and Smart Factories			
	Industrial Automation			
	Smart Materials and Systems			
	X-Reality and Haptics			
	Robot Programming Laboratory			
	Mechatronics in Electric Vehicle			
	Automotive Software			
	Automotive Technology			
	Journal Publication			
21IPC501J	Research Methodology	3	2.6	
	Open Elective			
	Specialization Project			
	Specialization Project			
21MHP503L	Domain Internship			
	Program Average			

^{3 –} High Correlation, 2 – Medium Correlation, 1 – Low Correlation



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43. M.Tech in Nanotechnology

43. (a) Department Vision Statement

Stmt - 1	To evolve as a world-class hub in Physics and Nanotechnology to meet the rapidly changing global scientific and	
Strit - 1	technological needs for societal development.	

43. (b) Department Mission Statement

Stmt - 1	To impart quality education both in theory and experiment with state-of-the-art infrastructure to develop scientific temper in young minds.				
Stmt - 2 To carry out multidisciplinary research of fundamental and technological importance by partnering with leading ginstitutions and industries.					
Stmt - 3	To develop various skill sets and translate scientific ideas into product innovations to enhance the employability and serve the society.				

43. (c) Program Education Objectives (PEO)

PEO - 1	Develop strong background in nanoscience and nanotechnology by employing the scientific concepts for higher-level understanding of the matter at the nanoscale			
PEO - 2 Employ critical thinking, analytical problem-solving skills in the basic and applied areas of name state of the art tools.				
PEO - 3	Prepare students to work effectively in diverse teams in both class-room and laboratory with integrated, cross-disciplinary scientific knowledge and professional skills.			
PEO - 4 Equip the students with professional, scientific and computational skills for employment opportunities and empowering them to create job opportunities and entrepreneurships				
PEO - 5	Appreciate the need for engaging independent and life-long learning in the broadest context of technological changes and operate within the regulatory framework.			

43. (d) Consistency of PEO's with Mission of the Department

70. (a) 00	moistering of the or with imposion of the	20partinont	
	Mission Stmt 1	Mission Stmt 2	Mission Stmt 3
PEO - 1	3	3	3
PEO - 2	3	3	3
PEO - 3	3	3	3
PEO - 4	3	3	3
PEO - 5	3 7 E A R	V 1 1 3 5	3

43. (e) PO - Program Outcomes

PO - 1	An ability to independently carry out research /investigation and development work to solve practical problems.		
PO - 2	An ability to write and present a substantial technical report/document.		
PO - 3	Students should be able to demonstrate a degree of mastery over the area as per the specialization of the program. The mastery should be at a level higher than the requirements in the appropriate bachelor program.		

43. (f) Consistency of PEO's with Program Outcomes (PO)

	Program Outcomes (PO)		
	1	2	3
PEO - 1	3	3	2
PEO - 2	3	3	2
PEO - 3	3	3	2
PEO - 4	3	3	3
PEO - 5	3	3	3

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